

# Classes and weights

$$\mathbb{C} = \{c_{i=1}, \dots, c_{i=l}\}; \Theta = \{0, 0.5, 1\}$$

## Primary data

$$L_P = \begin{bmatrix} q_{1,1} & q_{1,2} & \dots & q_{1,m} \\ q_{2,1} & q_{2,2} & \dots & q_{2,m} \\ \vdots & \vdots & \ddots & \vdots \\ q_{j,1} & q_{j,2} & \dots & q_{j,m} \end{bmatrix}; \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_j \end{bmatrix}; k_P$$

## Auxiliary data

$$L_A = \begin{bmatrix} b_{1,1} & b_{1,2} & \dots & \dots & b_{1,n} \\ b_{2,1} & b_{2,2} & \dots & \dots & b_{2,n} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ b_{j,1} & b_{j,2} & \dots & \dots & b_{j,n} \end{bmatrix}; \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_j \end{bmatrix}; k_A$$

## Neighbour matrices

$$N_P = \begin{bmatrix} c_{i=1} & \dots & c_{i=l} \\ n_{1,1}^P & \dots & n_{1,l}^P \\ n_{2,1}^P & \dots & n_{2,l}^P \\ \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots \end{bmatrix}; N_A = \begin{bmatrix} c_{i=1} & \dots & c_{i=l} \\ n_{1,1}^A & \dots & n_{1,l}^A \\ n_{2,1}^A & \dots & n_{2,l}^A \\ \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots \end{bmatrix}$$

# Classes and weights

$$\mathbb{C} = \{c_{i=1}, \dots, c_{i=l}\}; \Theta = \{0, 0.5, 1\}$$

## Primary data

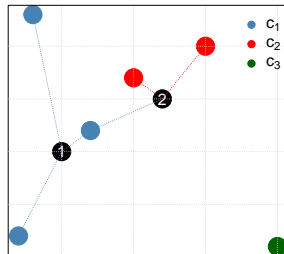
$$L_P = \begin{bmatrix} q_{1,1} & q_{1,2} & \dots & q_{1,m} \\ q_{2,1} & q_{2,2} & \dots & q_{2,m} \\ \vdots & \vdots & \ddots & \vdots \\ q_{j,1} & q_{j,2} & \dots & q_{j,m} \end{bmatrix}; \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_j \end{bmatrix}; k_P$$

## Auxiliary data

$$L_A = \begin{bmatrix} b_{1,1} & b_{1,2} & \dots & \dots & b_{1,n} \\ b_{2,1} & b_{2,2} & \dots & \dots & b_{2,n} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ b_{j,1} & b_{j,2} & \dots & \dots & b_{j,n} \end{bmatrix}; \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_j \end{bmatrix}; k_A$$

## Neighbour matrices

$$N_P = \begin{bmatrix} c_{i=1} & \dots & c_{i=l} \\ n_{1,1}^P & \dots & n_{1,l}^P \\ n_{2,1}^P & \dots & n_{2,l}^P \\ \vdots & \vdots & \vdots \end{bmatrix}; N_A = \begin{bmatrix} c_{i=1} & \dots & c_{i=l} \\ n_{1,1}^A & \dots & n_{1,l}^A \\ n_{2,1}^A & \dots & n_{2,l}^A \\ \vdots & \vdots & \vdots \end{bmatrix}$$



$$N_P = \begin{matrix} & c_1 & c_2 & c_3 \\ p_1 & \begin{bmatrix} 3 \\ 3 \\ 3 \end{bmatrix} & \begin{bmatrix} 0 \\ 2 \\ 3 \end{bmatrix} & \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\ p_2 & \vdots & \vdots & \vdots \end{matrix}$$

