Distributed Systems

Master of Science in Engineering in Computer
Science

AA 2017/2018

LECTURE 3 (PART 2): TIME IN DISTRIBUTED SYSTEMS

Logical Time

Logical clock

Physical clock synchronization algorithms try to coordinate distributed clocks to reach a common value

- Physical clock synchronization algorithms are based on the estimation of transmission delay but in several system it can be hard to find a good estimation.
- In several applications it is not important when things happened but in which order they happened

However in a Distributed System, each system has its own "logical clock"

 If clocks are not aligned it is not possible to order events generated by different processes

Reliable way of ordering events is required!

Notes:

- Two events occurred at some process p_i happened in the same order as p_i observes them
- □ When p_i sends a message to p_j the *send* event happens before the *receive* event
- Lamport introduces the happened-before relation that captures the causal dependencies between events (causal order relation)
 - \square We note with \rightarrow_i the ordering relation between events in a process p_i
 - \square We note with \rightarrow the happened-before between any pair of events

Happened-Before Relation: Definition

Two events e and e' are related by happened-before relation (e \rightarrow e') if:

- $\circ \exists p_i \mid e \rightarrow_i e'$
- \circ \forall message m send(m) \rightarrow receive(m)
 - send(m) is the event of sending a message m
 - receive(m) is the event of receipt of the same message m
- \exists e, e', e'' | (e \rightarrow e'') \land (e'' \rightarrow e') (happened-before relation is transitive)

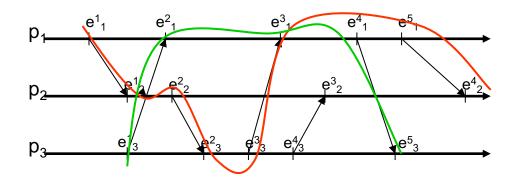
Happened-Before Relation

Using the three rules is possible to define a causal ordered sequence of events $e_1, e_2, ..., e_n$

Notes:

- The sequence e_1 , e_2 , ..., e_n may not be unique
- It may exists a pair of events $\langle e_1, e_2 \rangle$ such that e_1 and e_2 are not in happened-before relation
- If e_1 and e_2 are not in happened-before relation then they are *concurrent* ($e_1 | | e_2$)
- For any two events e_1 and e_2 in a distributed system, either $e_1 \rightarrow e_2$, $e_2 \rightarrow e_1$ or $e_1 | |e_2|$

happened-before: example



 e^{j}_{i} is j-th event of process p_{i}

$$S_1 = \langle e_1^1, e_2^1, e_2^2, e_3^2, e_3^3, e_1^3, e_1^4, e_1^5, e_2^4 \rangle$$

 $S_2 = \langle e_3^1, e_1^2, e_1^3, e_1^4, e_3^5 \rangle$

Note:

e₃ and e₂ are concurrent

Logical Clock

The Logical Clock, introduced by Lamport, is a software counting register monotonically increasing its value

Logical clock is not related to physical clock

Each process p_i employs its logical clock L_i to apply a *timestamp* to events

 $L_i(e)$ is the "logical" timestamp assigned, using the logical clock, by a process p_i to events e.

Property:

• If $e \rightarrow e'$ then L(e) < L(e')

Observation:

• The ordering relation obtained through logical timestamps is only a partial order. Consequently timestamps could not be sufficient to relate two events

Scalar Logical Clock: an implementation

Each process p_i initializes its logical clock $L_i=0$ ($\forall i=1...N$)

p_i increases L_i of 1 when it generates an event (either send or receive)

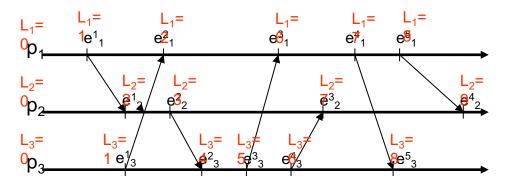
When p_i sends a message m

- creates an event send(m)
- increases L_i
- timestamps m with t=L_i

When p_i receives a message m with timestamp t

- Updates its logical clock L_i = max(t, L_i)
- Produces an event receive(m)
- Increases L_i

Scalar Logical Clock: example



- e^j_i is j-th event of process p_i
- L_i is the logical clock of p_i
- Note:
 - $e^1_1 \rightarrow e^2_1$ and timestamps reflect this property
 - $e_1^1 \mid \mid e_3^1$ and respective timestamps have the same value
 - $e_2^1 \mid e_3^1$ but respective timestamps have different values

Limits of Scalar Logical Clock

Scalar logical clock can guarantee the following property

• IF $e \rightarrow e'$ then L(e) < L(e')

But it is not possible to guarantee

• IF L(e) < L(e') then $e \rightarrow e'$

Consequently:

• It is not possible to determine, analyzing only scalar clocks, if two events are concurrent or correlated by the happened-before relation.

