

Building a Variational Monte Carlo program

Morten Hjorth-Jensen Email mhjensen@uio.no¹

Department of Physics and Center for Computing in Science Education, University
of Oslo, Oslo, Norway¹

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Overview of week January 27-31

Topics

- ▶ Repetition from last week and discussions of code templates in python and C++
- ▶ Essential ingredients: Variational Monte Carlo methods, Metropolis Algorithm, statistics and Markov Chain theory
- ▶ How to structure the VMC code

Teaching Material, videos and written material

- ▶ Reading suggestions:
- ▶ Video of lecture to be added

Code templates for first project

1. The C++ template
2. The python template, using JAX

Basic Quantum Monte Carlo, repetition from last week

We start with the variational principle. Given a hamiltonian H and a trial wave function $\Psi_{\mathcal{T}}(\mathbf{R}; \alpha)$, the variational principle states that the expectation value of \mathcal{H} , defined through

$$\mathcal{E}[\mathcal{H}] = \frac{\int [\mathcal{R} \Theta_{\mathcal{T}}^*(\mathcal{R}; \alpha) \mathcal{H}(\mathcal{R}) \Theta_{\mathcal{T}}(\mathcal{R}; \alpha)]}{\int [\mathcal{R} \Theta_{\mathcal{T}}^*(\mathcal{R}; \alpha) \Theta_{\mathcal{T}}(\mathcal{R}; \alpha)]},$$

is an upper bound to the ground state energy E_0 of the hamiltonian H , that is

$$E_0 \leq \mathcal{E}[H].$$

Multi-dimensional integrals

In general, the integrals involved in the calculation of various expectation values are multi-dimensional ones. Traditional integration methods such as Gauss-Legendre quadrature will not be adequate for say the computation of the energy of a many-body system.

Here we have defined the vector $\mathbf{R} = [\mathbf{r}_1, \mathbf{r}_2, \dots, \mathbf{r}_n]$ as an array that contains the positions of all particles n while the vector $\boldsymbol{\alpha} = [\alpha_1, \alpha_2, \dots, \alpha_m]$ contains the variational parameters of the model, m in total.

Trail functions

The trial wave function can be expanded in the eigenstates $\Psi_i(\mathbf{R})$ of the hamiltonian since they form a complete set, viz.,

$$\Psi_T(\mathbf{R}; \alpha) = \sum_i a_i \Psi_i(\mathbf{R}),$$

and assuming that the set of eigenfunctions are normalized, one obtains

$$\frac{\sum_{nm} a_m^* a_n \int d\mathbf{R} \Psi_m^*(\mathbf{R}) H(\mathbf{R}) \Psi_n(\mathbf{R})}{\sum_{nm} a_m^* a_n \int d\mathbf{R} \Psi_m^*(\mathbf{R}) \Psi_n(\mathbf{R})} = \frac{\sum_n a_n^2 E_n}{\sum_n a_n^2} \geq E_0,$$

where we used that $H(\mathbf{R})\Psi_n(\mathbf{R}) = E_n\Psi_n(\mathbf{R})$.

Variational principle

The variational principle yields the lowest energy of states with a given symmetry.

In most cases, a wave function has only small values in large parts of configuration space, and a straightforward procedure which uses homogeneously distributed random points in configuration space will most likely lead to poor results. This may suggest that some kind of importance sampling combined with e.g., the Metropolis algorithm may be a more efficient way of obtaining the ground state energy. The hope is then that those regions of configurations space where the wave function assumes appreciable values are sampled more efficiently.

Tedious parts of VMC calculations

The tedious part in a VMC calculation is the search for the variational minimum. A good knowledge of the system is required in order to carry out reasonable VMC calculations. This is not always the case, and often VMC calculations serve rather as the starting point for so-called diffusion Monte Carlo calculations (DMC). Diffusion Monte Carlo is a way of solving exactly the many-body Schrodinger equation by means of a stochastic procedure. A good guess on the binding energy and its wave function is however necessary. A carefully performed VMC calculation can aid in this context.

