

**University of Toronto Scarborough**  
**Department of Computer & Mathematical Sciences**

MAT B41H

2013/2014

Solutions #1

1. (a) If a finite limit exists,  $f'(a) = \lim_{x \rightarrow a} \frac{f(x) - f(a)}{x - a} = \lim_{x \rightarrow a} \frac{2x^2 + x - 3 - (2a^2 + a - 3)}{x - a} =$   
 $\lim_{x \rightarrow a} \frac{2(x^2 - a^2) + (x - a)}{x - a} = \lim_{x \rightarrow a} (2(x - a) + 1) = 2(a + a) + 1 = 4a + 1.$

(b) Choose a regular partition of  $[0, 2]$ ,  $x_0 = 0$ ,  $x_i = \frac{2i}{n}$  and  $\Delta x = \frac{2}{n}$ . Now

choose  $w_i = x_i$ , so  $f(w_i) = f(x_i) = 2x_i^2 + x_i - 3 = 2\left(\frac{2i}{n}\right)^2 + \left(\frac{2x_i}{n}\right) - 3.$

$$\sum_{i=1}^n f(w_i) \Delta x = \sum_{i=1}^n \left[ 2\left(\frac{2i}{n}\right)^2 + \left(\frac{2i}{n}\right) - 3 \right] \frac{2}{n} = \frac{16}{n^3} \sum_{i=1}^n i^2 + \frac{4}{n^2} \sum_{i=1}^n i - \frac{6}{n} \sum_{i=1}^n 1 =$$

$$\frac{16}{n^3} \left( \frac{n(n+1)(2n+1)}{6} \right) + \frac{4}{n^2} \left( \frac{n(n+1)}{2} \right) - 6 = \frac{8}{3} \left( 2 + \frac{3}{n} + \frac{1}{n^2} \right) + 2 \left( 1 + \frac{1}{n} \right) - 6.$$

Now  $\int_0^2 f(x) dx = \lim_{n \rightarrow \infty} \sum_{i=1}^n f(w_i) \Delta x = \lim_{n \rightarrow \infty} \left[ \frac{8}{3} \left( 2 + \frac{3}{n} + \frac{1}{n^2} \right) + 2 \left( 1 + \frac{1}{n} \right) - 6 \right] =$   
 $\frac{16}{3} + 2 - 6 = \frac{4}{3}.$

(c)  $F(x) = \int_{\cos x}^{1-x^3} e^{t^2} dt = \int_{\cos x}^a e^{t^2} dt + \int_a^{1-x^3} e^{t^2} dt = \int_a^{1-x^3} e^{t^2} dt - \int_a^{\cos x} e^{t^2} dt.$   
Hence  $\frac{dF}{dx} = \left( e^{(1-x^3)^2} \right) \left( -3x^2 \right) - \left( e^{\cos^2 x} \right) \left( -\sin x \right).$

2. (a) (i)  $\int \frac{x^6 + x^3}{1 + x^2} dx \stackrel{\text{divide}}{=} \int \left( x^4 - x^2 + x + 1 + \frac{x-1}{1+x^2} \right) dx = \int \left( x^4 - x^2 + x + \right.$   
 $\left. 1 + \frac{x}{1+x^2} - \frac{1}{1+x^2} \right) dx = \frac{x^5}{5} - \frac{x^3}{3} + \frac{x^2}{2} + x + \frac{1}{2} \ln(1+x^2) - \tan^{-1} x + C.$

(ii)  $\int \frac{(\ln w)^3}{w} dw \stackrel{\substack{\text{substitute} \\ z = \ln w}}{=} \int z^3 dz = \frac{1}{4} z^4 + C = \frac{1}{4} (\ln w)^4 + C.$

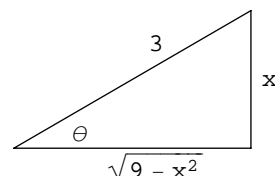
(iii)  $\int \sin^4 x \cos^3 x dx = \int \sin^4 x (1 - \sin^2 x) \cos x dx = \int (\sin^4 x - \sin^6 x) \cos x dx$   
 $\stackrel{\substack{\text{substitute} \\ u = \sin x}}{=} \int (u^4 - u^6) du = \frac{u^5}{5} - \frac{u^7}{7} + C = \frac{\sin^5 x}{5} - \frac{\sin^7 x}{7} + C.$