Mattern [1989] and Fridge [1991] proposed an improved version of logical clock where events are timestamped with local logical clock and node identifier

Vector Clock

Vector Clock: definition

Vector Clock for a set of N processes is composed by an array of N integer counters

Each process p_i maintains a Vector Clock V_i and timestamps events by mean of its Vector Clock

Similarly to scalar clock, Vector Clock is attached to message m (in this case we attach an array of integer)

Vector Clock allows nodes to order events in happens-before order based on timestamps

- Scalar clocks: $e \rightarrow e'$ implies L(e) < L(e')
- Vector clocks: e → e' iff L(e) < L(e')

Vector Clock : an implementation

Each process p_i initializes its Vector Clock V_i

• $V_i[j]=0 \ \forall \ j=1... \ N$

p_i increases V_i[i] of 1 when it generates an event

V_i[i]=V_i[i]+1

When p_i sends a message m

- Creates an event send(m)
- Increases V_i
- timestamps m with t=V_i

When p_i receives a message m containing timestamp t

- Updates it logical clock V_i[j] = max(t[j], V_i[j]) ∀ j = 1... N
- Generates an event receive(m)
- Increases V_i

Vector Clock: properties

A Vector Clock V_i

- V_i[i] represents the number of events produced by p_i
- $V_i[j]$ with $i \neq j$ represents the number of events generated by p_i that p_i can known

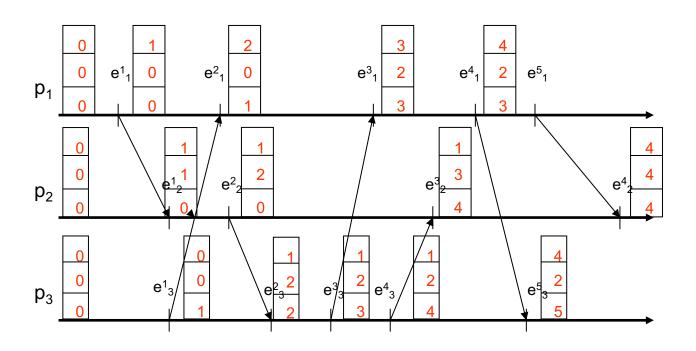
V = V' if and only if

 $V \le V'$ if and only if

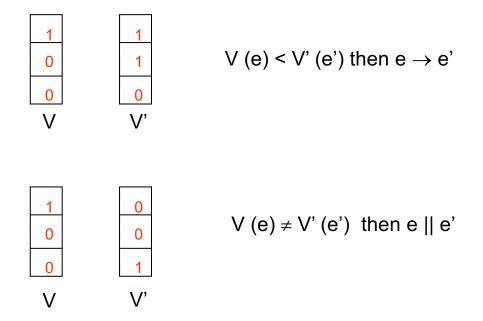
V < V' therefore the event associated to V happened before the event associated to V' if and only if

- \circ $V \leq V' \wedge V \neq V'$
 - ∘ ∀ i = 1...N V' [i] ≥ V [i]
 - $^{\circ} \quad \exists \ i \in \{1 \ ... \ N\} \ \big| \ V' \ \big[\ i \ \big] > V \ \big[\ i \ \big]$

Vector Clock: an example



A comparison of Vector Clocks



Differently from Scalar Clock, Vector Clock allows to determine if two events are concurrent or related by an happened-before relation

Logical Time and Distributed Algorithms

Logical clock in distributed algorithms

We have seen two mechanisms to represent logical time

- Scalar Clock
- Vector Clock

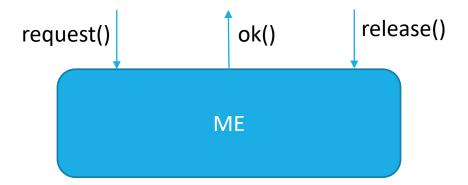
Each mechanism can be used to solve different problems, depending on the problem specification

- Scalar Timestamp → Lamport's Mutual Exclusion
- Vector Timestamp → Causal Broadcast

The Mutual Exclusion abstraction

Specification

- Mutual Exclusion: at every time t at most one process p is in critical section
- No-Deadlock: there always exists a process p able to enter the critical section.
- No-Starvation: every process p requesting the critical section eventually gets in.