Bird's eye view on Variational MC

The basic procedure of a Variational Monte Carlo calculations consists thus of

1. Construct first a trial wave function $\psi_T(\mathbf{R}; \alpha)$, for a many-body system consisting of n particles located at positions $\mathbf{R} = (\mathbf{R}_1, \dots, \mathbf{R}_n)$. The trial wave function depends on α variational parameters $\alpha = (\alpha_1, \dots, \alpha_M)$.
2. Then we evaluate the expectation value of the hamiltonian H

$$\bar{E}[\alpha] = \frac{\int d\mathbf{R} \Psi_T^*(\mathbf{R}, \alpha) H(\mathbf{R}) \Psi_T(\mathbf{R}, \alpha)}{\int d\mathbf{R} \Psi_T^*(\mathbf{R}, \alpha) \Psi_T(\mathbf{R}, \alpha)}.$$

1. Thereafter we vary α according to some minimization algorithm and return eventually to the first step if we are not satisfied with the results.

Here we have used the notation \bar{E} to label the expectation value of the energy.

Linking with standard statistical expressions for expectation values

In order to bring in the Monte Carlo machinery, we define first a likelihood distribution, or probability density distribution (PDF). Using our ansatz for the trial wave function $\psi_T(\mathbf{R}; \alpha)$ we define a PDF

$$P(\mathbf{R}) = \frac{|\psi_T(\mathbf{R}; \alpha)|^2}{\int |\psi_T(\mathbf{R}; \alpha)|^2 d\mathbf{R}}.$$

This is our model for probability distribution function. The approximation to the expectation value of the Hamiltonian is now

$$\bar{E}[\alpha] = \frac{\int d\mathbf{R} \psi_T^*(\mathbf{R}; \alpha) H(\mathbf{R}) \psi_T(\mathbf{R}; \alpha)}{\int d\mathbf{R} \psi_T^*(\mathbf{R}; \alpha) \psi_T(\mathbf{R}; \alpha)}.$$

The local energy

We define a new quantity

$$E_L(\mathbf{R}; \alpha) = \frac{1}{\psi_T(\mathbf{R}; \alpha)} H \psi_T(\mathbf{R}; \alpha),$$

called the local energy, which, together with our trial PDF yields a new expression (and which look similar to the the expressions for moments in statistics)

$$\overline{E}[\alpha] = \int P(\mathbf{R}) E_L(\mathbf{R}; \alpha) d\mathbf{R} \approx \frac{1}{N} \sum_{i=1}^N E_L(\mathbf{R}_i; \alpha)$$

with N being the number of Monte Carlo samples. The expression on the right hand side follows from Bernoulli's law of large numbers, which states that the sample mean, in the limit $N \rightarrow \infty$ approaches the true mean

The Monte Carlo algorithm

The Algorithm for performing a variational Monte Carlo calculations runs as this

- ▶ Initialisation: Fix the number of Monte Carlo steps. Choose an initial \mathbf{R} and variational parameters α and calculate $|\psi_T^\alpha(\mathbf{R})|^2$.
- ▶ Initialise the energy and the variance and start the Monte Carlo calculation.
 - ▶ Calculate a trial position $\mathbf{R}_p = \mathbf{R} + r * \text{step}$ where r is a random variable $r \in [0, 1]$.
 - ▶ Metropolis algorithm to accept or reject this move $w = P(\mathbf{R}_p)/P(\mathbf{R})$.
 - ▶ If the step is accepted, then we set $\mathbf{R} = \mathbf{R}_p$.
 - ▶ Update averages
- ▶ Finish and compute final averages.

Observe that the jumping in space is governed by the variable *step*. This is often referred to as the **brute-force** sampling and is normally replaced by what is called **importance sampling**, discussed in more detail next week..

Example from last week, the harmonic oscillator in one dimension (best seen with jupyter-notebook)

We present here a well-known example, the harmonic oscillator in one dimension for one particle. This will also serve the aim of introducing our next model, namely that of interacting electrons in a harmonic oscillator trap.

