```
rule[LU|RD|RI] = RU|LD|RI;
rule[LU|LE|RD] = RU|LE|LD;
rule[RU|LE|LD] = LU|LE|RD;
// two-particle cyclic rules
rule[LE|RI] = RU|LD;
rule[RU|LD] = LU|RD;
rule[LU|RD] = LE|RI;
// four-particle cyclic rules
rule[RU|LU|LD|RD] = RU|LE|LD|RI;
rule[RU|LE|LD|RI] = LU|LE|RD|RI;
rule[LU|LE|RD|RI] = RU|LU|LD|RD;
// stationary particle creation rules
rule[LU|RI] = RU|S;
rule[RU|LE] = LU|S;
rule[LU|LD] = LE|S;
rule[LE|RD] = LD|S;
rule[LD|RI] = RD|S;
rule[RD|RU] = RI|S;
rule[LU|LE|LD|RD|RI] = RU|LE|LD|RD|S;
rule[RU|LE|LD|RD|RI] = LU|LD|RD|RI|S;
rule[RU|LU|LD|RD|RI] = RU|LE|RD|RI|S;
rule[RU|LU|LE|RD|RI] = RU|LU|LD|RI|S;
rule[RU|LU|LE|LD|RI] = RU|LU|LE|RD|S;
rule[RU|LU|LE|LD|RD] = LU|LE|LD|RI|S;
// add all rules indexed with a stationary particle (dual rules)
for(int i = 0;i<S;i++) {
   // ^ is the exclusive or operator
   rule[i^(RU|LU|LE|LD|RD|RI|S)] = rule[i]^(RU|LU|LE|LD|RD|RI|S);
}
// add rules to bounce back at barriers
for(int i = BARRIER;i<NUM_RULES;i++) {
   int highBits = i&(LE|LU|RU); // & is bitwise and operator
   int lowBits = i&(RI|RD|LD);
   rule[i] = BARRIER|(highBits>>3)|(lowBits<<3);
}
}
static { // set average site velocities
   // for every particle site configuration i, calculate total net
   // velocity and place in vx[i], vy[i]
   vx = new double[NUM_RULES];
   vy = new double[NUM_RULES];
   for(int i = 0;i<NUM_RULES;i++) {
      for(int dir = 0;dir<NUM_CHANNELS;dir++) {
         if((i&(1<<dir))!=0) {
            vx[i] += ux[dir];
            vy[i] += uy[dir];
         }
      }
   }
}
public void initialize(int Lx, int Ly, double density) {
   this.Lx = Lx;
   this.Ly = Ly-Ly%2;                                    // Ly must be even
   // approximate total number of particles
   numParticles = Lx*Ly*NUM_CHANNELS*density;
   // density = particles divided by maximum number possible
```



```
   lattice = new int[Lx][Ly];
   newLattice = new int[Lx][Ly];
   int sevenParticleSite = ((1<<NUM_CHANNELS)-1); // equals 127
   for(int i = 0;i<Lx;i++) {
      // wall at top and bottom
      lattice[i][1] = lattice[i][Ly-2] = BARRIER;
      for(int j = 2;j<Ly-2;j++) {
         // occupy site by 0 or 7 particles, average occupation will
         // be approximately the density
         int siteValue =
               Math.random()<density ? sevenParticleSite : 0;
         lattice[i][j] = siteValue; // random particle configuration
      }
   }
   for(int j = 3*Ly/10;j<7*Ly/10;j++) {
      lattice[2*Lx/10][j] = BARRIER; // obstruction toward the left
   }
}

public void step() {
   // move all particles forward
   for(int i = 0;i<Lx;i++) {
      // define the columns of a 2D array
      int[] left = newLattice[(i-1+Lx)%Lx];
      // use abbreviations to align expressions
      int[] cent = newLattice[i];
      int[] rght = newLattice[(i+1)%Lx];
      for(int j = 1;j<Ly-2;j += 2) {
         // loop j in increments of 2 to decrease reads and writes
         // of neighbors
         int site1 = lattice[i][j];
         int site2 = lattice[i][j+1];
         // move all particles in site1 and site2 to their neighbors
         rght[j-1] |= site1&RIGHT_DOWN;
         cent[j-1] |= site1&LEFT_DOWN;
         rght[j] |= site1&RIGHT;
         cent[j] |= site1&(STATIONARY|BARRIER)|site2&RIGHT_DOWN;
         left[j] |= site1&LEFT|site2&LEFT_DOWN;
         rght[j+1] |= site1&RIGHT_UP|site2&RIGHT;
         cent[j+1] |= site1&LEFT_UP|site2&(STATIONARY|BARRIER);
         left[j+1] |= site2&LEFT;
         cent[j+2] |= site2&RIGHT_UP;
         left[j+2] |= site2&LEFT_UP;
      }
   } // handle collisions, find average x velocity
   double vxTotal = 0;
   for(int i = 0;i<Lx;i++) {
      for(int j = 0;j<Ly;j++) {
         int site = rule[newLattice[i][j]]; // use collision rule
         lattice[i][j] = site;
         // reset newLattice values to 0
         newLattice[i][j] = 0;
         vxTotal += vx[site];
      }
   }
   int scale = 4;
```