# **Super Resolution**

## **Network Architecture**

I build 3-layered network for Super Resolution tasks(2x), Vanilla RNN with ReLU as activation. (see **SuperResolutionNetwork** at network/rnn.py)

Detail hyper parameter setup as below:

- Use Adam optimizer with 1r=.001 and 1r\_decay=.0.
- Use Mean Squared Error as loss

$$\sum_{n=0}^{2}\left|\left|y_{gt}-y_{n}
ight|
ight|^{2}$$

- Use PSNR as evaluation metric
- Create new vanilla RNN (network/rnn.py)

#### **Dataset**

Use all [91] and [291] dataset. Create target image, random crop from image after random scale down and create source image using scale down and up by half.

## **Evaluation**

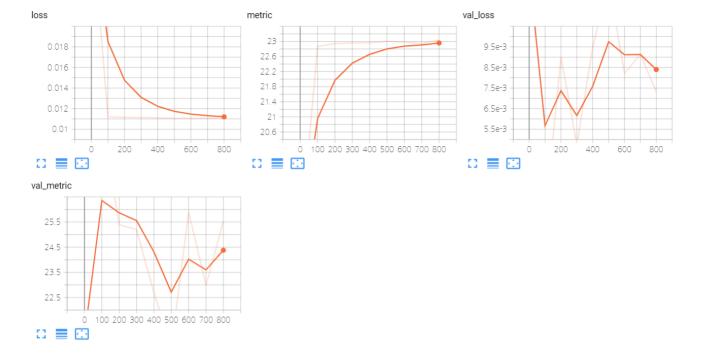
I use PSNR as evaluation metric, (see **SuperResolutionNetwork.metric** at network/rnn.py) using TensorFlow implementation, tf.image.psnr.

Implement **Custom Callback** (see **CustomCallback** at utils/callbacks.py) for logging loss, accuracy and sample images. For each interval, write inferenced image summary for one train set and all test set.

# **Results**

In terms of time, it was only 1000 epoch. However, PSN and loss is saturated after 1000 epoch. Model parameters is saved on model.hdf5 using keras model save method.

See ./assets directory for results. Train, prediction and test image is merged for easy compare (re-scale image, prediction image, ground truth image).



This is some train samples for check train is running well.

