Reproducing Performance of Data-Centric Python by SCC Team from National Tsing Hua University

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***Abstract*—As part of the Student Cluster Competition at the SC22 conference, this work aims to reproduce the performance evaluations of the Data Centric (DaCe) Python framework by leveraging Intel MKL and NVIDIA CUDA interface. The evaluations are conducted on a single CPU-based node, NVIDIA A100 GPUs, and a eight-node cloud supercomputer. Our experimental results successfully reproduce the performance evaluations on our cluster. Additionally, we provide insightful analysis and propose effective methods for achieving higher performance when utilizing DaCe as an acceleration library.**

***Index Terms*—Student Cluster Competition, Parallel Computing, Reproducibility**

I. Introduction

PYthon has become one of the most widely used languages [1] for scientific code. Its popularity is attributed to the availability of numerous frameworks based on NumPy [2], such as SciPy [3], scikit-learn [4], and pandas [5], which make writing Python code easier. These frameworks are extensively employed by developers and users in scientific simulation [6], [7] and machine learning [8], [9] domains. However, existing Python libraries for high-performance computing (HPC) lack simultaneous support for the three Ps [1], [10]: Productivity, Portability, and Performance.

To bridge this gap, the Data-Centric (DaCe) Python framework [1] is proposed. DaCe offers several advantages. Firstly, it allows users to integrate it into existing programs using annotating statements, enhancing productivity. Secondly, DaCe provides compatibility with various computing backends, including CPUs, GPUs, FPGAs, and distributed computing, ensuring portability. Lastly, DaCe demonstrates significant performance improvements compared to state-of-the-art libraries. DaCe identifies data parallelism and data reusing patterns in dataflows, optimizing them and converting Python functions to C code. The resulting code can be compiled to run efficiently on CPUs, GPUs, or FPGAs.

In this work, as part of the Student Cluster Competition (SCC) at the SC22 conference, we aim to reproduce the performance evaluations of DaCe on CPUs, GPUs, and multi-node supercomputers. Our cluster includes state-of-the-art CPUs and GPUs. Despite running on different architectures (Intel Xeon 6130 CPU and NVIDIA V100 GPU in [1]), our results successfully reproduce the evaluation work presented by the authors [1]. The contributions of this paper are as follows: ① We reproduced the CPU experiments on NumPy and DaCe. ② We reproduced the DaCe GPU experiments against NumPy. ③ We reproduced the distributed experiments with the scale of at most eight nodes. ④ We provide a comprehensive analysis of the benchmarks to explain how DaCe achieves performance enhancements.

The remainder of the paper is organized as follows: Section II presents the hardware and software configurations used in the experiments. Section III describes the experimental procedures. Sections IV, V, and VI evaluate the experiments. Finally, Section VII concludes the paper.

TABLE I
THE HARDWARE CONFIGURATION OF OUR TESTBED

Type	Our GPU cluster	Azure Cloud HC
Number of nodes	2	8
CPU model	AMC EPYC 7763	Intel Xeon Platinum 8168
CPU architecture	Milan	Skylake
CPU frequency	2.45GHz	3.4 GHz
Cores per CPU	64	22
Number of CPU per node	2	2
L1d/i cache per core	32 KiB	32 KiB
L2 cache per core	512KiB	1 MiB
L3 cache	256 MiB	33 MiB
GPU model	NVIDIA A100*4	-
Interconnection bandwidth	200 Gb/s	100 Gb/s
Operating system environment	Bare-metal	Virtual machine
Experiments performed	GPU	CPU and distributed

II. Experimental Setup

A. Hardware configuration

Our experimental environment consists of two GPU nodes and a eight-node Azure cluster (HB44rs). Table I summarizes the hardware configurations used in our experiments.

The GPU cluster comprises two QuantaGrid D43N-3U nodes. Each node is equipped with two AMD EPYC "Milan" 7763 64-core processors, with hyperthreading enabled, resulting in a total of 128 cores per node. Each node has 512GB of memory and 3.84TB of NVMe storage. The cluster is equipped with two network connections: an InfiniBand capable

Fu-Chiang Chang and En-Ming Huang contributed equally to this work as first authors. They designed the study methodology, performed the experiments, analyzed the results, and drafted the paper. Pin-Yi Kuo, Chan-Yu Mou, Hsu-Tzu Ting and Pang-Ning Wu are the team members helped to review the text and provided comments for improving the articles. Jerry Chou is the corresponding author and team advisor who guided the team to compete this study and writing. All authors approve of the content of the manuscript and agree to be held accountable for the work.

TABLE II
THE SOFTWARE STACK CONFIGURATION OF OUR ENVIRONMENTS

OS & Libraries	Version
Operating system	Ubuntu 20.04
C Compiler & MPI	Intel oneAPI 2022.3.0
Intel ICC Compiler	20220726
GPU Compiler	CUDA 11.3 & gcc 9.4
DaCe	Commit with SHA 82314d8
NPBench	Commit with SHA 6fcd180

of transmitting at 200Gbps and a ConnectX-6 Ethernet for system control utilities.

The Azure cluster consists of up to 10 HB44rs instances. Each instance provides two Intel Xeon Platinum 8168 CPUs and has 352GB of memory. It should be noted that although the Intel CPU consists of 24 cores in a socket, the Azure platform only provide 22 virtual CPU cores. The cluster is connected using Mellanox EDR InfiniBand with a speed of 100Gbps in a fat tree topology.

B. Software Configuration

Table II lists the software installed on both the local cluster and cloud instances. We used the DaCe version released on September 26, 2022, with the commit SHA `82314d8` from the GitHub repository. The benchmarks we selected are downloaded from the NPBench GitHub repository. In our experiments, we employed the Intel oneAPI Math Kernel Library (MKL) for improved performance with NumPy, as also mentioned in the original work [1].

III. Description of Experimental Run

The benchmark applications used in our experiments were downloaded from the NPBench repository on GitHub. We evaluated all benchmarks using the "paper" dataset. For certain benchmarks (e.g., `syrk`), we made modifications to improve performance by annotating loops with `dace.map` to eliminate data dependencies across iterations. Please note that due to the potential bugs within DaCe, some benchmarks could not be compiled with NVCC when using the GPU as the backend.

To achieve better performance, we switched the C compiler from GCC to Intel ICC (included in oneAPI). Additionally, we analyzed the performance of AMD CPUs on our GPU node. However, the Intel CPUs on Azure consistently outperformed the AMD CPUs for the CPU benchmarks. Despite leveraging the AMD compiler (AOCC) and optimizing libraries (AOCL), the Intel CPUs demonstrated superior performance. Therefore, we only conducted GPU experiments on our GPU cluster.

The methods used to employ DaCe, as presented in NPBench, are as follows:

1) Variables representing loop sizes (e.g., `dace.map`) and arrays should be converted to DaCe symbols using `dace.symbol`.
2) Functions optimized by DaCe should be decorated with `@dace.program`.
3) To parallelize loops in an OpenMP-style manner, the Python `range()` function should be replaced with the `dace.map` construct.

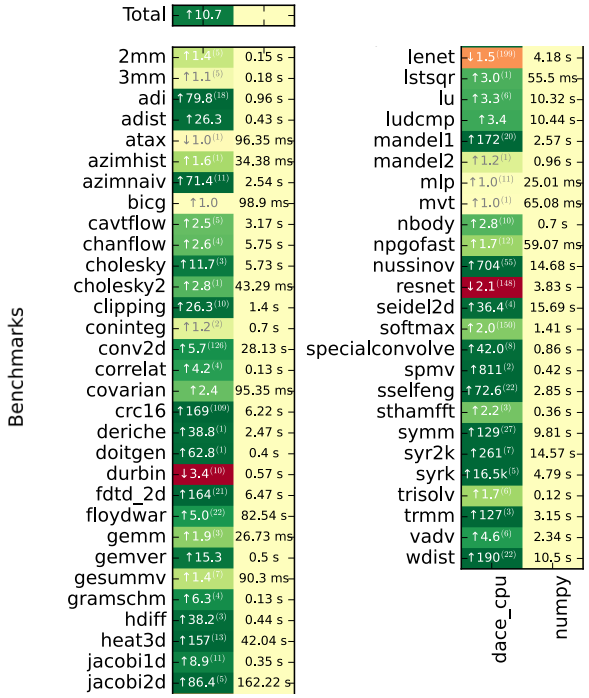

Fig. 1. Comparison of DaCe CPU Runtime to NumPy on CPU, showcasing speedup values for DaCe compared to NumPy. The first column number represent the speedup or slowdown factor of the DaCe run compared to the Numpy run. Performance improvements are highlighted in green and uparrows ↑, while performance degradation is indicated in red (or orange) and downarrows ↓ for each benchmark.

IV. CPU Results

We successfully reproduced a total of 56 CPU benchmarks on our Azure cluster, and the results are visualized in Figure 1. In general, DaCe's performance closely matches that reported in the original work [1]. Notably, in specific cases such as `heat3d`, `mandel1`, and `spmv`, DaCe demonstrates a remarkable performance improvement, achieving speedups of up to 100 times compared to NumPy. On the other hand, benchmarks like `atax`, `bicg`, and `durbin` do not exhibit such substantial enhancements.

Furthermore, this work includes a few additional benchmarks which were not included in [1], such as `lstsqr`, `specialconvolve`, and `wdist`. While the performance of these benchmarks is undocumented in the original work, our experimental results demonstrate that DaCe can indeed deliver performance improvements for these newly introduced benchmarks.

Benchmarks that experience significant speedup in DaCe typically involve operations performed on arrays, allowing DaCe to optimize them by leveraging OpenMP for parallel execution. Furthermore, applying the Stateful Dataflow multiGraphs [11] model to the calculations enables further optimization of the data flow, resulting in improved performance.

On the other hand, benchmarks such as `lenet`, `resnet`, and `durbin` are unable to benefit from the aforementioned optimizations for higher performance. The performance degradation observed in `lenet` and `resnet` is due to the representation of convolutions. The implementation of convolutions in

DaCe is translated into multiple atomic operations, resulting in decreased performance compared to other benchmarks. Such observations are also mentioned in the original work [1]. Regarding the `durbin` benchmark, the implementation utilizes `dace.map` to explicitly parallelize the `flip()` computation. Nontheless, in this specific case, the problem size is not sufficient to offset the overhead of parallelization. By explicitly configuring `OMP_NUM_THREADS` to 8, reducing the parallelism, DaCe can achieve a performance improvement of 2x compared to NumPy.

In the DaCe framework, parametric parallelism is supported to enable Python loops to be executed in parallel. There are two ways to take advantage of this feature. First, DaCe provides the LoopToMap transformation, which detects for-loops in the intermediate representation (IR) and uses symbolic affine expression analysis to validate the safety of parallel execution of iterations. Second, DaCe also offers explicit parallelism declaration through map scopes (`dace.map`), allowing programmers to identify data dependencies based on their knowledge.

Our reproduced results demonstrate that by replacing the Python built-in `range` iterator with `dace.map` in the `syrk` benchmark, the execution time can be significantly optimized, achieving a speedup of 16.5k times compared to NumPy and 30x faster than the original DaCe benchmark. This enhancement also extends to GPU performance. These findings highlight the importance of a programmer's effort in achieving optimal performance. If a programmer can accurately identify data dependencies, the benefits will be much greater than those achieved through the automatic LoopToMap transformation.

V. GPU Results

In this section, we present the evaluation results of 44 benchmarks conducted successfully on our GPU node. Figure 2 illustrates the performance comparison between DaCe and NumPy running on a single-node CPU. Notably, our experimental environment employs a more recent version of DaCe compared to the one referenced in the original work [1], enabling the execution of additional benchmarks on the GPU platform. The majority of our findings align with those reported in the original work [1]. For instance, benchmarks like `cholesky` and `ludcmp` exhibit slower performance on the GPU, while `clipping` and `heat3d` continue to demonstrate significant speedups of over 100x compared to NumPy. On the other hand, it is also important to note that the additional atomic operations introduced in `resnet` cause DaCe to perform more slowly on the GPU compared to NumPy. This issue is consistent with our observations in Section IV and is also documented in the original work [1].

In addition to observing similar results, we selected several benchmarks that exhibited either speedup or performance degradation to provide further analysis. Specifically, we analyze `cholesky`, `ludcmp`, `adist`, and `cholesky2`. The first two benchmarks demonstrate slower performance on the GPU, while the latter two show improved performance.

The reason behind the poorer performance of `cholesky` and `ludcmp` on the GPU is the communication and synchronization time between the CPU and GPU, which acts as a bottleneck. These benchmarks involve numerous scalar operations nested inside loops that cannot be parallelized. Since each scalar operation must be executed by a GPU kernel, significant communication overhead is introduced. Additionally, the problem size of each GPU kernel function is too small to effectively hide the communication overhead through computation.

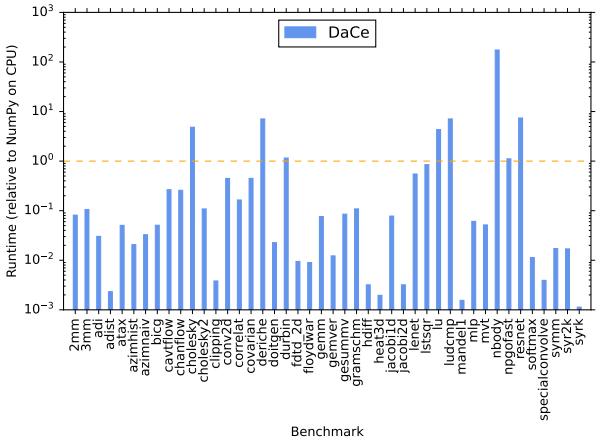

Fig. 2. DaCe GPU runtime normalized to NumPy on CPU (lower is better).

The benchmark `cholesky2` implements the same algorithm as `cholesky`, but it invokes the NumPy linear algebra function. DaCe recognizes this and ports it to the GPU by utilizing cuBLAS [12], the CUDA implementation of the Basic Linear Algebra Subprograms (BLAS) library. This optimization significantly improves the performance on the GPU.

Regarding the `adist` benchmark, we discovered that NumPy is unable to leverage Intel MKL and parallel processing for mathematical functions on arrays (e.g., `np.sin()`) [13]. However, DaCe is capable of exploiting data parallelism and dispatching computations on the GPU, leading to improved performance in this scenario.

VI. Distributed Results

We evaluated the scalability of DaCe on our Azure cluster due to smaller scale of the physical cluster used in the SCC. We choose the "hb44rs" instance type, which is equipped with the Intel CPUs. Despite AMD CPUs' prowess in highly scalable workloads, DaCe relies on Intel MKL-ScaLAPACK for distributed computations, and some ScaLAPACK optimizations are tailored to Intel-specific structures, which resulted in reduced performance on AMD CPUs.

Figure 3 illustrates our experimental results. Overall, our findings align with the original work. For instance, benchmarks that require minimal communication, such as `doitgen`, exhibit nearly perfect efficiency. However, we observed earlier degradation of parallel efficiency and significantly increased runtime variability in benchmarks with higher communication overhead. Notably, kernels like `atax`, `bicg`, `gemver`, `gesummv`, and `mvt`, responsible for matrix-vector products, exhibit optimal efficiency with 1 to 2 nodes but experience a rapid drop in efficiency when the scale exceeds 2 nodes.

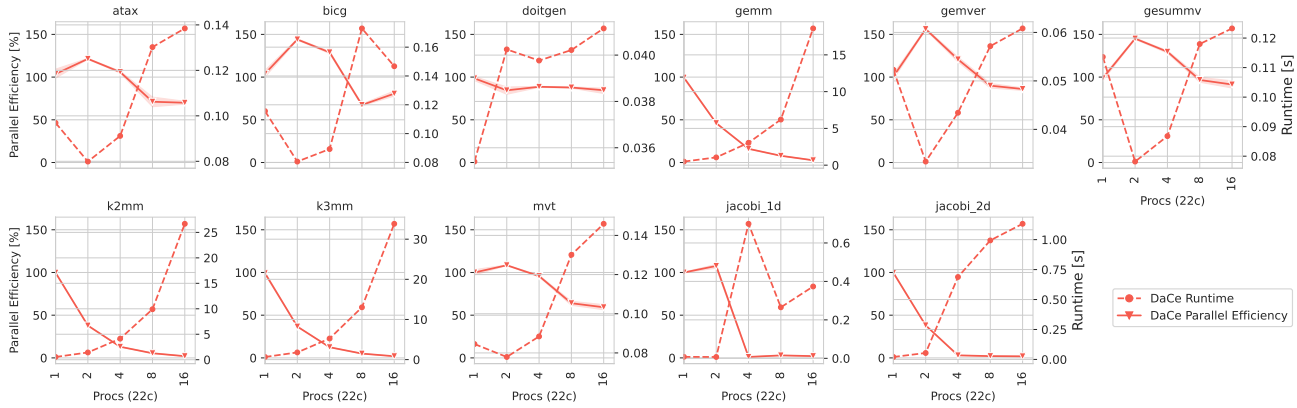

Fig. 3. Distributed performance of DaCe on the Azure Cycle Cloud. The X-axis represents the number of processes, where each process is assigned to a single CPU socket (22 CPU cores). The dashed lines represent the runtime, while the solid lines represent the scaling efficiency.

This performance variation is influenced by both CPU and interconnect differences. The Piz Daint supercomputer used by the authors employs the 'Aries' interconnect from Cray with a dragonfly network topology, while Azure instances use a fat-tree style. Additionally, our Azure environment runs within virtual machines, and the communication libraries within these virtual machines aren't as optimized as those on dedicated supercomputers. These factors contribute to the increased runtime variation compared to the original paper [1].

For the matrix-matrix product kernels, namely `gemm`, `k2mm`, and `k3mm`, the scalability is not ideal, which is an expected behavior of MKL-ScaLAPACK [14]. Such issues are also reported by the authors [1].

We reproduced the distributed experiments on our Azure cluster, providing insights into the scalability of DaCe. Despite observing efficiency degradation in certain scenarios, our results corroborate the original work and shed light on the behavior and limitations of MKL-ScaLAPACK in distributed computations.

VII. Conclusion

In this work, our reproducibility experiments on a single CPU node, a single GPU, and a multi-node distributed setup confirm the effectiveness of DaCe in enhancing application performance. We observed consistent improvements compared to the numpy library across various benchmarks. Additionally, we provided valuable insights into optimizing DaCe's performance.

By analyzing the experiments, we discovered important factors that impact DaCe's performance. Firstly, we found that excessive use of OpenMP threads for atomic operations in CPU benchmarks can lead to significant performance degradation. By determining the optimal number of OpenMP threads, we were able to mitigate this issue and improve overall performance. Secondly, we emphasized the critical role of identifying data dependencies. By annotating critical loops, we observed substantial speedup in certain benchmarks. Finally, in GPU computations, we highlighted the potential bottleneck of communication and synchronization between the CPU and GPU, especially in cases where benchmarks are not highly parallel or involve numerous scalar operations.

It is worth noting that the artifacts provided in [1] make it possible for others to conduct experiments on different architectures. However, one ongoing challenge in employing DaCe is deploying applications onto GPUs, as some benchmarks couldn't be successfully executed on the GPU. Further development to fully support GPUs would advance the maturity of the DaCe framework as an HPC library.

Overall, our reproducibility efforts not only validated the findings of the original work but also provided additional insights for optimizing DaCe's performance. These findings are valuable for researchers and practitioners seeking to leverage DaCe for high-performance computing, enabling them to make informed decisions and achieve better performance in their applications.

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A GAN-based Data Augmentation Framework for Federated Learning on Non-IID Data

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Federated Learning (FL) is a distributed learning technique that allows devices to collaboratively learn a shared prediction model while keeping all the training data locally and thus enable more secured and accurate model training. However, the convergence and accuracy of federated learning can be degraded by the non-IID (non independent and identically distributed) data across all edge devices. Hence, we proposed a **GAN**-based **D**ata **A**ugmentation **L**earning **F**ramework named ***GANDALF***, which aims to solve the non-IID problem by performing data augmentation with GAN models based on a mediator-based system architecture. Fault tolerance and data privacy mechanism are also provided to ensure system reliability and security. We conducted experiments to compare GANDALF with the traditional FedAvg and several other recently proposed data augmentation methods, and their top-1 test accuracy can be improved by 2.54% ~ 15.66% on CINIC-10 dataset and 2.85% ~14.8% on EMNIST dataset.

Additional Key Words and Phrases: Federated Learning, Generative Adversarial Network, Non-IID data, Differentail Privacy

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1 INTRODUCTION

With the vigorous development of deep learning (DL), DL has been used in many applications such as sign-to-speech translation [57], medical imaging [18], and self-driving cars [38]. Deep learning is a data-based technology; its current success is based on the centralized training method, which performs model training on the high-quality data collected in a single node or a data center. In recent years, the advancement of technology has caused a large amount of data to be generated in edge side. These distributed data are of great help to the development and quality of the deep learning model. However, as people gradually attach importance to the right to privacy, laws and policies are enforced to protect privacy, making it more difficult to collect available data. The dilemma of not obtaining a large amount of data leads to the failure of deep learning to achieve better performance. To address this challenge, a new learning technique called Federated Learning [39] is proposed, and it has drawn great attention to both academic and industry communities.

Federated Learning (FL) [39] is a distributed framework for deep learning without centralizing data and with privacy by default. FL allows clients to train a global model collaboratively while keeping private data local. During the training process, clients do not need to share their private

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data and only exchange the updated model with the FL server. FL can be divided into two settings according to the types of clients. The first one is cross-device, where clients are a large number of mobile or IoT devices, and the second one is cross-silo, where clients are different organizations or distributed datacenters. In reality, FL has been used in cross-device and cross-silo applications, such as improving word prediction [22], query suggestions of Google keyboard [51], and medical data segmentation [8]. In sum, this decentralized framework solves the problem of private data and provides economic benefits.

However, FL encounters several challenges with different deployment environments. The challenges of cross-device FL are mainly from the scalability [4], reliability [29], and heterogeneity of hardware [11] due to a large number of clients and limited computing resources of edge devices. By contrast, non-IID (non Independent and Identically Distributed) is a more significant challenge for cross-silo FL [26, 50] because the data each organization collects may differ a lot due to differences in geography, customer groups, and services of organizations. The non-IID problem means that the data in each local dataset fail to represent the global data, namely, the heterogeneity of local class distributions. Recent work [56] shows that highly skewed non-IID data can make the updated local model weights different from each other and reduce the accuracy of FL significantly. Another work [35] analyzed the convergence of FedAvg [39] on non-IID data and indicates that heterogeneity of data slows down the convergence of deep learning models.

Recently, several works focused on solving the non-IID problem. For example, [56] improves non-IID by establishing a subset of data that is shared between clients, but how to create a shared dataset is still an open question. Another way to address non-IID is performing active client selection in each round of FL to counterbalance the bias introduced by non-IID data, and [45] proposed a reinforcement-learning-based framework to achieve this goal. More intuitively, [12], [47], and [27] combine data augmentation, which is used to solve insufficient data and overfitting in centralized training, with their framework to handle the non-IID problem and further improve the accuracy. However, static data augmentation introduced by [12] only produces limited plausible alternative data, so it performs poorly in severe class distribution skews. Another work [27] requires clients to share data to obtain a well-trained GAN [19], which violates privacy. Thus, although many methods have been proposed, how to address the non-IID problem effectively is still an open question.

In this paper, we consider the non-IID problem and the additional requirements of preserving privacy, reducing the cost, being robust and reliable under the the cross-silo setting where clients can be local computers or powerful IoT devices installed in organizations for training. To solve the problem, we proposed ***GANDALF***, a **GAN**-based **D**ata **A**ugmentation **L**earning **F**ramework, which effectively solves the non-IID problem in FL and meets the requirement mentioned above.

In GANDALF, we solve the non-IID problem by performing data augmentation with multiple GAN models. Since insufficient data diversity of a single client does not limit GAN's data generation, GAN is more robust than other data augmentation methods. Also, we use mediator-based architecture combined with sequential training to speed up the convergence of the model and ensure the diversity of generated data, which helps GANDALF outperform other state-of-the-art GAN data augmentation methods. Furthermore, we prevent the model weights from leaking privacy and satisfy the strict differential privacy guarantee. Finally, We implement fault tolerance mechanisms in our framework to ensure training reliability over networks with unstable network connectivity.

Our approach is extensively evaluated using the CINIC-10 and EMNIST datasets, and the results are compared to the traditional FedAvg, three other recently proposed data augmentation methods [12], [56], and three GAN data augmentation methods [36, 48, 55]. The main results are summarized as follows.

- Comparing to the FedAvg and the two data augmentation methods without sharing local private data, GANDALF improved their top-1 test accuracy by 2.54% ~ 15.66% on CINIC-10 and 2.85% ~8.41% on EMNIST.
- Comparing to data augmentation method sharing partial local private data, GANDALF ensures strict data privacy while achieving comparable results for the top-1 test accuracy of +0.11% and -1.7% on CINIC-10 and EMNIST, respectively.
- Comparing to data augmentation methods using GAN models, GANDALF is able to train high quality GAN models in more flexible ways. GANDALF improved their top-1 test accuracy by 1.84%~2.41% on CINIC-10 and 2.89%~14.8% on EMNIST.
- A significant improvement on accuracy over 30% can be observed on n-class non-IID problems, which contain much higher data skewness.
- In a system environment with unpredictable node or network failures, our proposed fault tolerance mechanism can accelerate the training convergence speed up to 6× and 11× while improving the top-1 test accuracy results by 1.34% ~ 4.92%.

The rest of this paper is organized as follows. Section 2 defines the problem of FL with non-IID data and summarizes the objectives of the system design. Section 3 and 4 detail the design and implementation of *GANDALF*. Section 5 presents the evaluation results, along with the analysis. Related work is discussed in Section 6, and conclusions are given in Section 7.

2 PROBLEM DEFINITION

In this section, we first formally define the problem of federated learning and show the effect of non-IID data on federated learning. Then, in Section 2.2, we summarize the objectives of the system design and briefly explain how we achieve it.

2.1 Mathematical Preliminaries

In this subsection, we formally define the problem of federated learning with non-IID data. We consider a c class classification problem defined over a compact space $\mathcal{X}$ and a label space $\mathcal{Y} = [C]$, where $[C] = \{1...., C\}$. Let $\{x, y\}$ denote a labeled sample, which distributes over $\mathcal{X} \times \mathcal{Y}$ following the class distribution p. Let $f : \mathcal{X} \rightarrow \mathcal{S}$ denote the prediction function, where $\mathcal{S} = \{z \mid \sum_{i=1}^{C} z_i = 1, z_i \geq 0, \forall i \in [C]\}$. Let f_i denote the predicted probability that the sample belongs to the i-th class. Let ω denote the model weight. For training, we define the training loss with the commonly used cross-entropy loss as

$$L(\omega) = \mathbb{E}_{x,y\sim p}[\sum_{i=1}^{C} \mathbb{1}_{y=i} \log f_i(x, \omega)]$$
$$= \sum_{i=1}^{C} p(y = i)\mathbb{E}_{x|y=i}[\log f_i(x, \omega)]$$

We simplify the analysis by ignoring the generalization error. Therefore, the learning problem becomes the following optimization problem.

$$\min_{\omega} \sum_{i=1}^{C} p(y = i)\mathbb{E}_{x|y=i}[\log f_i(x, \omega)]$$

To solve the optimization problem, SGD updates the model weight iteratively to minimize the loss function. Let $\omega_t^{(c)}$ denote the weight after t-th update in the centralized learning and η denote

the learning rate. Next, centralized SGD performs the following update:

$$\begin{aligned}\omega_t^{(c)} &= \omega_{t-1}^{(c)} - \eta \nabla L(\omega_{t-1}^{(c)}) \\ &= \omega_{t-1}^{(c)} - \eta \sum_{i=1}^{C} p(y=i) \nabla \mathbb{E}_{x|y=i}[\log f_i(x, \omega_{t-1}^{(c)})]\end{aligned}$$

We regard $\omega^{(c)}$ as the optimal model weight because the performance of centralized learning is greater than or equal to that of federated learning [41].

In federated learning, we assume there are K clients in total. Let $n^{(k)}$ denote the amount of samples and $p^{(k)}$ denote the class distribution of local dataset of client $k \in [K]$. For local training, each client performs SGD to update the local model weight separately. At iteration t on client $k \in [K]$, local SGD performs the following update:

$$\begin{aligned}\omega_t^{(k)} &= \omega_{t-1}^{(k)} - \eta \nabla L(\omega_{t-1}^{(k)}) \\ &= \omega_{t-1}^{(k)} - \eta \sum_{i=1}^{C} p^{(k)}(y=i) \nabla \mathbb{E}_{x|y=i}[\log f_i(x, \omega_{t-1}^{(k)})]\end{aligned}$$

We assume the synchronization, that is, the server aggregates model weights from all K clients, is conducted every E local epochs, and let $\omega_{mE}^{(f)}$ denote the global model weight updated after the m-th synchronization. Finally, we have:

$$\omega_{mE}^{(f)} = \sum_{k=1}^{K} \frac{n^{(k)}}{\sum_{k=1}^{K} n^{(k)}} \omega_{mE}^{(k)}$$

Based on the analysis of non-IID derived by [56], weight divergence between $\omega_{mE}^{(c)}$ and $\omega_{mE}^{(f)}$ is affected by two factors. First, if the clients in FL starts from different initialization, regardless of whether the data is non-IID or not, a considerable weight divergence is still expected. Second, the class distribution difference between the local datasets and the total data $\sum_{i=1}^{C} ||p^{(k)}(y=i) - p(y=i)||$ is another reason for the weight divergence. It implies that the more non-IID the local datasets are, $\omega_{mE}^{(f)}$ is farther away from the optimal model weight $\omega_{mE}^{(c)}$, and it leads to degraded accuracy of federated learning. We assume all the clients start from the same initialization as the centralized learning, so the non-IID data is the root cause of degraded accuracy and is the problem we try to solve.

