Assignment 01

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1 Ray-plane intersection

A ray equation can be formulated as follows:

$$s(t) = o + td$$

For a plane \mathbf{n} , the ray-plane intersection can be formulated as:

$$\mathbf{n}^{\mathsf{T}}(\mathbf{o} + t\mathbf{d}) - b = 0$$

solving for t, we get

$$\mathbf{n}^{\top}(\mathbf{o} + t\mathbf{d}) - b = 0$$

$$\mathbf{n}^{\top}\mathbf{o} + t\mathbf{n}^{\top}\mathbf{d} - b = 0$$

$$\implies t\mathbf{n}^{\top}\mathbf{d} = b - \mathbf{n}^{\top}\mathbf{o}$$

$$\implies t = \frac{b - \mathbf{n}^{\top}\mathbf{o}}{\mathbf{n}^{\top}\mathbf{d}}$$

2 Ray-cylinder intersection

The implicit equation for a cylinder centered on z with radius r is

$$x^2 + y^2 = r^2$$

where

$$x = r \cos \phi$$
$$y = r \sin \phi$$

Now we can write

$$\|\mathbf{q} - \mathbf{p}_a - (\mathbf{v}_a \cdot (\mathbf{q} - \mathbf{p}_a))\mathbf{v}_a\|^2 - r^2 = 0$$

- r: radius of a cylinder
- $\mathbf{p}_a + t\mathbf{v}_a$: line orientation of the cylinder
- q: point on the cylinder

to find intersection points with a ray $\mathbf{p} + t\mathbf{v}$, substitute $\mathbf{q} = \mathbf{p} + t\mathbf{v}$

$$\|\mathbf{p} + t\mathbf{v} - \mathbf{p}_{a} - (\mathbf{v}_{a} \cdot (\mathbf{p} + t\mathbf{v} - \mathbf{p}_{a}))\mathbf{v}_{a}\|^{2} - r^{2} = 0$$

$$\|\mathbf{p} + t\mathbf{v} - \mathbf{p}_{a} - (\mathbf{v}_{a} \cdot (\mathbf{p} - \mathbf{p}_{a}) + \mathbf{v}_{a} \cdot t\mathbf{v}))\mathbf{v}_{a}\|^{2} - r^{2} = 0$$

$$\|\mathbf{p} + t\mathbf{v} - \mathbf{p}_{a} - (\mathbf{v}_{a} \cdot (\mathbf{p} - \mathbf{p}_{a}))\mathbf{v}_{a} - (\mathbf{v}_{a} \cdot t\mathbf{v}))\mathbf{v}_{a}\|^{2} - r^{2} = 0$$

$$\|t(\mathbf{v} - (\mathbf{v}_{a} \cdot \mathbf{v}))\mathbf{v}_{a}) + \mathbf{p} - \mathbf{p}_{a} - (\mathbf{v}_{a} \cdot (\mathbf{p} - \mathbf{p}_{a}))\mathbf{v}_{a}\|^{2} - r^{2} = 0$$

$$\|t\mathbf{F} + \mathbf{G}\|^{2} - r^{2} = 0$$

$$t^{2} \underbrace{\mathbf{F}^{\mathsf{T}}\mathbf{F}}_{a} + t \underbrace{2\mathbf{F}^{\mathsf{T}}\mathbf{G}}_{b} + \underbrace{\mathbf{H}^{\mathsf{T}}\mathbf{H} - r^{2}}_{c} = 0$$

This is a quadratic equation with the following coefficients:

- $a = \|\mathbf{v} (\mathbf{v}_a \cdot \mathbf{v}))\mathbf{v}_a\|^2$
- $b = 2(\mathbf{v} (\mathbf{v}_a \cdot \mathbf{v}))\mathbf{v}_a)^{\mathsf{T}}(\mathbf{p} \mathbf{p}_a (\mathbf{v}_a \cdot (\mathbf{p} \mathbf{p}_a))\mathbf{v}_a)$ $c = \|\mathbf{p} \mathbf{p}_a (\mathbf{v}_a \cdot (\mathbf{p} \mathbf{p}_a))\mathbf{v}_a\|^2 r^2$

References

[1] Denis Zorin, https://mrl.nyu.edu/~dzorin/rend05/lecture2.pdf