Consider to deploy the "Eager Reliable Broadcast" algorithm for the Regular Reliable Broadcast in a system consisting of **10 processes**.

Assume that the computation delay on the processes is negligible and equal to 0, and that each process is able to send/receive (P2P) 10 msgs/sec.

If each process execute a rb-broadcast every 20 seconds on average, what is the expected time to rb-deliver to deliver a message in the system assuming all correct processes?

```
Algorithm 3.3: Eager Reliable Broadcast

Implements:
    ReliableBroadcast, Instance rb.

Uses:
    BestEffortBroadcast, Instance beb.

upon event ⟨ rb, Init ⟩ do
    delivered := ∅;

upon event ⟨ rb, Broadcast | m⟩ do
    trigger ⟨ beb, Broadcast | [DATA, self, m] ⟩;

upon event ⟨ beb, Deliver | p, [DATA, s, m] ⟩ do
    if m ∉ delivered then
    delivered := delivered ∪ {m};
    trigger ⟨ rb, Deliver | s, m ⟩;
    trigger ⟨ beb, Broadcast | [DATA, s, m] ⟩;
```

mersage rate = 10 msgs/sec service rate
reb-broadcast = 20 s ou average ornival
10 processes
Ju the eager RB we assure all correct
processes and the algo retrasuit every mag
Ju the eager RB we assume all correct processes and the algo retrasmit every mag that received (broadcost deliver).
Harring 10 processes that broadcasts every 20 s
Harring 10 processes that broadcasts energ 20 s on average, me ou calculate the time that
it is required to perform the operation for
each process:
$\frac{1}{20}$ = 0.05 msgs/sec execution = 10.0.05
Resource time = 1 = 0015
Response time = $\frac{1}{10.10 - 0.05}$ = 0,015
rate $\lambda = 10.0,05.10 = 5 \text{ reg/s}$
reate
$R = \frac{1}{1000} = \frac{1}{1000} = 0.25$
μ - λ 5

Consider the two distributed protocols presented in the following pseudo codes: getValuesBiring and getValuesUniring.

Suppose that the system is composed by **10 processes**, each of which is equipped with a local perfect failure detector that can provide the identity of a new process when a current one fails.

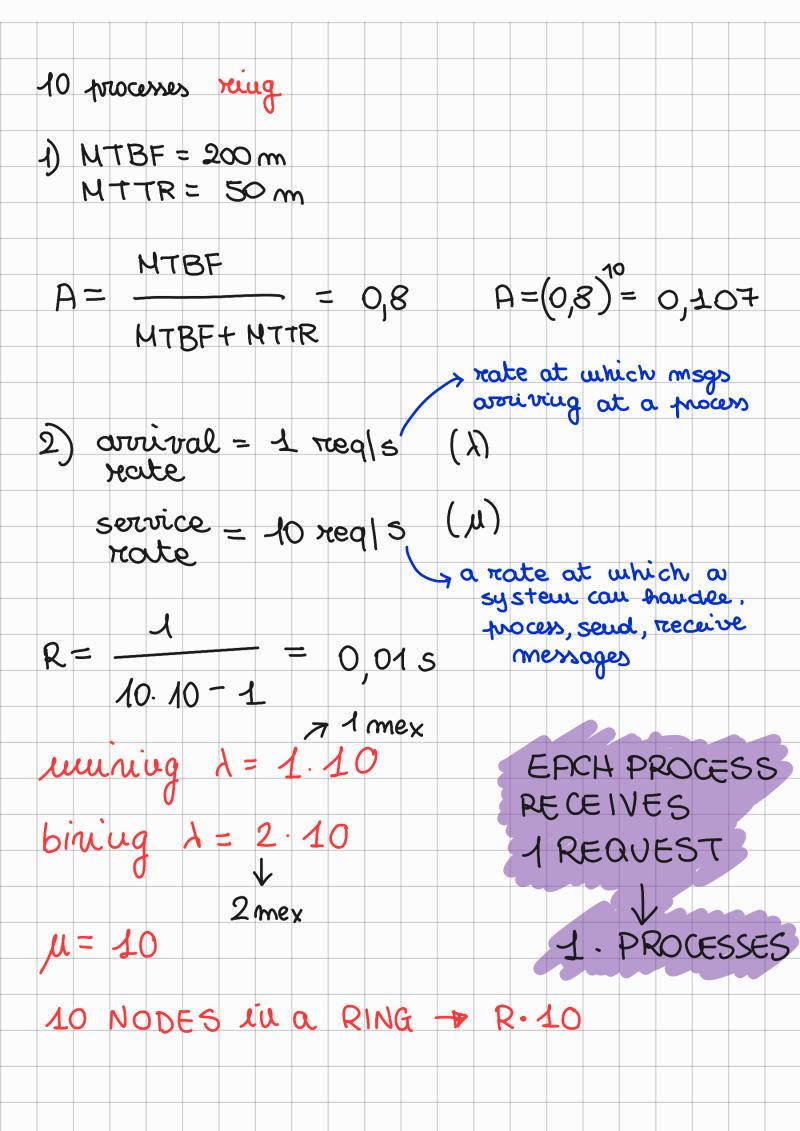
- 1) If a process crashes every 200 minutes on average, and the local failure detector takes 50 minutes to identify a faulty process and to provide the identity of a new neighbor, evaluate the availability of the system
- 2) If each process receives **1 request** (i.e., a call to <G, get>) **per second**, what is the expected response time, i.e., the expected time between <G, get> and <G, return>, assuming that the computation delay on the processes is negligible and equal to 0, that no crashes occurs, and that each process is able to send/receive **10 msgs/sec**?

