

# SRM INSTITUTE OF SCIENCE & TECHNOLOGY DEPARTMENT OF COMPUTER SCIENCE AND ENGINEERING 18CSC305J-ARTIFICIAL INTELLIGENCE

# SEMESTER - 6

# BATCH-2

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**LAB:** 1

**DATE: 21-01-2021** 

**TOY PROBLEM** 

Problem Statement: Given an integer N and an array of seats[] where N is the number of

people standing in a line to buy a movie ticket and seat[i] is the number of empty seats in the ith

row of the movie theater. The task is to find the maximum amount a theater owner can make by

selling movie tickets to N people. Price of a ticket is equal to the maximum number of empty

seats among all the rows.

Algorithm:

1. Initialize queue q insert all seats array elements to the queue.

2. Tickets sold and the amount generated to be set to 0.

3. If tickets sold  $\leq$  N (People in the queue) and q top  $\geq$  0

4. Then remove top element from queue and update total amount

5. Repeat step 3 and 4 until tickets sold = number of people in the queue.

**Optimization technique:** This problem can be solved by using a priority queue that will store

the count of empty seats for every row and the maximum among them will be available at the

top.

1. Create an empty priority queue q and traverse the seats[] array and insert all elements

into the priority queue.

2. Initialize two integer variable ticketSold = 0 and ans = 0 that will store the number of

tickets sold and the total collection of the amount so far.

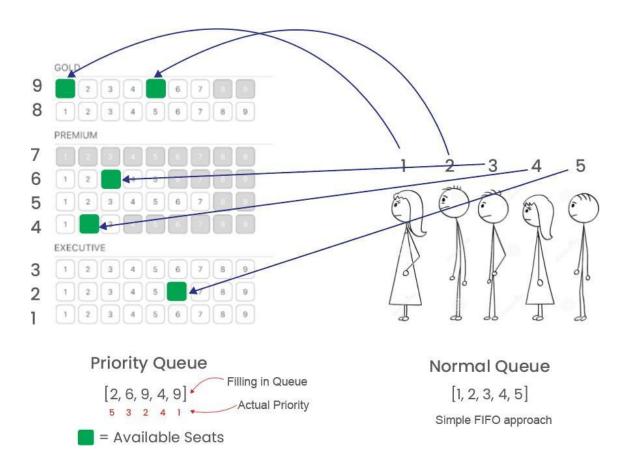
3. Now check while ticketSold  $\leq$  N and q.top()  $\geq$  0 then remove the top element from the

priority queue and update ans by adding top element of the priority queue. Also store

this top value in a variable temp and insert temp -1 back to the priority queue.

4. Repeat these steps until all the people have been sold the tickets and print the final result.

3



 $\textbf{Tool:} \ VS \ Code \ and \ Python \ 3.9.0$ 

# **Programming code:**

 $def \ maxAmount(M, N, seats):$  q = []  $for \ i \ in \ range(M):$  q.append(seats[i])

```
ticketSold = 0
       ans = 0
       q.sort(reverse = True)
       while (ticketSold \leq N and q[0] \geq 0):
               ans = ans + q[0]
               temp = q[0]
               q = q[1:]
               q.append(temp - 1)
               q.sort(reverse = True)
               ticketSold += 1
       return ans
if __name__== '_main_':
       seats = []
       rows = int(input("Enter number of rows available : "))
       for i in range(0, rows):
               empty = int(input())
```

# seats.append(empty)

```
print(seats)

M = len(seats)

N = int(input("Enter the number of People standing in the queue : "))
print("Maximum Profit generated = ", maxAmount(N, M, seats))
```

# Output screen shots:

```
PS E:\Studies\SRM University\SEM 6\AI\week 1> python -u "e:\Studies\SRM University\SEM 6\AI\week 1\solution.py"
Enter number of rows available : 4
2
3
5
3
[2, 3, 5, 3]
Enter the number of People standing in the queue : 4
Maximum Profit generated = 15
```

**Result :** Successfully found out the maximum amount the theater owner can make by selling movie tickets to N people for a movie.

**LAB: 2** 

DATE: 29-01-2021

#### **GRAPH COLORING PROBLEM**

PROBLEM STATEMENT: Given a graph color its edges such that no two adjacent have the same color using minimum number of colors and return the Chromatic number.

#### **ALGORITHM:**

Initialize:

1. Color first vertex with first color.

Loop for remaining V-1 vertices.:

- 1. Consider the currently picked vertex and color it with the lowest numbered color that has not been used on any previously colored vertices adjacent to it.
- 2. If all previously used colors appear on vertices adjacent to v, assign a new color to it.
- 3. Repeat the following for all edges.
- 4. Index of color used is the chromatic number.

# **OPTIMIZATION TECHNIQUE:**

Graph coloring problem is to assign colors to certain elements of a graph subject to certain constraints.

Vertex coloring is the most common graph coloring problem. The problem is, given m colors, find a way of coloring the vertices of a graph such that no two adjacent vertices are colored using

the same color. The other graph coloring problems like Edge Coloring (No vertex is incident to two edges of same color) and Face Coloring (Geographical Map Coloring) can be transformed into vertex coloring.

Chromatic Number: The smallest number of colors needed to color a graph G is called its chromatic number. For example, the following can be colored at least 2 colors.

**TOOLS:** VS Code, Python 3.9.0

## **CODE - EDGE COLORING:**

```
import matplotlib.pyplot as plt
```

import networkx as nx

from matplotlib.patches import Polygon

import numpy as np

$$G = nx.Graph()$$

```
colors = {0:"red", 1:"green", 2:"blue", 3:"yellow"}
```

```
G.add\_nodes\_from([1,2,3,4,5])
```

```
nodes = list(G.nodes)
```

$$edges = list(G.edges)$$

```
color_of_edge = []
some_colors = ['red','green','blue','yellow']
for i in range(len(nodes) + 1):
color_lists.append([])
color_of_edge.append(-1)
def getSmallestColor(ls1,ls2): i
= 1
while(i in ls1 or i in ls2): i =
i + 1
return i
#iterate over edges i
=0
for ed in edges:
newColor = getSmallestColor(color_lists[ed[0]],color_lists[ed[1]])
color lists[ed[0]].append(newColor)
color lists[ed[1]].append(newColor)
color_of_edge[i] = newColor i =
i + 1
# Makin graph again
```

G = nx.Graph()

for i in range(len(edges)):

G.add\_edge(edges[i][0],edges[i][1],color=some\_colors[color\_of\_edge[i]-1])

 $colors = nx.get\_edge\_attributes(G,'color').values()$ 

nx.draw(G, edge\_color=colors, with\_labels=True, width=2)

plt.show()

# **OUTPUT:**

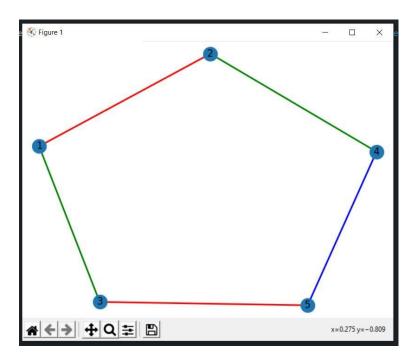


Fig: Edge Coloring

# **CODE - VERTEX COLORING:**

```
import matplotlib.pyplot as plt
import networkx as nx
G = nx.Graph()
colors = {0:"red", 1:"green", 2:"blue"}
G.add\_nodes\_from([1,2,3,4,5])
G.add_edges_from([(1,2), (1,3), (2,4), (3,5), (4,5)])
d
        nx.coloring.greedy_color(G,
                                        strategy
                                                       "largest_first")
node_colors = []
                          (d.keys()):
for
           in
                sorted
node\_colors.append(colors[d[i]])
nx.draw(G, node_color = node_colors, with_labels = True, width = 5)
plt.show()
```

