



QCDNUM: Fast QCD Evolution and Convolution

QCDNUM Version 18.00/00

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Abstract

The QCDNUM program numerically solves the evolution equations for parton densities and fragmentation functions in perturbative QCD. Un-polarised parton densities can be evolved up to next-to-next-to-leading order in powers of the strong coupling constant, while polarised densities or fragmentation functions can be evolved up to next-to-leading order. In addition to these evolution routines, a large set of tools is provided to solve n-fold coupled QCD evolution equations and to compute convolution integrals in the zero-mass or generalised mass schemes. Based on this toolbox and included in the software distribution are two add-on packages to calculate zero-mass structure functions in un-polarised deep inelastic scattering, and heavy flavour contributions to these structure functions in the fixed flavour number scheme.

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PROGRAM SUMMARY

Program Title: QCDNUM

Version: 18.00

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Program obtainable from: https://www.nikhef.nl/~h24/qcdnum

Distribution format: gzipped tar file

Journal Reference: Catalogue identifier:

Licensing provisions: GNU Public License

Programming language: FORTRAN77 with a C++ interface to user front-end

Computer: all

Operating system: all

RAM: Typically 3 Mbytes

Keywords: QCD evolution, DGLAP evolution equations, Parton densities, Fragmentation

functions, Structure functions

Classification: 11.5 Quantum Chromodynamics, Lattice Gauge Theory

External routines/libraries: none, except the MBUTIL, ZMSTF, HQSTF and SPLINT packages that are part of the QCDNUM software distribution.

Nature of problem: Evolution of the strong coupling constant and parton densities, up to next-to-next-to-leading order in perturbative QCD. Computation of observable quantities by Mellin convolution of the evolved densities with partonic cross-sections.

Solution method: Parameterisation of the parton densities as linear or quadratic splines on a discrete grid, and evolution of the spline coefficients by solving (coupled) triangular matrix equations with a forward substitution algorithm. Fast computation of convolution integrals as weighted sums of spline coefficients, with weights derived from user-given convolution kernels.

Restrictions: Accuracy and speed are determined by the density of the evolution grid.

Running time: Less than 4 ms on a 2012 MacBook Pro to evolve the gluon and 12 quark densities at next-to-next-to-leading order over a large kinematic range.

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1 Introduction

In perturbative quantum chromodynamics (pQCD), a hard hadron-hadron scattering cross section is calculated as the convolution of a partonic cross section with the momentum distributions of the partons inside the colliding hadrons. These parton distributions depend on the Bjorken-x variable (fractional momentum of the partons inside the hadron) and on a scale μ^2 characteristic of the hard scattering process. Whereas the x-dependence of the parton densities is non-perturbative, the μ^2 dependence can be described in pQCD by the DGLAP evolution equations [1]. The perturbative expansion of the splitting functions in these equations has recently been calculated up to next-to-next-to-leading order (NNLO) in powers of the strong coupling constant α_s [2, 3].

QCDNUM is a FORTRAN77 program (with a C++ interface)¹ that numerically solves the DGLAP evolution equations on a discrete grid in x and μ^2 . Input to the evolution are the x-dependence of the parton densities at some input mass factorisation scale, and an input value of α_s at some input renormalisation scale. To study the scale uncertainties, the renormalisation scale can be varied with respect to the mass factorisation scale. All calculations in QCDNUM are performed in the $\overline{\rm MS}$ scheme.

The program was originally developed in 1988 by members of the BCDMS collaboration [4] for a next-to-leading order (NLO) pQCD analysis of the SLAC and BCDMS structure function data [5]. This code was adapted by the NMC for use at low x [6]. A complete revision led to the version 16.12 which was used in the QCD fits by ZEUS [7], and in a global QCD analysis of deep inelastic scattering data by the present author [8].

QCDNUM17 is the NNLO upgrade of QCDNUM16. A new evolution algorithm, based on quadratic spline interpolation, yields large gains in accuracy and speed. The program can evolve un-polarised parton densities up to NNLO, and polarised densities or fragmentation functions up to NLO. One can also read an external pdf set into memory.

A large toolbox provides routines to solve user-defined coupled QCD evolution equations and to calculate convolution integrals in the zero-mass or generalised mass schemes. Using these tools the functionality of QCDNUM can be extended in add-on packages.

Based on the toolbox and included in the software distribution are the ZMSTF and HQSTF packages to compute un-polarised zero-mass structure functions and, in the fixed flavour number scheme, the contribution from heavy quarks to these structure functions. With the SPLINT package you can cast QCDNUM results into cubic interpolation splines.

Over the years, QCDNUM17 has developed in the present stable version QCDNUM18.

This write-up is organised as follows. In Section 2 we summarise the formalism underlying the DGLAP evolution of parton densities. The QCDNUM numerical method is described in Section 3. Details about the program itself and the description of an example job can be found in Section 4. A subroutine-by-subroutine manual is given in Section 5, while Section 6 shows how to steer the program with data cards. The QCDNUM toolbox is presented in Section 7, and the computation of structure functions in the Appendices E and F, respectively. The C++ interface [9] is described in Section 5.1 and in dedicated text boxes.

¹I thank V. Bertone for providing a first working version of the interface.

2 QCD Evolution

In pQCD, the strong coupling constant α_s evolves on the renormalisation scale μ_R^2 . The starting value of α_s is specified at some input scale, which usually is taken to be m_Z^2 .

The parton density functions (pdf) evolve on the factorisation scale $\mu_{\rm F}^2$. The starting point of a pdf evolution is given by the x dependence of the pdf at some initial scale μ_0^2 . The coupled evolution equations that are obeyed by the gluon and the quark densities can, to a large extent, be decoupled by writing them in terms of the *singlet* quark density (sum of all active quarks and anti-quarks) and *non-singlet* densities (orthogonal to the singlet in flavour space). A nice feature of QCDNUM is that it automatically takes care of the singlet/non-singlet decomposition of a set of pdfs.

Another input to the QCD evolution is the number of active flavours $n_{\rm f}$ which specifies how many quark species (d,u,s,...) are participating in the QCD dynamics. In the fixed flavour number scheme (FFNS), $n_{\rm f}$ is kept fixed throughout the evolution. Input to the evolution are the gluon density and $2n_{\rm f}$ (anti-)quark densities at the input scale μ_0^2 .

In the variable flavour number scheme (VFNS), the flavour thresholds $\mu_{c,b,t}^2$ are introduced and the number of active flavours changes by one unit when crossing a threshold from $n_f = 3$ below μ_c^2 to $n_f = 6$ at and above μ_t^2 . Also here $2n_f$ input densities must be specified at the input scale μ_0^2 . In the VFNS one should make a distinction between the light (d,u,s) and heavy flavours (c,b,t). Like the light quarks, the heavy flavours evolve according to the QCD evolution equations but only at and above their thresholds; below threshold a heavy flavour is either set to zero (dynamic heavy flavour) or to some scale-independent input parameterisation (intrinsic heavy flavour).

The QCD evolution formalism is relatively simple when the renormalisation and factorisation scales are equal, but it becomes more complicated when $\mu_R^2 \neq \mu_F^2$. QCDNUM supports a linear relation between the two scales.

In the following sections we describe the evolution of α_s and the pdfs, the renormalisation scale dependence, the singlet/non-singlet decomposition, and the flavour schemes.

2.1 Evolution of the Strong Coupling Constant

The evolution of the strong coupling constant reads, up to NNLO,

$$\frac{\mathrm{d}a_{\mathrm{s}}(\mu^2)}{\mathrm{d}\ln\mu^2} = -\sum_{i=0}^2 \beta_i \ a_{\mathrm{s}}^{i+2}(\mu^2). \tag{2.1}$$

Here $\mu^2 = \mu_R^2$ is the renormalisation scale and $a_s = \alpha_s/2\pi$. The β -functions in (2.1) depend on the number n_f of active quarks with pole mass $m < \mu$. In the $\overline{\rm MS}$ scheme they are given by [10, 11]

$$\beta_0 = \frac{11}{2} - \frac{1}{3} n_{\rm f}$$

$$\beta_1 = \frac{51}{2} - \frac{19}{6} n_{\rm f}$$

$$\beta_2 = \frac{2857}{16} - \frac{5033}{144} n_{\rm f} + \frac{325}{432} n_{\rm f}^2.$$
(2.2)

The leading order (LO) analytic solution of (2.1) can be written as

$$\frac{1}{a_{\rm s}(\mu^2)} = \frac{1}{a_{\rm s}(\mu_0^2)} + \beta_0 \ln\left(\frac{\mu^2}{\mu_0^2}\right) \equiv \beta_0 \ln\left(\frac{\mu^2}{\Lambda^2}\right). \tag{2.3}$$

In (2.3), the parameter Λ is defined as the scale where the first term on the right-hand side vanishes, that is, the scale where α_s becomes infinite. Beyond LO, the definition of a scale parameter is ambiguous so that it is more convenient to take $\alpha_s(m_Z^2)$ as a reference. The value of α_s at any other scale is then obtained from a numerical integration of (2.1), instead of from approximate analytic solutions parameterised in terms of Λ .

