# Formal Methods Formulas and Algorithm

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## 1 Introduciton

this document is a collection of formulas to use during formal methods exercises. The .tex file is available to make it always richer, bigger and better.

## 2 FOL

 $\alpha$ -rules:

$$\begin{array}{cccc} \frac{\phi \wedge \psi}{\phi} & \frac{\neg(\phi \vee \psi)}{\neg \phi} & \frac{\neg(\phi \supset \psi)}{\phi} & \frac{\neg \neg \phi}{\phi} \\ \psi & \neg \psi & \neg \psi & \end{array}$$

 $\beta$ -rules:

$$\frac{\phi \vee \psi}{\phi | \psi} \ \frac{\neg (\phi \land \psi)}{\neg \phi | \neg \psi} \ \frac{\phi \supset \psi}{\neg \phi | \psi}$$

extra-rules:

$$\frac{\neg \phi}{X} \quad \frac{\phi \equiv \psi)}{\phi \mid \neg \phi} \quad \frac{\neg (\phi \equiv \psi)}{\neg \phi \mid \phi} \\
\psi \mid \neg \psi \quad \psi \mid \neg \psi$$

 $\delta$ -rules:

$$\frac{\forall x.\phi(x)}{\phi(t)} \ \frac{\neg \exists x.\phi(x)}{\neg \phi(t)}$$

 $\gamma$ -rules:

$$\frac{\neg \forall x. \phi(x)}{\neg \phi(c)} \quad \frac{\exists x. \phi(x)}{\phi(c)}$$

#### Tableaux:

prove  $\phi \equiv \psi$ : check  $\neg(\phi \equiv \psi)$  is UNSAT

 $\phi$  is valid:  $\neg \phi$  is UNSAT

 $\Gamma \models \phi$ : check  $\Gamma \cup \neg \phi$  closes (UNSAT)

 $\Gamma$  SAT: check for an open branch of  $\Gamma$ 

In general each existential is a fresh new constant while universal can be any term also the constant of the existential. To clash instantiate existential and then use universal to make the clash.

### 3 UML TO FOL

a is the attribute name, A the association name, C is the class name, T is the type name, i and j the multiplicities, P is type name for parameter, R is type name for return value. Class:

 $\forall x, y. a(x, y) \supset C(x) \land T(y)$  $\forall x. C(x) \supset i \le \{y | a(x, y)\} \le j$ 

Association:

$$\forall x_1, ..., x_n. A(x_1, ..., x_n) \supset C(x_1) \land ... C(x_n)$$
  
$$\forall x_1. C(x_1) \supset i \leq \{x2 | a(x_1, x_2, ...)\} \leq j$$
  
$$\forall x_2. C(x_2) \supset i \leq \{x1 | a(x_1, x_2, ...)\} \leq j$$

Generalization:

$$\forall x. C_i(x) \supset C(x) for i = 1, ..., n \text{ (is-a)}$$
 
$$\forall x. C_i(x) \supset \neg C_j(x) for i \neq j \text{ (disjoint)}$$
 
$$\forall x. C(x) \supset C_1 \vee ... \vee C_i(x) ... \vee C_n(x) \text{ (completeness)}$$

Subset:

 $\forall x, y.assoc_1(x, y) \supset assoc_2(x, y)$  can refine mult.

Association Class:

$$\begin{split} \forall x,y,z. & a(x,y,z) \supset A(x,y) \land T(z) \\ \forall x,y & A(x,y) \supset \forall z. i \leq \{z | a(x,y,z)\} \leq j \text{ + assoc mult.} \end{split}$$

Reification (when assoc is a class+key constr):

 $\forall x, yr_i(x, y) \supset A(x) \land C_i(y) for i = 1, ..., n$ 

 $\forall x A(x) \supset \exists y . r_i(x, y) fori = 1, ..., n$ 

 $\forall x, y, y'r_i(x, y) \land r_i(x, y') \supset y = y'fori = 1, ..., n$ 

 $\forall y_1, ..., y_n, x, x' . \wedge_{i=1}^n r_i(x, y_i) \wedge r_i(x', y_i) \supset x = x'$ 

