
MATH96023/MATH97032/MATH97140 - Computational Linear Algebra

Edition 2020.0

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PRELIMINARIES

In this preliminary section we revise a few key linear algebra concepts that will be used in the rest of the course, emphasising the column space of matrices.

1.1 Matrices, vectors and matrix-vector multiplication

We will consider the multiplication of a vector

$$x = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}, \quad x_i \in \mathbb{C}, i = 1, 2, \dots, n, \text{ i.e. } x \in \mathbb{C}^n,$$

by a matrix

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix},$$

i.e. $A \in \mathbb{C}^{m \times n}$. A has m rows and n columns so that the product

$$b = Ax$$

produces $b \in \mathbb{C}^m$, defined by

$$b_i = \sum_{j=1}^n a_{ij}x_j, \quad i = 1, 2, \dots, m.$$

In this course it is important to consider the general case where $m \neq n$, which has many applications in data analysis, curve fitting etc. We will usually state generalities in this course for vectors over the field \mathbb{C} , noting where things specialise to \mathbb{R} .

We can quickly check that the map $x \rightarrow Ax$ given by matrix multiplication is a linear map from $\mathbb{C}^n \rightarrow \mathbb{C}^m$, since it is straightforward to check from the definition that

$$A(\alpha x + y) = \alpha Ax + Ay,$$

for all $x, y \in \mathbb{C}^n$ and $\alpha \in \mathbb{C}$. (Exercise: show this for yourself.)

It is very useful to interpret matrix-vector multiplication as a linear combination of the columns of A with coefficients taken from the entries of x . If we write A in terms of the columns,

$$A = (a_1 \quad a_2 \quad \dots \quad a_n),$$

where

$$a_i \in \mathbb{C}^m, \quad i = 1, 2, \dots, n,$$

then

$$b = \sum_{j=1}^n x_j a_j,$$

i.e. a linear combination of the columns of A as described above.

We can extend this idea to matrix-matrix multiplication. Taking $A \in \mathbb{C}^{l \times m}$, $C \in \mathbb{C}^{m \times n}$, $B \in \mathbb{C}^{l \times n}$, with $B = AC$, then the components of B are given by

$$b_{ij} = \sum_{k=1}^m a_{ik} c_{kj}, \quad 1 \leq i \leq l, \quad 1 \leq j \leq n.$$

Writing $b_j \in \mathbb{C}^m$ as the j th column of B , for $1 \leq j \leq n$, and c_j as the j th column of C , we see that

$$b_j = A c_j.$$

This means that the j th column of B is the matrix-vector product of A with the j th column of C . This kind of “column thinking” is very useful in understanding computational linear algebra algorithms.

An important example is the outer product of two vectors, $u \in \mathbb{C}^m$ and $v \in \mathbb{C}^n$. Here it is useful to see these vectors as matrices with one column, i.e. $u \in \mathbb{C}^{m \times 1}$ and $v \in \mathbb{C}^{n \times 1}$. The outer product is $uv^T \in \mathbb{C}^{m \times n}$. The columns of v^T are just single numbers (i.e. vectors of length 1), so viewing this as a matrix multiplication we see

$$uv^T = (uv_1 \quad uv_2 \quad \dots \quad uv_n),$$

which means that all the columns of uv^T are multiples of u . We will see in the next section that this matrix has rank 1.

1.2 Range, nullspace and rank

In this section we’ll quickly rattle through some definitions and results.

Definition 1 (Range) The range of A , $\text{range}(A)$, is the set of vectors that can be expressed as Ax for some x .

The next result follows directly from the column interpretation of matrix-vector multiplication.

Theorem 2 The range of A is the vector space spanned by the columns of A .

Definition 3 (Nullspace) The nullspace of A , $\text{null}(A)$, is the set of vectors $x \in \mathbb{C}^n$ such that $Ax = 0$.

Definition 4 (Rank) The rank of A , $\text{rank}(A)$, is the dimension of the column space of A , i.e. $\text{span}(a_1, a_2, \dots, a_n)$ where

$$A = \begin{pmatrix} a_1 & a_2 & \dots & a_n \end{pmatrix}.$$

Hence, we now understand why the outer product uv^T is rank 1.

Definition 5 (Full rank) A matrix $A \in \mathbb{C}^{m \times n}$ is full rank if it has maximum possible rank (the minimum of m and n). If $m \geq n$, then A must have linearly independent columns to be full rank.

We quote the following result which follows from the linear independence of the columns of a full rank matrix A with $m \geq n$, and the column interpretation of matrix multiplication.

Theorem 6 A matrix $A \in \mathbb{C}^{m \times n}$ with $m \geq n$ has full rank if and only if it maps no two distinct vectors to the same vector.

Definition 7 (Invertible) A matrix $A \in \mathbb{C}^{m \times n}$ is nonsingular (or equivalently, invertible) if it is square ($m = n$) and of full rank.

A consequence of this definition is that the columns of A form a basis for \mathbb{C}^m .

Writing e_j as the j th canonical basis vector,

$$e_j = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix},$$

i.e. the vector with zeros everywhere except for in the j th entry, we can write

$$e_j = \sum_{i=1}^m z_{ij} a_i,$$

using the columns of A , since the columns form a basis, for coefficients z_{ij} , $1 \leq i, j \leq m$. In other words,

$$I = \begin{pmatrix} e_1 & e_2 & \dots & e_m \end{pmatrix} = ZA,$$

and we call Z the (left) inverse of A .

Let A also have a right inverse Y so that $I = AY$. Then,

$$Z = ZI = ZAY = (ZA)Y = IY = Y,$$

so the left and right inverses agree, and we call them A^{-1} . (Exercise, show that a full-rank square matrix has unique left and right inverse.)

We quote the following result, which partially follows from what we have seen so far.