(iv)  $\int z^2 \cos z dz \stackrel{\substack{\text{parts with} \\ u = z^2, dv = \cos z dz}}{=} z^2 \sin z - 2 \int z \sin z dz \stackrel{\substack{\text{parts with} \\ u = z, dv = \sin z dz}}{=} z^2 \sin z - 2 \left( -z \cos z + \int \cos z dz \right) = z^2 \sin z + 2z \cos z - 2 \sin z + C.$

(v)  $\int \sin(\ln x) dx$   $\xrightarrow[u = \sin(\ln x), dv = dx]{\text{parts with}}$   $x \sin(\ln x) - \int \cos(\ln x) dx$   $\xrightarrow[u = \cos(\ln x), dv = dx]{\text{parts with}}$   $x \sin(\ln x) - x \cos(\ln x) - \int \sin(\ln x) dx$ . Hence  $2 \int \sin(\ln x) dx = x \sin(\ln x) - x \cos(\ln x) + C'$ , so  $\int \sin(\ln x) dx = \frac{x}{2} (\sin(\ln x) - \cos(\ln x)) + C$ .

(vi) We need to find  $A$  and  $B$  so that  $\frac{1}{(x+1)(x-2)} = \frac{A}{x+1} + \frac{B}{x-2}$ ; i.e., we need  $1 = A(x-2) + B(x+1)$ . Solving we get  $A = -\frac{1}{3}$  and  $B = \frac{1}{3}$ . Hence  $\int \frac{dx}{(x+1)(x-2)} = -\frac{1}{3} \int \frac{dx}{x+1} + \frac{1}{3} \int \frac{dx}{x-2} = -\frac{1}{3} \ln|x+1| + \frac{1}{3} \ln|x-2| + C = \frac{1}{3} \ln \left| \frac{x-2}{x+1} \right| + C$ .

(vii)  $\int x^2 \sqrt{9-x^2} dx$   $\xrightarrow[x = 3 \sin \theta]{\text{substitute}}$   $\int 9 \sin^2 \theta \sqrt{9-9 \sin^2 \theta} 3 \cos \theta d\theta =$   
 $81 \int \sin^2 \theta \cos^2 \theta d\theta =$   
 $81 \int \left( \frac{1-\cos 2\theta}{2} \right) \left( \frac{1+\cos 2\theta}{2} \right) d\theta = \frac{81}{4} \int (1 - \cos^2(2\theta)) d\theta = \frac{81}{4} \int \left( 1 - \frac{1+\cos 4\theta}{2} \right) d\theta =$   
 $\frac{81}{8} \int (1 - \cos 4\theta) d\theta = \frac{81\theta}{8} - \frac{81}{32} \sin 4\theta + C = \frac{81}{8} \sin^{-1} \left( \frac{x}{3} \right) -$   
 $\frac{81}{32} (2 \sin 2\theta \cos 2\theta) + C = \frac{81}{8} \sin^{-1} \left( \frac{x}{3} \right) - \frac{81}{16} (2 \sin \theta \cos \theta) (1 - 2 \sin^2 \theta) +$   
 $C = \frac{81}{8} \sin^{-1} \left( \frac{x}{3} \right) - \frac{81}{8} \left( \frac{x \sqrt{9-x^2}}{9} \right) \left[ 1 - 2 \left( \frac{x}{3} \right)^2 \right] + C = \frac{81}{8} \sin^{-1} \left( \frac{x}{3} \right) -$   
 $\frac{x(9-2x^2) \sqrt{9-x^2}}{8} + C$ .



(b) (i)  $\int_4^9 \frac{e^{\sqrt{y}}}{\sqrt{y}} dy$   $\xrightarrow[w = \sqrt{y}]{\text{substitute}}$   $= 2 \int_2^3 e^w dw = 2 \left[ e^w \right]_2^3 = 2(e^3 - e^2)$ .

