

University of Rome “La Sapienza”

Master in Artificial Intelligence and Robotics

Machine Learning

A.Y. 2018/2019

Prof. Luca Iocchi

Sapienza University of Rome, Italy
Master in Artificial Intelligence and Robotics
Machine Learning (2018/19)

17. Dimensionality reduction

Luca Iocchi

Overview

- Continuous latent variables
- Principal Component Analysis (PCA)
- Probabilistic PCA
- Non-linear latent variable models
- Autoencoders

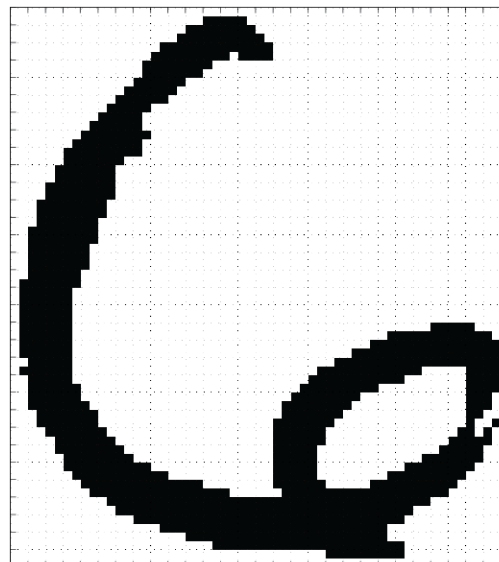
Reference

C. Bishop. Pattern Recognition and Machine Learning. Chapter 12.

Latent Variables

Example

USPS dataset: 64 rows by 57 columns



Latent Variables

Data space contains more than just digits



Latent Variables

Data space contains more than just digits



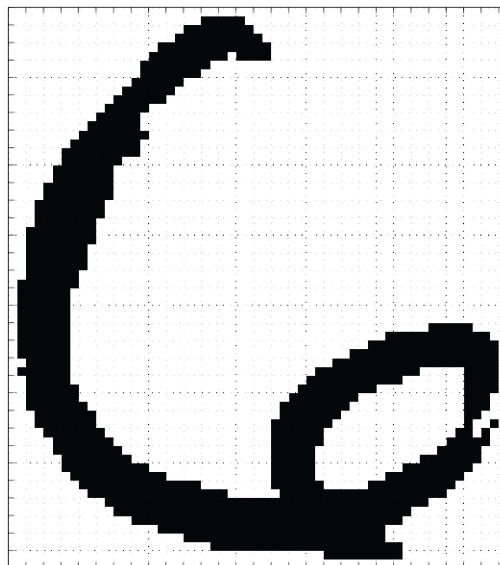
Latent Variables

Data space contains more than just digits



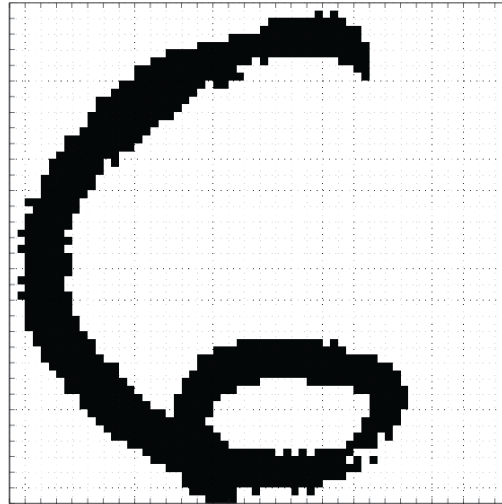
Latent Variables

Prototype rotation (1 dof transformation)



