

EIGENVALUE PROBLEMS AND THE SVD. [5.1 TO 5.3 & 7.4]

Eigenvalue Problems. Introduction

Let A an $n \times n$ real nonsymmetric matrix. The eigenvalue problem:

$$Au = \lambda u$$

$\lambda \in \mathbb{C}$: eigenvalue

$u \in \mathbb{C}^n$: eigenvector

Example:

$$A = \begin{pmatrix} 2 & 0 \\ 2 & 1 \end{pmatrix}$$

- $\lambda_1 = 1$ with eigenvector $u_1 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$
- $\lambda_2 = 2$ with eigenvector $u_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$
- The set of eigenvalues of A is called the spectrum of A

Eigenvalue Problems. Their origins

- Structural Engineering [$Ku = \lambda Mu$]
- Stability analysis [e.g., electrical networks, mechanical system,..]
- Quantum chemistry and Electronic structure calculations [Schrödinger equation..]
- Application of new era: page ranking on the world-wide web.

Basic definitions and properties

A scalar λ is called an **eigenvalue** of a square matrix A if there exists a nonzero vector u such that $Au = \lambda u$. The vector u is called an **eigenvector** of A associated with λ .

- The set of all eigenvalues of A is the 'spectrum' of A . Notation: $\Lambda(A)$.
- λ is an eigenvalue iff the columns of $A - \lambda I$ are linearly dependent.
- λ is an eigenvalue iff $\boxed{\det(A - \lambda I) = 0}$

 Compute the eigenvalues of the matrix:

 Eigenvectors?

$$A = \begin{pmatrix} 2 & 1 & 0 \\ -1 & 0 & 1 \\ 0 & 1 & 2 \end{pmatrix}$$

Basic definitions and properties (cont.)

- An eigenvalue is a root of the Characteristic polynomial:




$$p_A(\lambda) = \det(A - \lambda I)$$

- So there are n eigenvalues (counted with their multiplicities).
- The multiplicity of these eigenvalues as roots of p_A are called algebraic multiplicities.

 Consider

$$A = \begin{bmatrix} 1 & 2 & -4 \\ 0 & 1 & 2 \\ 0 & 0 & 2 \end{bmatrix}$$


Find all eigenvalues of A .


-  How many eigenvalues can you find if a_{33} is replaced by one?
-  Same questions if a_{12} is replaced by zero.
-  What are all the eigenvalues of a diagonal matrix?

➤ Two matrices A and B are **similar** if there exists an invertible matrix X such that

$$A = XBX^{-1}$$

➤ A and B represent the same mapping in 2 different bases.

 Explain why [Hint: Assume a column of X represents one basis vector of the new basis expressed in the old basis...]

 Show: A and B have the same eigenvalues. What about eigenvectors?

Definition: A is **diagonalizable** if it is similar to a diagonal matrix

➤ Note : not all matrices are diagonalizable

➤ Theorem 1: A matrix is diagonalizable iff it has n linearly independent eigenvectors

Example: Which of these matrices is/are diagonalizable

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 2 & 1 \\ 0 & 0 & 3 \end{bmatrix} \quad B = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix} \quad C = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 2 \end{bmatrix}$$

➤ Theorem 2: The eigenvectors associated with **distinct** eigenvalues are linearly independent

 Prove the result for 2 distinct eigenvalues

➤ Consequence: if all eigenvalues of a matrix A are simple then A is diagonalizable.

➤ Theorem 3: A symmetric matrix has real eigenvalues and is diagonalizable. In addition A admits a set of orthonormal eigenvectors.

The Singular Value Decomposition (SVD)

Theorem For any matrix $A \in \mathbb{R}^{m \times n}$ there exist orthogonal matrices $U \in \mathbb{R}^{m \times m}$ and $V \in \mathbb{R}^{n \times n}$ such that

