

①③ objective function \mathcal{L}

$$\begin{aligned}\mathcal{L}(a, b, e, f, \mu, \Sigma) = & \mathbb{E} \{ \ln p(\gamma) \} + \mathbb{E} \{ \ln p(w | \alpha_1, \dots, \alpha_d) \} \\ & + \sum_{k=1}^d \mathbb{E} \{ \ln p(\alpha_k) \} + \sum_{i=1}^N \mathbb{E} \{ \ln p(y_i | x_i, w, \gamma) \} \\ & - \mathbb{E} \{ \ln q(\gamma) \} - \mathbb{E} \{ \ln q(w) \} - \sum_{k=1}^d \mathbb{E} \{ \ln q(\alpha_k) \}\end{aligned}$$

$$\begin{aligned}\mathbb{E} \{ \ln p(\gamma) \} &= e_0 \ln f_0 - \ln \Gamma(e_0) + (e_0 - 1) \underbrace{\frac{\mathbb{E} \{ \ln \gamma \}}{\text{entropy}}} - f_0 \mathbb{E} \{ \gamma \} \\ &= e_0 \ln f_0 - \ln \Gamma(e_0) + (e_0 - 1) [\Psi(e_0) - \ln(f_0)] - f_0 \frac{e_1}{f_1}\end{aligned}$$

$$\begin{aligned}\mathbb{E} \{ \ln p(w | \alpha_1, \dots, \alpha_d) \} &= -\frac{d}{2} \ln 2\pi + \frac{1}{2} \sum_{k=1}^d \mathbb{E} \{ \ln \alpha_k \} - \frac{1}{2} \text{trace}(\text{diag}[\mathbb{E}(\alpha_1), \dots, \mathbb{E}(\alpha_d)] (ww^T)) \\ &= -\frac{d}{2} \ln 2\pi + \frac{1}{2} \sum_{k=1}^d [\Psi(a_{1,k}) - \ln(b_{1,k})] - \frac{1}{2} \text{trace} \left(\frac{a_{11}}{b_{11}}, \dots, \frac{a_{dd}}{b_{dd}} \right) (\xi + \mu \mu^T)\end{aligned}$$

$$\mathbb{E} \{ \ln p(\alpha_k) \} = a_{0,k} \ln b_{0,k} - \ln \Gamma(a_{0,k}) + (a_{0,k} - 1) [\Psi(a_{1,k}) - \ln(b_{1,k})] - b_{0,k} \frac{a_{1,k}}{b_{1,k}}$$

$$\begin{aligned}\mathbb{E} \{ \ln p(y_i | x_i, w, \gamma) \} &= -\frac{1}{2} \ln(2\pi) + \frac{\mathbb{E} \{ \ln \gamma \}}{2} - \frac{\mathbb{E} \{ \gamma \}}{2} \mathbb{E} \left\{ \sum_{i=1}^N (y_i - x_i^T w)^2 \right\} \\ &= -\frac{1}{2} \ln(2\pi) + \frac{1}{2} [\Psi(e_1) - \ln(f_1)] - \frac{1}{2} \frac{e_1}{f_1} \left(\sum_{i=1}^N (y_i - x_i^T w)^2 + x_i^T \Sigma x_i \right)\end{aligned}$$

$$\mathbb{E} \{ \ln q(\gamma) \} = e_1 \ln f_1 + \ln \Gamma(e_1) + (1 - e_1) \Psi(e_1)$$

$$\mathbb{E} \{ \ln q(w) \} = \frac{N}{2} + \frac{N}{2} \ln(2\pi) + \frac{1}{2} \ln \Sigma$$

$$\mathbb{E} \{ \ln q(\alpha_k) \} = a_{1,k} \ln b_{1,k} + \ln \Gamma(a_{1,k}) + (1 - a_{1,k}) \Psi(a_{1,k})$$

Plugging in these values to the equation above we get the objective. □