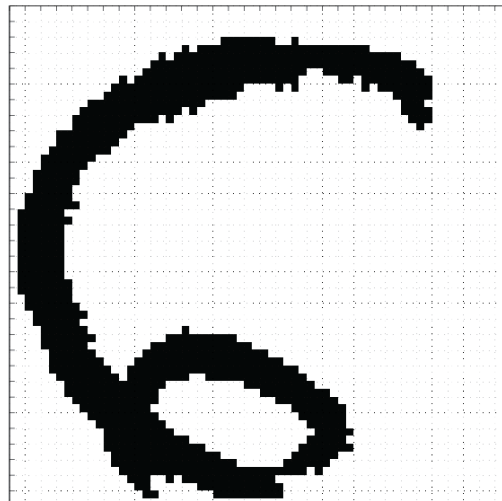
Latent Variables

Prototype rotation (1 dof transformation)



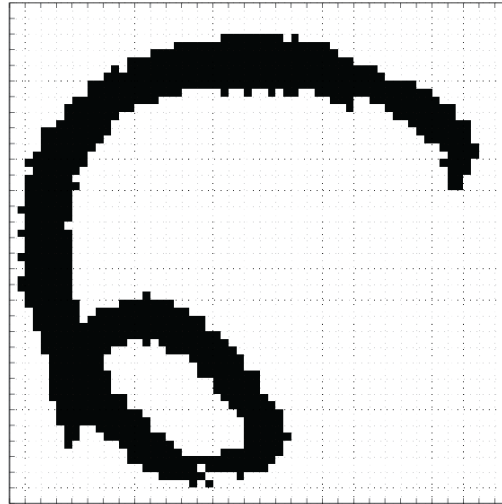
Latent Variables

Prototype rotation (1 dof transformation)



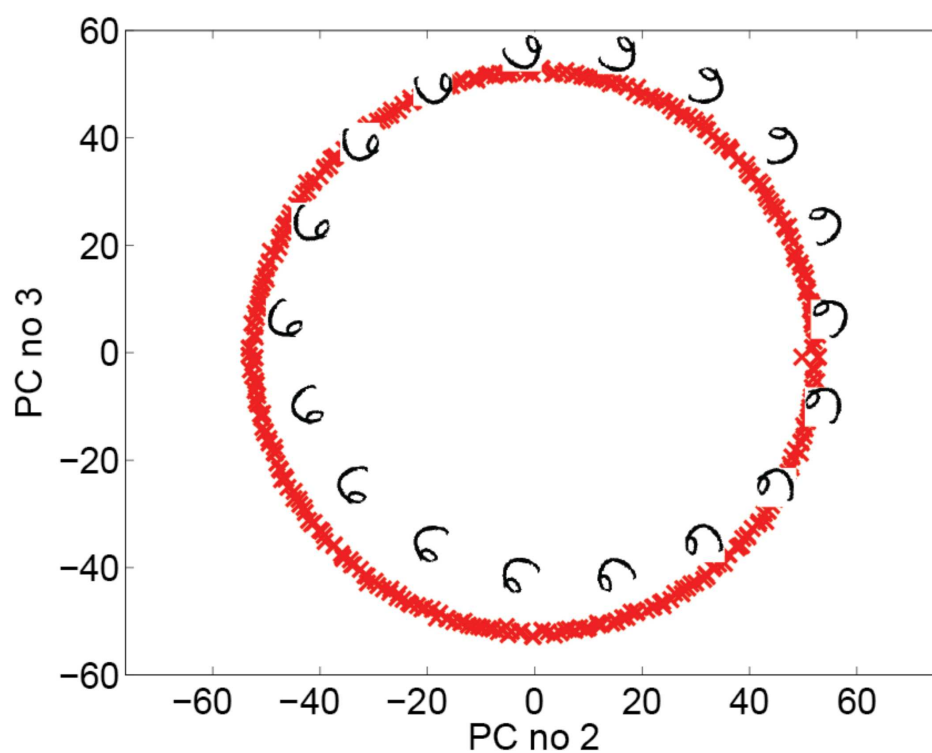
Latent Variables

Prototype rotation (1 dof transformation)