(ii) There is a singularity when  $x = 4$ , so the integral is improper. Now

$$\int_0^4 \frac{dx}{(x-4)^{\frac{2}{3}}} = \lim_{t \rightarrow 4^-} 3(x-4)^{\frac{1}{3}} \Big|_0^t = 3 \lim_{t \rightarrow 4^-} \left[ (t-4)^{\frac{1}{3}} - (-4)^{\frac{1}{3}} \right] = 3(4^{\frac{1}{3}})$$

and  $\int_4^6 \frac{dx}{(x-4)^{\frac{2}{3}}} = \lim_{t \rightarrow 4^+} 3(x-4)^{\frac{1}{3}} \Big|_t^6 = 3 \lim_{t \rightarrow 4^+} \left[ 2^{\frac{1}{3}} - (t-4)^{\frac{1}{3}} \right] = 3(2^{\frac{1}{3}})$ . Since

both integrals converge,  $\int_0^6 \frac{dx}{(x-4)^{\frac{2}{3}}}$  will also converge and  $\int_0^6 \frac{dx}{(x-4)^{\frac{2}{3}}} =$

$$\int_0^4 \frac{dx}{(x-4)^{\frac{2}{3}}} + \int_4^6 \frac{dx}{(x-4)^{\frac{2}{3}}} = 3(4^{\frac{1}{3}}) + 3(2^{\frac{1}{3}}).$$

(iii) Since one of the limits of integration is infinite, the integral is improper. Now

$$\begin{aligned} \int_0^\infty \frac{x}{e^x} dx & \stackrel{\text{parts with}}{=} \lim_{t \rightarrow \infty} \left[ -x e^{-x} \Big|_0^t + \int_0^t e^{-x} dx \right] = \\ \lim_{t \rightarrow \infty} \left[ (-1)(1+x)e^{-x} \right]_0^t & = 1 - \lim_{t \rightarrow \infty} (1+t)e^{-t} = 1 - 0 = 1. \end{aligned}$$

The integral converges to 1.

3. We are given that  $\frac{dv}{dt} = -20$ , so integrating gives  $v = v_0 - 20t$  where  $v_0$  is the speed when the brakes were first applied. Integrating again for distance we have  $s = s_0 + v_0 t - 10t^2$ . Since the skidding started when the brakes were applied,  $s_0 = 0$ . When  $v = 0$  (car stopped) we have  $t = \frac{v_0}{20}$  and  $s = 200$ , so  $200 = \frac{v_0^2}{20} - 10 \frac{v_0^2}{400}$ . Hence  $v_0 = \sqrt{(200)(40)} = 40\sqrt{5} \approx 89.4$  m/sec.
4. For  $\mathbf{v} = (1, -1, 1)$  and  $\mathbf{w} = (0, 1, -2)$  we have  $\mathbf{v} \cdot \mathbf{w} = 0 - 1 - 2 = -3$ ,  $\|\mathbf{v}\| = \sqrt{1+1+1} = \sqrt{3}$  and  $\|\mathbf{w}\| = \sqrt{0+1+4} = \sqrt{5}$ .

(a) If  $\theta$  is the angle between  $\mathbf{v}$  and  $\mathbf{w}$ , we have  $\cos \theta = \frac{\mathbf{v} \cdot \mathbf{w}}{\|\mathbf{v}\| \|\mathbf{w}\|} = \frac{-3}{\sqrt{3}\sqrt{5}} = -\frac{\sqrt{3}}{\sqrt{5}}$ ,  
so  $\theta = \cos^{-1} \left( -\frac{\sqrt{3}}{\sqrt{5}} \right)$ .

(b) Now  $\|\mathbf{v}\| \|\mathbf{w}\| = \sqrt{3}\sqrt{5} > \sqrt{3}\sqrt{3} = 3 = |\mathbf{v} \cdot \mathbf{w}|$ . Hence the Cauchy-Schwarz inequality holds for  $\mathbf{v}$  and  $\mathbf{w}$ . Also  $\mathbf{v} + \mathbf{w} = (1, 0, -1)$  and  $\|\mathbf{v} + \mathbf{w}\| = \sqrt{1+0+1} = \sqrt{2} < \sqrt{3} < \sqrt{3} + \sqrt{5} = \|\mathbf{v}\| + \|\mathbf{w}\|$ . Hence the triangle inequality holds for  $\mathbf{v}$  and  $\mathbf{w}$ .

