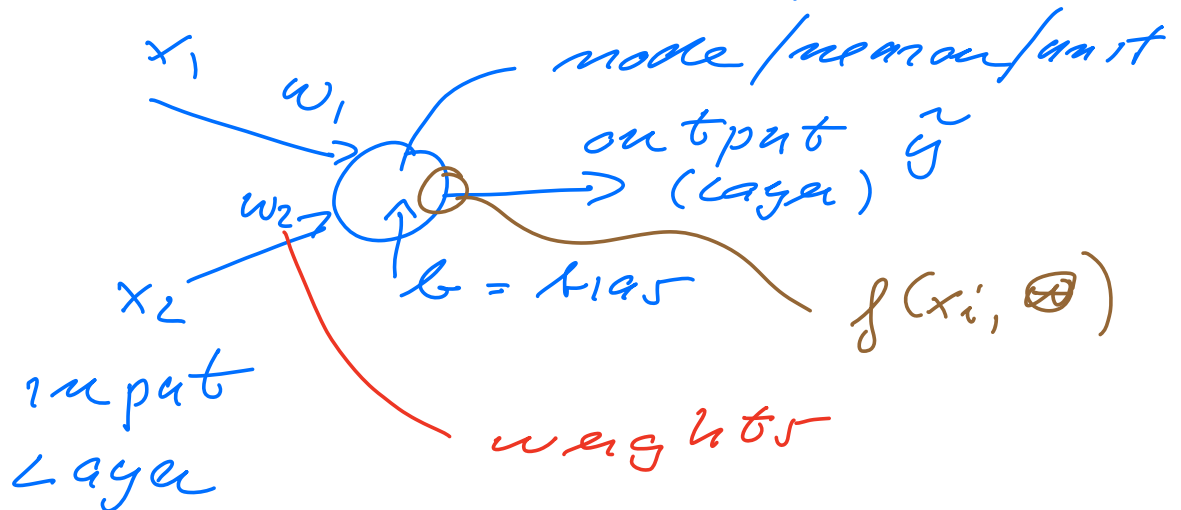


Lecture November 29

Mathematics of feed forward Neural Networks (FFNN) / Multi-Layer Perceptron (MLP)

- Simple perceptron model.
- activation function.



$$\tilde{y}_i = f(x_i; \underbrace{\epsilon}_{\text{activation}}) = w^T x_i + b$$

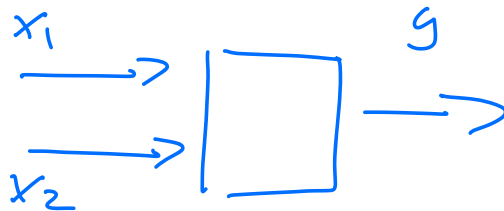
$$\epsilon = \{w, b\} \quad w^T = [w_1, w_2]$$

$$\text{Targets / outputs} \left\{ y_i' \quad (= t_i) \right.$$

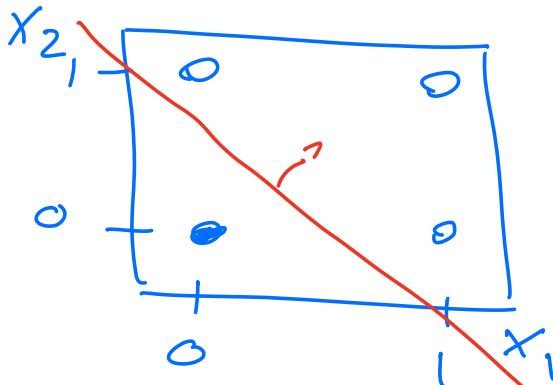
$$D = \{ (x_0, y_0), (x_1, y_1) \dots (x_{n-1}, y_{n-1}) \}$$