Here as well, we do have analytical solutions and the energy of the ground state, with $\hbar = 1$, is $1/2\omega$, with ω being the oscillator frequency. We use the following trial wave function

$$\psi_T(x; \alpha) = \exp\left(-\frac{1}{2}\alpha^2 x^2\right),$$

which results in a local energy

$$\frac{1}{2} (\alpha^2 + x^2(1 - \alpha^4)) .$$

We can compare our numerically calculated energies with the exact energy as function of α

$$\bar{E}[\alpha] = \frac{1}{4} \left(\alpha^2 + \frac{1}{\alpha^2} \right) .$$

Why Markov chains, Brownian motion and the Metropolis algorithm

- ▶ We want to study a physical system which evolves towards equilibrium, from given initial conditions.
- ▶ We start with a PDF $w(x_0, t_0)$ and we want to understand how the system evolves with time.
- ▶ We want to reach a situation where after a given number of time steps we obtain a steady state. This means that the system reaches its most likely state (equilibrium situation)
- ▶ Our PDF is normally a multidimensional object whose normalization constant is impossible to find.
- ▶ Analytical calculations from $w(x, t)$ are not possible.
- ▶ To sample directly from $w(x, t)$ is not possible/difficult.
- ▶ The transition probability W is also not known.
- ▶ How can we establish that we have reached a steady state?
Sounds impossible!

Use Markov chain Monte Carlo

Brownian motion and Markov processes

A Markov process is a random walk with a selected probability for making a move. The new move is independent of the previous history of the system.

The Markov process is used repeatedly in Monte Carlo simulations in order to generate new random states.

The reason for choosing a Markov process is that when it is run for a long enough time starting with a random state, we will eventually reach the most likely state of the system.

In thermodynamics, this means that after a certain number of Markov processes we reach an equilibrium distribution.

This mimicks the way a real system reaches its most likely state at a given temperature of the surroundings.

Brownian motion and Markov processes, Ergodicity and Detailed balance

To reach this distribution, the Markov process needs to obey two important conditions, that of **ergodicity** and **detailed balance**. These conditions impose then constraints on our algorithms for accepting or rejecting new random states.

The Metropolis algorithm discussed here abides to both these constraints.

The Metropolis algorithm is widely used in Monte Carlo simulations and the understanding of it rests within the interpretation of random walks and Markov processes.

For a proof the ergodic theorem see

<https://www.pnas.org/doi/10.1073/pnas.17.2.656>.

Brownian motion and Markov processes, jargon

In a random walk one defines a mathematical entity called a **walker**, whose attributes completely define the state of the system in question.

The state of the system can refer to any physical quantities, from the vibrational state of a molecule specified by a set of quantum numbers, to the brands of coffee in your favourite supermarket.

The walker moves in an appropriate state space by a combination of deterministic and random displacements from its previous position.

This sequence of steps forms a **chain**.

Brownian motion and Markov processes, sequence of ingredients

- ▶ We want to study a physical system which evolves towards equilibrium, from given initial conditions.
- ▶ Markov chains are intimately linked with the physical process of diffusion.
- ▶ From a Markov chain we can then derive the conditions for detailed balance and ergodicity. These are the conditions needed for obtaining a steady state.
- ▶ The widely used algorithm for doing this is the so-called Metropolis algorithm, in its refined form the Metropolis-Hastings algorithm.

Applications: almost every field in science

- ▶ Financial engineering, see for example Patriarca *et al*, *Physica* **340**, page 334 (2004).
- ▶ Neuroscience, see for example Lipinski, *Physics Medical Biology* **35**, page 441 (1990) or Farnell and Gibson, *Journal of Computational Physics* **208**, page 253 (2005)
- ▶ Tons of applications in physics
- ▶ and chemistry
- ▶ and biology, medicine
- ▶ Nobel prize in economy to Black and Scholes

$$\frac{\partial V}{\partial t} + \frac{1}{2}\sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + rS \frac{\partial V}{\partial S} - rV = 0.$$

The Black and Scholes equation is a partial differential equation, which describes the price of the option over time. It is a diffusion equation with a random term.