(c) Let  $\mathbf{u} = (a, b, c)$  be orthogonal to both  $\mathbf{v}$  and  $\mathbf{w}$ ; hence  $(a, b, c) \cdot (1, -1, 1) = a - b + c = 0$  and  $(a, b, c) \cdot (0, 1, -2) = b - 2c = 0$ . Solving these two equations we get  $b = 2c$  and  $a = c$ . Hence all vectors in  $\mathbb{R}^3$  which are orthogonal to both  $\mathbf{v}$  and  $\mathbf{w}$  are of the form  $c(1, 2, 1)$ ,  $c \in \mathbb{R}$ . We also need  $\|\mathbf{u}\| = 1$  or  $c^2(1+4+1) = 1 \implies c^2 = \frac{1}{6}$  or  $c = \pm \frac{1}{\sqrt{6}}$ . The required vectors are  $\left( \frac{1}{\sqrt{6}}, \frac{2}{\sqrt{6}}, \frac{1}{\sqrt{6}} \right)$  and  $\left( -\frac{1}{\sqrt{6}}, -\frac{2}{\sqrt{6}}, -\frac{1}{\sqrt{6}} \right)$ .

(d) (i) The projection of  $\mathbf{v}$  onto  $\mathbf{w}$  is a vector in direction  $\frac{1}{\|\mathbf{w}\|} \mathbf{w}$  with length  $\|\mathbf{v}\| \cos \theta = \left( \frac{\mathbf{v} \cdot \mathbf{w}}{\|\mathbf{w}\|} \right)$ . Hence the projection is  $\left( \frac{\mathbf{v} \cdot \mathbf{w}}{\|\mathbf{w}\|} \right) \left( \frac{1}{\|\mathbf{w}\|} \right) \mathbf{w} = \frac{\mathbf{v} \cdot \mathbf{w}}{\|\mathbf{w}\|^2} \mathbf{w}$   
 $= \frac{-3}{5} (0, 1, -2) = \left( 0, -\frac{3}{5}, \frac{6}{5} \right)$ .

(ii) The projection of  $\mathbf{w}$  onto  $\mathbf{v}$  is  $\frac{\mathbf{w} \cdot \mathbf{v}}{\|\mathbf{v}\|^2} \mathbf{v} = \frac{-3}{3} (1, -1, 1) = (1, -1, 1)$ .

5. (a)  $\mathbf{u} \cdot \mathbf{v} = \mathbf{w} \cdot \mathbf{v}$  means  $\mathbf{u} \cdot \mathbf{v} - \mathbf{w} \cdot \mathbf{v} = 0$  or  $(\mathbf{u} - \mathbf{w}) \cdot \mathbf{v} = 0$  for all  $\mathbf{v}$ . To be true for all  $\mathbf{v}$ , it must be true for  $\mathbf{v} = \mathbf{u} - \mathbf{w}$  which gives  $(\mathbf{u} - \mathbf{w}) \cdot (\mathbf{u} - \mathbf{w}) = \|\mathbf{u} - \mathbf{w}\|^2 = 0 \implies \mathbf{u} - \mathbf{w} = \mathbf{0} \implies \mathbf{u} = \mathbf{w}$ .
- (b) This time we have  $\mathbf{u} \cdot \mathbf{v} = \mathbf{w} \cdot \mathbf{v}$  or  $(\mathbf{u} - \mathbf{w}) \cdot \mathbf{v} = 0$ , but only for some nonzero  $\mathbf{v}$ . Recall  $\mathbf{x} \cdot \mathbf{y} = 0 \implies \mathbf{x} \perp \mathbf{y}$ , so here we have  $(\mathbf{u} - \mathbf{w}) \cdot \mathbf{v} = 0$ . Choosing  $\mathbf{u} = (0, 3)$  and  $\mathbf{w} = (0, 2)$  we note that, with  $\mathbf{v} = (1, 0) \neq \mathbf{0}$ , we have  $(\mathbf{u} - \mathbf{w}) \cdot \mathbf{v} = ((0, 3) - (0, 2)) \cdot (1, 0) = (0, 1) \cdot (1, 0) = 0$ , but  $\mathbf{u} \neq \mathbf{w}$ .