In the evolution of α_s , the number of active flavours is set to $n_f = 3$ below the charm threshold $\mu_R^2 = \mu_c^2$ and is changed from n_f to $n_f + 1$ at the flavour thresholds $\mu_R^2 = \mu_{c,b,t}^2$. At NNLO, and sometimes also at NLO, there are small discontinuities in the α_s evolution at the flavour thresholds [12]; see Section 2.5 for details.

In Figure 1, we plot the evolution of α_s calculated at LO, NLO and NNLO.³ Because

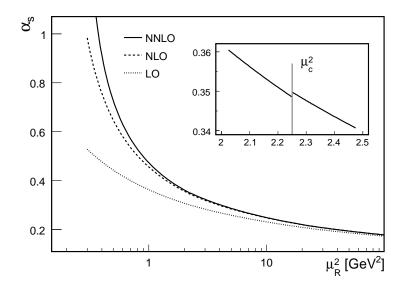


Figure 1 – The strong coupling constant $\alpha_s(\mu_R^2)$ evolved downward from $\alpha_s(m_Z^2) = 0.118$ at LO (dotted curve), NLO (dashed curve) and NNLO (full curve). The inset shows an enlarged view of the NNLO discontinuity in α_s at the charm threshold μ_c^2 .

pQCD breaks down when α_s becomes large, QCDNUM will issue a fatal error when $\alpha_s(\mu^2)$ exceeds a pre-set limit. For a given value of $\alpha_s(m_Z^2)$, it is clear from the figure that such a limit will correspond to larger values of μ^2 at larger perturbative order.

²I thank A. Vogt for providing his 4th order Runge-Kutta routine to integrate (2.1) up to NNLO.

³With the settings $\alpha_{\rm s}(m_{\rm Z}^2) = 0.118$ and $\mu_{\rm c,b,t} = (1.5, 5, 188)$ GeV.

2.2 The DGLAP Evolution Equations

The DGLAP evolution equations can be written as

$$\frac{\partial f_i(x,\mu^2)}{\partial \ln \mu^2} = \sum_{j=q,\bar{q},q} \int_x^1 \frac{\mathrm{d}z}{z} P_{ij} \left(\frac{x}{z},\mu^2\right) f_j(z,\mu^2) \tag{2.4}$$

where f_i denotes an un-polarised parton number density, P_{ij} are the QCD splitting functions, x is the Bjorken scaling variable and $\mu^2 = \mu_{\rm F}^2$ is the mass factorisation scale which we assume here to be equal to the renormalisation scale $\mu_{\rm R}^2$. The indices i and j in (2.4) run over the parton species i.e., the gluon and $n_{\rm f}$ active flavours of quarks and anti-quarks. In the quark parton model, and also in LO pQCD, the parton densities are defined such that $f(x, \mu^2) dx$ is, at a given μ^2 , the number of partons which carry a fraction of the nucleon momentum between x and x + dx. The distribution $xf(x, \mu^2)$ is then the parton momentum density.⁴ Beyond LO there is no such intuitive interpretation. The definition of f then depends on the renormalisation and factorisation scheme in which the calculations are carried out $(\overline{\rm MS}$ in QCDNUM).⁵

Introducing a short-hand notation for the Mellin convolution,

$$[f \otimes g](x) = \int_{x}^{1} \frac{\mathrm{d}z}{z} f\left(\frac{x}{z}\right) g(z) = \int_{x}^{1} \frac{\mathrm{d}z}{z} f(z) g\left(\frac{x}{z}\right), \tag{2.5}$$

we can write (2.4) in compact form as (we drop the arguments x and μ^2 in the following)

$$\frac{\partial f_i}{\partial \ln \mu^2} = \sum_{j=q,\bar{q},q} P_{ij} \otimes f_j. \tag{2.6}$$

If the x dependencies of the parton densities are known at some scale μ_0^2 , they can be evolved to other values of μ^2 by solving this set of $2n_{\rm f}+1$ coupled integro-differential equations. Fortunately, (2.6) can be considerably simplified by taking the symmetries in the splitting functions into account [10]:

$$P_{gq_{i}} = P_{g\bar{q}_{i}} = P_{gq}$$

$$P_{q_{i}g} = P_{\bar{q}_{i}g} = \frac{1}{2n_{f}} P_{qg}$$

$$P_{q_{i}q_{k}} = P_{\bar{q}_{i}\bar{q}_{k}} = \delta_{ik} P_{qq}^{v} + P_{qq}^{s}$$

$$P_{q_{i}\bar{q}_{k}} = P_{\bar{q}_{i}q_{k}} = \delta_{ik} P_{q\bar{q}}^{v} + P_{q\bar{q}}^{s}.$$
(2.7)

Inserting (2.7) into (2.6), we find after some algebra that the singlet quark density

$$q_{\rm s} = \sum_{i=1}^{n_{\rm f}} (q_i + \bar{q}_i) \tag{2.8}$$

obeys an evolution equation coupled to the gluon density

$$\frac{\partial}{\partial \ln \mu^2} \begin{pmatrix} q_{\rm s} \\ g \end{pmatrix} = \begin{pmatrix} P_{\rm qq} & P_{\rm qg} \\ P_{\rm gq} & P_{\rm gg} \end{pmatrix} \otimes \begin{pmatrix} q_{\rm s} \\ g \end{pmatrix}, \tag{2.9}$$

⁴In this section we use the number densities $f(x, \mu^2)$. In QCDNUM itself, however, we use $xf(x, \mu^2)$.

⁵In the DIS scheme f is defined such that the LO (quark-parton model) expression for the F_2 structure function is preserved at NLO. But this is true only for F_2 and not for F_L and xF_3 .

with P_{qq} given by

$$P_{qq} = P_{q\bar{q}}^{v} + P_{q\bar{q}}^{v} + n_{f}(P_{qq}^{s} + P_{q\bar{q}}^{s}). \tag{2.10}$$

Likewise, we find that the non-singlet combinations

$$q_{ij}^{\pm} = (q_i \pm \bar{q}_i) - (q_j \pm \bar{q}_j)$$
 and $q_v = \sum_{i=1}^{n_t} (q_i - \bar{q}_i)$ (2.11)

evolve independently from the gluon and from each other according to

$$\frac{\partial q_{ij}^{\pm}}{\partial \ln \mu^2} = P_{\pm} \otimes q_{ij}^{\pm} \quad \text{and} \quad \frac{\partial q_{v}}{\partial \ln \mu^2} = P_{v} \otimes q_{v}, \tag{2.12}$$

with splitting functions defined by

$$P_{\pm} = P_{qq}^{v} \pm P_{q\bar{q}}^{v}$$
 and $P_{v} = P_{qq}^{v} - P_{q\bar{q}}^{v} + n_{f}(P_{qq}^{s} - P_{q\bar{q}}^{s}).$ (2.13)

The evolution of the q_{ij}^{\pm} is linear in the densities, so that any linear combination of the q_{ij}^{+} or q_{ij}^{-} also evolves according to (2.12).

The splitting functions can be expanded in a perturbative series in α_s which presently is known up to NNLO. For the four splitting functions P_{ij} in (2.9) we may write

$$P_{ij}(x,\mu^2) = a_s(\mu^2) P_{ij}^{(0)}(x) + a_s^2(\mu^2) P_{ij}^{(1)}(x) + a_s^3(\mu^2) P_{ij}^{(2)}(x) + O(a_s^4)$$
(2.14)

where we have set, as in the previous section, $a_s = \alpha_s/2\pi$. Note the separation in the variables x and μ^2 on the right-hand side of (2.14). We drop again the arguments x and μ^2 and write the expansion of the non-singlet splitting functions as

$$P_{\pm} = a_{s} P_{qq}^{(0)} + a_{s}^{2} P_{\pm}^{(1)} + a_{s}^{3} P_{\pm}^{(2)} + O(a_{s}^{4})$$

$$P_{v} = a_{s} P_{qq}^{(0)} + a_{s}^{2} P_{-}^{(1)} + a_{s}^{3} P_{v}^{(2)} + O(a_{s}^{4}).$$
(2.15)

Truncating the right-hand side to the appropriate order in a_s , it is seen that at LO the three types of non-singlet obey the same evolution equations. At NLO, q_{ij}^- and q_v evolve in the same way but different from q_{ij}^+ . At NNLO, all three non-singlets evolve differently.

It is evident from (2.7), (2.10) and (2.13) that several splitting functions depend on the number of active flavours $n_{\rm f}$. This number is set to 3 below $\mu_{\rm F}^2 = \mu_{\rm c}^2$ and changed to $n_{\rm f} = (4,5,6)$ at and above the thresholds $\mu_{\rm F}^2 = \mu_{\rm c,b,t}^2$. In case $\mu_{\rm F}^2 \neq \mu_{\rm R}^2$, QCDNUM adjusts the $\mu_{\rm R}^2$ thresholds such that $n_{\rm f}$ changes in both the splitting and the beta functions when crossing a threshold; see also Section 2.5.

