Formal Methods Formulas and Algorithm

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1 Introduciton

this document is a collection of formulas to use during formal methods exercises. The .tex file is available to make it always richer, bigger and better.

2 FOL

 α -rules:

$$\begin{array}{cccc} \frac{\phi \wedge \psi}{\phi} & \frac{\neg(\phi \vee \psi)}{\neg \phi} & \frac{\neg(\phi \supset \psi)}{\phi} & \frac{\neg \neg \phi}{\phi} \\ \psi & \neg \psi & \neg \psi & \end{array}$$

 β -rules:

$$\frac{\phi \vee \psi}{\phi | \psi} \ \frac{\neg (\phi \land \psi)}{\neg \phi | \neg \psi} \ \frac{\phi \supset \psi}{\neg \phi | \psi}$$

extra-rules:

$$\frac{\neg \phi}{X} \quad \frac{\phi \equiv \psi)}{\phi \mid \neg \phi} \quad \frac{\neg (\phi \equiv \psi)}{\neg \phi \mid \phi} \\
\psi \mid \neg \psi \quad \psi \mid \neg \psi$$

 δ -rules:

$$\frac{\forall x.\phi(x)}{\phi(t)} \ \frac{\neg \exists x.\phi(x)}{\neg \phi(t)}$$

 γ -rules:

$$\frac{\neg \forall x. \phi(x)}{\neg \phi(c)} \quad \frac{\exists x. \phi(x)}{\phi(c)}$$

Tableaux:

prove $\phi \equiv \psi$: check $\neg(\phi \equiv \psi)$ is UNSAT

 ϕ is valid: $\neg \phi$ is UNSAT

 $\Gamma \models \phi$: check $\Gamma \cup \neg \phi$ closes (UNSAT)

 Γ SAT: check for an open branch of Γ

In general each existential is a fresh new constant while universal can be any term also the constant of the existential. To clash instantiate existential and then use universal to make the clash.

3 UML TO FOL

a is the attribute name, A the association name, C is the class name, T is the type name, i and j the multiplicities, P is type name for parameter, R is type name for return value. Class:

 $\forall x, y. a(x, y) \supset C(x) \land T(y)$ $\forall x. C(x) \supset i \le \{y | a(x, y)\} \le j$

Association:

$$\forall x_1, ..., x_n. A(x_1, ..., x_n) \supset C(x_1) \land ... C(x_n)$$

$$\forall x_1. C(x_1) \supset i \leq \{x2 | a(x_1, x_2, ...)\} \leq j$$

$$\forall x_2. C(x_2) \supset i \leq \{x1 | a(x_1, x_2, ...)\} \leq j$$

Generalization:

$$\forall x. C_i(x) \supset C(x) for i = 1, ..., n \text{ (is-a)}$$

$$\forall x. C_i(x) \supset \neg C_j(x) for i \neq j \text{ (disjoint)}$$

$$\forall x. C(x) \supset C_1 \vee ... \vee C_i(x) ... \vee C_n(x) \text{ (completeness)}$$

Subset:

 $\forall x, y.assoc_1(x, y) \supset assoc_2(x, y)$ can refine mult.

Association Class:

$$\begin{split} \forall x,y,z. & a(x,y,z) \supset A(x,y) \land T(z) \\ \forall x,y & A(x,y) \supset \forall z. i \leq \{z | a(x,y,z)\} \leq j \text{ + assoc mult.} \end{split}$$

Reification (when assoc is a class+key constr):

 $\forall x, yr_i(x, y) \supset A(x) \land C_i(y) for i = 1, ..., n$

 $\forall x A(x) \supset \exists y . r_i(x, y) fori = 1, ..., n$

 $\forall x, y, y'r_i(x, y) \land r_i(x, y') \supset y = y'fori = 1, ..., n$

 $\forall y_1, ..., y_n, x, x' . \wedge_{i=1}^n r_i(x, y_i) \wedge r_i(x', y_i) \supset x = x'$

Methods:

$$\forall x, p_1, ..., p_m, r. f_{C, P_1, ..., P_m}(x, p_1, ..., p_m, r) \supset C(x)$$
$$(\wedge_{i=i}^m P_i(p_i)) \wedge R(r)$$

$$\forall x, p_1, ..., p_m, r, r'. f_{C, P_1, ..., P_m}(x, p_1, ..., p_m, r)$$
$$f_{C, P_1, ..., P_m}(x, p_1, ..., p_m, r') \supset r = r'$$

Λ

4 Evaluation Semantic

$$\frac{(a,s) \rightarrow s'}{true}$$
 if $s \models Pre(a) \land s' \models Post(a,s)$

 $\frac{(skip,s)\rightarrow s}{true}$

$$\frac{(\delta_1; \delta_2, s_0) \rightarrow s_f}{(\delta_1, s_0) \rightarrow s_1 \land (\delta_2, s_1) \rightarrow s_f}$$

$$\frac{(if(\phi)then\{\delta_1\}else\{\delta_2\},s) \rightarrow s'}{(\delta_1,s) -> s'}, s \models \phi$$

$$\frac{(if(\phi)then\{\delta_1\}else\{\delta_2\},s) \rightarrow s'}{(\delta_2,s) -> s'}, s \not\models \phi$$

$$\tfrac{(while(\phi)do\{\delta\},s)\to s'}{(\delta,s)\to s''\wedge (while\phi do\{\delta\},s'')\to s'},s\models\phi$$

$$\frac{(while(\phi)do\{\delta\},s)\rightarrow s'}{true},s \not\models \phi$$

5 Transition Semantic

5.1 Transition Rules

 $\frac{(a,s) \rightarrow (\epsilon,s')}{true} \text{ if } s \models Pre(a) \land s' \models Post(a,s)$

