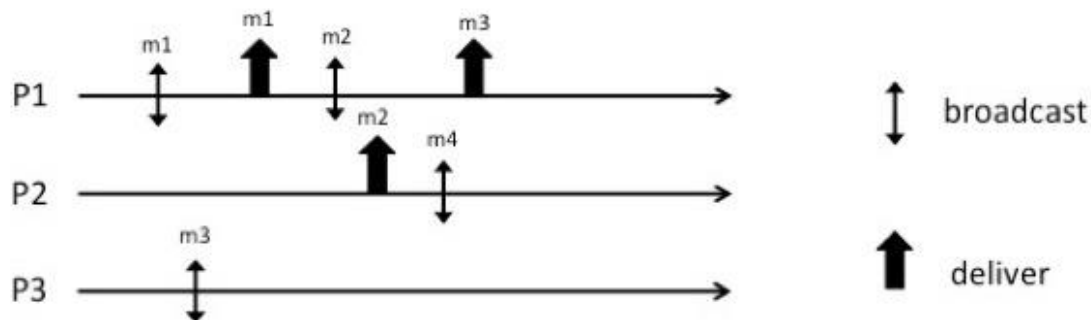


Dependable Distributed Systems
Master of Science in Engineering in Computer Science

AA 2023/2024

Lecture 13 – Exercises
October 25th, 2023

Ex 1: Let us consider the following partial execution



Answer the following points:

1. Provide all the possible sequences satisfying Causal Order
2. Complete the execution to have a run satisfying FIFO order but not causal order

Ex 2: Consider a distributed system constituted by n processes $\Pi = \{p_1, p_2, \dots, p_n\}$ with unique identifiers that exchange messages through FIFO perfect point-to-point links and are structured through a line (i.e., each process p_i can exchange messages only with processes p_{i-1} and p_{i+1} when they exist). Processes may crash and each process is equipped with a perfect oracle (having the interface *new_right(p)* and *new_left(p)*) reporting a new neighbor when the previous one is failing.

Write the pseudo-code of an algorithm implementing a Perfect failure detector primitive.

Ex 3: Consider a distributed system constituted by n processes $\Pi = \{p_1, p_2, \dots, p_n\}$ with unique identifiers that exchange messages through perfect point-to-point links and are structured through a ring (i.e., each process p_i can exchange messages only with processes p_{i-1} and $p_{i+1 \pmod n}$). Processes may crash and each process is equipped with a perfect oracle (having the interface *new_next(p)*) reporting a new neighbor when the previous one is failing.

Write the pseudo-code of an algorithm implementing a Uniform Reliable Broadcast communication primitive.

Ex 4: A transient failure is a failure that affects a process temporarily and that randomly alter the state of the process (i.e., when the process is affected by a transient failure, its local variables assume a random value).

Let us consider a distributed system composed by N processes where f_c processes can fail by crash and f_t processes can suffer transient failures between time t_0 and t_{stab} .

Let us consider the following algorithm implementing the Regular Reliable Broadcast specification

Algorithm 3.2: Lazy Reliable Broadcast

Implements:
ReliableBroadcast, **instance** rb .

Uses:
BestEffortBroadcast, **instance** beb ;
PerfectFailureDetector, **instance** \mathcal{P} .

upon event $\langle rb, Init \rangle$ **do**
 $correct := \Pi$;
 $from[p] := [\emptyset]^N$;

upon event $\langle rb, Broadcast \mid m \rangle$ **do**
 trigger $\langle beb, Broadcast \mid [DATA, self, m] \rangle$;

upon event $\langle beb, Deliver \mid p, [DATA, s, m] \rangle$ **do**
 if $m \notin from[s]$ **then**
 trigger $\langle rb, Deliver \mid s, m \rangle$;
 $from[s] := from[s] \cup \{m\}$;
 if $s \notin correct$ **then**
 trigger $\langle beb, Broadcast \mid [DATA, s, m] \rangle$;

upon event $\langle \mathcal{P}, Crash \mid p \rangle$ **do**
 $correct := correct \setminus \{p\}$;
 forall $m \in from[p]$ **do**
 trigger $\langle beb, Broadcast \mid [DATA, p, m] \rangle$;