# **OUTPUT:**

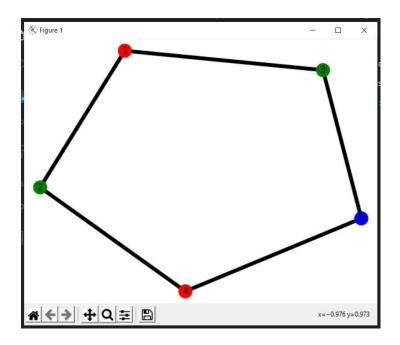


Fig: Vertex Coloring

# **CODE - FACE COLORING:**

```
import networkx as nx

G = nx.Graph()

colors = {0:"red", 1:"green", 2:"blue", 3:"yellow"}

G.add_nodes_from([1,2,3,4,5])

G.add_edges_from([(1,2), (1,3), (2,4), (3,4), (4,5)])

nodes = list(G.nodes)

edges = list(G.edges)

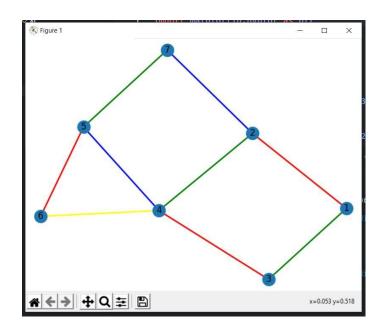
some_colors = ['red','green','blue','yellow']

no_of_faces = len(edges)+2-len(nodes)-1

def regionColour(regions):
```

```
print("NO OF FACES : "+str(regions)) for i
in range(1,regions+1):
print("FACE 1 : "+some_colors[i%4])
regionColour(no_of_faces)
```

# **OUTPUT:**



```
NO OF FACES: 3

FACE 1: green

FACE 2: blue

FACE 3: yellow

PS E:\Studies\SRM University\SEM 6\AI>
```

fig: Face Coloring

# **RESULT:**

Edge, vertex and face coloring problem which are together known as graph coloring problem solved and visualized in an optimized way using greedy approach.

**LAB:3** 

**DATE: 05-02-2021** 

#### CONSTRAINT SATISFACTION PROBLEM

1) SEND + MORE = MONEY

5 4 3 2 1

S E N D

+ MORE

c3 c2 c1

-----

#### MONEY

- 1. From Column 5, M=1, since it is the only carry-over possible from the sum of 2 single digit numbers in column 4.
- 2. To produce a carry from column 4 to column 5 'S + M' is at least 9 so 'S=80r9' so 'S+M=90r10' & so 'O = 0 or 1'. But 'M=1', so 'O = 0'.
- 3. If there is c+rry from Column 3 to 4 then 'E=9' & so 'N=0'.

  But 'O = 0' so there is no carry & 'S=9' & 'c3=0'.
- 4. If there is no carry from column 2 to 3 then 'E=N' which is impossible, therefore there is carry & 'N=E+1' & 'c2=1'.
- 5. If there is carry from column 1 to 2 then 'N+R=E mod 10' & 'N=E+1' so 'E+1+R=E mod 10', so 'R=9' but 'S=9', so there must be c+rry from column 1 to 2. Therefore 'c1=1' & 'R=8'.
- 6. To produce carry 'c1=1' from column 1 to 2, we must h+ve'D+E=10+Y'

as Y cannot be 0/1 so D+E is at least 12. As D is at most 7 & E is

At least 5 (D cannot be 8 or 9 as it is already assigned). N is at most 7 & 'N=E+1' so 'E=5or6'.

- 7. If E were 6 & D+E at least 12 then D would be 7, but 'N=E+1' & N would also be 7 which is impossible. Therefore 'E=5' & 'N=6'.
- 8. D+E is at least 12 for that we get 'D=7' & 'Y=2'.

# SOLUTION:

- ) ; ; · ·
- -1);
  - -----
- 1 0 6 5 2

# VALUES:

- S=9
- *E*=5
- *N*=6
- D=7
- M=1
- *0=0*
- R=8
- *Y*=2

#### 2. BASE + BALL = GAMES

Assuming numbers can't start with 0, G is 1 because two four-digit numbers can't sum to 20000 or more. SE+LL=ES or 1ES.

If it is ES, then LL must be a multiple of 9 because SE and ES are always congruent mod 9. But LL is a multiple of 11, so it would have to be 99, which is impossible.

So SE+LL=1ES. LL must be congruent to 100 mod 9. The only multiple of 11 that work is 55, so L is 5.

SE+55=1ES. This is possible when E+5=S. The possibilities for ES are 27, 38, or 49.

BA+BA+1=1AM. B must be at least 5 because B+B (possibly +1 from a carry) is at least 10.

If A is less than 5, then A+A+1 does not carry, a and A must be even. Inversely, if A is greater than 5, it must be odd. The possibilities for A are 0, 2, 4, 7, or 9.

0 does not work because M would have to be 1.

2 and 7 don't work because M would have to be 5. 9

doesn't work because M would also have to be 9.

So A is 4, M is 9, and B is 7. This leaves 38 as the only possibility for ES. The

## full equation is:

7483

+ 7455

14938

## 3. TWO + TWO = FOUR

F = 1 for carry over  $T \ge 5$ .

'O' can't be 0 as R will be 0. So T can't be 5 so let  $T \ge 6$ 

If T = 6, O = 2 and R = 4 and W + W = U for W can't be 1,2,6,4. W < 4 + s to

avoid carry over. W can't be 3 as U will be 6.

So T = 7, so, O can be 4 or 5 depending on whether or W + W > 10. If O is 4 then R

= 8. W can't be 1, 2. So W = 3

If W = 3 then U = 6 hence

*Here is one* + *answer:* 

734

+734

\_\_\_\_

1468

## 4. CROSS + ROADS= DANGER

Solution:

C5C4C3C2C1

**CROSS** 

+ROADS

DANGER

Since it is already mentioned that the carry value of resultaint cannot be 0 then

let's presume that the carry value of D is 1

We know that the sum of two similar values is even, hence R will have an even

value

Hence S+S= R So R is an even number for sure.

So the value of R can b (0, 2, 4, 6, 8)

Value of R cannot be 0 as two different values cannot be allotted the same

Digit, (if S=10 then their sum = 20 carry forward 2, then the value of R=0)

which is not possible.

IF S=1:

Not possible since D has the same value. IF

S = 2

Then R=4 which is possible Hence S=2 and R=4

C4+C+R=A+10

C4+C+4=A+10

C4+C>5 (Being the v+lue of c+rry will be gener+ted when the v+lue of C is

greater th+n 5

C=

C1+S+D=E

C1+2+1=E

Therefore E=3

C4+C+R= A+10

C4+9+4=A+10

Therefore A= 3 but it c+nnot be possible +s E= 3

Now let's Consider S+D+C1=E

2+1+0=3

Therefore E= 3 m+king C2= 0 since 2+1=3

Now let's consider the equation again:

C+R+C4=A+10

9+4+0=A+10

13 = A + 10

Therefore A= 3 but E= 3 So

A is not equ+1 to 3

Ag+in considering R= 6 So S= 3 C4= 0

C+R+C4=A+10

9+6+0=A+10

15 = A + 10

Therefore A=5

And S+D+C1=E

3+1+0= E therefore E= 4 +nd C2= 0

Now considering the equ+tion R+O+C3=

N

6+0+C3=N

So 6+0+C3< or equ+l to 3

Let C3 = 1

Then O< or equ+l to 2

Th+t is O=0, 1, 2

Let O = 2

Ag+in considering R+O+C3= N

6+2+1=N

Hence N= 9 but C= 9 so N c+nnot be equ+l to 9.