Time stamp based algorithm: Lamport

Difference from concurrent system

When a process wants to enter the CS sends a request message to all the other

An history of the operations is maintained by using a counter (time stamp)

Each transmission and reception event is relevant to the computation:

- The counter is incremented for each send and receive event
- The counter is incremented also when a message, not directly related to the mutual exclusion computation, is sent or received.

Lamport's algorithm: implementation

Local data structures to each process pi

- ck
 - Is the counter for process pi
- ° Q
 - Is a queue maintained by pi where CS access requests are stored

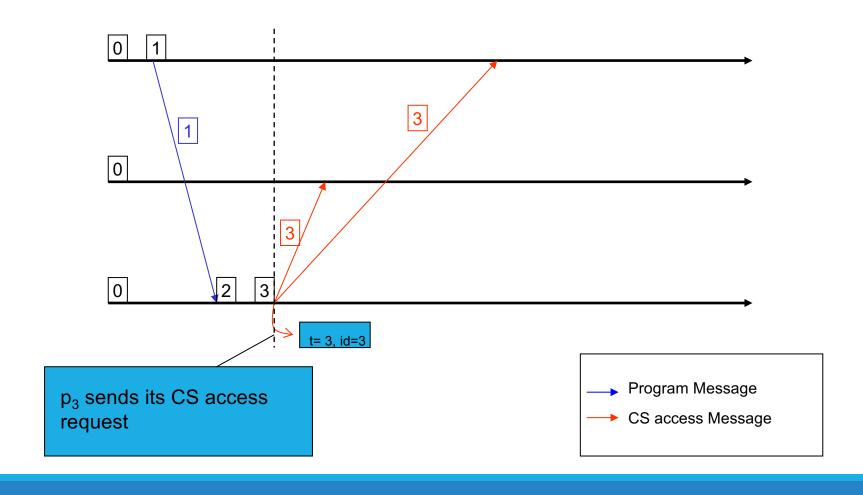
Algorithm rules for a process pi

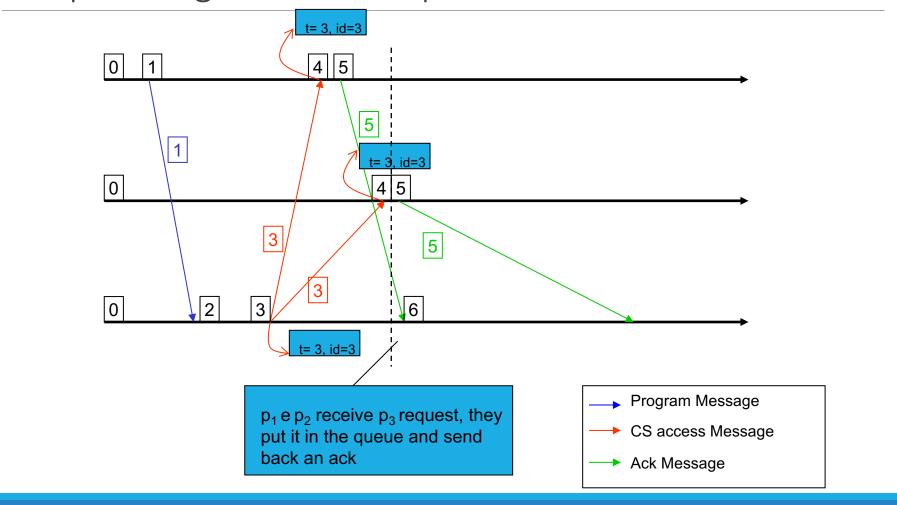
- Access the CS
 - pi sends a request message, attaching ck, to all the other processes
 - pi adds its request to Q
- Request reception from a process pj
 - pi puts pj request (including the timestamp) in its queue
 - pi sends back an ack to pj

