

Lecture January 14

$$E[H] = \langle H \rangle = \frac{\int d\vec{r} \psi_T^*(\vec{r}) \hat{H} \psi_T(\vec{r})}{\int d\vec{r} \psi_T^*(\vec{r}) \psi_T(\vec{r})}$$

$$\vec{r} = (\vec{r}_1, \vec{r}_2, \vec{r}_3, \dots, \vec{r}_N)$$
$$d\vec{r} = d\vec{r}_1, d\vec{r}_2, \dots, d\vec{r}_N$$

TRUE ground state E_0
variational principle

$$\begin{cases} \hat{H} \psi_0(\vec{r}) = E_0 \psi_0(\vec{r}) \\ \psi_T(\vec{r}) \neq \psi_0(\vec{r}) \\ \hat{H} \psi_T(\vec{r}) \neq \text{const} \times \psi_T(\vec{r}) \end{cases}$$
$$E_0 \leq E[H]$$

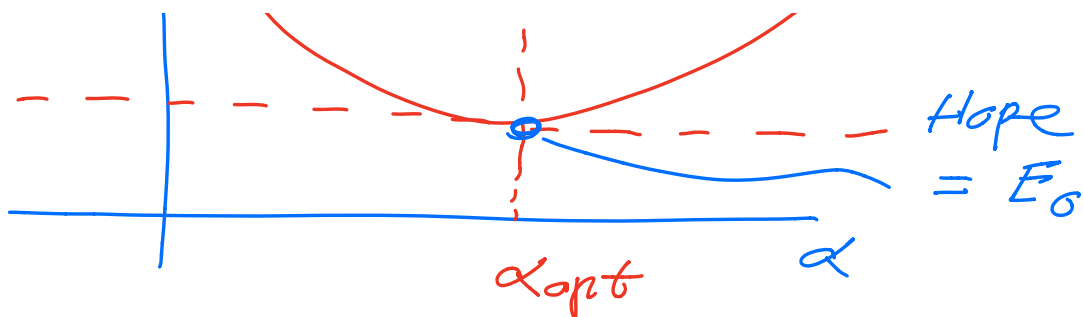
$$\psi_T(\vec{r}) \rightarrow \psi_T(\vec{r}; \vec{\alpha})$$

↑
variational
parameters

$$E[H] = E[H(\vec{\alpha})]$$

$$\vec{\alpha} = (\alpha_1, \alpha_2, \dots, \alpha_m)$$

$$E[H(\vec{\alpha})]$$



want

$$\frac{d \langle E[H(\alpha)] \rangle}{d\alpha} = 0$$

$$\psi_T(\vec{r}) = \psi_T = \psi_{\text{Exact}}$$

$$\hat{H} \psi_{\text{Exact}} = E_0 \psi_{\text{Exact}}$$

$$\langle E[H^2] \rangle = \int d\vec{r} \psi_{\text{Exact}}^* \underbrace{H^2 \psi_{\text{Exact}}}_{E_0^2 \psi_{\text{Exact}}}$$

$$\int d\vec{r} |\psi_{\text{Exact}}|^2 = \underline{1}$$

$$= E_0^2$$

$$\sigma_E = \text{var}[H] = \langle E[H^2] \rangle - (\langle E[H] \rangle)^2$$

$$= E_0^2 - E_0^2 \equiv 0 \quad \nabla$$

Expected values

$$\langle E[x^n] \rangle = \int dx \underline{p(x)} x^n$$

PDF
(Discrete version)
 $\sum_i x_i^n P(x_i)$

Define

QM-PDF

$$P(\vec{r}) = \frac{|\psi_T(\vec{r})|^2}{\int |\psi_T(\vec{r})|^2 d\vec{r}}$$

$$E_L(\vec{r}) = \frac{\hat{H} \psi_T(\vec{r})}{\psi_T(\vec{r})} = \frac{\hat{H} \psi_T}{\psi_T}$$

$$E[H] = \frac{\int d\vec{r} \psi_T^* \hat{H} \psi_T}{\int d\vec{r} |\psi_T|^2}$$

$$= \int d\vec{r} P(\vec{r}) E_L(\vec{r})$$

$$E[H(\vec{\alpha})] = \int d\vec{r} P(\vec{r}; \vec{\alpha}) E_L(\vec{r}; \vec{\alpha})$$

MCS $\rightarrow \dots$

$$\underline{\sim} \frac{1}{\underbrace{MCS}_{\text{Monte Carlo samples}}} \sum_{i=1} E_L(R_i; \alpha)$$

$$E_L(\vec{r}) = \frac{1}{\psi_T(\vec{r})} \hat{H} \psi_T(\vec{r})$$

1-particle, 1-Dim
 $\vec{r} \rightarrow x$

$$\underline{E_L(x)} = \frac{1}{\psi_T(x)} \left(\underbrace{-\frac{\hbar^2 \nabla^2}{2m}}_{-\frac{\hbar^2 d^2}{2m dx^2}} + V(x) \right) \psi_T(x)$$

$$= -\frac{\hbar^2}{2m} \frac{1}{\psi_T(x)} \frac{d^2}{dx^2} \psi_T(x)$$

$$V(x) = \frac{1}{2} \underline{k} x^2$$

$$= -\frac{\hbar^2}{2m} \frac{1}{\psi_T} \frac{d^2}{dx^2} \psi_T + \frac{1}{2} k x^2$$

$-\alpha^2 x^2 / 2$

$$HO: \psi_T \sim e$$

$$E_0 = \hbar \omega \cdot \frac{1}{2}$$

$$\frac{d^2}{dx^2} u(x) \approx \frac{\underline{u(x+h)} + \underline{u(x-h)} - 2\underline{u(x)}}{h^2}$$