

How to Program a Calculator

A look at the geometric cosine method

Jake Darby

Project Overview

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- ▶ Numerical Analysis of Common Functions

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 - ▶ Approximations

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 - ▶ Implemented in C
 - ▶ GNU & MPFR libraries

Trigonometric Functions

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- ▶ Looked at \sin , \cos and \tan

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- ▶ Looked at \sin , \cos and \tan
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 - ▶ Use Trigonometric Identities to reduce the problem

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- ▶ Analysed several different methods

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 - ▶ CORDIC
 - ▶ Geometric

Geometric Method Figure 1

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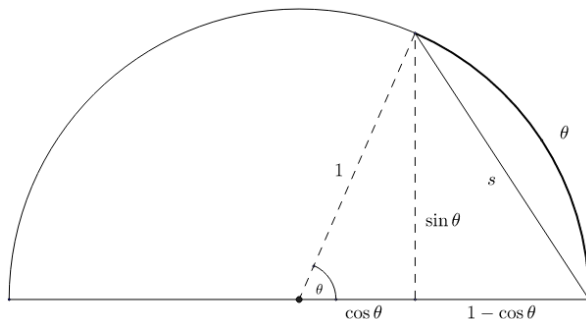


Figure: First diagram in developing the geometric method

Geometric Method Derivation 1

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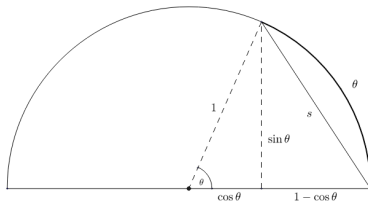
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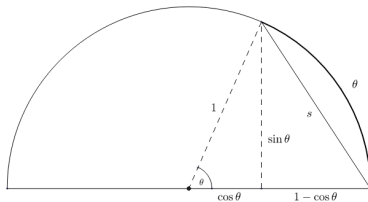
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- ▶ $s^2 = \sin^2 \theta + (1 - \cos \theta)^2$
- ▶ $s^2 = 2 - 2 \cos \theta$
- ▶ $\cos \theta = 1 - \frac{1}{2}s^2$



Geometric Method Derivation 1

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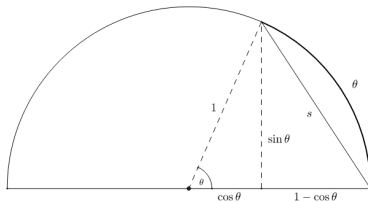
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- ▶ $\cos \theta = 1 - \frac{1}{2}s^2$
- ▶ $s \approx \theta$



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Geometric Method Diagrams 2

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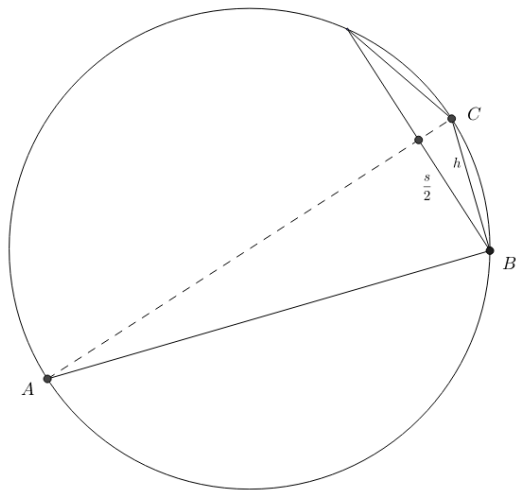


Figure: Diagram to show how to recursively calculate s

Geometric Method Derivation 2

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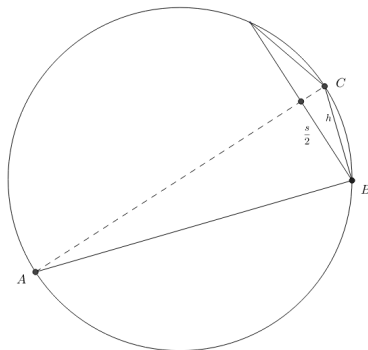
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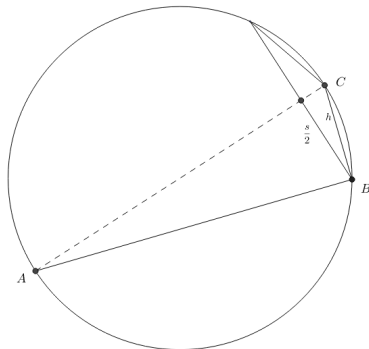
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- ▶ ABC is right angled
- ▶ $AB = \sqrt{AC^2 - BC^2}$
 $= \sqrt{4 - h^2}$