The list of applications is endless

Markov processes

A Markov process allows in principle for a microscopic description of Brownian motion. As with the random walk studied in the previous section, we consider a particle which moves along the x -axis in the form of a series of jumps with step length $\Delta x = l$. Time and space are discretized and the subsequent moves are statistically independent, i.e., the new move depends only on the previous step and not on the results from earlier trials. We start at a position $x = j\Delta x$ and move to a new position $x = i\Delta x$ during a step $\Delta t = \epsilon$, where $i \geq 0$ and $j \geq 0$ are integers. The original probability distribution function (PDF) of the particles is given by $w_i(t = 0)$ where i refers to a specific position on the grid in The function $w_i(t = 0)$ is now the discretized version of $w(x, t)$. We can regard the discretized PDF as a vector.

Markov processes

For the Markov process we have a transition probability from a position $x = j\ell$ to a position $x = i\ell$ given by

$$W_{ij}(\epsilon) = W(i\ell - j\ell, \epsilon) = \begin{cases} \frac{1}{2} & |i - j| = 1 \\ 0 & \text{else} \end{cases},$$

where W_{ij} is normally called the transition probability and we can represent it, see below, as a matrix. **Here we have specialized to a case where the transition probability is known.**

Our new PDF $w_i(t = \epsilon)$ is now related to the PDF at $t = 0$ through the relation

$$w_i(t = \epsilon) = \sum_j W(j \rightarrow i) w_j(t = 0).$$

This equation represents the discretized time-development of an original PDF with equal probability of jumping left or right.

Markov processes, the probabilities

Since both \mathbf{W} and \mathbf{w} represent probabilities, they have to be normalized, i.e., we require that at each time step we have

$$\sum_i w_i(t) = 1,$$

and

$$\sum_j W(j \rightarrow i) = 1,$$

which applies for all j -values. The further constraints are $0 \leq W_{ij} \leq 1$ and $0 \leq w_j \leq 1$. Note that the probability for remaining at the same place is in general not necessarily equal zero.

Markov processes

The time development of our initial PDF can now be represented through the action of the transition probability matrix applied n times. At a time $t_n = n\epsilon$ our initial distribution has developed into

$$w_i(t_n) = \sum_j W_{ij}(t_n) w_j(0),$$

and defining

$$W(il - jl, n\epsilon) = (W^n(\epsilon))_{ij}$$

we obtain

$$w_i(n\epsilon) = \sum_j (W^n(\epsilon))_{ij} w_j(0),$$

or in matrix form

$$\mathbf{w}(n\epsilon) = \mathbf{W}^n(\epsilon) \mathbf{w}(0). \quad (1)$$

An Illustrative Example

The following simple example may help in understanding the meaning of the transition matrix \hat{W} and the vector \hat{w} . Consider the 4×4 matrix \hat{W}

$$\mathbf{W} = \begin{pmatrix} 1/4 & 1/9 & 3/8 & 1/3 \\ 2/4 & 2/9 & 0 & 1/3 \\ 0 & 1/9 & 3/8 & 0 \\ 1/4 & 5/9 & 2/8 & 1/3 \end{pmatrix},$$

and we choose our initial state as

$$\mathbf{w}(t=0) = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}.$$

An Illustrative Example

We note that both the vector and the matrix are properly normalized. Summing the vector elements gives one and summing over columns for the matrix results also in one. Furthermore, the largest eigenvalue is one. We act then on \mathbf{w} with \mathbf{W} . The first iteration is

$$\mathbf{w}(t = \epsilon) = \mathbf{W}\mathbf{w}(t = 0),$$

resulting in

$$\mathbf{w}(t = \epsilon) = \begin{pmatrix} 1/4 \\ 1/2 \\ 0 \\ 1/4 \end{pmatrix}.$$

An Illustrative Example, next step

The next iteration results in

$$\mathbf{w}(t = 2\epsilon) = \mathbf{W}\mathbf{w}(t = \epsilon),$$

resulting in

$$\mathbf{w}(t = 2\epsilon) = \begin{pmatrix} 0.201389 \\ 0.319444 \\ 0.055556 \\ 0.423611 \end{pmatrix}.$$

Note that the vector \mathbf{w} is always normalized to 1.

