

# Introduction to Communications and IOT

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## 1 Introduction

### 1.1 What a Signal is

- It's a Quantitative Representation of Information
- The most basic representation of a signal is in the form of a graph ( $t$  on X-axis and  $f(t)$  on Y-axis )

### 1.2 Types of Communication

#### 1.2.1 Wired / Wireless

##### 1. Wired:

- Via Coaxial cables or Fibre-Optic Cables

##### 2. Wireless:

- Via Electromagnetic waves or rays

### 1.2.2 Unidirectional / Bidirectional

#### 1. Simplex:

- One-way
- Eg. Broadcast, FM

#### 2. Half-Duplex:

- Two-way, but only one direction at a time
- Eg. walkie-talkie

#### 3. Duplex:

- Two-way, and both directions are simultaneously possible

### 1.2.3 Analogue / Digital

#### 1. Analog:

- Both  $t$  and  $f(t)$  are continuous

#### 2. Digital:

- Both  $t$  and  $f(t)$  are discrete

#### 3. Continuous-Time:

- $t$  is continuous, but  $f(t)$  is discrete

#### 4. Discrete-Time:

- $t$  is discrete and  $f(t)$  is continuous

### 1.2.4 Transmission Technique

Before knowing this, you must know what bandwidth is:

**Bandwidth:**

- Range of frequencies a signal operates.
- In other words:

$$\text{Bandwidth} = (\text{Highest Frequency of the Wave/Signal}) - (\text{Lowest Frequency of the Wave/Signal})$$

#### 1. Baseband:

- Digital Signals which are sent via TDM (Time Division Multiplexing)
- One signal uses the entire bandwidth

#### 2. Broadband:

- (I'll add this later)

## 2 Characteristics of a Signal

### 2.1 Standard Notation of a Standard Sinusoidal Signal

- For a graph where X-axis =  $\theta$  and Y-axis =  $\sin(\theta)$ , the measure of input is  $\theta$ .
- To actually measure a signal against time, X-axis =  $t$  (time) and Y-axis =  $\sin(\theta)$
- Here's what we do for that:  $\sin(\theta + \phi) = \sin(\omega t + \phi)$

### 2.2 Angular Frequency

- $\omega$  = Angular Frequency/Velocity
- =  $\frac{\text{Angle}}{\text{Time}}$
- =  $\frac{2\pi}{T}$

### 2.3 Frequency

- $f = \frac{1}{T}$
- So,  $\omega = \frac{2\pi}{T}$  can also be written as  $\omega = 2\pi f$

### 2.4 Phase

- $\theta$  or  $\omega t$  is the X-coordinate.
- Phase  $\phi$  is added to the X-coordinate, so the wave shifts to the left by  $\phi$
- In a way, it's an offset to a wave. (Check <https://www.geogebra.org/m/rzzqtx6q> for some Visualization)
- For example, if a sine wave is offset by  $\frac{1}{6}th$  of a cycle, then the phase would be  $\frac{1}{6} * 360^\circ \Rightarrow \text{Phase} = 60^\circ$

