

# ECE 450 - Homework #13

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## 1 ECE 450 - Homework #13

### 1.0.1 Package Imports

```
In [1]: import numpy as np
import seaborn as sns
import pandas as pd
import matplotlib.pyplot as plt
from scipy import signal as sig
from control import margin, tf
import warnings
warnings.filterwarnings('ignore')
```

### 1.1 Generic function to convolve any number of equations

```
In [9]: def convolve_all(values):
temp_conv = values[0]
if len(values) > 1:
    for next_val in values[1:]:
        temp_conv = np.convolve(temp_conv, next_val)

return temp_conv
```

### 1.2 Generic function shift a given filter to a new center frequency

```
In [11]: def shift_filter(num, den, new_center):
new_num = np.pad(num, (len(den) - len(num), 0), 'constant')
new_den = den

for i in range(len(new_den)):
    new_num[i] *= (new_center ** i)
    new_den[i] *= (new_center ** i)

return new_num, new_den
```

#### 1.2.1 Generic function to plot the responses of a system

```
In [2]: # Color list for multiple lines on each subplot
colors = ["red", "blue", "green", "gray", "purple", "orange"]
```

```

step_size = 0.005

# Generic Function to create a plot
def create_plot(x, y, xLabel=["X-Values"], yLabel=["Y-Values"],
               title=[("Plot", )], num_rows=1, size=(18, 14), logx=False):
    plt.figure(figsize=size, dpi=300)
    for c, (x_vals, y_vals, x_labels, y_labels, titles) in enumerate(zip(x, y, xLabel, y
        for c2, (y_v, t) in enumerate(zip(y_vals, titles)):
            plt.subplot(num_rows, 1, c + 1)
            # Add a plot to the subplot, use transparency so they can both be seen
            plt.plot(x_vals, y_v, label=t, color=colors[c2], alpha=0.70)
            plt.ylabel(y_labels)
            plt.xlabel(x_labels)
            plt.grid(True)
            plt.legend(loc='lower right')
            if logx:
                plt.xscale("log")

plt.show()

```

### 1.2.2 Generic function to generate the $|H|$ and $\phi$ values of a $H(z)$ function

```

In [3]: def z_plot(num, den, T):
    phi = np.arange(0.001, np.pi, T)
    angles = angles = [np.exp(complex(0, angle)) for angle in phi]

    # Loop through all angles, calculate that angles H(z)
    h_z = []
    for z in angles:
        num_sum, den_sum = 0, 0
        for z_pow, num_val in enumerate(num):
            num_sum += num_val * z ** (len(num) - z_pow)
        for z_pow, den_val in enumerate(den):
            den_sum += den_val * z ** (len(den) - z_pow)
        h_z.append(num_sum / den_sum)

    return np.multiply(180 / np.pi, phi), 20 * np.log10(h_z)

```

9.1.3, 9.2.1, 9.3.1

## 1.3 Problem 9.1.3

2nd order monotonic monotonic band pass filter with a pass band between 500 and 550  $\frac{\text{rad}}{\text{s}}$ . The sampling time is 0.1 milliseconds.

Start with  $n = 1$ , a bandwidth  $W = 50$ , and a center frequency of  $\omega_c = 525$ .

$$H_{lp} = \frac{1}{s + 1}$$

Scale up this low-pass filter:

$$G_0(s) = H_{lp}\left(\frac{s}{50}\right) = \frac{50}{s + 50}$$

Now, transform this to a bandpass filter:

$$G(s) = G_0\left(\frac{s^2 + 525^2}{s}\right) = \frac{50s}{s^2 + 50s + 275,625}$$

Now, to convert this function to a z-equivalent transfer function:

$$\alpha = \frac{50}{2} = 25, \omega^2 = 275625 - \left(\frac{50}{2}\right)^2 = 275000, K_2 = 50, K_1 = \frac{-50 * 25}{\sqrt{275000}} = -2.38$$

$$H(s) = K_1 \frac{\omega}{(s + \alpha)^2 + \omega^2} + K_2 \frac{s + \alpha}{(s + \alpha)^2 + \omega^2}$$

$$H(s) = -2.38 \frac{524.4}{(s + 25)^2 + 275000} + 50 \frac{s + 25}{(s + 25)^2 + 275000}$$

$$H(t) = (-2.38e^{-25t}\sin(25t) + 50e^{-25t}\cos(25t)) \cdot u(t)$$

$$H(z) = -2.38T \frac{e^{-25T}\sin(25T)z}{z^2 - 2e^{-25T}\cos(25T)z + e^{-50T}} + 50T \frac{z^2 - e^{-25T}\cos(25T)z}{z^2 - 2e^{-25T}\cos(25T)z + e^{-50T}}$$