The LO splitting functions are given in Appendix B. Those at NLO can be found in [13] (non-singlet) and [14] (singlet). The NNLO splitting functions and their parameterisations are given in [2] (non-singlet) and [3] (singlet). The DGLAP equations also apply to polarised parton densities and to fragmentation functions (time-like evolution), each with their own set of evolution kernels. For the polarised splitting functions up to NLO we refer to [15], and references therein. The time-like evolution of fragmentation functions at LO is described in [16]. The NLO time-like splitting functions can be found in [13] and [14]. In Appendix A we show which splitting functions actually enter in the space-like and time-like evolution (2.9) since this is not entirely obvious from [14].

Two well-known misprints in [14] are: (i) the lower integration limit in the definition of $S_2(x)$ must read x/(1+x); (ii) in the expression for $\hat{P}_{\rm FF}^{(1,{\rm T})}$ the term $(10-18x-\frac{16}{3}x^2)$ must read $(-10-18x-\frac{16}{3}x^2)$.

2.3 Renormalisation Scale Dependence

In the previous section, we have assumed that the factorisation and renormalisation scales are equal. For $\mu_F^2 \neq \mu_R^2$ we expand a_s in a Taylor series on a logarithmic scale around μ_R^2

$$a_{\rm s}(\mu_{\rm F}^2) = a_{\rm s}(\mu_{\rm R}^2) + a_{\rm s}'(\mu_{\rm R}^2)L_{\rm R} + \frac{1}{2}a_{\rm s}''(\mu_{\rm R}^2)L_{\rm R}^2 + \dots$$
 (2.16)

with $L_{\rm R} = \ln(\mu_{\rm F}^2/\mu_{\rm R}^2)$. Using (2.1) to calculate the derivatives in (2.16), we obtain

$$a_{s}(\mu_{F}^{2}) = a_{s}(\mu_{R}^{2}) - \beta_{0}L_{R} \ a_{s}^{2}(\mu_{R}^{2}) - (\beta_{1}L_{R} - \beta_{0}^{2}L_{R}^{2}) \ a_{s}^{3}(\mu_{R}^{2}) + O(a_{s}^{4})$$

$$a_{s}^{2}(\mu_{F}^{2}) = a_{s}^{2}(\mu_{R}^{2}) - 2\beta_{0}L_{R} \ a_{s}^{3}(\mu_{R}^{2}) + O(a_{s}^{4})$$

$$a_{s}^{3}(\mu_{F}^{2}) = a_{s}^{3}(\mu_{R}^{2}) + O(a_{s}^{4}).$$
(2.17)

To calculate the renormalisation scale dependence of the evolved parton densities, the powers of a_s in the splitting function expansions (2.14) and (2.15) are replaced by the expressions on the right-hand side of (2.17), with the understanding that these are truncated to order a_s when we evolve at LO, to order a_s^2 when we evolve at NLO, and to order a_s^3 when we evolve at NNLO.

2.4 Decomposition into Singlet and Non-singlets

In this section we describe the transformations between a flavour basis and a singlet/non-singlet basis, as is implemented in QCDNUM. For this purpose we write an arbitrary linear combination of quark and anti-quark densities as

$$|f\rangle = \sum_{i=1}^{n_{\rm f}} (\alpha_i |q_i\rangle + \beta_i |\bar{q}_i\rangle),$$
 (2.18)

where the index i runs over the number of active flavours n_f , that is, over those which participate in the QCD evolution. To make a clear distinction between a coefficient and a pdf, we introduce here the ket notation $|f\rangle$ for $f(x, \mu^2)$.

Because a linear combination of non-singlets is again a non-singlet, it follows directly from the definition (2.11) that the coefficients of any non-singlet satisfy the constraint

$$\sum_{i=1}^{n_{\rm f}} (\alpha_i + \beta_i) = 0. \tag{2.19}$$

Thus a non-singlet is—by definition—orthogonal to the singlet in flavour space.

It is convenient to define $|q_i^{\pm}\rangle = |q_i\rangle \pm |\bar{q}_i\rangle$ and write the linear combination (2.18) as

$$|f\rangle = \sum_{i=1}^{n_{\rm f}} (b_i^+|q_i^+\rangle + b_i^-|q_i^-\rangle).$$
 (2.20)

The coefficients $b_i^{\pm}, \, \alpha_i$ and β_i are related by

$$b_i^{\pm} = \frac{\alpha_i \pm \beta_i}{2}, \qquad \alpha_i = b_i^+ + b_i^-, \qquad \beta_i = b_i^+ - b_i^-.$$
 (2.21)

We define a basis of singlet, valence, and $2(n_{\rm f}-1)$ additional non-singlets by

$$|e_1^+\rangle = |q_s\rangle, \qquad |e_1^-\rangle = |q_v\rangle, \qquad |e_i^{\pm}\rangle = \sum_{j=1}^{i-1} |q_j^{\pm}\rangle - (i-1)|q_i^{\pm}\rangle \text{ for } 2 \le i \le n_f. \quad (2.22)$$

In matrix notation, this transformation can be written as

$$|e^{\pm}\rangle = U|q^{\pm}\rangle,$$
 (2.23)

where $U \equiv U(n_{\rm f})$ is the $n_{\rm f} \times n_{\rm f}$ sub-matrix of the 6×6 transformation matrix

$$\boldsymbol{U}(6) = \begin{pmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & -1 & 0 & 0 & 0 & 0 \\ 1 & 1 & -2 & 0 & 0 & 0 \\ 1 & 1 & 1 & -3 & 0 & 0 \\ 1 & 1 & 1 & 1 & -4 & 0 \\ 1 & 1 & 1 & 1 & 1 & -5 \end{pmatrix}. \tag{2.24}$$

It is seen that the second to sixth row of (2.24) are orthogonal to the first row (singlet), so that they indeed represent non-singlets as defined by (2.19). In fact, all rows of \boldsymbol{U} are orthogonal to each other, so that scaling by the row-wise norm yields a rotation matrix, which has the transpose as its inverse. By scaling back this inverse we obtain

$$\boldsymbol{U}^{-1} = \boldsymbol{U}^{\mathrm{T}} \boldsymbol{S}^{2}, \tag{2.25}$$

where $m{U}^{\mathrm{T}}$ is the transpose of $m{U}$ and $m{S}^2$ is the square of the diagonal scaling matrix:

$$S_{ij}^{2} = \delta_{ij} \left(\sum_{k=1}^{n_{\rm f}} U_{ik}^{2} \right)^{-1} = \begin{cases} \delta_{ij}/n_{\rm f} & \text{for } i = 1\\ \delta_{ij}/i(i-1) & \text{for } i > 1. \end{cases}$$
 (2.26)

Using (2.25) and (2.26) to invert any $n_f \times n_f$ sub-matrix of (2.24), it is straight forward to show by explicit calculation that

$$U_{ij}^{-1} = \begin{cases} 1/n_{\rm f} & \text{for } j = 1\\ -1/j & \text{for } j = i \neq 1\\ 1/j(j-1) & \text{for } j > i\\ 0 & \text{otherwise.} \end{cases}$$
 (2.27)

The inverse of the transformation (2.22) is thus given by⁷

$$|q_{1}^{\pm}\rangle = \frac{|e_{1}^{\pm}\rangle}{n_{f}} + \sum_{j=2}^{n_{f}} \frac{|e_{j}^{\pm}\rangle}{j(j-1)}$$

$$|q_{i}^{\pm}\rangle = \frac{|e_{1}^{\pm}\rangle}{n_{f}} - \frac{|e_{i}^{\pm}\rangle}{i} + \sum_{j=i+1}^{n_{f}} \frac{|e_{j}^{\pm}\rangle}{j(j-1)} \quad \text{for } 2 \leq i \leq n_{f}.$$
(2.28)

⁷Here are two fast algorithms to convert flavour pdfs to basis pdfs and *vice versa*, for n flavours.

We can now write the linear combination $|f\rangle$ on the $|e^{\pm}\rangle$ basis as

$$|f\rangle = \sum_{i=1}^{n_{\rm f}} (d_i^+|e_i^+\rangle + d_i^-|e_i^-\rangle),$$
 (2.29)

where the coefficients d_i^{\pm} are related to the b_i^{\pm} of (2.20) by

$$d_i^{\pm} = \sum_{j=1}^{n_f} b_j^{\pm} U_{ji}^{-1}, \qquad b_i^{\pm} = \sum_{j=1}^{n_f} d_j^{\pm} U_{ji}. \tag{2.30}$$

Let the starting values of the DGLAP evolutions be given by the gluon density and $2n_{\rm f}$ arbitrary quark densities, that is, by $2n_{\rm f}+1$ functions of x at some input scale μ_0^2 . Given the flavour decomposition (2.18) of all the input quark densities we can, provided that they are independent, solve the resulting $2n_{\rm f}$ linear equations for the $|q_i^{\pm}\rangle$ and compute from (2.23) start values for the $|e^{\pm}\rangle$ basis of active flavours. We mention here that in QCDNUM a non-active heavy flavour basis function is set to the heavy flavour density itself,

$$|e_i^{\pm}\rangle = |q_i^{\pm}\rangle \quad \text{for } n_f + 1 \le i \le 6.$$
 (2.31)

2.5 Flavour Number Schemes

QCDNUM supports two evolution schemes, known as the fixed flavour number scheme (FFNS) and the variable flavour number scheme (VFNS, see below for the MFNS variant.) In both schemes, the input scale μ_0^2 can be chosen anywhere inside the μ^2 -grid although one should be careful with backward evolution in QCDNUM; see Section 3.4.