Examples : XOR, OR, AND gates

OR-gate



x_1	x_2	y
0	0	0
0	1	1
1	0	1
1	1	1

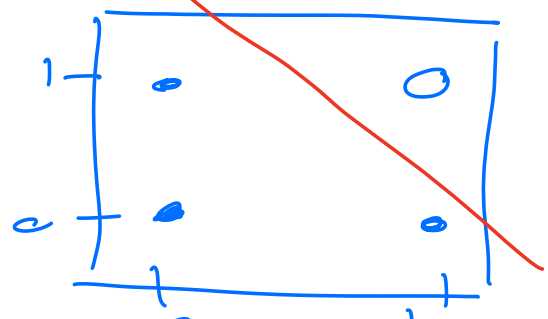


$y = 0$ ●
 $y = 1$ ○

linear reg
 logistic
 reg.

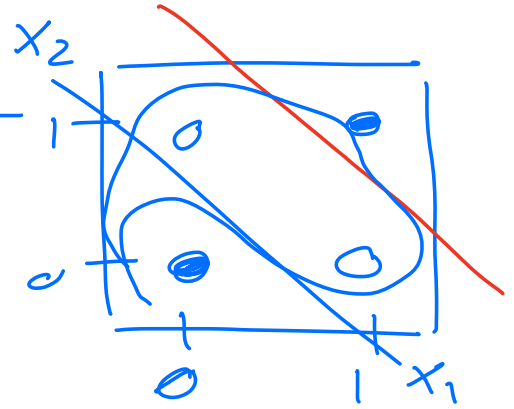
AND-gate

x_1	x_2	y
0	0	0
0	1	0
1	0	0
1	1	1



XOR - Gate

x_1	x_2	y
0	0	0
0	1	1
1	0	1
1	1	0



$$\tilde{y}_i = x_i w_1 + x_i w_2 + \text{intercept}$$

Linear regression

$$X = \begin{bmatrix} 1 & \overset{x_1}{0} & \overset{x_2}{0} \\ 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{bmatrix} \in \mathbb{R}^{4 \times 3}$$