Answer to the following questions:

1. For every property of the Regular Reliable Broadcast specification, discuss if it is guaranteed between time t_0 and t_{stab} and provide a motivation for your answer.
2. For every property of the Regular Reliable Broadcast specification, discuss if it is eventually guaranteed after t_{stab} and provide a motivation for your answer.
3. Assuming that the system is synchronous, explain if and how you can modify the algorithm (no pseudo-code required) to guarantee that No Duplication, Validity and Agreement properties will be eventually guaranteed after t_{stab} .

Ex 5: Let us consider the following algorithm

```

upon event  $\langle frb, Init \rangle$  do
   $lsn := 0;$ 
   $pending := \emptyset;$ 
   $next := [1]^N;$ 

upon event  $\langle frb, Broadcast \mid m \rangle$  do
  for each  $p \in \Pi$  do
    trigger  $\langle l, send \mid p, [DATA, self, m, lsn] \rangle;$ 
   $lsn := lsn + 1;$ 

upon event  $\langle l, deliver \mid p, [DATA, s, m, sn] \rangle$  do
   $pending := pending \cup \{(s, m, sn)\};$ 

while exists  $(s, m', sn') \in pending$  such that  $sn' = next[s]$  do
   $next[s] := next[s] + 1;$ 
   $pending := pending \setminus \{(s, m', sn')\};$ 
  trigger  $\langle frb, Deliver \mid s, m' \rangle;$ 

```

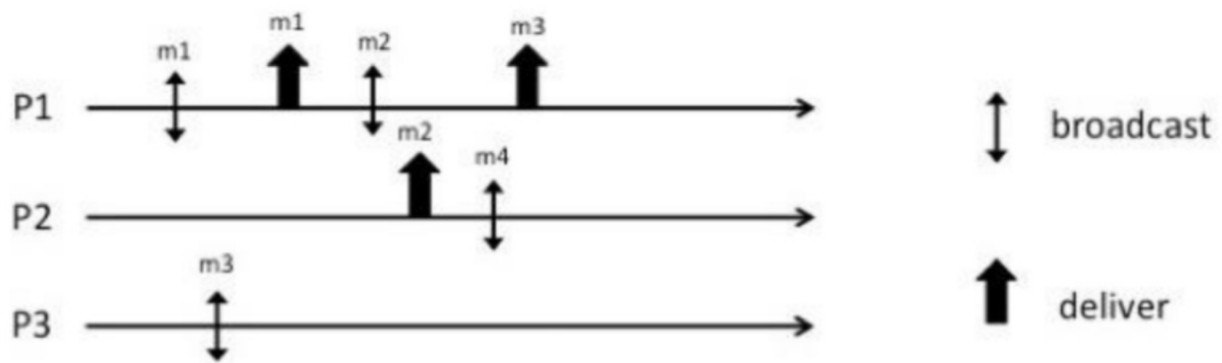
Let us consider the following properties:

- **Validity:** If a correct process p broadcasts a message m , then p eventually delivers m .
- **No duplication:** No message is delivered more than once.
- **No creation:** If a process delivers a message m with sender s , then m was previously broadcast by process s .
- **Agreement:** If a message m is delivered by some correct process, then m is eventually delivered by every correct process.
- **FIFO delivery:** If some process broadcasts message m_1 before it broadcasts message m_2 , then no correct process delivers m_2 unless it has already delivered m_1 .

Assuming that every process may fail by crash, address the following points:

1. Considering that messages are sent by using *perfect point to point links*, for each property mentioned, discuss if it is satisfied or not and provide a motivation for your answer;
2. Considering that messages are sent by using *fair loss links*, for each property mentioned, discuss if it is satisfied or not and provide a motivation for your answer.

