



FYS4411/9411 March 7

Secant method

Derivative is approximated

$$\hat{f}'(x_k) = \frac{f(x_k) - f(x_{k-1})}{x_k - x_{k-1}}$$

Back to Newton's method

$$x_{k+1} = x_k - \frac{f(x_k)}{\hat{f}'(x_k)} \quad \leftarrow D_\lambda / E(E_\lambda)$$

with secant approx

$$x_{k+1} = x_k - f(x_k) \left( \frac{x_k - x_{k-1}}{f(x_k) - f(x_{k-1})} \right)$$

Newton's method

$$x_{k+1} = x_k - J^{-1}(x_k) f(x_k)$$

Normal not to invert  
but solve

$$J(x_k) s_k = -f(x_k)$$

$$(x_{k+1} = x_k - J^{-1} f(x_k))$$

$$x_{k+1} = x_k + s_k$$

Algorithm

Define  $x_0$  (initial guess)  
and initial Jacobian  $B_0$

For  $K=0$ , Maxiter

Solve  $B_K S_K = -f(x_K)$

$$x_{K+1} = x_K + s_K$$

$$y_K = f(x_{K+1}) - f(x_K)$$

$$B_{K+1} = B_K + \left[ \frac{(y_K - B_K s_K) s_K^T}{s_K^T s_K} \right]$$

end for

$$B_K S_K = -f(x_K)$$

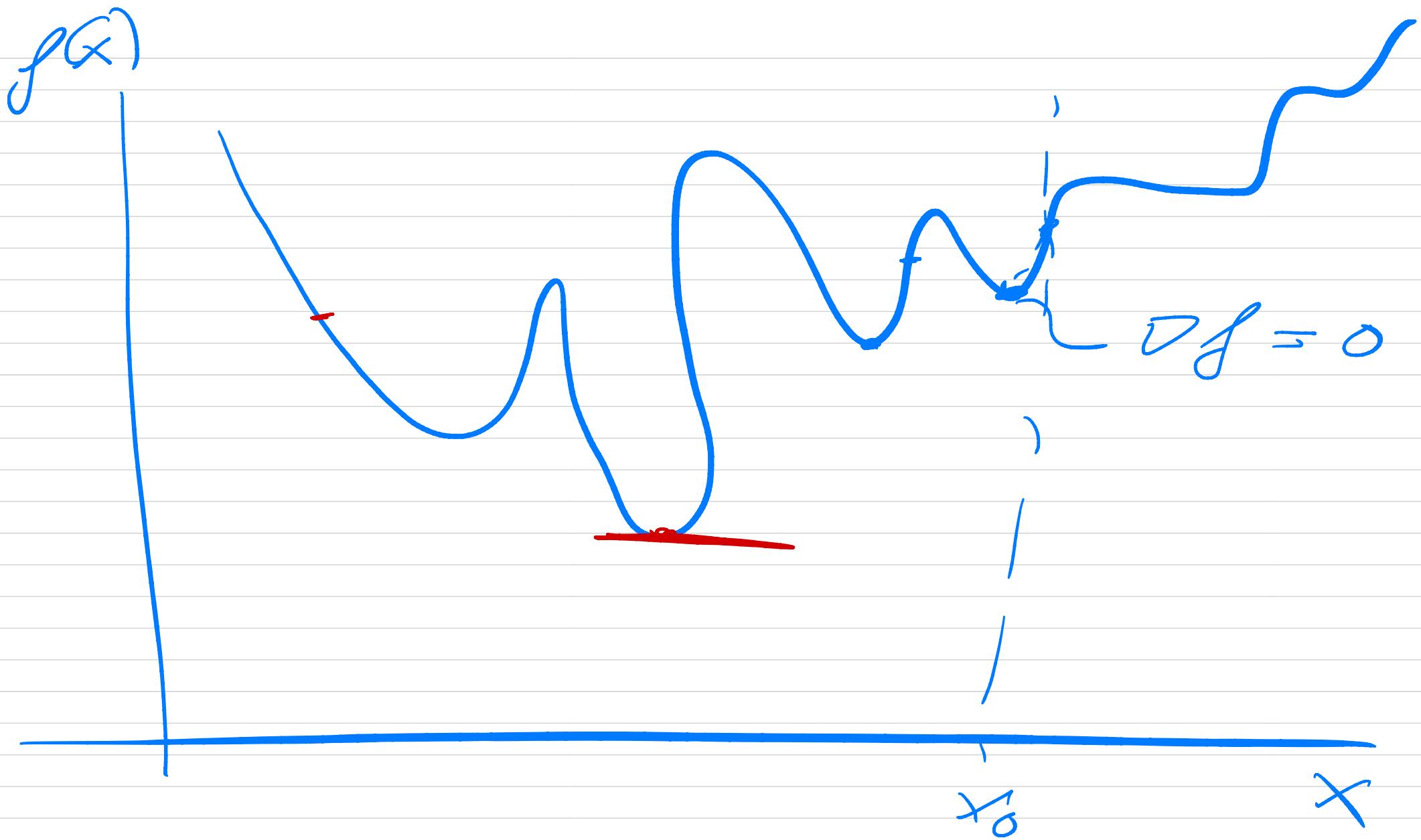
improving GD with momentum

$$\alpha_{k+1} = \alpha_k - \gamma_k \nabla f(\alpha_k)$$

could weight previous iteration with a constant value

$$\alpha_k \rightarrow$$

$$(1-\gamma) \alpha_k + \gamma \alpha_{k-1}$$



# Automatic differentiation

- Not symbolic

$$f(x) = \sqrt{x^2 + \exp x^2} \quad \begin{matrix} 10 \\ \text{FLOPs} \end{matrix}$$

$$f'(x) = \frac{(x + x e^{x^2})}{\sqrt{x^2 + \exp x^2}} \quad \begin{matrix} 4 \text{ FLOPs} \\ 1 \text{ FLOP} \end{matrix}$$

$$\begin{matrix} 2 \text{ FLOPs} \\ \boxed{a = x^2} \end{matrix} \quad \begin{matrix} \sqrt{x^2 + \exp x^2} \\ b = \exp x^2 = \boxed{\exp a} \end{matrix} \quad \begin{matrix} 5 \text{ FLOPs} \\ 1 \text{ FLOP} \end{matrix}$$

$$c = \boxed{a + b} \quad 1 \text{ FLOP}$$

$$d = \boxed{\sqrt{c}} \quad = f(x) : 5 \text{ FLOPs}$$

$$f'(x) = \frac{x + x - b}{d} \quad \begin{matrix} 2 \text{ FLOPs} \\ 1 \text{ FLOP} \end{matrix}$$
$$= 3 \text{ FLOPs}$$

not finite difference

$$\frac{d^2 u(x)}{dx^2} \underset{\approx}{=} \frac{u(x+h) + u(x-h) - 2u(x)}{h^2}$$

AD:

repeated usage of the  
chain rule on simple

functions like  $x, x^2,$   
 $\sin(x), \cos(x), \exp(x) \dots$