$$\beta \rightarrow \Theta = \begin{bmatrix} b \\ w_1 \\ w_2 \end{bmatrix}$$

$$X^T X = \begin{bmatrix} 4 & 2 & 2 \\ 2 & 2 & 1 \\ 2 & 1 & 2 \end{bmatrix}$$

$$\hat{E} = (X^T X)^{-1} X^T y$$

OK-Gate

$$= [1/4, 1/2, 1/2]^T$$

$$= [1/4, 1/2, 1/2]$$

$$g^2 = \chi E^1 = [1/4, 3/4, 3/4, 5/4]$$

$\tilde{y}^2 \leq 1/2$ then $\tilde{y} = 0$

$\tilde{y} > 1/2$ then $\tilde{y} = 1$

Linear/Logistic one ck

AND gate

$$y = [0, 0, 0, 1]^T$$

$$\hat{y} = [-1/4, 1/4, 1/4, 3/4]^T$$

$y^z \leq 0.5$ then $y^z = 0$

else $g^2 = 1$

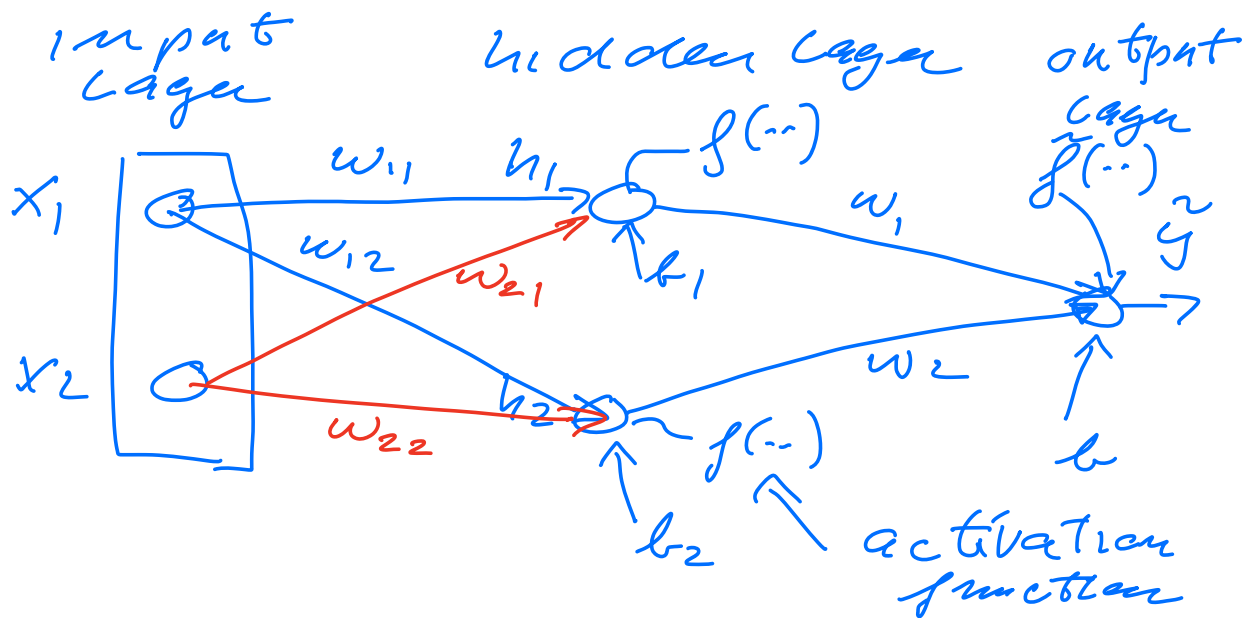
XOR-gate

$$y = [0, 1, 1, 0]^T$$

$$\tilde{y} = \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & \frac{1}{2} & \frac{1}{2} \end{bmatrix}^T$$

... ..

With one hidden layer and two hidden neurons/nodes, we can reproduce the XOR output



Hidden Layer

— # hidden layers

— # neurons in a layer

— W : $w_{12}, w_{11}, w_{21}, w_{22}$

b : b_1, b_2

— activation functions

— output layer

— # output nodes

— activation functions

Universal approximation

theorem:

Given a function $F \in \mathcal{C}([a, 1]^d)$
and a parameter $\varepsilon > 0$,
then there is a one layer
(= 1 hidden layer) neural
network $f(x; W, b)$

with $= f(x; \theta)$
with $W \in \mathbb{R}^{n \times m}$ and
 $b \in \mathbb{R}^m$ for which

$$|f(x; \theta) - F(x)| < \varepsilon$$

for all $x \in [a, 1]^d$ (unit cube)