2.2 Objectives of system design

In this subsection, we summarize the objectives of the system design and describe how we achieve those objectives.

Accuracy. To solve the non-IID problem and further increase the top-1 test accuracy of the model that solves the main task, we replenish the lack of data in local datasets and deal with the bias of the model weights introduced by non-IID data. The above two steps make $\omega_{mE}^{(f)}$ be more close to the optimal model weight $\omega_{mE}^{(c)}$ through changing the class distribution of each client and model weights respectively.

Cost. Cost and time complexity are significant considerations for whether an algorithm can be applied in practice. To reduce the cost of solving the non-IID problem, we introduced the concept of parallelism. In addition, we design an algorithm that allows us to avoid generating unnecessary data to reduce computation and storage costs.

Robustness. Making our framework robustness is a critical objective. We hope that GANDALF can handle non-IID in different situations, even in highly skewed non-IID data. To achieve it, we

Table 1. Comparison of recently proposed data augmentation methods, where ✓ means the objective is well achieved. △ means the work considered the objective but can be improved. Finally, × means the objective was not considered or achieved by the work.

Objective	Privacy	Robustness	Reliability
GANDALF	✓	✓	✓
RFA-RFD [47]	△	✓	×
FAug [27]	△	✓	×
Astraea [12]	△	×	×
Fedmix [52]	×	×	×

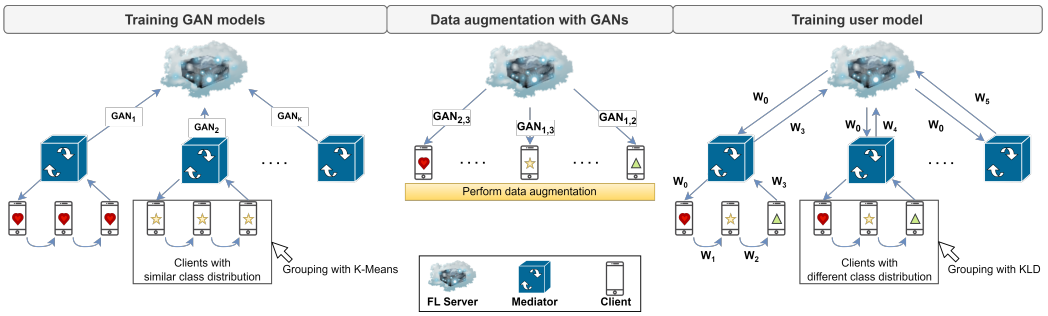


Fig. 1. The design of our proposed framework, *GANDALF*. The training process of our framework consists of three phases: training GAN models, data augmentation with GANs, and training user model.

introduce GAN, which offers valuable data for data augmentation and is more flexible than other data augmentation methods.

Reliability. Due to the unstable network connectivity of distributed systems, the training of FL is often interrupted, and a lot of overheads are caused. To handle it, we design several fault tolerance mechanisms which can avoid unavailable clients and stabilize the training process.

Privacy. Last but not least, privacy is essential for FL and also GANDALF. To provide a strict privacy guarantee in the whole process, we ensure that all private data are kept in the edge nodes while solving the non-IID problem. Furthermore, we introduce differential privacy with a Gaussian mechanism to make the model weights passed to each other leak less privacy.

3 FRAMEWORK DESIGN

In this section, we first discuss the design principles of our approach. Then the framework design and architecture of *GANDALF* are presented. Finally, we explain how reliability and security are ensured in *GANDALF*. The detail of our implementation is given in the next section.

3.1 Design Principals

Deep learning is a data-based technology. The gradient contributed by the clients with insufficient data or severe class distribution skews may cause the aggregated network to generalize poorly. One common method is performing data augmentation to replenish the target classes. However, existing data augmentation methods for solving the non-IID problem have some areas for improvement. As summarized in Table 1, our proposed framework has the advantage in privacy, robustness, and reliability, as discussed below.

Privacy. Astraea [12] performs static (Z-score-based) data augmentation with only local data and does not expose any sensitive information about private data. However, the server needs to know the probability distributions of clients, which could cause privacy leakage. In comparison, GANDALF does not expose clients' data and data distribution to other clients or the server. Fedmix [52] has the highest privacy vulnerability because it requires mashed (averaged) private data shared among clients, and the data leakage problem is only highly dependent on the number of data instances used in computing the average. FAug [27] uses the seed data samples uploaded and labeled by clients to train a global GAN model at the server for data augmentation. Also, FAug [27] attempts to reduce privacy leakage by adding noises to the uploaded data samples. In comparison, similar to RFA-RFD [47], GANDALF trains the augmentation generator locally at clients and only exchanges the generator model, not the data among clients. To provide a more strict privacy guarantee, GANDALF introduces differential privacy to ensure that the generated data and model weights passed between clients and the server do not leak privacy while FAug and RFA-RFD do not. The detail of the privacy guarantee is discussed in Section 3.5.

Robustness. To achieve robustness, we must ensure the quality and diversity of the augmented data. The static data augmentation (rotation, shift, flip, etc.) used by Astraea [12] and the mashed (averaged) data augmentation used by Fedmix [52] only produce limited plausible alternative data. Thus, they perform poorly in severe class distribution skews. In comparison, both the variational autoencoder (VAE) method used by RFA-RFD [47] and the GAN method used by FAug [27] and GANDALF can greatly improve the data quality with proven results [3, 16, 44, 58]. While the data quality of GAN is known to be better than VAE, GAN more easily suffers from the mode collapse problem, which limits the diversity of generated data. Hence, RFA-RFD [47] and FAug [27] address the problem by using conditional GAN/VAE, which can generate data for specific labels. On the other hand, we address this issue by training multiple generators for different classes of labels as described in Section 3.3. Therefore, RFA-RFD [47], FAug [27], and GANDALF can achieve robustness, while Astraea [12] and Fedmix [52] cannot.

Reliability. Even in the cross-silo environment, federated learning will still suffer from unstable network and node failure. Its instability often causes additional overhead and reduces the performance of DL models. If a framework does not consider reliability, it will not be applied in practice. To make GANDALF not only an algorithm but also a framework that can be applied in the real environment, we expect that GANDALF is reliable enough to exclude unavailable clients from participating in training and keep the system usually operating when clients disconnect arbitrarily. Although the previous works solved the non-IID problem with a well-designed algorithm, they all neglect the reliability discussion and analysis. In comparison, we implement some fault tolerance mechanisms to provide reliability as detailed in Section 3.4.

In sum, GANDALF solves the non-IID problem by performing data augmentation with multiple GAN models, ensuring the diversity of generated data. In addition, in the process, GANDALF keeps private data local and introduces differential privacy to ensure that the model weight and generated data do not leak privacy. Finally, We have implemented GANDALF that can work in a real environment and designed several fault tolerance mechanisms to ensure its reliability while other works do not. Therefore, we believe that GANDALF is a better solution for performing FL on non-IID data with enhanced security and reliability for practical uses.

3.2 Framework Overview

The overview of the proposed framework is shown in Fig. 1. This framework consists of three phases: Training GAN models, Data augmentation with GANs, and Training user model. In addition, our framework also introduces the mediator-based architecture, which brings optimizations and

reduces overhead. The detail of the framework and mediator-based architecture are discussed below.

Training GAN models. In this phase, we train multiple GAN models. At first, the clients with similar class distribution are grouped into the same group based on a clustering algorithm, and each group will be assigned a mediator. Next, each group trains a GAN model independently in parallel. In each group, the GAN model weight is passed between the clients and updated sequentially until it converges. Mediators in this phase are responsible for scheduling the training process of each group and returning the converged GAN model to the server.

Data augmentation with GANs. In this phase, each client performs data augmentation with GAN models. After the first phase, the server already has multiple trained GAN models. Next, the server sends the appropriate GAN models to each client according to its class distribution. Then, each client performs data augmentation with received GAN models to replenish the minority classes. Considering the computation cost of data generation and randomness of GAN data augmentation, we design an algorithm used to calculate the amount of data that each received GAN model should generate to minimize the computation cost. Furthermore, we also combine GAN data augmentation with static data augmentation to handle the randomness of GAN data augmentation. The detail of this algorithm is shown in section. 4.2.

Training user model. We train the model which solves the main task here. At first, we perform grouping, which makes the class distribution of each group as close to uniform as possible. Then each group will be assigned a mediator. Next, the server initializes the global model and broadcasts it to all mediators. After that, each group updates the received model weight independently in parallel. In each group, the model weight is passed between the clients and updated sequentially. Finally, the server aggregates the updated model weight of all mediators, performs weighted FedAvg, and updates the global model. Then the server broadcast the global model to all mediators again to start the next round of training. After several training rounds, we get a well-trained model at the end.

3.3 Mediator-based architecture

Mediator-based architecture brings two significant optimizations. One is handling the problem of mode collapse where the generator only concentrates on generating data lying on a few modes instead of the entire data space; namely, the diversity of generated data is insufficient. GANDALF trains a set of GAN models in parallel through the mediator-based architecture. It uses different collections of local datasets for training to encourage the generators to specialize in different data modes. That is why we perform grouping, which groups clients with similar class distribution into the same group in the first phase. A similar approach is also used by [24], [17]. With this optimization, we ensure the diversity of generated data. Compared with training a single GAN model for data augmentation [27], GANDALF can better balance local datasets. We will show this in Section 5.2

The second optimization is sequential training, where each client performs local training and updates the model sequentially. In addition to accelerating model convergence [28], sequential training can also counterbalance the bias of model weight introduced by non-IID data [12]. However, the communication overhead and time overhead of sequential training are K times that of FedAvg, where K is the number of clients. With mediator-based architecture, we significantly reduce the overhead by performing grouping and making each group perform sequential training parallelly under the coordination of the mediators. Hence, the overhead reduces to $\frac{K}{M}$ times, where M is the number of mediators. Thus, with this optimization, we accelerate the convergence of the models and reduce the time overhead of training. Furthermore, in the third phase, to better counterbalance the bias introduced by non-IID data instead of accumulating it, we make each group's class distribution

as close to uniform as possible. We will show the advantage brought by sequential training in Section 5.2.

3.4 Fault Tolerance

In reality, the clients may not complete the local training task within the time limit due to network issues, hardware limitations, and node failures. The common solution for reliability-agnostic clients is to define a maximum waiting time threshold T_R, discard clients that cannot complete the task in time and aggregate only for clients who successfully return the result. The difficulty of this solution lies in the choice of T_R. If T_R is too large, it will lead to spending too much time waiting for a few clients, and the training process will become inefficient. On the other hand, if T_R is too small, the server may miss too many clients that contribute generously to the global model, resulting in adverse effects on accuracy and model convergence. The mediator-based architecture also faces the same problem in such an unstable environment. To solve it, we design three fault tolerance mechanisms to ensure reliability and further reduce the time and communication overhead.

Training Order. For mediator-based architecture, the fail of local training tasks aggravates the weight divergence and cancels out the improvement brought by sequential training mentioned in Section. 3.3. In order to make each client's contribution to the global model more evenly in each round, we let each mediator determine the training order of the corresponding group based on a maintained table, which records the number of times each client completes a local training task. Whenever we need to decide which the next client is, the mediator prioritizes the clients based on the maintained table, and those less involved in training are given higher priority. On the other hand, to avoid client selection bias, we set an upper limit for the number of times each client is selected in a round and a minimum interval between two tasks for each client. Moreover, smaller T_R is allowed in our approach because we reduce the cost of missing a client by iteratively confirming the level of each client's contribution and re-balancing it. In short, we use shorter waiting time intervals to minimize the time overhead from the possible failed clients while avoiding the bias of model weight caused by the frequently selected clients.

Heartbeat. After a client is selected, its local training process still may not be complete due to node failure or degraded performance. To overcome this issue, our framework introduces the heartbeat message, a periodic signal generated by the client holding the model weight. If the mediator does not receive a heartbeat for a certain period, we assume the client is unavailable and perform a rollback to resume training as detailed next.

Rollback. As described in Section 3.2, the model weight is passed between clients without going through the mediator to avoid performance bottleneck. Hence, when the client holding the latest model weight becomes unavailable, we let the mediator perform the rollback mechanism to resume the training processing from the available client having the latest model weight. The rollback mechanism consists of the following steps. First, the mediator decides which is the next client to perform training. Then, the mediator requests the previous client that completed training to send the model weight to the next one. If the previous client is unavailable, the mediator asks the one before the previous instead until an available client is found.

3.5 Data Privacy

To provide a strict privacy guarantee on the model weight and generated data, we combine differential privacy(DP) with our framework. We formally define DP as follows,

Definition 1. *(ϵ, δ)-DP [14]. A randomized algorithm $\mathcal{M}$ with domain $\mathcal{X}$ is (ϵ, δ)-differential private if for all $\mathcal{S} \subseteq Range(\mathcal{M})$ and for all adjacent databases $x, y \in \mathcal{X}$,*

$$Pr[\mathcal{M}(x) \in \mathcal{S}] \leq e^{\epsilon} Pr[\mathcal{M}(y) \in \mathcal{S}] + \delta \tag{1}$$

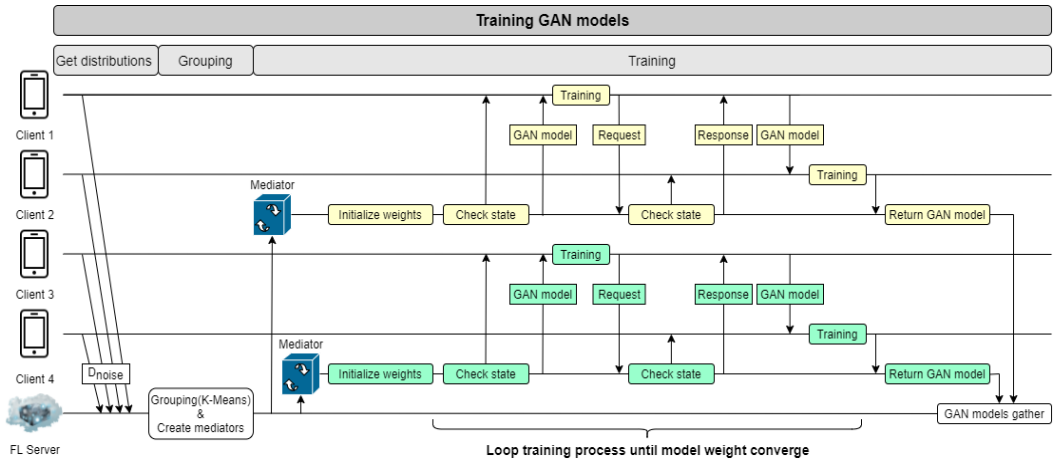


Fig. 2. Workflow of training GAN models for data augmentation.

According to [14], a Gaussian mechanism can be used to guarantee (ϵ, δ)-DP. We present this as follows,

Theorem 1. *The given noise* $n \sim \mathcal{N}(0, \sigma^2)$ *satisfies* (ϵ, δ)*-DP if the parameter* $\sigma \geq c\Delta s/\epsilon$*, and the constant* $c \geq \sqrt{2ln(1.25/\epsilon)}$ *for* $\epsilon \in (0, 1)$*, where* $\Delta s = max_{x,y}||\mathcal{M}(x) - \mathcal{M}(y)||$*, which is the sensitivity of the algorithm* $\mathcal{M}$

We achieve differential privacy by adding Gaussian noise satisfying Theorem. 1 to the model weights and other private information such as class distribution. In the first and third phases, clients always add noise to the model weight before passing it to another.

Finally, according to [14], DP not only protects the model weight from violating privacy but also the generated data. We provide proof in Theorem 2 below.

Definition 2. *Post-processing property of DP [14]. Let a randomized algorithm* $\mathcal{M}$ *be* (ϵ, δ)*-differential private, and let* F *be any deterministic or randomized function. Then* $F(\mathcal{M})$ *also satisfies* (ϵ, δ)*-differential privacy.*

Theorem 2. *The output of a generator guarantees* (ϵ, δ)*-differential privacy.*

Proof. According to Theorem. 1, the discriminator and the generator trained in each client has satisfied DP, and with the Definition. 2, the data generated by the generator also satisfies DP.

Although differential privacy provides adequate protection for privacy without expensive computational cost, it affects the model's performance. We will show the trade-off between privacy and accuracy in section 5.2.

4 IMPLEMENTATION DETAILS

In this section, we explain the detailed workflow implementation of the three phases mentioned in Section. 3.

4.1 Training GAN Models

As shown in Fig. 2 and Algorithm. 1, we train multiple GAN models for data augmentation in this phase. First, to determine the clients participating in the training and obtain the class distributions used to perform grouping, each client needs to join the training task by uploading its

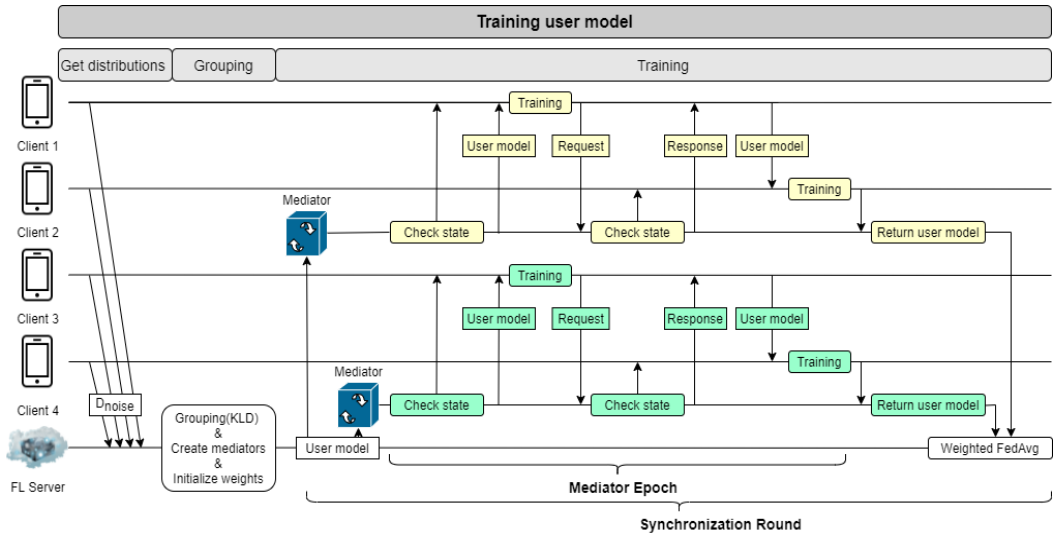


Fig. 3. Workflow of training the user model based on FedAvg algorithm.

Algorithm 1 Training WGAN with gradient penalty based on FL

Input: s_g, sensitivity of generator model weight. s_d, sensitivity of discriminator model weight. T_d, number of discriminator iterations per generator iteration. T_g, generator iteration. σ_n, noise scale. λ, penalty coefficient. M_g, number of mediators. b, batch size.

Output: M_g GAN models

for each mediator m in $m = 1, ..., M_g$ parallelly **do**
  Initialize : weights of discriminator ω, weights of generator θ
  while θ has not converged **do**
    Take out a client from mediator m
    for t_g = 1,...,T_g **do**
      for t_d = 1,...,T_d **do**
        for i = 1,...,b **do**
          Sample real data $x \sim P_r$, latent variable $z \sim p(z)$, a random number $\gamma \sim U[0, 1]$
          $\tilde{x} \leftarrow G_\theta(z)$
          $\hat{x} \leftarrow \gamma x + (1 - \gamma)\tilde{x}$
          $g \leftarrow \lambda(||\nabla_{\hat{x}} D_\omega(\hat{x})||_2 - 1)^2$
          $L^{(i)} \leftarrow D_\omega(\tilde{x}) - D_\omega(x) + g$
        $\omega \leftarrow Adam(\nabla_\omega \frac{1}{b} \sum_{i=1}^{b} L^i, \omega, \alpha_d)$
      Sample a batch of variables$\{z_i\}_{i=1}^{b} \sim p(z)$
      $\theta \leftarrow Adam(\nabla_\theta \frac{1}{b} \sum_{i=1}^{b} -D_\omega(G_\theta(z)), \theta, \alpha_g)$
    $\theta \leftarrow \theta + N(0, (\sigma_n s_g)^2 I)$
    $\omega \leftarrow \omega + N(0, (\sigma_n s_d)^2 I)$
  Send θ to server

Algorithm 2 Grouping with K-Means

Input: M_g, number of mediators. $iter$, termination condition of $K\text{-}Means$.
Output: $S_{mediator}$, result of grouping.
1: $Initialize : S_{mediator} \leftarrow \emptyset, S_{km} \leftarrow \emptyset, P \leftarrow P_1, ..., P_K$.
2: **repeat**
3: $S_{km} \leftarrow K\text{-}Means(P, M_g, iter)$.
4: **until** sensitivity of $S_{km} < M_g$
5: **for** each set s in S_{km} **do**
6: Create mediator m
7: **for** each client c in s **do**
8: Mediator m add client c
9: $S_{mediator} \cup m$

class distribution with Gaussian noise to the FL server. After all clients join, the server performs grouping, which groups clients with similar class distribution into the same group to solve the mode collapse problem. The policy of grouping is shown in Algorithm. 2. This algorithm is based on K-Means, a clustering algorithm, and P is the input of K-Means, where P means the class distributions of all clients. Because K-Means can not guarantee that the number of clients in each group is close, leading to an increase in time overhead, we execute K-Means a few times until the difference in the number of clients each mediator has is less than M_g (Algorithm. 2, line 2). Once grouping finish, we create M_g mediators, which are responsible for scheduling the training process of the groups (Algorithm. 2, line 5).

As mentioned in Section. 3.3, to solve the mode collapse problem, we use different collections of local datasets to train a set of GAN models. In the implementation, we achieve the goal by making each mediator train a GAN model with the data in its group independently. The process is as follows. First, each mediator initializes the model weight respectively and decides on a subordinate client performing local training (Algorithm. 1, line 4). Then the mediator sends it to the chosen client. Next, the client holding model weight performs training with local data. In local training (Algorithm. 1, line 5), the generator is updated after the discriminator is trained T_d times, and the generator is updated T_g times. Finally, at the end of local training, the client adds Gaussian noise with noise scale σ_n to the model weight to satisfy the differential privacy (Algorithm. 1, line 16, 17).

After local training, the model weight will be passed to the next client. As mentioned in Section. 3.4, the training order is determined by the mediator to avoid additional time overhead caused by unavailable clients. First, the client requests the mediator to obtain information about the next client (Fig. 2, Request). After that, the mediator decides which next client is and sends the information about the next one to the client, which sends a request. Finally, the model weight is passed to the next client. Then the model weight is continuously updated and given between clients until the model converges. We judge whether the model converges mainly based on whether the loss change of the generator and discriminator tends to be flat. Once the model converges, the mediator lets the client holding the model weight return the model to the mediator. Finally, the mediator returns it to the server.

4.2 Data Augmentation with GANs

After the first phase, the server has M_g GAN models. Given communication overhead, it is unreasonable to send all the GAN models to each client. Instead, the server determines which GAN models a client needs based on its class distribution. We assume that the training of each GAN model goes well, the class distribution of data generated by the GAN model is the same as that

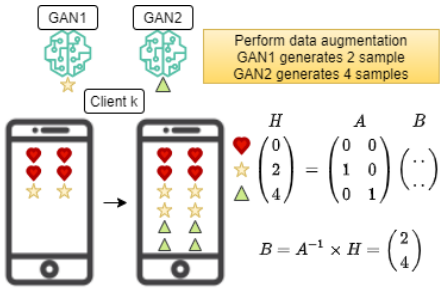


Fig. 4. Example of GAN data augmentation. A client k with 4 hearts and 2 stars receives two GAN models that focus on generating stars and triangles, respectively. H means how many samples of each class this client lacks to reach uniform distribution. A means the class distributions of received GAN models, namely the first and second columns of A represent the class distribution of GAN1 and GAN2, respectively. Finally, B, the target matrix, means how much data each GAN should generate. After calculation, we obtain $B = [2, 4]$, which implies that GAN1 and GAN2 should generate 2 and 4 samples, respectively.

of the training dataset. Then we calculate the Kullback–Leibler divergence (KLD) between GAN models and the client. The larger the value, the more likely the GAN model generates the data that the client lacks. After calculation, the server sends J GAN models to each client respectively, where $J \leq M_g$.

Given that using GAN models to generate data has randomness and brings computation costs, we design an algorithm used to calculate how many samples each GAN model should generate theoretically for a client to achieve the best balance and the least computation costs. As shown by the example in Fig. 4 and the algorithm is described as follows. First, we simplify the problem to a matrix multiplication problem. To do so, we express H as the product of two matrices: $H = AB$, where $A \in \mathbb{R}^{C \times J}$, $B \in \mathbb{R}^{J \times 1}$, C is the number of classes, and J is the number of GAN models the client receives. The matrix A means the class distribution of J GAN models, the matrix B means how many samples each GAN model should generate, and matrix H means how many samples of each class this client lacks to reach uniform distribution. A and H can be obtained from the server and its dataset, and B is the target we need to calculate. Finally, We obtain B by calculating the pseudo inverse matrix of A and basic matrix multiplication operations.

Zhao *et al.*[56] shows that when the data become less non-IID to a certain degree, its decrease does not bring a significant improvement to the accuracy. In other words, we do not need to generate many samples to reach the uniform distribution. Based on the observation, We finally multiply matrix B by τ, where $\tau \in (0, 1]$. τ indicates the degree of balancing. Taking Fig. 4 as an example, if $\tau = 0.5$, the matrix B becomes [1,2], which implies that the client only needs to generate half of the number of data. As a result, the computation and storage cost can be reduced, but the degree of data balancing also decreases. Thus, τ is a parameter for adjusting the trade-off between accuracy and cost, and its impact is evaluated by our experiments in Section. 5.2.

Because the data augmentation with GANs has randomness, the actual class distribution of generated data is usually not as expected. So, finally, we make some adjustments to the local dataset and the generated data. If the amount of data actually generated is more than theoretically generated, we delete the redundant generated data for each class. Otherwise, we use static data augmentation to generate at most twice the amount of source data to make up for the gap.

Algorithm 3 Hierarchical distributed neural network training

Input: s_c, sensitivity of model weight. M_c, number of mediators. E_m, number of mediator epoch. E, number of local epoch. η, learning rate. σ_n, noise scale.
Output: A trained user model.

1: $Initialize : \omega_1$
2: **for** each synchronization round $r = 1, ..., R$ **do**
3: **for** each mediator m in $1, ..., M_c$ parallelly **do**
4: $\omega^* \leftarrow \omega_r$
5: **for** each mediator epoch $e_m = 1, ..., E_m$ **do**
6: **for** each available client i in mediator m **do**
7: **for** each local epoch $e = 1, ...E$ **do**
8: $\omega_r \leftarrow \omega_r - \eta \nabla L(\omega; \mathbb{X}^{(i)}, \mathbb{Y}^{(i)})$
9: $\omega_r \leftarrow \omega_r + N(0, (\sigma_n s_c)^2 I)$
10: $\Delta\omega^m_{r+1} \leftarrow \omega_r - \omega^*$
11: $\omega_{r+1} \leftarrow \omega_r - \sum_{m=1}^{M_c} \frac{n_m}{n} \Delta\omega^m_{r+1}$

Algorithm 4 Grouping with KLD,D_{KL} is Kullback-Leibler divergence

Input: M_c, number of mediators.
Output: $S_{mediator}$, result of grouping

1: $Initialize : S_{mediator} \leftarrow \emptyset, S_{client} \leftarrow 1, ...K$
2: **while** S_{client} is not $\emptyset$ **do**
3: Create mediator m
4: **while** S_{client} is not $\emptyset$ and $|m| < \lceil \frac{K}{M_c} \rceil$ **do**
5: $c \leftarrow argmin_i D_{KL}(P_m + P_i || P_u), i \in S_{client}$
6: Mediator m add client c
7: $S_{mediator} \leftarrow S_{mediator} \cup m$

4.3 Training user Model

As shown in Fig. 3 and Algorithm. 3, we train a model which solves the main task here. Same as the first phase, each client needs to join the training task by sending the class distribution with Gaussian noise to the FL server. After determining the clients participating in the training and obtaining the class distributions, the server performs grouping, making each group's class distribution close to the uniform distribution to allow sequential training to improve non-IID better. The policy of grouping of this phase is shown in Algorithm. 4, which is a greedy algorithm. The server traverses the class distribution of all clients and selects the one that minimizes the KLD between the class distribution $P_m + P_i$ and uniform distribution P_u (Algorithm. 4, line 5). When the number of clients in the group reaches the max limitation, the server will create a new mediator and repeat the above process until all clients have been grouped (Algorithm. 4, line 4).