In the FFNS we assume that $n_{\rm f}$ quark flavours have zero mass, while those of the remaining flavours are infinitely large. Thus only $n_{\rm f}$ flavours participate in the QCD dynamics so that in the FFNS the value of $n_{\rm f}$ is simply kept constant for all μ^2 , with $3 \le n_{\rm f} \le 6$.

In the VFNS, the number of active flavours changes from $n_{\rm f}$ to $n_{\rm f}+1$ when the factorisation scale is equal to the pole mass of the heavy quarks $\mu_h^2=m_h^2$, $h=({\rm c,b,t})$. A heavy quark h is thus considered to be infinitely massive below μ_h^2 and mass-less above μ_h^2 . As a consequence, the heavy flavour distributions are scale-independent below their thresholds and evolve according to the QCD evolution equations at and above μ_h^2 .

A feature of the VFNS is the existence of discontinuities at the flavour thresholds in α_s and in the parton densities; we will now turn to the calculation of these so-called matching conditions. Because the beta functions (2.2) depend on n_f , it follows that the slope of the α_s evolution is discontinuous when crossing a threshold in the VFNS. Beyond LO there are not only discontinuities in the slope but also in α_s itself [12]. In N^{ℓ}LO, the value of $\alpha_s^{(n_f+1)}$ is, at a flavour threshold, related to $\alpha_s^{(n_f)}$ by, in the notation of [17],

$$a_{\rm s}^{(n_{\rm f}+1)}(\kappa\mu_h^2) = a_{\rm s}^{(n_{\rm f})}(\kappa\mu_h^2) + \sum_{n=1}^{\ell} \left\{ \left[a_{\rm s}^{(n_{\rm f})}(\kappa\mu_h^2) \right]^{n+1} \sum_{j=0}^{n} C_{n,j} \ln^j \kappa \right\} \qquad \ell = 1, 2.$$
 (2.32)

Here μ_h^2 is the threshold defined on the factorisation scale and κ is the ratio μ_R^2/μ_F^2 at μ_h^2 . For $a_s = \alpha_s/4\pi$, the coefficients C in (2.32) read

$$C_{1,0} = 0,$$
 $C_{1,1} = \frac{2}{3},$ $C_{2,0} = \frac{14}{3},$ $C_{2,1} = \frac{38}{3},$ $C_{2,2} = \frac{4}{9}.$

Note that there is always a discontinuity in α_s at NNLO. At NLO, a discontinuity only occurs when $\kappa \neq 1$, that is, when the renormalisation and factorisation scales are different. In case of upward evolution, $\alpha_s^{(n_f+1)}$ is computed directly from (2.32) while for downward evolution, $\alpha_s^{(n_f-1)}$ is evaluated by numerically solving the equation

$$a_{\rm s}^{(n_{\rm f})} - a_{\rm s}^{(n_{\rm f}-1)} - \Delta a_{\rm s} \left(a_{\rm s}^{(n_{\rm f}-1)} \right) = 0,$$

where the function $\Delta a_{\rm s}(a_{\rm s})$ is given by the second term on the right-hand side of (2.32).

In the VFNS, not only α_s but also the parton densities may have discontinuities at the flavour thresholds μ_h^2 because of matching conditions that relate the pdfs evolved in regions of different n_f [18, 19, 20]. For upward evolution these relations read

$$f_i(x, \mu_h^2, n_f + 1) = \sum_j [A_{ij} \otimes f_j](x, \mu_h^2, n_f) \qquad i, j = g, q, \bar{q}.$$
 (2.33)

The matching kernels are expanded in powers of a_s .

$$A_{ij} = A_{ij}^{(0)} + a_{\rm s} A_{ij}^{(1)} + a_{\rm s}^2 A_{ij}^{(2)} + \mathcal{O}(a_{\rm s}^3). \tag{2.34}$$

Here $A_{ij}^{(0)}(z) = \delta_{ij}\delta(1-z)$ and a_s stands for $a_s^{(n_f+1)}(\kappa\mu_h^2)$ as defined by (2.32).

Note that several kernels A_{ij} are absent either because they don't exist or because they are not yet known. At present the discontinuities $\Delta f = f(x, \mu_h^2, n_{\rm f} + 1) - f(x, \mu_h^2, n_{\rm f})$ are given by, for unpolarised evolution,

$$\Delta g = a_{\rm s} A_{\rm gh} \otimes h^{+} + a_{\rm s}^{2} \{ A_{\rm gq} \otimes q_{\rm s} + A_{\rm gg} \otimes g \} \qquad \Delta q_{i}^{\pm} = a_{\rm s}^{2} A_{\rm qq} \otimes q_{i}^{\pm}$$

$$\Delta h^{+} = a_{\rm s} A_{\rm hh} \otimes h^{+} + a_{\rm s}^{2} \{ A_{\rm hq} \otimes q_{\rm s} + A_{\rm hg} \otimes g \} \qquad \Delta h^{-} = a_{\rm s} A_{\rm hh} \otimes h^{-} \qquad (2.35)$$

where, for $n_{\rm f}$ active flavours, g is the gluon, $q_{\rm s}$ the quark singlet, q_i^{\pm} a light or heavy quark that is active, and h^{\pm} the heavy quark that becomes active at μ_h^2 .

Clearly there are no matching discontinuities at LO. For the unpolarised evolution the NLO kernels $A_{\rm gh}$ and $A_{\rm hh}$ contribute only when $h^{\pm}(x, \mu_h^2, n_{\rm f}) \neq 0$, that is, for VFNS evolution with intrinsic heavy flavours. These NLO kernels are given by [18]

$$A_{\rm hh}(x) = -\left[C_{\rm F} p_{\rm FF}(x) \left[1 + 2\log(1 - x)\right]\right]_{+}$$

$$A_{\rm gh}(x) = -C_{\rm F} p_{\rm FG}(x) \left[1 + 2\log(x)\right],$$
(2.36)

with $p_{\rm FF}$ and $p_{\rm FG}$ listed in Appendix A. The other kernels [19] contribute at NNLO.⁸ We remark here that the matching prescription given in [19] is considerably simplified (all terms proportional to powers of $\ln(m^2/\mu^2)$ vanish) because, in QCDNUM, the flavour thresholds on the renormalisation scale are adjusted such that $n_{\rm f}$ changes by one unit in both the beta functions and the splitting functions when crossing a threshold.

At present there is in QCDNUM no matching condition applied to the polarised evolution. For the time-like evolution there is one matching kernel $A_{\rm hg}$ which enters at NLO [20]

⁸In the notation of [19], $A_{\rm gq} = A_{\rm gq,H}^{\rm S,(2)}$ (eq. B.5), $A_{\rm gg} = A_{\rm gg,H}^{\rm S,(2)}$ (B.7), $A_{\rm qq} = A_{\rm qq,H}^{\rm NS,(2)}$ (B.4), $A_{\rm hq} = \tilde{A}_{\rm Hq}^{\rm PS,(2)}$ (B.1) and $A_{\rm hg} = \tilde{A}_{\rm Hg}^{\rm S,(2)}$ (B.3). For the latter we use a parameterisation provided by A. Vogt.

and is the same as $A_{\rm gh}$ in (2.36). How QCDNUM computes the forward and reverse matching of the basis functions $|e^{\pm}\rangle$ is described, case by case, in Appendix C.

As mentioned already above, the heavy quarks (c,b,t) evolve in the VFNS at and above their thresholds μ_h^2 . Below threshold these densities do not evolve and can, in QCDNUM, either be set to zero (VFNS with dynamic heavy flavours) or to some user-defined scale-independent parameterisation (intrinsic heavy flavours). Of course the matching conditions are applied in each case so that even a dynamic heavy flavour evolves upward from a non-zero start value at threshold.

This is illustrated in Figure 2 where we plot the charm and bottom starting pdfs,

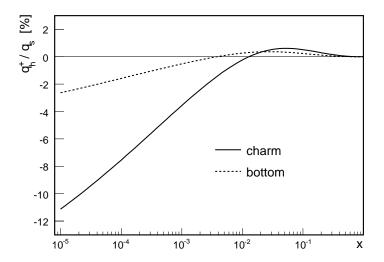


Figure 2 – The NNLO starting densities $q_h^+(x, \mu_h^2)$, normalised to the singlet density $q_s(x, \mu_h^2)$, for charm (full curve) and bottom (dotted curve).

normalised to the singlet density. It is seen that the bottom discontinuity is less than 3% of the singlet over the whole range in x, while for charm it is much larger, exceeding 10% at low x. Note that the starting distributions are negative below $x \approx 10^{-2}$.