Algorithm 7 getValuesUniring \mathcal{G}

```
1: procedure INIT
         // v : local value that changes over time
         // next : neighbor's ID in the ring
         // id : local identifier
 4:
 5: upon event \langle \mathcal{G}, get \rangle do
         trigger \langle PP2PL, send \mid next, \langle id, \emptyset \rangle \rangle
 7: upon event \langle PP2PL, deliver \mid q, \langle source, values \rangle \rangle do
         locValues := values \cup \{v\}
 8:
         if source == id then
 9:
              trigger \langle \mathcal{G}, return \mid locValues \rangle
10:
         else
11:
              trigger \langle PP2PL, send \mid next, \langle id, locValues \rangle \rangle
12:
13: upon event \langle \mathcal{P}, newNext \mid newNext \rangle do
         next := newNext
14:
```

Algorithm 8 getValuesBiring \mathcal{G}

```
1: procedure INIT
          // v : local value that changes over time
          // left : neighbor's ID in the ring
          // right : neighbor's ID in the ring
 4:
          // id : local identifier
 5:
 6: upon event \langle \mathcal{G}, qet \rangle do
          trigger \langle PP2PL, send \mid left, \langle id, \emptyset \rangle \rangle
          trigger \langle PP2PL, send \mid right, \langle id, \emptyset \rangle \rangle
 9: upon event \langle PP2PL, deliver \mid q, \langle source, values \rangle \rangle do
          locValues := values \cup \{v\}
10:
          if source == id then
11:
              trigger \langle \mathcal{G}, return \mid locValues \rangle
12:
          else if q == right then
13:
              trigger \langle PP2PL, send \mid left, \langle id, locValues \rangle \rangle
14:
          else
15:
              trigger \langle PP2PL, send \mid right, \langle id, locValues \rangle \rangle
16:
17: upon event \langle \mathcal{P}, newRight \mid newRight \rangle do
         right := newRight
19: upon event \langle \mathcal{P}, newLeft | newLeft \rangle do
         next := newLeft
```



Consider to deploy the "Exclude on Timeout" algorithm for the perfect failure detector in a system consisting of **30 processes**.

Assume that the computation delay on the processes is negligible and equal to 0, and that each process is able to send/receive **10 msgs/sec**.

What is the expected minimum value for the timeout Δ that can be set?

```
Algorithm 2.5: Exclude on Timeout
Implements:
     PerfectFailureDetector, instance P.
Uses:
     PerfectPointToPointLinks, instance pl.
upon event (P, Init) do
     alive := \Pi;
     detected := 0:
     starttimer(\Delta);
upon event ( Timeout ) do
     forall p \in \Pi do
          if (p \notin alive) \land (p \notin detected) then
               detected := detected \cup \{p\};
               trigger ( P, Crash | p );
          trigger (pl, Send | p, [HEARTBEATREQUEST]);
     alive := \emptyset:
     starttimer(\Delta);
upon event (pl, Deliver | q, [HEARTBEATREQUEST] ) do
     trigger (pl, Send | q, [HEARTBEATREPLY]);
upon event (pl, Deliver | p, [HEARTBEATREPLY] ) do
     alive := alive \cup \{p\};
```

