

FYS 5419, MARCH 27, 2023

$$H = \begin{bmatrix} H_{11} & H_{12} \\ H_{21} & H_{22} \end{bmatrix}$$

Basis states $|0\rangle = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

$$|1\rangle = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$H = H_0 + H_1$$

$$H_0 |0\rangle = \epsilon_0 |0\rangle$$

$$H_0 |1\rangle = \epsilon_1 |1\rangle$$

$$\epsilon = \frac{\epsilon_0 + \epsilon_1}{2} \quad \Omega = \frac{\epsilon_0 - \epsilon_1}{2}$$

$$H_0 = \epsilon \mathbb{I} + \Omega \sigma_z$$

$$\sigma_z = z \quad \sigma_y = y \quad \sigma_x = x$$

$$H_0 = \begin{bmatrix} \epsilon_0 & 0 \\ 0 & \epsilon_1 \end{bmatrix}$$

$$z = \sigma_z = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$$

$$H_1 = \begin{bmatrix} V_{11} & V_{12} \\ V_{21} & V_{22} \end{bmatrix}$$

$$C = \frac{V_{11} + V_{22}}{2} \quad \omega_z = \frac{(V_{11} - V_{22})}{2}$$

$$\omega_x = \omega_z = \omega$$

$$H_I = cI + \omega_z Z + \omega_x X$$

$$X = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, Y = \begin{bmatrix} 0 & -i \\ i & 0 \end{bmatrix}$$

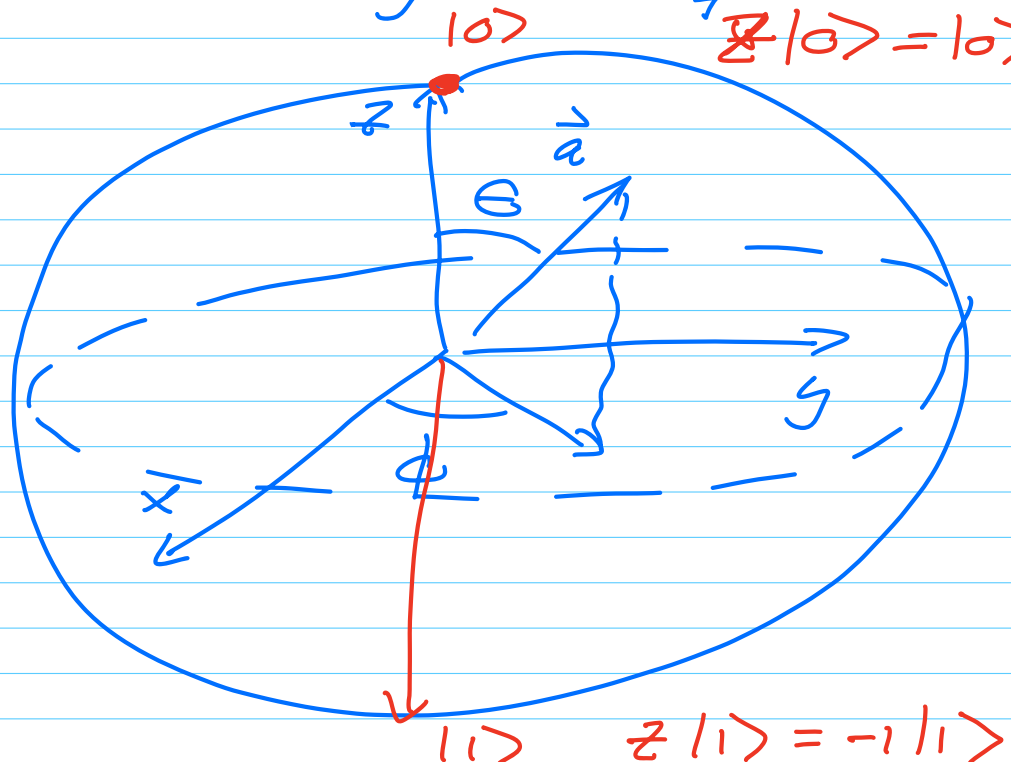
$$I^2 = I = XX = YY = Z \cdot Z$$

$$|0\rangle \rightarrow [R_x(\theta)] \rightarrow [R_y(\phi)] \rightarrow |\psi\rangle$$

$$|\psi\rangle = R_y(\phi) R_x(\theta) |0\rangle$$

ansatz.

Block sphere can represent an arbitrary one-qubit state



Every qubit system can be visualized as a point on a 3dim sphere with radius 1 (r) and angles ϕ and θ

$$|\psi\rangle = \cos\left(\frac{\theta}{2}\right)|0\rangle + e^{i\phi}\sin\left(\frac{\theta}{2}\right)|1\rangle$$

Rotation matrices

$$\begin{aligned} R_x(\theta) &= e^{i\theta/2}X \\ &= \begin{bmatrix} \cos\frac{\theta}{2} & -i\sin\frac{\theta}{2} \\ -i\sin\frac{\theta}{2} & \cos\frac{\theta}{2} \end{bmatrix} \end{aligned}$$

$$= \cos\left(\frac{\theta}{2}\right)\mathbb{I} - i\sin\frac{\theta}{2}X$$

$$R_y(\theta) = \cos\left(\frac{\theta}{2}\right)\mathbb{I} - i\sin\frac{\theta}{2}Y$$

$$R_z(\theta) = \begin{bmatrix} e^{-i\theta/2} & 0 \\ 0 & e^{i\theta/2} \end{bmatrix}$$

with $|\psi\rangle$, we will evaluate

$$\langle\psi_T|H|\psi_T\rangle =$$

$$\begin{aligned} \langle\psi_T|(\varepsilon+c)\mathbb{I} + (\Omega+W_z)Z \\ + W_x X |\psi_T\rangle = E_T \end{aligned}$$