Resulting in the following Z-domain transfer function:

$$H(z) = \frac{z^2 0.005 + z 0.005}{z^2 - z 1.995 + 1}$$

#### 1.4 Problem 9.2.1

The below section of code gives me the  $H(s)$  function for the third order butterworth filter:

```
In [18]: scipy.signal.TransferFunction([50, 0], [1, 50, 275625], dt=0.1 * 10 ** -3)
```

```
Out[18]: TransferFunctionDiscrete(
  array([50.,  0.]),
  array([1.00000e+00, 5.00000e+01, 2.75625e+05]),
  dt: 0.0001
)
```

```
In [14]: n = 3
```

```
pole_list = []
for m in range(1, n + 1):
    phi = np.pi / 2 + np.pi / 2 * (2 * m - 1) / n
    pole_list.append(complex(np.cos(phi), np.sin(phi)))

num = [1]
den = convolve_all([1, -pole] for pole in pole_list)
final_num, final_den = shift_filter(num, den, 10 ** 3)

print ("Num: ", num, "\nDen: ", np.real(den))
```

Num: [1]  
 Den: [1.e+00 2.e+03 2.e+06 1.e+09]

$$H(s) = \frac{1}{s^3 + s^2 \cdot 10^3 + s \cdot 10^6 + 10^9}$$

Which can be converted to:

$$H(z) = \frac{1}{z^3 + z^2 \cdot 10^3 + z \cdot 10^6 + 10^9}$$

### 1.5 Problem 9.3.1

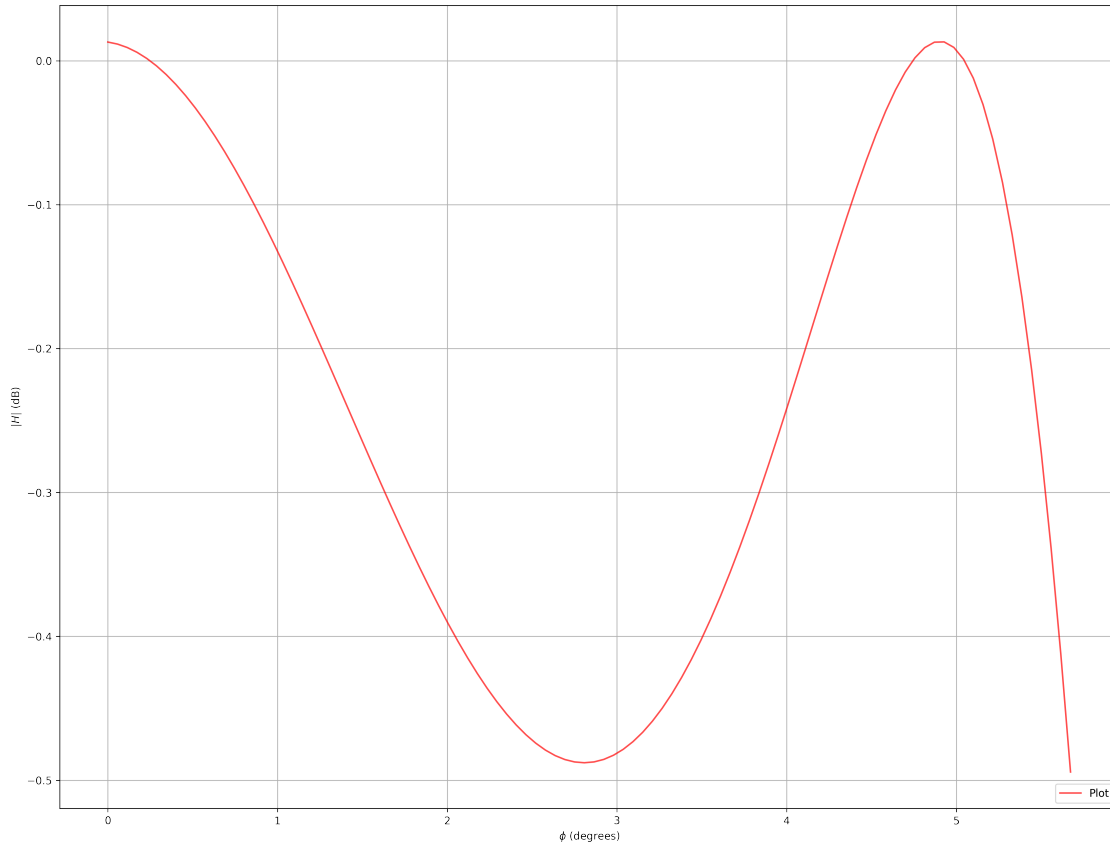
In [49]: T = 0.1

```
phi = np.arange(0, 2 * np.pi, T / 100)
NN = len(phi)
H = []

for n in range(1, NN):
    z = np.exp(complex(0, phi[n]))
    s = (2 / T) * (z - 1) / (z + 1)
    H.append(0.716 / ((s + 0.626) * (s * s + 0.626 * s + 1.142)))

phi = np.multiply(180 / np.pi, phi[:-1])[:int(len(phi)/2)][:100]
H = np.multiply(20, np.log10(H[:len(phi)]))[:100]

create_plot([phi], [(H, )], ["$\phi$ (degrees)", "$|H|$ (dB)"])
```