Ex 1: Let us consider the following partial execution



Answer the following points:

1. Provide all the possible sequences satisfying **Causal Order**
2. Complete the execution to have a run satisfying **FIFO order** but not causal order

① All sequences for CAUSAL ORDER

FIFO + $m_1 \rightarrow m_2$

LOCAL: $m_2 \rightarrow m_4$

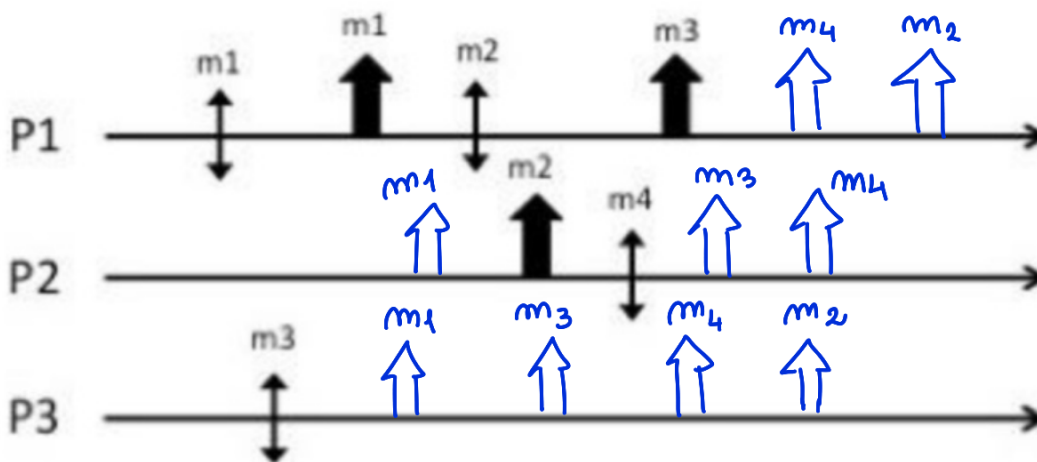
$m_1 \ m_2 \ m_3 \ m_4$

$m_1 \ m_3 \ m_2 \ m_4$

$m_1 \ m_2 \ m_4 \ m_3$

$m_3 \ m_1 \ m_2 \ m_4$

② FIFO not causal



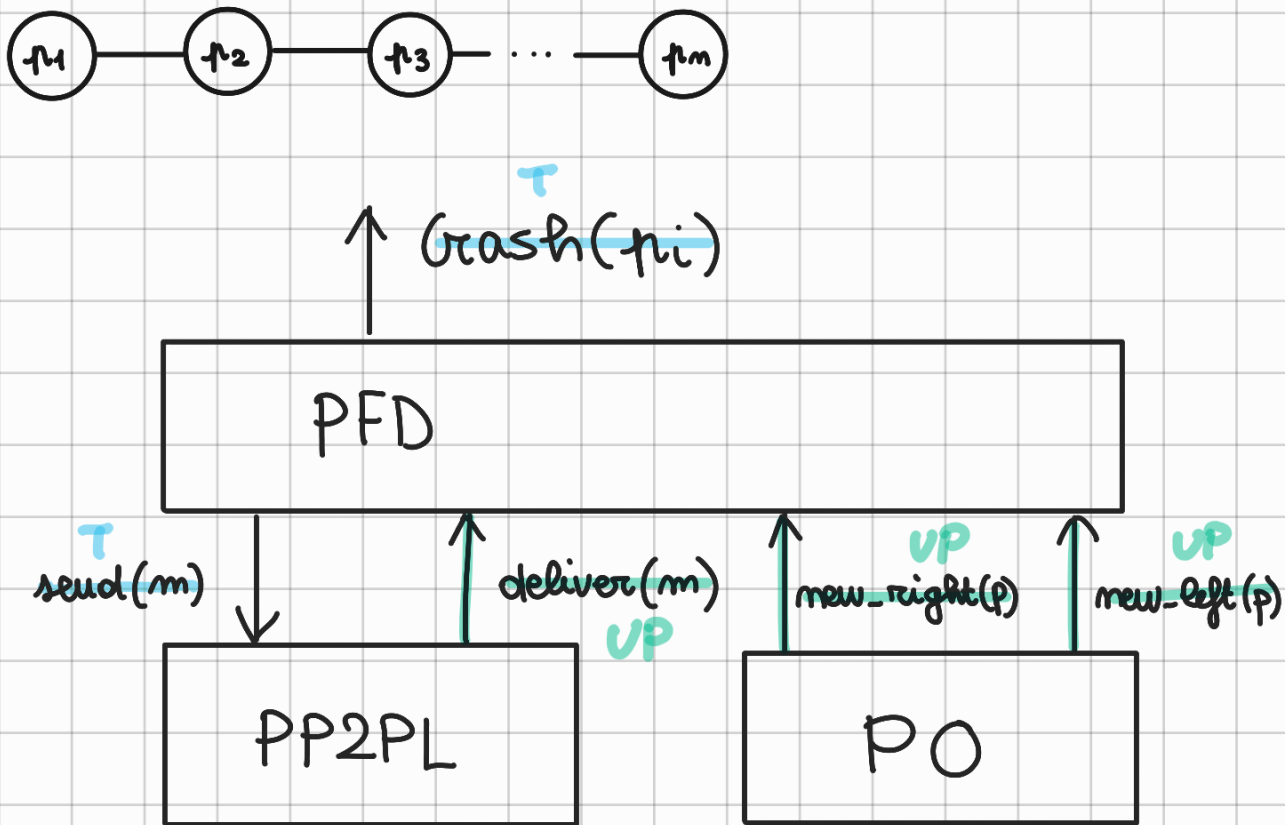
FIFO: $m_1 \rightarrow m_2$

not CAUSAL: $m_2 \rightarrow m_4$

Ex 2: Consider a distributed system constituted by n processes $\Pi = \{p_1, p_2, \dots, p_n\}$ with unique identifiers that exchange messages through FIFO perfect point-to-point links and are structured through a line (i.e., each process p_i can exchange messages only with processes p_{i-1} and p_{i+1} when they exist). Processes may crash and each process is equipped with a perfect oracle (having the interface $new_right(p)$ and $new_left(p)$) reporting a new neighbor when the previous one is failing.

Write the pseudo-code of an algorithm implementing a Perfect failure detector primitive.

$\Pi = \{p_1, \dots, p_m\}$ FIFO PP2PL



upon event $\langle \text{PFD}, \text{mit} \rangle$ do

$\text{alive} = \Pi$