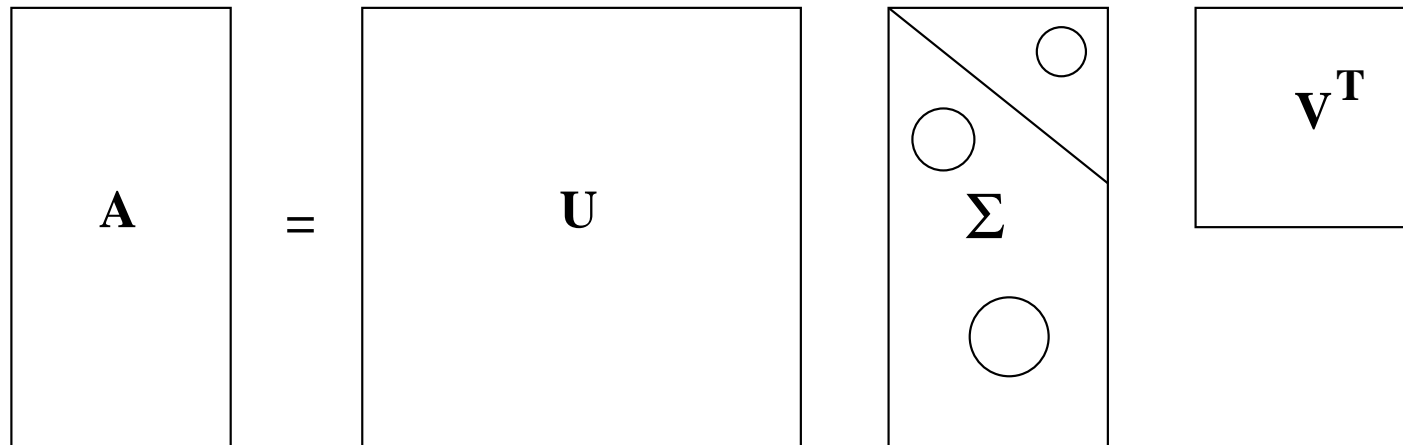
$$A = U\Sigma V^T$$

where Σ is a diagonal matrix with entries $\sigma_{ii} \geq 0$.

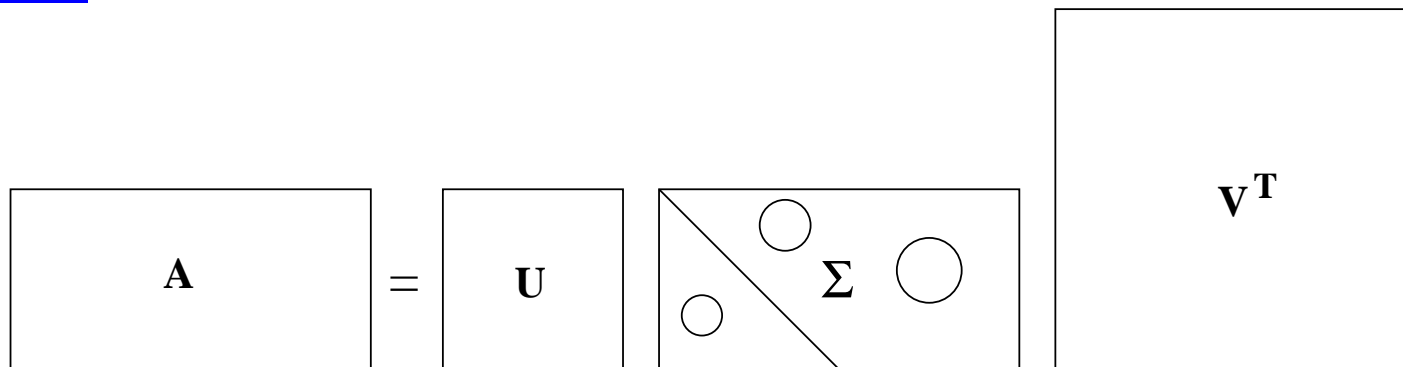
$$\sigma_{11} \geq \sigma_{22} \geq \cdots \sigma_{pp} \geq 0 \text{ with } p = \min(n, m)$$

- The σ_{ii} are the **singular values** of A .
- σ_{ii} is denoted simply by σ_i

Case 1:



Case 2:



The “thin” SVD

- Consider the Case-1. It can be rewritten as

$$A = [U_1 U_2] \begin{pmatrix} \Sigma_1 \\ 0 \end{pmatrix} V^T$$

Which gives:

$$A = U_1 \Sigma_1 V^T$$

where U_1 is $m \times n$ (same shape as A), and Σ_1 and V are $n \times n$

- referred to as the “thin” SVD. Important in practice.

 How can you obtain the thin SVD from the QR factorization of A and the SVD of an $n \times n$ matrix?

A few properties. Assume that

$$\sigma_1 \geq \sigma_2 \geq \cdots \geq \sigma_r > 0 \text{ and } \sigma_{r+1} = \cdots = \sigma_p = 0$$

Then:

- $\text{rank}(A) = r = \text{number of nonzero singular values.}$
- $\text{Ran}(A) = \text{span}\{u_1, u_2, \dots, u_r\}$
- $\text{Null}(A) = \text{span}\{v_{r+1}, v_{r+2}, \dots, v_n\}$
- The matrix A admits the SVD expansion:

$$A = \sum_{i=1}^r \sigma_i u_i v_i^T$$

Rank and approximate rank of a matrix

- The number of nonzero singular values r equals the rank of A
- Can define approximate rank if we simply 'neglect smallest singular values

Example: Let

$$\begin{array}{lll} \sigma_1 = 10.0; & \sigma_2 = 6.0; & \sigma_3 = 3.0; \\ \sigma_4 = 0.030; & \sigma_5 = 0.0130; & \sigma_6 = 0.0010; \end{array}$$

- $\sigma_4, \sigma_5, \sigma_6$, are likely due to noise - so the approximate rank is 3.
- Rigorous way of stating this exists – but beyond scope of this class [see csci 5304]

Right and Left Singular vectors:

$$\begin{aligned}Av_i &= \sigma_i u_i \\ A^T u_j &= \sigma_j v_j\end{aligned}$$

- Consequence $A^T A v_i = \sigma_i^2 v_i$ and $A A^T u_i = \sigma_i^2 u_i$
- Right singular vectors (v_i 's) are eigenvectors of $A^T A$
- Left singular vectors (u_i 's) are eigenvectors of $A A^T$
- Possible to get the SVD from eigenvectors of $A A^T$ and $A^T A$
– but: difficulties due to non-uniqueness of the SVD