Now let N = 8 + nd C3 = 0

Let us consider equ+tion

O+A+C2=G

Therefore G= 7

Hence D= 1 S= 3 A= 5 G= 7 C= 9 O= 2 E= 4 R= 6 N= 8

And C1= 0 C2= 0 C3= 0 C4= 0 C5= 1

Now verifying the above values in the equ+tion we get:

C5C4C3C2C1

**CROSS** 

96233

**ROADS** 

62513

Shape

**DANGER** 

158746

## $5. \quad If AA + BB = ABC$

Explanation:

AA

BB+CC

-----

ABC

\_\_\_\_\_

The digits are distinct and positive. Let's first focus on the value A, when we add three 2 digit numbers the most you get is in the 200's (ex: AA + BB + CC = ABC u 99 + 88 + 77 = 264). From this, we can tell that the largest value of A can be 2. So Either A = 1 or A = 2.

Now focus on value B, let's take the unit digit of the given question: A + B + C = C (units). This can happen only if A + B = 0 (in the units) u A and B add up to 10. Two possibilities: 11 + 99 + CC = 19C u (1) or 22 + 88 + CC = 28C u (2)

Focus on ten's place, 1 + C = 8, here C = 7. Then 22 + 88 + 77 = 187

Thus, Equ+tion (2) is not possible.

Take equation (2), 110 + CC = 28C

From Equ+tion (1), 11+99+CC = 19C u 110 + CC = 19C u 1 + C = 9, then C = 8.

11 + 99 + 88 = 198 u hence solved A = 1, B = 9 + nd C = 8 A

+B+C=18

# 6. NO + GUN + NO = HUNT

Solution:

N O

+ GUNN

O

HUNT

Here H = 1, from the NUNN column we must have "carry 1," so G = 9, U = zero. Since we have "carry" zero or 1 or 2 from the ONOT column, correspondingly we h+ve N + U = 10 or 9 or 8. But duplication is not allowed, so N = 8 with "carry 2" from ONOT. Hence, O + O = T + 20 - 8 = T + 12. Testing for T = 2, 4 or 6, we find only T = 2 +accept+able, O = 7. So we h+ve 87 + 908 + 87 = 1082.

# **TOOLS:** VS Code, Python 3.9.0

## **CODE:**

```
def solutions():
# letters = ('s', 'e', 'n', 'd', 'm', 'o', 'r', 'y')
     all solutions = list()
for s in range(9, -1, -1):
for e in range(9, -1, -1):
for n in range(9, -1, -1):
for d in range(9, -1, -1):
for m in range(9, 0, -1):
for o in range(9, -1, -1):
for r in range(9, -1, -1):
for y in range(9, -1, -1):
if len(set([s, e, n, d, m, o, r, y])) == 8: send = 1000 * s + 100 * e +
                             10 * n + d more = 1000 * m + 100 * o
                             +10 * r + e
money = 10000 * m + 1000 * o + 100 * n + 10 * e + y
if send + more == money: all_solutions.append((send, more, money))
return all solutions
print(solutions()
```

# **OUTPUT:**

```
PS E:\Studies\SRM University\SEM 6\AI> python -u [(9567, 1085, 10652)]
PS E:\Studies\SRM University\SEM 6\AI> [
```

# **RESULT:**

The constraint satisfying problem SEND + MORE = MONEY solved using the carry over technique and values for the alphabets obtained successfully.

# **Experiment No: 4**

Date: 12-02-2021

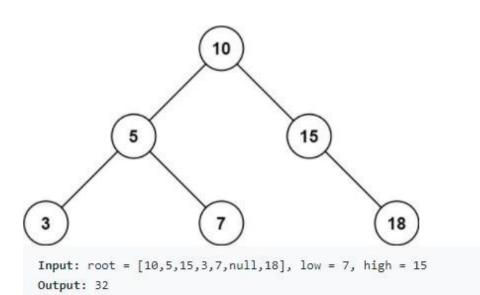
# RANGE SUM OF BINARY SEARCH TREE

# (Implementation and Analysis of DFS and BFS for an application)

**AIM**: Given the root node of a binary search tree, return the sum of values of all nodes with a value in the range [low, high] using depth first and then breadth first search.

# While:

- The number of nodes in the tree is in the range [1, 2 \* 104].
- 1 <= Node.val <= 105
- $1 \le low \le high \le 105$
- All Node.value are unique.



#### **ALGORITHM #1 DFS:**

- 1. Traverse the tree using a depth first search.
- 2. Create a stack to store accessed nodes.
- 3. If node.value falls outside the range [L, R]
- 4. Then only the right branch could have nodes with value inside [L, R].
- 5. If Left <= node.value <= Right then Result[0] += node.value
- 6. Else, recursively call the function until all nodes are visited.

#### **ALGORITHM #2 BFS:**

- 1. Traverse the tree using the breadth first search approach.
- 2. Maintain a queue and ptr to point toward the current node.
- 3. If node == None then continue.
- 4. If Left <= node.value <= Right the result += node.value
- 5. If Left > node.value then queue.append(node.right)
- 6. If R < node.value then queue.append(node.left)
- 7. Repeat till all nodes are visited.

## **OPTIMIZATION TECHNIQUE:**

Time Complexity: O(N), where N is the number of nodes in the tree. Space Complexity: O(N). For the recursive implementation, the recursion will consume additional space in the function call stack. In the worst case, the tree is of chain shape, and we will reach all the way down to the leaf node. For the iterative implementation, essentially we are doing a BFS (Breadth-First Search) traversal, where the stack will contain no more than two levels of the nodes. The maximal number of nodes in a binary tree is N/2.

Therefore, the maximal space needed for the stack would be O(N).

```
TOOLS: VS Code and Python 3.9.0
DEPTH FIRST SEARCH (DFS) CODE:
#ITERATIVE APPROACH
class Solution(object):
  def rangeSumBST(self, root, L, R):
    def dfs(node):
      if node:
         if L \le node.val \le R:
           self.ans += node.val
         if L < node.val:
           dfs(node.left)
         if node.val < R:
           dfs(node.right)
    self.ans = 0
                   dfs(root)
    return self.ans
# RECURSIVE APPROACH
def rangeSumBST(root, L, R):
  ans = 0
  stack = [root]
  while stack:
    node = stack.pop()
    if node:
```

```
if L <= node.val <= R:
    ans += node.val

if L < node.val:
    stack.append(node.left)

if node.val < R:
    stack.append(node.right)

return ans</pre>
```

## **DEPTH FIRST SEARCH OUTPUT:**

```
PS E:\Studies\SRM University\SEM 6\AI> python -u
Enter the Lower value of the range : 7
Enter the Higher value of the range : 15
The sum of the nodes in the range 7 and 15 is 32
PS E:\Studies\SRM University\SEM 6\AI>
```

## **BREADTH FIRST (BFS) CODE:**

```
class TreeNode:
    def __init__(self, val=0, left=None, right=None):
        self.val = val
        self.left = left
        self.right = right

class Solution(object):
    def rangeSumBST(self, root, L, R):
        if root == None:
            return 0
        res = 0
        q = [root]
        while q:
```

```
next = []
for node in q:
    if L <= node.val <= R:
        res += node.val
    if node.left:
        next.append(node.left)
    if node.right:
        next.append(node.right)
    q = next

return res

bst = TreeNode(10, 7, 15)
Solution().rangeSumBST(bst,10,7,15)</pre>
```

## **BREADTH FIRST OUTPUT:**

```
PS E:\Studies\SRM University\SEM 6\AI> python -u
Enter the Lower value of the range : 7
Enter the Higher value of the range : 15
The sum of the nodes in the range 7 and 15 is 32
PS E:\Studies\SRM University\SEM 6\AI>
```

**RESULT:** Successfully found the sum of nodes in a binary search tree between any given range (min, max) using both depth first search and breadth first search approach.