An Illustrative Example, the steady state

We find the steady state of the system by solving the set of equations

$$w(t = \infty) = Ww(t = \infty),$$

which is an eigenvalue problem with eigenvalue equal to **one**! This set of equations reads

$$\begin{aligned} W_{11}w_1(t = \infty) + W_{12}w_2(t = \infty) + W_{13}w_3(t = \infty) + W_{14}w_4(t = \infty) &= w_1(t = \infty) \\ W_{21}w_1(t = \infty) + W_{22}w_2(t = \infty) + W_{23}w_3(t = \infty) + W_{24}w_4(t = \infty) &= w_2(t = \infty) \\ W_{31}w_1(t = \infty) + W_{32}w_2(t = \infty) + W_{33}w_3(t = \infty) + W_{34}w_4(t = \infty) &= w_3(t = \infty) \\ W_{41}w_1(t = \infty) + W_{42}w_2(t = \infty) + W_{43}w_3(t = \infty) + W_{44}w_4(t = \infty) &= w_4(t = \infty) \end{aligned} \tag{2}$$

with the constraint that

$$\sum_i w_i(t = \infty) = 1,$$

Code for the iterative process

```
from matplotlib import pyplot as plt
import numpy as np

# Define dimension of matrix and vectors
Dim = 4
#Setting up a transition probability matrix
TransitionMatrix = np.matrix('0.25 0.1111 0.375 0.3333; 0.5 0.2222 0.0
# Making a copy of the transition matrix
W = TransitionMatrix
print(W)
# our first state
wold = np.zeros(Dim)
wold[0] = 1.0
wnew = np.zeros(Dim)

# diagonalize and obtain eigenvalues, not necessarily sorted
EigValues, EigVectors = np.linalg.eig(TransitionMatrix)
# sort eigenvectors and eigenvalues
permute = EigValues.argsort()
EigValues = EigValues[permute]
EigVectors = EigVectors[:,permute]
for i in range(Dim):
    print(EigValues[i])

count = 0
while count < 20:
    for i in range(Dim):
```

Small exercise

Write a small code which diagonalized the matrix \mathbf{W} and find the eigenpairs and compare the coefficients w_i . **Note:** You may need to normalize the eigenvectors from the diagonalization procedure. What is the largest eigenvalue?

What do the results mean?

We have after t -steps

$$\mathbf{w}(t) = \mathbf{W}^t \mathbf{w}(0),$$

with $\mathbf{w}(0)$ the distribution at $t = 0$ and \mathbf{W} representing the transition probability matrix.

Understanding the basics

We can always expand $\mathbf{w}(0)$ in terms of the right eigenvectors \mathbf{v} of \mathbf{W} as

$$\mathbf{w}(0) = \sum_i \alpha_i \mathbf{v}_i,$$

resulting in

$$\mathbf{w}(t) = \mathbf{W}^t \mathbf{w}(0) = \mathbf{W}^t \sum_i \alpha_i \mathbf{v}_i = \sum_i \lambda_i^t \alpha_i \mathbf{v}_i,$$

with λ_i the i^{th} eigenvalue corresponding to the eigenvector \mathbf{v}_i . If we assume that λ_0 is the largest eigenvector we see that in the limit $t \rightarrow \infty$, $\mathbf{w}(t)$ becomes proportional to the corresponding eigenvector \mathbf{v}_0 . This is our steady state or final distribution.

