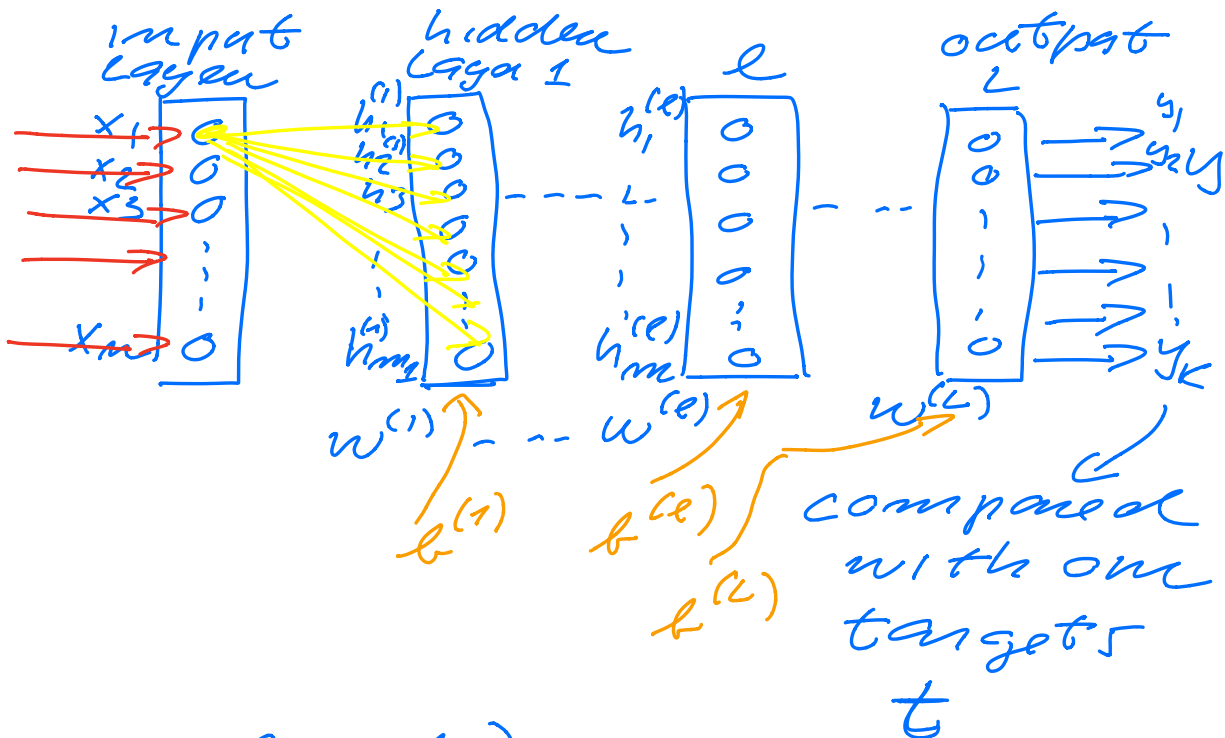


# Lecture January 26

## Neural Network - Feed Forward (FFNN/MLP)

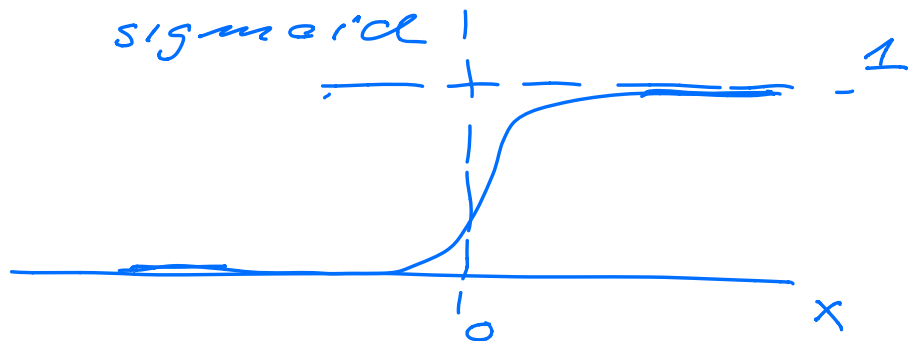


$$C(W, b)$$

- Backpropagation algo to define  $\frac{\partial C}{\partial W}$  and  $\frac{\partial C}{\partial b}$
- Use gradient method to compute new  $W$  and new  $b$ .
- Feed Forward