After grouping, the server initializes the global model and broadcasts it to all mediators to start a new synchronization round. Next, each mediator schedules the training of its group in parallel (Algorithm. 3, line 3) to reduce the overhead brought by sequential training. The process is as follows. First, each mediator decides on a client ready to perform local training. After that, the mediator sends the model weight to the chosen client. Next, the client trains the model for E local epochs and then sends the model weight with Gaussian noise to the next client through the information provided by the mediator. Under the scheduling of the mediator, the unavailable

clients will be skipped to avoid additional overhead. We call it a mediator epoch that all available clients in the group have been trained once (Algorithm. 3, line 5). After looping mediator epochs E_m times, the server performs aggregation and makes all clients holding the model weights send it to the server through mediators (Algorithm. 3, line 10). Next, because the amount of data in each mediator is various, we adopt weighted FedAvg, which is more reasonable (Algorithm. 3, line 11). The server aggregates the model weights with the weight of n_m/n, where n_m is the size of data in the group m, and n is the size of data of all groups. Then, the server updates the global model to ω_{r+1}. We call the process from broadcasting to aggregation a synchronization round. Finally, the server broadcast updated model weight to mediators to start the next synchronization round.

5 EVALUATION

In this section, we introduce our experimental setup and then present the results of our evaluation in four parts. First is to analyze the training accuracy of our framework under various system settings, including noise scale σ_n, degree of balancing τ, and the number of mediators M_g, M_c. The second is to show that our framework can outperform other existing solutions for better training accuracy. The third is to show that our solution is capable of solving the more extreme n-class non-IID problem, which the traditional static data augmentation approaches cannot solve. Finally, we evaluate the impact of the fault tolerance mechanisms on test accuracy and model convergence.

5.1 Experimental Setup

Implementation: We implement the proposed solution based on Tensorflow [1]. The communication between clients, mediators, and the server is implemented using the NATS messaging library. The IBM differential privacy library [25] is used to add noise to the model weights for privacy. Our experiments were conducted on an in-house cluster with two physical nodes. Each node has 2 Intel Xeon E5-2620 v4 2.1GHz CPUs, 4 V100 GPUs, and 128GB memory.

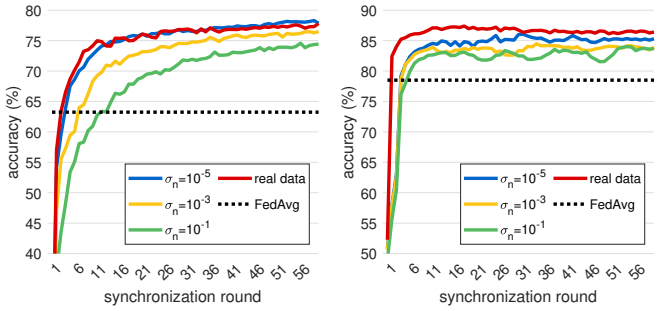
Dataset: We evaluate our solution on CINIC-10 [9] and EMNIST [7] that have 10 and 47 classes, respectively. CINIC-10 has a total of 270k images, 4.5 times that of CIFAR-10 [31](and more challenging). EMNIST(balanced), an extension of MNIST [10], has 131k images and constitutes a more challenging classification task involving letters and digits. For the non-IID setting, we divide the training dataset into 20 partitions of the same size. Then each partition has four major classes, whose size is about ten times that of the other minority classes. Finally, a total of 20 clients will be randomly assigned one partition.

Models: The implemented GAN model is as same as WGAN with gradient penalty [21], and we set the batch size to 256, and the learning rate of discriminator and generator to 1.0×10^{-4} and 5.0×10^{-5} respectively. We use a widely used model, ResNet-18 [23], as the user model. For training, we set the batch size to 128, and the optimizer of ResNet-18 is SGD with learning rate 1.0×10^{-1} and momentum 0.9. Finally, we evaluate the user model with top-1 accuracy on the testing set and consider the maximum accuracy while training as the result of the model.

FL setting: For FL setting, we set iteration of generator T_g to 3, iteration of discriminator T_d to 2, the local epoch of the user model E to 3, mediator epoch E_m to 1, and the number of clients to 20, as same as the number of partitions mentioned in *Dataset*.

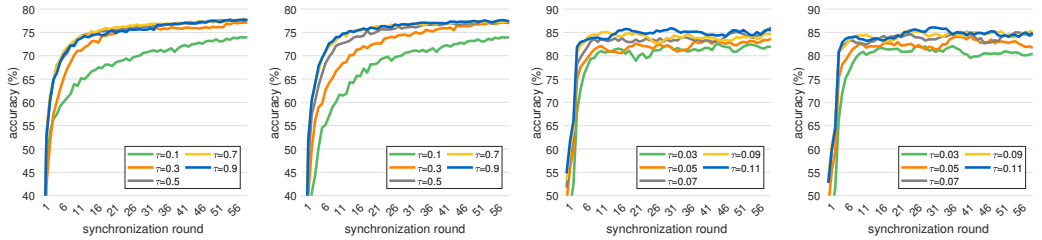
5.2 Effect of Framework Parameters

Our framework has three important parameter settings, naming the noise scale σ_n, degree of balancing τ, and number of mediators M_g, M_c. We evaluate the impact of these settings to the model accuracy result as follows. The default settings of these parameters for our approach in all the experiments are $M_g = 2$, $M_c = 2$, $\tau = 0.5$ for CINIC-10 [9], $\tau = 0.07$ for EMNIST [7], and $\sigma_n = 1 \times 10^{-5}$. The result of FedAvg [39] is also shown in the plots as a comparison baseline.



(a) On CINIC-10 (b) On EMNIST

Fig. 5. Test accuracy of GANDALF under varied noise scale training settings of σ_n. The results are compared with the idea result from using real data for data augmentation and the result from FedAvg without data augmentation.



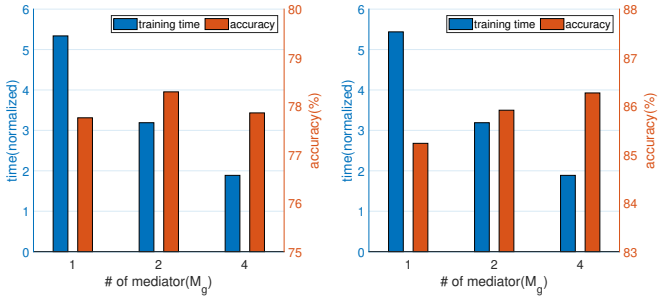
(a) With static data augmentation, on CINIC-10 (b) Without static data augmentation, on CINIC-10 (c) With static data augmentation, on EMNIST (d) Without static data augmentation, on EMNIST

Fig. 6. Test accuracy of GANDALF under varied degree of balancing settings of τ. The results of both with and without using static data augmentation to make up the lack of generated data are shown.

5.2.1 Quality of generated data. Noise scale σ_n, the standard deviation of the Gaussian noise used to satisfy differential privacy mentioned in Section. 3.5, determines how large the noise is added while training GAN models to achieve differential privacy. Fig. 5 shows that the accuracy is reduced, and the model converges slower when the noise scale increase from 10^{-5} to 10^{-1}. The reason for the decline is that the considerable noise reduces the quality of generated data, and the class distribution of generated data has a more significant gap from the theoretical value. This results in the inability to balance the local datasets and adversely affects training.

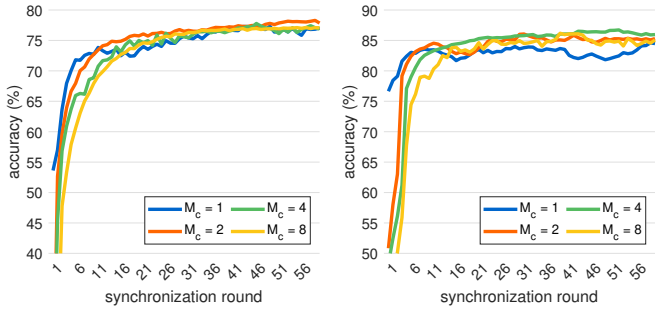
In order to show that the data generated by GAN has the potential to be more beneficial to training than the well-processed data in the training dataset, we also show the result of using real data for data augmentation in Fig. 5 labeled as "real data". Surprisingly, we found that if σ_n is small enough, the generated data could obtain a similar or even better accuracy than the real data. We believe the reason is that a small amount of data generated by GAN not only can solve the non-IID problem without exposing private data but also makes the model more robust with more diverse features and information such as image size, shape, and location of key components. Therefore, our approach achieves both the goals of accuracy and privacy.

5.2.2 Degree of balancing and static data augmentation. Degree of balancing τ is a parameter that determines the number of data GAN generated. As shown in Fig. 6, The more data GAN generates,



(a) On CINIC-10 (b) On EMNIST

Fig. 7. Test accuracy and training time of *G*ANDALF under varied number of mediators while training GAN models.



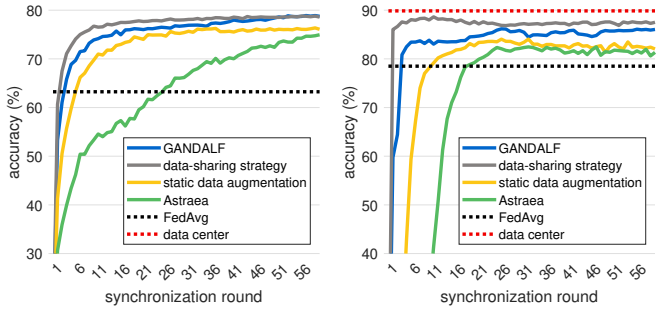
(a) On CINIC-10 (b) On EMNIST

Fig. 8. Test accuracy of *G*ANDALF under varied number of mediators while training the user model.

the higher the accuracy. However, after τ reaches 0.5, its increase will not bring significant changes to accuracy. This observation shows that generating too much generated data may be inefficient to balance local datasets because computation cost is proportional to the amount of generated data, but the accuracy is not. Therefore, our approach provides a tuning knob to address the performance and accuracy trade-off.

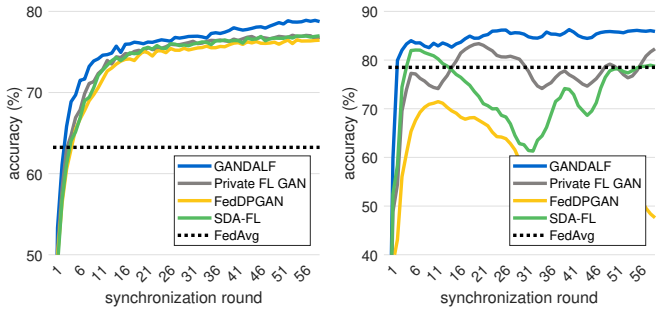
To observe the benefit of using static data augmentation to make up for the lack of generated data, we plot the result without static data augmentation in Fig. 6. We found that static data augmentation only improves the accuracy when τ is small enough. The results of with and without static augmentation are almost the same when τ is larger than 0.5 for CINIC10 and 0.07 for EMNIST. Therefore, our GAN augmentation is robust enough by itself. However, static augmentation does have the advantage of consuming less computing power for data generation than GAN augmentation. Thus, static augmentation can still be helpful to combine with our method to reach similar accuracy results with less computing power requirement.

The above results show that our proposed framework provides the mechanisms to address the trade-off between model accuracy, cost, and performance. However, the discussion of finding the best setting for optimizing performance and cost is considered to be our future work and out of the scope of this paper.



(a) On CINIC-10 (b) On EMNIST

Fig. 9. Test accuracy comparison of different data augmentation algorithms.

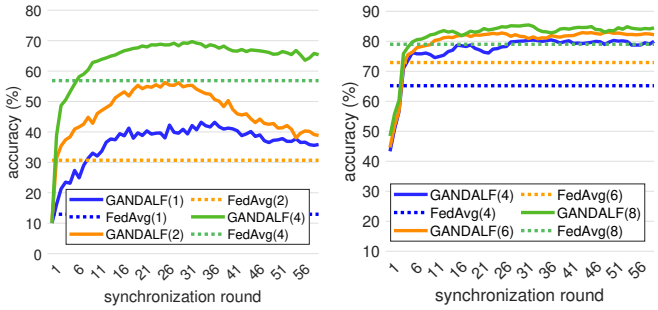


(a) On CINIC-10 (b) On EMNIST

Fig. 10. Test accuracy comparison of different GAN data augmentation algorithms.

5.2.3 Number of mediators. Fig. 7 shows the accuracy of the user model and training time of GAN models under the different number of mediators M_g while training GAN models. To evaluate the relationship of the time overhead between training GAN models and the user model, we normalize the training time of GAN models by dividing it by the training time of the user model. In Fig. 7, as the number of mediators increases, the time overhead of training GAN models also decreases. Because each mediator performs training in parallel, increasing the number of mediators is equivalent to increasing parallelism and reducing time overhead. For accuracy, we observe that training with only one mediator (one GAN model) got the lowest accuracy in both datasets. This result shows that training multiple GAN models in parallel instead of one can mitigate the mode collapse problem and slightly improve accuracy.

Next, We evaluate the different number of mediators M_c while training a CNN model. Fig. 8 shows that with the advantage of sequential training, we could accelerate the convergence of the model without affecting accuracy by decreasing the number of mediators. However, reducing the number of mediators will also reduce the parallelism of training. Thus, it is a trade-off between convergence and parallelism, and how to set this system parameter to achieve the minimum time overhead is another interesting and challenging problem for our future works.



(a) On CINIC-10 (b) On EMNIST

Fig. 11. Test accuracy of GANDALF for the n-class non-IID problem, where each client only has data from n classes (n = {1,2,4}).

5.3 Solution Comparison

Next, we conducted experiments to compare the accuracy result of our framework with other types of data augmentation and state-of-the-art GAN data augmentation methods.

5.3.1 Data augmentation algorithms. In this subsection, we first compare GANDALF with the following two baselines and three data augmentation methods which do not use GAN models.

- FedAvg [39]: a widely used FL algorithm, which has been deployed in a large-scale system to test its effectiveness [4]. Also, [39] shows that FedAvg is robust to non-IID data.
- Datacenter: a standard ML approach that trains with a centralized training dataset on a machine or in a data center.
- Data-sharing strategy [56]: we establish a globally shared dataset G that each client contributes and consists of a uniform distribution over classes. The size of G is $0.2 \times ||D||$, where $||D||$ represents the number of data in training dataset. And then, a random 20% of G is distributed to each client.
- Static data augmentation: each client doubles the data size of the six minority classes of its local dataset using the static data augmentation operations, including rotation, shift, and flip.
- Astraea [12]: a self-balancing FL framework that alleviates the non-IID by i) Z-score-based data augmentation and ii) multi-client rescheduling.

As shown in Fig. 9, although our solution converges slower than the data-sharing strategy, it achieves a similar or even better accuracy. This similar observation can also be found in Fig. 5: Generated data can bring performance close to that of real data. The generated data not only balances the local datasets but also enhances the robustness of the model. Among them, static data augmentation has a slower convergence speed. The reason for the slower convergence of static data augmentation is that the amount of supplemented data is not as enough as GANDALF. On the other hand, it is not appropriate to use static data augmentation to generate a large amount of data because it may cause a model to overfit the minority class, which is being oversampled. Similarly, the Z-scored-based data augmentation proposed by Astraea [12] can not effectively supplement the data for the differences of each local dataset. Therefore, the two works have a slower convergence rate and less accuracy. In short, static data augmentation is not appropriate for severe class distribution skew.

5.3.2 GAN model training method. This subsection aims to prove our proposed GAN model training method described in Section 4.1 can help the GANDALF framework to achieve better user model accuracy on non-IID data by comparing to the following three state-of-the-art GAN data augmentation methods. Each of them proposes its own method to train a GAN model in the FL environment as described below.

- Private FL GAN [48]: a method combining serialized model-training and differential privacy into GAN model training. Specifically, all clients sequentially train the GAN model and add random noises to the GAN model while communicating.
- FedDPGAN [55]: a method which trains GAN models with FedAvg algorithm.
- SDA-FL [36]: a method making each client trains a GAN model based on its private data independently. After training, we will get K GAN models, where K is the number of clients.

To focus our comparison on the GAN model training method, we only replace how the GAN model is trained in our GANDALF framework by the three compared methods above, while the rest of steps, including data augmentation and user model training, remain unchanged.

As observed from the final user model accuracy comparison shown in Fig. 10, GANDALF with our proposed GAN model training method successfully achieves the best model performance and convergence comparing to all other state-of-the-art methods. Among the three methods, private FL GAN is the special case of GANDALF, where the number of mediators M_g equals 1. The benefits and impact of the number of mediators on training GAN have been discussed in Section. 5.2.3. Compared with private FL GAN, we introduce mediators to improve the parallelism of training and better solve mode collapse. In addition, SDA-FL is also a special case of GANDALF, where the number of mediators M_g equals the number of clients. Although SDA-FL lets all clients perform training to achieve better parallelism, the trained GAN models may be overfitting due to the limited size of a single local dataset. Overfitting GAN models may not be suitable for data augmentation since they simply memorize a few data points and cause the user model to overfit the generated data. Finally, FedDPGAN is the most naive method. Compared with FedDPGAN, private FL GAN and SDA-FL show the benefit of sequential training and multiple GAN models, respectively. Furthermore, GANDALF cleverly combined the two mechanisms, thus achieving the best results.

5.4 n-class non-IID Problem

In order to further demonstrate that our solution can be applied to more extreme cases than static data augmentation, we evaluate our solution in three extreme cases where static data augmentation cannot work at all. The extreme cases are named n-class non-IID, where each client only has data from n classes, and n = {1,2,4} for CINIC-10 [9], and n = {4,6,8} for EMNIST [7]. In these extreme cases, each client does not have any data of minority class, so it is impossible to balance the local datasets through static data augmentation. As shown in Fig. 11, our solution effectively improves the accuracy in all cases.

In summary, the above experiments show that our solution not only can obtain higher accuracy than other solutions with almost no invasion of privacy but also can be applied to more extreme non-IID cases, which the traditional static data augmentation approaches cannot solve.

5.5 Fault Tolerance

Finally, we conducted experiments to show the fault tolerance (FT) mechanisms we designed for improving test accuracy and accelerating model convergence. To simulate the unpredictable network and node failures or performance degradation in the real-world environment, we introduce a randomly generated delay time to the local training process of each client in the experiment. The baseline comparison method without our fault tolerance mechanism will wait for the response

Table 2. Test accuracy and Model convergence with/without Fault Tolerance

		Stop @R_{max} = 40						Stop @Acc = 0.7/0.8					
		Best accuracy			Round length(min)			Round needed			Total time(min)		
Dropout rate		0.1	0.4	0.7	0.1	0.4	0.7	0.1	0.4	0.7	0.1	0.4	0.7
CINIC-10	With FT	78.17	77.85	76.89	3.92	3.81	3.69	7	7	12	27.44	16.75	44.27
	Without FT	76.80	74.58	71.97	5.66	10.96	16.20	9	11	18	50.91	120.53	291.57
EMNIST	With FT	86.82	86.20	85.58	5.07	4.81	4.17	4	6	7	20.28	28.89	29.17
	Without FT	85.48	83.93	81.74	6.98	12.08	16.46	6	10	21	41.90	120.83	345.70

of clients for a maximum waiting time threshold T_R. Once the waiting time threshold is reached, mediators will skip the client from the training round and move on to the next client in the fixed training sequence. In contrast, our fault tolerance mechanism dynamically adjusts each client's training priority and sets smaller T_R with less cost. Therefore, with FT, we can use shorter waiting time intervals to minimize the wait time overhead from the possible failed clients while avoiding the bias of model weight caused by the frequently selected clients.

The improvement of our approach is evaluated in two use case scenarios: i) stop the training at a maximum preset synchronization round R_{max}. ii) stop the training when a preset test accuracy is achieved for the global model. In Table. 2, we present the result in terms of maximum test accuracy in R_{max} rounds, the average length of a round, the number of needed rounds, and the total time duration for achieving sure accuracy. The results in the table were collected from the experiments when we gradually increased the degree of delay time from failures. The dropped rate in the table indicates the percentage of client requests that exceeds the maximum waiting time threshold under the training method without FT. As shown in Table. 2, training with FT gets better accuracy and reduces the number of needed rounds and time to achieve the target accuracy in all cases, especially in the cases where the dropout rate is greater than 0.4. Since the FT tolerance mechanisms mentioned in Section. 3.4 adjust the training sequence of clients to avoid the bias of model weight introduced by clients frequently selected. Furthermore, it also introduces heartbeat mechanism to avoid additional time overhead caused by node failure.

6 RELATED WORK

Federated Learning enables edge nodes to train a model collaboratively while keeping all the data on local clients and ensuring privacy. Existing FL research mainly focuses on addressing key challenges such as heterogeneity of local datasets, communication overhead, privacy issues, etc.

Non-IID: Recently, Zhao *et al.* [56] showed that non-IID data reduce the accuracy of federated learning through experiment and mathematical demonstration. To solve the non-IID issue, Li *et al.* [33] proposed FedProx, which introduces a proximal term to the loss function to alleviate weight divergence. Similarly, Li *et al.* [32] proposed MOON, which utilizes the similarity between model representations to correct the local loss function. In addition, several works introduce existing DL techniques to solve non-IID. Kavya Kopparapu *et al.* [30] combine federated learning and lifelong learning to tackle catastrophic forgetting brought by non-IID data. Park *et al.* [42] proposed GPAL, which utilizes meta-learning to prepare a well-initialized model that can adapt various local datasets within a few rounds. Another intuitive way is to use data augmentation. Yoon *et al.* [52] proposed FedMix, which appropriately modifies Mixup [54] to generate synthetic data by linear interpolation between samples. Yoshida *et al.* [53] proposed HybridFL, which gathers private data from volunteered clients to build a shared dataset and use it to update the global model. Compared with the above two data augmentation works [52, 53], our work combines static and GAN data augmentation to make our method more robust. Furthermore, we keep the data on the

local side instead of uploading it to the server [53] throughout the process of training GAN models to minimize the privacy cost.

GAN data augmentation: The existing literature has proved that GAN can indeed be applied to data augmentation. Bowles *et al.* [5] and Frid-Adar *et al.* [15] show that GAN can be used for data augmentation and improve the performance of the model for medical imaging. Tanaka *et al.* [44] show that the fake data generated by GAN has the potential to help a decision tree and different networks achieve better accuracy. Some works noticed that mode collapse hinders the performance of GAN data augmentation. Li *et al.* [34] add an independent classifier and introduce Wasserstein distance to the loss functions to overcome model collapse and gradient vanishing. Guo *et al.* [20] introduce multiple generators to ensure the diversity of generated data. Recently, how to train a GAN model based on distributed learning or FL effectively has been a focus of active work. Rasouli *et al.* [43] proposed a communication-efficient distributed GAN which is robust to reduced communications. Xin *et al.* [49] proposed a differential privacy GAN based on FL, which provides a strict privacy guarantee. In addition, some works try to apply GAN data augmentation into FL to solve the non-IID issue. Zhang *et al.* [55] proposed FedDPGAN, which used GAN to generate patient data of COVID-19 privately. Nguyen *et al.* [40] proposed a scheme for COVID-19 detection by the joint design of FL, blockchain, and GAN. Li *et al.* [36] proposed SDA-FL, which makes each client train a GAN model independently and generate synthetic data. The applications [40, 55] widely used in COVID-19 verified the feasibility of GAN in a cross-silo setting. Compared with them, GANDALF uses multiple GAN models to ensure the diversity of generated data and the effectiveness of data augmentation. On the other hand, SDA-FL [36] train multiple GAN models as we do, but it does not allow clients to perform GAN training collaboratively and has a higher risk of overfitting. Compared with SDA-FL, we train GAN models in more flexible ways and bring more improvements in the final accuracy.

Privacy issues: Regarding privacy, Liu *et al.* [37] proposed a framework, Federated Transfer Learning (FTL), that is compatible with two secure approaches, namely, homomorphic encryption and secret sharing. Differential privacy [13] is widely used to protect the recovery of specific data information during training. The impact of differential privacy on the quality of ML and FL training is explored by Abadi *et al.* [2] and Wei *et al.* [46]. Our work introduced differential privacy to reduce privacy leakage, but it will affect performance. Research related to privacy will help us achieve better performance and reduce costs.

7 CONCLUSION

In this paper, we proposed GANDALF, which solves the non-IID problem under the cross-silo setting effectively and meets the requirements of preserving privacy, reducing the cost, robustness, and reliability. In GANDALF, we introduce GAN to avoid data augmentation relying on existing data in a single local dataset like traditional static data augmentation. Thus it is robust to more extreme non-IID problems. Also, we introduce mediator-based architecture combined with sequential training, which considerably improves the model's convergence speed and further reduces overhead. With this architecture, we also cleverly ensure the diversity of the generated data by training multiple GAN models in parallel. Furthermore, in terms of privacy, we do not share private data and ensure that model weight does not leak privacy by adding artificial noise that satisfies differential privacy, enabling GANDALF to provide strict privacy guarantees. Finally, we design multiple fault tolerance mechanisms to provide reliability and avoid the overhead caused by unavailable clients. Experiment results show that GANDALF improved 15.66 and 14.8 top-1 test accuracy over FedAvg on imbalanced CINIC-10 and imbalanced EMNIST, respectively. Also, we demonstrate the robustness of GANDALF by applying it to n-class non-IID, and we significantly improve the accuracy in all cases. Finally, we

show that the fault tolerance mechanisms for GANDALF bring better accuracy and faster model convergences while training with highly unavailable clients.

Finally, there are some limitations and promising areas of improvement for GANDALF. First, data labeling, an unavoidable step for GAN data augmentation, causes additional overhead and affects test accuracy. Although many studies and automated data labeling services such as AWS sagemaker can assist in labeling, performing labeling effectively in decentralized environment is still an open question. Second, training GAN model is known to be time consuming and power demanding. But as known, the computing power of edge devices has proliferated over the past few years, and the increasing rate is not expected to slow down. Many recent research also aims to reduce the computational cost of model training, such as the model compression [6] technique. Hence, we would also like to investigate and adopt these solutions in our work, so that our approach can be applied in broader computing environments. Finally, our framework offers several system parameters that could affect the trade-off between computation cost, convergence speed, and accuracy. Hence, it will be our future direction to conduct more quantitative and qualitative studies on the impact of these settings for meeting the desired expectation of cost and accuracy under different data characteristics and computing environments.

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FreezeFL: Accelerating Federated Learning in Heterogeneous Edge Devices by Layer Freezing

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***Abstract*—Federated learning is an emerging paradigm that enables edge devices to collaboratively train a model without sharing private data. There are two key challenges in the setting. 1) system heterogeneity, the significant variability in hardware resources on edge devices. 2) statistical heterogeneity, non-identically distributed data on edge devices. In this work, we propose a framework, FreezeFL, which alleviates the system heterogeneity by applying layer freezing and a fairness guaranteed client selection algorithm. We further show that FreezeFL does not exacerbate statistical heterogeneity while solving system heterogeneity and keeps client-oblivious; namely, clients do not need to share information besides model weights. Extensive experiment results on FEMNIST and Shakespeare show that FreezeFL outperforms various existing methods. Relative to FedAvg, FreezeFL shortens round length by 33% and 46%, respectively, while not hurting test accuracy.**

***Index Terms*—Federated learning, Statistical heterogeneity, system heterogeneity, Layer freezing, partial model training**

I. Introduction

Federated Learning (FL) [26] is a distributed framework for deep learning without centralizing data and with privacy by default. It enables edge devices such as mobile phones or IoT sensors to participate in training without exposing private data. During the training, each client (i.e., edge device) uses local private data to train a local model and only exchanges model updates with servers, which aggregate all updates to form a single global model. Recently, several successful applications such as improving query suggestions of Google keyboard [42] and next word prediction [11] are derived under FL.

However, as deployments move from the data center to the edge devices, FL encounters two key challenges that differentiate it from traditional distributed learning: 1) *system heterogeneity*, the differences in terms of the communication and computation capabilities of the edge devices, and 2) *statistical heterogeneity*, the heterogeneity of data distributions where training data are not independent and identically distributed (Non-IID) [21], [32], [44] on the local devices. System heterogeneity causes a lower training efficiency because all the clients must wait for the slower clients, known as stragglers, to complete each training round. On the other hand, statistical heterogeneity causes a lower training accuracy due to statistical bias, such as client overfitting. To mitigate system heterogeneity, techniques have been proposed to reduce the participation of stragglers, such as dropping the clients that fail to complete local training tasks in time [2]. Nevertheless, these techniques could further exacerbate statistical heterogeneity and harm the training performance, especially when the stragglers hold high-quality data. Therefore, despite recent attempts [20], [25], [30], designing a FL algorithm being the best of both worlds remains an open problem.