$$\frac{(skip,s) \rightarrow (\epsilon,s')}{true}$$

$$\frac{(\delta_1; \delta_2, s) \rightarrow (\delta_1'; \delta_2, s')}{(\delta_1, s) \rightarrow (\delta_1', s')}$$

$$\frac{(\delta_1;\delta_2,s)\to(\delta_2',s')}{(\delta_2,s)\to(\delta_2',s')}$$
 if $(\delta_1,s)^{\sqrt{}}$

$$\frac{(if(phi)then\{\delta_1\}else\{\delta_2\},s)\to(\delta_1',s')}{(\delta_1,s)\to(\delta_1',s')}$$
 if $s\models\phi$

$$\frac{(if(phi)then\{\delta_1\}else\{\delta_2\},s)\rightarrow(\delta_2',s')}{(\delta_2,s)\rightarrow(\delta_2',s')} \text{ if } s \not\models \phi$$

$$\tfrac{(while(\phi)do\{\delta\},s)\to (\delta';while(\phi)do\{\delta\},s')}{\delta,s)\to (\delta',s')}ifs\models\phi$$

5.2 Termination Rules

 $\frac{(\epsilon,s)^{\checkmark}}{true}$

$$\frac{(\delta_1; \delta_2, s)^{\checkmark}}{(\delta_1, s)^{\checkmark} \wedge (\delta_2, s)^{\checkmark}}$$

$$\frac{(if(phi)then\{\delta_1\}else\{\delta_2\},s)^{\checkmark}}{(\delta_1,s)^{\checkmark}}$$

$$\frac{(if(phi)then\{\delta_1\}else\{\delta_2\},s)^{\checkmark}}{(\delta_2,s)^{\checkmark}}$$

$$\frac{(while(\phi)do\{\delta\},s)^{\checkmark}}{true}, ifs \models \neg \phi$$

$$\frac{(while(\phi)do\{\delta\},s)^{\checkmark}}{(\delta,s)^{\checkmark}}, ifs \models \phi$$

6 Hoare Logic

 $P \Rightarrow I$

$$(\neg g \land I) \Rightarrow Q$$

$$\{g \wedge I\}S\{I\}$$
: find wp of S and check if $(g \wedge I) \Rightarrow wp$

 \land

7 CTL TO μ -CALC

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\begin{split} EXp : &< - > p \\ AXp : [-]p \\ EFp : &\mu X.p \lor < - > X \\ AFp : &\mu X.p \lor [-]X \\ pEUq : &\mu X.q \lor p \land < - > X \\ pAUq : &\mu X.q \lor p \land [-]X \\ EGp : &\nu X.p \land < - > X \\ AGp : &\nu X.p \land [-]X \end{split}
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8 Conjunctive Queries

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Algorithm 1: Canonical Interpretation

Input: q: conj query

1 \Delta^{I_q} = all constant and variable of q;

2 P^{I_q} = (t_1, ..., t_n), ...for all P_i(t_1, ..., t_n) in q;

3 c^{I_q} = c c is in q;
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Algorithm 2: $I \models q \ (\exists h(I_q) = I)$

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Input: q: conj queryI: interpretation (DB)write q in canonical Interp.;
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2 find assignment $\alpha(.)$ for each variable in q;

3 assign to each constant itself: $\alpha(c) = c$;

4 return α as the homomorphism between I and I_q if exist or $I \not\models q$;

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Algorithm 3: q_1 \subseteq q_2
  Input: q_1: conj query
  q_2: conj query
  show q_1 \subseteq q_2 i.e. q_2 \Rightarrow q_1
1 begin containement
       freeze all variable by assigning a constant:
        assume q_1(x,y) \leftarrow e(x,y,z)... you must freeze
        only the one in the argument
        q_1(c_1, c_2) \leftarrow e(c_1, c_2, z)...;
3
       check if db tables of I_{q_1} are true in q_2: find an
        assignment to q_2 variables that makes
        I_{q_1} \models q_2 by guessing;
5 end
6 begin homomorphism
       /* To verify the homomorphism check
           I_{q_1} \models q_2 \text{ iff } \exists h.I_{q_2} \Rightarrow I_{q_1}
       compute I_{q_2} as interpretation of q_2;
7
```

9 Bisimilarity

10 end

A state s_0 of transition system S is bisimilar, or simply equivalent, to a state t_0 of transition system T iff there

compute mapping from object o I_{q_2} to $\delta^{I_{q_1}}$; check if mapping holds also for tuples;

Algorithm 4: Check if incomplete db $\models q$

Input: q: conj query Incomplete DB

1 transform DB into q_D where each null become an existentially quantified variable;
2 DB = q iff q_D ⊆ q (see containment algorithm);

exists a bisimulation between the initial states s_0 and t_0 (note: bisimilarity the largest bisimulation).

A binary relation R is a bisimulation if $(s,t) \in R$ implies that s is final iff t is final and for all action a if $s \to_a s'$ then $\exists t'.t \to_a t' and(s',t') \in R$ if $t \to_a t'$ then $\exists s'.s \to_a s' and(s',t') \in R$

Algorithm 5: Check Bisimulation between T and S

Input: T, S

- 1 Compute $R = T \times S$;
- 2 remove from R all tuples (s,t) where s is final and t is not and vice versa;
- **3** remove from R all tuples (s,t) where s can do a_i and t cannot (and vice versa);
- 4 remove from R all tuples (s_i, t_j) that can reach (s',t') but then (s',t') is not in R;
- 5 return R;