

Ingredients needed to
build a VMC program

$$|E[H] = \langle E[\vec{\alpha}] \rangle$$

$$(\equiv \bar{E}[\alpha])$$

$$= \frac{\int_{\vec{r} \in D} d\vec{r} \, \psi_T^*(\vec{r}; \vec{\alpha}) \overset{\frac{\psi_T}{\psi_T}}{H(\vec{r})} \psi_T(\vec{r}; \vec{\alpha})}{\int d\vec{r} \, |\psi_T(\vec{r}; \vec{\alpha})|^2}$$

Define a PDF

$$P_T(\vec{r}; \vec{\alpha}) = \frac{|\psi_T(\vec{r}; \vec{\alpha})|^2}{\int_{\vec{r} \in D} d\vec{r} \, |\psi_T(\vec{r}; \vec{\alpha})|^2}$$

Local energy

$$E_L(\vec{r}; \vec{\alpha}) = \frac{1}{\psi_T(\vec{r}; \vec{\alpha})} H(\vec{r}) \psi_T(\vec{r}; \vec{\alpha})$$

$$\vec{\alpha} = [\alpha_1, \alpha_2, \alpha_3, \dots, \alpha_m]$$

$$|E[H] = E[E_L(\vec{\alpha})]$$

$$= \langle E_L(\vec{\alpha}) \rangle = \int_{\vec{R} \in D} d\vec{R} P_T(\vec{R}; \vec{\alpha}) \times E_L(\vec{R}; \vec{\alpha})$$

Define $\psi_T(\vec{R}; \vec{\alpha})$

— | — $H(\vec{R})$

— | — E_L, P_T

How to build a program

system

— wave(trial)
— functions

— local energy
Hamiltonian
if possible
analytical

solver

— Markov—
— chain MC
(MC)²

— sampling
— Metropolis
— ...

expression
for E_L, Ψ
and their
derivatives

- ~~Optimal~~
- Evaluate errors
- Resampling methods
 - Bootstrap
 - Jackknife
 - Blocking
- optimal parameters
 $\alpha_i \quad i=1, 2, \dots, m$
$$\frac{\partial \langle E_L(\vec{\alpha}) \rangle}{\partial \alpha_i} = 0$$
- gradient methods
- High-performance computing
 - MPI
 - OPENMP
- Neural Networks
- other many-body

1-Dim ho potential

Schrödinger's equation

$$-\frac{\hbar^2}{2m} \frac{d^2 \psi(x)}{dx^2} + \frac{1}{2} m \omega^2 x^2 \psi(x) = E \psi(x)$$

$$E_n = \hbar \omega (n + 1/2) \quad n=0,1,2,\dots$$

Scale equation

Dim less length $\rho = \gamma \cdot x$

$$x = \rho / \gamma$$

$$-\frac{\hbar^2 \gamma^2}{2m} \frac{d^2}{d\rho^2} \psi(\rho) + \frac{1}{2} \frac{m \omega^2 \rho^2}{\gamma^2}$$

$$= E \psi(\rho)$$

$$\times \frac{m}{\hbar^2 \gamma^2}$$



$$-\frac{1}{2} \frac{d^2}{ds^2} \psi(s) + \frac{1}{2} \left(\frac{m^2 \omega^2}{\hbar^2 s^4} \right) s^2 \psi(s)$$

$$\frac{m^2 \omega^2}{\hbar^2 s^4} = 1$$

$$s^2 = \frac{\hbar}{m \omega} \Rightarrow$$

$$s = \sqrt{\frac{\hbar}{m \omega}}$$

↖ natural length scale

natural units

$$\hbar = m = \omega = 1$$

Trial wf :

$$\psi_T(x; \alpha) = e^{-\frac{1}{2} \alpha^2 x^2}$$

$$E_2 = \frac{1}{\psi_T} \left(-\frac{1}{2} \frac{d^2}{dx^2} + \frac{1}{2} x^2 \right) \psi_T$$