In this work, we propose **FreezeFL**, which applies the layer freezing technique to tackle the aforementioned problem. Freezing layer can effectively reduce the communication and computing cost of stragglers because the weight of frozen layers can be eliminated from the backward computation and the client-server model exchange. Although the idea is simple and it has been applied to other learning objectives, such as transfer learning [14], [24], surprisingly, no existing work has applied it to solve the straggler problem in FL. The reason is that previous studies mainly focus on the freezing [8], [34] and pruning [16], [27] techniques in the units of neurons instead of layers due to the general belief (as stated by [8]) that coarse granularity (i.e., layer) cannot provide efficient solutions. To the best of our knowledge, only a few works [4], [23] applied layer freezing for fine tuning models, but they are not designed for FL learning environment and not aiming to solve system heterogeneity problem. Therefore, our main objective is to explore the applicability and efficiency of layer freezing technique for solving the system and statistical heterogeneity problem in FL. Our research not only provides a positive answer, but also achieves the following four important requirements in FL environment by carefully designing the algorithm for making the freezing decision during the training process.

(1) Low algorithm complexity: Unlike traditional centralized training, scalability is a critical requirement for FL as the number of clients can grow quickly, and the computing power of clients could be limited, especially in the cross-device setting [35]. Therefore, it is essential to keep the learning method lightweight and non-intrusive. Our approach avoids additional overhead or complexity by simply adjusting the number of frozen layers in client training without changing the model architecture or learning behavior. Also, by answering how many layers instead of which neuron to be frozen, our problem complexity is significantly reduced.

(2) Adaptation: Applying layer freezing in FL is challenging because we have to consider other concerns, such as client availability, fairness, and statistical heterogeneity, and the interaction or impact of these factors are complicated and

dynamic. To overcome these obstacles, both our client selection and layer freezing decisions are made adaptively according to the runtime information (i.e., local model weight and training time). By quantifying and considering the statistical importance and training time of each layer, our layer freezing algorithm is able to keep stragglers' contribution as much as possible while reducing stragglers' workload. By carefully controlling client selection probability with the warm-start technique, we can ensure the fairness of client participation and improve training efficiency. Hence, we can strike a better balance between system and statistical heterogeneity and be more resilient to client variability.

(3) Client oblivious: FL is a collaborative learning environment, so the server should have as little information about the clients as possible for security, privacy, and scalability reasons. Unfortunately, all previous system heterogeneity solutions [10], [13], [27] require explicit client knowledge about the local training time or computing capability. In contrast, FreezeFL avoids such requirements by deferring decisions to the local side and utilizing the layer freezing information. Therefore, our approach is client oblivious, which means the server does not need to know any status of clients that influences the local training time, such as the number of available resources and the battery level.

(4) Compatibility: FL often has to tackle multiple learning objectives (e.g., fairness, security, performance) in a learning environment with diverse characteristics. Layer freezing technical is a non-intrusive approach that skips the computation and communication of the frozen layer from training, so it can be easily combined with other training techniques for addressing multiple challenges.

To validate our approach, we conduct extensive experiments on two federated datasets with a heterogeneous setting to demonstrate the effectiveness of our frameworks. We empirically show that FreezeFL shortens round length up to 46%, improves test accuracy up to 2%, and speed up convergence rate up to $2\times$. Furthermore, we show that FreezeFL is compatible with other existing methods aiming to solve system heterogeneity and achieve better test accuracy and shorter round length.

II. Related work

In FL, edge devices are enabled to train a model collaboratively while keeping all private data on local devices and ensuring privacy [36], [37], [43]. Although FL has been proven feasible [18], [19], [26], [40], the characteristics of the FL environment bring many challenges, such as heterogeneous data and devices, privacy, and massively distributed devices.

Layer freezing Layer freezing is a representative technique for accelerating fine-tuning neuron networks in centralized learning [4], [23]. The methods exclude the parameters of layers from training in an input-output direction sequentially. Since most model architectures converge from the input side sequentially, layer freezing can accelerate training without degrading accuracy performance. However, the existing methods are not applicable to FL since FL is a very different environment from a centralized one. The freezing mechanism in FL should consider clients' limited capabilities and the trade-off between training efficiency and performance. Moreover, the information assumed known in centralized learning is usually unavailable in FL. In this work, we address the challenges mentioned above and introduce layer freezing into FL to solve system heterogeneity.

Partial model training Training a subset of a model is a common strategy in deep learning. Several works [3], [8], [31], [34], [39], [41] achieve communication-efficient FL by performing freezing/dropping in units of neurons and only uploading trainable parameters. By contrast, our work co-optimizes both communication and computation by performing layer freezing [4], [23], which excludes parameters from training in units of layers instead of neurons. In the past, layer freezing was considered inapplicable for FL due to its coarse operation granularity and the lack of freezing strategy [8]. In this work, we explore whether freezing in units of layers is applicable for FL and give a positive answer.

Heterogeneous local models The works about heterogeneous local models [6], [10], [13], [16], [27], [38] combine the ideas of partial model training and model pruning. In other words, they allow local models to have different architectures, usually a subset of the global model and still produce a single global model. It is natural to distribute subnetworks of various sizes according to clients' capabilities to solve system heterogeneity. However, such solutions depend highly on the model architecture and have high algorithm complexity. By contrast, FreezeFL does not need network-specific knowledge and has lower algorithm complexity since we do not modify the model architecture and simply decide the number of frozen layers. In addition, they remain orthogonal to our work and can be complementarily combined to reduce costs further.

Client selection Limiting the participation of stragglers effectively improves training efficiency. [29] proposed FedCS, which selects powerful clients greedily. [7] proposed TiFL, which selects clients with similar performance in each round to counterbalance the slowdown introduced by stragglers. However, they do not consider that an interplay exists between system and statistical heterogeneity and select clients too biased so that the accuracy performance may be degraded. Compared with them, our work provides a fairness guarantee in client selection to tackle the trade-off between training efficiency and model performance.

III. Preliminaries

Layer freezing. Layer freezing in deep learning means that the frozen layers' weights do not be modified by backward propagation. It is widely used in transfer learning [14], [24] for transferring domain knowledge to tasks with fewer data without overfitting. In this work, we explore its benefit on accelerating training. Layer freezing can save communication costs because only the weight of the unfrozen layers needs to be uploaded from clients to the server. On the other hand, in order to save computation cost, the layers must be frozen one by one from the first layer to the last layer in consecutive order so that the frozen

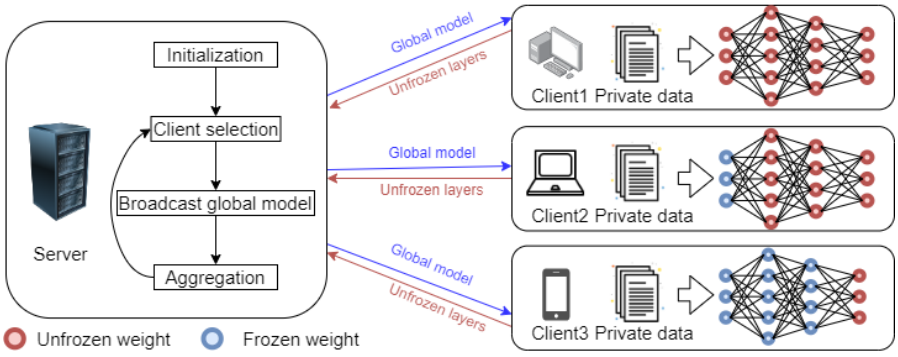
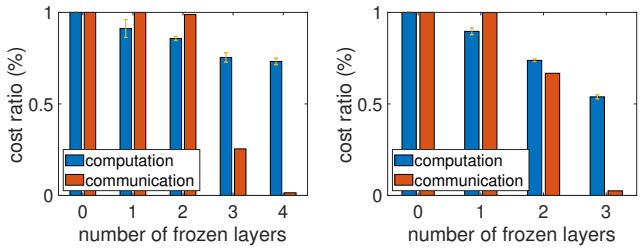


Fig. 1. The training procedure of FL with layer freezing. Clients with poorer capabilities will be frozen for more layers. In addition, we only upload unfrozen layers to reduce communication costs.



(a) CNN on FEMNIST (b) RNN on Shakespeare

Fig. 2. Cost ratio under a different number of frozen layers. The computation cost reduction is proportional to the computation complexity of frozen layers, and the communication cost reduction is proportional to the frozen layers' number of neurons.

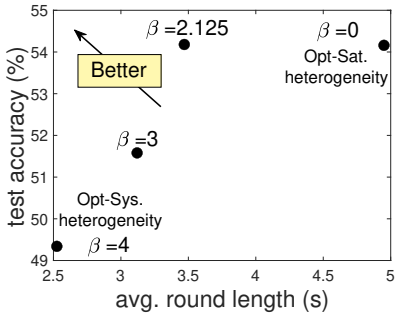


Fig. 3. FreezeFL explores the β to find the sweet spot between two heterogeneity. The numerical results are from the RNN on Shakespeare(experimental setting is detailed in Section. V-A)

layers can be excluded from the backward passes. As shown in Fig. 2, we evaluate the cost-saving of layer freezing on CNN and RNN and show that layer freezing can bring considerable cost reduction under different network architectures (The detail of the setup is summarized in Section. V-A).

FL with layer freezing. In this work, we propose to apply layer freezing in the FL training procedure as shown in Fig. 1. In FL, all clients train a model collaboratively. First, the server selects a subset of clients at each round and broadcasts the global model to them. Next, the selected clients perform training for some local epochs over local private datasets. Finally, the server collects and aggregates the updates to form an up-to-date global model. In the training procedure, the time cost of a round depends on the maximum of selected clients' model exchange time. We refer to the model exchange time as the time spent on a local training task, including model broadcasting, model training, and model uploading. In this work, we apply layer freezing to local training to shorten the stragglers' model exchange time. Each selected client will independently determine the number of frozen layers. Furthermore, we optimize the aggregation rule to account for the different degrees of freezing. Finally, we use the number of frozen layers reported by the clients as the reference for client selection to achieve the goal of client-oblivious.

Strength. Compared with the previous works that attempt to prune [16], [27] or freeze [8] of individual neural, layer freezing offers several advantages. (1) It does not alter the network architecture. Therefore, we do not deal with the problem of aggregating heterogeneous network models among clients. (2) The problem complexity is significantly reduced and oblivious to the model complexity because we simply decide the number of freezing layers of each client according to their computing capability. (3) The early layers tend to converge faster. Hence, freezing converged layers can potentially reduce computing cost without sacrificing training results.

Challenges. The key challenge in our approach is to decide the number of frozen layers of each client during the learning process. Since statistical heterogeneity will deteriorate and degrade model performance if we freeze too many layers rashly. On the other hand, system heterogeneity will not be improved if we freeze too few layers. In other words, the decision on the number of frozen layers is the trade-off between statistical and system heterogeneity. Therefore, the goal of our work is to propose a layer freezing strategy that can minimize additional statistical heterogeneity while solving the system heterogeneity problem.

IV. Algorithm

In this section, we first present the overview of FreezeFL, which addresses system heterogeneity while minimizing additional statistical heterogeneity in FL. Next, in Section IV-B, we detail how we adaptively decide the number of frozen layers for clients and the layerwise aggregation rule. Finally, Section IV-C

Algorithm 1 FreezeFL

Input: K, number of selected clients in each round. E, number of local epochs. η, learning rate. R, number of rounds, B. local minibatch size. Φ, the warm-restart interval.

Output: A trained global model.

1: **procedure** SERVEREXECUTE
2: Initialize $w_0, T_0, u_0^k, k \in 1, ..., N$
3: **for** each round $r = 1, 2, ..., R$ **do**
4: Sample a set S_r from N clients according to clients' utility $u_r^k, k \in 1, ..., N$
5: **for** each client $k \in S_r$ in parallel **do**
6: $(w_{r+1}^k, n^k) \leftarrow$ ClientUpdate(k, w_r, T_r)
7: Update soft deadline T_{r+1} as in Eq. 1
8: Update clients' utilities $u_{r+1}^k, k \in S_r$ as in Eq. 7
9: Update the global model w_{r+1} as in Eq. 4
10: **if** r mod Φ == 0 **then**
11: Update all clients' utilities $u_r^k, k \in 1, ..., N$ as in Eq. 8
12: **procedure** CLIENTUPDATE(k, w, T_r)
13: $w^k \leftarrow w$
14: $B_i \leftarrow$ Split local dataset X_i into batches of size B
15: **for** each local epoch $e = 1, ..., E$ **do**
16: **for** batch $b \in B_i$ **do**
17: $w^k \leftarrow w^k - \eta \nabla \ell(w; b)$
18: **if** $e == 1$ **then**
19: Calculate the importance of layers P as in Eq. 2
20: Freeze first n layers as in Eq. 3 and rollback their weights
21: return $\{w^{k,l}\}_{l \in n+1,...,L}, n$ to server

presents our novel reputation-based client selection scheme, which aims to address both system and statistical heterogeneity while only needing the client's layer freezing information.

A. Overview

The proposed framework, FreezeFL, is summarized at Algorithm. 1. Training proceeds as follows: for each round, the server performs client selection based on all clients' utility, namely, their training efficiency and quality of local datasets (line 4). Next, the server broadcasts global model weights and the soft deadline T_r to the selected clients (line 6), where the soft deadline T_r means the estimated average model exchange time at the rth round. On the client side, selected clients first perform training for a single local epoch without layer freezing to collect needed knowledge such as model weight update and further quantify the importance of each layer based on it (line 19, Eq 2). Afterward, each client determines the number of frozen layers according to the importance of each layer and comparison between its model exchange time and soft deadline (Eq 3). Subsequently, each client performs layer freezing, rollbacks the frozen layers' weight to that of the received global model (line 20), and finishes the remaining local epochs. Finally, after receiving all clients' responses, the server updates the soft deadline, clients' utility, and global model weights (line 7~11, Eq. 1, 4, 7, 8). We describe critical steps in further detail in the following subsections.

B. Layer freezing

Adaptive layer freezing. As mentioned in Section. III, determining the number of frozen layers is the tradeoff between two heterogeneity. Our goal is to solve system heterogeneity while not exacerbating statistical heterogeneity. Therefore, we try to quantify the effect of layer freezing on the above two heterogeneity and find the sweet spot between the tradeoff. For system heterogeneity, we maintain a criterion T_r, called soft deadline, to let clients determine if they are stragglers. In addition, Since the acceleration brought by layer freezing can be predicted, we can further estimate how much improvement each layer can bring to the system heterogeneity. The key insight we have for statistical heterogeneity is that discarding the model updates of clients is the source of additional statistical heterogeneity. Therefore, we quantify the importance of each layer in terms of weight update to measure the deterioration caused by layer freezing for statistical heterogeneity. More specific descriptions and formulas are as follows.

During the training process, the only information provided by the server to the clients is soft deadline T_r, more specifically, the estimated average model exchange time at the rth round. In our algorithm, T_r is used as a criterion to judge whether clients are stragglers. T_0 is customized by the developer. After each round, the server updates T_r with the average of selected clients' model exchange time by Exponential Moving Average (EMA). In the EMA equation below, the first parameter is the estimated value, and the second parameter is the current observation:

$$T_{r+1} = EMA(T_r, \frac{\sum_{k=1}^{K} t^k}{K}) \tag{1}$$

where r is the round index, K is the number of selected clients, t^k is the model exchange time of client k. As the number of rounds increases, the server accumulates more samples of model exchange time reported by clients. Therefore, the T_r will gradually approach the actual value.

Next, we detail the method of quantifying the importance of layers, which is motivated by Deep Gradient Compression (DGC) [22], [33]. In DGC, gradient magnitude is used as a heuristics for importance. Obliviously, since the larger gradient magnitude brings larger model weight updates, it is reasonable to use weight updates magnitude as another heuristics for importance. Based on the above insight, the metric of layer importance is formulated as follows:

$$P_l = \frac{||w^l - w^{k,l}||_1}{dim(w^l)}, \quad l \in \{1, ..., L\} \tag{2}$$

Where l is the layer index, L is the number of total layers, w is the received global model weights, w^k is client k's local model weights that have been trained for one local epoch, and $dim(.)$ is the number of neurons. This metric quantifies how much each layer contributes to the model training by calculating the average of absolute weight change, i.e., its ℓ_1-norm. For layers with more significant weight changes, we give them

higher importance scores and less chance of being frozen since freezing such layers is harmful to statistical heterogeneity.

Finally, we decide on the number of frozen layers based on the importance of layers and the model exchange time. To shorten the straggler's model exchange time while preserving their significant updates as much as possible, we should maximize the sum of unfrozen layers' importance scores with a time penalty. Each client obtains the specific number of frozen layers by the following formula:

$$\max_{n} \underbrace{\Sigma_{l=n+1}^{L} P_l}_{statistical} \times \underbrace{(\frac{T_r}{\tau_n})^{I(T_r<\tau_n)\times\beta}}_{system}, \quad n \in \{0, ..., L-1\} \quad (3)$$

where n means the number of frozen layers, τ_n means the model exchange time while freezing the first n layers, $I(T_r < \tau_n)$ is an indicator function where the output is 1 when the content is true, and 0 otherwise, and β is a hyperparameter handling the tradeoff between statistical heterogeneity and system heterogeneity. τ_n is calculated based on the performance profiling information collected from the previous training round at the client. In the formula, the clients whose model exchange time is longer than T_r receive the time penalty and thus increase the number of frozen layers to reduce their model exchange time. However, we still allow clients' model exchange time longer than T_r if the importance scores of the layers are large enough to offset the time penalty imposed by unfreezing the layers. Moreover, all clients unfreeze at least one layer, namely, the number of frozen layers n is up to $L-1$, to avoid entirely discarding the stragglers' model updates.

β is a purposely designed tuning knob in our algorithm to tackle the tradeoff between the two heterogeneities. In extreme settings, our algorithm does not freeze any layers ($\beta = 0$, as same as FedAvg [26]) to avoid introducing additional statistical heterogeneity and suffers from poor training efficiency. On the other hand, we can also freeze most of the straggler models ($\beta = \infty$) to address system heterogeneity but suffer from significant accuracy degradation. As shown in Fig. 3, the best results in accuracy and round length can be achieved under two extreme settings, respectively. Furthermore, the sweet spot that tackles the tradeoff does exist, and we can search for it through parameter tuning or multi-objective optimization algorithms. In summary, compared with other works, we perform better by quantifying two heterogeneity and exploring a 1-dimension tuning space.

Layerwise Aggregation. The heterogeneity of clients leads to heterogeneity in the degree of freezing. Therefore, involving the weights of the frozen layers in aggregation may make the updates too small and hurt the global model convergence. To this end, we perform aggregation in the following way:

$$w_{r+1}^{l} = \sum_{k} \frac{|D_k|}{\sum_k |D_k|} w_r^{k,l}, \quad k \in S_r^l \quad (4)$$

where $|D_k|$ means the size of client k's local dataset, and S_r^l means the set of clients which do not freeze layer l. For each layer, We only let clients which unfroze it participate in aggregation. Otherwise, the out-of-date weights of the previous round will slow down the model convergence and even reduce the test accuracy. We will show the advantage of layerwise aggregation in Section. V-B.

C. Fair reputation-based client selection

Given the highly variable FL environment, we address the following two concerns to select more valuable participants in terms of increasing test accuracy and shortening model exchange time. 1) *client-oblivious.* A client's utility can only be determined by its historical performance since reconfirming all clients' states before each round is not feasible. 2) *Fairness.* To avoid increasing statistical heterogeneity and account for the change in clients' utility; we should guarantee fairness in participation. To tackle the challenges, we develop a client selection algorithm that keeps client-oblivious through freezing-based reputation and guarantees fairness through the warm-restart mechanism.

Freezing-based reputation. In the client selection algorithm, our target is to determine clients' utility without client-specific information. A client's utility means its training efficiency and quality of the local dataset. The main idea is to obtain such information from a client's number of unfrozen layers and model weight updates reported by clients. For each client, the number of unfrozen layers is positively correlated with its computation and communication capability. Therefore, we cleverly use this information to estimate clients' training efficiency. In addition, we use the inner product between local model update and global model update to evaluate whether the client's local dataset is valuable. As a result, u_r^k, the utility of client k in round r is formulated as follows:

$$U_{sys}^k = (L - n^k) \quad (5)$$

$$U_{data}^k = max(0, \Sigma_{l=n^k+1}^{L} \frac{\langle w_{r+1}^{k,l} - w_r^l, w_{r+1}^l - w_r^l \rangle}{dim(w^l)}) \quad (6)$$

$$u_{r+1}^k = EMA(u_r^k, U_{sys}^k \times U_{data}^k) \quad (7)$$

where n^k is the number of frozen layers of client k, w_{r+1}^k is client k's uploaded model weights, w_{r+1} is global model weights, $\langle \cdot, \cdot \rangle$ is the inner product function, U_{sys}^k means the training efficiency, and U_{data}^k means the quality of the local dataset. Intuitively, a client with more unfrozen layers usually has a shorter model exchange time, which helps the training efficiency. Hence the number of unfrozen layers is proportional to the utility. On the other hand, the inner product considers both the direction and step size of the weight update. When the client's weight update direction is more similar to most others, it is more helpful to the training. A similar idea is also theoretically proven by Nguyen *et al.* [28], where a client's contribution in reducing the global loss is bound by the similarity of local gradient and global gradient. In FreezeFL, we extend this insight to the layer level and use the weight updates as an alternate. In addition, such an algorithm can effectively identify malicious clients uploading random weight updates. Through the inner product, when the update direction of the client does not match most people, we can significantly reduce the client's utility. Finally, the utility of a client is

updated by EMA with the product of the two factors above. In the client selection stage, FreezeFL samples clients with probability proportional to their utility.

Warm-restart. In our algorithm, a client's selection probability is proportional to its utility. As the training progresses, the utilities and selection probabilities of stragglers will be gradually decreased due to their low training efficiency. Although reducing stragglers' number of participation helps address system heterogeneity, excessively reducing it may introduce additional statistical heterogeneity. To tackle the tradeoff between two heterogeneity in client selection, we apply warm-restart to adjust client selection probability and further improve the fairness of client participation. The warm-restart mechanism means to rollback a value or state to an earlier one but not from scratch. Specifically, warm-restart adjusts the current selection probability distribution to be close to the uniform one every Φ rounds while satisfying the following two goals. First, we give the clients with lower utility larger utility increments to help them participate more in training and better improve fairness. Second, we give less change to the clients whose utility is already well certain because re-exploring clients' utility through Eq. 7 takes several rounds, and the improvement of training efficiency brought by client selection may decrease. The adjustment of the utility of client k is formulated as follows:

$$u^k = \begin{cases} min(\bar{u}, u^k + \sqrt{2\frac{\log \Phi}{\phi_k}}), & \text{if } u^k < \bar{u} \\ max(\bar{u}, u^k - \sqrt{2\frac{\log \Phi}{\phi_k}}), & \text{otherwise} \end{cases} \tag{8}$$

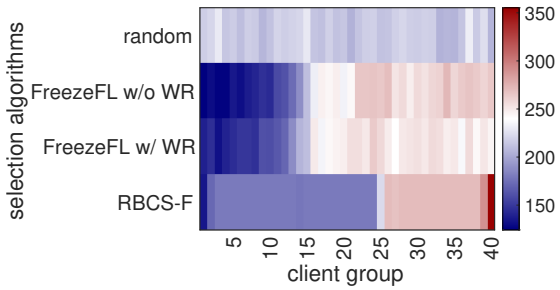
where $\bar{u}$ is the average of all clients' utility, and ϕ_k is client k's number of times of participation in the last Φ rounds. As observed from the equation, if the client's utility (u_k) is less than the average utility ($\bar{u}$), its value is increased; otherwise, it is decreased. The reputation-based utility estimation method described in Eq. 7 is similar to a multi-armed bandit problem [17]. Hence, our adjustment is based on the confidence bound of utility ($\sqrt{2\frac{\log \Phi}{\phi_k}}$) to ensure the two design goals mentioned above are satisfied. For the clients with more participation (i.e., larger ϕ_k) and higher utility, its confidence bound will be lower and hence receives a smaller decrement. Vice versa, for the client with less participation and lower utility, its confidence bound will be higher and hence receives a larger increment from our proposed equation.

V. Evaluation

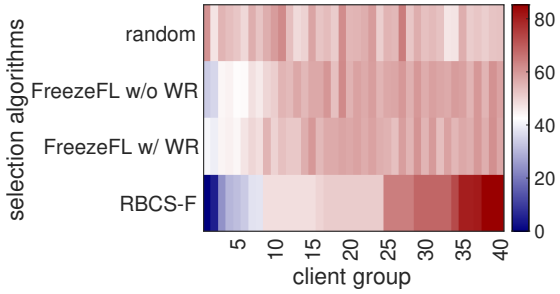
In this section, we provide a thorough evaluation of FreezeFL. We show that our framework solves the system heterogeneity, relieves the trade-off between system and statistical heterogeneity, and achieves superior performance. Also, we explore additional beneficial properties of FreezeFL.

A. Setup

Testing platform setting. We implement FreezeFL based on tensorflow [1] and LEAF [5], a benchmark for federated settings. Given that LEAF does not implement system heterogeneity, we add the feature ourselves. We randomly assign



(a) On FEMNIST



(b) On Shakespeare

Fig. 4. Number of participation of clients under different selection algorithms

capabilities to each client. Specifically, the distribution of capabilities follows a uniform distribution, and the ability gap is up to six times among all clients. Each client's computation and communication capabilities are proportional. Our experiments were conducted on an in-house cluster with two physical nodes. Each node has 2 Intel Xeon Silver 4110 CPU 2.10GHz, 4 V100 GPUs, and 128GB memory.

Datasets and models. The detail of datasets and hyperparameters in our framework are summarized in Table I. We conduct experiments on two different LEAF datasets: 1) FEMNIST dataset [9] for 62-class image classification. 2) Shakespeare dataset for next-character prediction. Both datasets are divided based on the writer or role to form non-IID partitions. For FEMNIST, we use a CNN with two convolutional layers followed by two fully connected layers and a softmax layer. For Shakespeare, we use a RNN with an embedding layer followed by two LSTM layer [12] and a softmax layer.

Baseline. We compare FreezeFL with FedAvg [26] and the following state-of-the-art solutions: 1) Fjord [13], a framework that addresses system heterogeneity by dynamically adapting model size through ordered dropout. 2) RBCS-F [15], a client selection algorithm that strikes a balance between training efficiency and fairness. It is worth noting that Fjord assumes clients' status is known, and RBCS-F predicts it by a Contextual Combinatorial Multi-Arm Bandit Model. Here, we make both solutions have clients' status set to known, and it is clear that the setting provides tougher baselines.

B. Experimental results

Sensitivity analysis of hyper-parameters First of all, we present the analysis of two important hyper-parameters, β and the number of local epochs E, in Table. II. As mentioned in

TABLE I
DATASETS AND MODELS

Dataset	Model	Total clients	Total samples	Samples per device		E	T_0	β	Φ
				mean	stdev				
FEMNIST	CNN	3550	805,263	227.4	88.9	3	1	4	60
Shakespeare	RNN	660	4,035,372	6114.2	7,184.1	3	4	2.125	30

TABLE II
SENSITIVITY ANALYSIS OF HYPER-PARAMETERS, AVERAGE AND STAND DEVIATION

		FEMNIST		Shakespeare	
Methods	Hyper-parameter	Best accuracy	Round length	Best accuracy	Round length
FreezeFL	$\beta = 4/2.25$	79.40 (0.24)	1.04 (0.03)	53.26 (0.34)	2.46 (0.13)
	$\beta = 6/2.5$	78.09 (0.16)	0.99 (0.01)	53.03 (0.13)	2.28 (0.12)
	$\beta = 8/2.75$	77.68 (0.26)	0.92 (0.01)	52.28 (0.20)	2.19 (0.10)
	$\beta = 10/3$	75.50 (0.17)	0.90 (0.02)	51.80 (0.25)	2.09 (0.06)
	$E = 2$	75.40 (0.15)	0.85 (0.01)	53.74 (0.43)	2.70 (0.41)
	$E = 3$	79.72 (0.27)	1.03 (0.02)	53.89 (0.36)	3.14 (0.15)
	$E = 4$	79.98 (0.17)	1.15 (0.02)	54.49 (0.20)	3.73 (0.33)
	$E = 5$	79.21 (0.25)	1.27 (0.09)	52.35 (0.28)	4.08 (0.20)
FedAvg	$E = 2$	76.60 (0.13)	1.22 (0.01)	52.51 (0.43)	3.50 (0.41)
	$E = 3$	77.92 (0.19)	1.52 (0.02)	54.16 (0.68)	4.95 (0.79)
	$E = 4$	77.65 (0.12)	1.80 (0.01)	54.00 (0.29)	6.39 (0.51)
	$E = 5$	77.7 (0.21)	2.10 (0.02)	52.85 (0.37)	7.91 (0.44)

TABLE III
AVERAGE (STANDARD DEVIATION) TEST ACCURACY AND CONVERGENCE FOR DIFFERENT METHODS

	FEMNIST				Shakespeare			
	Stop @$R_{max} = 80$		Stop @$Acc = 0.75$		Stop @$R_{max} = 40$		Stop @$Acc = 0.51$	
Methods	Best accuracy	Round length	Round needed	Total time	Best accuracy	Round length	Round needed	Total time
FedAvg	77.92 (0.19)	1.52 (0.02)	46.13 (2.98)	70.56 (5.06)	54.16 (0.68)	4.95 (0.79)	22.63 (2.63)	109.22 (16.40)
Freezing	79.87 (0.18)	1.07 (0.02)	**42.18 (1.15)**	44.81 (1.89)	**54.18 (0.43)**	3.47 (0.47)	20.08 (2.45)	68.80 (6.23)
Freezing w/ CS	79.49 (0.33)	1.01 (0.01)	42.44 (1.52)	**42.96 (1.35)**	53.91 (0.80)	2.66 (0.375)	**19.53 (2.65)**	**51.09 (4.96)**
Freezing w/ CS,WR	**80.02 (0.39)**	1.03 (0.02)	43.52 (2.52)	44.78 (3.12)	54.15 (0.51)	2.94 (0.41)	19.71(2.36)	54.48(2.80)
RBCS-F	77.67 (0.33)	**0.892 (0.02)**	52.75 (2.75)	47.01 (1.82)	51.99 (0.79)	**1.94 (0.09)**	35.68 (3.77)	69.34 (8.98)
Fjord	75.79 (0.16)	0.95 (0.03)	68.74 (4.83)	64.83 (6.22)	51.56 (0.43)	3.70 (0.18)	34.41 (3.78)	127.75 (13.57)

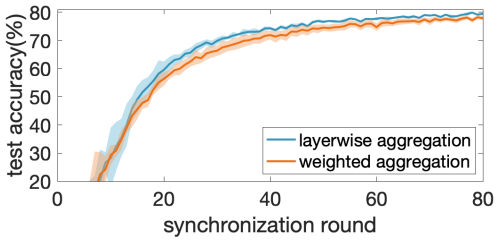
TABLE IV
AUGMENTING FJORD WITH CLIENT SELECTION

	FEMNIST		Shakespeare	
Methods	Best accuracy	Round length	Best accuracy	Round length
FJORD	75.86 (0.14)	0.95 (0.03)	51.56 (0.43)	3.71 (0.19)
FJORD W/ CS	76.17 (0.36)	0.93 (0.02)	52.02 (0.61)	3.34 (0.04)

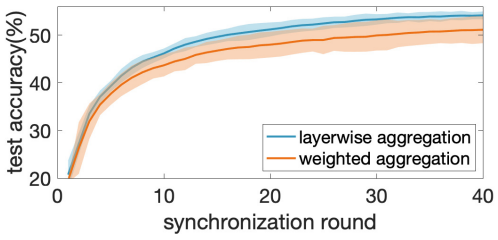
Section. IV, β is a key design in our approach for addressing the challenges of statistical heterogeneity (i.e., measured by "best accuracy") and the system heterogeneity (i.e., measured by "round length"). When $\beta = 0$, FreezeFL doesn't freeze any layer and acts the same as FedAvg. As β increases, FreezeFL tends to freeze more layers of the straggler models to mitigate system heterogeneity; hence the round length and training efficiency can be improved; but at the same time, the frozen layers can cause accuracy degradation. Therefore, as shown by the results in Table. II, both the training accuracy and round length strictly decrease as β increases. Take the result of FEMNIST as an example, its accuracy decreases from 79.4 to 75.5, and round length decreases from 1.04 to 0.90 as β becomes larger. This strong correlation property gives users the explicit control of optimizing their training for accuracy or efficiency, and any setting of β results in an optimal solution in the Pareto set from our multi-objective optimization problem.