6. (a) To show that  $\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3$  form an orthonormal basis for  $\mathbb{R}^3$  we must show that  $\mathbf{b}_i \cdot \mathbf{b}_j = \delta_{ij}$ , for  $1 \leq i, j \leq 3$ . Now

$$\mathbf{b}_1 \cdot \mathbf{b}_1 = \left( \frac{1}{\sqrt{5}}, 0, \frac{2}{\sqrt{5}} \right) \cdot \left( \frac{1}{\sqrt{5}}, 0, \frac{2}{\sqrt{5}} \right) = \frac{1}{5} + \frac{4}{5} = 1,$$

$$\mathbf{b}_1 \cdot \mathbf{b}_2 = \left( \frac{1}{\sqrt{5}}, 0, \frac{2}{\sqrt{5}} \right) \cdot \left( -\frac{2}{\sqrt{6}}, \frac{1}{\sqrt{6}}, \frac{1}{\sqrt{6}} \right) = -\frac{2}{\sqrt{30}} + 0 + \frac{2}{\sqrt{30}} = 0,$$

$$\mathbf{b}_1 \cdot \mathbf{b}_3 = \left( \frac{1}{\sqrt{5}}, 0, \frac{2}{\sqrt{5}} \right) \cdot \left( -\frac{2}{\sqrt{30}}, -\frac{5}{\sqrt{30}}, \frac{1}{\sqrt{30}} \right) = -\frac{2}{\sqrt{150}} + \frac{2}{\sqrt{150}} = 0,$$

$$\mathbf{b}_2 \cdot \mathbf{b}_2 = \left( -\frac{2}{\sqrt{6}}, \frac{1}{\sqrt{6}}, \frac{1}{\sqrt{6}} \right) \cdot \left( -\frac{2}{\sqrt{6}}, \frac{1}{\sqrt{6}}, \frac{1}{\sqrt{6}} \right) = \frac{4}{6} + \frac{1}{6} + \frac{1}{6} = 1,$$

$$\mathbf{b}_2 \cdot \mathbf{b}_3 = \left( -\frac{2}{\sqrt{6}}, \frac{1}{\sqrt{6}}, \frac{1}{\sqrt{6}} \right) \cdot \left( -\frac{2}{\sqrt{30}}, -\frac{5}{\sqrt{30}}, \frac{1}{\sqrt{30}} \right) = \frac{4}{\sqrt{180}} - \frac{5}{\sqrt{180}} + \frac{1}{\sqrt{180}} = 0,$$

$$\text{and } \mathbf{b}_3 \cdot \mathbf{b}_3 = \left( -\frac{2}{\sqrt{30}}, -\frac{5}{\sqrt{30}}, \frac{1}{\sqrt{30}} \right) \cdot \left( -\frac{2}{\sqrt{30}}, -\frac{5}{\sqrt{30}}, \frac{1}{\sqrt{30}} \right) = \frac{4}{30} + \frac{25}{30} + \frac{1}{30} = 1.$$

Hence  $\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3$  form an orthonormal basis for  $\mathbb{R}^3$ .

- (b) We want  $\mathbf{v} = (1, 0, 1) = a_1 \mathbf{b}_1 + a_2 \mathbf{b}_2 + a_3 \mathbf{b}_3$ . The  $a_i$  are the projections of  $\mathbf{v}$  onto the  $\mathbf{b}_i$ ,  $i = 1, 2, 3$ . Hence

$$a_1 = \mathbf{v} \cdot \mathbf{b}_1 = (1, 0, 1) \cdot \left( \frac{1}{\sqrt{5}}, 0, \frac{2}{\sqrt{5}} \right) = \frac{1}{\sqrt{5}} + \frac{2}{\sqrt{5}} = \frac{3}{\sqrt{5}},$$

$$a_2 = \mathbf{v} \cdot \mathbf{b}_2 = (1, 0, 1) \cdot \left( -\frac{2}{\sqrt{6}}, \frac{1}{\sqrt{6}}, \frac{1}{\sqrt{6}} \right) = -\frac{2}{\sqrt{6}} + \frac{1}{\sqrt{6}} = -\frac{1}{\sqrt{6}},$$

$$\text{and } a_3 = \mathbf{v} \cdot \mathbf{b}_3 = (1, 0, 1) \cdot \left( -\frac{2}{\sqrt{30}}, -\frac{5}{\sqrt{30}}, \frac{1}{\sqrt{30}} \right) = -\frac{2}{\sqrt{30}} + \frac{1}{\sqrt{30}} = -\frac{1}{\sqrt{30}}.$$

$$\text{Hence } \mathbf{v} = \left( \frac{3}{\sqrt{5}} \right) \mathbf{b}_1 + \left( -\frac{1}{\sqrt{6}} \right) \mathbf{b}_2 + \left( -\frac{1}{\sqrt{30}} \right) \mathbf{b}_3.$$