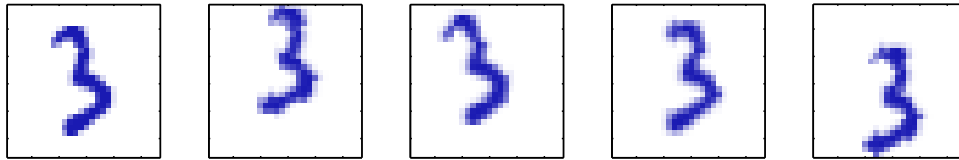
Latent Variables

Manifold



Latent Variables

Another example



3 degrees of freedom transformation (2D translation + rotation)

Latent Variables

For data with ‘structure’*

- We expect fewer distortions than dimensions
- data live on a lower dimensional manifold

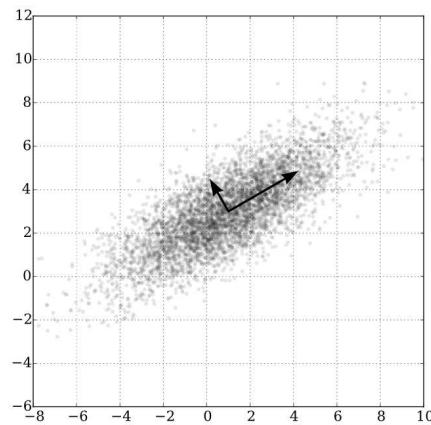
Conclusion: deal with high dimensional data by looking for lower dimensional embedding

*from Raquel Urtasun’s slides

Principal Component Analysis

Principal Component Analysis (PCA) is a widely used technique for various tasks as

- dimensionality reduction
- data compression (lossy)
- data visualization
- feature extraction



PCA - Variance Maximization

Given data $\{\mathbf{x}_n\} \in \mathbb{R}^D$

Goal: Maximize data variance after projection to some direction \mathbf{u}_1

Projected points:

$$\mathbf{u}_1^T \mathbf{x}_n$$

Note: $\mathbf{u}_1^T \mathbf{u}_1 = 1$

PCA - Variance Maximization

Mean value of data points:

$$\bar{\mathbf{x}} = \frac{1}{N} \sum_{n=1}^N \mathbf{x}_n$$

Mean of projected points:

$$\mathbf{u}_1^T \bar{\mathbf{x}}$$

Variance of projected points:

$$\frac{1}{N} \sum_{n=1}^N [\mathbf{u}_1^T \mathbf{x}_n - \mathbf{u}_1^T \bar{\mathbf{x}}]^2 = \mathbf{u}_1^T S \mathbf{u}_1$$

with

$$S = \frac{1}{N} \sum_{n=1}^N (\mathbf{x}_n - \bar{\mathbf{x}})(\mathbf{x}_n - \bar{\mathbf{x}})^T$$

PCA - Variance Maximization

Problem definition

Maximize the projected variance

$$\max_{\mathbf{u}_1} \mathbf{u}_1^T S \mathbf{u}_1$$

subject to constraint $\mathbf{u}_1^T \mathbf{u}_1 = 1$

Equivalent to unconstrained maximization with a Lagrange multiplier

$$\max_{\mathbf{u}_1} \mathbf{u}_1^T S \mathbf{u}_1 + \lambda_1 (1 - \mathbf{u}_1^T \mathbf{u}_1)$$

PCA - Variance Maximization

Solution

Setting derivative w.r.t. \mathbf{u}_1 to zero we have

$$S\mathbf{u}_1 = \lambda_1\mathbf{u}_1$$

\mathbf{u}_1 must be an eigenvector of S

Left-multiplying by \mathbf{u}_1^T and using $\mathbf{u}_1^T\mathbf{u}_1 = 1$, we have

$$\mathbf{u}_1^T S\mathbf{u}_1 = \lambda_1$$

which is the variance after the projection.

PCA - Variance Maximization

Solution

$$\mathbf{u}_1^T S\mathbf{u}_1 = \lambda_1$$

Variance is maximal when \mathbf{u}_1 is the eigenvector corresponding to the largest eigenvalue λ_1 .