QCDNUM also supports what we call the mixed flavour number scheme (MFNS) where the pdfs are evolved with a fixed number of active flavours, while α_s evolves with a variable number of flavours that change at given heavy-quark mass thresholds. Thus n_f remains fixed in the splitting functions, but is variable in the β -functions, as is required in some heavy-flavour calculations, see for instance [21].

3 Numerical Method

The DGLAP evolution equations are in QCDNUM numerically solved on a discrete $n \times m$ grid in x and μ^2 . In such an approach the convolution integrals can be evaluated as weighted sums with weights calculated once and for all at program initialisation. Because of the convolutions, the total number of operations to solve a DGLAP equation

is quadratic in n and linear in m. The accuracy of the solution depends, for a given grid, on the interpolation scheme chosen (linear or quadratic).

The advantage of this 'x-space' approach, compared to 'N-space' [17], is its conceptual simplicity and the fact that one is completely free to chose the functional form of the input distribution since it is fed into the evolution as a discrete vector of input values. A disadvantage is that accuracy and speed depend on the choice of grid and that each evolution will yield no less than $n \times m$ parton density values (typically 10^4) whether you want them or not.

The numerical method used in QCDNUM is based on polynomial spline interpolation of the parton densities on an equidistant logarithmic grid in x and a (not necessarily equidistant) logarithmic grid in μ^2 . The order of the x-interpolation can in be set to k=2 (linear) or 3 (quadratic). The interpolation in μ^2 is always quadratic. With such an interpolation scheme, the DGLAP evolution equations transform into a triangular set of linear equations in the interpolation coefficients. This leads to a very fast evolution of these coefficients from some input scale μ_0^2 to any other scale μ_i^2 on the grid. In the following sections we will describe the spline interpolation, the calculation of convolution integrals and the QCD evolution algorithm. Note that several features of the QCDNUM numerical method have also been proposed in, for example, [22, 23].

3.1 Polynomial Spline Interpolation

To interpolate a function h(y), we sample this function on an (n+1)-point grid

$$y_0 < y_1 < \ldots < y_{n-1} < y_n$$

and parameterise it in each interval by a piece-wise polynomial of order k. Such a piece-wise polynomial is turned into a spline by imposing one or more continuity relations at each of the grid points. Usually—but not always—continuity is imposed at the internal grid points on the function itself and on all but the highest derivative, which is allowed to be discontinuous. Without further constraints at the end points, the spline has k+n-1 free parameters. Increasing the order k of the interpolation thus costs only *one* and not n extra parameters as is the case for unconstrained piece-wise polynomials.

It is convenient to write a spline function as a linear combination of so-called B-splines

$$h(y) = \sum_{i} a_i Y_i(y). \tag{3.1}$$

The basis Y_i of B-splines depends on the order k, on the distribution of the grid points along the y axis (equidistant in QCDNUM) and on the number of continuity relations we wish to impose at the internal grid points and at the two end points. For how to construct a B-spline basis and for more details on splines in general we refer to [24].

In Figure 3 are shown the B-splines for linear (k = 2) quadratic (k = 3) and cubic (k = 4) interpolation on an equidistant grid. In case $h(y_0) = h(0) = 0$ —which is always

⁹In QCDNUM, h(y) represents a parton momentum density in the scaling variable $y = -\ln x$. However, for this section the identification of h with a parton density is not so relevant.

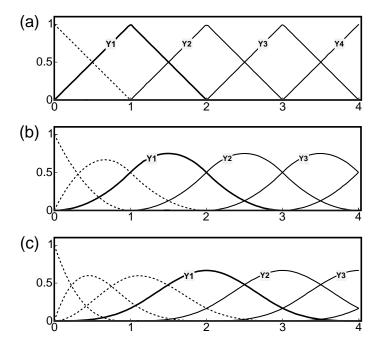


Figure 3 – B-spline bases generated on an equidistant grid. (a) Linear B-splines (k=2). Removing the dashed spline enforces the boundary condition $h(y_0) = 0$; (b) Quadratic B-splines (k=3). Removing the first two dashed splines enforces the boundary condition $h(y_0) = h'(y_0) = 0$; (c) Cubic B-splines (k=4). Removing the first three dashed splines enforces the boundary condition $h(y_0) = h'(y_0) = h''(0) = 0$. Spline interpolation on such a basis is numerically unstable.

true for parton densities—we may remove the first B-spline in the plots of Figure 3. Removing the second B-spline in Figure 3b gives quadratic interpolation with an additional boundary condition $h'(y_0) = 0.10$ With these boundary conditions—and because the grid is equidistant—the remaining B-splines possess translation invariance, that is, the basis can be generated by successively shifting the first spline one interval to the right (full curves in Figure 3a,b). Translation invariance greatly simplifies the evolution algorithm, as we will see later.

It is therefore tempting to extend the scheme to cubic interpolation by removing the first three B-splines in Figure 3c. This would yield a translation invariant basis with the boundary conditions $h(y_0) = h'(y_0) = h''(y_0) = 0$. However, it turns out that such a cubic spline interpolation tends to be numerically unstable. The cure is to drop the constraint $h''(y_0) = 0$ and impose a constraint on $h'(y_n)$ at the other end of the grid. But this cannot be accommodated by the evolution algorithm as it now stands so that we have abandoned cubic and higher order splines in QCDNUM.

If we number the B-splines 1, 2, ..., n from left to right as indicated in Figure 3 it is seen that for both k = 2 and 3 the following relation holds (translation invariance):

$$Y_i(y) = Y_1(y - y_{i-1}). (3.2)$$

 $^{^{10}}$ A parton density parameterisation should thus behave like $h(y \to 0) \propto y^{\lambda}$ with $\lambda > 1$ because otherwise the condition h'(0) = 0 is violated and the spline might oscillate. All known pdf parameterisations fulfil this requirement but when the parameters are under control of a fitting program one should take precautions that λ will always stay above unity.

Furthermore, for linear interpolation (k=2) we have $Y_i(y_i)=1$ so that

$$h(y_0) = 0$$

 $h(y_i) = a_i Y_i(y_i) = a_i 1 \le i \le n.$ (3.3)

Likewise, for quadratic interpolation (k = 3) we have $Y_{i-1}(y_i) = Y_i(y_i) = 1/2$ so that

$$h(y_0) = 0$$

$$h(y_1) = a_1 Y_1(y_1) = a_1/2$$

$$h(y_i) = a_{i-1} Y_{i-1}(y_i) + a_i Y_i(y_i) = (a_{i-1} + a_i)/2 \qquad 2 \le i \le n.$$
(3.4)

We denote $h(y_i)$ by h_i , the column vector of function values by $\mathbf{h} = (h_1, \dots, h_n)^{\mathrm{T}}$, the corresponding vector of spline coefficients by \mathbf{a} and write (3.3) and (3.4) as

$$h = S a \tag{3.5}$$

where S is the identity matrix in case of linear interpolation and a lower diagonal band matrix for the quadratic spline. On a 5-point equidistant grid y_0, \ldots, y_4 , for instance, we have in case of quadratic interpolation the vector $\mathbf{h} = (h_1, \ldots, h_4)^T$ and the matrix

Note that S is sparse but S^{-1} is not. Thus, when a parton distribution h_0 is given at some input scale μ_0^2 , the corresponding vector a_0 of spline coefficients is found by solving (3.5).¹¹ This vector is then evolved to other values of μ^2 using the DGLAP evolution equations as is described in the next two sections.

3.2 Convolution Integrals

The Mellin convolution (2.5) calculated in QCDNUM is not that of a number density f and some kernel g but, instead, that of a momentum density p = xf and a kernel q = xg. These convolutions differ by a factor x:

$$[p \otimes q](x) = x[f \otimes g](x). \tag{3.7}$$

This also true for multiple convolution: for p = xf, q = xg and r = xh we have

$$[p \otimes q \otimes r](x) = x[f \otimes g \otimes h](x). \tag{3.8}$$

A change of variable $y = -\ln x$ turns a Mellin convolution into a Fourier convolution:

$$[f \otimes g](x) = [u \otimes v](y) = \int_0^y dz \ u(z) \ v(y-z) = \int_0^y dz \ u(y-z) \ v(z), \tag{3.9}$$

¹¹Obtaining \boldsymbol{a} from solving (3.5) by forward substitution (Appendix D) costs O(2n) operations. This is cheaper than the alternative of calculating $\boldsymbol{a} = \boldsymbol{S}^{-1}\boldsymbol{h}$ which costs O(n²/2) operations.

where the functions u and v are defined by $u(y) = f(e^{-y})$ and $v(y) = g(e^{-y})$.