Methods:

$$\forall x, p_1, ..., p_m, r. f_{C, P_1, ..., P_m}(x, p_1, ..., p_m, r) \supset C(x)$$
$$(\wedge_{i=i}^m P_i(p_i)) \wedge R(r)$$

$$\forall x, p_1, ..., p_m, r, r'. f_{C, P_1, ..., P_m}(x, p_1, ..., p_m, r)$$
$$f_{C, P_1, ..., P_m}(x, p_1, ..., p_m, r') \supset r = r'$$

Λ

## 4 Evaluation Semantic

$$\frac{(a,s) \rightarrow s'}{true}$$
 if  $s \models Pre(a) \land s' \models Post(a,s)$ 

 $\frac{(skip,s)\rightarrow s}{true}$ 

$$\frac{(\delta_1; \delta_2, s_0) \rightarrow s_f}{(\delta_1, s_0) \rightarrow s_1 \land (\delta_2, s_1) \rightarrow s_f}$$

$$\frac{(if(\phi)then\{\delta_1\}else\{\delta_2\},s) \rightarrow s'}{(\delta_1,s) -> s'}, s \models \phi$$

$$\frac{(if(\phi)then\{\delta_1\}else\{\delta_2\},s) \rightarrow s'}{(\delta_2,s) -> s'}, s \not\models \phi$$

$$\tfrac{(while(\phi)do\{\delta\},s)\to s'}{(\delta,s)\to s''\wedge (while\phi do\{\delta\},s'')\to s'},s\models\phi$$

$$\frac{(while(\phi)do\{\delta\},s)\rightarrow s'}{true},s \not\models \phi$$

## 5 Transition Semantic

#### 5.1 Transition Rules

 $\frac{(a,s) \rightarrow (\epsilon,s')}{true} \text{ if } s \models Pre(a) \land s' \models Post(a,s)$ 

$$\frac{(skip,s) \rightarrow (\epsilon,s')}{true}$$

$$\frac{(\delta_1; \delta_2, s) \rightarrow (\delta_1'; \delta_2, s')}{(\delta_1, s) \rightarrow (\delta_1', s')}$$

$$\frac{(\delta_1;\delta_2,s)\to(\delta_2',s')}{(\delta_2,s)\to(\delta_2',s')}$$
 if  $(\delta_1,s)^{\sqrt{}}$ 

$$\frac{(if(phi)then\{\delta_1\}else\{\delta_2\},s)\to(\delta_1',s')}{(\delta_1,s)\to(\delta_1',s')}$$
 if  $s\models\phi$ 

$$\frac{(if(phi)then\{\delta_1\}else\{\delta_2\},s)\rightarrow(\delta_2',s')}{(\delta_2,s)\rightarrow(\delta_2',s')} \text{ if } s \not\models \phi$$

$$\tfrac{(while(\phi)do\{\delta\},s)\to (\delta';while(\phi)do\{\delta\},s')}{\delta,s)\to (\delta',s')}ifs\models\phi$$

#### 5.2 Termination Rules

 $\frac{(\epsilon,s)^{\checkmark}}{true}$ 

$$\frac{(\delta_1; \delta_2, s)^{\checkmark}}{(\delta_1, s)^{\checkmark} \wedge (\delta_2, s)^{\checkmark}}$$

$$\frac{(if(phi)then\{\delta_1\}else\{\delta_2\},s)^{\checkmark}}{(\delta_1,s)^{\checkmark}}$$

$$\frac{(if(phi)then\{\delta_1\}else\{\delta_2\},s)^{\checkmark}}{(\delta_2,s)^{\checkmark}}$$

$$\frac{(while(\phi)do\{\delta\},s)^{\checkmark}}{true}, ifs \models \neg \phi$$

$$\frac{(while(\phi)do\{\delta\},s)^{\checkmark}}{(\delta,s)^{\checkmark}}, ifs \models \phi$$