From the variational principle

$$E_T \geq E_0 \text{ (exact lowest state)}$$

$|0\rangle$ and $|1\rangle$

$$|4\rangle = R_y(\phi) R_x(\epsilon) |0\rangle$$

$$H|0\rangle = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$= \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix} =$$

$$\frac{1}{\sqrt{2}} (|0\rangle + |1\rangle)$$

$$H|1\rangle = \frac{1}{\sqrt{2}} (|0\rangle - |1\rangle)$$

$$R_y(\phi) R_x(\epsilon) |0\rangle =$$

$$\alpha(\phi) \beta(\epsilon) |0\rangle +$$

$$\delta(\phi) \chi(\epsilon) |1\rangle$$

$$X = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$
$$= \frac{1}{2} \begin{bmatrix} 0 & 2 \\ 2 & 0 \end{bmatrix} =$$

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} = X$$

$$\hat{H} = \alpha I + \beta Z + \gamma X$$

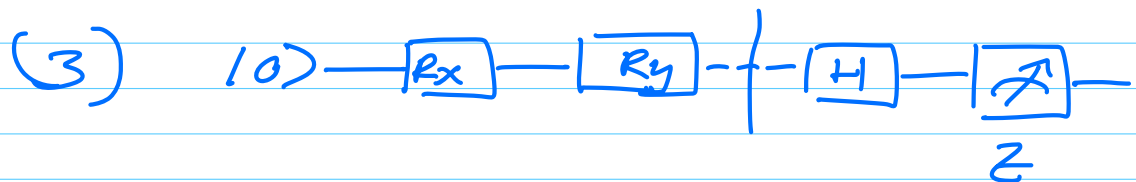
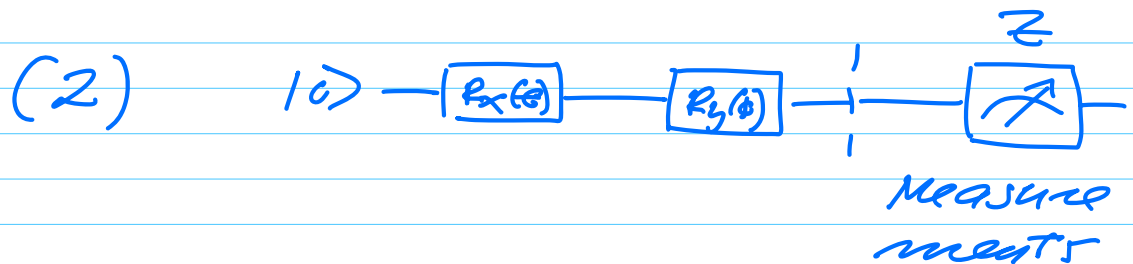
$$= \alpha \mathbb{I} + \beta Z + \gamma HZH$$

$$\langle \psi_T | \hat{H} | \psi_T(\phi, \epsilon) \rangle = \langle \psi_T | \hat{H} | \psi_T \rangle$$

$$= \alpha \langle \psi_T | \mathbb{I} | \psi_T \rangle \quad (1)$$

$$+ \beta \langle \psi_7 | \hat{z} | \psi_4 \rangle \quad (2)$$

$$+ \gamma \langle \psi_T | H | \psi_T \rangle \quad (3)$$



$$R_x(G)|a\rangle =$$

$$\left(\cos(\theta/2) \underline{\Pi} - i \sin(\theta/2) X \right) |0\rangle$$

$$\cos \frac{\theta}{2} |0\rangle - i \sin \frac{\theta}{2} |1\rangle$$

$$\times |0\rangle = |1\rangle$$

$$R_y(\phi) = \cos(\phi/2) \mathbb{I} - i \sin \phi/2 \gamma$$

$$R_y(\phi) R_x(\theta) |0\rangle$$

$$\cos \frac{\theta}{2} \cos \frac{\phi}{2} \mathbb{I} |0\rangle$$

$$- \cos \frac{\phi}{2} \mathbb{I} \times (i \sin \frac{\theta}{2}) |1\rangle$$

$$- i \sin \frac{\phi}{2} \gamma \cos \frac{\theta}{2} |0\rangle$$

$$- \sin \frac{\theta}{2} \cdot \sin \frac{\phi}{2} \gamma |1\rangle$$

$$= (\cos \frac{\theta}{2} \cos \frac{\phi}{2}) |0\rangle$$

$$- (\cos \frac{\phi}{2} i \sin \frac{\theta}{2}) |1\rangle$$

$$+ \sin \frac{\phi}{2} \cos \frac{\theta}{2} |1\rangle$$

$$- i \sin \frac{\theta}{2} \sin \frac{\phi}{2} |0\rangle$$

Two-qubit case

$$Z_2 \otimes I_{2 \times 2} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

in the Lipkin model

$\sum_{j=1}^N \sigma_j^z \tau_j^z$ acts only on
one qubit at the time,

In general when doing a
measurement we need the
following expression

$$U^\dagger (Z \otimes I) U$$

For $Z \otimes I$ $U = I \otimes I$

$$X_i X_j \quad \text{and} \quad Y_i Y_j$$

$$XX = X \otimes X \quad YY = Y \otimes Y$$

$$Z \cdot Z = Z \otimes Z$$

$Z \otimes Z$: $U = CX_{10}$

$$CX_{10} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{bmatrix}$$

XX has $U = CX_{10}(H \otimes H)$

$$XX = U^\dagger (Z \otimes Z) U$$

YY has $U = CX_{10} \underbrace{(HS \otimes HS)}_{\text{ex2}}^\dagger$

$$S = \begin{bmatrix} 1 & 0 \\ c & i \end{bmatrix}$$