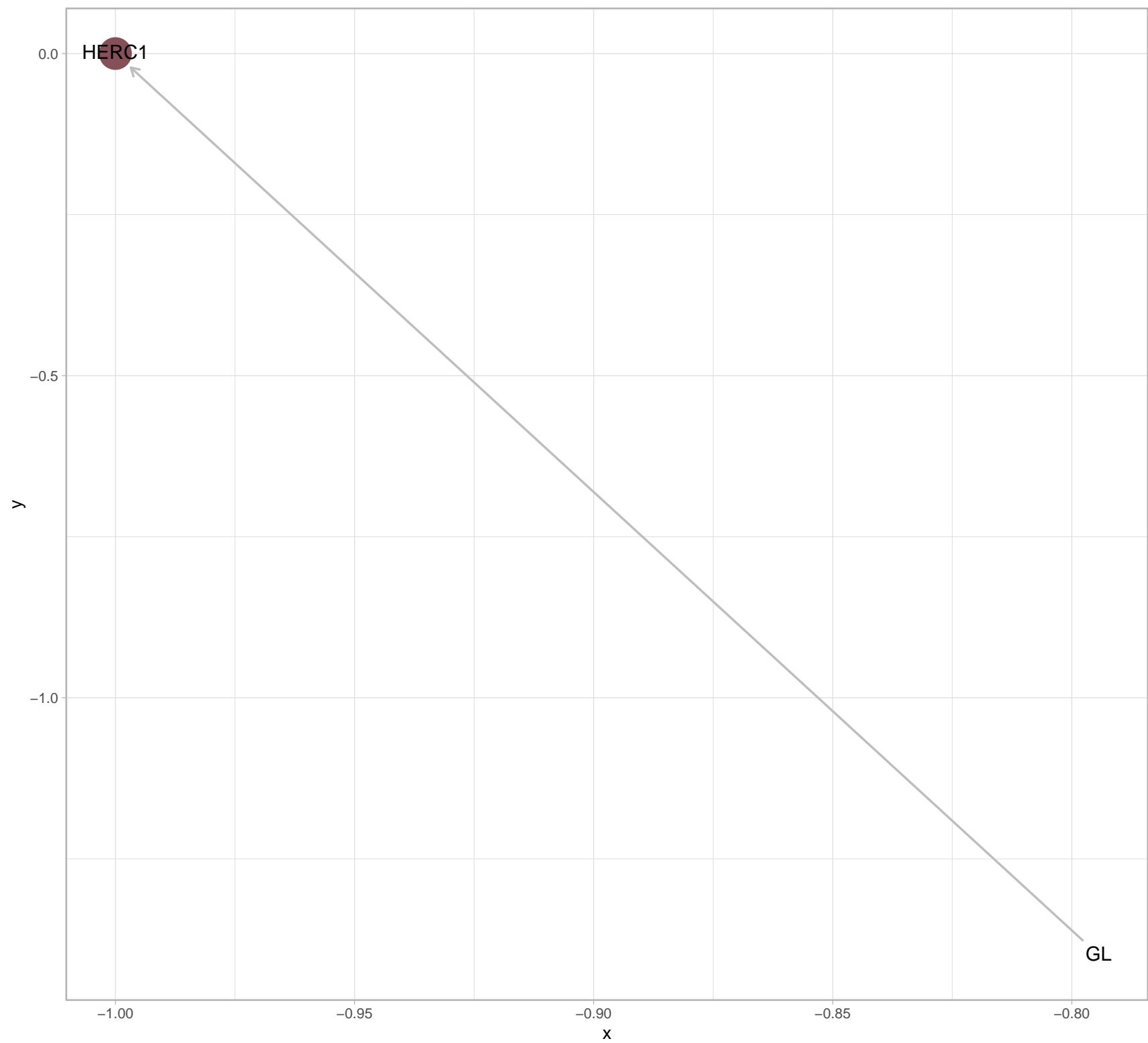


# Driver to driver trajectories



DET index ● 0

Driver counts ● 2

Penalty ➤ 1

Significant enrichment at level 0.05 ➤ FALSE