7. We have  $A = \begin{pmatrix} 1 & 0 & 3 \\ 2 & -1 & 4 \\ -3 & 2 & 1 \end{pmatrix}$ ,  $B = \begin{pmatrix} \frac{3}{2} & -1 & -\frac{1}{2} \\ \frac{7}{3} & -\frac{5}{3} & -\frac{1}{3} \\ -\frac{1}{6} & \frac{1}{3} & \frac{1}{6} \end{pmatrix}$ , and  $C = \begin{pmatrix} -1 & 3 & 2 \\ 4 & -1 & 1 \\ 3 & 2 & 3 \end{pmatrix}$ .

(a) (i)  $\det A = (1) \det \begin{pmatrix} -1 & 4 \\ 2 & 1 \end{pmatrix} + 0 + (3) \det \begin{pmatrix} 2 & -1 \\ -3 & 2 \end{pmatrix} = (1)(-9) + (3)(1) = -6.$

(ii)  $\det B = \left( \frac{3}{2} \right) \det \begin{pmatrix} -\frac{5}{3} & -\frac{1}{3} \\ \frac{7}{3} & \frac{1}{6} \end{pmatrix} - (-1) \det \begin{pmatrix} \frac{7}{3} & -\frac{1}{3} \\ -\frac{1}{6} & \frac{1}{6} \end{pmatrix} +$

$$\left(-\frac{1}{2}\right) \det \begin{pmatrix} \frac{7}{3} & -\frac{5}{3} \\ -\frac{1}{6} & \frac{1}{3} \end{pmatrix} = \left(\frac{3}{2}\right)\left(-\frac{1}{6}\right) + (1)\left(\frac{1}{3}\right) + \left(-\frac{1}{2}\right)\left(\frac{1}{2}\right) = -\frac{1}{6}.$$

$$\text{(iii) } \det C = (-1) \det \begin{pmatrix} -1 & 1 \\ 2 & 2 \end{pmatrix} - (3) \det \begin{pmatrix} 4 & 1 \\ 3 & 3 \end{pmatrix} + (2) \det \begin{pmatrix} 4 & -1 \\ 3 & 2 \end{pmatrix} = (-1)(-5) - (3)(9) + (2)(11) = 5 - 27 + 22 = 0.$$

$$\text{(iv) } \det(A B) = \det A \det B = (-6)\left(-\frac{1}{6}\right) = 1.$$

$$\begin{aligned} \text{(v) } \det(A + B) &= \det \left[ \begin{pmatrix} 1 & 0 & 3 \\ 2 & -1 & 4 \\ -3 & 2 & 1 \end{pmatrix} + \begin{pmatrix} \frac{3}{2} & -1 & -\frac{1}{2} \\ \frac{7}{3} & -\frac{5}{3} & -\frac{1}{3} \\ -\frac{1}{6} & \frac{1}{3} & \frac{1}{6} \end{pmatrix} \right] = \\ &= \det \begin{pmatrix} \frac{5}{2} & -1 & \frac{5}{2} \\ \frac{13}{3} & -\frac{8}{3} & \frac{11}{3} \\ -\frac{19}{6} & \frac{7}{3} & \frac{7}{6} \end{pmatrix} = \left(\frac{5}{2}\right) \det \begin{pmatrix} -\frac{8}{3} & \frac{11}{3} \\ \frac{7}{3} & \frac{7}{6} \end{pmatrix} - (-1) \det \begin{pmatrix} \frac{13}{3} & \frac{11}{3} \\ -\frac{19}{6} & \frac{7}{6} \end{pmatrix} + \\ &= \left(\frac{5}{2}\right) \det \begin{pmatrix} \frac{13}{3} & -\frac{8}{3} \\ -\frac{19}{6} & \frac{7}{3} \end{pmatrix} = \left(\frac{5}{2}\right)\left(-\frac{35}{3}\right) + (1)\left(\frac{50}{3}\right) + \left(\frac{5}{2}\right)\left(\frac{5}{3}\right) = -\frac{25}{3}. \end{aligned}$$