This is called the first **principal component**.

PCA - Variance Maximization

Repeat to find other directions which

- maximize variance of projected data
- are orthogonal to the previous directions

Summary:

To perform PCA in a M -dimensional projection space, with $M < D$

- compute $\bar{\mathbf{x}}$: mean of the data
- compute S : covariance matrix of the dataset
- find M eigenvectors of S corresponding to the M largest eigenvalues

PCA - Error minimization

Consider a complete orthonormal D -dimensional basis such that

$$\mathbf{u}_i^T \mathbf{u}_j = \delta_{ij}$$

$$\text{with } \delta_{ij} = \begin{cases} 1 & \text{if } i = j \\ 0 & \text{otherwise} \end{cases}$$

Each data point can be written as

$$\mathbf{x}_n = \sum_{i=1}^D \alpha_{ni} \mathbf{u}_i$$

Using the orthonormality property we have $\alpha_{nj} = \mathbf{x}_n^T \mathbf{u}_j$, hence

$$\mathbf{x}_n = \sum_{i=1}^D (\mathbf{x}_n^T \mathbf{u}_i) \mathbf{u}_i$$

PCA - Error minimization

Goal: Approximate \mathbf{x}_n using a lower-dimensional representation.

We can write

$$\tilde{\mathbf{x}}_n = \sum_{i=1}^M z_{ni} \mathbf{u}_i + \sum_{i=M+1}^D b_i \mathbf{u}_i$$

Evaluate approximation error as

$$J = \frac{1}{N} \sum_{n=1}^N \|\mathbf{x}_n - \tilde{\mathbf{x}}_n\|^2$$

Minimize w.r.t. z_{nj} we get

$$z_{nj} = \mathbf{x}_n^T \mathbf{u}_j, \quad j = 1, \dots, M$$

Minimize w.r.t. b_j we get

$$b_j = \bar{\mathbf{x}}^T \mathbf{u}_j, \quad j = M + 1, \dots, D$$

PCA - Error minimization

Using these expression we get

$$\mathbf{x}_n - \tilde{\mathbf{x}}_n = \sum_{i=M+1}^D [(\mathbf{x}_n - \bar{\mathbf{x}})^T \mathbf{u}_i] \mathbf{u}_i$$

Hence, the residual lies in the space orthogonal to the principal subspace.

The overall approximation error becomes

$$J = \frac{1}{N} \sum_{n=1}^N \sum_{i=M+1}^D (\mathbf{x}_n^T \mathbf{u}_i - \bar{\mathbf{x}}^T \mathbf{u}_i)^2 = \sum_{i=M+1}^D \mathbf{u}_i^T S \mathbf{u}_i$$

PCA - Error minimization

Minimize the approximation error subject to constraint $\mathbf{u}_i^T \mathbf{u}_i = 1$:

$$\tilde{J} = \sum_{i=M+1}^D \mathbf{u}_i^T S \mathbf{u}_i + \lambda_i (1 - \mathbf{u}_i^T \mathbf{u}_i)$$

Setting derivative of a \mathbf{u}_i to zero we have:

$$S \mathbf{u}_i = \lambda_i \mathbf{u}_i$$

Hence \mathbf{u}_i is an eigenvector of S with eigenvalue λ_i .

