LINEAR EQATIONS [1.1] + (CONTINUED)

#### Gaussian Elimination

Back to arbitrary linear systems.

Principle of the method: Since triangular systems are easy to solve, we will transform a linear system into one that is triangular. Main operation: combine rows so that zeros appear in the required locations to make the system triangular.

### Notation.

$$\left\{egin{array}{llll} 2x_1+4x_2+4x_3=&2 & & 2&4&4&2 \ x_1+3x_2+1x_3=&1 & ext{Notation:} & 1&3&1&1 \ x_1+5x_2+6x_3=-6 & & 1&5&6&-6 \ \end{array}
ight.$$

Main operation used: scaling and adding rows.

Examples of such operations.

**Example:** | : Replace row 2 by: row 2 + row 1:

Example: | :

Replace row 3 by: 2 times row 3 - row 1:

Example:

3-3

Replace row 1 by: (0.5 \* row 1)

3 7 5 3

# Gaussian Elimination (cont.)

- ightharpoonup Go back to original system. Step 1 must eliminate  $x_1$  from equations 2 and 3, i.e.,
- It must transform:

 $row_2 := row_2 - \frac{1}{2} \times row_1$ :  $row_3 := row_3 - \frac{1}{2} \times row_1$ :

$$egin{array}{c|cccc} 2 & 4 & 4 & 2 \ 0 & 1 & -1 & 0 \ 1 & 5 & 6 & -6 \ \end{array}$$

> Step 2 must now transform:

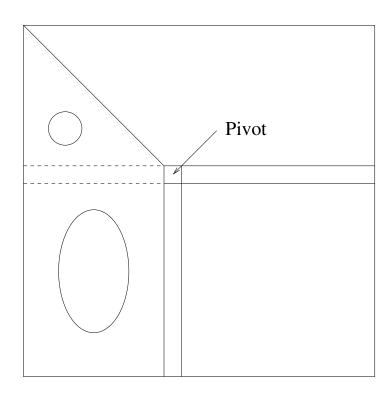
System is now triangular  $\left\{egin{array}{ll} 2x_1+4x_2+4x_3=2 \ x_2-x_3=0 \ 7x_3=-7 \end{array}
ight.
igh$ 

Find the solution of the above triangular system and verify that it is a solution of the original system

# Gaussian Elimination: The algorithm

Recall: an algorithm is a sequence of operations (a 'recipe') to be performed by a computer.

- General step of Gaussian elimination :
- At step k subtract multiples of row k from rows  $k+1, k+\frac{\text{Row } k}{2, \cdots, n}$  in order to zero-out entries below  $a_{kk}$  in column k.
- Repeat this step for k=1,2,...,n-1



Text: 1.1 – Gauss

Step k in words: for row k+1 to row n do: subtract piv \* row k from row i (where  $piv=a_{ik}/a_{kk}$ ).

### ALGORITHM: 1. Gaussian Elimination

```
1. For k = 1 : n - 1 Do:

2. For i = k + 1 : n Do:

3. piv := a_{ik}/a_{kk}

4. For j := k + 1 : n + 1 Do:

5. a_{ij} := a_{ij} - piv * a_{kj}

6. End

6. End

7. End
```

3-7 Text: 1.1 – Gauss

### Matlab Script:

```
function [x] = gauss (A, b)
% function [x] = gauss (A, b)
% solves A x = b by Gaussian elimination
n = size(A,1);
A = [A,b];
for k=1:n-1
    for i=k+1:n
        piv = A(i,k) / A(k,k);
        A(i,k+1:n+1)=A(i,k+1:n+1)-piv*A(k,k+1:n+1);
    end
end
x = backsolv(A,A(:,n+1));
```

- $\blacktriangleright$  Input: matrix A and right-hand side b. Output: solution x.
- Invokes backsolv.m to solve final triangular system.

Text: 1.1 – Gauss

### Gaussian Elimination: Pivoting

Consider again Gaussian Elimination for the linear system

$$\left\{egin{array}{lll} 2x_1+2x_2+4x_3=&2&&2&4&2\ x_1+x_2+x_3=&1& ext{Or:}&1&1&1&1\ x_1+4x_2+6x_3=&-5&&1&4&6&-5 \end{array}
ight.$$

$$row_2 := row_2 - \frac{1}{2} \times row_1$$
:  $row_3 := row_3 - \frac{1}{2} \times row_1$ :

$$egin{array}{c|ccccc} 2 & 2 & 4 & 2 \ 0 & 0 & -1 & 0 \ 0 & 3 & 4 & -6 \ \end{array}$$

$$ightharpoonup$$
 Pivot  $a_{22}$  is zero. Solution : permute rows 2 and 3  $\longrightarrow$ 

# Gaussian Elimination: Partial Pivoting

Row k

Largest | a ik | Permite rous

General situation

ightharpoonup Partial Pivoting: \*Always\* Permute row  $m{k}$  with row  $m{l}$  such that

$$|a_{lk}| = \max_{i=k,\dots,n} |a_{ik}|$$

More 'stable' algorithm.