$s \rightarrow x$

... 411

$$= \frac{1}{2} (\alpha^2 + x^2(1-\alpha^4))$$

$$\begin{aligned} \langle E_L[\alpha] \rangle &= \int_{-\infty}^{\infty} dx \, p_T(x; \alpha) E_L(x; \alpha) \\ &= \frac{\int_{-\infty}^{\infty} dx \, e^{-\alpha^2 x^2} \frac{1}{2} (\alpha^2 + x^2(1-\alpha^4))}{\int_{-\infty}^{\infty} dx \, e^{-\alpha^2 x^2}} \end{aligned}$$

$$= \frac{1}{4} \left(\alpha^2 + \frac{1}{\alpha^2} \right)$$

optimal α

$$\frac{d \langle E_L[\alpha] \rangle}{d\alpha} = 0$$

$$= \frac{1}{2} \alpha - \frac{1}{2\alpha^3} = 0$$

$$\underline{\underline{\alpha = 1}}$$

$$\langle E_L[\alpha = 1] \rangle = \underline{1}$$

$$\hbar = c = m = 1 \quad (W = 1)$$

normally we don't know

ψ_{Exact} , how can we

judge from $\psi_i(x; \alpha)$

whether we are close
or equal to ψ_{Exact} ?

variance defined as

$$\sigma_x^2 = \int_{x \in D} x^2 p(x) dx - \left[\int_{x \in D} x p(x) dx \right]^2$$

" μ_x

$$E[H^2] = \frac{\int_{x \in D} \psi^*(x) H^2 \psi(x) dx}{\int dx |\psi|^2}$$

$$H \psi(x) = \sum \psi(x) ; \text{ exact solution}$$

" " " "

$$2) \quad \psi_T = \psi_{\text{exact}}$$

$$E[H^2] = \frac{\varepsilon^2 \int |\psi|^2 dx}{\int |\psi|^2 dx}$$

$$\left(E[H] \right)^2 = \varepsilon^2$$

$$\sigma_H^2 = E[H^2] - [E[H]]^2$$

$$= 0 \quad \text{if } \psi_T = \psi_{\text{exact}}$$

$$\psi_T(x; \alpha) = e^{-\frac{1}{2}\alpha^2 x^2}$$

$$\sigma^2[\alpha] = \frac{1}{4} \left(1 + (1 - \alpha^2) \frac{3}{4\alpha^2} \right) - \langle E_L[\alpha] \rangle^2$$

$$\alpha = 1$$

$$\sigma^2[\alpha] = \frac{1}{4} - \left(\frac{1}{2} \right)^2 = 0$$

How to find ψ_T ?

Hydrogen atom

$$\left(-\frac{\hbar^2}{2m} \nabla^2 - \frac{ke^2}{r} \right) \psi(\vec{r}) = E \psi(\vec{r})$$

$$x, y, z \Rightarrow r, \theta, \varphi$$
$$r \in [0, \infty)$$

Diff eq. for r

$$\left(-\frac{\hbar^2}{2m} \frac{d}{dr} r \frac{d}{dr} + \frac{l(l+1)\hbar^2}{r^2} - \frac{ke^2}{r} \right) R(r) = E_r R(r)$$

$$l = 0, \quad \hbar = 1 = e = c = m$$

$$E_L(r) = \frac{1}{R(r)} \left(-\frac{d^2}{dr^2} - \frac{2}{r} \frac{d}{dr} - \frac{1}{r} \right) R(r)$$

$r \rightarrow 0$ divergence

$$\text{in } -\frac{2}{r} \frac{d}{dr} \text{ and } -\frac{1}{r}$$

$$\lim_{r \rightarrow 0} \frac{d^n \psi(r)}{d r^n} = \text{constant}$$

$$\lim_{r \rightarrow 0} E_L(r) = \frac{1}{R} \left(-\frac{2}{r} \frac{dR}{dr} - \frac{1}{r} R \right) = 0$$

$$-\frac{2}{R} \frac{dR}{dr} R - \frac{1}{r} R \Rightarrow$$

$$\frac{dR}{dr} = -\frac{1}{2} R$$

$$R(r) = e^{-\frac{1}{2}r} \Rightarrow$$

$$\psi_T(r; \alpha) = e^{-\alpha \cdot r}$$