**Experiment No: 5** 

Date: 26-02-2021

**CUT OF TREE FOR GOLF EVENT** 

(Implementation and Analysis of BFS and A\* Search)

AIM: You are asked to cut off all the trees in a forest for a golf event. The forest is represented

as an m x n matrix. In this matrix:

• 0 means the cell cannot be walked through.

• 1 represents an empty cell that can be walked through.

• A number greater than 1 represents a tree in a cell that can be walked through, and

this number is the tree's height.

In one step, you can walk in any of the four directions: north, east, south, and west. If you are

standing in a cell with a tree, you can choose whether to cut it off.

You must cut off the trees in order from shortest to tallest. When you cut off a tree, the value at

its cell becomes 1 (an empty cell).

Starting from the point (0, 0), return the minimum steps you need to walk to cut off all the trees.

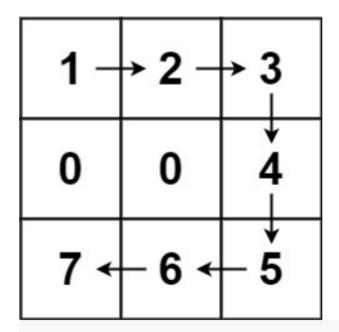
If you cannot cut off all the trees, return -1.

You are guaranteed that no two trees have the same height, and there is at least one tree that

needs to be cut off.

30

# Example 1:



**Input:** forest = [[1,2,3],[0,0,4],[7,6,5]]

Output: 6

Explanation: Following the path above allows you to cut off

the trees from shortest to tallest in 6 steps.

#### **ALGORITHM #1 BFS:**

- 1. Perform best-first-search, processing nodes (grid positions) in a queue.
- 2. Seen keeps track of nodes that have already been added to the queue at some point.
- 3. Those nodes will be already processed or are in the queue awaiting processing.
- 4. For each node that is next to be processed, look at it's neighbors. If they are in the forest (grid), they haven't been enqueued, and they aren't an obstacle, we will enqueue that neighbor.
- 5. Keep a side count of the distance travelled for each node. If the node we are processing is our destination 'target' (tr, tc), we'll return the answer.

**ALGORITHM #1 A\* SEARCH:** 

1. The A\* star algorithm is another path-finding algorithm

2. For every node at position (r, c), have some estimated cost node  $f = node \cdot g + node \cdot h$ 

3. node.g is the actual distance from (sr, sc) to (r, c).

4. node.h is our heuristic (guess) of the distance from (r, c) to (tr, tc).

5. The taxicab distance, node.h = abs(r-tr) + abs(c-tc).

6. Keep a priority queue to decide what node to search in (expand) next.

**OPTIMIZATION TECHNIQUE:** 

Frame the problem as providing some distance function dist(forest, sr, sc, tr, tc) that calculates the

path distance from source (sr, sc) to target (tr, tc) through obstacles dist[i][j] == 0. (This distance

function will return -1 if the path is impossible.)

What follows is code and complexity analysis that is common to all three approaches. After, the

algorithms presented in our approaches will focus on only providing our dist function.

All three algorithms have similar worst case complexities, but in practice each successive

algorithm presented performs faster on random data.

Time Complexity: O((RC)^2) where there are R rows and C columns in the given forest. We walk

to R\*C trees, and each walk could spend O(R\*C) time searching for the tree.

Space Complexity: O(R\*C), the maximum size of the data structures used.

**TOOLS:** Python 3.9.0 and VS Code.

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#### **CODE #1 BFS:**

#### **OUTPUT #1 BFS:**

```
PS E:\Studies\SRM University\SEM 6\AI> Input: forest = [[1,2,3],[0,0,4],[7,6,5]] >> Output: 6
```

#### **CODE #2 A\* SEARCH:**

```
def astar(forest, sr, sc, tr, tc):
    R, C = len(forest), len(forest[0])
    heap = [(0, 0, sr, sc)]
    cost = {(sr, sc): 0}
    while heap:
        f, g, r, c = heapq.heappop(heap)
        if r == tr and c == tc: return g
        for nr, nc in ((r-1,c), (r+1,c), (r,c-1), (r,c+1)):
        if 0 <= nr < R and 0 <= nc < C and forest[nr][nc]:
            ncost = g + 1 + abs(nr - tr) + abs(nc - tc)
            if ncost < cost.get((nr, nc), 9999):
            cost[nr, nc] = ncost
            heapq.heappush(heap, (ncost, g+1, nr, nc))
        return -1</pre>
```

## **OUTPUT #2 A\* SEARCH:**

```
PS E:\Studies\SRM University\SEM 6\AI> Input: forest = [[1,2,3],[0,0,4],[7,6,5]] >> Output: 6
```

**RESULT:** The cutting off of tree problem for a golf event successfully solved with 2 different approaches: Best first search and A\* search algorithm.

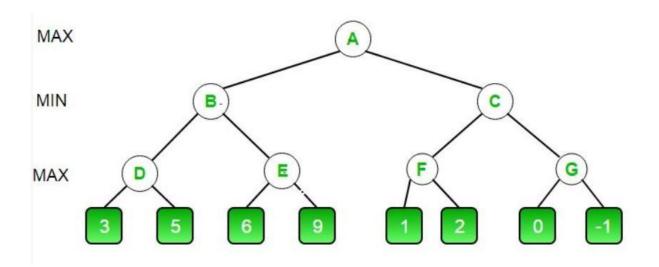
**Experiment No: 6** 

Date: 26-02-2021

## MINIMAX ALGORITHM IN ALPHA BETA PRUNING

**AIM**: Developing a mini max algorithm for real world problems.

**PROBLEM**: Find the optimal value in the given tree of integer values in the most optimal way possible under the time complexity O(B^D).