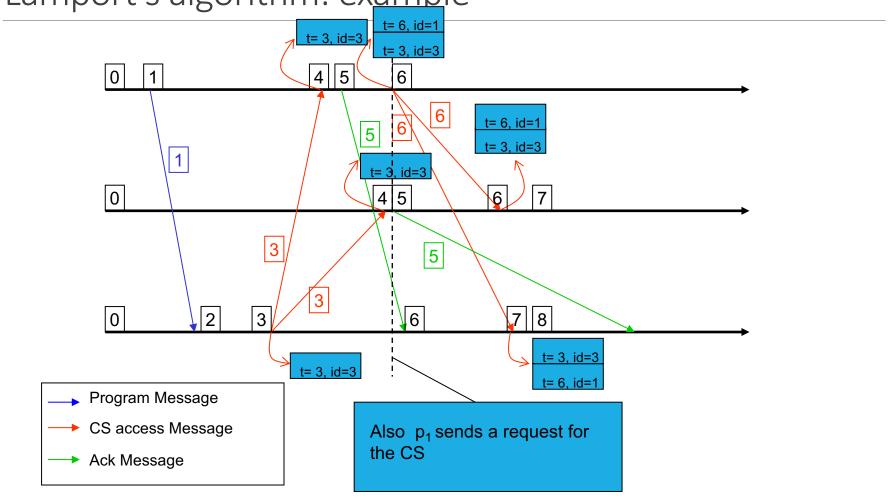
Lamport's algorithm: implementation

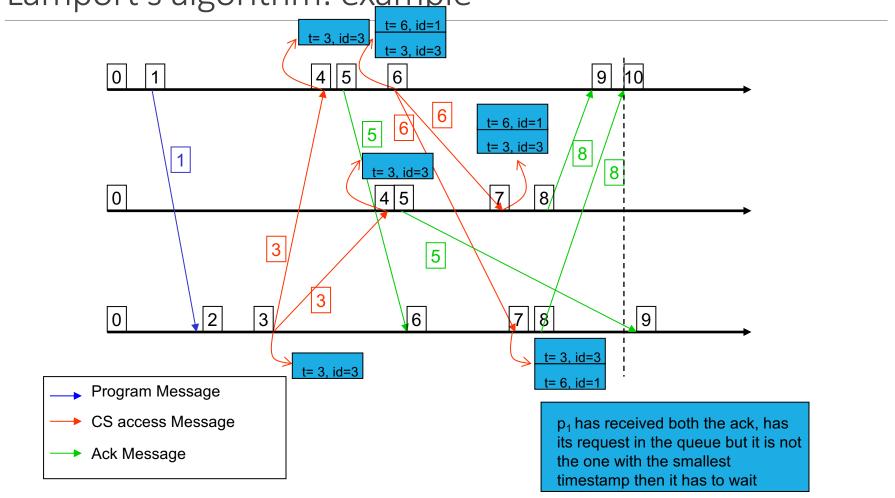
Algorithm rules for a process pi

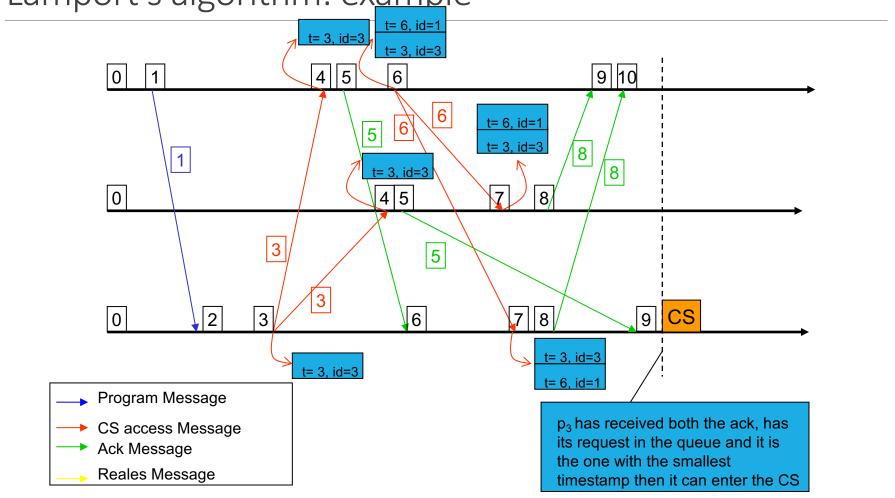
- p_i enters the CS iff
 - p_i has, in its queue, a request with timestamp t
 - t is the small timestamp in the queue
 - p_i has already received an ack with timestam t' from any other process and t'>t
- Release of the CS
 - p_i sends a RELEASE message to all the other processes
 - p_i deletes its request from the queue
- Reception of a release message from a process pj
 - \circ p_i deletes p_j's request from the queue