In the following we will denote by h(y,t) a parton momentum density in the logarithmic scaling variables $y = -\ln x$ and $t = \ln \mu^2$. In terms of h, the DGLAP non-singlet evolution equation (2.12) is written as

$$\frac{\partial h(y,t)}{\partial t} = \int_0^y dz \ Q(z,t) \ h(y-z,t) = \int_0^y dz \ Q(y-z,t) \ h(z,t)$$
 (3.10)

with a kernel $Q(y,t) = e^{-y}P(e^{-y},t)$. Here P(x,t) is a non-singlet splitting function, as given in Section 2.2. To solve (3.10) we first have to evaluate the Fourier convolution

$$I(y,t) \equiv \int_0^y dz \ Q(y-z,t) \ h(z,t).$$
 (3.11)

Inserting (3.1) in (3.11) we find for the integrals at the grid points y_i (for clarity, we drop the argument t in the following)

$$I(y_i) = \sum_{j=1}^{i} a_j \int_0^{y_i} dz \ Q(y_i - z) \ Y_j(z) \equiv \sum_{j=1}^{i} W_{ij} a_j \qquad (1 \le i \le n).$$
 (3.12)

The summation is over the first i terms only, because B-splines with an index j > i are zero in the integration domain $z \le y_i$, see Figure 3.

Eq. (3.12) defines the weights W_{ij} which are calculated as follows. Because $Y_j(y) = 0$ for $y < y_{j-1}$ the weights can be written as

$$W_{ij} = \int_{y_{i-1}}^{y_i} dz \ Q(y_i - z) Y_j(z) = \int_0^{y_i - y_{j-1}} dz \ Q(y_i - y_{j-1} - z) Y_1(z)$$
 (3.13)

where we have used (3.2) in the second identity. From the property of equidistant grids

$$y_i + y_j = y_{i+j}$$

it follows that W_{ij} depends only on the difference i-j (Toeplitz matrix):

$$W_{ij} = w_{i-j+1}$$
 with $w_{\ell} \equiv \int_{0}^{y_{\ell}} dz \ Q(y_{\ell} - z) Y_{1}(z)$ $(1 \le \ell \le n)$. (3.14)

The integrand only contributes in the region $k\Delta$ where Y_1 is non-zero so that in practical calculations the upper integration limit y_{ℓ} is replaced by $\min(y_{\ell}, k\Delta)$, with Δ the grid spacing. We remark that the calculation of the weights w_{ℓ} is a bit more complicated than suggested by (3.14) because singularities in the splitting functions have to be taken into account; for the relevant formula's we refer to Appendix B.

The weights can thus be arranged in a lower-triangular Toeplitz matrix, as is illustrated by the 4×4 example below:

$$W_{ij} = \begin{pmatrix} w_1 & & & \\ w_2 & w_1 & & \\ w_3 & w_2 & w_1 & \\ w_4 & w_3 & w_2 & w_1 \end{pmatrix}.$$
(3.15)

This matrix is fully specified by the first column, taking n instead of n(n+1)/2 words of storage. This is not only advantageous in terms of memory usage but also in terms of computing speed since frequent calculations like summing the perturbative expansion

$$\mathbf{W}(t) = a_{s}(t) \{ \mathbf{W}^{(0)} + a_{s}(t) \mathbf{W}^{(1)} + \cdots \}$$
(3.16)

takes only O(n) operations instead of $O(n^2/2)$. We write the vector of convolution integrals as I and express (3.12) in vector notation as

$$I = Wa. (3.17)$$

Also multiple convolutions can be calculated as weighted sums. Let f(x) be a number density and $K_{a,b}(x)$ be two convolution kernels. The vector of Mellin convolutions

$$I_i = x_i [f \otimes K_a \otimes K_b](x_i)$$

can be calculated from (3.17), using the weight table

$$\boldsymbol{W} = \boldsymbol{W}_a \boldsymbol{S}^{-1} \boldsymbol{W}_b. \tag{3.18}$$

Here W_a and W_b are the weight tables of K_a and K_b , respectively, and S is the transformation matrix defined by (3.5).

Another interesting convolution is that of two number densities f_a and f_b

$$I_i = x_i [f_a \otimes f_b](x_i).$$

This 'parton luminosity' [25] (times x) is calculated from the Fourier convolution

$$I(y_i) = \int_0^{y_i} dz \ h_a(z) h_b(y_i - z). \tag{3.19}$$

Inserting the spline representation (3.1) gives an expression for the convolution integral as a weighted sum over the set of spline coefficients \boldsymbol{a} of h_a and \boldsymbol{b} of h_b ,

$$I(y_i) = \sum_{j=1}^i \sum_{k=1}^i a_j b_k W_{ijk} \quad \text{with} \quad W_{ijk} \equiv \int_0^{y_i} dz Y_j(z) Y_k(y_i - z).$$

To reduce the dimension of W_{ijk} , we use the translation invariance (3.2) and write

$$W_{ijk} = \int_0^{y_{i-j+1}} dz \ Y_1(z) \ Y_k(y_{i-j+1} - z).$$

Because B-splines with index k > i-j+1 do not have their support inside the integration domain, we obtain an upper limit $k \le i-j+1$. Again using translation invariance yields

$$W_{ijk} = \int_0^{y_{i-j-k+2}} dz \ Y_1(z) \ Y_1(y_{i-j-k+2} - z).$$

We now have a compact expression for the convolution integral (3.19):

$$I(y_i) = \sum_{j=1}^{i} \sum_{k=1}^{i-j+1} a_j b_k \ w_{i-j-k+2} \quad \text{with} \quad w_{\ell} = \int_0^{y_{\ell}} dz \ Y_1(z) \ Y_1(y_{\ell} - z). \quad (3.20)$$

Because Y_1 has a limited support, it turns out that only the first 3 (5) terms of w_{ℓ} are non-zero in case of linear (quadratic) interpolation. The operation count to calculate a convolution of parton densities is thus not more than O(5n), for quadratic splines.

3.3 Rescaling Variable in Convolution Integrals

Calculating structure functions for heavy quarks leads to convolution not in x, but in the so-called rescaling variable χ . In this section we describe how QCDNUM handles such convolution integrals.

The general expression for a structure function can be written as [26]

$$\mathcal{F}_{i}(x,Q^{2}) = \sum_{j} x \int_{\chi}^{1} \frac{\mathrm{d}z}{z} f_{j}(z,\mu^{2}) C_{ij} \left[\frac{\chi}{z}, \mu^{2}, Q^{2}, m_{h}^{2}, \alpha_{s}(\mu^{2}) \right].$$
 (3.21)

Here the index i labels the structure function (e.g. F_2 , F_L , xF_3 , F_2^c , ...) and j labels a parton number density like the gluon, the singlet and various non-singlets. The coefficient function C_{ij} depends on x, on the scale variables μ^2 and Q^2 , on one or more quark masses m_h^2 and on the strong coupling constant α_s . The variable $\chi = ax$, $a \ge 1$, is a so-called rescaling variable which takes into account the kinematic constraints of heavy quark production, for instance,

$$\chi = ax = \left(1 + \frac{4m_h^2}{Q^2}\right)x. {(3.22)}$$

We have $0 \le \chi \le 1$ so that the range of x in (3.21) is restricted to $0 \le x \le 1/a$. In the zero-mass limit a = 1, $\chi = x$, and (3.21) reduces to the Mellin form $x[f \otimes C](x)$.

To calculate the structure function, we first have to evaluate the convolution integrals (for clarity we drop α_s and the indices i, j)

$$\mathcal{F}(x,Q^2) = x \int_{\chi}^{1} \frac{dz}{z} f(z,\mu^2) C\left(\frac{\chi}{z},\mu^2,Q^2,m_h^2\right).$$
 (3.23)

As in Section 3.2 we denote by h(y,t) a parton momentum density in the logarithmic scaling variables $y = -\ln x$ and $t = \ln \mu^2$. In terms of these, and provided that χ is proportional to x, (3.23) can be written as a weighted sum of spline coefficients

$$\mathcal{F}(y_i, Q^2) = \sum_{j=1}^{i} W_{ij} a_j$$
 (3.24)

with $W_{ij} = w_{i-j+1}$ and

$$w_{\ell} = e^{-b} \int_{0}^{y_{\ell}-b} dz \, Y_{1}(z) D(y_{\ell} - b - z, t, Q^{2}, m_{h}^{2}) \qquad (1 \le \ell \le n).$$
 (3.25)

Here $D(y,t,Q^2,m_h^2)=e^{-y}C(e^{-y},e^t,Q^2,m_h^2)$ and $b=\ln(a)$. It is understood that the integral (3.25) is set to zero in case $y_\ell-b\leq 0$.

In the massive schemes, b > 0 depends on t which implies that the weights must be stored in 2-dimensional y-t tables unless, of course, $\chi = x$ (b = 0) so that we are back to the integrals of Section 3.2 which are functions of y only.