On the other hand, the impact of E lies in the improvement of training efficiency, measured by round length. As observed in the results of Shakespeare, compared with FedAvg, the improvement of round length increases from 23% (=(3.5-2.7)/3.5) to 48% (=(7.91-4.08)/7.91) as E increases from 2 to 5. On the other hand, the impact of local epochs on training accuracy is less certain. But we can find that FreezeFL often has higher model accuracy results than FedAvg under the same setting of E in Table. II. Hence, overall FreezeFL provides an efficient solution to address the tradeoff problem between statistic heterogeneity and system heterogeneity and achieves comparable model accuracy to FedAvg with much higher training efficiency (i.e., fewer round length).

Solution Comparison As shown in Table. III, we evaluate the solutions in two scenarios: 1) stop the training at the preset round and compare the best accuracy and average round length. 2) stop the training when a preset test accuracy is



(a) On FEMNIST



(b) On Shakespeare

Fig. 5. Test accuracy under different aggregation methods

achieved and compare the total time and number of rounds needed for convergence. We can see that, compared with FedAvg, layer freezing shortens the round length by 30% and 33%, respectively, while not hurting the accuracy and model convergence. After applying client selection, the round length can be further reduced by 4% and 16%, respectively, but accuracy may be reduced due to additional statistical heterogeneity introduced by biased client selection. Tackling such accuracy reduction is the main target of warm-restart. We can observe that warm-restart increases accuracy at the cost of slightly increasing round length but still has a shorter round length than only applying layer freezing. Compared with the other two baselines, we got a big win in accuracy and convergence while being competitive in round length. This is because we consider the interaction between two heterogeneity and tackle the trade-off properly when deciding the number of frozen layers and client selection.

Furthermore, the variance in accuracy and convergence could be alternatively explained by Fig. 4. In this experiment, we divide the clients into 40 groups based on their capabilities. The clients in group 1 have the least capability, namely, the stragglers. In contrast, the clients in group 40 have the most powerful capability. Fig. 4 records the number of participation of the groups. We noticed that warm-restart does improve fairness. It less chooses the clients with powerful capability and guarantees the number of participation of the stragglers. It explains why warm-restart improves the accuracy but has a slightly larger round length. Compared with RBCS-F, we better guarantee fairness in the extreme case where the ability gap is up to six times. As described in Section. IV-B, the clients whose model exchange time is below the average do not need to perform layer freezing, and the client's utility is proportional to the number of unfrozen layers instead of its capability. Therefore, we do not excessively select the most powerful clients. Moreover, we apply the warm-restart in client selection to help stragglers more participate in training. To sum up, freezing-based reputation precisely captures the presence of stragglers and reduces their involvement, and warm-restart is used as a tuning knob, which can be adjusted according to different requirements for fairness.

Model aggregation analysis Next, we compare the layerwise aggregation with the normal weighted aggregation used in FedAvg. As shown in Fig. 5, layerwise aggregation stably achieves higher accuracy because it considers the heterogeneity in the degree of freezing and kicks out the weights of frozen layers during aggregation to prevent it slow down the convergence. With layerwise aggregation, layer freezing could bring more significant improvement to FL.

Algorithm adaptation Finally, our proposed layer freezing and client selection methods can be independently combined with other approaches to obtain better results. We demonstrate it by combing our client selection method with Fjord. To achieve it, we use the dropout rate instead of the number of unfrozen layers in Eq. 5 to estimate clients' capability. As shown in Table. IV, Fjord with client selection achieves better accuracy and shorter round length on both datasets. Furthermore, FreezeFL remains client-oblivious when combined with other methods.

VI. Conclusion

We proposed FreezeFL, which is the first work introducing layer freezing to solve system heterogeneity to the best of our knowledge. We first justify the challenge of introducing layer freezing to FL and then address the challenge by quantifying the two heterogeneity and exploring a one-dimension tuning space. We further design a client selection algorithm that cleverly uses the number of unfrozen layers to identify clients' capability to achieve client-oblivious. Furthermore, we apply warm-restart to provide a fairness guarantee and improve model performance. Our empirical evaluation across two federated datasets has demonstrated that FreezeFL can significantly improve training efficiency while not hurting model performance under the heterogeneous FL. Several remaining problems are worth to further study in the future, including providing theoretical analysis on the convergence of our technique, improving client selection and layer freezing decisions based on more experimental analyses, comparing our results with other types of system heterogeneous solutions, such as network pruning, and evaluating the impact from other FL challenges, such as the data privacy issue and availability problem in the cross-device environment.

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Federated Learning: A Survey on Statistical and System Heterogeneity

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ABSTRACT With the development of Artificial Intelligence (AI) and growing data privacy concerns, Federated Learning (FL), the paradigm for distributed training on data silos in a privacy-preserving manner, is proposed. Specifically, FL allows data silos or edge devices to collaboratively learn a shared model while keeping all the private data locally and thus enable more secure and accurate model training. However, as the FL is deployed in edge devices and applied in large-scale scenarios(e.g., cross-countries), the differences in data properties and computing power lead to the challenges of heterogeneous learning. These issues have quickly attracted the research community's attention but are still open problems and lack systematic review. In this survey, we explore the domain of heterogeneous FL, especially in 1) statistical heterogeneity, non-identically distributed data on edge devices. 2) system heterogeneity, the significant variability in system characteristics on edge devices. We analyze the root causes and the derived issues of the two heterogeneities and propose a unique taxonomy of heterogeneous FL techniques based on their key ideas and strategies. In addition, we present limitations of existing works under multiple heterogeneities and help researchers design algorithms robust to both statistical and system heterogeneities. Finally, we discuss the open problems of the two heterogeneities and several promising future research directions.

INDEX TERMS Federated learning, statistical heterogeneity, system heterogeneity, survey

I. INTRODUCTION

WITH the vigorous development of edge devices, such as mobile phones and Internet-of-Things (IoT) devices, an unprecedented amount of data are generated at the edge side. While the numerous data are attractive for the deep learning (DL) community, they exist as data silos due to privacy concerns and intolerable communication costs. Specifically, traditional centralized model training approaches require edge devices to transfer their data to a third-party server for training. However, as people gradually attach importance to privacy preservation, legislation such as the general data protection regulation (GDPR) is introduced to prevent the leak of sensitive data, such as health information and personal preferences. In addition, aggregating such a tremendous amount of data is a severe challenge to the communication cost of the server and edge devices. To break data silos and solve the above challenges, federated learning (FL) was proposed and has drawn great attention to academic and industry communities. FL [1] is a distributed learning paradigm without centralizing data and with privacy by default. FL allows data silos (a.k.a. clients), which can be edge devices or organizations, collaboratively train a shared model under the coordination of the FL server. More specifically, the FL server first initializes a global model and broadcasts it to selected clients. Next, each client performs training on the received model by using its private dataset and uploading model updates to the server. Then the server aggregate all model updates to construct an improved global model for the next round of training. The above steps are iterated several times to build a global model which achieves target accuracy. With this innovative operational concept, FL can offer various benefits, such as data privacy enhancement and better utilization of private data. However, the differences between centralized learning and collaborated learning bring several new challenges to FL, including system design [2], communication [3], resource management [4], and privacy attack [5]. In this survey, we focus on the challenge of statistical and system heterogeneity, which has become a critical problem since the larger scale and more extensive learning environment exacerbate the disparity and diversity

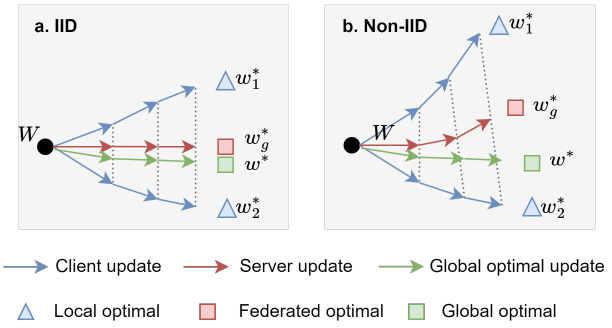

FIGURE 1: Illustration of weight divergence from statistical heterogeneity. The client drift leads to a diverged FL model. (a) IID setting. (b) Non-IID setting

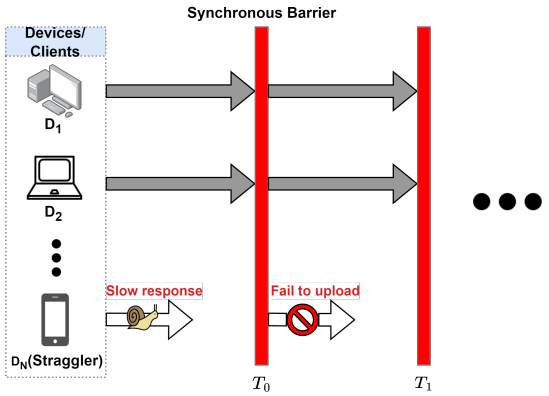

FIGURE 2: Illustration of straggler issue from system heterogeneity. Each round of FL training gets stuck with the straggler.

among the FL clients in terms of their data quality (statistical heterogeneity) and compute capability (system heterogeneity).

A. CHALLENGES OF STATISTICAL HETEROGENEITY

Statistical heterogeneity refers to non-independent and identical distribution (non-IID) data. The IID sampling of training data is an essential assumption for DL algorithms to get an unbiased estimate of the full gradient. Furthermore, the effectiveness of stochastic gradient descent (SGD), widely used in FL, also relies on the IID assumption. In centralized distributed learning, non-IID data have been fine since the server has access to the whole training dataset and splits it in a carefully designed IID manner. Unfortunately, in FL, it is unrealistic to assume that the local datasets are IID since each local dataset is only accessible by the data owner. Moreover, the local datasets usually follow different data distributions due to the difference in how clients collect data. Under the challenge of non-IID data, FL suffers from serious accuracy loss and convergence speed degradation.

B. CHALLENGES OF SYSTEM HETEROGENEITY

System heterogeneity means the significant variability in processing capabilities on edge devices. As the deployments move from the data center to the edge devices, edge devices' computation, and communication capabilities are less powerful than the central server, and the gap between devices is even more prominent. In addition to the heterogeneity of hardware resources, variability in the size of local datasets, network bandwidth, and battery level further contribute to a significantly inefficient training environment. In addition, system heterogeneity makes straggler issue [6] more prevalent than the centralized environment., where straggler issue means a subset of clients may slow down the wall-clock time convergence due to their poor completion time.

Actually, the two types of heterogeneity coexist in FL, and an interplay exists between them. For example, as shown in [7], the methods solving system heterogeneity, such as dropping stragglers (as in FedAvg) or naively tolerating partial model update, implicitly increase statistical heterogeneity and further hurt the model performance. Similarly, the methods solving statistical heterogeneity, such as selecting specific clients in each training round, may hurt training efficiency since the 'good' clients for statistical heterogeneity may be the stragglers, which are 'bad' clients for system heterogeneity. We revisit the concepts in greater detail subsequently.

C. COMPARISON AND OUR CONTRIBUTIONS

With the recent advance of FL, several surveys or tutorials related to FL were proposed. However, the existing studies treat two heterogeneities separately and do not discuss the solutions to the two heterogeneities in depth. For existing surveys in FL, the comparison of their contribution and discussion on heterogeneity are summarized in Table. 1. In this table, we confirm whether the existing survey papers satisfied below four requirements: 1) introduce heterogeneities in detail (background), 2) present and analyze the existing works (algorithm), 3) put two heterogeneities together to discuss (discussion), 4) and proposed a systematic taxonomy (taxonomy).

Some survey papers focus on introducing the concept of FL and summarizing the open challenges. For example, the authors in [8]–[10] provide definitions, categorizations, and applications for FL. Furthermore, they also discuss the open challenges of FL and how FL can be applied to various industries successfully. The authors in [11] discuss the unique characteristics and challenges of FL and introduce a few promising future directions surrounding the challenges of FL. The focus of [12] is systematically introducing FL from the aspects of data partitioning, privacy mechanism, learning model, system architecture, and system heterogeneity. In addition, authors in [2] take a survey on FL from the system view and analyze the system components, including clients, FL server, and the computation-communication framework. Other surveys in [3], [13] discuss the key challenges and future research direction on FL in the context of 5G and 6G wireless communication, respectively. Meanwhile, the authors in [14] discuss FL as an enabling technology for mobile edge computing (MEC) optimization and describe the

potential applications of FL in MEC. Furthermore, the survey in [15] presents a concept of integrating FL and blockchain and further explores the opportunities of such integration in MEC networks. In addition, the authors in [4] explore and analyze the opportunity of FL for enabling IoT devices such as data offloading, caching, and privacy. The similar concept of integrating FL and IoT and taxonomy for FL over IoT networks are also explored by [16]. Moreover, the work in [5], [17] both provide comprehensive surveys on threat models and attacks on FL, such as poisoning attacks, inference attacks, and backdoor attacks, and discuss future research directions towards more robust privacy in FL. The authors in [18] explore the concept of personalized FL to address the challenge of statistical heterogeneity.

In summary, the existing surveys and tutorials on FL do not put two heterogeneities together to discuss, and they need more exploration of the interplays between proposed approaches and heterogeneities. Therefore, it motivates us to take a survey that comprehensively discusses system and statistical heterogeneities and how to tackle two heterogeneities simultaneously. The contributions of this survey are as follows.

- We provide an overview, categorization for FL, and a deeper discussion about the challenges of statistical and system heterogeneities.
- To our best knowledge, this survey is the first to perform a holistic analysis of the strategies for solving system and statistical heterogeneities and present limitations of existing works under multiple heterogeneities. Furthermore, we propose a hierarchical taxonomy to present existing works on heterogeneity, as shown in Fig. 3, highlighting the challenges, assumptions, main ideas, and limitations.
- We highlight the lesson learned from the existing works and identify several possible directions for future works toward building FL robust to statistical and system heterogeneity.

The rest of this paper is organized as follows. Section. III reviews the solutions provided to tackling statistical heterogeneity. Section. IV discusses the approaches for system heterogeneity. Section. V discusses the limitations of existing works under multiple heterogeneities and presents the advance works considering both heterogeneities simultaneously. Section. VI highlights several promising research directions for heterogeneity in FL. Section. VII concludes this paper.

II. FEDERATED LEARNING: FUNDAMENTAL CONCEPTS AND PRELIMINARIES

This section presents an introduction to FL, a detailed definition of statistical and system heterogeneities, and an overview of issues brought by the two heterogeneities.

A. FEDERATED LEARNING

FL is a distributed machine learning paradigm aiming to address privacy concerns among data owners. Specifically, FL allows clients to collaboratively train a global model without sharing their private data with others. Therefore, FL has the potential to utilize a large amount of private data and contributes to the progress of deep learning. For an introduction to FL categorizations based on the data distribution characteristics, e.g., vertical, horizontal, and transfer, we refer the readers to [8]. In this survey, if not specified, the FL setting is horizontal.

FL differs from centralized training, which aggregates data from each resource before model training. Generally, the two main kinds of components in the FL system are clients (data owners) and the FL server. Let $\mathcal{N} = \{1, ..., N\}$ denote the set of clients, which can be IoT devices or computers in different organizations. In an FL process, each client $i \in \mathcal{N}$ uses its local private dataset D_i to perform local training on a local model w_i, and uploads only the local model weights to the FL server. Then the FL server aggregates all local models to update a global model w_g.

In general, the FL process follows the below four steps, first proposed by McMahan et al. [1]

1) **Training Initialization**: The FL server first decides on the target task, such as computer vision and natural language processing. Then it sets up the model architectures, data requirements, and hyper-parameters. Some FL frameworks even synchronize hardware resource information with clients in this step.
2) **Client Selection**: Unlike distributed learning, FL allows only a subset of clients S to participate in training in each round instead of all. The most basic approach is random sampling, meaning every client has the same probability of being selected. Moreover, the FL server may select clients based on several factors, such as local loss or communication conditions, to improve model accuracy or training efficiency. After selection, the FL server broadcasts the global model w_g^t to the selected clients, where t denotes the current round index.
3) **Distributed Local Training**: After receiving the global model w_g^t, selected clients start the local training task. Each client $i \in S$ updates the local model w_i^t iteratively by the local dataset D_i and tries to find the optimal model w_i^* that minimizes the loss function $\mathcal{L}(w_i^t)$:

$$w_i^* = \arg\min_{w_i^t} \mathcal{L}(w_i^t)$$

The loss function can be different for different FL approaches. We will discuss this in detail in a subsequent section. Finally, the updated local models $w_{i \in S}$ are subsequently uploaded to the FL server.
4) **Model Aggregation and Global Model Update**: After the server collects local model updates from selected clients, it aggregates them and updates the global model as follows:

$$w_g^{t+1} = \frac{1}{\Sigma_{i \in S}|D_i|} \sum_{i \in S} |D_i| w_i$$

The aggregation method above is called weighted av-

Reference	Topic	Contribution	Heterogeneity			
			Background	Algorithm	Discussion	Taxonomy
[8]	FL concept	Introducing the categorization of different FL schemes, such as horizontal FL, vertical FL, Federated Transfer Learning.	×	×	×	×
[9]		Elaborating comprehensive taxonomies covering various challenge, contributions, and trends.	✓	✓	×	×
[10]		Providing a thorough summary of the most relevant protocols, platforms, and real-life use-cases of FL.	✓	✓	×	×
[11]		Providing a tutorial on FL and a discussion of the open problems worth future research effort.	✓	✓	×	△
[12]		Introducing FL from five aspects: data partitioning, privacy mechanism, machine learning model, communication architecture and systems heterogeneity.	✓	✓	×	×
[2]	FL systems	Providing a comprehensive analysis on FL from a system's point of view.	×	×	×	×
[3]	Wireless FL	Discussing the role of FL addressing the challenges in 5G wireless communication.	×	×	×	×
[13]		Introducing the integration of 6G and FL, FL applications and open problems in the context of 6G communications.	✓	×	×	×
[14]	FL with MEC	Discussing FL as an enabling technology for MEC optimization, and the application of FL in edge computing.	✓	✓	×	×
[15]	FL with blockchain	Discussing an emgerging paradigm in MEC enabled by the integration of FL and blockchain.	✓	✓	×	×
[4]	FL with IoT	Providing a comprehensive survey of FL and IoT networks, especially their integration.	✓	✓	×	×
[16]		Presenting the advances of FL towards enabling FL-powered IoT applications and a taxonomy for FL over IoTnetworks.	✓	✓	×	×
[5]	FL with privacy	Providing a taxonomy covering threat models and major attacks on FL: poisoning attacks and inference attacks.	×	×	×	×
[17]		Providing a study on the security and privacy achievements, issues, and impacts in the FL environment.	×	✓	×	×
[18]	Personalized FL	Exploring personalized FL to address statistical heterogeneity, and presenting a taxonomy of personalization.	✓	✓	×	×

TABLE 1: Summary of selected survey in FL, where ✓ means the objective is well achieved, △ mean that the objective is achieved but can be improved, and × means that the objective is not considered or achieved.

eraging [1], which weights the clients based on the number of samples in their local datasets. In the current research, the aggregation method can also be different for improving model performance.

Then the steps 2∼4 are repeated iteratively until the global model converges or the target number of communication rounds is achieved.

B. STATISTICAL HETEROGENEITY

Statistical heterogeneity refers to the heterogeneity of local datasets across clients, namely, *non-IID*. All along, DL algorithms are usually designed based on the assumption of IID. However, in the FL setting, privacy requirements limit data access to the local datasets. In addition, the data properties of local datasets may be different from each other. After moving away from the IID assumption, FL suffers severe accuracy loss and convergence speed degradation. In this subsection, we first introduce the categories of statistical heterogeneity and then analyze the their impact on FL training. Note that we alternate statistical heterogeneity with non-IID in the following sections.

1) Categories of Statistical Heterogeneity

a: Feature distribution skew

The features refer to the information of data and usually serve as input of a DL model. Feature distribution skew means that the feature distribution $P_i(x)$, where x refers to the input variable, varies between clients i. At the same time, a conditional label distribution $P(y|x)$ is shared, where y refers to the class variable. For example, in a digit handwriting recognition task, different writers can be regarded as different clients. The digits written by different clients may have various strokes, widths, or slants (different feature distribution $P_i(x)$). Meanwhile, the predicted labels of the same digit written by different clients are close (same $P(y|x)$).

b: Label distribution skew

Label distribution skew refers that the label distributions $P_i(y)$ varies between different clients i, while a conditional feature distribution $P(x|y)$ is shared. For instance, in the cat-dog recognition task, the clients preferring cats own more cat data, and vice versa (different label distribution $P_i(y)$). Meanwhile, when the y is given, even the data held by different clients will have the same features (same $P(x|y)$). Generally, the setting of label distribution skew in FL research is making the label distribution of local datasets follow Dirichlet distribution $Dir(\beta)$, where β is the hyperparameter tuning the imbalance level. A larger β value leads

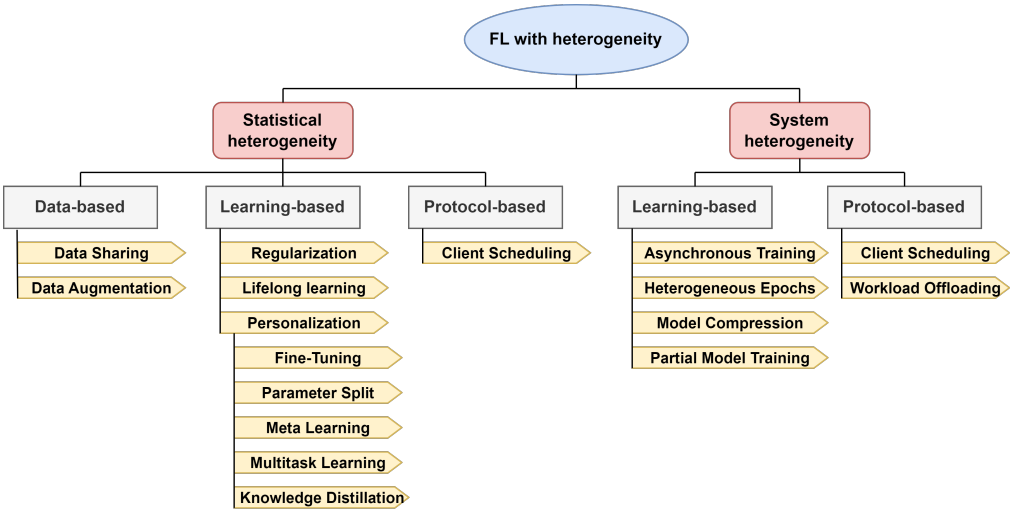

FIGURE 3: Taxonomy of heterogeneous federated learning

to a more unbalanced data partition, and vice versa.

c: Quantity skew

Quantity skew means that the number of local data varies according to clients.

d: Concept shift

Concept shift happens when the relationship between the input and label variable varies between clients. It can be further subdivided into the following two types. The first is that the data sharing the same label may have different features, namely, a conditional feature distribution $P_i(y|x)$ varies between clients, although $P(y)$ is shared. For example, images labeled as 'cat' (same $P(y)$) may contain different species which have distinct features (different $P_i(y|x)$) due to geographic location. The second type of concept shift is that the data sharing the same features may have different labels, namely, a conditional label distribution $P_i(x|y)$ varies between clients, although $P(x)$ is shared. For instance, clients may hold different views (label) on the same image (data) due to their preferences.

2) The Effect of Statistical Heterogeneity on FL

For the above different categories of non-IID, what they have in common is that each local dataset can not represent the global dataset; namely, the data owned by each client is incomplete. Although the authors in [1] claim that FedAvg is robust to non-IID data, recent work [19] has theoretically shown that non-IID data slow down the convergence of FedAvg [1], which match empirical observations. This performance degradation can be attributed to the phenomenon of weight divergence [20], which means that the weights of each local model converge in different directions, and the aggregation of the local models will have an error with the optimal one. Weight divergence can be understood with the illustration in Fig. 1. When data is IID, for clients 1 and 2, the divergence between federated optimal w_g^* (global model), which is the average of local optimal w_i^* (trained local model), and global optimal w^* is small. However, when data are non-IID, the divergence between w_g^* and w^* becomes much larger since the heterogeneity of data makes clients converge to completely different local optimal points. Furthermore, Zhao et al. [20] quantify the weight divergence by the EMD between the distribution over classes on each local dataset. For the mathematical definition of EMD, we refer interested readers to [21]. Here, the important insight is that the greater the difference in the label distribution or feature distribution between local datasets, the higher the degree of non-IID and the higher the impact on training. Although the simulation result shows that sharing data with other clients [20] can reduce EMD and improve accuracy performance, such a data-sharing strategy is unrealistic due to violating privacy requirements.

C. SYSTEM HETEROGENEITY

System heterogeneity means the heterogeneity of processing capabilities on clients. The participants in FL are usually edge devices with less computation and communication capabilities than the powerful clusters. Generally, the time required for each client to complete local training is inversely proportional to its capabilities. Therefore, system heterogeneity leads to variability in the completion time of local training tasks. Then it further brings a straggler issue, which significantly degrades the training efficiency of FL. In this subsection, we first introduce the composition and factors of the local training workload, then detail the straggler issue.

a: Workload of Local Training

Given a local training task, the workload can be divided into the following two types:

- Communication: It includes downloading the latest global model and uploading model updates. The communication workload is positively correlated to the size of the model architecture. For clients, the completion

time of communication depends on the stability of network connection, bandwidth, transmission latency, etc.
- Computation: It includes performing training on the local model with private data. The computation workload is positively correlated to the complexity of model architecture, the number of local epochs, size of local datasets. For clients, the completion time of computation depends on the hardware resources, such as processing units, memory, battery level, etc.

b: Straggler Issue

Synchronous distributed learning means the server must wait for every worker to complete assigned work before starting the next round of training. If the difference in workers' completion time is too large, a straggler issue will be derived. Specifically, as shown in Fig. 2, the straggler issue means that the time cost of a training round is bounded by the slowest worker and significantly reduces the training efficiency. Unfortunately, the standard FL algorithm is synchronous, and system heterogeneity causes the completion time of clients to vary a lot. In FedAvg, the way of handling system heterogeneity is dropping stragglers which do not complete local training in time. Although the exclusion of stragglers improves training efficiency, it makes the waste of potential high-quality data and may bring model performance reduction. For FL, handling stragglers or reducing the computation and communication costs without hurting model performance is still an open question.

