F45 4411/9411 Felnuary 3,2022

- Markov chain Monte Carlo (MC)²

Discretized probability of being in a given state

ー人ー

 $w_i(t)$

un our cauze

 $w_{\kappa}(\epsilon) \rightarrow P_{T}(\vec{k}; \vec{\alpha})$ $= \frac{\left| \mathcal{A}_{T}(\vec{k}; \alpha) \right|^{2}}{\left| \vec{k} \cdot \vec{k$

 $\sum_{i \in State} w_i(t) = 1$

Transition probabluts W(j-7i) = Wij

Markov chain

w: (6) = [[w(j->i) w(6)

W is a stockastic matrix $\sum_{i,j} w_{i,j} = \underline{1}$ $W = \begin{bmatrix} -1/4 & 1/9 & 3/8 & 1/3 \\ 1/4 & 2/9 & 0 & 1/3 \\ 0 & 1/9 & 3/8 & 0 \\ 1/4 & 5/9 & 2/8 & 1/3 \end{bmatrix}$ w(t=1) = W.w(t=0)- 1/4 7 1/2 0

$$w(t=\theta) = \begin{bmatrix} 0.249 \\ 0.3196 \\ 0.057 \\ 0.579 \end{bmatrix}$$

$$Max eigenvalue W = 1$$
and represents the
$$50-called steady state$$

$$w(t) = Ww(t-1)$$

$$w(t) = Ww(t-1)$$

$$w(t) = Ww(t-1)$$

$$w(t) = Ww(t-1)$$

$$w(t) = 1$$

$$eigenvalue pratonn$$

$$with \lambda = 1$$

eigenvalue maklenn with $\lambda = 1$ w(t) = W t w(t=0) $w(t=0) = \sum_{i} \alpha_{i} v_{i}$ eigenvectors $w(t) = \lambda_{i} v_{i}$

W(+) = W tw (6=0)

 λ_{t} : $\lambda_0 = 1 \geq \lambda_1 \geq \lambda_2 - - W(t) = \lambda_0 \alpha_0 v_0 + \sum_{i=1}^{s} \alpha_i v_i \lambda_i^t$ = >0000 ケーショ Mar Kov-chain Montre Casto - motogase the system (instrale positions Ro) - # attempted moves (# Monte Carlo Cycles) Define Pr(R;à) DO FOR i=1, # Mante Caslo agoles - suggest new position

R = Ro + RNG x stepsize PG) | uniform des Tribution VI Small Jpa) x dx too large ROS XO RNG E [91] $X_1 = X_0 + (n - 0.5) \times STepsize$ (1) wants to sample regions with large p(x) if only this, then the contribution to 1 = Sp(x)dx x uill be blased (ii) Allow jermping into regions with lower PQ). _> sampling rule = Metropolis also if position accepted

- upda de vanables else Stag in same place previous value = new value end 100 P update averages Sampling Rale = Me tropols - Hastings algo. $w_i(t) = \sum_{i} w_i(t-i)$ W(j->i) = T(j->i)A(g-n') probability for making trans, tran Acceptance

/ makalility time independent $W_{\lambda'}(t) = \sum_{j} (w_{j'}(t-1) \overline{J}_{j-2\lambda'} A_{j-2\lambda'}$ + Wi(t) Ti->j(1-Ai->j) $\left(\begin{array}{ccc} \sum_{i} T_{i} \Rightarrow j & = & \underline{1} \end{array}\right)$ $= w_{i}(t-1) + \sum_{i} \left[w_{i}(t-1) \int_{J-2n'} A_{J-2n'} A_{J-2n'}$ $\omega_{n'}(t-)-\omega_{n'}(t-1)=\sum_{i,j}$ $w_{n'}(t) = w_{n'}(t-1) - 7$ Wi(t) = Wi time un depen den t

 $O = \sum_{i=1}^{n} \left[w_{i} T_{i} + A_{i} - A_{i} \right]$

- VVA . V-7/ 12-11

$$\sum_{j} w_{j} T_{j} = \lambda_{j} A_{j} = \lambda_{i} - \lambda_{j}$$

$$\sum_{j} w_{i} T_{i} = \lambda_{j} A_{i} - \lambda_{j}$$

$$\sum_{j} w_{i} T_{i} - \lambda_{j} A_{i} - \lambda_{j} A_{i} - \lambda_{j}$$

$$\sum_{j} w_{i} T_{i} - \lambda_{j} A_{i} - \lambda_{j} A_{i} - \lambda_{j}$$

$$\sum_{j} w_{i} T_{i} - \lambda_{j} A_{i} -$$

$$\frac{\omega_{i}}{\omega_{j}} = \frac{\pi_{j} - \lambda_{i} - \lambda_{j}}{\pi_{i} - \lambda_{j}}$$

in our case

$$\frac{\omega_{\lambda}}{\omega_{j}} = \frac{|\mathcal{A}_{T}(\vec{R}_{\lambda};\vec{\alpha})|^{2}}{|\mathcal{A}_{T}(\vec{R}_{j};\vec{\alpha})|^{2}}$$

$$= \frac{|\mathcal{A}_{T}(\vec{R}_{j};\vec{\alpha})|^{2}}{|\mathcal{A}_{J}=\lambda_{j}|}$$

$$= \frac{|\mathcal{A}_{J}=\lambda_{j}|}{|\mathcal{A}_{\lambda}=\lambda_{j}|}$$

importance sampling part.

$$\frac{\omega_{i}}{\omega_{j}} = \frac{A_{j}-7\lambda}{A_{i}-7j}$$

$$0 \le A_{i \ni j} \le 1$$

 $(\hat{x}) \quad |w_{\hat{x}}| \geq |w_{\hat{y}}|$ $\int p(x) \times dx \qquad \frac{p(x_{\hat{x}})}{p(x_{\hat{y}})}$

if wizw; accept

Aini

$$A_{\lambda \rightarrow j}' = 1$$

$$xts \quad max \quad value,$$

$$A_{i \rightarrow j} \leq A_{i \rightarrow j}'$$

$$A_{j \rightarrow i} \leq u_{j}'$$

$$A_{i \rightarrow j} = 1$$

$$A_{i \rightarrow j} = 1$$

$$A_{j \rightarrow i} \leq A_{i \rightarrow j}'$$

$$Me \quad teopolis \quad algo;$$

$$A_{j \rightarrow i} = \begin{cases} n \quad ij \quad w_{i \rightarrow i} \neq w_{j}' \\ w_{j}' \quad else \end{cases}$$

$$= min \left\{ \frac{w_{i}}{w_{j}'} \mid 1 \right\}$$

Implement 9 trans w; = | 4, (R; ; 2) |2 wi = | 47 (Rija) | if r = wilw; nandour & [GI] new position is Ri up date expectation raluer Filia), Filia) Call to E-local function. else. Ri = Rj add Ec (Ri), not moving it 9150 a measurement.

Metropolis - Hastings

we need a model

for Tiəj

USE ank between

diffusion equation and
Markov chains