## **ALGORITHM MINIMAX APPROACH:**

- 1. Start traversing the given tree in top to bottom manner.
- 2. If node is a leaf node then return the value of the node.
- 3. If isMaximizingPlayer exist then bestVal = -INFINITY
- 4. For each child node, value = minimax(node, depth+1, false, alpha, beta)
- 5. bestVal = max(bestVal, value) and alpha = max(alpha, bestVal)
- 6. If beta <= alpha then stop traversing and return bestVal
- 7. Else, bestVal = +INFINITY
- 8. For each child node, value = minimax(node, depth+1, true, alpha, beta)

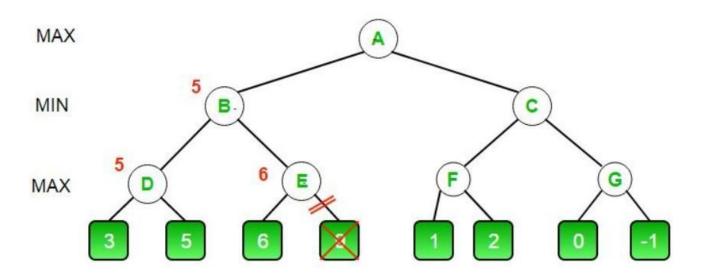
- 9. bestVal = min( bestVal, value) and beta = min( beta, bestVal)
- 10. if beta <= alpha the stop traversing and return bestVal

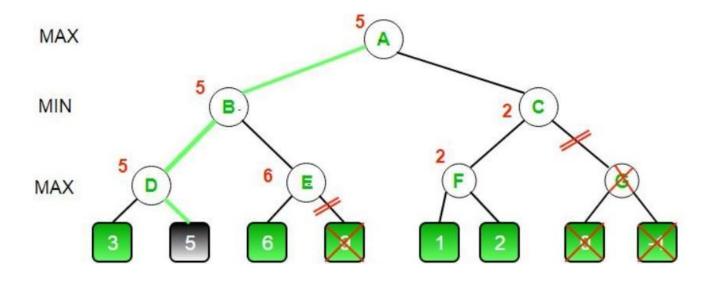
# **OPTIMIZATION TECHNIQUE:**

Alpha-Beta pruning is not actually a new algorithm, rather an optimization technique for minimax algorithms. It reduces the computation time by a huge factor. This allows us to search much faster and even go into deeper levels in the game tree. It cuts off branches in the game tree which need not be searched because there already exists a better move available. It is called Alpha-Beta pruning because it passes 2 extra parameters in the minimax function, namely alpha and beta. Let's define the parameters alpha and beta.

**Alpha** is the best value that the **maximizer** currently can guarantee at that level or above.

Beta is the best value that the minimizer currently can guarantee at that level or above.





# **CODE (MINIMAX ALGORITHM):**

```
MAX, MIN = 1000, -1000

def minimax(depth, nodeIndex, maximizingPlayer, values, alpha, beta):

if depth == 3:
    return values[nodeIndex]

if maximizingPlayer:

best = MIN

for i in range(0, 2):

val = minimax(depth + 1, nodeIndex * 2 + i, False, values, alpha, beta)

best = max(best, val)
    alpha = max(alpha, best)

if beta <= alpha:
```

break

```
return best
       else:
              best = MAX
              for i in range(0, 2):
                      val = minimax(depth + 1, nodeIndex * 2 + i,
                                                   True, values, alpha, beta)
                      best = min(best, val)
                      beta = min(beta, best)
                      if beta <= alpha:
                             break
              return best
if name == " main ":
  values = []
  for i in range(0, 8):
    x = int(input(f"Enter Value {i} : "))
    values.append(x)
  print ("The optimal value is:", minimax(0, 0, True, values, MIN, MAX))
```

# **OUTPUT:**

```
PS E:\Studies\SRM University\SEM 6\AI> python
Enter Value 0 : 3
Enter Value 1 : 5
Enter Value 2 : 6
Enter Value 3 : 9
Enter Value 4 : 1
Enter Value 5 : 2
Enter Value 6 : 0
Enter Value 7 : -1
The optimal value is : 5
PS E:\Studies\SRM University\SEM 6\AI>
```

**RESULT:** The Optimal value of the given tree successfully found using Minimax Algorithm with Alpha Beta Pruning in time complexity  $O(B^D)$ .

**Experiment No: 7** 

Date: 13-04-21

## IMPLEMENTATION OF UNIFICATION AND RESOLUTION

**PROBLEM STATEMENT:** Developing an optimized technique using an appropriate artificial intelligence algorithm to solve the Unification and Resolution.

### **ALGORITHM:**

- 1. function PL-RESOLUTION (KB, Q) returns true or false inputs: KB,
- 2. the knowledge base, group of sentences/facts in propositional logic
- 3. Q, the query, a sentence in propositional logic
- 4. clauses  $\rightarrow$  the set of clauses in the CNF representation of KB  $^{\land}$  Q new  $\rightarrow$  {}
- 5. loop do for each Ci, Cj in clauses do
- 6. resolvents  $\rightarrow$  PL-RESOLVE (Ci, Cj)
- 7. if resolvents contains the empty clause the return true
- 8.  $\text{new} \rightarrow \text{new union resolvents}$
- 9. if new is a subset of clauses then return false
- 10. clauses  $\rightarrow$  clauses union true

# **OPTIMIZATION TECHNIQUE:**

Resolution basically works by using the principle of proof by contradiction. To find the conclusion we should negate the conclusion. Then the resolution rule is applied to the resulting clauses. Each clause that contains complementary literals is resolved to produce a2. new clause, which can be added to the set of facts (if it is not already present). This process continues until one of the two things happen: There are no new clauses that can be added. An application of the resolution rule derives the empty clauseAn empty clause shows that the negation of the conclusion is a complete contradiction, hence the negation of the conclusion is invalid or false or the assertion is completely valid or true.

- 1. Convert the given statements in Predicate/Propositional Logic
- 2. Convert these statements into Conjunctive Normal Form
- 3. Negate the Conclusion (Proof by Contradiction)
- 4. Resolve using a Resolution Tree (Unification)

# **CODE UNIFICATION:**

```
def get_index_comma(string):
  index_list = list()
  par count = 0
  for i in range(len(string)):
     if string[i] == ',' and par count == 0:
        index list.append(i)
     elif string[i] == '(':
        par count += 1
     elif string[i] == ')':
       par count -= 1
  return index list
def is variable(expr):
  for i in expr:
     if i == '(' \text{ or } i == ')':
        return False
  return True
def process expression(expr):
  expr = expr.replace(' ', ")
```

index = None

```
for i in range(len(expr)):
     if expr[i] == '(':
       index = i
       break
  predicate symbol = expr[:index]
  expr = expr.replace(predicate_symbol, ")
  expr = expr[1:len(expr) - 1]
  arg list = list()
  indices = get index comma(expr)
  if len(indices) == 0:
     arg list.append(expr)
  else:
     arg_list.append(expr[:indices[0]])
     for i, j in zip(indices, indices[1:]):
       arg list.append(expr[i + 1:j])
     arg list.append(expr[indices[len(indices) - 1] + 1:])
  return predicate symbol, arg list
def get arg list(expr):
  _, arg_list = process_expression(expr)
  flag = True
  while flag:
     flag = False
     for i in arg list:
       if not is variable(i):
          flag = True
          _, tmp = process_expression(i)
```

```
for j in tmp:
            if j not in arg_list:
               arg_list.append(j)
          arg list.remove(i)
  return arg_list
def check occurs(var, expr):
  arg_list = get_arg_list(expr)
  if var in arg_list:
     return True
  return False
def unify(expr1, expr2):
  if is_variable(expr1) and is_variable(expr2):
     if expr1 == expr2:
       return 'Null'
     else:
       return False
  elif is_variable(expr1) and not is_variable(expr2):
     if check occurs(expr1, expr2):
       return False
     else:
       tmp = str(expr2) + '/' + str(expr1)
       return tmp
  elif not is variable(expr1) and is variable(expr2):
     if check_occurs(expr2, expr1):
       return False
```

```
else:
    tmp = str(expr1) + '/' + str(expr2)
     return tmp
else:
  predicate symbol 1, arg list 1 = process expression(expr1)
  predicate_symbol_2, arg_list_2 = process_expression(expr2)
  # Step 2
  if predicate symbol 1!= predicate symbol 2:
    return False
  # Step 3
  elif len(arg list 1) != len(arg list 2):
     return False
  else:
     # Step 4: Create substitution list
     sub list = list()
    # Step 5:
     for i in range(len(arg list 1)):
       tmp = unify(arg list 1[i], arg list 2[i])
       if not tmp:
          return False
       elif tmp == 'Null':
          pass
       else:
          if type(tmp) == list:
            for j in tmp:
               sub list.append(j)
          else:
            sub_list.append(tmp)
```

```
# Step 6
return sub_list

if __name__ == '__main__':

# f1 = 'Q(a, g(x, a), f(y))'
# f2 = 'Q(a, g(f(b), a), x)'
f1 = input('f1 : ')
f2 = input('f2 : ')

result = unify(f1, f2)
if not result:
    print('The process of Unification failed!')
else:
    print('The process of Unification successful!')
    print(result)
```