3.4 DGLAP Evolution

We denote by the vector $\mathbf{h_0}$ a non-singlet quark density at the input scale $t_0 = \ln \mu_0^2$. The derivative of $\mathbf{h_0}$ with respect to the scaling variable t is given by the DGLAP evolution equation (3.10) which can be written in vector notation as, from (3.5) and (3.17)

$$\frac{\mathrm{d}\boldsymbol{h_0}}{\mathrm{d}t} = \frac{\mathrm{d}\boldsymbol{S}\boldsymbol{a_0}}{\mathrm{d}t} = \boldsymbol{W_0} \; \boldsymbol{a_0} \qquad \text{or} \qquad \frac{\mathrm{d}\boldsymbol{a_0}}{\mathrm{d}t} \equiv \boldsymbol{a_0'} = \boldsymbol{S}^{-1}\boldsymbol{W_0} \; \boldsymbol{a_0}. \tag{3.26}$$

Likewise we have at t_1

$$a_1' = S^{-1}W_1 a_1. (3.27)$$

We have indexed the weight matrices above by a subscript because they depend on t through multiplication by powers of a_s , see (3.16).

Assuming that a(t) is quadratic in t, we can relate a_0 , a_1 , a_0' and a_1' by

$$a_1 = a_0 + (a_0' + a_1')\Delta_1 \tag{3.28}$$

with $\Delta_1 = (t_1 - t_0)/2$. If $t_1 > t_0$, Δ_1 is positive and we perform forward evolution. If $t_1 < t_0$, Δ_1 is negative and we perform backward evolution.

Inserting (3.26) and (3.27) in (3.28) we obtain a relation between the known spline coefficients a_0 and the unknown coefficients a_1

$$(1 - S^{-1}W_1\Delta_1) a_1 = (1 + S^{-1}W_0\Delta_1) a_0.$$
(3.29)

Multiplying both sides from the left by $U_1 \equiv S/\Delta_1$ gives

$$(U_1 - W_1) a_1 = (U_1 + W_0) a_0.$$
 (3.30)

Eq. (3.30) is more convenient than (3.29) because matrix multiplication $S^{-1}W$ is replaced by matrix addition.¹² Note that U is a lower diagonal band matrix so that $U \pm W$ is still lower triangular with, in fact, the Toeplitz structure (3.15) preserved. All this leads to a very simple and fast evolution algorithm, starting from a_0 :

- 1. At t_0 , calculate a_0 from (3.5), W_0 from (3.16) and U_1 as defined above. Then construct the vector $b_1 \equiv (U_1 + W_0) a_0$.
- 2. Subsequently, at t_1 ,
 - (a) Calculate W_1 and the lower triangular matrix $V_1 = U_1 W_1$;
 - (b) Solve the equation $V_1a_1 = b_1$ by forward substitution, see Appendix D;
 - (c) Calculate U_2 and $b_2 = (U_1 + U_2)a_1 b_1$ for the next evolution to t_2 .¹³
- 3. Repeat step 2 at t_2 and so on.

 $^{^{12}}$ In fact, adding a matrix with band structure (3.6) to a lower triangular matrix with structure (3.15) takes only two additions irrespective of the dimension of the matrices.

¹³Using (3.30) it is a simple exercise to establish this relation between b, U and a. Note that b in step (2c) is calculated much faster than b in step (1).

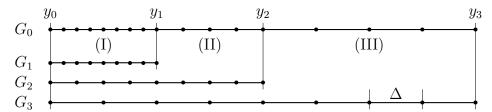
With this algorithm each evolution step consists of a few vector manipulations which have an operation count O(n) and solving one triangular matrix equation which has an operation count $O(n^2/2)$. The total operation count only very weakly depends on the order k of the interpolation chosen: quadratic interpolation is almost for free.

The algorithm can also be used for the coupled evolution of the singlet quark (a_s) and gluon (a_g) spline coefficients, provided we make the following replacements in the formalism:

In Appendix D is shown how the coupled triangular equations are solved by extending the forward substitution algorithm. The operation count is $4 \times O(n^2/2)$ so that for m grid points in t we have in total $O(2n^2m)$ operations for the singlet-gluon evolution and $O(n^2m/2)$ operations for each non-singlet evolution.

It can be seen from (3.5) and (3.28) that h(y,t) is, by construction, a spline in both the variables y and t. However, it turns out that it is technically more convenient to represent the pdfs by their values on the grid, instead of by their spline coefficients. Polynomial interpolation of order k in y and quadratic in t is then done locally on a $k \times 3$ mesh around the interpolation point. The matching discontinuities are preserved by storing, at the flavour thresholds, the pdf values for both $n_f - 1$ and n_f , and by prohibiting the interpolation mesh to cross a flavour threshold. Note, however, that the interpolation routine yields a single-valued function of t, so that one has to calculate $h(y, t_{c,b,t} - \epsilon)$ to view the discontinuity.¹⁴

In QCDNUM it is possible to evolve on multiple equidistant y-grids which allow for a finer binning at low y (large x) where the parton densities are rapidly varying. This is illustrated below by a grid G_0 which is built-up from three equidistant sub-grids G_1 , G_2 and G_3 with spacing $\Delta/4$, $\Delta/2$ and Δ , respectively.



On such a multiple grid, the parton densities are first evolved on the grid G_1 and the results are copied to the region (I) of G_0 . The evolution is then repeated on the grids G_2 and G_3 followed by a copy to the regions (II) and (III) of G_0 , respectively. We refer to Section 4.3 for spectacular gains in accuracy that can be achieved by employing these multiple grids.

3.5 Backward Evolution

As remarked above, the evolution algorithm can—at least in principle—handle both forward and backward evolution in μ^2 simply by changing the sign of Δ in (3.28). This

¹⁴Do not take ϵ too small because QCDNUM may snap to the threshold, see Section 5.5.

works very well for linear spline interpolation but it turns out that backward evolution of quadratic splines can sometimes lead to severe oscillations. This is illustrated in Figure 4 where is shown a non-singlet quark density evolved downward from $\mu_0^2 = 5$

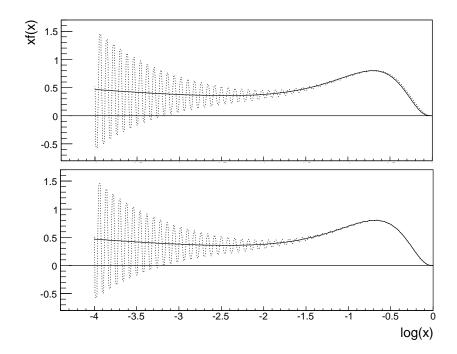


Figure 4 – A non-singlet parton density xf(x) versus $\log(x)$ evolved downward from $\mu_0^2 = 5$ to $\mu^2 = 2 \text{ GeV}^2$ in the quadratic interpolation scheme showing large oscillations (dotted curve). The full curve in the top plot shows the result of downward evolution in the linear interpolation scheme. The full curve in the bottom plot shows an improved result obtained by iteration, as described in the text.

to $\mu^2 = 2 \text{ GeV}^2$ in the quadratic interpolation scheme (dotted curve). In QCDNUM this numerical instability is handled as follows: (i) evolve downward from μ_0^2 to μ^2 in the linear interpolation scheme (which is stable); (ii) then take μ^2 as the starting scale and evolve *upward* to μ_0^2 in the quadratic interpolation scheme (also stable); (iii) calculate the difference Δf between the newly evolved pdf and the original one at μ_0^2 ; (iv) subtract Δf from the starting value at μ_0^2 used in (i) and repeat the procedure.

The full curve in the top plot of Figure 4 shows the result of downward evolution in the linear interpolation scheme, that is, without iterations. Oscillations are absent but the evolution is not very accurate as is evident from the difference between the dotted and full curve at large x. One iteration already much improves the precision as can be seen from the good match at large x between the two curves in the bottom plot. It turns out that one iteration (QCDNUM default), perhaps two, are sufficient while more iterations tend to spoil the convergence. Clearly best is to limit the range of downward evolution by keeping μ_0^2 low or, if possible, to set it at the lowest grid point to avoid downward evolution altogether.

QCDNUM checks for quadratic spline oscillation as follows. We denote the values of the quadratic B-spline at $(\frac{1}{2}\Delta, \Delta, \frac{3}{2}\Delta)$ by $(b_1, b_2, b_3) = (\frac{1}{8}, \frac{1}{2}, \frac{3}{4})$. It is easy to show that

quadratic interpolation mid-between the grid points is given by $\boldsymbol{u} = \boldsymbol{D}\boldsymbol{a}$, where \boldsymbol{D} is a lower diagonal Toeplitz band matrix, of bandwidth 3, which is characterised by the vector (b_1, b_3, b_1) . Likewise, the linear interpolation of the spline at the mid-points is calculated from $\boldsymbol{v} = \boldsymbol{E}\boldsymbol{a}$, where \boldsymbol{E} is the lower diagonal Toeplitz band matrix $(\frac{1}{2}b_2, b_2, \frac{1}{2}b_2)$. The maximum deviation $\boldsymbol{\epsilon} = \|\boldsymbol{u} - \boldsymbol{v}\| = \|(\boldsymbol{D} - \boldsymbol{E})\boldsymbol{a}\|$ should be small; for pdfs sampled on a reasonably dense grid, $\boldsymbol{\epsilon} \approx 0.1$ or less. For each pdf evolution, $\boldsymbol{\epsilon}$ is computed at the input scale, and at the lower and upper end of the μ^2 grid. An error condition is raised when it exceeds a given limit, indicating that the spline oscillates, or that the x-grid is not dense enough.