## Classes and weights

$$\mathbb{C} = \{c_{i=1}, \dots, c_{i=I}\}; \Theta = \{0, 0.5, 1\}$$

## Primary data

$$L_P = \begin{bmatrix} q_{1,1} & q_{1,2} & \dots & q_{1,m} \\ q_{2,1} & q_{2,2} & \dots & q_{2,m} \\ \vdots & \vdots & \ddots & \vdots \\ q_{j,1} & q_{j,2} & \dots & q_{j,m} \end{bmatrix}; \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_j \end{bmatrix}; k_P$$

## Auxiliary data

$$L_A = \begin{bmatrix} b_{1,1} & b_{1,2} & \dots & \dots & b_{1,n} \\ b_{2,1} & b_{2,2} & \dots & \dots & b_{2,n} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ b_{j,1} & b_{j,2} & \dots & \dots & b_{j,n} \end{bmatrix}; \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_j \end{bmatrix}; k_A$$

## Neighbour matrices

$$N_P = \begin{bmatrix} c_{i=1} & \dots & c_{i=I} \\ n_{1,1}^P & \dots & n_{1,I}^P \\ n_{2,1}^P & \dots & n_{2,I}^P \\ \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots \end{bmatrix}; N_A = \begin{bmatrix} c_{i=1} & \dots & c_{i=I} \\ n_{1,1}^A & \dots & n_{1,I}^A \\ n_{2,1}^A & \dots & n_{2,I}^A \\ \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots \end{bmatrix}$$

## Weights matrix (labelled)

$$\begin{matrix} & c_1 & c_2 & c_3 \\ \theta_1 & \begin{bmatrix} 0 & 0 & 0 \end{bmatrix} \\ \theta_2 & \begin{bmatrix} 0 & 0 & 1 \end{bmatrix} \\ \theta_i & \begin{bmatrix} \vdots & & \vdots \end{bmatrix} \\ \vdots & \begin{bmatrix} 1 & 1 & 0 \end{bmatrix} \\ \theta_{\Theta^I} & \begin{bmatrix} 1 & 1 & 1 \end{bmatrix} \end{matrix} \begin{bmatrix} F_{1_1} \\ F_{1_2} \\ F_{1_i} \\ \vdots \\ F_{1_{\Theta^I}} \end{bmatrix}$$

$$\theta^* = \{1, 0, 1\}$$

(♥ BiocParallel)

$$\mathbb{C} = \{c_{j=1}, \dots, c_{j=l}\}; \Theta = \{0, 0.5, 1\}$$
$$L_P = \begin{bmatrix} q_{1,1} & q_{1,2} & \dots & q_{1,m} \\ q_{2,1} & q_{2,2} & \dots & q_{2,m} \\ \vdots & \vdots & \ddots & \vdots \\ q_{i,1} & q_{i,2} & \dots & q_{i,m} \end{bmatrix}; \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_i \end{bmatrix}; k_P$$
$$L_A = \begin{bmatrix} b_{1,1} & b_{1,2} & \dots & \dots & b_{1,n} \\ b_{2,1} & b_{2,2} & \dots & \dots & b_{2,n} \\ \vdots & \vdots & & & \vdots \\ b_{i,1} & b_{i,2} & \dots & \dots & b_{i,n} \end{bmatrix}; \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_j \end{bmatrix}; k_A$$
$$N_P = \begin{bmatrix} C_{i=1} & \dots & C_{i=l} \\ n_{1,1}^P & \dots & n_{1,l}^P \\ n_{2,1}^P & \dots & n_{2,l}^P \\ \vdots & & \vdots \end{bmatrix}; N_A = \begin{bmatrix} C_{i=1} & \dots & C_{i=l} \\ n_{1,1}^A & \dots & n_{1,l}^A \\ n_{2,1}^A & \dots & n_{2,l}^A \\ \vdots & & \vdots \end{bmatrix}$$
$$V(c_i)_j = \theta^* n_{ij}^P + (1 - \theta^*) n_{ij}^A$$

$$V(C_i)_j = \begin{bmatrix} 1 & & \\ 2 & & \\ 3 & & \\ \vdots & & \\ j & & \end{bmatrix}$$

$$y_i = \operatorname{argmax}(V(c_i)_i)$$