# **OUTPUT UNIFICATION:**

```
Vaishnavimoorthy:~/environment/RA1811028010049 $ python unification.py
f1 : 'Q(a, g(x, a), f(y))'
f2 : 'Q(a, g(f(b), a), x)'
The process of Unification successful!
['f(b)/x', 'f(y)/x']
Vaishnavimoorthy:~/environment/RA1811028010049 $
```

## **CODE RESOLUTION:**

```
import copy
import time
class Parameter:
  variable_count = 1
  def init (self, name=None):
    if name:
       self.type = "Constant"
       self.name = name
     else:
       self.type = "Variable"
       self.name = "v" + str(Parameter.variable_count)
       Parameter.variable_count += 1
  def isConstant(self):
    return self.type == "Constant"
  def unify(self, type_, name):
     self.type = type
     self.name = name
  def eq (self, other):
    return self.name == other.name
  def __str__(self):
    return self.name
```

class Predicate:

```
def __init__(self, name, params):
     self.name = name
     self.params = params
  def eq (self, other):
     return self.name == other.name and all(a == b for a, b in zip(self.params, other.params))
  def str (self):
    return self.name + "(" + ",".join(str(x) for x in self.params) + ")"
  def getNegatedPredicate(self):
     return Predicate(negatePredicate(self.name), self.params)
class Sentence:
  sentence count = 0
  def init (self, string):
     self.sentence index = Sentence.sentence count
     Sentence sentence count += 1
     self.predicates = []
     self.variable map = {}
     local = \{\}
     for predicate in string.split("|"):
       name = predicate[:predicate.find("(")]
       params = []
       for param in predicate[predicate.find("(") + 1: predicate.find(")")].split(","):
          if param[0].islower():
            if param not in local: # Variable
               local[param] = Parameter()
```

```
self.variable_map[local[param].name] = local[param]
         new param = local[param]
       else:
         new param = Parameter(param)
          self.variable map[param] = new param
       params.append(new param)
     self.predicates.append(Predicate(name, params))
def getPredicates(self):
  return [predicate.name for predicate in self.predicates]
def findPredicates(self, name):
  return [predicate for predicate in self.predicates if predicate.name == name]
def removePredicate(self, predicate):
  self.predicates.remove(predicate)
  for key, val in self.variable map.items():
     if not val:
       self.variable map.pop(key)
def contains Variable(self):
  return any(not param.isConstant() for param in self.variable map.values())
def eq (self, other):
  if len(self.predicates) == 1 and self.predicates[0] == other:
     return True
  return False
def __str__(self):
  return "".join([str(predicate) for predicate in self.predicates])
```

```
class KB:
  def init (self, inputSentences):
    self.inputSentences = [x.replace(" ", "") for x in inputSentences]
     self.sentences = []
     self.sentence map = \{\}
  def prepareKB(self):
     self.convertSentencesToCNF()
     for sentence string in self.inputSentences:
       sentence = Sentence(sentence string)
       for predicate in sentence.getPredicates():
         self.sentence map[predicate] = self.sentence map.get(
            predicate, []) + [sentence]
  def convertSentencesToCNF(self):
     for sentenceIdx in range(len(self.inputSentences)):
       # Do negation of the Premise and add them as literal
       if "=>" in self.inputSentences[sentenceIdx]:
          self.inputSentences[sentenceIdx] = negateAntecedent(
            self.inputSentences[sentenceIdx])
  def askQueries(self, queryList):
    results = []
     for query in queryList:
       negatedQuery = Sentence(negatePredicate(query.replace(" ", "")))
       negatedPredicate = negatedQuery.predicates[0]
       prev sentence map = copy.deepcopy(self.sentence map)
       self.sentence map[negatedPredicate.name] = self.sentence map.get(
         negatedPredicate.name, []) + [negatedQuery]
```

```
self.timeLimit = time.time() + 40
    try:
       result = self.resolve([negatedPredicate], [
                    False]*(len(self.inputSentences) + 1))
    except:
       result = False
    self.sentence map = prev sentence map
    if result:
       results.append("TRUE")
    else:
       results.append("FALSE")
  return results
def resolve(self, queryStack, visited, depth=0):
  if time.time() > self.timeLimit:
    raise Exception
  if queryStack:
    query = queryStack.pop(-1)
    negatedQuery = query.getNegatedPredicate()
    queryPredicateName = negatedQuery.name
    if queryPredicateName not in self.sentence map:
       return False
    else:
       queryPredicate = negatedQuery
       for kb sentence in self.sentence map[queryPredicateName]:
         if not visited[kb sentence.sentence index]:
            for kbPredicate in kb_sentence.findPredicates(queryPredicateName):
```

```
canUnify, substitution = performUnification(
  copy.deepcopy(queryPredicate), copy.deepcopy(kbPredicate))
if canUnify:
  newSentence = copy.deepcopy(kb sentence)
  newSentence.removePredicate(kbPredicate)
  newQueryStack = copy.deepcopy(queryStack)
  if substitution:
    for old, new in substitution.items():
       if old in newSentence.variable map:
         parameter = newSentence.variable map[old]
         newSentence.variable map.pop(old)
         parameter.unify(
            "Variable" if new[0].islower() else "Constant", new)
         newSentence.variable map[new] = parameter
    for predicate in newQueryStack:
       for index, param in enumerate(predicate.params):
         if param.name in substitution:
            new = substitution[param.name]
            predicate.params[index].unify(
              "Variable" if new[0].islower() else "Constant", new)
  for predicate in newSentence.predicates:
    newQueryStack.append(predicate)
  new visited = copy.deepcopy(visited)
  if kb sentence.containsVariable() and len(kb sentence.predicates) > 1:
    new visited[kb sentence.sentence index] = True
  if self.resolve(newQueryStack, new visited, depth + 1):
```