### Gauss-Jordan Elimination

Principle of the method: We will now transform the system into one that is even easier to solve than a triangular system, namely a diagonal system. The method is very similar to Gaussian Elimination. It is just a bit more expensive.

Back to original system (P. 2-2). Step 1 must transform:

Same step as Gaussian Elimination.

Text: 1.1-2 – GaussJordan

 $row_2 := row_2 - 0.5 \times row_1$ :  $row_3 := row_3 - 0.5 \times row_1$ :

$$egin{array}{c|ccccc} 2 & 4 & 4 & 2 \ 0 & 1 & -1 & 0 \ 1 & 5 & 6 & -6 \ \hline \end{array}$$

Step 2:  $\begin{vmatrix} 2 & 4 & 4 & 2 \\ 0 & 1 & -1 & 0 \\ 0 & 3 & 4 & -7 \end{vmatrix}$  into:

 $egin{array}{c|ccccc} x & 0 & x & x \ 0 & x & x & x \ 0 & 0 & x & x \end{array}$ 

 $row_1 := row_1 - 4 \times row_2$ :  $row_3 := row_3 - 3 \times row_2$ :

### There is now a third step:

$$egin{array}{c|cccc} x & 0 & 0 & x \ 0 & x & 0 & x \ 0 & 0 & x & x \end{array}$$

$$row_1 := row_1 - \frac{8}{7} \times row_3$$
:  $row_2 := row_2 - \frac{-1}{7} \times row_3$ :

$$egin{array}{c|cccc} 2 & 0 & 0 & 10 \ 0 & 1 & 0 & -1 \ 0 & 0 & 7 & -7 \ \end{array}$$

Final System: 
$$egin{cases} 2x_1 &=& 10 \ x_2 &=& -1 \ 7x_3 &=& -7 \end{cases}$$
 Solution:  $egin{cases} x_1 = 5 \ x_2 = -1 \ x_3 = -1 \end{cases}$ 

$$egin{aligned} x_1 &= 5 \ x_2 &= -1 \ x_3 &= -1 \end{aligned}$$

### Gauss-Jordan - variants

Common variant: Before an elimination step is started divide the row by diagonal entry  $a_{kk}$ 

- $\blacktriangleright$  At the end all diagonal entries are ones  $\rightarrow$  solution = rhs
- Redo the previous example with this variant.
- Is this more or less costly than the original method?

NOTE: unless otherwise specified Gauss-Jordan will refer to this scaled version.

Also: Pivoting can be implemented just like Gaussian elimination.

Important: Never swap a pivot row with a row above it! (destroys structure)

Text: 1.1-2 – Gauss Jordan

```
function x = gaussj(A, b)
% function x = gaussj (A, b)
% solves A x = b by Gauss-Jordan elimination
\% this version scales rows.
n = size(A,1);
A = [A,b] ;
 for k=1:n
    A(k,k:n+1) = A(k,k:n+1)/A(k,k);
    for i=1:n
        if (i = k)
            piv = A(i,k);
            \bar{A}(i,k:n+1) = A(i,k:n+1) - piv*A(k,k:n+1);
        end
    end
 end
x = A(:,n+1);
```

3-15 \_\_\_\_\_\_ Text: 1.1-2 – Gauss Jordan

## Linear systems – summary of complexity results

ightharpoonup The number of operations needed to solve a triangular linear system with  $m{n}$  unknowns is

$$C_T(n) = n^2$$

ightharpoonup The number of operations required to solve a linear system with n unknowns by Gaussian elimination is

$$C_G(n)pprox rac{2}{3}n^3$$

ightharpoonup The number of operations required to solve a linear system with  $m{n}$  unknowns by Gauss-Jordan elimination is

$$C_{GJ}(n) pprox n^3$$

 $\triangleright$  Note: remember that Gauss-Jordan costs 50% more than Gauss.