Basics of the Metropolis Algorithm

The Metropolis algorithm is a method to sample a normalized probability distribution by a stochastic process. We define $\Xi_i^{(n)}$ to be the probability for finding the system in the state i at step n . In the simulations, our assumption is that we have a model for $\Xi_i^{(n)}$, but we do not know W . We will hence model W in terms of a likelihood for making transition T and a likelihood for accepting a transition. That is

$$W_{i \rightarrow j} = A_{i \rightarrow j} T_{i \rightarrow j}$$

The basic of the Metropolis Algorithm

- ▶ Sample a possible new state j with some probability $T_{i \rightarrow j}$.
- ▶ Accept the new state j with probability $A_{i \rightarrow j}$ and use it as the next sample.
- ▶ With probability $1 - A_{i \rightarrow j}$ the move is rejected and the original state i is used again as a sample.

We wish to derive the required properties of T and A such that $\pi_i^{(n \rightarrow \infty)} \rightarrow p_i$ so that starting from any distribution, the method converges to the correct distribution. Note that the description here is for a discrete probability distribution. Replacing probabilities p_i with expressions like $p(x_i)dx_i$ will take all of these over to the corresponding continuum expressions.

More on the Metropolis

The dynamical equation for $\Xi_i^{(n)}$ can be written directly from the description above. The probability of being in the state i at step n is given by the probability of being in any state j at the previous step, and making an accepted transition to i added to the probability of being in the state i , making a transition to any state j and rejecting the move:

$$\Xi_i^{(n)} = \sum_j \left[\Xi_j^{(n-1)} T_{j \rightarrow i} A_{j \rightarrow i} + \Xi_i^{(n-1)} T_{i \rightarrow j} (1 - A_{i \rightarrow j}) \right] . \quad (3)$$

Metropolis algorithm, setting it up

Since the probability of making some transition must be 1, $\sum_j T_{i \rightarrow j} = 1$, and Eq. (3) becomes

$$\Xi_i^{(n)} = \Xi_i^{(n-1)} + \sum_j \left[\Xi_j^{(n-1)} T_{j \rightarrow i} A_{j \rightarrow i} - \Xi_i^{(n-1)} T_{i \rightarrow j} A_{i \rightarrow j} \right] . \quad (4)$$

Metropolis continues

For large n we require that $\Xi_i^{(n \rightarrow \infty)} = p_i$, the desired probability distribution. Taking this limit, gives the balance requirement

$$\sum_j [p_j T_{j \rightarrow i} A_{j \rightarrow i} - p_i T_{i \rightarrow j} A_{i \rightarrow j}] = 0, \quad (5)$$

Detailed Balance

The balance requirement is very weak. Typically the much stronger detailed balance requirement is enforced, that is rather than the sum being set to zero, we set each term separately to zero and use this to determine the acceptance probabilities. Rearranging, the result is

$$\frac{A_{j \rightarrow i}}{A_{i \rightarrow j}} = \frac{p_i T_{i \rightarrow j}}{p_j T_{j \rightarrow i}}. \quad (6)$$

This is the detailed balance requirement

More on Detailed Balance

The Metropolis choice is to maximize the A values, that is

$$A_{j \rightarrow i} = \min \left(1, \frac{p_i T_{i \rightarrow j}}{p_j T_{j \rightarrow i}} \right). \quad (7)$$

Other choices are possible, but they all correspond to multiplying $A_{i \rightarrow j}$ and $A_{j \rightarrow i}$ by the same constant smaller than unity. The penalty function method uses just such a factor to compensate for p_i that are evaluated stochastically and are therefore noisy. Having chosen the acceptance probabilities, we have guaranteed that if the $\Xi_i^{(n)}$ has equilibrated, that is if it is equal to p_i , it will remain equilibrated. Next we need to find the circumstances for convergence to equilibrium.

Dynamical Equation

The dynamical equation can be written as

$$\Xi_i^{(n)} = \sum_j M_{ij} \Xi_j^{(n-1)} \quad (8)$$

with the matrix M given by

$$M_{ij} = \delta_{ij} \left[1 - \sum_k T_{i \rightarrow k} A_{i \rightarrow k} \right] + T_{j \rightarrow i} A_{j \rightarrow i}. \quad (9)$$

Summing over i shows that $\sum_i M_{ij} = 1$, and since $\sum_k T_{i \rightarrow k} = 1$, and $A_{i \rightarrow k} \leq 1$, the elements of the matrix satisfy $M_{ij} \geq 0$. The matrix M is therefore a stochastic matrix.