# return False return True def performUnification(queryPredicate, kbPredicate): substitution = {} if queryPredicate == kbPredicate: return True, {} else: for query, kb in zip(queryPredicate.params, kbPredicate.params): if query == kb: continue if kb.isConstant(): if not query.isConstant(): if query.name not in substitution: substitution[query.name] = kb.name elif substitution[query.name] != kb.name: return False, {} query.unify("Constant", kb.name) else: return False, {} else: if not query.isConstant(): if kb.name not in substitution: substitution[kb.name] = query.name elif substitution[kb.name] != query.name: return False, {} kb.unify("Variable", query.name) else:

if kb.name not in substitution:

substitution[kb.name] = query.name

return True

```
elif substitution[kb.name] != query.name:
               return False, {}
  return True, substitution
def negatePredicate(predicate):
  return predicate[1:] if predicate[0] == "\sim" else "\sim" + predicate
def negateAntecedent(sentence):
  antecedent = sentence[:sentence.find("=>")]
  premise = []
  for predicate in antecedent.split("&"):
     premise.append(negatePredicate(predicate))
  premise.append(sentence[sentence.find("=>") + 2:])
  return "|".join(premise)
def getInput(filename):
  with open(filename, "r") as file:
     noOfQueries = int(file.readline().strip())
    inputQueries = [file.readline().strip() for in range(noOfQueries)]
     noOfSentences = int(file.readline().strip())
     inputSentences = [file.readline().strip()
                for in range(noOfSentences)]
     return inputQueries, inputSentences
def printOutput(filename, results):
  print(results)
```

```
with open(filename, "w") as file:
     for line in results:
       file.write(line)
       file.write("\n")
  file.close()
if name == ' main ':
  inputQueries , inputSentences = getInput('input.txt')
  knowledgeBase = KB(inputSentences )
  knowledgeBase.prepareKB()
  results = knowledgeBase.askQueries(inputQueries)
  printOutput("output.txt", results )
INPUT RESOLUTION:
6
A(Alice)
~A(Alice)
Z(Zig)
\simZ(Zig)
G(Golf)
\simG(Good)
10
A(x) \Rightarrow B(x)
B(x) => C(x)
C(x) \Rightarrow D(x)
D(x) \Rightarrow E(x)
E(x) => A(x)
G(g)
H(h)
I(i)
J(j)
```

X(x)

# **OUTPUT RESOLUTION:**

```
Vaishnavimoorthy:~/environment $ cd RA1811028010049
Vaishnavimoorthy:~/environment/RA1811028010049 $ python resolution.py
['FALSE', 'FALSE', 'FALSE', 'TRUE', 'FALSE']
Vaishnavimoorthy:~/environment/RA1811028010049 $
```

**RESULT**: Developed Unification and Resolution Algorithm in Python for solving logical problems.

**Experiment No: 10** 

Date: 12-03-2021

### IMPLEMENTATION OF BLOCK WORLD PROBLEM

**AIM**: To implement the block world problem using correct artificial intelligence optimization techniques.

### **ALGORITHM:**

- 1. Initialise a stack to store the blocks.
- 2. Make sure the stack is empty when HEAD NODE.NEXT = NULL
- 3. Read the pattern of blocks given label it START STATE
- 4. Compare the given pattern to the given final pattern label it GOAL STATE
- 5. Now start the movement of the blocks one by on either one on top or to the floor according to the need.
- 6. Keep recording these movements in the empty stack created by STACK.PUSH and STACK.POP methods.
- 7. Stop the block manipulation when goal state is reached.

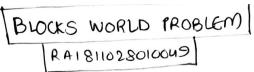
# **OPTIMIZATION TECHNIQUE:**

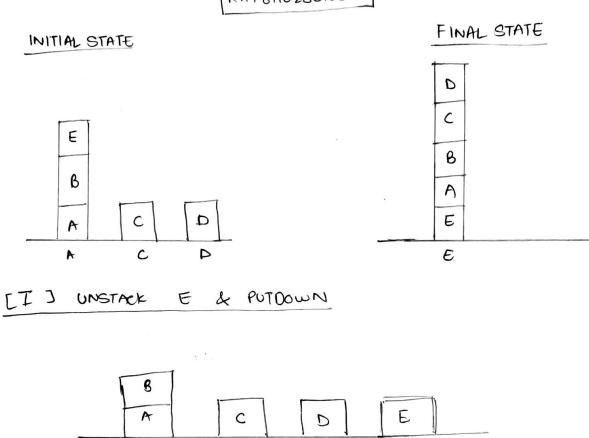
Here keeping track of movement of the block is the main problem, if we keep traversing the floor again and again after each move, our time complexity will be  $O(n^2)$  which is exponentially higher than what is needed and should be avoided.

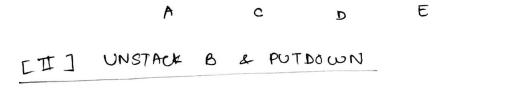
To solve this problem STACK data structure can be used, so whenever a movement is made the movement can be conveniently stored in the stack which will be initialized as empty which HEAD.NEXT = NULL.

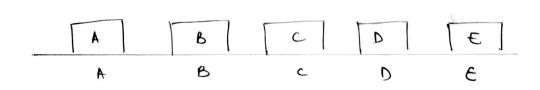
When the block is to be added to the sequence of blocks simply use STACK.PUSH() to make the movement. And when a block is supposed to be removed from the pattern of blocks STACK.POP() can be used to make that movement.

Implementing this will bring down the time complexity from O(n) and worst case of  $O(n^2)$  to O(1) that is unit time which is a major optimization from exponential time.