D. BASIS AND ADVANTAGES OF OUR TAXONOMY

The optimization of FL involves many aspects, such as adjustment of local datasets, local training algorithms, aggregation methods, and interaction between FL components. In order to help readers better understand which part of the FL process each work optimizes, we derive a taxonomy based on *where* the works optimizes. As shown in Fig. 3, we divide existing works into data-based, learning-based, and protocol-based. Data-based algorithms are usually executed during task initialization (step 1 in Sec II-A), and they all focus on augmenting local datasets. Next, the learning-based category refers to the works optimizing learning algorithms of FL, such as the DL hyper-parameters, local training (step 3 in Sec II-A), and aggregation methods (step 4 in Sec II-A). Last but not least is the protocol-based category, which refers to the works optimizing the interaction between the FL server and clients, such as client selection (step 2 in Sec II-A). Moreover, some works in the protocol-based category even try to modify standard FL architecture to achieve more efficient training.

After categorizing existing works based on *where* they optimize, we further classify them based on *how* they optimize, namely, their key techniques. For example, the data-based approaches are divided into data sharing and data augmentation based on whether they directly share raw data. More detailed discussions with insights will be given in later sections. In summary, our taxonomy can help readers not only understand what state-of-the-art methods are but also better understand which parts of the FL process these approaches specifically optimize. It is worth noting that a single work can be classified into more than one category since it involves multiple optimization methods. For example, Astraea [22] is classified into data-based and protocol-based approaches since it involves data augmentation techniques and client scheduling algorithms.

III. TAXONOMY OF STATISTICAL HETEROGENEITY

In this section, we present a unique taxonomy of works on statistical heterogeneity according to their key insight and technique. Based on our proposed taxonomy, the works are divided into *data-based*, *learning-based*, and *protocol-based*. Data-based algorithms aim to solve statistical heterogeneity by modifying the data distribution of local datasets to reduce the degree of non-IID. In addition, learning-based algorithms revise the optimization objective or the learning algorithm to relieve the negative impact brought by non-IID data. Finally, protocol-based algorithms solve it by proposing new FL system architectures or communication protocols. The detailed discussions are as follows.

A. DATA-BASED ALGORITHMS

Motivated by the fact that statistical heterogeneity arises from the EMD between the data distribution of local datasets, data-based algorithms aim to re-balance the data distributions of local datasets and make them more representative of the global data distribution. Specifically, data-based algorithms can be divided into two categories. The first is directly sharing raw data with clients or the server, and the other is performing data augmentation to compensate for the lack of specific data types. We detail the data-based algorithms in this subsection.

1) Data Sharing

As shown in [20], the test accuracy falls sharply with respect to EMD beyond a certain threshold. Thus, for non-IID data, the model performance can significantly increase by slightly reducing EMD. The intuitive and effective way to achieve it is by building an IID globally shared dataset. As shown in Fig. 4(a), Zhao et al. [20] proposed a data-sharing strategy that distributed a subset of the globally shared dataset to each client to re-balance its data distribution. The experiment results show that the accuracy can be improved by 30% for the CIFAR-10 dataset with only a tiny amount of globally shared data. In contrast to distributing data to clients, Hybrid-FL [23] updates the global model with the shared dataset gathered from the volunteered clients in addition to aggregating the model updates in each round. Hybrid-FL can be intuitively seen as several additional clients with IID data also participating in each round of training, and the EMD is therefore reduced. Although the above two algorithms differ in applying globally shared datasets, they achieve the same purpose. Both works show that a shared dataset with a size of 1%∼5% of the total data is enough to relieve the accuracy

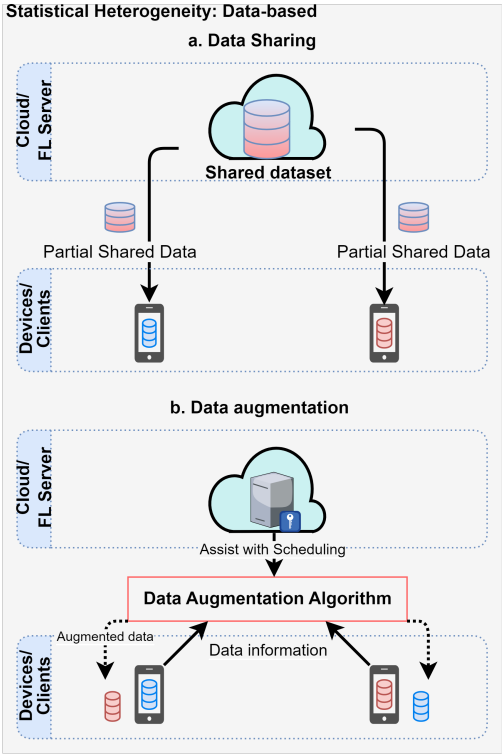

FIGURE 4: Illustration of data-based approaches, including (a) data sharing and (b) data augmentation.

degradation brought by non-IID data effectively. However, it is unrealistic to assume that the server already has an available globally shared dataset [20]. In addition, requiring the clients to upload raw data [23] also violates the purpose of FL.

2) Data Augmentation

Compared with data sharing that directly shares raw data, data augmentation reduces EMD through generating synthetic data (Fig. 4(b)). Data augmentation has been extensively studied in DL to compensate for the lack of data. For class-imbalance learning, over-sampling [24], [25] which generates synthetic data for the minority class, and under-sampling [26] which uses only a subset of the majority class, have been proposed. In addition, data augmentation techniques based on the original data, such as cropping, rotation, and random erasing, are also used to inflate the dataset and further improve the performance of the DL model [27]–[29]. However, the above techniques can not be directly applied to FL since the private data is only accessible to the data owner.

Limited by the privacy requirement of FL, data augmentation is highly challenging in FL. The data augmentation algorithms in FL can only rely on a tiny number of local data or conceive some forms of data sharing that do not violate privacy. Duan et al. [22] proposed Astraea, a self-balancing FL framework that solves imbalanced global data by Z-score-based data augmentation. Astraea first defines the under-sampling and over-sampling threshold and treats a class as a majority or minority class if its z-score is greater than the under-sampling or less than the over-sampling threshold. Then all clients perform data augmentation, such as shift, rotation, and zoom, on minority classes and drop partial samples of majority classes. However, the augmentation methods in Astraea rely on a tiny local dataset of each client, so it may not be feasible in highly skewed non-IID scenarios. In addition, it may take work to decide the thresholds for different scenarios in advance. To generate more diverse data and tackle the limitation of relying on a single local dataset, several works indirectly share data information. Hao et al. [30] proposed ZSDG that generates synthetic labeled data by finding the data that result in similar statistics as those stored in the batch normalization layers of the trained model. Although ZSDG does not need any access to private data and can generate diverse data, the quality of synthetic data highly depends on the model performance. Therefore, ZSDG may not help convergence in the early stage of training. Shin et al. [31] proposed XorMixFL, a privacy-preserving XOR-based mixup data augmentation technique. The core idea of XorMixFL is collecting other clients' encoded samples, which are decoded only with the data samples of each client. Since both encoding and decoding are bit-wise XOR operations that intentionally distort raw data, data privacy is preserved to some degree. Similarly, Yoon et al. [32] proposed FedMix, which appropriately modifies Mixup [33], a popular data augmentation technique generating synthetic data by linear interpolation between samples, under the restrictions of federated learning. In FedMix, clients exchange averaged data comprised of M local samples. Then, FedMix modifies the local loss function to approximate the global Mixup with only averaged data, where global Mixup means that raw data are exchanged and directly used for Mixup between clients. However, the works indirectly sharing data information may cause some privacy issues. There is the possibility that individual data could be inferred from the exchanged information, such as batch normalization layers, encoded data, and averaged data. In addition, the ownership or data distribution of local datasets also could be inferred if the exchanged information includes client-specific information or labels. Therefore, with users' different privacy requirements, the above methods may not be directly applied in FL.

Moreover, Generative Adversarial Network (GAN) [34] has also been applied in FL for data augmentation. Jeong et al. [35] proposed FAug, which trains a conditional GAN [36] with the seed data samples uploaded by clients. The trained GAN generator is distributed to each client, and each client can replenish the minority classes until reaching an IID dataset. With a similar idea of FAug, Yan et al. [37] proposed FAu, which trains a WGAN [38] at the server and lets clients replenish the lack of their local datasets with it. Recently, GAN has also been applied in FL for facilitating COVID-19 detection. Nguyen et al. [39] and Zhnaget al. [40] proposed FedGAN and FedDPGAN, respectively. To better protect privacy, both FedGAN and FedDPGAN

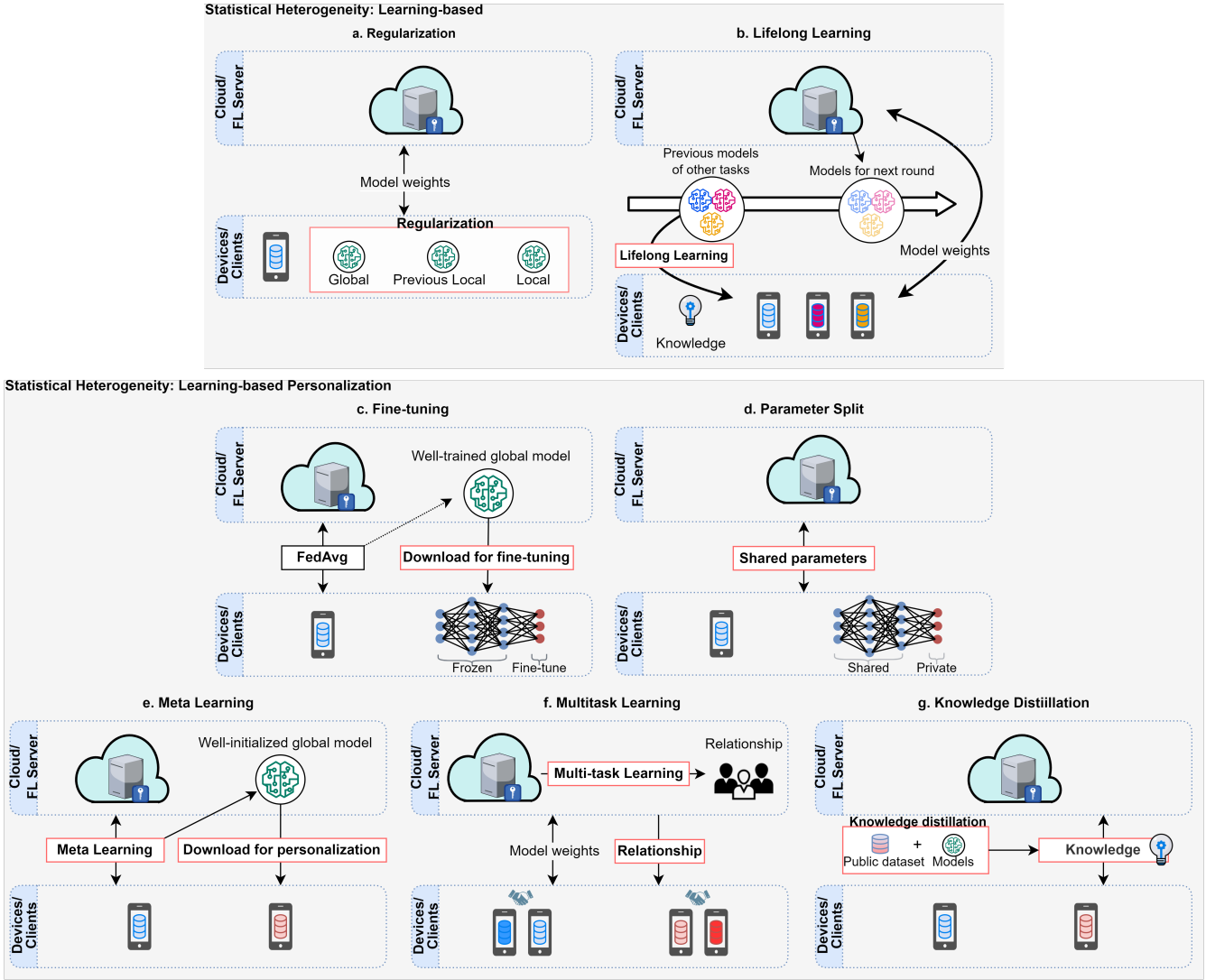

FIGURE 5: Illustration of learning-based approaches, including (a) regularization, (b) lifelong learning, (c) fine-tuning, (d) parameter split, (e) meta learning, (f) multitask learning, and (g) knowledge distillation.

train a GAN following the standard FL procedure instead of uploading raw data to the server like FAug and FAu. Specifically, the GAN model weights are exchanged between the server and medical institutions and updated iteratively on the client side. After the training, the GAN model is used to perform COVID-19 image augmentation and solves the non-IID issue. Furthermore, the differential privacy (DP) technique, which adds Gaussian noise in the training gradient or model weight, is integrated into FedGAN and FedDPGAN to alleviate the privacy leakage from the GAN model weight. However, although DP effectively increases privacy, it reduces the quality of data generated by GAN, which in turn degrades model performance. Achieving a balance between privacy preservation and model performance is still an open problem for further investigation.

B. LEARNING-BASED ALGORITHMS

On the non-IID data, the model weights of local models usually diverge, and such conflicting model updates further hurt the performance of the global model. To handle the weight divergence, learning-based algorithms modify the optimization objective or learning algorithms. More precisely, some algorithms add a regularization term into the loss function to prevent weight divergence. In addition, several existing DL techniques are applied to FL to help local or global models generalize better. Furthermore, the concept of personalization is proposed to train a specific local model for each client instead of a single global model. In this subsection, we review the ideas and techniques applied by the learning-based algorithms in detail.

1) Regularization

Regularization is a technique that lowers the complexity of a neural network and thus prevents overfitting and improves generalization while training DL models. In FL, regularization can be used to prevent local models from drifting away from the global optimal point and overfitting to their local objectives. Specifically, instead of only minimizing the local loss function $F_k(\omega)$, clients minimize the following objective, which considers the regularization terms $L_{reg}(\omega)$:

$$\min_{\omega} h_k = F_k(\omega) + L_{reg}(\omega) \tag{1}$$

In FL, several existing works mitigate weight divergence by introducing a variety of regularization terms (or proximal terms) to restrain local model updates to the global model. Generally, the regularization terms are composed of the local model, local historical models, or the global model, as shown in Fig. 5(a). Karimireddy et al. [41] proposed SCAFFOLD, which uses variance reduction to correct the weight divergence in clients' local updates. SCAFFOLD estimates the update directions for the global model (c) and local models (c_i). Then the difference of directions ($c - c_i$) is used as the correction terms to correct the local update and ensure the updates move towards the true optimum. Li et al. [7] proposed FedProx, which introduces a proximal term $\frac{\mu}{2}\|w - w_t\|$ to penalize local updates far from the global model. Furthermore, FedProx considers the interaction between statistical and system heterogeneity and allows for safely incorporating local updates with variable local epochs. Recently, Acar et al. [42] has shown that minimizing local empirical loss is fundamentally inconsistent with minimizing the global one under non-IID data. Motivated by the idea, FedDyn [42], which dynamically modifies the local objective with a proximal term, was proposed to ensure that the local optimal point is asymptotically consistent with the stationary point of the global empirical loss. In addition, with the intuitive insight that the global model integrating the knowledge of all local datasets can perform better than each local model, Li et al. proposed MOON [43], which utilizes the similarity between model representations to correct the local objective. Specifically, MOON adds a regularization term to minimize the distance between the representation of the global model and the local model and increase the distance between that of the current and previous local models. Although MOON achieves state-of-the-art results in learning visual representation, it incurs $\sim$ 3x cost in both memory and computation since calculating the loss function requires storing three models in memory and forward passing of each model every local epoch. In a resource-scarce FL setting, the resource requirement of MOON may not be satisfied.

Although the works [7], [41]–[43] have brought significant progress on the problem of non-IID data, as shown in [44], since the proximal terms restrain the weight divergence, the local convergence potential of clients is limited, and less information is aggregated per training round. Consequently, several above works do not provide stable performance across variable non-IID settings. To tackle the issue, Mendieta et al. proposed FedAlign [44], which uses a distillation-based regularization, rather than proximal restriction, to promote local learning generality. To be more specific, FedAlign regularizes the Lipschitz constant of the final block in the model for its representations. Furthermore, compared with MOON [43], FedAlign keeps memory and computation resource requirements to a minimum by focusing on the last block only.

2) Lifelong Learning

In lifelong learning, the challenge is to learn multiple tasks with the same model sequentially but without forgetting while learning the new task, where forgetting means hurting the performance of previous tasks. As shown in Fig. 5(b), under the statistical heterogeneity, it is intuitive to view learning a model on each local dataset as a separate learning task. Consequently, lifelong learning shares a common target with FL: learning a task without disturbing the others learned on the same model. With the above intuition, several works are proposed to apply lifelong learning to FL to solve statistical heterogeneity. In addition, the most common lifelong learning algorithm applied in FL is Elastic Weight Consolidation (EWC) [45], which aims to prevent catastrophic forgetting when moving from learning task A to learning task B. The idea of EWC is to identify the critical parameters in the model that are the most informative for task A. Then the model will be penalized for changing these parameters while training task B.

Kopparapu et al. [46] proposed FedFMC, a method that dynamically groups clients with similar archetypes together and regards each group as a task to learn. At first, FedFMC dynamically groups the clients with similar data distributions and makes each group trains its model separately with FedAvg. After the first step, several global models that learn different data distributions are obtained. Next, the merging process begins with a group's model. Then, it iteratively merges each group's model into the globally shared model with the EWC. In the end, FedFMC gets a global model that learns all different data distributions. In comparison with FedFMC, which treats groups as different tasks, FedCurv, proposed by Shoham et al. [47], treats each client as a different task. Specifically, FedCurv uses the EWC algorithm to identify important parameters of each client and then broadcast such information to selected clients in every round. Then selected client will be penalized for drifting away from the important parameters of others while performing its local training. However, the cost of maintaining all the historical information required by FEDFMC or FedCurv is expensive with the aspect of memory and communication, even with some optimization tricks. Motivated by considerable overheads brought by treating groups or clients as different tasks, Yao et al. [48] proposed FedCL, which treats learning on the server as a task and constrains local training with parameter information. Specifically, FedCL uses the EWC algorithm to evaluate important parameters of the global model on a proxy

dataset on the server. Then the importance of parameters is transferred to the clients and is used to constrain the local training and alleviate the weight divergence. Since FedCL performs less EWC and requires less historical storage, it only incurs a few extra costs.

3) Personalization

In the vanilla FL setting, a single global model is trained to fit all clients. However, the global model generalizes poorly due to statistical heterogeneity. Therefore, training a single model may be insufficient for the FL environment, which often has non-IID data. Motivated by the observation, personalized FL (PFL) is proposed to provide a personalized model tailored to each client and better fit the local dataset. Generally, the personalization strategies are related to transfer learning (TL) [49], which extracts knowledge and experience from one or more source domains and applies to the target domain. Specifically, the local datasets are regarded as different domains, and the challenge of PFL is integrating the knowledge of all source domains and applying it to the personalized model (target domain) of each client under the FL setting. In this subsection, we discuss the key ideas and techniques in personalization strategies.

a: Fine-Tuning

Fine-tuning in DL means training a model from a pre-trained one instead of scratch. As illustrated in Fig. 5(c), the works that apply fine-tuning into FL involve two steps: 1) training a single global model via FL; 2) each client fine-tunes the global model with its local dataset. FedHealth [50] and FedSted [51] both follow the steps mentioned above to achieve personalization. In addition, several techniques, such as parameter freezing and correlation alignment (CORAL) layer, are introduced for better transferring the knowledge. Although the performance of personalized fine-tuning is highly dependent on the global model trained in the first step, fine-tuning algorithms can be easily compatible with FL algorithms optimizing the global model by adding a tuning step.

b: Parameter Split

As shown in Fig. 5(d), parameter split means that the model parameters are divided into shared and private parameters. Shared parameters are exchanged and updated between the server and clients, just like the normal FL process. In contrast, the private parameters of each client are updated separately and not shared with the server. The private parameters excluded from the averaging procedure can help achieve personalization and combat the negative effects of statistical heterogeneity. Bui et al. [52] proposed FURL, which treats user embeddings in a bidirectional LSTM architecture as private parameters. Furthermore, FURL theoretically and empirically shows that parameter split improves model performance in the FL setting. Arivazhagan et al. [53] proposed FedPer, a base + personalized layers approach for PFL. In FedPer, the last fully connected layer is set as a personalized layer to learn the domain-specific features. On the other hand, the FL process updates the base layers to learn low-level features that generalize all clients. With the similar idea of FedPer, FedRep [54] leverages all clients to learn global low-dimensional features and enables each client to maintain a private, personalized classifier. In contrast to FedRep, LG-FedAvg [55] divides parameters with opposite insights. Specifically, the private and shared parameters in LG-FedAvg are designed to be complementary: private parameters are responsible for capturing important features of local data for prediction. By contrast, shared parameters operate only on low-dimensional features and ensure that data from all clients can be classified correctly. In the above works, parameter split also shows additional advantages with respect to privacy and costs. Since the private parameters do not be transferred back to the server, the privacy-sensitive information in such parameters is kept local. In addition, communication cost is reduced because only shared parameters are required to be exchanged during training.

c: Meta Learning

Meta-learning [56] is a learning paradigm that learns "how to learn". In meta-learning, the goal is to let a model learn prior knowledge on a collection of tasks such that it can adapt faster and better when facing new tasks. The characteristic of meta-learning makes it particularly well-suited for PFL. The key insight applying meta-learning into FL is similar to that of lifelong learning: learning on each local dataset is viewed as a learning task. The common meta-learning applied in FL is model-agnostic meta-learning (MAML) [57], which can be applied to any gradient-based approach. Noteworthy, although the algorithm flow of federated meta-learning (Fig. 5(e)) seems like personalized fine-tuning (Fig. 5(c)), which trains a single global model and then performs personalization on it, the global models they trained have different meanings and targets. The global model trained by meta-learning optimizes the performance after adaptation to tasks, while the global model trained by personalized fine-tuning optimizes the performance before adaptation to tasks.

Jiang et al. [58] point out the connection between two widely used FL and MAML algorithms and discover that FedAvg can be interpreted as meta-learning when all clients possess the equal size of the local data. In addition, the authors proposed a fine-tuning stage using Reptile [59] to improve the initial model initialized by FedAvg. Given the relationship between metal learning and FL, this work shows that meta-learning is a critical technique that helps FL yield a better personalization result.

Chen et al. [60] proposed FedMeta, which aims to train an initialization for the global model using all clients. In FedMeta, the local training process is replaced by MAML or MetaSGD [61]. After the training, the well-initialized model is personalized with the local dataset by each client. With a similar idea, Fallah et al. [62] proposed Per-FedAvg, a variant of FedAvg based on the MAML formulation. In Per-FedAvg,

the authors evaluated two forms of approximations to avoid computing second-order gradients, which is computationally expensive and required by MAML. Furthermore, they also characterize how this performance is affected by the closeness of underlying distributions of user data, measured in terms of Total Variation and 1-Wasserstein metric. Compared with the works [61], [62] attempting to approximate Hessian matrix, pFedMe [63], a federated meta-learning formulation using Moreau envelopes, only needs gradient calculation using a first-order approach. Specifically, pFedMe uses Moreau envelopes as clients' regularized loss functions, decoupling personalized models' optimization from learning the global model. Although the problem formulation of pFedMe has a similar meaning to Per-FedAvg, pFedMe pursues the performance of personalized and global models in parallel instead of using the global model as the initialization.

Different from the works [58], [60], [62], [63] optimizing the personalized models for individual clients, GPAL [64] aims to utilize meta-learning to prepare an initial model that can quickly adapt to any group of clients to achieve few-round FL. In more detail, the goal of GPAL is to prepare an initial model that fits a group of clients with new tasks within only a few "rounds", while personalized FL aims for an initial model that leads to personalized models within a few "local updates". Although these are two completely different problems and solutions, they both make the initial model serve as prior knowledge, preventing local models from overfitting the local data and ensuring fast convergence.

d: Multitask Learning

Multitask learning (MTL) is an approach that shares domain-specific information between related tasks to make the model better generalize on the target task. As illustrated in Fig. 5(f), MTL aims to model the relationships between tasks and learn models for multiple related tasks. By regarding the clients in FL as different tasks, MTL approaches can directly capture relationships among non-IID datasets, which helps clients with similar data enable each other to generalize the model better. Furthermore, since each task might not be closely related to all tasks, simply aggregating the weights with unrelated tasks may hurt performance. Therefore, applying MTL to FL also helps clients neglect the information from unrelated clients and further alleviates weight divergence while aggregating model weights.

Smith et al. [65] proposed MOCHA, which extends distributed MTL into FL. MOCHA models the pair-wise collaboration relationships between clients by a bi-convex alternating method that performs well on convex cases. However, MOCHA is not applicable to non-convex problems due to its requirement of strong duality. This motivated Corinzia et al. [66] to propose VIRTUAL, an algorithm for federated multitask learning for general non-convex models. In VIRTUAL, the network between the server and clients is treated as a star-shaped Bayesian network, and learning is performed on the network using approximated variational inference.

Li et al. [67] proposed Ditto, a simple MTL framework addressing the competing constraints of accuracy, fairness, and robustness in FL. Ditto only considers two tasks: the global model and the local model. To relate the two tasks, Ditto incorporates a regularization term, as same as that in FedProx [7], which encourages the personalized models to be close to the optimal global model. Huang et al. [68] proposed FedAMP, an algorithm employing federated attentive message passing to facilitate similar clients to collaborate more. Specifically, FedAMP identifies the relationships between clients by the similarity of clients' model weights. If the model weights of the two clients are similar, they contribute more to each other's local training. Compared with capturing relationships by the similarity of model weights, SFL [69] achieves it by leveraging the graph-based structural information among clients. To be specific, the client-centric model aggregation will be conducted along the relation graph's structure built by a graph convolutional network [70].

However, a general limitation of the above works is that the MTL algorithm is justified qualitatively but not on the basis of clear statistical assumptions on local data distributions. To tackle the limitation, Marfoq [71] proposed FedEM, which studies federated MTL under the flexible assumption that each local data distribution is a mixture of M underlying distributions. In FedEM, a personalized model is a linear combination of M shared component models. All clients are required to learn the M components jointly, while each client learns its personalized one. Although FedEM requires M times of computation and communication costs than FedAvg, the extensive experiments show that FedEM achieves state-of-the-art model performance on accuracy, fairness, and generalization.

e: Knowledge Distillation

Knowledge distillation (KD), referred to as a teacher-student paradigm, is a technique used to transmit learned information in a model-agnostic way. By encouraging the student model to approximate the output logits of the teacher model on the shared data, the student can have a similar or better performance with the teacher. As shown in Fig. 5(g), with the help of a public dataset and knowledge distillation algorithms, we could extract knowledge of local models or the global model and share it to help local training or global model updates. Besides, in the original framework of FL, all clients are required to perform training on a particular model architecture. However, in real-world scenarios, each client might expect to design its model independently due to the differences in personalized requirements, data distribution, and business purposes. Therefore, it poses a practical challenge: model heterogeneity. Preceding weight-based aggregation methods are developed under the assumption that local models share the same model architecture, which can not work on heterogeneous models. To achieve PFL with model heterogeneity, KD is introduced into FL as a translation protocol enabling clients to share knowledge in a model-agnostic way. Moreover, KD alleviates the weight divergence issue since it does not follow weight-based aggregation, which is shown to be

more effective than simple FedAvg.

In general, the main difference of distillation-based FL algorithms is the direction of distillation, which can be classified into three types: 1) distillation between clients, 2) distillation of knowledge from clients to the server to learn a stronger global model, and 3) distillation of knowledge from the server to each client to learn a better-personalized model.

For the first type of direction of distillation, the knowledge communication is mainly based on a public dataset. Jeong et al. [35] proposed federated distillation (FD), which exchanges not the model weights but the model output in the FL process. In FD, each device treats itself as a student and sees the mean model output of all the other devices on a public dataset as its teacher's output. Similarly, Li et al. [72] proposed FedMD, which re-purposes the public dataset as the basis of knowledge transfer. In a round of FedMD, the server collects all clients' model output computed on a public dataset as the consensus. Each client then learns to approach the consensus on the public dataset and fit its own private dataset iteratively for personalization. Huang et al. [73] proposed FCCL, which constructs a cross-correlation matrix to learn a generalizable representation and utilizes KD to handle catastrophic forgetting. Specifically, FCCL distills the knowledge of the local models learned in previous rounds and the initially pre-trained local model to avoid forgetting inter and intra-domain information, respectively. Despite the high algorithm complexity, FCCL achieves state-of-the-art model performance in the comprehensive evaluation.

However, the prerequisite, preparing a public dataset, can leave the above works [35], [72], [73] infeasible for many scenarios. A carefully engineered dataset may only sometimes be publicly available on the server. To tackle such limitation, Zhu et al. [74] proposed FedGen, a data-free KD approach that learns a generative model by ensembling the knowledge of multiple local models over the latent space. To be more specific, given a target label, the generative model can yield feature representations consistent with the ensemble of client predictions. Then this generator is broadcasted to clients to help with local training tasks by augmented samples that embody the distilled knowledge from other clients.