$\text{suspected} := \emptyset$ empty

$\text{left} := \text{get_left}()$

$\text{right} := \text{get_right}()$

$\text{starttimer}(\Delta)$ to check the failure

} can be null

CRASH \rightarrow I have to assign a new value to
 upon event $\langle PO, \text{new_right} \mid r \rangle$ do right
 if $\text{right} \neq \text{null}$
 $\text{crash}_r = \text{right}$
 $\text{suspected} := \text{suspected} \cup \{ \text{crash}_r \}$
 trigger $\langle PFD, \text{Crash} \mid \text{crash}_r \rangle$
 trigger $\langle PP2PL, PP2P_send \mid [\text{Crash}, \text{crash}_r] \rangle$
 to right are you alive?

upon event $\langle PO, \text{new_left} \mid l \rangle$ do
 if $\text{left} \neq \text{null}$
 $\text{crash}_l = \text{left}$
 $\text{suspected} := \text{suspected} \cup \{ \text{crash}_l \}$
 trigger $\langle PFD, \text{Crash} \mid \text{crash}_l \rangle$
 trigger $\langle PP2PL, PP2PL_send \mid [\text{Crash}, \text{crash}_l] \rangle$
 to left

upon event $\langle PP2PL, \text{PP2PL_deliver} \mid [\text{Crash}, r] \rangle$ do
 if $\text{suspected} \neq \emptyset$
 for each r_i in suspected
 $\text{right} := \text{new_right}$
 $\text{left} := \text{new_left}$
 trigger $\langle PP2PL, PP2PL_send \mid [\text{Crash}] \text{ to left} \rangle$
 trigger $\langle PP2PL, PP2PL_send \mid [\text{Crash}] \text{ to right} \rangle$