

$$\delta) R_1 = H$$

$$\frac{(v_0 \cos \alpha)^2}{2g} = \frac{(v_0 \sin \alpha)^2}{g}$$

$$\tan \alpha = \sqrt{2}, \quad \alpha = 54,8^\circ$$

1.34

$$v_x = \lambda y$$

a) Оскільки по осі y маємо рух з рівно-
 ширною із швидкістю v_0 , то координата мо-
 на y змінюється лінійно за законом $y = v_0 t$.

$$v_x = \lambda y = \frac{dx}{dt}$$

$$\lambda v_0 t = \frac{dx}{dt}$$

$$\int_0^x \lambda v_0 t dt = \int_0^x dx$$

$$\frac{\lambda v_0 t^2}{2} = x$$

$$y(xy) = \frac{\lambda v_0}{2} \frac{y^2}{v_0^2} = \frac{\lambda y^2}{2 v_0}$$

$$\delta) a = \sqrt{a_x^2 + a_y^2}$$

$$a_y = \frac{d^2 y}{dt^2} = 0, \quad a_x = \frac{d^2 x}{dt^2} = \lambda v_0$$

$$a = \lambda v_0$$

$$a_x = \frac{dv}{dt}$$

$$v = \sqrt{v_x^2 + v_y^2}$$

$$v_x = \frac{dx}{dt} = \alpha v_0 t$$

$$v_y = \frac{dy}{dt} = v_0$$

$$v = v_0 \sqrt{\alpha^2 t^2 + 1}$$

$$a_x(t) = \frac{2v_0 \alpha^2 t}{2\sqrt{\alpha^2 t^2 + 1}} = \frac{v_0 \alpha^2 t}{\sqrt{\alpha^2 t^2 + 1}}$$

$$a_x(y) = \frac{v_0 \alpha^2 y}{v_0 \sqrt{\frac{\alpha^2 y^2}{v_0^2} + 1}} = \frac{v_0 \alpha^2 y}{\sqrt{\alpha^2 y^2 + v_0^2}}$$

$$a_n = \sqrt{a^2 - a_x^2} = \sqrt{(\alpha v_0)^2 - \left(\frac{\alpha^2 v_0 y}{\sqrt{\alpha^2 y^2 + v_0^2}} \right)^2} =$$

$$= \frac{\alpha v_0^2}{\sqrt{\alpha^2 y^2 + v_0^2}}$$

1. 35

$$v = \alpha \vec{i} + \beta x \vec{j}, \quad x = y = 0$$

$$a) \quad \frac{dx}{dt} = \alpha, \quad \int_0^x dx = \alpha \int_0^t dt, \quad x = \alpha t$$

$$\frac{dy}{dt} = \beta x, \quad \int_0^y dy = \int_0^t \alpha \beta t dt, \quad y = \alpha \beta \frac{t^2}{2}$$

$$y(x) = \frac{\alpha \beta}{2} \frac{x^2}{\alpha^2} = \frac{\beta}{2\alpha} x^2$$

$$b) \quad R = \frac{v^2}{a_n}$$

$$v = \sqrt{v_x^2 + v_y^2} = \sqrt{\alpha^2 + \beta^2 x^2}$$

$$a_n = \sqrt{a^2 - a_c^2}$$

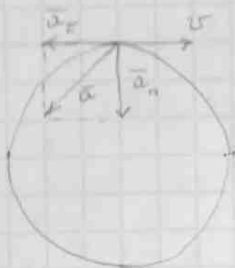
$$\vec{a} = \frac{dv_x}{dt} \vec{i} + \frac{dv_y}{dt} \vec{j} = \frac{L\beta \vec{j}}{x}$$

$$\beta_c = \frac{dv}{dt} = \frac{dv}{dx} \frac{dx}{dt} = \frac{\frac{L\beta^2 x}{\sqrt{L^2 + \beta^2 x^2}}}{\frac{(L^2 + \beta^2 x^2)^{3/2}}{L^4 \beta^2 + L^2 \beta^4 x^2 - L^2 \beta^2 x^2}} =$$