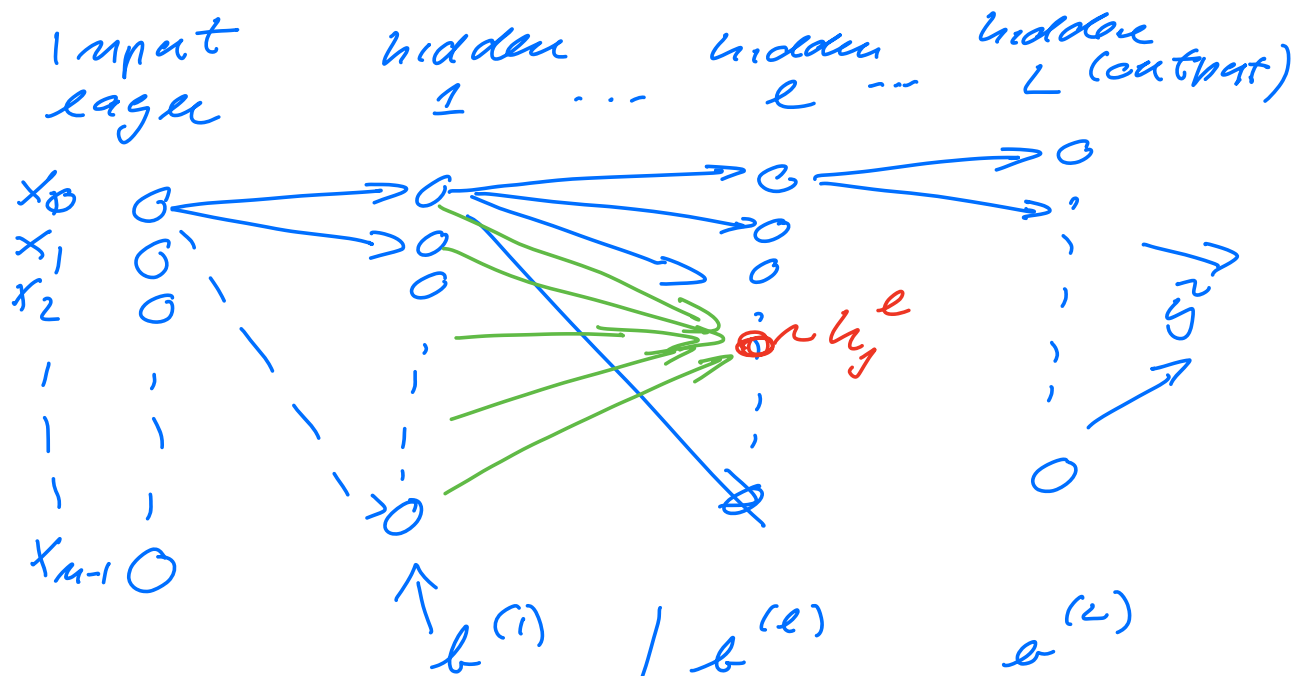
practicalities: How do we
find θ ?

- Back propagation algorithm (chain rule)
 \Rightarrow Gradients to be used
in optimization of
 W and b

Back propagation algorithm

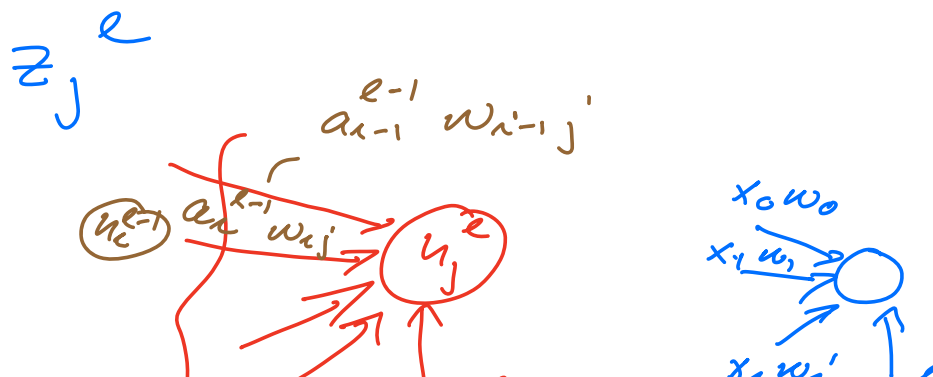
- Regression

$$C(E) = \frac{1}{2} \sum_{i=0}^{n-1} (y_i - \hat{y}_i)^2$$



hidden layer - l -

input to node j :



$$z_j^l = \sum_{i=0}^{M_{l-1}-1} w_{ij}^l a_i^{l-1} + b_j^l \quad z = \sum_i w_i x_i + c$$

\uparrow
 outputs from layer
 $l-1$ and node i

inputs to layer l

$$z^l = (W^l)^T a^{l-1} + b$$

This is modulated by
an activation $f(z_j^l)$

and produces an output

$$a_j^l = f(z_j^l)$$

$$a^l = f(z^l)$$

with two hidden layers

First hidden layer

$$z_j^1 = \sum_i w_{ij}^1 \underset{\uparrow}{x_i} + b_j^1$$

output $a_j^1 = \overset{\text{input}}{\text{layer}} f(z_j^1)$

$$a^1 = f(z^1)$$

2nd hidden = output layer
(last = output)

