

Assignment 01

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1 Ray-plane intersection

A ray equation can be formulated as follows:

$$\mathbf{s}(t) = \mathbf{o} + t\mathbf{d}$$

For a plane \mathbf{n} , the ray-plane intersection can be formulated as:

$$\mathbf{n}^\top(\mathbf{o} + t\mathbf{d}) - b = 0$$

solving for t , we get

$$\begin{aligned}\mathbf{n}^\top(\mathbf{o} + t\mathbf{d}) - b &= 0 \\ \mathbf{n}^\top\mathbf{o} + t\mathbf{n}^\top\mathbf{d} - b &= 0 \\ \implies t\mathbf{n}^\top\mathbf{d} &= b - \mathbf{n}^\top\mathbf{o} \\ \implies t &= \frac{b - \mathbf{n}^\top\mathbf{o}}{\mathbf{n}^\top\mathbf{d}}\end{aligned}$$

2 Ray-cylinder intersection

The implicit equation for a cylinder centered on z with radius r is

$$x^2 + y^2 = r^2$$

where

$$\begin{aligned}x &= r \cos \phi \\ y &= r \sin \phi\end{aligned}$$

Now we can write

$$\|\mathbf{q} - \mathbf{p}_a - (\mathbf{v}_a \cdot (\mathbf{q} - \mathbf{p}_a))\mathbf{v}_a\|^2 - r^2 = 0$$

- r : radius of a cylinder
- \mathbf{p}_a : cylinder center
- \mathbf{v}_a : cylinder axis
- \mathbf{q} : point on the cylinder

to find intersection points with a ray $\mathbf{p} + t\mathbf{v}$, substitute $\mathbf{q} = \mathbf{p} + t\mathbf{v}$

$$\begin{aligned}
& \|\mathbf{p} + t\mathbf{v} - \mathbf{p}_a - (\mathbf{v}_a \cdot (\mathbf{p} + t\mathbf{v} - \mathbf{p}_a))\mathbf{v}_a\|^2 - r^2 = 0 \\
& \|\mathbf{p} + t\mathbf{v} - \mathbf{p}_a - (\mathbf{v}_a \cdot (\mathbf{p} - \mathbf{p}_a) + \mathbf{v}_a \cdot t\mathbf{v})\mathbf{v}_a\|^2 - r^2 = 0 \\
& \|\mathbf{p} + t\mathbf{v} - \mathbf{p}_a - (\mathbf{v}_a \cdot (\mathbf{p} - \mathbf{p}_a))\mathbf{v}_a - (\mathbf{v}_a \cdot t\mathbf{v})\mathbf{v}_a\|^2 - r^2 = 0 \\
& \underbrace{\|t(\mathbf{v} - (\mathbf{v}_a \cdot \mathbf{v}))\mathbf{v}_a\|}_{\mathbf{F}} + \underbrace{\|\mathbf{p} - \mathbf{p}_a - (\mathbf{v}_a \cdot (\mathbf{p} - \mathbf{p}_a))\mathbf{v}_a\|}_{\mathbf{G}}^2 - r^2 = 0 \\
& \|t\mathbf{F} + \mathbf{G}\|^2 - r^2 = 0 \\
& t^2 \underbrace{\mathbf{F}^\top \mathbf{F}}_a + t \underbrace{2\mathbf{F}^\top \mathbf{G}}_b + \underbrace{\mathbf{H}^\top \mathbf{H}}_c - r^2 = 0
\end{aligned}$$

This is a quadratic equation with the following coefficients:

- $a = \|\mathbf{v} - (\mathbf{v}_a \cdot \mathbf{v})\mathbf{v}_a\|^2$
- $b = 2(\mathbf{v} - (\mathbf{v}_a \cdot \mathbf{v})\mathbf{v}_a)^\top (\mathbf{p} - \mathbf{p}_a - (\mathbf{v}_a \cdot (\mathbf{p} - \mathbf{p}_a))\mathbf{v}_a)$
- $c = \|\mathbf{p} - \mathbf{p}_a - (\mathbf{v}_a \cdot (\mathbf{p} - \mathbf{p}_a))\mathbf{v}_a\|^2 - r^2$

3 Intersection Normal Vector

- **c2**: projection of intersection point to cylinder axis
- **n**: normal vector on intersection

$$\begin{aligned}
\mathbf{c2} &= \mathbf{p}_a + (\mathbf{q} - \mathbf{p}_a \cdot \mathbf{v}_a)\mathbf{v}_a \\
\mathbf{n} &= \frac{\mathbf{c2} - \mathbf{q}}{r}
\end{aligned}$$

References

- [1] Denis Zorin, <https://mrl.nyu.edu/~dzorin/rend05/lecture2.pdf>