

rosjet

ROS nodes and arduino libraries for the 'Jet' Toolkit.

installation

For installing and configuring your Jetson board for the Jet robot, see the TK1_Installation file.

Running rosjet

For Gazebo Simulation:

```
roslaunch jet_bringup jet_gazebo.launch
```

For Real Robot:

```
roslaunch jet_bringup jet_real.launch
```