(b) To show that  $A$  and  $B$  are inverse matrices we must show that  $AB = I$  and  $BA = I$ .

$$\begin{aligned} AB &= \begin{pmatrix} 1 & 0 & 3 \\ 2 & -1 & 4 \\ -3 & 2 & 1 \end{pmatrix} \begin{pmatrix} \frac{3}{2} & -1 & -\frac{1}{2} \\ \frac{7}{3} & -\frac{5}{3} & -\frac{1}{3} \\ -\frac{1}{6} & \frac{1}{3} & \frac{1}{6} \end{pmatrix} = \\ &= \begin{pmatrix} \frac{3}{2} - \frac{1}{2} & -1 + 1 & -\frac{1}{2} + \frac{1}{2} \\ 3 - \frac{7}{3} - \frac{2}{3} & -2 + \frac{5}{3} + \frac{4}{3} & -1 + \frac{1}{3} + \frac{2}{3} \\ -\frac{9}{2} + \frac{14}{3} - \frac{1}{6} & 3 - \frac{10}{3} + \frac{1}{3} & \frac{3}{2} - \frac{2}{3} + \frac{1}{6} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = I_3. \end{aligned}$$

$$\begin{aligned} BA &= \begin{pmatrix} \frac{3}{2} & -1 & -\frac{1}{2} \\ \frac{7}{3} & -\frac{5}{3} & -\frac{1}{3} \\ -\frac{1}{6} & \frac{1}{3} & \frac{1}{6} \end{pmatrix} \begin{pmatrix} 1 & 0 & 3 \\ 2 & -1 & 4 \\ -3 & 2 & 1 \end{pmatrix} = \\ &= \begin{pmatrix} \frac{3}{2} - 2 + \frac{3}{2} & 1 - 1 & \frac{9}{2} - 4 - \frac{1}{2} \\ \frac{7}{3} - \frac{10}{3} + 1 & \frac{5}{3} - \frac{2}{3} & 7 - \frac{20}{3} - \frac{1}{3} \\ -\frac{1}{6} + \frac{2}{3} - \frac{1}{2} & -\frac{1}{3} + \frac{1}{3} & -\frac{1}{2} + \frac{4}{3} + \frac{1}{6} \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = I_3. \end{aligned}$$

(i) The system of equations 
$$\begin{aligned} x + 3z &= 1 \\ 2x - y + 4z &= 2 \\ -3x + 2y + z &= 3 \end{aligned}$$
 can be written as

$$\begin{aligned} A \begin{pmatrix} x \\ y \\ z \end{pmatrix} &= \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \text{ so the solution can be given by } \begin{pmatrix} x \\ y \\ z \end{pmatrix} = A^{-1} \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = \\ B \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} &= \begin{pmatrix} \frac{3}{2} & -1 & -\frac{1}{2} \\ \frac{7}{3} & -\frac{5}{3} & -\frac{1}{3} \\ -\frac{1}{6} & \frac{1}{3} & \frac{1}{6} \end{pmatrix} \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} = \begin{pmatrix} -2 \\ -2 \\ 1 \end{pmatrix}. \end{aligned}$$

- (ii) We now need to solve  $A \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ , so we have  $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = A^{-1} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} =$
- $$B \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}.$$
- (c) If  $\mathbf{v} = \begin{pmatrix} -5 \\ -9 \\ 11 \end{pmatrix}$ , we have  $C\mathbf{v} = \begin{pmatrix} -1 & 3 & 2 \\ 4 & -1 & 1 \\ 3 & 2 & 3 \end{pmatrix} \begin{pmatrix} -5 \\ -9 \\ 11 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$ , so there are nonzero vectors such that  $C\mathbf{v} = \mathbf{0}$ .

The argument used in (b)(ii) requires the matrix to have an inverse (i.e.  $\det C \neq 0$ ). Here we know that  $\det C = 0$  and, consequently, that  $C$  is not invertible.