## 3 Time Domain vs Frequency Domain

In both cases, Y-Axis = *Amplitude*. Only X-Axis changes

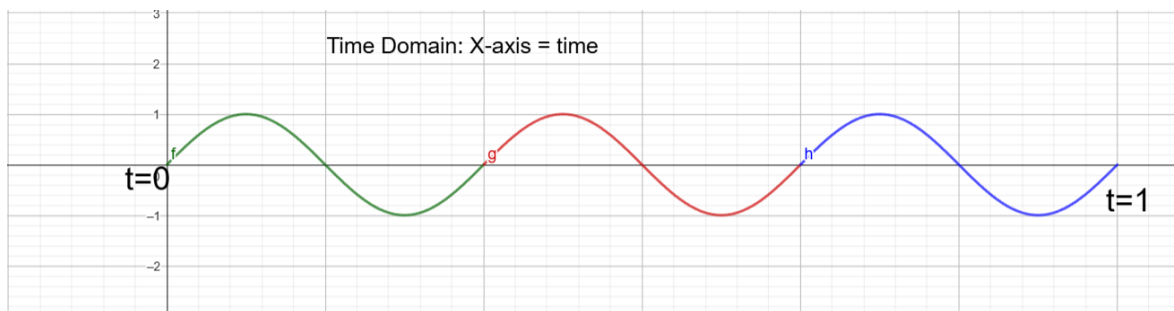


Figure 1: Time Domain

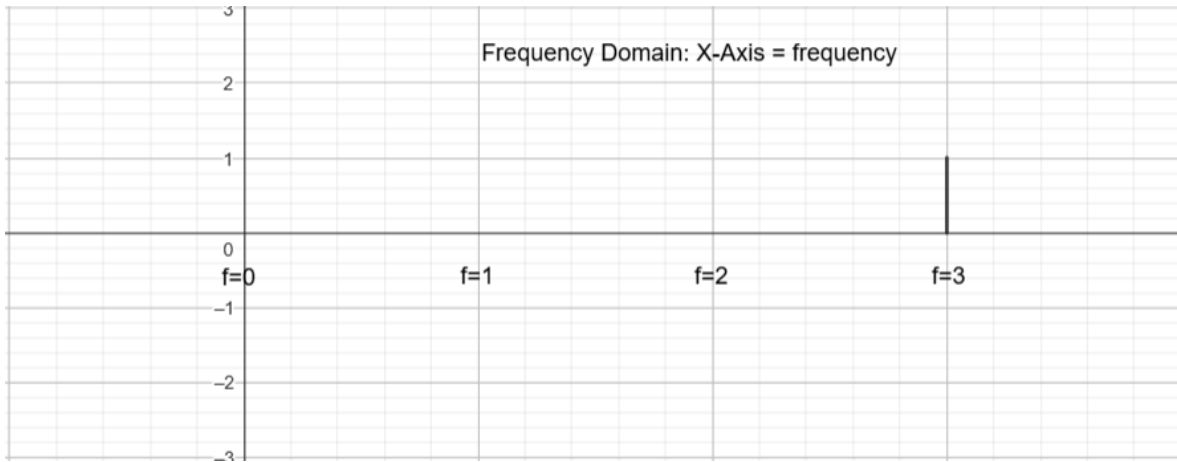


Figure 2: Frequency Domain

## 4 Odd Signals vs Even Signals

- **Odd Signals/Functions:**  $y(-x) = -y(x)$
- **Even Signals/Functions:**  $y(-x) = y(x)$

## 5 Energy and Power of a Signal

### 5.1 Prerequisite knowledge

- Let's assume we have a sinusoidal voltage and current
- $P = \frac{V^2}{R} = I^2 R$
- This means that the power of a signal is some **constant** times **voltage squared** or **current squared**
- Let us have a general signal  $x(t)$  which can either be sinusoidal voltage or sinusoidal current

$$x(t) = V \text{ or } x(t) = I$$

- So Instantaneous Power =  $P = (x(t))^2$

### 5.2 Energy

- Energy = Power \* time
- But the above formula is only applicable for discrete values.
- So the energy of a signal would be the area of the Power-Time Graph

$$\text{Energy} = \int P dt = \int_{-\frac{T}{2}}^{\frac{T}{2}} (x(t))^2 dt$$

- The limits are actually from 0 to  $T$ , but having them from  $-\frac{T}{2}$  to  $\frac{T}{2}$  simplifies calculations.

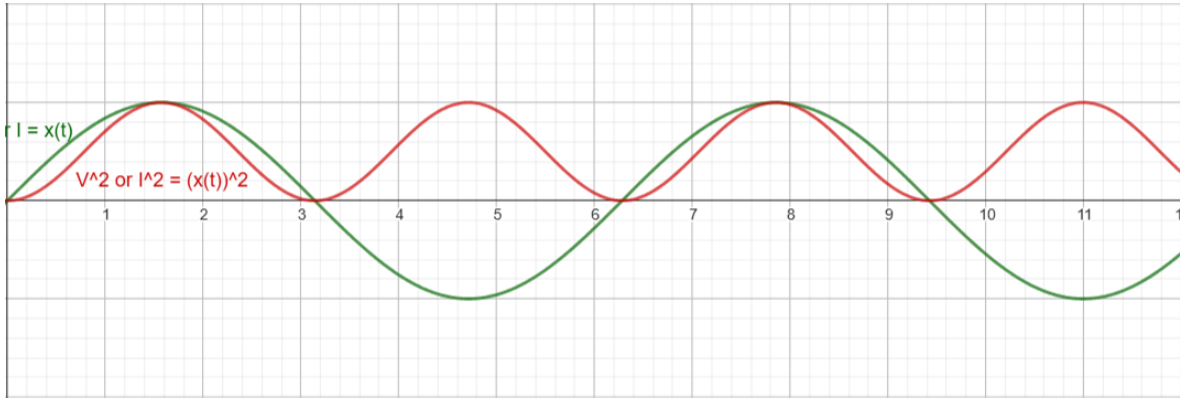


Figure 3: Green Curve showing V or I and the Red Curve showing P

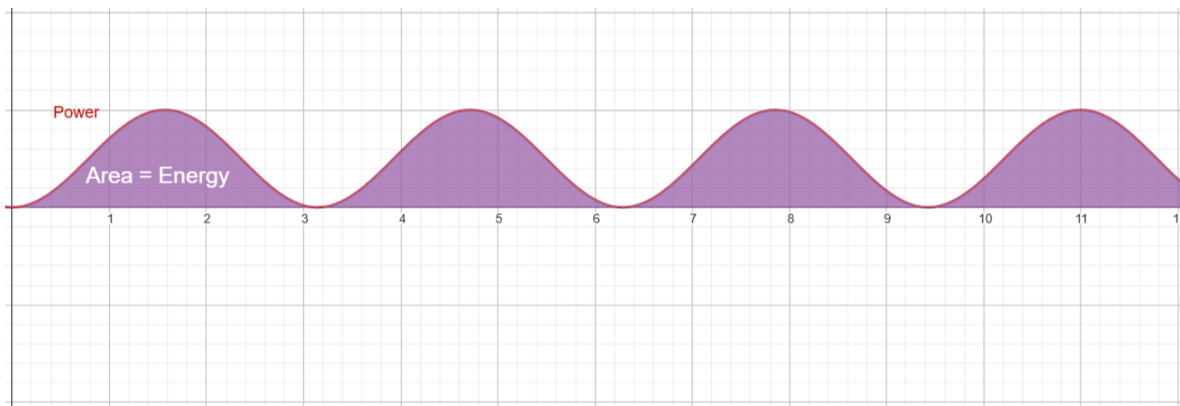


Figure 4: Area under the Red Curve

### 5.3 Power

- Power is just  $\frac{\text{Energy}}{\text{Time}}$ .
- Power =  $\frac{\int_{-\frac{T}{2}}^{\frac{T}{2}} (x(t))^2 dt}{T}$