## 6 Hoare Logic

 $P \Rightarrow I$ 

$$(\neg g \land I) \Rightarrow Q$$

$$\{g \wedge I\}S\{I\}$$
: find wp of S and check if  $(g \wedge I) \Rightarrow wp$ 

 $\land$ 

## CTL TO $\mu$ -CALC

```
EXp :< -> p
AXp:[-]p
EFp: \mu X.p \lor <-> X
AFp: \mu X.p \vee [-]X
pEUq: \mu X.q \lor p \land <->q
pAUq: \mu X.q \lor p \land [-]q
EGp: \nu X.p \land <-> X
AGp: \nu X.p \wedge [-]X
```

#### Conjunctive Queries 8

```
Algorithm 1: Canonical Interpretation
  Input: q: conj query
1 \Delta^{I_q} = all constant and variable of q;
2 P^{I_q} = (t_1, ..., t_n), ... for all P_i(t_1, ..., t_n) in q;
```

 $c^{I_q} = c c is in q$ ;

## **Algorithm 2:** $I \models q \ (\exists h(I_q) = I)$

Input: q: conj query I: interpretation (DB) 1 write q in canonical Interp.;

**2** find assignment  $\alpha(.)$  for each variable in q;

**3** assign to each constant itself:  $\alpha(c) = c$ ;

**4 return**  $\alpha$  as the homomorphism between I and  $I_q$ if exist or  $I \not\models q$ ;

```
Algorithm 3: q_1 \subseteq q_2
```

```
q_2: conj query
  show q_1 \subseteq q_2 i.e. q_2 \Rightarrow q_1
1 begin containement
       freeze all variable by assigning a constant:
```

**Input:**  $q_1$ : conj query

assume  $q_1(x,y) \leftarrow e(x,y,z)...$  you must freeze only the one in the argument  $q_1(c_1, c_2) \leftarrow e(c_1, c_2, z) \dots ;$ 3

check if db tables of  $I_{q_1}$  are true in  $q_2$ : find an assignment to  $q_2$  variables that makes  $I_{q_1} \models q_2$  by guessing;

5 end

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6 begin homomorphism

```
/* To verify the homomorphism check
             I_{q_1} \models q_2 \text{ iff } \exists h.I_{q_2} \Rightarrow I_{q_1}
        compute I_{q_2} as interpretation of q_2;
        compute mapping from object oI_{q_2} to \delta^{I_{q_1}};
        check if mapping holds also for tuples;
10 end
```

#### 9 **Bisimilarity**

A state  $s_0$  of transition system S is bisimilar, or simply equivalent, to a state  $t_0$  of transition system T iff there

#### **Algorithm 4:** Check if incomplete db $\models q$

Input: q: conj query Incomplete DB

- 1 transform DB into  $q_D$  where each null become an existentially quantified variable;
- **2** DB $\models q$  iff  $q_D \subseteq q$  (see containment algorithm);

exists a bisimulation between the initial states  $s_0$  and  $t_0$ (note: bisimilarity the largest bisimulation).

A binary relation R is a bisimulation if  $(s,t) \in R$ implies that s is final iff t is final and for all action a if  $s \to_a s'$  then  $\exists t'.t \to_a t'$  and  $(s',t') \in R$  if  $t \to_a t'$  then  $\exists s'.s \rightarrow_a s' and(s',t') \in R$ 

# Algorithm 5: Check Bisimulation between T

Input: T, S

- 1 Compute  $R = T \times S$ ;
- 2 remove from R all tuples (s,t) where s is final and t is not and vice versa;
- **3** remove from R all tuples (s,t) where s can do  $a_i$ and t cannot (and vice versa);
- 4 remove from R all tuples  $(s_i, t_i)$  that can reach (s',t') but then (s',t') is not in R;
- 5 return R;