

Exam June 10, 2020. Complete solutions of selected problems

1. Find the linear homogeneous difference equation with constant coefficients of minimal order that has as solution the sequence $(x_k)_{k \geq 0}$ with

(a) $x_k = \cos(k) + 3 \sin(k)$, $k \geq 0$

(b) the first terms of $(x_k)_{k \geq 0}$ are 1, 0, 0, 1, -2, 5.

Solution (a) It must be a second order difference equation whose characteristic eq. has the roots $\pm i$.
Then, the characteristic eq. is $r^2 + 1 = 0 \Rightarrow$

the LHDE is $x_{k+2} + x_k = 0$.

(b) Note that this sequence is not a geometric progression, thus, it is not a solution of a first order difference eq.

We have $x_0 = 1$, $x_1 = 0$, $x_2 = 0$, $x_3 = 1$, $x_4 = -2$, $x_5 = 5$.

A second order LHDE has the form $x_{k+2} + ax_{k+1} + bx_k = 0$ $\forall k \geq 0$

$k=0$: $x_2 + ax_1 + bx_0 = 0 \Rightarrow b = 0$

$k=1$: $x_3 + ax_2 + bx_1 = 0 \Rightarrow 1 = 0$ contradiction.

A third order LHDE has the form $x_{k+3} + ax_{k+2} + bx_{k+1} + cx_k = 0$

$k=0$: $x_3 + ax_2 + bx_1 + cx_0 = 0 \Rightarrow 1 + c = 0$

$k=1$: $x_4 + ax_3 + bx_2 + cx_1 = 0 \Rightarrow -2 + a = 0$

$k=2$: $x_5 + ax_4 + bx_3 + cx_2 = 0 \Rightarrow 5 - 2a + b = 0$

$$\begin{cases} a = 2 \\ b = -1 \\ c = -1 \end{cases}$$

Conclusion: $x_{k+3} + 2x_{k+2} - x_{k+1} - x_k = 0$, $k \geq 0$.

2.

$$\begin{cases} y' = x^2 + y^2 \\ y(0) = 1 \end{cases}$$

$$y(x) = \sum_{n=0}^{\infty} a_n x^n$$

Find $a_0, a_1, a_2 \in \mathbb{R}$.

Solution $y(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + \dots$

$$\Rightarrow y(0) = a_0 \quad \text{and} \quad y'(x) = a_1 + 2a_2 x + 3a_3 x^2 + \dots$$

$$\Rightarrow \begin{cases} a_1 + 2a_2 x + 3a_3 x^2 + \dots = x^2 + (a_0 + a_1 x + a_2 x^2 + \dots)^2, \quad \forall x \\ a_0 = 1 \end{cases}$$

$$\Rightarrow a_1 + 2a_2 x + 3a_3 x^2 + \dots = x^2 + \underbrace{a_0^2}_{1} + \underbrace{2a_0 a_1 x}_{2a_1 x} + a_1^2 x^2 + 2a_0 a_2 x^2 + \dots$$

$$\Rightarrow a_1 = a_0^2 = 1, \quad 2a_2 = 2a_0 a_1 \Rightarrow a_0 = a_1 = a_2 = 1.$$

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4.

Specify the type and stability of the linear system $\dot{x} = -6x, \dot{y} = 3y$. Find a global first integral of this system. Check that H is indeed a global first integral using the definition.

Solution The matrix's system is $A = \begin{pmatrix} -6 & 0 \\ 0 & 3 \end{pmatrix}$, which is diagonal. Hence, its eigenvalues are $\lambda_1 = -6$ and $\lambda_2 = 3$. Since $\lambda_{1,2} \in \mathbb{R}$ with $\lambda_1 < 0 < \lambda_2$, this linear system has the origin an unstable saddle.

Since we have to use the definition of a first integral, we find now the flow.

Let $\eta = (\eta_1, \eta_2) \in \mathbb{R}^2$ and consider the IVP $\begin{cases} \dot{x} = -6x \\ \dot{y} = 3y \\ x(0) = \eta_1 \\ y(0) = \eta_2 \end{cases}$

$$\Rightarrow \varphi(t, \eta_1, \eta_2) = (\eta_1 e^{-6t}, \eta_2 e^{3t}), \quad \forall t \in \mathbb{R}.$$

Since $(\eta_1 e^{-6t}) \cdot (\eta_2 e^{3t})^2 = \eta_1 \eta_2^2, \quad \forall t \in \mathbb{R}$ we have that $H: \mathbb{R}^2 \rightarrow \mathbb{R}, H(x, y) = xy^2$ is a first integral which is global since it is well-defined on \mathbb{R}^2 , and $H \in C^1(\mathbb{R}^2)$.

5 (a) Represent in the complex plane the curve
 $\left\{ \frac{1+i}{\sqrt{2}} e^{-3t-it} : t \geq 0 \right\}$.