Besides distillation between clients, some works focus on distilling knowledge from clients to the server for a better global model. For example, Lin et al. [75] proposed FedDF, which investigates more powerful and flexible aggregation schemes for FL. In FedDF, FedAvg is first performed among clients to build an initial student model. Then all local models are treated as teacher models to transfer knowledge to the student model via ensemble distillation. Moreover, knowledge may be distilled in a bidirectional manner between the clients and the server. He et al. [76] proposed FedGKT, a variant of the alternating minimization approach to train small local models and periodically exchange their knowledge by KD with a large server-side model. Specifically, the sever-side model takes the feature extracted from the local datasets by local models as inputs and uses the soft labels uploaded by clients to distill knowledge from local models. Similarly, the local models utilize the soft labels predicted by the server-side model to absorb its knowledge. Besides using KD to improve both local and server-side models, another principal advantage of FedGKT is reducing the burden on the computation of clients by shifting it to a more powerful server. However, FedGKT makes clients share ground truth labels with the server, which causes potential privacy risks.

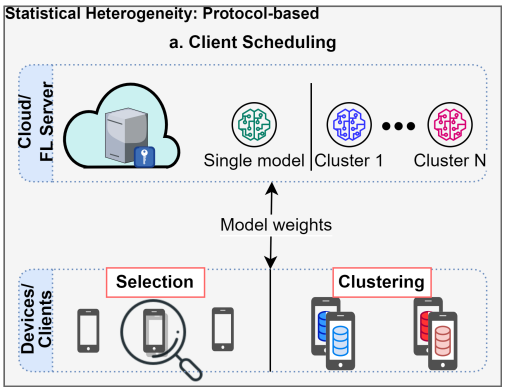

FIGURE 6: Illustration of protocol-based approaches, including (a) client scheduling.

C. PROTOCOL-BASED ALGORITHMS

Protocol-based algorithms aim to design a system architecture or a communication protocol to help counterbalance the bias between clients introduced by non-IID data. Intuitively, an implicit connection exists between model weights and the data distribution of the training dataset. Therefore, actively arranging clients' participation will reduce the negative impact of weight divergence. In this subsection, we detail the concept above and explore the architectures and protocols proposed by the protocol-based algorithms.

1) Client Scheduling

In FL, it is impractical to perform local training on all clients simultaneously due to the limited bandwidth and unstable network connectivity. Therefore, FL algorithms usually select a small subset of clients to participate in each round, which can exacerbate the adverse effects of statistical heterogeneity. In addition, randomly selecting the clients may not be optimal. For example, as shown by Cho et al. [77], the model convergence can be sharply accelerated by biasing the client selection towards clients with higher local losses. In addition, Wang et al. [78] proposed FAVOR, which uses reinforcement learning (RL) to learn which clients have a higher priority in participating in training. FAVOR models the per-round FL process as a Markov Decision Process with the states represented by the model weights, the actions represented by client selection strategies, and the rewards represented by the function of test accuracy achieved by the global model so far. By carefully designing the states and reward functions, the RL agent can learn the potential

interplay between client selection strategies and the model performance and further take the strategy, which aggressively improves the accuracy of the global model. Besides the client selection, Astraea, proposed by Duan et al. [22], alleviates the bias of non-IID data by the mediator-based multi-client rescheduling. Specifically, Astraea divides the clients based on their data distributions and makes the distribution of each group close to uniform. Then the clients in the same group perform local training sequentially to counterbalance the bias introduced by the non-IID data of the clients.

Moreover, some client scheduling algorithms introduce the concept of personalization mentioned before. As shown in Fig. 6, each client can arrive at a more specialized model by clustering the homogeneous clients into the same cluster and training a shared model for each cluster. Next, we introduce the algorithms focusing on clustering for personalization. Sattler et al. [79] proposed CFL, which is viewed as a post-processing method achieving greater or equal performance than conventional FL. With the theoretical finding that the cosine similarity between the weight updates of clients is highly indicative of the similarity of their data distributions, a cosine similarity-based bi-partitioning algorithm is used to divide the clients into clusters. However, the recursive bi-partitioning algorithm requires multiple training rounds to separate all heterogeneous clients. The above drawback limits the scalability of CFL due to the high computation and communication costs. Compared with CFL, which performs clustering every round, FL+HC, proposed by Briggs et al. [80], reduces clustering into a single step to reduce costs. Specifically, the clustering step begins after several training rounds of the normal FL process. At first, the global model is broadcasted and fine-tuned by each client. Then, the difference between the global and fine-tuned local models is used to judge the similarity between clients. Finally, each cluster's FL training is performed independently to generate multiple personalized models. The operation of FL+HC is computationally intensive when there are many clients. Although the operation occurs on the server, the costs of FL+HC still need to be considered while deployed in a real-world environment.

Different from CFL and FL+HC, which do not require setting the number of clusters while clustering, some other algorithms need. Xie et al. [81] proposed FeSEM, which learns multiple global models and simultaneously derives the optimal matching between clients and clusters. FedSEM proposed a formulation to minimize the distance between each local model and the global model of its cluster. Then expectation-Maximization [82] with an additional step, i.e., updating the local model, is applied to solve the distance-based objective function of clustering. FedSEM is an iterative procedure that updates cluster assignments each iteration. The iteration is repeated until convergence. Ghose et al. [83]proposed IFCA, an iterative federated clustering algorithm. Given the number of clusters k, the server constructs k global models and broadcasts them to all clients. Then each client estimates its cluster identity by finding the global model with the lowest local loss. After all clients send their cluster identities and gradients back to the server, the server collects all the updates from the clients whose cluster identities are the same and updates the model of the corresponding cluster. However, the communication cost of the broadcasting step of IFCA is k times as FedAvg. In addition, the edge devices may not have enough resources to store k models in the memory or storage and further be excluded from the training.

D. SUMMARY AND LESSON LEARNED

In this section, we have discussed data-based, learning-based, and protocol-based approaches for statistical heterogeneity in FL. We summarized and compared the works in terms of their key ideas, disadvantages, and limitations, as shown in Table. 2.

Data-based approaches aim to reduce the degree of non-IID by sharing raw data or generating synthetic data. Although data sharing or data augmentation is easy to implement in the realistic FL system and is efficient in relieving accuracy reduction, their applicability is limited due to the possibility of privacy leakage and the potential communication cost of transmitting data information. In data sharing, the server only sometimes has an available globally shared dataset, and the clients may not be willing to share any private data. Therefore, the data sharing approaches may only be applicable in some FL scenarios. On the other hand, although the data augmentation methods avoid sharing raw data by generating synthetic data, they bring additional costs and a trade-off between privacy and model performance. For example, the encode-decode operations and exchanging process in the [31], [32] brings overhead proportional to the number of synthetic data. In addition, training GAN models used to augment local datasets [35], [37], [39], [40] exposes a heavy burden to the clients with limited resources. For the trade-off, performance improvement depends on the quality of synthetic data, but the higher the quality of synthetic data, the higher the possibility of privacy leaks. How to tackle the trade-off and achieve privacy preservation and performance improvement simultaneously is needed to be clarified in the future.

Learning-based approaches aim to tackle statistical heterogeneity by modifying learning algorithms or applying existing DL techniques. One of the key insights of learning-based approaches is that weight divergence can be relieved by punishing local models whose update direction or feature representation is far from that of the global model [7], [41]–[43]. To achieve it, different varieties of regularization terms are introduced to the local loss function to quantify the bias of local updates. Similarly, lifelong learning achieves the same purpose by identifying the important parameters of the local or global models and using them to regularize local training [46]–[48]. Another key insight of learning-based approaches is personalization: providing a personalized model better fits the local data for each client instead of a single global model. The fundamental challenge of personalization

is how to identify and transfer helpful knowledge to build personalized models. Therefore, most PFL algorithms are related to transfer learning. Among the approaches, fine-tuning and parameter split are easy to implement. However, they rely on FedAvg to aggregate the knowledge of all clients, so their performance highly depends on that of the global model obtained from FedAvg and still suffers from the non-IID data. Similarly, the performance of meta-learning methods also depends on the initial global model, which learns the prior knowledge of all clients. In addition, the meta-learning algorithms theoretically require computing Hessian terms, which are computationally prohibitive. Although some approximation methods are proposed to reduce its computation overhead, the costs of meta-learning methods are still considerable. Multi-task learning excels in modeling the relationships between clients and enables clients to learn better with the help of related clients. However, the cost of modeling the relationship between such a significant amount of clients may be infeasible in the FL environment. Compared with the above methods, KD methods give each client better flexibility in designing its personalized model architectures. In addition, KD methods also relieve weight divergence by utilizing KD to transfer knowledge instead of model weight aggregation. Nevertheless, most KD methods require a representative proxy dataset, which may be unavailable in the FL setting. Moreover, KD methods' privacy analysis and protection mechanism should be discussed more.

Protocol-based approaches aim to design a system architecture or a communication protocol to help relieve the bias introduced by non-IID data. The existing works [77] have shown that actively selecting clients each round is a better strategy than random selection. Based on the above idea, several ideas about client scheduling have been proposed and efficiently improve model performance in FL. However, most client scheduling algorithms do not consider system heterogeneity, and not all clients are always ready for training. Therefore, the training efficiency may be degraded due to biased client selection. In addition, client scheduling methods usually assume that all clients' statuses, such as local data distribution and their separate model weights, are known. However, it is infeasible in the FL setting. Moreover, scheduling such a large amount of clients places an enormous burden on the server.

IV. TAXONOMY OF SYSTEM HETEROGENEITY

In this section, we present a unique taxonomy of works on system heterogeneity according to their key insight and technique. Based on our proposed taxonomy, the works are divided into *learning-based* and *protocol-based*. The insight of taxonomy for system heterogeneity is consistent with the one for statistical heterogeneity. Learning-based algorithms aim to solve system heterogeneity by revising the learning algorithm or the information of model updates. In addition, protocol-based algorithm solve it by modifying the FL system architecture or communication protocols. Next, we further introduce and discuss the algorithms in detail.

A. LEARNING-BASED ALGORITHMS

Under system heterogeneity, FL algorithms suffer from stragglers. To solve the straggler issue, learning-based algorithms modify the learning algorithm to reduce the impact of stragglers or balance the workloads. More specifically, some algorithms update the global model with an asynchronous scheduler to tolerate slow clients. In addition, workload balancing re-balances the workload of clients to accelerate the training of stragglers. For example, some algorithms enable heterogeneous local epochs, model architecture, or compression rate of model updates. In this subsection, we explore the learning-based algorithms' main ideas and challenges.

1) Asynchronous Training

Asynchronous training in distributed learning and FL means that the global model can be updated without waiting for others clients. As illustrated in Fig. 7(a), by introducing asynchronous algorithms into FL, each client can train and update the global model at its own pace, and the stragglers do not slow down the whole training process. However, asynchronous algorithms face the challenges of staleness, which means the out-of-date updates from clients, especially slow-responding clients, may not provide helpful information for training or even hurt the global model performance.

To address the staleness, several asynchronous approaches correct the model updates of clients according to staleness. Xie et al. [84] proposed FedAsync, an asynchronous federated optimization algorithm that adaptively controls the trade-off between the convergence rate and variance reduction based on the staleness. Specifically, the model update uploaded to the server is re-weighted by a function of staleness and then aggregated to the global model. The staler the model update is, the smaller it will be re-weighted to have a minor effect on the global model. Lu et al. [85] proposed PAFLM, which contains a dual-weights correction to solve the performance degradation caused by the staleness issue. The dual-weights of PAFLM consider two factors, the proportion of the local samples to the total samples and the time difference between downloading the model and uploading the corresponding model update. The dual-weights correct uploaded model updates according to the above two factors, where the more samples a client has and the less stale it is, the more the model update will be retained. Otherwise, the value of the model update will be corrected to be smaller. Compared with the previous work [85], Chen et al. [86] has the opposite view. Chen et al. thinks that clients with high latency may have more data samples, so the clients uploading fewer updates need to be given greater step sizes to compensate for the loss.

Besides correcting the model updates, some works proposed semi-asynchronous algorithms which combine the advantages of both synchronous and asynchronous algorithms, such as tackling the stragglers and mitigating the impact of staleness. For example, Wu et al. [87] proposed SAFA, a semi-asynchronous training scheme that only synchronizes a specific subset of clients. SAFA classifies all clients into

Method		Key Ideas	Disadvantages and Limitations
Data-based	Data Sharing	Sharing raw data collected from clients or the server with clients to reduce the degree of non-IID.	• Sharing raw data causes critical privacy issues. • The communication cost of transmitting raw data may be intolerable. • The trade-off between privacy, utility, and model performance is still unclear.
	Data Augmentation	Generating synthetic data by traditional data augmentation or indirectly sharing data information for clients to reduce the degree of non-IID.	• Traditional data augmentation methods may not be feasible in highly skewed non-IID scenarios. • The process of generating synthetic data causes privacy issues and additional overheads. • The trade-off between privacy and model performance is still unclear.
Learning-based	Regularization	Introducing a regularization term to correct the update direction and prevent weight divergence.	• The regularization terms may slow the local convergence speed due to the weight restriction. • Calculating regularization terms brings additional computation and memory overheads.
	Lifelong Learning	Treating learning on different clients or the server as individual tasks and applying lifelong learning to learn tasks without forgetting.	• Performing EWC algorithm and exchanging weight information result in a heavy workload in aspects of computation and communication.
	Fine-Tuning	Let each client perform fine-tuning on the well-trained global model to obtain a better-personalized model.	• Performance is highly depended on the trained global model.
	Parameter Split	Splitting the model into shared and private parameters. Each client can personalize their model by training private parameters independently.	• It is difficult to determine the optimal splitting strategy for each scenario.
	Meta Learning	Utilizing meta-learning to obtain an initial model aggregating all clients' prior knowledge. Then clients train it separately to obtain a personalized model.	• Performance is highly depended on the initial global model. • The meta-learning algorithms, such as MAML, theoretically require computing Hessian terms, which are computationally prohibitive.
	Multitask Learning	Treating learning on different clients as individual tasks and applying multitask learning to model the relationships between tasks and make the model generalize better on the target task.	• Modeling the relationships between clients may be unaffordable due to its complexity. • Most works only justify algorithms qualitatively but not under the clear statistical assumption.
	Knowledge Distillation	Introducing KD as an alternative aggregation method to tackle weight divergence better, protect privacy, and achieve model heterogeneity.	• The algorithms often require a representative proxy dataset, and their performance depends highly on the dataset. • Lack of analysis and comparison of the degree of privacy leakages between gradient, model weights, and logits. • Data-free KD methods may violate the privacy regulation in FL.
Protocol-based	Client scheduling	By actively arranging client selection, we can counterbalance the bias introduced by non-IID data or even achieve personalization through clustering clients.	• Most works do not consider system heterogeneity; therefore, the training efficiency may decrease due to biased client selection. • The assumption that all clients' statuses are known is not feasible in the real world. • Scheduling amount of clients may bring considerable overhead to the server.

TABLE 2: Summary of techniques in *Taxonomy of Statistical Heterogeneity*

three states. The first is up-to-date clients that have completed the previous local training. The second is deprecated clients, which train on the global model that are too stale. The last one is tolerable clients, which trains on a global model, not the latest version but not stale either. SAFA only requires up-to-date and deprecated clients to stay synchronous with the server. Chai et al. [88] proposed FedAT, a FL algorithm with asynchronous tiers. FedAt logically partitions all clients into tiers based on their response latency, where the clients with similar latency are divided into the same tier. Then all tiers in FedAT participate in the training simultaneously, where intra-tier training is synchronous and cross-tier training is asynchronous. However, frequently interacting with the faster tiers relative to slower ones would introduce biases to the global model. To solve it, similar to the insight of Chen et al. [86], FedAT assigns higher coefficients to the slower tiers while performing aggregation so that the global model would not bias toward the faster tiers.

Although asynchronous methods can alleviate the straggler issue, aggregating individual model updates is incompatible with secure aggregation [89], which could leak privacy. To solve it, FedBuff is proposed by Nguyen et al. [90]. In FedBuff, clients begin and finish local training asynchronously. However, the aggregation is not performed immediately upon receiving model updates. Instead, model updates are stored in a buffer until K model updates are in the buffer so that FedBuff can achieve privacy against the honest-but-curious threat model through secure aggregation and

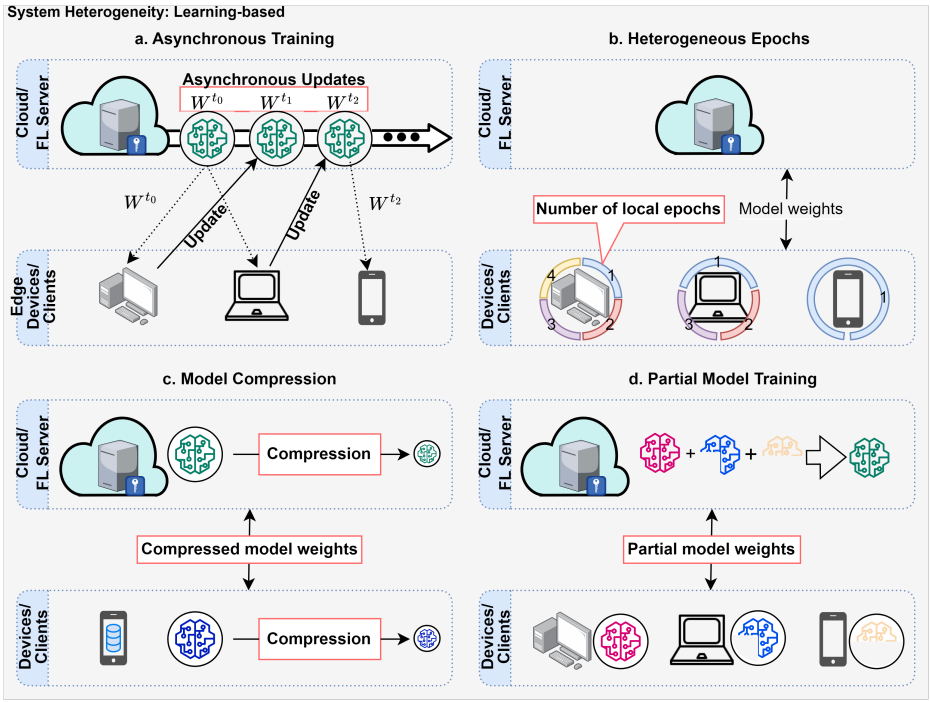

FIGURE 7: Illustration of learning-based approaches, including (a) synchronous training, (b) heterogeneous epochs, (c) model compression, and (d) partial model training

differential privacy [91]. Noteworthy, FedBuff is integrated into PAPAYA [92], the first production FL system to support asynchronous and synchronous training at scale.

2) Heterogeneous Epochs

In most FL algorithms, the number of local epochs is the same across all clients. However, with the various size of local datasets, computation, and communication speeds, the number of local epochs completed by clients within a given time interval can vary greatly. Therefore, making each client perform a uniform number of local epochs is unrealistic. Although tolerating partial works (heterogeneous local epochs) for solving system heterogeneity is effective (Fig. 7(b)), it may result in heterogeneity in the model progress at each client and further hurt the convergence speed and test accuracy of the global model.

To enable heterogeneous local epochs and solve the adverse impact brought by it, some solutions are proposed. Li et al. [7] proposed FedProx, which can be viewed as a generalization and re-parameterization of FedAvg. FedProx allows for variable amounts of local epochs to be performed across clients based on their system resources and then aggregate the partial work sent from the stragglers. To safely incorporate the partial work, FedProx adds a proximal term mentioned in Section. III-B1, which penalizes the model updates far from the global model. Different from the proximal term, Ruan et al. [93] alleviate the bias of heterogeneous local epochs by re-weighting the model updates. By assigning clients that run fewer local epochs a greater aggregation coefficient, the difference in training progress is compensated, and the bias introduced by tolerating partial works is reduced. Wang et al. [94] proposed FedNova, a normalized averaging method. Specifically, FedNova first normalizes the model updates and accumulates them. Next, the accumulative model updates are re-scaled before being aggregated into the global model. The normalization step can help counterbalance the different step sizes of model updates. In addition, the re-scaling step can ensure that the normalization step does not decrease the convergence speed.

3) Model Compression

Communication is often the bottleneck of FL, especially for the stragglers, due to the limited bandwidth and unstable network connection. Therefore, applying compression algorithms to reduce the communication cost (Fig. 7(c)) is a popular research topic. Although existing compression methods can efficiently reduce communication costs for distributed learning, there are several challenges to applying them to FL due to the unique characteristics of the FL environment. First, the compression methods may degrade the ability of the server to update the global model accurately and further hurt model performance. The trade-off between compression and model accuracy in the FL environment remains to be determined. Second, the compression method should be robust to features of the FL environment, such as non-IID data, small batch sizes, and partial client participation. In summary, how to design an efficient compression method to minimize communication cost and accuracy reduction in FL or tackle the trade-off between compression rate and model accuracy is the point we discuss here.

Recently, several works on compression methods have been proposed to meet the requirements of the FL environment. Sattler et al. [95] proposed STC, a new compression framework designed explicitly for FL. STC first shows that top-k sparsification suffers the least from non-IID data out of all compression methods. However, its utility is limited in the FL setting as it only directly compresses the upstream communication. Motivated by the observation, STC extends the existing top-k gradient sparsification compression technique with a novel mechanism to enable downstream compression, ternarization, and optimal Golomb encoding of the weight updates. Mills et al. [96] proposed CE-FedAvg, composed of distributed Adam optimization and compression methods. For the compression, CE-FedAvg comprises sparsification followed by quantization. To sparsify gradients, the top $(s-1)\%$ of deltas with the largest absolute value are chosen for each tensor. After sparsification, the weights are quantized from 32-bit floats to 8-bit unsigned ints with exponential quantization, which prevents gradient explosion caused by Adam. Shlezinger et al. [97] proposed an encoding-decoding strategy that mitigates the effect of quantization errors on the ability of the server to recover the updated model accurately. Specifically, the method encodes each model update with subtractive dithered lattice quantization. Furthermore, the theoretical analysis shows that this error can be bounded by a term that decays exponentially with the number of users. Xu et al. [98] proposed FTTQ, which optimizes the quantized networks on the clients through a self-learning quantization factor. With the observation that two quantization factors in standard TTQ will converge to the same absolute value, FTTQ adopts one quantization factor instead of two in each layer to reduce communication and computation costs. Additionally, a single quantization factor may also alleviate weight divergence. Haddadpour et al. [99] proposed FedCOMGATE, which lowers the communication overhead by periodic averaging and exchanging compressed messages. To be more specific, FedCOMGATE uses compressed messages for uplink communication to reduce communication costs. In addition, to make the compression method robust to non-IID data, FedCOMGATE applies local gradient tracking that ensures that each node uses an estimate of the global gradient direction to update its model locally. From the algorithmic standpoint, FedCOMGATE is similar to SCAFFOLD [41], which corrects the local update and ensures the updates move towards the true optimum, but FedCOMGATE is much simpler and does not require any extra control variable.

Most existing compression methods or the corresponding convergence analysis typically require identical compression rates across all the clients, which can limit their applicability and effectiveness. As mentioned, the trade-off between compression rate and model accuracy in the FL environment remains unclear. Dynamically adapting compression rate has an opportunity to minimize accuracy reduction brought by compression error. In addition, it is important to take the heterogeneity in clients' communication capacity and energy consumption into account to further improve training efficiency and robustness in the real environment. Han et al. [100] proposed FAB-top-k, a fairness-aware online learning method that ensures that different clients provide a similar amount of updates. Specifically, with the goal of minimizing the overall training time, FAB-top-k uses an estimated derivative sign and adjustable search interval to determine the optimal value of gradient sparsity for each client. Moreover, by replacing training time with another type of additive resource, FAB-top-k can be easily extended to minimize other resource consumption. Li et al. [101] proposed FT-LSGD-DB, which balances the energy consumption between local computation and communication from the long-term learning perspective. Specifically, FT-LSGD-DB allows the client to perform gradient sparsification with different degrees by using generalized Benders decomposition and inner convex approximation to find a satisfactory solution for compression rates. In addition, FT-LSGD-DB novelly incorporates error compensation and batch size increment into FL procedures to accelerate model convergence. From the theoretical respect, Cui et al. [102] for the first time systematically examine the trade-off identifying the influence of the compression error on the final model accuracy with respect to the learning rate by factoring the compression error into the convergence rate analysis. Then, based on the derived convergence rate, the authors establish the policy to maximize the final model accuracy by adapting compression rates in accordance with learning rates.

4) Partial Model Training

The basic assumption of FedAvg is that all local models have to share the same architecture as the global model. However, this assumption makes the model architecture complexity limited by the most indigent client. Furthermore, assigning a uniform workload to the clients with various computation and communication capabilities can cause the straggler issue. Therefore, as shown in Fig. 7(d), the objective of partial model training is to achieve model heterogeneity and assign heterogeneous models with different complexity levels according to clients' capabilities adaptively. Although partial model training shares the same objective with KD, a model-agnostic algorithm mentioned in Section. III-B3e, the two methods are quite distinct from each other. First of all, partial model training aims to enable clients only to perform training on and exchange a subset of the model but still generate a single global model, while KD allows clients to perform training on completely different models and achieve personalization. Secondly, partial model training follows a weight-based aggregation method as in FedAvg, instead of using KD as a translation protocol and exchanging knowledge by a public dataset. Recently, the main research direction of works about partial model training is how to generate optimal subnetworks from the global model for each client, with respect to size and component.

Diao et al. [103] proposed HeteroFL, which proposes the concept of model heterogeneity and identifies its effectiveness. To generate the subnetworks, HeteroFL varies the

width of hidden channels and ensures that the local and global model architectures are within the same model class, which stabilizes global model aggregation. Moreover, the global model in HeteroFL is constructed from the union of all disjoint sets of the partition. Sidahmed et al. [104] proposed FedPT, which splits the model into trainable and non-trainable. In FedPT, only the trainable parameters are exchanged and updated by the clients to reduce costs. However, FedPT highly depends on the network architecture, and it may be hard to find the optimal partition of parameters. Similar methods are also evaluated on neural networks for speech recognition [105], [106]; the experiment results show that different model architectures have different abilities to handle aggressive freezing rates. Chen et al. [107] proposed APF, which adaptively freezes (fixes) a subset of model parameters. Specifically, APF freezes parameters in intermittent periods, and the freezing periods are tentatively adjusted in an additively-increase and multiplicatively-decrease manner, depending on if the previously frozen parameters remain stable in subsequent iterations.

On the other hand, some works take inspiration from dropout [108] or pruning [109] to implement partial model training. In the traditional dropout, the parameters are multiplied by a random binary mask to drop a fraction of the parameters during each training pass. Empirically, traditional dropout is used as a regularization strategy for solving overfitting [110], but this technique is used for system-level concerns here. In addition to dropout, traditional pruning reduces the parameter counts to reduce the complexity of the model. The important research on model pruning is the "lottery ticket hypothesis [111]", which claims that an optimal subnetwork can be identified through pruning, and such subnetwork can reach test accuracy comparable to the original network. Compared with the works mentioned before [104]–[107], the works motivated by dropout or pruning pay more attention to how to select the best subnetwork for the global model or each client.

Caldas et al. [112] proposed Federated Dropout, which efficiently trains on a smaller subset of the global model. To realize communication and computation savings, Federated Dropout zeros out a fixed number of activations at each fully-connected layer and drop out a fixed percentage of filters. Then the sparse model is re-packed as a smaller dense model. Xu et al. [113] proposed ELFISH, a resource-aware FL framework. ELFISH first identifies the number of kept parameters for each client based on its resource constraints. Next, ELFISH selects the parameters with larger updates last round since larger parameter updates imply more significant impacts on the global model. Horvath et al. [114] proposed FjORD, which introduces ordered dropout into FL to enable partial model training. Ordered dropout is a mechanism ordering knowledge representation in nested subnetworks of the original network. In addition, ordered dropout is shown that it can recover the singular value decomposition in the case where there exists a linear mapping from features to response. Munir et al. [115] proposed FedPrune,

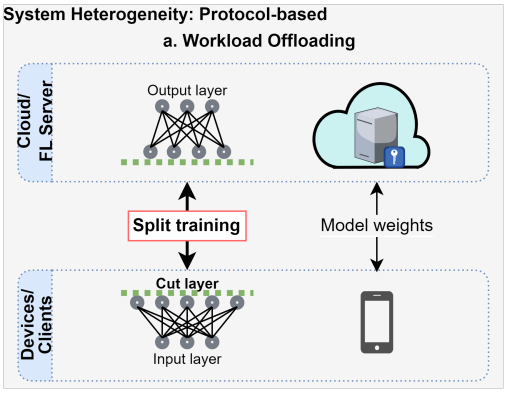

FIGURE 8: Illustration of protocol-based approaches, including (a) workload offloading

which prunes the global model for slow clients based on resource characteristics. Specifically, FedPrune sorts parameters based on their post-activation values and picks the top m parameters that satisfy the model size constraint as the subnetwork. In addition, FedPrune uses insights from the central limit theorem to aggregate clients' model weights to better generalize the global model under non-IID data. Li et al. [116] proposed Hermes, a communication and inference-efficient FL framework. Hermes applies structured pruning to find a subnetwork for each client. Moreover, instead of taking the average over all parameters of clients, Hermes performs the average on only overlapped parameters across each subnetwork. Different from the works assigning a subnetwork for each client, PruneFL, proposed by Jiang et al. [117], adapts the global model size during the training process. Specifically, PruneFL first performs initial pruning on the global model at a selected client, and then the global model is pruned iteratively during the training process.