Interpreting the Metropolis Algorithm

The Metropolis method is simply the power method for computing the right eigenvector of \mathbf{M} with the largest magnitude eigenvalue. By construction, the correct probability distribution is a right eigenvector with eigenvalue 1. Therefore, for the Metropolis method to converge to this result, we must show that \mathbf{M} has only one eigenvalue with this magnitude, and all other eigenvalues are smaller.

Even a defective matrix has at least one left and right eigenvector for each eigenvalue. An example of a defective matrix is

$$\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix},$$

with two zero eigenvalues, only one right eigenvector

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

and only one left eigenvector $(0 \ 1)$.

Gershgorin bounds and Metropolis

The Gershgorin bounds for the eigenvalues can be derived by multiplying on the left with the eigenvector with the maximum and minimum eigenvalues,

$$\begin{aligned}\sum_i \psi_i^{\max} M_{ij} &= \lambda_{\max} \psi_j^{\max} \\ \sum_i \psi_i^{\min} M_{ij} &= \lambda_{\min} \psi_j^{\min}\end{aligned}\tag{10}$$

Normalizing the Eigenvectors

Next we choose the normalization of these eigenvectors so that the largest element (or one of the equally largest elements) has value 1. Let's call this element k , and we can therefore bound the magnitude of the other elements to be less than or equal to 1. This leads to the inequalities, using the property that $M_{ij} \geq 0$,

$$\begin{aligned}\sum_i M_{ik} &\leq \lambda_{\max} \\ M_{kk} - \sum_{i \neq k} M_{ik} &\geq \lambda_{\min}\end{aligned}\tag{11}$$

where the equality from the maximum will occur only if the eigenvector takes the value 1 for all values of i where $M_{ik} \neq 0$, and the equality for the minimum will occur only if the eigenvector takes the value -1 for all values of $i \neq k$ where $M_{ik} \neq 0$.

More Metropolis analysis

That the maximum eigenvalue is 1 follows immediately from the property that $\sum_i M_{ik} = 1$. Similarly the minimum eigenvalue can be -1, but only if $M_{kk} = 0$ and the magnitude of all the other elements ψ_i^{\min} of the eigenvector that multiply nonzero elements M_{ik} are -1.

Let's first see what the properties of M must be to eliminate any -1 eigenvalues. To have a -1 eigenvalue, the left eigenvector must contain only ± 1 and 0 values. Taking in turn each ± 1 value as the maximum, so that it corresponds to the index k , the nonzero M_{ik} values must correspond to i index values of the eigenvector which have opposite sign elements. That is, the M matrix must break up into sets of states that always make transitions from set A to set B ... back to set A. In particular, there can be no rejections of these moves in the cycle since the -1 eigenvalue requires $M_{kk} = 0$. To guarantee no eigenvalues with eigenvalue -1, we simply have to make sure that there are no cycles among states. Notice that this is generally trivial since such cycles cannot have any rejections at any stage. An example of such a cycle is sampling a noninteracting Ising spin. If the transition is taken to flip the spin, and the energy

Final Considerations I

Next we need to make sure that there is only one left eigenvector with eigenvalue 1. To get an eigenvalue 1, the left eigenvector must be constructed from only ones and zeroes. It is straightforward to see that a vector made up of ones and zeroes can only be an eigenvector with eigenvalue 1 if the matrix element $M_{ij} = 0$ for all cases where $\psi_i \neq \psi_j$. That is we can choose an index i and take $\psi_i = 1$. We require all elements ψ_j where $M_{ij} \neq 0$ to also have the value 1. Continuing we then require all elements ψ_ℓ where $M_{j\ell} \neq 0$ to have value 1. Only if the matrix M can be put into block diagonal form can there be more than one choice for the left eigenvector with eigenvalue 1. We therefore require that the transition matrix not be in block diagonal form. This simply means that we must choose the transition probability so that we can get from any allowed state to any other in a series of transitions.