$$R = \frac{L^2 + \beta^2 x^2}{\sqrt{(L\beta)^2 - \frac{L^4 \beta^4 x^4}{L^2 + \beta^2 x^2}}} = \frac{(L^2 + \beta^2 x^2)^{3/2}}{\sqrt{L^4 \beta^2 + L^2 \beta^4 x^2 - L^2 \beta^2 x^2}} =$$

$$= \frac{L}{\beta} \left(1 + \left(\frac{x\beta}{L} \right)^2 \right)^{3/2}$$

1.38



$$|\vec{a}_n| = |\vec{a}_c|$$

$$t = 0 \quad - \quad v = v_0$$

$$a) \quad \frac{v^2}{R} = - \frac{dv}{dt}$$

$$\int_{v_0}^v \frac{dv}{v^2} = \int_0^t \frac{dt}{R}$$

$$\frac{1}{v} \Big|_{v_0}^v = \frac{t}{R}$$

$$\frac{1}{v} - \frac{1}{v_0} = \frac{t}{R}$$

$$v(t) = \frac{1}{\frac{t}{R} + \frac{1}{v_0}} = \frac{v_0 R}{v_0 t + R}$$

$$s(t) = \int_0^t v dt = v_0 R \int_0^t \frac{dt}{v_0 t + R} = R \ln |R + v_0 t| \Big|_0^t =$$

$$= R \ln \frac{R + v_0 t}{R}$$

$$e^{\frac{s}{R}} = 1 + \frac{v_0}{R} t = \frac{v_0 t + R}{R} = \frac{v_0}{v}$$

$$v(s) = v_0 e^{-\frac{s}{R}}$$

$$a(t) = \frac{dv}{dt} = \sqrt{a_z^2 + a_n^2} = \sqrt{2} |a_n| \quad (a_z = a_n)$$

$$a_n = \frac{dv}{dt} \neq, \quad v = \frac{ds}{dt}$$

$$dt = \frac{dv}{a_n}, \quad dt = \frac{ds}{v}$$

$$\frac{dv}{a_n} = \frac{ds}{v}, \quad \frac{dv}{ds} = \frac{a_n}{v}$$

$$\frac{dv}{ds} = -\frac{v_0}{R} e^{-\frac{s}{R}}$$

$$a_n = -\frac{v_0^2}{R} e^{-\frac{2s}{R}}$$

$$a(s) = \sqrt{2} \frac{v_0^2}{R} e^{-\frac{2s}{R}}$$

$$a(v) = \frac{\sqrt{2}}{R} v^2$$

1.39

$$v = \omega \sqrt{S}$$



$$\operatorname{tg} \varphi = \frac{a_n}{a_z}$$

$$a_n = \frac{v^2}{R}$$

$$a_z = \frac{dv}{dt}$$

$$a_n = \frac{\omega^2 S}{R}$$

$$a_z = \frac{dv}{dt} = \frac{dv}{ds} \frac{ds}{dt} = \frac{dv}{ds} v = \frac{\omega}{2\sqrt{S}} \omega \sqrt{S} = \frac{\omega^2}{2}$$

$$\operatorname{tg} \varphi = \frac{2S}{R}$$

1.42

$$a) \quad x=0, \quad y = 2x^2$$

$$\frac{dy}{dt} = 2 \omega x \frac{dx}{dt}$$

$$\frac{d^2 y}{dt^2} = 2 \omega \left(\frac{dx}{dt} \frac{dx}{dt} + x \frac{d^2 x}{dt^2} \right)$$

$$a = \left. \frac{d^2 y}{dt^2} \right|_{x=0} = 2 \omega v^2 = a_n \text{ (основная радиальная составляющая скорости движения)}$$