$$z_j^2 = \sum_i w_{ij}^2 a_i^1 + b_j^2$$

output = $\hat{y} = a^2 = f(z^2)$

3-layers = $f(f(f(z')))$
we have defined

$$a_j^l = f(z_j^l)$$

typical function

$$f(z_j^l) = \frac{1}{1 + \exp(-z_j^l)}$$

we need to define:

$$\partial z_1^l \quad l-1$$

$$\frac{\partial}{\partial w_{ij}^l} = a_i$$

$$\frac{\partial z_j^l}{\partial a_i^{l-1}} = w_{ij}^l$$

$$\begin{aligned} \frac{\partial a_j^l}{\partial z_j^l} &= \frac{\partial f(z_j^l)}{\partial z_j^l} \\ &= f(z_j^l) (1 - f(z_j^l)) \end{aligned}$$

Specialize to output layer $l = L$

my output is $\tilde{y}_i = a_i^L$

$$\begin{aligned} \frac{\partial C(\theta)}{\partial w_{jk}^L} &= \frac{\partial}{\partial w_{jk}^L} \left[\frac{1}{2} \sum_i (\tilde{y}_i - y_i)^2 \right] \\ &= (a_j^L - y_j) \frac{\partial a_j^L}{\partial z_j^L} \end{aligned}$$

chain-rule: $\nwarrow w_{jk}$

$$\frac{\partial a_j^L}{\partial w_{jk}^L} = \frac{\partial a_j^L}{\partial z_j^L} \frac{\partial z_j^L}{\partial w_{jk}^L}$$

$$= a_j^L (1 - a_j^L) a_k^{L-1}$$

$$\frac{\partial C(e)}{\partial w_{jk}^L} = (a_j^L - y_j)(1 - a_j^L) \times a_k^{L-1} a_j^L$$

Define:

$$\delta_j^L = \underbrace{a_j^L (1 - a_j^L)}_{f'(z_j^L)} \frac{\partial C}{\partial a_j^L}$$

$$\boxed{\frac{\partial C}{\partial a_k^L} = \delta_1^L a_k^{L-1}}$$

$$\frac{\partial C}{\partial w_{jk}}$$

$$\delta_j^L = \frac{\partial C}{\partial z_j^L} = \frac{\partial C}{\partial a_j^L} \frac{\partial a_j^L}{\partial z_j^L}$$

$$\delta_j^L = \frac{\partial C}{\partial b_j^L}$$

$$\frac{\partial C}{\partial w_{jk}^L} = \delta_j^L a_k^{L-1}$$

$$\delta_j^L = f'(z_j^L) \frac{\partial C}{\partial a_j^L}$$

$$\delta_j^L = \frac{\partial C}{\partial b_j^L}$$

all for final layer.

Need to Back propagate

$L \rightarrow l$

$$\delta_j^l = \frac{\partial C}{\partial z_j^l} =$$

$l+1$

$$\sum_k \frac{\partial C}{\partial z_k^{l+1}} \frac{\partial z_k^{l+1}}{\partial z_j^l}$$

$$= \sum_k \delta_k^{l+1} \frac{\partial z_k^{l+1}}{\partial z_j^l}$$

$$z_j^{l+1} = \sum_i w_{ij}^{l+1} \underline{a_i^l} + b_j^{l+1}$$

$$\underline{f(z_i^l)}$$

$$\frac{\partial z_k^{l+1}}{\partial z_j^l} = w_{kj}^{l+1} f'(z_j^l)$$

$$\delta_j^l = \sum_k \delta_k^{l+1} w_{kj}^{l+1} f'(z_j^l)$$

Now can set up gradients for each layer:

$$l = L-1, L-2, \dots, 1$$

$$w_{jk}^l \leftarrow w_{jk}^l - \eta \delta_j^l a_k^{l+1}$$

$$b_j^e \leftarrow b_j^e - \eta \frac{\partial C}{\partial b_j^e}$$

$$= b_j^e - \eta \delta_j^e$$