Final Considerations II

Finally, we note that for a defective matrix, with more eigenvalues than independent eigenvectors for eigenvalue 1, the left and right eigenvectors of eigenvalue 1 would be orthogonal. Here the left eigenvector is all 1 except for states that can never be reached, and the right eigenvector is $p_i > 0$ except for states that give zero probability. We already require that we can reach all states that contribute to p_i . Therefore the left and right eigenvectors with eigenvalue 1 do not correspond to a defective sector of the matrix and they are unique. The Metropolis algorithm therefore converges exponentially to the desired distribution.

Final Considerations III

The requirements for the transition $T_{i \rightarrow j}$ are

- ▶ A series of transitions must let us to get from any allowed state to any other by a finite series of transitions.
- ▶ The transitions cannot be grouped into sets of states, A, B, C, \dots such that transitions from A go to B , B to C etc and finally back to A . With condition (a) satisfied, this condition will always be satisfied if either $T_{i \rightarrow i} \neq 0$ or there are some rejected moves.

The system: two particles (fermions normally) in a harmonic oscillator trap in two dimensions

The Hamiltonian of the quantum dot is given by

$$\hat{H} = \hat{H}_0 + \hat{V},$$

where \hat{H}_0 is the many-body HO Hamiltonian, and \hat{V} is the inter-electron Coulomb interactions. In dimensionless units,

$$\hat{V} = \sum_{i < j}^N \frac{1}{r_{ij}},$$

with $r_{ij} = \sqrt{r_i^2 + r_j^2}$.

Separating the degrees of freedom

This leads to the separable Hamiltonian, with the relative motion part given by ($r_{ij} = r$)

$$\hat{H}_r = -\nabla_r^2 + \frac{1}{4}\omega^2 r^2 + \frac{1}{r},$$

plus a standard Harmonic Oscillator problem for the center-of-mass motion. This system has analytical solutions in two and three dimensions (M. Taut 1993 and 1994).

Variational Monte Carlo code (best seen with jupyter-notebook)

We want to perform a Variational Monte Carlo calculation of the ground state of two electrons in a quantum dot well with different oscillator energies, assuming total spin $S = 0$. Our trial wave function has the following form

$$\psi_T(\mathbf{r}_1, \mathbf{r}_2) = C \exp(-\alpha_1 \omega (r_1^2 + r_2^2)/2) \exp\left(\frac{r_{12}}{(1 + \alpha_2 r_{12})}\right), \quad (12)$$

where the α s represent our variational parameters, two in this case. Why does the trial function look like this? How did we get there?

This will be one of our main motivations for switching to Machine Learning later.

To find an ansatz for the correlated part of the wave function, it is useful to rewrite the two-particle local energy in terms of the relative and center-of-mass motion. Let us denote the relative distance between the two electrons as r_{12} . We omit the center-of-mass motion since we are only interested in the case when $r_{12} \rightarrow 0$. The contribution from the center-of-mass (CoM) variable \mathbf{R}_{CoM} gives only a finite contribution. We focus only on the terms

First code attempt for the two-electron case

First, as with the hydrogen case, we declare where to store files.

```
# Common imports
import os

# Where to save the figures and data files
PROJECT_ROOT_DIR = "Results"
FIGURE_ID = "Results/FigureFiles"
DATA_ID = "Results/VMCQdotMetropolis"

if not os.path.exists(PROJECT_ROOT_DIR):
    os.mkdir(PROJECT_ROOT_DIR)

if not os.path.exists(FIGURE_ID):
    os.makedirs(FIGURE_ID)

if not os.path.exists(DATA_ID):
    os.makedirs(DATA_ID)

def image_path(fig_id):
    return os.path.join(FIGURE_ID, fig_id)

def data_path(dat_id):
    return os.path.join(DATA_ID, dat_id)

def save_fig(fig_id):
    plt.savefig(image_path(fig_id) + ".png", format='png')

outfile = open(data_path("VMCQdotMetropolis.dat"), 'w')
```