$$a_n = 2 \omega v^2 = \frac{v^2}{R}, \quad R = \frac{1}{2\omega}$$

1.46

$$\varphi = at - bt^3$$

↑ z
↑ ω

$$\omega_z = \frac{d\varphi}{dt}, \quad \beta_z = \frac{d\omega_z}{dt}$$

$$\omega_z = a - 3bt^2$$

↺ φ

$$\beta_z = -6bt, \quad \beta = |\beta_z|$$

Also symmetrisch, wenn $\omega_z = 0$:

a)

$$a = 3bt^2, \quad t_0 = \sqrt{\frac{a}{3b}}$$

$$\langle \omega \rangle = \frac{\int_0^{t_0} \omega_z dt}{\int_0^{t_0} dt} = \frac{a\sqrt{\frac{a}{3b}} - b\left(\frac{a}{3b}\right)^{3/2}}{\sqrt{\frac{a}{3b}}} = a - \frac{a}{3} = \frac{2a}{3}$$

$$\langle \beta \rangle = \frac{\int_0^{t_0} |\beta_z| dt}{\int_0^{t_0} dt} = \frac{6b\left(\sqrt{\frac{a}{3b}}\right)^2}{2\sqrt{\frac{a}{3b}}} = \sqrt{3ab}$$

$$\delta) \quad \beta_z \Big|_{t=\sqrt{\frac{a}{3b}}} = -6b\sqrt{\frac{a}{3b}} = -2\sqrt{3ab}$$

$$\beta = \left| \beta_z \Big|_{t=t_0} \right| = 2\sqrt{3ab}$$

1.47

$$\beta = \alpha t, \quad \varphi = 60^\circ$$



$$\tan \varphi = \frac{a_n}{a_t}$$

$$a_n = \beta R = \alpha R t$$

$$a_t = \frac{dv}{dt}$$

$$\int_0^v dv = \int_0^t \alpha R t dt$$

$$\frac{dv}{dt} = \alpha R t,$$

$$v = \frac{\alpha R t^2}{2}$$

$$a_n = \frac{v^2}{R} = \frac{\alpha^2 t^4 R}{4}$$

$$\tan \varphi = \frac{\frac{\alpha^2 t^4 R}{4}}{\frac{\alpha R t}{2}} = \frac{\alpha t^3}{2}$$

$$t = \sqrt[3]{\frac{2 \tan \varphi}{\alpha}}$$

1.48

$$\beta = \alpha \sqrt{\omega}, \quad t=0 - \omega = \omega_0$$

$$\beta_0 < 0$$

$$\beta = - \frac{d\omega}{dt}$$

$$- \frac{d\omega}{dt} = \alpha \sqrt{\omega}$$

$$-\int_{\omega_0}^{\omega} \frac{d\omega}{\sqrt{\omega}} = \mathcal{L} \int_0^t dt$$

$$-2\sqrt{\omega}' + 2\sqrt{\omega_0}' = \mathcal{L}t$$

$$\sqrt{\omega}' = \sqrt{\omega_0}' - \frac{\mathcal{L}t}{2}$$

$$\text{At } \omega = 0, \quad t_0 = \frac{2\sqrt{\omega_0}'}{\mathcal{L}}$$

$$\langle \omega \rangle = \frac{\int_0^{t_0} \omega dt}{\int_0^{t_0} dt} = \frac{\int_0^{t_0} \left(\omega_0 - \mathcal{L}t\sqrt{\omega_0}' + \frac{\mathcal{L}^2 t^2}{4} \right) dt}{\int_0^{t_0} dt}$$

$$= \frac{\left(\omega_0 t - \frac{\mathcal{L}}{2} \sqrt{\omega_0}' t^2 + \frac{\mathcal{L}^2 t^3}{12} \right) \bigg|_0^{2\sqrt{\omega_0}'/\mathcal{L}}}{\frac{2\sqrt{\omega_0}'}{\mathcal{L}}} =$$

$$= \frac{\frac{2\omega_0^{3/2}}{\mathcal{L}} - \frac{\mathcal{L}\omega_0^{3/2} \mathcal{L}}{2\mathcal{L}^2} + \frac{\mathcal{L}^2 8\omega_0^{3/2}}{12\mathcal{L}^3}}{\frac{2\sqrt{\omega_0}'}{\mathcal{L}}} = \frac{\omega_0}{3}$$