Geometric Method Derivation 2

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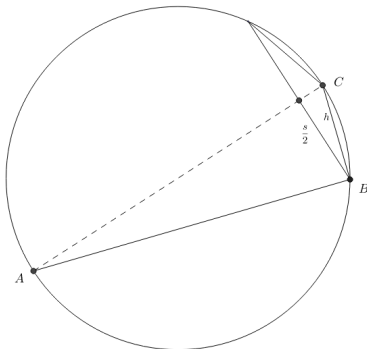
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- ▶ ABC is right angled
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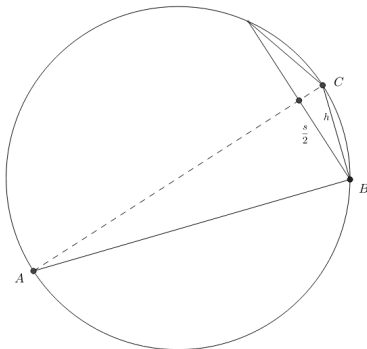
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- ▶ ABC is right angled
- ▶ $AB = \sqrt{AC^2 - BC^2}$
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- ▶ Area of ABC :
 - ▶ $\frac{1}{2} h \sqrt{4 - h^2}$
 - ▶ $\frac{1}{2} \cdot 2 \cdot \frac{s}{2}$
- ▶ $s^2 = h^2(4 - h^2)$
- ▶ $h \approx \frac{\theta}{2}$



geometric_cos ($\theta \in [0, \frac{\pi}{2}], k \in \mathbb{N}$):

$h_0 := \theta 2^{-k}$

$n := 0$

while $n < k$:

$h_{n+1}^2 := h_n^2 \cdot (4 - h_n^2)$

$n \mapsto n + 1$

return $1 - \frac{1}{2}h_k^2$

Geometric Method Implementation

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```
#include <assert.h>
#include <math.h>

double geometric_cos(double theta,
                    unsigned int k){
    //k > 0
    assert(k);
    //0 <= theta < pi/2
    assert(0 <= theta < 1.57079632679);

    double h = theta * pow(2, -k);
    h *= h;

    for(int i = 0; i < k; ++i)
        h = h * (4 - h);

    return 1 - h/2;
}
```

Basics and Assumptions

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- ▶ Errors occur due to the assumption that $h_0 = \theta 2^{-k}$

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$$\epsilon_x := |x - \bar{x}|$$

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- ▶ Assumptions:
 - ▶ All calculations are performed without error
 - ▶ All calculations are performed to arbitrary precision

Error Analysis 1

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 - ▶ $\epsilon_k < 2^k \epsilon_0$

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 - ▶ $\epsilon_k < 2^k \epsilon_0$
 - ▶ Proven by showing $\epsilon_{n+1} < 2\epsilon_n$
 - ▶ Uses simple trigonometry and algebraic re-arrangement

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► $\epsilon_k = h_k - s$

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$$\triangleright \epsilon_k = h_k - s$$

$$\triangleright \epsilon_0 = \theta 2^{-k} - 2 \sin(\theta 2^{-k-1})$$

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- ▶ $\epsilon_k = h_k - s$
- ▶ $\epsilon_0 = \theta 2^{-k} - 2 \sin(\theta 2^{-k-1})$
- ▶ Let $\mathcal{C} := 1 - \frac{1}{2}h_k^2$

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- ▶ $2^{k+2} \sin(\theta 2^{-k-1}) = 2\theta - \frac{1}{6}\theta^3 2^{-2k-1} + \frac{1}{120}\theta^5 2^{-4k-1} + \dots$

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$$= 2\theta - 2^{k+2} \sin(\theta 2^{-k-1})$$
- ▶ $2^{k+2} \sin(\theta 2^{-k-1}) = 2\theta - \frac{1}{6}\theta^3 2^{-2k-1} + \frac{1}{120}\theta^5 2^{-4k-1} + \dots$
- ▶ $\epsilon_{\mathcal{C}} < \frac{1}{6}\theta^3 2^{-2k-1} + \mathcal{O}(2^{-4k-1})$

Digits of Accuracy

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$$\triangleright 2\theta - 2^{k+2} \sin(\theta 2^{-k-1}) < 10^{-N}$$

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- ▶ $2\theta - 2^{k+2} \sin(\theta 2^{-k-1}) < 10^{-N}$
 - ▶ Guarantee N digits of accuracy

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- ▶ $2\theta - 2^{k+2} \sin(\theta 2^{-k-1}) < 10^{-N}$
 - ▶ Guarantee N digits of accuracy
 - ▶ Must solve $2^{k+2} \sin(\theta 2^{-k-1}) > 2\theta - 10^{-N}$

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 - ▶ Must solve $2^{k+2} \sin(\theta 2^{-k-1}) > 2\theta - 10^{-N}$
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N	k
5	6
10	14
50	80
100	163
1000	1658

Figure: This table shows the minimum k required to guarantee N digits of accuracy for our approximation of $\cos(0.5)$

Final Remarks

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 - ▶ Digit by digit square root
 - ▶ Hardware implementable trig calculations
 - ▶ Continued fractions for exponentials

Thank you for listening

Thank you for listening

Project at:

<https://github.com/Ybrad/Year-4-Project>

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Any questions?