PCA - Error minimization

The approximation error is then given by

$$J = \sum_{i=M+1}^D \lambda_i$$

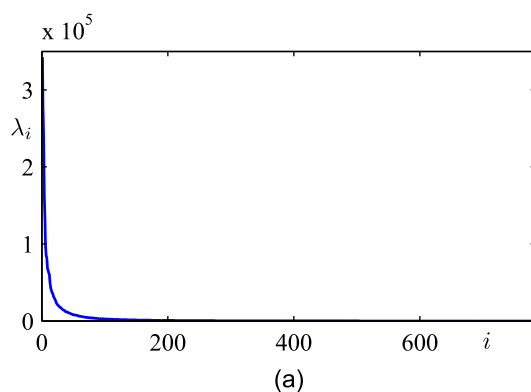
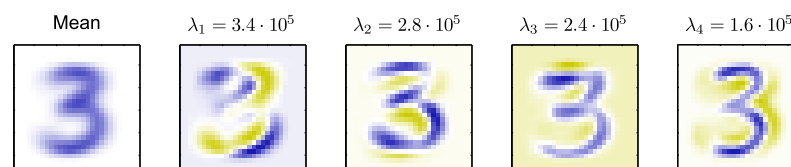
This is minimized by selecting \mathbf{u}_i as the eigenvectors corresponding to the $D - M$ smallest eigenvalues.

Note: Choosing $D - M$ smallest eigenvalues of S corresponds to finding M highest eigenvalues of S as in the maximum variance formulation.

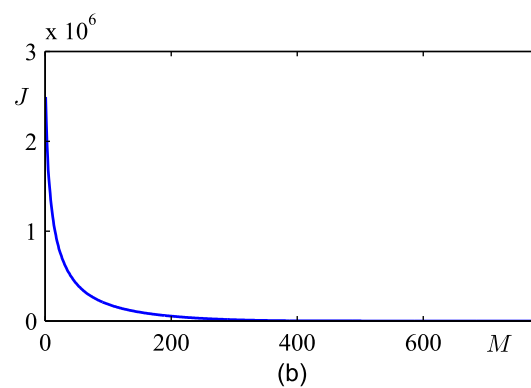
PCA - Algorithms

- ① Full eigenvalue decomposition of S (slow)
- ② Efficient eigenvalue decomposition - only M eigenvectors
- ③ Singular value decomposition of centered data matrix \mathbf{X}

PCA - Example



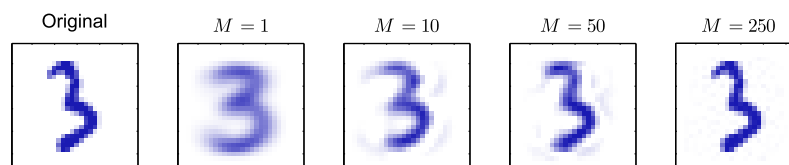
Eigenvalue spectrum



Sum of discarded eigenvalues (error)

PCA - Example

Reconstruction with a limited number of components



PCA for high-dimensional data

What if number of points is smaller than the dimensionality, i.e. $N < D$?
At least $D-N+1$ eigenvalues are zero.

Example: small set of high-resolution images.

In this case finding eigenvalues of S ($D \times D$ matrix) is inefficient.

PCA for high-dimensional data

Solution for $N < D$:

Define \mathbf{X} as the $N \times D$ centered data matrix whose n -th row is $(\mathbf{x}_n - \bar{\mathbf{x}})^T$

The covariance matrix can be written as

$$S = \frac{1}{N} \mathbf{X}^T \mathbf{X}$$

The corresponding eigenvector equations is

$$\frac{1}{N} \mathbf{X}^T \mathbf{X} \mathbf{u}_i = \lambda_i \mathbf{u}_i$$

PCA for high-dimensional data

By left-multiplying by \mathbf{X} we obtain

$$\frac{1}{N} \mathbf{X} \mathbf{X}^T (\mathbf{X} \mathbf{u}_i) = \lambda_i (\mathbf{X} \mathbf{u}_i)$$

By defining $\mathbf{v}_i = \mathbf{X} \mathbf{u}_i$ we have

$$\frac{1}{N} \mathbf{X} \mathbf{X}^T \mathbf{v}_i = \lambda_i \mathbf{v}_i$$

$\mathbf{X} \mathbf{X}^T$ has the same $N - 1$ eigenvalues of $\mathbf{X}^T \mathbf{X}$ (the others are 0).

$\mathbf{X} \mathbf{X}^T$ is an $N \times N$ matrix whose eigenvalues can be computed efficiently.

