Stochastic Variational Inference

Practice

Gaussian Processes for Big Data

Variational inducing variables:

$$p(\mathbf{y} \mid \mathbf{f}) = \mathcal{N} \left(\mathbf{y} \mid \mathbf{f}, \beta^{-1} \mathbf{I} \right),$$

$$p(\mathbf{f} \mid \mathbf{u}) = \mathcal{N} \left(\mathbf{f} \mid \mathbf{K}_{nm} \mathbf{K}_{mm}^{-1} \mathbf{u}, \widetilde{\mathbf{K}} \right),$$

$$p(\mathbf{u}) = \mathcal{N} \left(\mathbf{u} \mid \mathbf{0}, \mathbf{K}_{mm} \right),$$

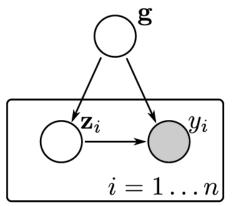
Marginal likelihood:

$$\log p(\mathbf{y} \mid \mathbf{X}) = \log \int p(\mathbf{y} \mid \mathbf{u}) p(\mathbf{u}) d\mathbf{u}$$
$$\geq \log \int \exp \{\mathcal{L}_1\} p(\mathbf{u}) d\mathbf{u} \triangleq \mathcal{L}_2,$$

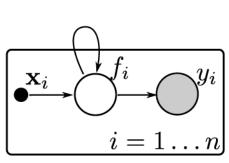
Lower bound:

$$\mathcal{L}_{2} = \log \mathcal{N} \left(\mathbf{y} | \mathbf{0}, \mathbf{K}_{nm} \mathbf{K}_{mm}^{-1} \mathbf{K}_{mn} + \beta^{-1} \mathbf{I} \right) - \frac{1}{2} \beta \operatorname{tr} \left(\widetilde{\mathbf{K}} \right)$$

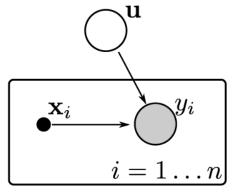
Gaussian Processes for Big Data







(b) Gaussian Process regression



(c) Variational GP regression

• Let u be the global variable with q(u) = N(m; S), leave m and S!

$$\log p(\mathbf{y} \mid \mathbf{X}) \ge \langle \mathcal{L}_1 + \log p(\mathbf{u}) - \log q(\mathbf{u}) \rangle_{q(\mathbf{u})} \triangleq \mathcal{L}_3.$$

$$\mathcal{L}_{3} = \sum_{i=1}^{n} \left\{ \log \mathcal{N} \left(y_{i} | \mathbf{k}_{i}^{\top} \mathbf{K}_{mm}^{-1} \mathbf{m}, \beta^{-1} \right) - \frac{1}{2} \beta \widetilde{k}_{i,i} - \frac{1}{2} \operatorname{tr} \left(\mathbf{S} \mathbf{\Lambda}_{i} \right) \right\} - \operatorname{KL} \left(q(\mathbf{u}) \parallel p(\mathbf{u}) \right)$$

Stochastic Variational Inference for Hidden Markov Models

Joint distribution

$$p(\mathbf{x}, \mathbf{y}) = \pi_0(x_1)p(y_1|x_1) \prod_{t=2}^{T} p(x_t|x_{t-1}, A)p(y_t|x_t, \phi)$$

Structured mean field

$$q(\theta, \mathbf{x}) = q(A)q(\phi)q(\mathbf{x})$$

Lower bound

$$\ln p(\mathbf{y}) \ge E_q \left[\ln p(\theta) \right] - E_q \left[\ln q(\theta) \right] + E_q \left[\ln p(\mathbf{y}, \mathbf{x} | \theta) \right] - E_q \left[\ln q(\mathbf{x}) \right] := \mathcal{L}(q(\theta), q(\mathbf{x}))$$

If non-sequential

$$\mathcal{L} = E_{q(\theta)} \left[\ln p(\theta) \right] - E_{q(\theta)} \left[\ln q(\theta) \right] + \sum_{i=1}^{T} E_{q(x_i)} \left[\ln p(y_i, x_i | \theta) \right] - E_{q(\mathbf{x})} \left[\ln q(\mathbf{x}) \right]$$

Stochastic Variational Inference for Hidden Markov Models

Objective:

$$\ln p(\mathbf{y}) \ge E_q \left[\ln p(\theta) \right] - E_q \left[\ln q(\theta) \right] + E_q \left[\ln p(\mathbf{y}, \mathbf{x} | \theta) \right] - E_q \left[\ln q(\mathbf{x}) \right] := \mathcal{L}(q(\theta), q(\mathbf{x}))$$

• For HMM, sample subchains $y^S = (y_1^S, ..., y_L^S)$, and decompose the lower bound: $\frac{T}{\ln p(y, y|\theta) = \ln \pi(x_1) + \sum_{l=1}^{T} \ln p(y_l|\theta)}$

$$\ln p(\mathbf{y}, \mathbf{x} | \theta) = \ln \pi(x_1) + \sum_{t=2}^{T} \ln A_{x_{t-1}, x_t} + \sum_{i=1}^{T} \ln p(y_t | x_t).$$

global update

$$E_{S}\left[E_{q} \ln p(\mathbf{y}^{S}, \mathbf{x}^{S} | \theta)\right] \approx p(S)E_{q} \left[\sum_{t=1}^{T-L+1} \ln \pi(x_{t}) + (L-1) \sum_{t=2}^{T} \ln A_{x_{t-1}, x_{t}} + L \sum_{t=1}^{T} p(y_{t} | x_{t})\right]$$

local update

$$q^*(\mathbf{x}^S) \propto \exp\left(E_{q(A)}\left[\ln \pi(x_1^S)\right] + \sum_{\ell=2}^L E_{q(A)}\left[\ln A_{x_{\ell-1}^S, x_{\ell}^S}\right] + \sum_{\ell=1}^L E_{q(\phi)}\left[\ln p(y_{\ell}^S | x_{\ell}^S)\right]\right)$$

Stochastic Variational Inference for Hidden Markov Models

• Improvements: Buffering subchains

return $q^*(\mathbf{x}^S) = q^{\text{new}}(\mathbf{x}^S)$

Set $S^{\text{old}} = S^{\text{new}}$ and $q^{\text{old}} = q^{\text{new}}$.

end if

10: end while

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Algorithm 2 GrowBuf procedure.

1: Input: subchain S, min buffer length u \in \mathbb{Z}_+, error tolerance \epsilon > 0.

2: Initialize q^{\text{old}}(\mathbf{x}^S) = \text{ForwardBackward}(\mathbf{y}^S, \hat{\pi}, \widetilde{A}, \widetilde{p}_S) and set S^{\text{old}} = S.

3: while true do

4: Grow buffer S^{\text{new}} by extending S^{\text{old}} by u observations in each direction.

5: q^{\text{new}}(\mathbf{x}^{S^{\text{new}}}) = \text{ForwardBackward}(\mathbf{y}^{S^{\text{new}}}, \hat{\pi}, \widetilde{A}, \widetilde{p}_{S^{\text{new}}}), reusing messages from S^{\text{old}}.

6: if ||q^{\text{new}}(\mathbf{x}^S) - q^{\text{old}}(\mathbf{x}^S)|| < \epsilon then
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