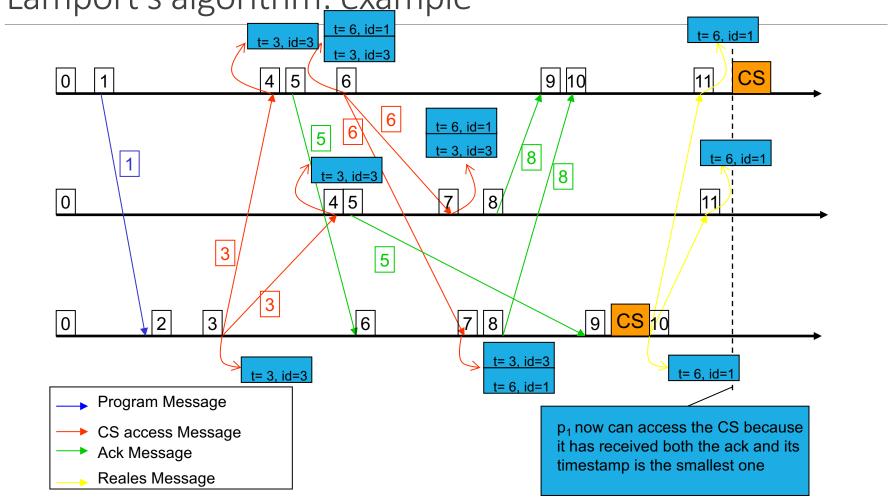








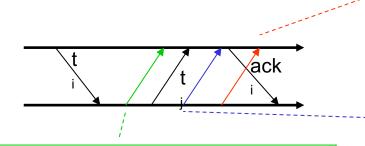




Lamport's algorithm: safety proof

Let us suppose by contradiction that both p_i and p_i enter the CS

- \circ \Rightarrow both the processes have received an ack from any other process and, to enter the CS, the timestamp has to be the smallest in the queue
 - t_i < t_i < ack_i.ts
 - t_i < t_i < ack_j.ts



p_j ack arrives before p_j request then p_i enters the CS without any problem

Both processes receive the ack when the two requests are in the queue but ME is guaranteed by the total order on the timestamps

p_j's ack arrives after p_j's request but before p_i's ack then p_i enters the CS without any problem and sends its ack after executing the CS

Lamport's algorithm: properties

<u>Fairness is satisfied</u>: different requests are satisfied in the same order as they are generated

- Such order comes from the happened-before relation:
 - ☐ If two requests are in happened-before relation then they are satisfied in the same order.
 - □ If two request are concurrent with respect to the happended before relation then the access can happen in any order

Lamport's algorithm: performances

Lamport's algorithm needs 3(N-1) messages for the CS execution

- N-1 requests
- N-1 acks
- N-1 releases

In the best case (none is in the CS and only one process ask for the CS) there is a delay (from the request to the access) of 2 messages

Ricart-Agrawala's algorithm: implementation

Local variables

- #replies (initially 0)
- State ∈ {Requesting, CS, NCS} (initially NCS)
- Q pending requests queue (initially empty)
- Last Req
- Num

Algorithm

begin

- 1. State=Requesting
- 2. Num=num+1; Last Reg=num
- 3. \forall i=1...N send REQUEST(num) to pi
- 4. Wait until #replies=n-1
- 5. State=CS
- 6. CS
- 7. \forall r \in Q send REPLY to r
- 8. $Q = \emptyset$; State=NCS; #replies=0

Upon receipt REQUEST(t) from pj

- If State=CS or (State=Requesting and {Last_Req,i}<{t,j})
- 2. Then insert in Q{t, j}
- 3. Else send REPLY to pi
- 4. Num=max(t,num)

Upon receipt of REPLY from pj

1. #replies=#replies+1