PCA for high-dimensional data

Given the eigenvalues λ_i of $\mathbf{X}\mathbf{X}^T$, to find the eigenvectors we left-multiply by \mathbf{X}^T

$$\left(\frac{1}{N}\mathbf{X}^T\mathbf{X}\right)(\mathbf{X}^T\mathbf{v}_i) = \lambda_i(\mathbf{X}^T\mathbf{v}_i)$$

This makes clear that $(\mathbf{X}^T\mathbf{v}_i)$ is an eigenvector of S with eigenvalue λ_i .

To find \mathbf{u}_i we have to normalize these eigenvectors such that $\mathbf{u}_i^T\mathbf{u}_i = 1$

$$\mathbf{u}_i = \frac{1}{\sqrt{N\lambda_i}}\mathbf{X}^T\mathbf{v}_i$$

Probabilistic PCA

Linear Latent Variable Model

- Represent data \mathbf{x} with lower dimensional latent variables \mathbf{z}
- Assume linear relationship

$$\mathbf{x} = \mathbf{W}\mathbf{z} + \boldsymbol{\mu}$$

- Assume Gaussian distribution of latent variables \mathbf{z}

$$P(\mathbf{z}) = \mathcal{N}(\mathbf{z}; \mathbf{0}, \mathbf{I})$$

- Assume Linear-Gaussian relationship between latent variables and data

$$P(\mathbf{x}|\mathbf{z}) = \mathcal{N}(\mathbf{x}; \mathbf{W}\mathbf{z} + \boldsymbol{\mu}, \sigma^2\mathbf{I})$$

Probabilistic PCA

Marginal distribution

$$P(\mathbf{x}) = \int P(\mathbf{x}|\mathbf{z})P(\mathbf{z})d\mathbf{z} = \mathcal{N}(\mathbf{x}; \boldsymbol{\mu}, \mathbf{C})$$

with

$$\mathbf{C} = \mathbf{W}\mathbf{W}^T + \sigma^2\mathbf{I}$$

Posterior distribution

$$P(\mathbf{z}|\mathbf{x}) = \mathcal{N}(\mathbf{z}; \mathbf{M}^{-1}\mathbf{W}^T(\mathbf{x} - \boldsymbol{\mu}), \sigma^2\mathbf{M})$$

with

$$\mathbf{M} = \mathbf{W}^T\mathbf{W} + \sigma^2\mathbf{I}$$

Maximum likelihood PCA

Maximum likelihood: given data \mathbf{X}

$$\operatorname{argmax}_{\mathbf{W}, \boldsymbol{\mu}, \sigma} \ln P(\mathbf{X}|\mathbf{W}, \boldsymbol{\mu}, \sigma^2) = \sum_{n=1}^N \ln P(\mathbf{x}_n|\mathbf{W}, \boldsymbol{\mu}, \sigma^2)$$

Setting derivatives to 0, we have a closed form solution

$$\boldsymbol{\mu}_{ML} = \bar{\mathbf{x}} = \frac{1}{N} \sum_{n=1}^N \mathbf{x}_n$$

$$\mathbf{W}_{ML} = \dots$$

$$\sigma_{ML}^2 = \dots$$

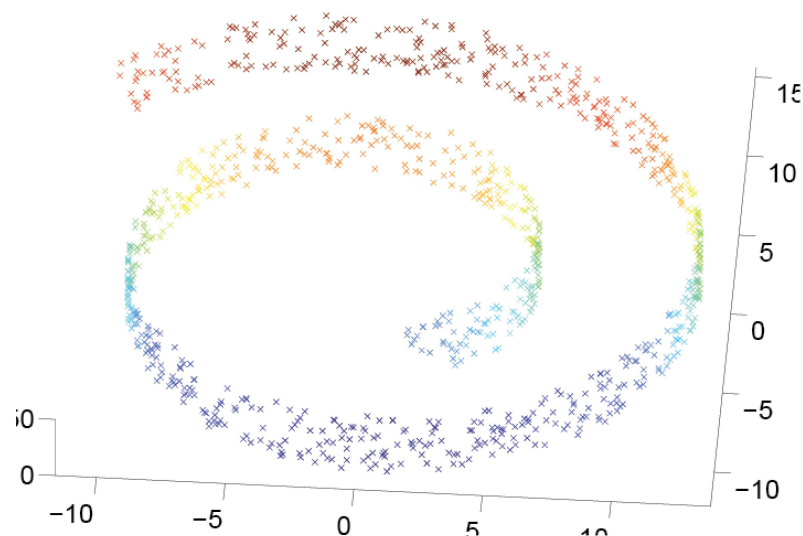
\mathbf{W} depends on the eigenvalues and eigenvectors of S (not trivial proof)