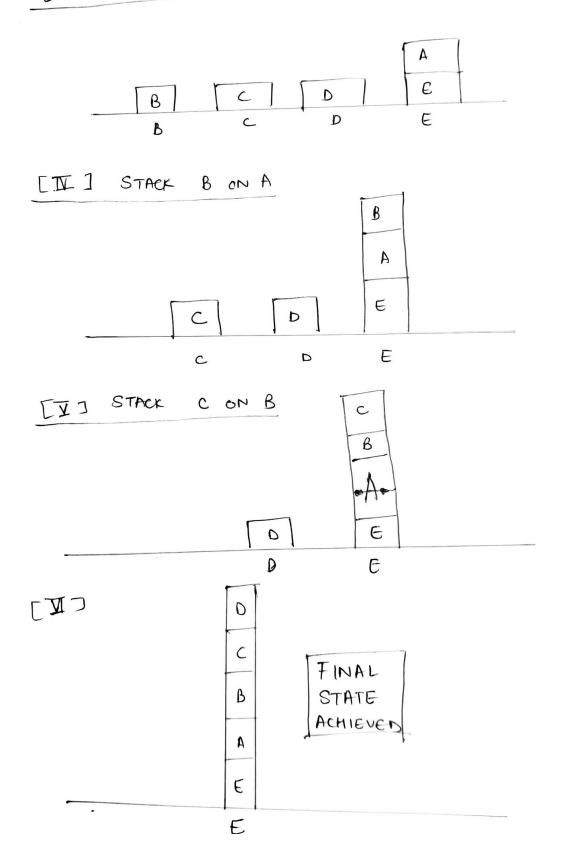








# CIII STACK A ON E



```
CODE:
class PREDICATE:
 def __str__(self):
  pass
 def __repr__(self):
  pass
 def __eq__(self, other) :
  pass
 def __hash__(self):
  pass
 def get_action(self, world_state):
  pass
class Operation:
 def __str__(self):
  pass
 def __repr__(self):
  pass
 def __eq__(self, other) :
  pass
 def precondition(self):
  pass
 def delete(self):
  pass
 def add(self):
  pass
```

```
return "ON({X},{Y})".format(X=self.X,Y=self.Y)
 def repr (self):
  return self. str ()
 def eq (self, other):
  return self. dict == other. dict and self. class == other. class
 def hash (self):
   return hash(str(self))
 def get action(self, world state):
  return StackOp(self.X,self.Y)
class ONTABLE(PREDICATE):
 def init_(self, X):
  self.X = X
 def __str__(self):
  return "ONTABLE({X})".format(X=self.X)
 def repr (self):
  return self. str ()
 def eq (self, other):
  return self. dict == other. dict and self. class == other. class
 def hash (self):
   return hash(str(self))
 def get action(self, world state):
  return PutdownOp(self.X)
class CLEAR(PREDICATE):
 def init (self, X):
  self.X = X
 def str (self):
  return "CLEAR({X})".format(X=self.X)
  self.X = X
 def __repr__(self):
  return self. str ()
```

```
def __eq__(self, other):
  return self. dict == other. dict and self. class == other. class
 def hash (self):
  return hash(str(self))
 def get action(self, world state):
  for predicate in world state:
   if isinstance(predicate,ON) and predicate.Y==self.X:
    return UnstackOp(predicate.X, predicate.Y)
  return None
class HOLDING(PREDICATE):
 def init_(self, X):
  self.X = X
 def str (self):
  return "HOLDING({X})".format(X=self.X)
 def repr (self):
  return self. str ()
 def eq (self, other):
  return self. dict == other. dict and self. class == other. class
 def hash (self):
  return hash(str(self))
 def get action(self, world state):
  X = self.X
  if ONTABLE(X) in world state:
   return PickupOp(X)
  else:
   for predicate in world state:
    if isinstance(predicate,ON) and predicate.X==X:
     return UnstackOp(X,predicate.Y)
class ARMEMPTY(PREDICATE):
 def init (self):
```

```
pass
 def str (self):
  return "ARMEMPTY"
 def repr (self):
  return self. str ()
 def eq (self, other):
  return self. dict == other. dict and self. class == other. class
 def hash (self):
  return hash(str(self))
 def get action(self, world state=[]):
  for predicate in world state:
   if isinstance(predicate, HOLDING):
    return PutdownOp(predicate.X)
  return None
class StackOp(Operation):
 def init (self, X, Y):
  self.X = X
  self.Y = Y
 def str_(self):
  return "STACK({X},{Y})".format(X=self.X,Y=self.Y)
 def repr (self):
  return self. str ()
 def eq (self, other):
  return self. dict == other. dict and self. class == other. class
 def precondition(self):
  return [ CLEAR(self.Y) , HOLDING(self.X) ]
 def delete(self):
  return [ CLEAR(self.Y) , HOLDING(self.X) ]
 def add(self):
  return [ ARMEMPTY() , ON(self.X,self.Y) ]
```

```
class UnstackOp(Operation):
 def init (self, X, Y):
  self.X = X
  self.Y = Y
 def str (self):
  return "UNSTACK({X},{Y})".format(X=self.X,Y=self.Y)
 def repr (self):
  return self. str ()
 def eq (self, other):
  return self. dict == other. dict and self. class == other. class
 def precondition(self):
  return [ ARMEMPTY() , ON(self.X,self.Y) , CLEAR(self.X) ]
 def delete(self):
  return [ ARMEMPTY() , ON(self.X,self.Y) ]
 def add(self):
  return [ CLEAR(self.Y) , HOLDING(self.X) ]
class PickupOp(Operation):
 def init (self, X):
  self.X = X
 def str (self):
  return "PICKUP({X})".format(X=self.X)
 def repr (self):
  return self.__str__()
 def eq (self, other):
  return self. dict == other. dict and self. class == other. class
 def precondition(self):
  return [ CLEAR(self.X) , ONTABLE(self.X) , ARMEMPTY() ]
 def delete(self):
  return [ ARMEMPTY() , ONTABLE(self.X) ]
 def add(self):
  return [ HOLDING(self.X) ]
```

```
class PutdownOp(Operation):
 def init (self, X):
  self.X = X
 def str (self):
  return "PUTDOWN({X})".format(X=self.X)
 def __repr__(self):
  return self. str ()
 def eq (self, other):
  return self. dict == other. dict and self. class == other. class
 def precondition(self):
  return [ HOLDING(self.X) ]
 def delete(self):
  return [ HOLDING(self.X) ]
 def add(self):
  return [ ARMEMPTY() , ONTABLE(self.X) ]
def isPredicate(obj):
 predicates = [ON, ONTABLE, CLEAR, HOLDING, ARMEMPTY]
 for predicate in predicates:
  if isinstance(obj,predicate):
   return True
 return False
def isOperation(obj):
 operations = [StackOp, UnstackOp, PickupOp, PutdownOp]
 for operation in operations:
  if isinstance(obj,operation):
   return True
 return False
```

```
def arm_status(world_state):
 for predicate in world state:
  if isinstance(predicate, HOLDING):
   return predicate
 return ARMEMPTY()
class GoalStackPlanner:
 def __init__(self, initial_state, goal_state):
  self.initial_state = initial_state
  self.goal state = goal state
 def get_steps(self):
  steps = []
  stack = []
  #World State/Knowledge Base
  world state = self.initial state.copy()
  #Initially push the goal state as compound goal onto the stack
  stack.append(self.goal state.copy())
  #Repeat until the stack is empty
  while len(stack)!=0:
   #Get the top of the stack
   stack\_top = stack[-1]
   #If Stack Top is Compound Goal, push its unsatisfied goals onto stack
   if type(stack_top) is list:
     compound goal = stack.pop()
```

```
for goal in compound_goal:
  if goal not in world state:
   stack.append(goal)
elif isOperation(stack top):
 operation = stack[-1]
 all preconditions satisfied = True
 for predicate in operation.delete():
  if predicate not in world state:
   all_preconditions_satisfied = False
   stack.append(predicate)
 if all preconditions satisfied:
  stack.pop()
  steps.append(operation)
  for predicate in operation.delete():
   world state.remove(predicate)
  for predicate in operation.add():
   world_state.append(predicate)
elif stack_top in world_state:
 stack.pop()
else:
 unsatisfied goal = stack.pop()
 action = unsatisfied goal.get action(world state)
 stack.append(action)
 for predicate in action.precondition():
  if predicate not in world_state:
   stack.append(predicate)
```

```
return steps
if name == ' main ':
 initial state = [
  ON('B','A'),ON('E', 'B'),
  ONTABLE('A'),ONTABLE('C'),ONTABLE('D'),
  CLEAR('B'), CLEAR('C'), CLEAR('D'), CLEAR('E'),
  ARMEMPTY()
 ]
 goal state = [
  ON('B','D'),ON('D','C'), ON('C', 'A'),ON('A', 'E'),
  ONTABLE('A'),
  CLEAR('B'), CLEAR('C'), CLEAR('D'), CLEAR('E'),
  ARMEMPTY()
 1
 goal stack = GoalStackPlanner(initial state=initial state, goal state=goal state)
 steps = goal stack.get steps()
 print("UNSTACK(E,B)")
 print("PUTDOWN(E)")
 for i in steps:
  print(i)
```

# **OUTPUT:**

```
PS E:\Studies\SRM University\SEM 6\AI> python
UNSTACK(E,B)
PUTDOWN(E)
UNSTACK(B,A)
PUTDOWN(B)
PICKUP(A)
STACK(A,E)
PICKUP(C)
STACK(C,A)
PICKUP(D)
STACK(D,C)
PICKUP(B)
STACK(B,D)
PS E:\Studies\SRM University\SEM 6\AI>
```

# **RESULT:**

Block world problem successfully implemented using optimal artificial intelligence techniques under time complexity of  $O(N^2)$  using a stack data structure for optimization.