Solution. Denote $z(t) = \frac{1+i}{\sqrt{2}} e^{-3t-it}$, $\forall t \geq 0$.
 we have $z(0) = \frac{1+i}{\sqrt{2}}$, $e^{-3t-it} = e^{-3t} (\cos t - i \sin t)$

$$\Rightarrow z(0) = \cos \frac{\pi}{4} + i \sin \frac{\pi}{4} = e^{i \frac{\pi}{4}}$$

$$\Rightarrow z(t) = e^{i \frac{\pi}{4}} \cdot e^{-3t-it} = e^{-3t} \cdot e^{i(\frac{\pi}{4}-t)} =$$

$$= e^{-3t} \left[\cos \left(\frac{\pi}{4} - t \right) + i \sin \left(\frac{\pi}{4} - t \right) \right] \quad \forall t \geq 0.$$

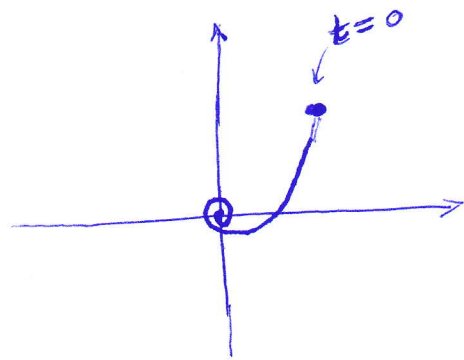
$$\Rightarrow |z(t)| = e^{-3t}, \quad \forall t \geq 0 \text{ and } \arg(z(t)) = \frac{\pi}{4} - t, \quad \forall t \geq 0.$$

\Rightarrow as t increases from 0 to ∞ ,

$|z(t)|$ decreases exponentially to 0

and $\arg(z(t))$ is strictly decreasing

\Rightarrow when moving on the curve as t increases from 0 to ∞ ,
 we approach the origin and rotate around
 the origin in the clockwise direction.



Remark. $z(t) = \frac{e^{-3t}}{\sqrt{2}} (1+i)(\cos t - i \sin t) =$

$$= \frac{1}{\sqrt{2}} e^{-3t} (\cos t - i \sin t + i \cos t + \sin t) = \frac{1}{\sqrt{2}} e^{-3t} \begin{bmatrix} \cos t + \sin t + \\ i(\cos t - \sin t) \end{bmatrix}$$

5(b)

Find the solution of the IVP $\begin{cases} \dot{x} = -3x + y, \\ \dot{y} = -x - 3y \end{cases}$ $x(0) = y(0) = -1$.

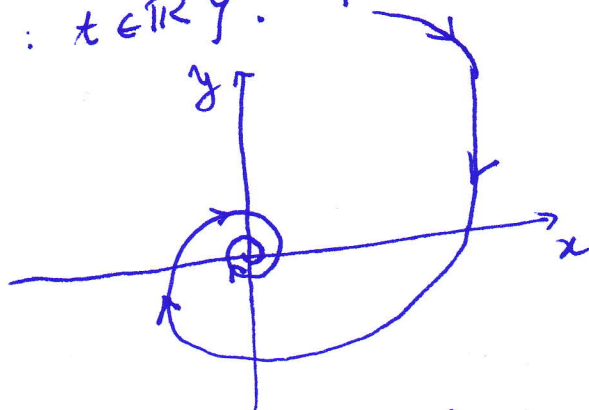
Represent in the phase plane the corresponding orbit.

Solution. I will not solve the first part. You have enough written examples (similar exercises). The following sol. is

obtained: $\begin{cases} x = e^{-3t} \cos t + e^{-3t} \sin t \\ y = e^{-3t} \cos t - e^{-3t} \sin t \end{cases}, t \in \mathbb{R}. \quad (*)$

By definition, the corresponding orbit is the curve of parametric equations (*). Using the notation at (a), we have that this orbit is, in fact, the curve

$\{ \sqrt{2} z(t) : t \in \mathbb{R} \}$. Thus it looks like



5(c)

Specify the type and stability of the linear system

$\begin{cases} \dot{x} = -3x + y \\ \dot{y} = -x - 3y \end{cases}$. If this system has a global first integral, find it.

Solution. $A = \begin{pmatrix} -3 & 1 \\ -1 & -3 \end{pmatrix} \quad \begin{vmatrix} -3-\lambda & 1 \\ -1 & -3-\lambda \end{vmatrix} = 0 \Leftrightarrow (3+\lambda)^2 + 1 = 0$

$\lambda_{1,2} = -3 \pm i \Rightarrow$ focus, global attractor.

We know from the lecture that a global attractor does not have a global first integral.

5(d) Let $\eta = \begin{pmatrix} -1 \\ -1 \end{pmatrix}$. Find $e^{2A}\eta$, where A is the matrix of the system from (c).

Solution. We know from the lecture that $e^{tA}\eta$ is the unique solution of the IVP $\dot{X} = AX$, $X(0) = \eta$.
Thus, $e^{tA}\eta$ is the solution found at b) in our case.

$$\Rightarrow e^{2A}\eta = e^{\begin{pmatrix} -6 & 2 \\ -2 & -6 \end{pmatrix}} \cdot \begin{pmatrix} -1 \\ -1 \end{pmatrix} =$$

$$= \begin{pmatrix} e^{-6}\cos 2 + e^{-6}\sin 2 \\ e^{-6}\cos 2 - e^{-6}\sin 2 \end{pmatrix}.$$