Maximum likelihood PCA

Maximum likelihood solution for the probabilistic PCA model can be obtained also with EM algorithm.

Non-Linear Latent Variable Models

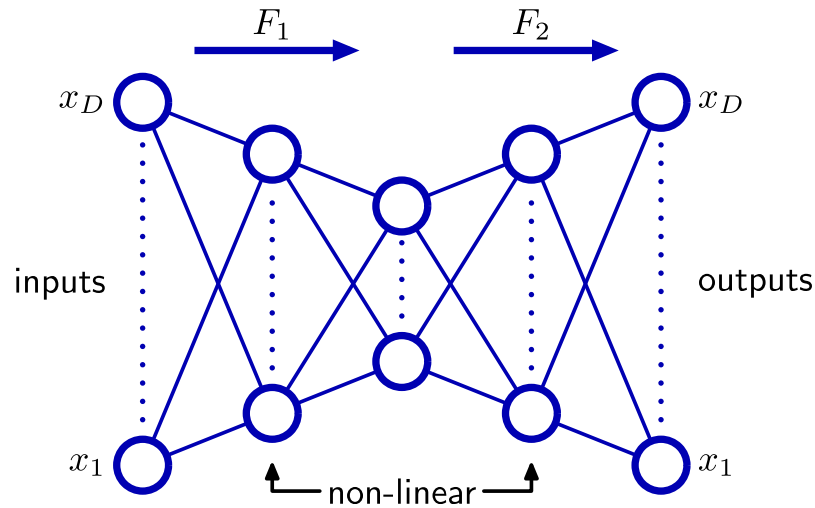
Motivation: Linear representations are not sufficient for complex data



The 'Swiss Roll' dataset. Two dimensional manifold embedded in 3D space.

Autoassociative Neural Networks (Autoencoders)

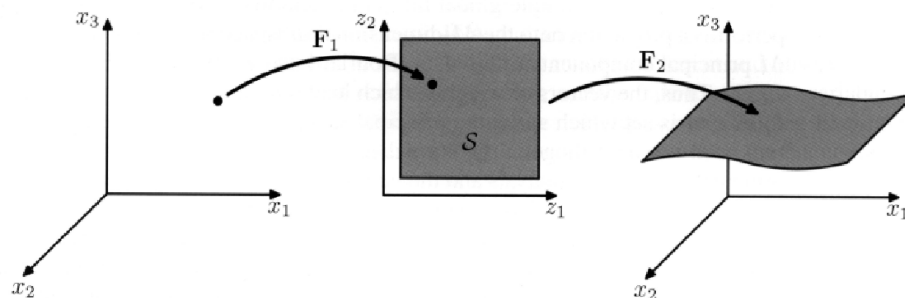
Neural networks with reduced sized hidden layers (bottleneck) which learn to reconstruct their input by minimizing a sum-of-squares error .



Autoencoders

Autoencoder example:

Input: 3-D, Hidden layer: 2-D, Output: 3-D



Non-linear PCA

Summary

- Dimensionality reduction aims at identifying the “real” degrees of freedom of a data set
- Analysis of latent variables helps in understanding the variability of the input data
- Deep associative neural networks provide a general tool for non-linear PCA