B. PROTOCOL-BASED ALGORITHMS

As mentioned, only a subset of clients is selected to participate in training at each round. The slowest straggler bounds the time cost of a round. To solve the straggler issue, protocol-based algorithms modify the client selection schemes or try to offload the stragglers' workload. Intuitively, limiting the time stragglers participate in training can help increase training efficiency. Motivated by it, some client scheduling algorithms that focus on actively selecting clients at each round are proposed. On the other hand, some algorithms bring the concept of workload balancing into FL. Specifically, the algorithms try to offload the stragglers' workload to the server and even other clients so that the completion times of the selected clients are close. In this subsection, we will detail the algorithms for client scheduling and workload offloading.

1) Client Scheduling

Similar to the insight of client selection algorithms mentioned in Section. III-C1 and illustrated in Fig. 6, randomly

selecting clients is not the optimal solution for both statistical and system heterogeneity. For system heterogeneity, it is intuitive that making stragglers participate less in training can effectively reduce the time cost of each round. With the above intuition, Nishio et al. [118] proposed FedCS, which solves the client selection problem in a greedy fashion. Specifically, FedCS sets a certain deadline for each round and assumes that the server can obtain all clients' resource information, such as bandwidth and computation speed. With the given deadline, the client scheduler uses a heuristic algorithm to select as many clients which can complete the local training task in time as possible. Empirically, the FedCS algorithm usually selects the top k fast clients in each round. Mourad [119] proposed FedMCCS, an enhanced FL with multicriteria client selection. FedMCCS efficiently leverages stratified-based sampling to filter the available clients and maximize the number of clients participating in each FL round while considering their heterogeneity and limited communication and computation resources. However, both FedCS and FedMCCS may introduce bias into the global model due to the highly biased client selection of the heuristic algorithms.

Compared with the methods maximizing the number of clients greedily, FLANP, proposed by Reisizadeh et al. [120], better balances client participation while solving the straggler issue. The key idea of FLANP is to start the training procedure with faster nodes and gradually involve the slower nodes in the model training once the statistical accuracy of the data corresponding to the current participating nodes is reached. Although the time cost of the last few rounds of FLANP is relatively high, it allows slower clients to contribute to the model to achieve better accuracy. Chai et al. [121] proposed TiFL, a Tier-based Federated Learning System. To alleviate the impact of stragglers, TiFL divides clients into tiers based on their hardware resources, where homogeneous clients are divided into the same tier. Then in each round, TiFL selects clients from the same tier so that the stragglers do not slow down the training efficiency. Moreover, TiFL also takes the non-IID data into account. To be more specific, TiFL employs an adaptive tier selection approach to update the tiering on-the-fly based on the observed training performance and accuracy. Furthermore, reinforcement learning is also introduced into FL to solve system heterogeneity. Kim et al. [122] proposed AutoFL, a reinforcement learning algorithm that learns and determines which clients are selected each round. By carefully designing the status, action, and reward, AutoFL can select participant clients expected to maximize FL's energy efficiency while satisfying the accuracy requirement.

2) Workload Offloading

Workload balancing, widely used in distributed system and distributed learning, is the ability to distribute workload evenly (or based on clients' capabilities). In distributed learning, we can achieve workload balancing by simply reallocating data samples. However, this method can not be directly applied in FL since the private data can only be accessed by the owner. To offload workload under privacy guarantee, some works combine split learning (SL) [123], [124] with FL and allow clients to offload partial computation cost to the powerful server.

SL is a distributed machine learning approach that enables clients to collaborate to train a model without sharing raw data, just like FL. Besides, SL provides better model privacy than FL since the model splits between clients and servers. In addition, SL splits the entire model into multiple smaller subnetworks and trains them separately; hence SL is a better option for resource-constrain clients. Specifically, in a simple vanilla setting (Fig. 8(a)), a model is split into two portions: client-side model and server-side model. Each client trains the client-side model up to its last layer, known as the cut layer. Then the output of the cut layer, called smashed data, is sent to the server, which completes the rest of the forward and corresponding backward propagation. Finally, the gradients at the cut layer are sent back to the client to complete the rest of the backward propagation. This process is repeated by all clients sequentially until the model converges. Despite the advantages of SL, there is a primary limitation. The relay-based training in SL causes only one client to participate in training at a time. Such low parallelism of SL causes a significant increase in time overhead. Currently, some researches focus on designing an efficient system that unites the primary strength of FL (parallel processing among distributed clients) and SL (model splitting for less computation cost of clients) and eliminating their inherent drawbacks.

Ye et al. [125] proposed EdgeFed, which separates the process of updating the local model that is supposed to be completed independently by clients. Specifically, EdgeFed comprises clients, edge servers, and the central server. Each round includes multiple split training between clients and corresponding edge servers and a global aggregation between edge servers and the central server. First, the clients perform training on the client-side model and then send the smashed data to the edge server. After the remaining calculation, the edge server updates the whole model and returns the model weights of the client-side model to clients instead of the gradient of the cut layer. Finally, after several split training, the edge servers send the updated model weights to the central server for the weighted averaging to obtain the aggregated model. In short, EdgeFed introduces SL to offload workload from clients to the edge server at the cost of communication. In addition, the edge servers are introduced to play as a mediator to guarantee the parallelism of EdgeFed and training efficiency. With a similar design, Ullah et al. [126] proposed FedFly, a distributed FL+SL system with three layers architecture. Besides offloading workload and increasing parallelism, FedFly addresses the mobility challenges of clients in edge-based FL.

Compared with [125], [126], which uses weighted averaging to update the entire global model, SplitFed [127], the state-of-the-art FL+SL framework, utilizes the edge server to reduce the communication cost of uploading model weights.

To be more specific, the edge servers are responsible for offloading partial workload from clients and updating the server-side model with gradient descent every round, while the central server is in charge of only updating the client-side model with weighted averaging of model weights. Since clients only need to send the client-side model, which is a small portion of the model, the communication cost for uploading is further reduced. In addition, SplitFed introduces differential privacy and PixelDP to avoid privacy leakage while transmitting the smashed data and model weights.

However, the above works [125]–[127] bring another question: how much workload should be offloaded by each client. To answer this question, Ji et al. [128] proposed EAFL, which uses a threshold-based offloading strategy to reduce the computational burdens for stragglers in federated learning. Specifically, the strategy determines non-offloading and optimal partial offloading for clients with offloading decision indicator below and above a given threshold, respectively. FedAdapt, proposed by Wu et al. [129], adopts reinforcement learning-based optimization and clustering to adaptively identify which layers of the model should be offloaded for each client to a server to tackle the challenges of computational heterogeneity and changing network bandwidth.

C. SUMMARY AND LESSON LEARNED

In this section, we have discussed learning-based and protocol-based approaches for system heterogeneity. We summarize and compare the techniques with respect to their key ideas, disadvantages, and limitations, as shown in Table. 3.

Learning-based approaches aim to tackle straggler issues by modifying the learning algorithms to reduce the impact of stragglers or clients' workloads. Asynchronous training methods enable the global model can be updated without waiting for stragglers. However, the stale model updates from the stragglers may hurt the model performance and slow the convergence. Although several correction terms based on staleness [84], [85] and semi-asynchronous approaches [87], [88] are proposed, staleness and the trade-off of the degree of asynchronous are still open problems for FL. In addition, asynchronous methods suffer communication bottlenecks as all clients can communicate with the server asynchronously. Furthermore, the trusted execution environment [130] required by FedBuff [90] is only sometimes available in FL. Hence, aggregating individual model updates could still result in an undesirable level of privacy for FL. The limitation of heterogeneous epochs is similar to the privacy concern of asynchronous approaches. The privacy may leak since some works [93], [94] need to operate individual model updates. Model compression methods are the most efficient for reducing communication costs. However, the reduction of communication costs is at the expense of additional computational costs for compressing model weights. In addition, the relationship between compression rate and accuracy reduction remains to be seen. To improve training efficiency while not degrading accuracy, How to dynamically decide the optimal compression rate for each client needs to be clarified in the future. Partial model training breaks the assumption that the model architectures of all local models are the same and further achieves model heterogeneity. Nevertheless, the works based on unstructured dropout/pruning methods [107], [113], [115] may bring less efficiency improvement due to the limited support of ML frameworks or hardware. In addition, a trade-off exists between model performance and the strategy of deciding subnetworks. Indeed, assigning smaller subnetworks to clients implicitly reduces their contribution to the global model and can introduce bias into the global model. How partial model training approaches affect the model performance is an open problem left for future work.

Protocol-based approaches aim to solve the straggler issue by modifying the client selection schemes or trying to offload the stragglers' workload. The intuition of client scheduling is that limiting the time stragglers participate in training can improve training efficiency. However, such biased client selection may hurt the convergence and model performance [118]. Motivated by the observation, Huang et al. [131] shown that the fairness of client selection is essential for model performance in FL. Therefore, it is a challenge to design a client scheduling that improves training efficiency while guaranteeing the fairness of client selection. In addition, the server may not acquire all clients' statuses and suffer computation and communication overheads due to the complexity of scheduling many clients. Workload offloading utilizes split learning to offload partial computation overhead to the server. However, the reduction in computation overhead is at the expense of additional communication overhead (smashed data and gradient). In addition, the process that exchanges smashed data and corresponding gradient may leak data privacy.

V. FEDERATED LEARNING UNDER BOTH STATISTICAL AND SYSTEM HETEROGENEITIES

In Section. III and Section. IV, we have discussed the works on statistical and system heterogeneities, respectively. Actually, the two heterogeneities usually coexist in the FL environment, and it is urgent to design approaches tackling the two heterogeneities simultaneously. However, as the challenges move from single objective optimization to multiple objectives optimization, there may exist trade-offs between improving model performance (solving non-IID data) and increasing training efficiency (solving straggler issue). In this section, we first analyze the trade-offs and point out the potential exacerbation for heterogeneity brought by existing works. Then, we present the advance works considering both heterogeneities simultaneously.

A. LIMITATION OF EXISTING WORKS UNDER MULTIPLE HETEROGENEITIES

Although previous works perform well on a single heterogeneity, few of them have explored whether the proposed methods are robust enough for other types of heterogeneity.

Method		Key Ideas	Disadvantages and Limitations
Learning-based	Asynchronous Training	Designing an algorithm to enable the global model could be updated without waiting for stragglers.	• Staleness issue from the out-of-date updates of the stragglers hurts the model performance. • Asynchronous methods can easily create a network communication bottleneck. • Although various semi-asynchronous methods are proposed, the trade-off between training efficiency and accuracy is still unclear. • Asynchronous algorithms may not be compatible with secure aggregation and further leak privacy.
	Heterogeneous epochs	Adjusting the number of local epochs each client performs to re-balance their workload.	• The heterogeneous model progresses may hurt the convergence and model performance. • Most existing methods need to re-scale each model update; hence they may leak privacy to the honest-but-curious server.
	Model compression	Compressing the message transmitted between clients and the server to reduce communication costs. In addition, compression rates can be dynamically set to relieve the compression error.	• The compression error usually degrades model accuracy, and the trade-off between communication cost reduction and accuracy is still unclear. • The reduction in communication costs is at the expense of increased computational costs. • How to design compression methods fitting the FL scenario is still an open problem.
	Partial Model Training	Let clients perform training on heterogeneous models with different complexity to balance workload but still generate a single global model.	• Since ML frameworks, such as Pytorch, have limited support for sparse matrix computation, the works based on unstructured pruning/dropout methods may bring less improvement. • Finding the optimal subnetwork for each client is still an open problem. • The methods may lead to a biased model with poor accuracy, and the trade-off between cost reduction and accuracy needs to be clarified.
Protocol-based	Client scheduling	The training efficiency can be improved by making stragglers participate less in training or clustering clients based on their capabilities.	• The methods may introduce bias into the global model due to the biased client selection. • The assumption that all clients' statuses are known is not feasible in the real world. • Scheduling amount of clients may bring considerable overhead to the server.
	Workload Offloading	Utilizing split learning to offload stragglers' workload to the other powerful server or even clients and further achieve workload balancing.	• The reduction in computational costs is at the expense of increased communication costs. • How much workload each client should offload is still an open problem. • The communication pattern brings privacy issues and the trade-off between privacy and utility.

TABLE 3: Summary of techniques in *Taxonomy of System Heterogeneity*

Moreover, they may further make solving another heterogeneity more difficult. In this subsection, we present the implicit limitations of existing works and the interplay between proposed algorithms and heterogeneities.

1) Causes of Worsening System Heterogeneity

First, we review the proposed methods on statistical heterogeneity and discuss the reason they implicitly hurt system heterogeneity.

- *Increased Latency Disparity due to Additional Overheads*: In the case that the capabilities of each client remain unchanged, the gap between clients' response latency is proportional to the total overhead of a local training task. Unfortunately, the majority of previous works for statistical heterogeneity bring more overheads to clients compared with FedAvg. It makes clients which are already slow in response spend relatively more time completing training and aggravates the straggler issue from system heterogeneity. For example, the regularization methods mentioned in Section. III-B, including FedProx [7] and MOON [43], incurs 2 $\sim$ 3x overheads in respect of both memory and computation due to the requirements of regularization terms. In addition, the personalization methods, which apply existing DL techniques to help clients better transfer helpful knowledge from others, also burden the clients. For instance, despite some approximation approaches [61], [62] being proposed to help compute hessian terms, meta-learning algorithms are still computationally prohibitive. The methods that increase latency disparity include, but are not limited to, the examples mentioned above. How to effectively solve statistical heterogeneity without increasing overhead or even reducing it still challenges the research community.
- *Increased Time Cost due to Inappropriate Communication Protocol*: In Section. III-C1, we discussed algorithms that actively schedule clients' participation to counterbalance the bias introduced by non-

IID data. However, the clients that are helpful for the global model performance may be the stragglers which hurt training efficiency. More specifically, the previous works [77], [78] only pay attention to the clients that contribute to model performance and prioritize them. However, the factors they consider, such as local loss and local data distribution, are entirely different from that of the works for system heterogeneity [118], [119], including network bandwidth and computational capacities. Therefore, the client scheduling strategies for different heterogeneities may conflict and worsen each other. Besides client scheduling, the way clients communicate may also exacerbate system heterogeneity. For example, in Astraea [22], the clients are divided into groups, and then the clients in the same group perform local training sequentially. Although sequentially updating the global model does help tackle non-IID, it makes the straggler issue more severe and significantly endangers training efficiency. In addition, the peer-to-peer communication pattern used in FedCurv [47] brings expensive communication and time overheads. In each synchronization session, each client has to wait for all clients to complete transmission with itself. This is not feasible in an FL environment with heterogeneous capabilities and unstable network connections. For works tackling statistical heterogeneity, it is also important to consider communication protocol design and compatibility with other heterogeneities.

2) Causes of Worsening Statistical Heterogeneity

Next, we review the proposed methods on system heterogeneity and discuss the reason they implicitly hurt statistical heterogeneity.

- *Weight Divergence due to Reducing Workload*: With the key insight similar to FedProx [7], reducing workload for stragglers and naively incorporating partial information from them implicitly increase statistical heterogeneity. Specifically, reducing clients' workload means only partial local training tasks are completed, or partial model updates are transmitted. This limits the amount of available information contributing to the global model and induces the global model to bias towards the clients performing complete training, implying more significant weight divergence. Related issues have been explored in recent works mentioned in Section. IV-A2. As shown in the papers [7], [93], [94], tolerating heterogeneous local epochs lead to inconsistent step sizes of model updates and enhances the degree of weight divergence. In addition, although the trade-off between model compression rate and model performance has been noticed and well-studied in centralized training, it is still unclear in the FL environment due to the additional interaction between model compression and non-IID data. Currently, model compression robust to the feature of FL, such as non-IID and unstable client participation, is a popular research topic [95], [98], [99]. Moreover, the partial model training methods mentioned in Section. IV-A4 enable stragglers to perform training on subnetworks with less complexity. However, the methods usually have the challenge of accuracy-time trade-off. The greater the difference in model size between fast clients and stragglers, the greater the risk of model weight disparity. Although several works [103], [114], [115], [117] have empirically shown that their methods are pretty robust for different dropout/pruning rates, whether accuracy-time trade-off can be solved well in the real world environment remains to be clarified.
- *Decreased Fairness due to Biased Client Participation*: Similar to reducing the workload of stragglers, the difference in the frequency of participating in training also makes the global model biased towards the clients completing more local training tasks. Such a global model with bias may perform poorly on the stragglers, which participate less in training and violate the requirement of fairness that the global model should perform well on all clients. For asynchronous FL approaches, the number of times each client participates in training is proportional to his capabilities. Furthermore, the model weight uploaded by stragglers may be re-weighted or discarded due to staleness. These mechanisms have exacerbated the degree of deviation and the reduction of accuracy of the global model. In addition, the client scheduling algorithms for system heterogeneity also have similar issues. For example, the works [118], [119] with highly biased client selection methods ignore the importance of stragglers' local datasets and make them participate less in training. Similar approaches have been shown to reduce accuracy and slow down convergence significantly. Recently, Huang et al. [131] was aware of the disadvantages of biased client participation and empirically showed the importance of fairness in the client participation rate.

B. FEDERATED LEARNING METHODS FOR MULTIPLE HETEROGENEITIES

Reviewing the state-of-the-art in the field, we find that there are advanced works considering both heterogeneities simultaneously. In this subsection, we would like to provide an overall picture of the methods which tackle multiple heterogeneities. Noteworthy, the main goal of the works for multiple heterogeneities is usually to solve system heterogeneity. They empirically found implicit pitfalls mentioned in the last subsection and avoided them. To solve system heterogeneity while not increasing the degree of weight divergence, the works attempt to show the unbiasedness of the methods, correct the biased model updates, or model the relationship between heterogeneities. In the following content, we will discuss their key insights and how they tackle the interplay mentioned in the last subsection.

1) Asynchronous Training for Both Heterogeneities

As mentioned in Section. IV-A1, asynchronous training suffers from the staleness issue. Most current asynchronous FL methods re-weight the stale model updates to reduce their adverse impact. However, the re-weighting methods may significantly reduce the contribution of stragglers to the global model and make the global model suffer more from weight divergence. Compared with them, Li et al. [132] develop an adaptive approximation method called AD-SGD. Specifically, AD-SGD applies the Taylor expansion to approximate the "up-to-date" gradient of stragglers from its stale gradient. In addition, an adaptive hyper-parameter controlling mechanism is also integrated into AD-SGD to reduce the bias of Taylor series approximation. By approximating the optimal gradient from the stale model updates instead of reducing their aggregation coefficient, AD-SGD has the potential to be more robust to non-IID data. Besides, frequently communicating with specific clients would also exacerbate statistical heterogeneity. To handle the issue brought by biased client participation, some asynchronous methods propose compensation mechanisms to achieve unbiased, balancing training. For example, FedAT [88], a FL algorithm with asynchronous tiers, dynamically assigns aggregation coefficients to tiers based on the number of times they upload model updates. In this way, although the slower tiers (stragglers) less update the global model, they are assigned more significant coefficients while performing aggregation, and the potential bias towards the faster tiers is avoided. Similarly, ASO-Fed [86] applies a dynamic learning step size for each client based on the time cost of past iterations, where a larger time cost implies a larger learning rate. By doing so, the contribution of stragglers to the global model can be compensated.

2) Heterogeneous Epochs for Both Heterogeneities

As explained earlier in Section. IV-A2, heterogeneous epoch causes the heterogeneity in the model progress and exacerbates weight divergence. Among the works enabling heterogeneous local epochs, FedProx [7] introduces a proximal term to pull the local models closer to the global model and alleviate the gap between the step sizes of local models. Compared with FedProx, FedNova [94] normalizes the gradient when averaging, instead of restricting them, to achieve unbiased model aggregation. The authors of FedNova claimed that FedProx only mitigates the heterogeneity in the model progress, but FedNova can eliminate it. In addition, similar to FedAT [88], Ruan et al. [93] enlarge the aggregation coefficient for the clients which perform less local epochs to ensure an unbiased gradient after aggregation.

3) Model Compression for Both Heterogeneities

As mentioned in Section. IV-A3, being robust to non-IID data is one of the critical requirements for model compression methods in FL. Among the compression methods, Sattler et al. [95] conducted a series of experiments to evaluate the robustness of existing compression methods to non-IID data. The results showed that top-k sparsification suffers the least from non-IID data. Sattler et al. use this observation as an outset to construct a more efficient compression method for FL. Furthermore, FAB-top-k [100] emphasizes the fairness among clients in the number of gradient elements contributed to the sparse global model, which is helpful for non-IID data and compression since compression methods may aggravate the deviation and unfairness of local models. In addition, FedCOMGATE [99] tackles a problem similar to SCAFFOLD [41] in the context of model compression. To be more specific, both of them enable each client to use an estimate of the global update direction to correct its local updates. However, FedCOMGATE additionally considered the effect of compression in theoretical analysis. Besides the above works, Cur et al. [102] factor the compression error and non-IID data into the convergence analysis and explore the trade-off between model compression and model performance in the FL environment.

4) Partial Model Training for Both Heterogeneities

For the partial model training described in Section. IV-A4, because the methods still follow the standard FL process, which performs multiple local epochs under statistical heterogeneity, the subnetworks with different complexity suffer from weight divergence and digress to various scales. To relieve the weight divergence, some works design specific aggregation strategies. For example, To avoid disrupting the information of the subnetworks, Hermes [116] only averages the model weights that are intersected across the subnetworks of clients while keeping others unchanged instead of averaging the entire model of all clients. In addition, FedPrune [115] uses the insight from Lyapunov's Central Limit Theorem to perform aggregation. Specifically, FedPrune randomly draws aggregated model weights from the normal distribution with specific mean and variance and empirically shows the strategy's effectiveness. Besides aggregation strategies, based on the observation that dropout [108] scales representations based on dropout rate during the training phase to directly use the full model for inference, HeteroFL appends a scaler module right after the parametric layer. The evaluation results show that the global model composed of scaled subnetworks can achieve improved model performance.

5) Client Scheduling for Both Heterogeneities

As mentioned in Section. IV-B1, the highly biased client selection methods waste the potentially valuable data of stragglers and introduce bias into the global model. Guaranteeing fairness in participation is a crucial issue that is often overlooked. In FLANP [120], the stragglers are gradually involved in training instead of being abandoned. The improved fairness compared to other heuristic algorithms [118] is shown to help speed up the convergence in wall-clock time. Similarly, TiFL [121] dynamically adjusts the selection probability of each tier of clients to avoid heavily selecting certain tiers (e.g., tiers with faster clients). Moreover, Oort [133] formulates the trade-off between system and statistical heterogeneity and turns it into an optimization

problem. Similarly, AutoFL [122] takes both heterogeneities into the reward function and tackles the optimization problem with a reinforcement learning approach.

C. SUMMARY AND LESSON LEARNED

In this section, we point out possible reasons of existing works for exacerbating another heterogeneity and review the methods considering both statistical and system heterogeneities simultaneously. The reason why the optimization for FL is challenging is its extremely complex learning environment and strict restrictions. When trying to solve statistical heterogeneity, we should pay attention to whether the proposed approaches cause a large amount of overhead or use inappropriate communication protocol, thus exacerbating the negative impact brought by system heterogeneity. Similarly, the works for system heterogeneity, especially tolerating partial workload and non-uniform client scheduling, need to take statistical heterogeneity into consideration to avoid exacerbating weight divergence or biasing the global model.

For the approaches considering both heterogeneities, compensating the model updates of specific clients is a widely used method. For instance, assigning larger learning rates [86] or aggregation coefficients [88], [93] to the clients which participate less in training or complete less workload can ensure unbiased updates after aggregation. In addition, to relieve weight divergence, some works correct the model updates by proximal terms [7] or estimate the 'better' update direction [94], [132]. Finally, fairness plays an important role in balancing heterogeneities. Although the definitions of fairness are different between different works, such as the number of gradients uploaded and the frequency of participating in training [120], [121], their theoretical or experimental results show that fairness is helpful for FL training.

VI. PROMISING FUTURE RESEARCH DIRECTIONS

Despite the research community's efforts, statistical and system heterogeneities are still open problems. Based on our survey of the existing heterogeneous FL literature, we would like to highlight a number of promising research directions, including heterogeneity analytics, fairness, FL architecture search, the Pareto Frontier of FL performance, and privacy issues.

A. PRIVACY CONCERNS

Although FL can provide a privacy guarantee for distributed systems by not sharing raw data during the training process, as shown in the works [134], [135], exchanging the model updates may still leak sensitive information to a third party. Even worse is that the relevant information about raw data (e.g., encoded data, GAN generators, and local data distributions) transmitted by data-based approaches has the opportunity to reveal more privacy. Although recent works adopted various privacy solutions, some challenges are still ahead. For example, differential privacy (DP) [136], [137] preserves training data and hidden information by inserting artificial noise, such as Gaussian noise, into the gradient or model weights. However, artificial noise can hurt the ability aggregating model updates accurately and brings the challenge of tackling the trade-off between privacy guarantee and model performance. On the other hand, encryption [138], [139] is considered lossless and does not degrade accuracy, but it can bring intensive computation and communication costs and further exacerbate the straggler issue. In addition, as mentioned in Section. IV-A1, asynchronous FL methods may be incompatible with secure aggregation and leak individual model updates to the server. Despite the effort of FedBuff [90], not all scenarios can support the Trusted Execution Environments [130], [140] required to implement FedBuff. In summary, privacy concerns have a strong link to the heterogeneity in FL. Therefore, it is an urge to design robust, low costs, practical solutions which simultaneously address heterogeneity and guarantee privacy.

B. HETEROGENEITY ANALYTIC

Most existing approaches have hyper-parameters that must be carefully adjusted to deal with varying degrees of heterogeneity. Furthermore, the model performance usually highly depends on hyper-parameter tuning. If we can accurately quantify heterogeneity over a federated environment before training starts, that would lead to better choices for hyper-parameters, model architecture design, and even FL algorithms. Recent works, such as FedProx [7], quantify statistical heterogeneity through local dissimilarity. However, these metrics can only be calculated during training instead of before starting. In sum, developing a simple analytic tool to quantify heterogeneity before training occurs quickly is essential for improving the convergence and performance of FL algorithms.

C. FAIR FEDERATED LEARNING

Fairness in FL is gaining attention in recent research. The general understanding of fairness in FL is that the global model performs well on all clients, which means the performance for all local datasets is similar and good enough. To avoid the global model biasing to specific clients, as mentioned in Section. V, current works ensure that each client at least participates in several training sessions or uploads several updates. However, unbiased FL training is challenging due to the diversity of clients, including the sizes of local datasets, activity patterns, hardware resources, and willingness to participate in training. While tackling statistical and system heterogeneities, existing work often needs to pay more attention to the importance of fairness. Although the model performance or training efficiency can be improved, the improvement is built on the sacrifice of partial clients. On the other hand, PFL is a promising direction for achieving fairness. Nevertheless, the study of PFL is still in its infancy. To make FL realistic and applicable, fair FL will become more and more critical.

D. FEDERATED LEARNING WITH NEURAL ARCHITECTURE SEARCH

In the presence of statistical heterogeneity, the predefined FL model architecture may not be the best choice. Neural Architecture Search (NAS) [141], [142] is a promising technique to help FL design better suitable model architecture for complex scenarios. Especially, Mendieta et al. [44] empirically shown that the Hessian eigenvalue and Hessian trace, which are significant predictors of performance and network generality in NAS [143], [144], help to determine the model architectures' robustness for non-IID data. Moreover, FedNAS [145] is proposed to enable scattered clients to search for better architecture collaboratively to achieve higher accuracy. On the other hand, NAS is the potential to automate the architecture design for the methods enabling model heterogeneity, such as PFL, and achieve better personalization.

E. MULTIPLE HETEROGENEITIES AND THE PARETO FRONTIER

As mentioned in Section. V, dealing with multiple heterogeneities is challenging. It is important to understand how these heterogeneities interact and systematically analyze the trade-off between them. According to the observation of this survey, model performance and training efficiency are in an intense relationship. Considering the effect of other heterogeneities while solving the main target is essential; otherwise, it may only find one of the Pareto optimal solutions. In other words, it can not bring improvement without detriment. In summary, improving the Pareto frontier, i.e., achieving better accuracy under the same costs or wall-clock time, is a popular but unsolved challenge in the research field.

VII. CONCLUSION

In this survey, we provide an overview of FL and present an in-depth and in-breadth investigation of FL with statistical and system heterogeneities. To the best of our knowledge, this survey is the first to discuss FL under multiple heterogeneities. Based on the key insights and techniques, we propose a unique taxonomy to categorize existing works for heterogeneous FL and highlight their features, limitations, and opportunities. Furthermore, we point out possible reasons of existing works for exacerbating another type of heterogeneity and systematically review the works for multiple heterogeneities. From the comprehensive review, several main lessons learned have been summarized and analyzed. Finally, we outline the research direction worth future effort. We believe that our taxonomy and the discussion of multiple heterogeneities will stimulate more attention in this emerging area and provide comprehensive insights to the research community.

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