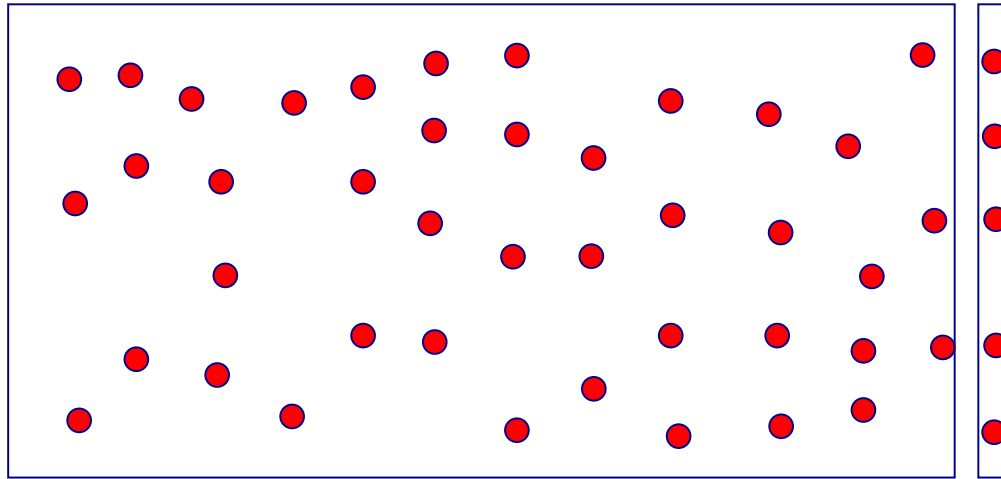
A few applications of the SVD

Many methods require to approximate the original data (matrix) by a low rank matrix before attempting to solve the original problem

- Regularization methods require the solution of a least-squares linear system $Ax = b$ approximately in the ‘dominant singular’ space of A
- The Latent Semantic Indexing (LSI) method in information retrieval, performs the “query” in the dominant singular space of A
- Methods utilizing Principal Component Analysis, e.g. Face Recognition.

Information Retrieval: Vector Space Model

- Given: a collection of documents (columns of a matrix A) and a query vector q .



- Collection represented by an $m \times n$ term by document matrix with $a_{ij} = L_{ij}G_iN_j$
- Queries ('pseudo-documents') q are represented similarly to a column

Vector Space Model - continued

- Problem: find a column of A that best matches q
- Similarity metric: angle between column c and query q

$$\cos \theta(c, q) = \frac{|c^T q|}{\|c\| \|q\|}$$

- To rank all documents we need to compute

$$s = A^T q$$

- s = similarity vector.
- Literal matching – not very effective.
- Problems with literal matching: *polysemy*, *synonymy*,...

Use of the SVD

- Solution: Extract intrinsic information – or underlying “semantic” information –
- LSI: replace matrix A by a low rank approximation using the Singular Value Decomposition (SVD)

$$A = U\Sigma V^T \rightarrow A_k = U_k \Sigma_k V_k^T$$

- U_k : term space, V_k : document space.
- Refer to this as **Truncated SVD (TSVD)** approach
- Amounts to replacing small sing. values of A by zeros

New similarity vector:

$$s_k = A_k^T q = V_k \Sigma_k U_k^T q$$

LSI : an example

```
%% D1 : INFANT & TODDLER first aid
%% D2 : BABIES & CHILDREN's room for your HOME
%% D3 : CHILD SAFETY at HOME
%% D4 : Your BABY's HEALTH and SAFETY
%% : From INFANT to TODDLER
%% D5 : BABY PROOFING basics
%% D6 : Your GUIDE to easy rust PROOFING
%% D7 : Beanie BABIES collector's GUIDE
%% D8 : SAFETY GUIDE for CHILD PROOFING your HOME
%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%%
%% TERMS: 1:BABY 2:CHILD 3:GUIDE 4:HEALTH 5:HOME
%% 6:INFANT 7:PROOFING 8:SAFETY 9:TODDLER
%% Source: Berry and Browne, SIAM., '99
```

- Number of documents: 8
- Number of terms: 9

➤ Raw matrix (before scaling).

$$A =$$

<i>d1</i>	<i>d2</i>	<i>d3</i>	<i>d4</i>	<i>d5</i>	<i>d6</i>	<i>d7</i>	<i>d8</i>	
	1		1	1		1		<i>bab</i>
	1	1					1	<i>chi</i>
					1	1	1	<i>gui</i>
			1					<i>hea</i>
	1	1					1	<i>hom</i>
1			1					<i>inf</i>
				1	1		1	<i>pro</i>
		1	1				1	<i>saf</i>
1			1					<i>tod</i>

 Get the answer to the query Child Safety, so

$$q = [0 \ 1 \ 0 \ 0 \ 0 \ 0 \ 0 \ 1 \ 0]$$

using cosines and then using LSI with $k = 3$.