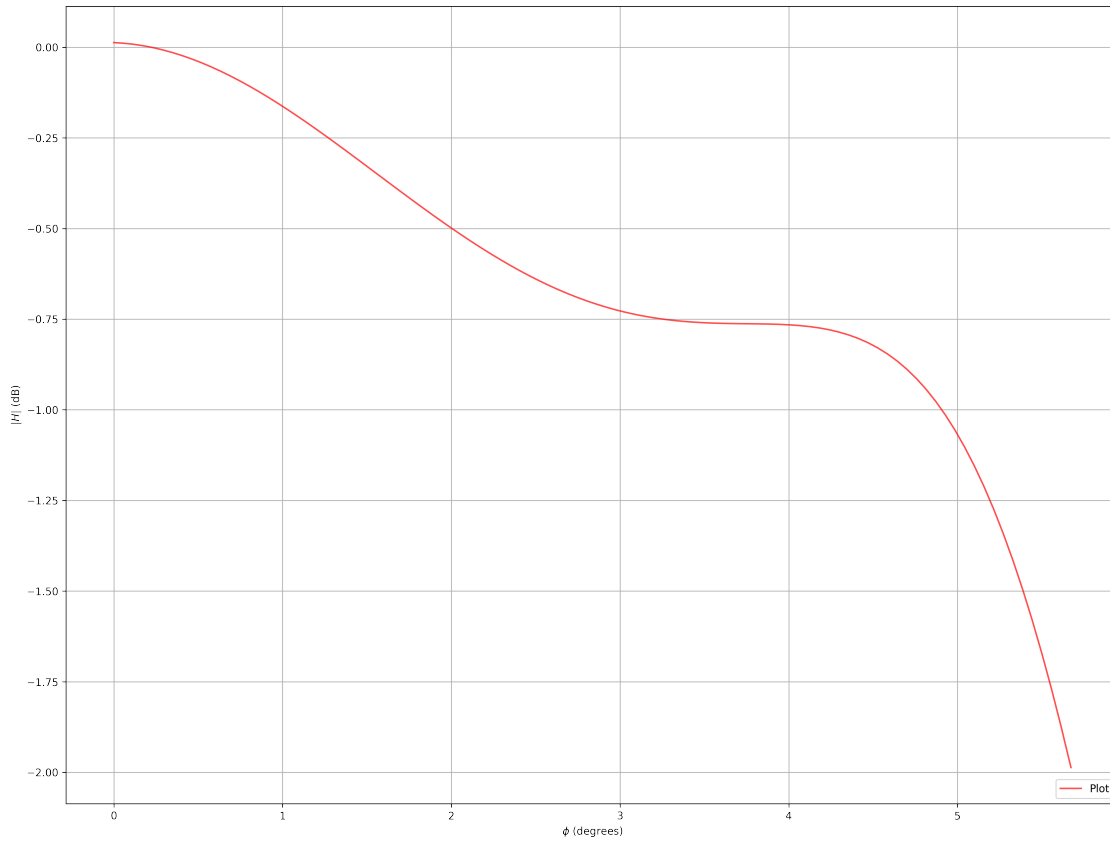
In [48]:  $T = 0.1$

```
phi = np.arange(0, 2 * np.pi, T / 100)
NN = len(phi)
H = []

for n in range(1, NN):
    z = np.exp(complex(0, phi[n]))
    s = (1 - 1 / z) / T
    H.append(0.716 / ((s + 0.626) * (s * s + 0.626 * s + 1.142)))

phi = np.multiply(180 / np.pi, phi[: -1])[:int(len(phi)/2)][:100]
H = np.multiply(20, np.log10(H[:len(phi)]))[:100]

create_plot([phi], [(H, )], [" $\phi$  (degrees)"], [" $|H|$  (dB)"])
```



As can be seen, the backward rectangular approximation does not meet the specification of the starting 3rd order Chevy-chase filter. The approximated  $H(z)$  is drastically different.