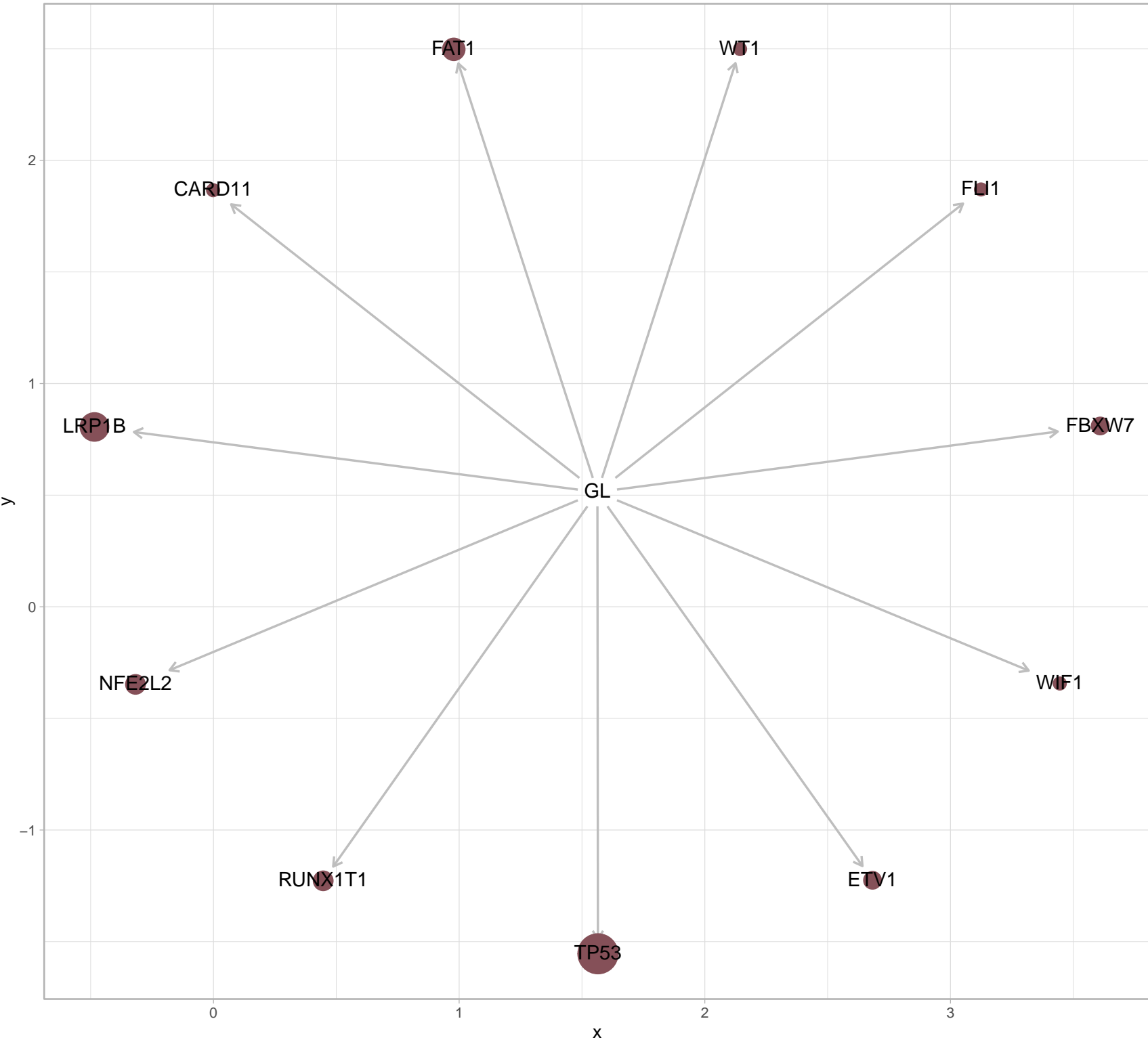


Driver to driver trajectories



Driver counts    10    20    30    DET index    0    Penalty    1    Significant enrichment at level 0.05    FALSE