## Parameter

- activation function



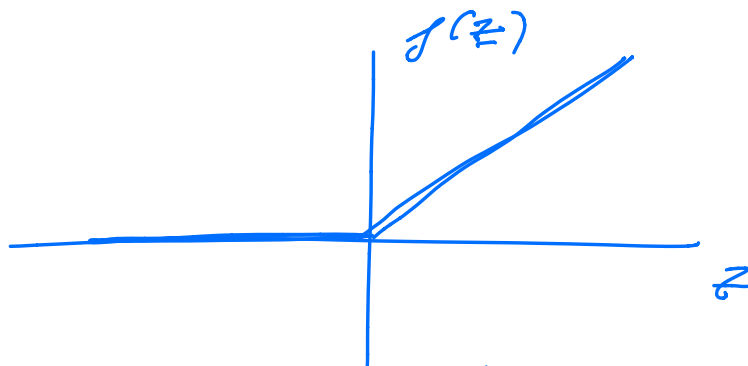
$$\sigma(x) = \frac{1}{1 + e^{-x}}$$

- # hidden layer
- # nodes/neurons
- Various algorithms for gradient descent
  - SGD with momentum
  - ADAM
  - AdaGrad
  - RMS prop
  - !
- Learning rate  $\gamma$
- hyperparameter  $\lambda$   
(shrinkage/regularization)

ReLU = Rectified Linear Unit

$$f(z) = \max(0, z)$$

outputs zero for half of the domain

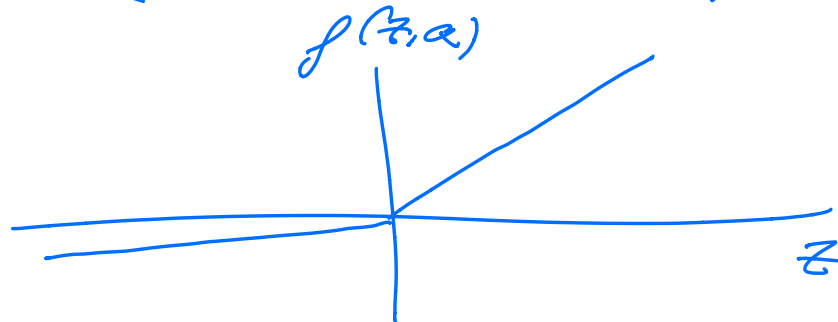


problem when  $z \leq 0$

Leaky ReLU:

$$f(z, \alpha) = \max(0, z) + \alpha \min(0, z)$$

$\alpha \sim 0.01$  (new parameter)



## Convolutional NN (CNN)

- CNNs are NNS that use convolution instead of general matrix multiplication in at least one of the layers.

- convolution:

location of spaceship as function, tracked with a laser sensor  $\rightarrow$  output

$x(t)$ ,  $x, t$  are real-valued, assume that the output is noisy, Focus on recent measurements.

$a$ -parameter  $\sim$  age of measurements, recent measurements are weighted by a function  $w(a)$

$$S(t) = \int x(a) w(t-a) da$$

$\left( = \text{convolution} \right)$

↓ Feature

$$= S(t) = (x * w)(t) \quad \left. \begin{array}{l} \text{Kernel} \\ \text{input} \end{array} \right\}$$

Discrete version:

$$S(t) = (x * w)(t) = \sum_{a=-\infty}^{\infty} x(a) w(t-a)$$

Two dim - image

$$I(k, j) \quad \text{input}$$

$$S(i, j) = (I * K)(i, j) \quad \left. \begin{array}{l} \text{Kernel} \end{array} \right\}$$

$$= \sum_m \sum_n I(m, n) \underbrace{K(i-m, j-n)}_w$$

MNIST

1797 images  
64 features

Input

a	b	c	d
e	f	g	h

Kernel

w	x
y	z