1.49

$$\omega = \omega_0 + a\varphi, \quad t=0 \rightarrow \varphi=0$$

$$a) \quad \omega = \frac{d\varphi}{dt}$$

$$\omega_0 + a\varphi = \frac{d\varphi}{dt}$$

$$\int_0^{\varphi(t)} \frac{d\varphi}{\omega_0 + a\varphi} = \int_0^t dt$$

$$-\frac{1}{a} \ln |\omega_0 + a\varphi| \bigg|_0^{\varphi(t)} = t$$

$$\ln \left| \frac{\omega_2 - a \varphi(t)}{\omega_0} \right| = -t a$$

$$1 - \frac{a}{\omega_0} \varphi(t) = e^{-t a}$$

$$\varphi(t) = \frac{\omega_0}{a} (-e^{-at} + 1)$$

$$\delta) \quad \vec{\beta} = \frac{d\vec{\omega}}{dt} \quad \omega = \frac{d\varphi}{dt} = \omega_0 e^{-at}$$

1.50

$$\vec{\beta} = \vec{\beta}_0 \cos \varphi$$

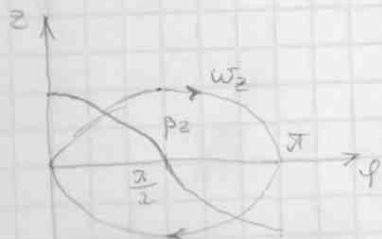
$$\frac{d\omega_z}{dt} = \beta_z, \quad \frac{d\varphi}{dt} = \omega_z$$

$$\omega_z \frac{d\omega_z}{d\varphi} = \beta_0 \cos \varphi$$

$$\int_0^{\omega(\varphi)} \omega_z d\omega_z = \int_0^{\varphi} \beta_0 \cos \varphi d\varphi$$

$$\frac{\omega(\varphi)^2}{2} = \beta_0 \sin \varphi$$

$$\omega(\varphi) = \pm \sqrt{2 \beta_0 \sin \varphi}$$



1.56

$$\vec{w} = at\vec{i} + bt^2\vec{j}$$

$$w = |\vec{w}| = \sqrt{a^2t^2 + b^2t^4}$$

$$\vec{\beta} = \frac{d\vec{w}}{dt} = a\vec{i} + 2bt\vec{j}$$

$$\beta = |\vec{\beta}| = \sqrt{a^2 + 4b^2t^2}$$

1.58

$$w' = \beta_0 t$$

$$\vec{w} = \vec{w}' + \vec{w}_0$$

$$\vec{w}' \perp \vec{w}_0$$

$$w = \sqrt{w'^2 + w_0^2} =$$

$$= \sqrt{w_0^2 + \beta_0^2 t^2}$$

$$\vec{\beta} = \frac{d\vec{w}}{dt} = \frac{d(\vec{w}' + \vec{w}_0)}{dt} = \frac{d\vec{w}'}{dt} + \frac{d\vec{w}_0}{dt}$$

$$\frac{d\vec{w}_0}{dt} = \vec{w}' \times \vec{w}_0, \quad \frac{d\vec{w}'}{dt} = \vec{\beta}_0 \times$$

$$\vec{\beta} = (\vec{\beta}_0 t + \vec{w}_0) + \vec{\beta}_0$$

$$\vec{\beta}_0 \perp \vec{w}_0; \quad \beta = \sqrt{(w_0 \beta_0 t)^2 + \beta_0^2}$$