4 The QCDNUM Program

4.1 Source Code

The QCDNUM source code can be downloaded from the web site

https://www.nikhef.nl/~h24/qcdnum

Unpacking the tar file produces a directory qdcnum-xx-yy-nn with xx-yy the version number and nn the update number (see Appendix G). Sub-directories contain the source code, example jobs and write-ups. See the README file for how to build QCDNUM with a simple script or with AUTOTOOLS.¹⁵

The code comes with a utility package MBUTIL which is a collection of general-purpose routines (some developed privately, some taken from CERNLIB and some taken from public source code repositories like NETLIB). Because QCDNUM uses several of these routines, MBUTIL must also be compiled and linked to your application program. Apart from this, QCDNUM is completely stand-alone. Structure functions can be computed with ZMSTF and HQSTF add-on packages while the SPLINT package can turn results into interpolation splines; see the write-ups in the doc directory of the QCDNUM distribution.

Before compiling QCDNUM you may want to set several parameters which control the size of internal arrays. These parameters can be found in the include file qcdnum.inc:

- mxg0 Maximum number of multiple x-grids [5].
- mxx0 Maximum number of points in the x-grid [300]. ¹⁶
- mqq0 Maximum number of points in the μ^2 -grid [150]. 16
- mst0 Maximum number of table sets in a workspace [30].
- mce0 Maximum number of coupled evolutions [20].
- mbf0 Maximum number of fast convolution scratch buffers [10].
- mky0 Maximum number of data-card keys [50].
- mqs0 Size of the QCDNUM user store [500].
- nwf0 Size of the QCDNUM dynamic store [1200000].

¹⁵AUTOTOOLS is mandatory if you want to use the C++ interface.

¹⁶For technical reasons the maximum number of grid points is about 10 less than mxx0 and mqq0.

The first 8 parameters are simply dimensions of book-keeping arrays which you may want to adjust to your needs. More important is the parameter nwf0 that defines the size of an internal store that contains the weight tables and the tables of parton densities. How many words are needed depends on the size of the tables which, in turn, depends on the size of the current $x-\mu^2$ grid. It also depends on how many pdf sets (un-polarised pdfs, polarised pdfs, fragmentation functions, etc.) you want to store. Note that QCDNUM is very user-friendly by always gracefully grinding to a halt if it runs out of memory, with a message that tells you how large nwf0 should be.

C++

QCDNUM offers the possibility to call its FORTRAN routines via a C++ interface [9]. To learn about the interface we refer to the code shown in Figure 6 below, to the general remarks made in Section 5.1 and to the information given in text boxes like this one.

4.2 User Program

To illustrate the use of QCDNUM, we present in Figure 5 the listing of a simple user program. For a detailed description of the subroutine calls, and for additional routines not included in the example, we refer to Section 5.

C++

In Figure 6 we show the C++ version of the example program.

The first step in a QCDNUM based analysis is initialisation (qcinit), setting up the $x-\mu^2$ grid (gxmake, gqmake) and the calculation of the weight tables (fillwt). The weights depend on the grid definition and the interpolation order so that fillwt must be called after the grid has been defined. The weight tables are calculated for LO, NLO and NNLO as well as for all possible flavour settings in the range $3 \le n_f \le 6$ so that you do not have to call fillwt again when you set or re-set QCDNUM parameters further downstream. Although the weight calculation is fast (typically about 10–20 s) it may become a nuisance in semi-interactive use of QCDNUM so that there is a possibility to dump the weights to disk and read them back in the next QCDNUM run.

In the example code, the weight calculation is followed by setting the perturbative order (setord) and the input value of α_s at some renormalisation scale μ_R^2 (setalf). The call to setcbt sets the VFNS mode and defines the thresholds on the factorisation scale μ_F^2 .

The second step is to evolve the parton densities from input specified at the scale μ_0^2 . It is important to note that QCDNUM evolves parton momentum densities xf(x), although all theory in this write-up is expressed in terms of parton number densities f(x). The evolution is done by calling the routine evolfg which evolves $2n_f + 1$ input parton densities (quarks plus gluon) in the FFNS, VFNS or MFNS scheme. Here n_f is the number of active flavours at μ_0^2 (3 in this example). The routine internally takes care of the proper decomposition of the input quark densities into singlet and non-singlets.

The flavour composition of each of the input quark densities is given by a table of weights def(-6:6,12). In the example program, six light quark input densities are defined: three valence densities $x(q - \bar{q})$ and three anti-quark densities $x\bar{q}$. This is sufficient input to start with 3 flavours in the VFNS. One is completely free to define the flavour composition of the input quark densities as long as they form a linearly

```
С
     program example
С
      _____
     implicit double precision (a-h,o-z)
     data ityp/1/, iord/3/, nfin/0/
                                       !unpolarised, NNLO, VFNS
     data as0/0.364/, r20/2.D0/
                                                      !alphas
     external func
                                            !input parton dists
     dimension def(-6:6,12)
                                          !flavor decomposition
     data def /
                             d u s c b
     tb bb cb sb ub db
                           g
     -6 -5 -4 -3 -2 -1 0
                             1 2
                                    3 4 5
    + 0., 0., 0., 0., -1., 0., 1., 0., 0., 0., 0., 0.,
                                                        !dval
    + 0., 0., 0., -1., 0., 0., 1., 0., 0., 0., 0.,
                                                        !uval
    + 0., 0., 0., -1., 0., 0., 0., 0., 0., 1., 0., 0.,
                                                        !sval
    + 0., 0., 0., 0., 1., 0., 0., 0., 0., 0., 0., 0.,
                                                        !dbar
    + 0., 0., 0., 0., 1., 0., 0., 0., 0., 0., 0., 0., 0.,
                                                        !ubar
    + 0., 0., 0., 1., 0., 0., 0., 0., 0., 0., 0., 0.,
                                                        !sbar
    + 78*0.
     data xmin/1.D-4/, nxin/100/, iosp/3/
                                               !x grid, splord
     dimension qq(2),wt(2)
                                                    !mu2 grid
     data qq/2.D0,1.D4/, wt/1.D0,1.D0/, nqin/60/
                                                    !mu2 grid
     data q2c/3.D0/, q2b/25.D0/, q0/2.0/
                                             !thresh and mu20
     data x/1.D-3/, q/1.D3/, qmz2/8315.25D0/
                                               !output scales
     dimension pdf(-6:6)
                                                 !output pdfs
C
      _____
      call qcinit(6,' ')
                                                  !initialise
      call gxmake(xmin,1,1,nxin,nx,iosp)
                                                      !x-grid
      call gqmake(qq,wt,2,nqin,nq)
                                                    !mu2-grid
                                              !compute weights
      call fillwt(ityp,id1,id2,nw)
      call setord(iord)
                                                !LO, NLO, NNLO
      call setalf(as0,r20)
                                                 !input alphas
                                              !charm threshold
      iqc = iqfrmq(q2c)
      iqb = iqfrmq(q2b)
                                              !bottom threshold
                                          !set VFNS thresholds
      call setcbt(nfin,iqc,iqb,0)
      iq0 = iqfrmq(q0)
                                                 !start scale
      call evolfg(ityp,func,def,iq0,eps)
                                            !evolve all pdf's
                                       !evolve all pdf's !interpolate all pdf's
      call allfxq(ityp,x,q,pdf,0,1)
      csea = 2.D0*pdf(-4)
                                          !charm sea at x,mu2
     asmz = asfunc(qmz2,nfout,ierr)
                                                 !alphas(mz2)
     end
C
     double precision function func(id,x) !momentum density xf(x)
      _____
C
      implicit double precision (a-h,o-z)
     if(id.eq.1) func = dvalence(x)
                                       !1 = defined in def
                                       !6 = defined in def
      if(id.eq.6) func = strangebar(x)
      return
      end
```

Figure 5 – Listing of a QCDNUM application program evolving a complete set of parton densities in the VFNS at NNLO. The array def defines the valence $x(q-\bar{q})$ and antiquark $x\bar{q}$ densities of the light quarks as an input to the evolution. The x dependence of these densities is coded in the function func. The evolved pdfs are interpolated to some x and μ^2 and $\alpha_s(m_Z^2)$ is calculated.

```
C++
        #include <iostream> //not shown <iomanip>, <cmath>, <fstream>
        #include "QCDNUM/QCDNUM.h"
        using namespace std;
        double func(int* ipdf, double* x) {
          int i = *ipdf;
          double xb = *x;
          double f = 0;
          if(i == 0) f = xglu(xb);
          if(i == 1) f = xdnv(xb);
          if(i == 6) f = xsbar(xb);
          return f;
        int main() {
                 ityp = 1, iord = 3, nfin = <math>0;
          double as 0 = 0.364, r20 = 2.0, xmin[] = {1.e-4};
                 iwt[] = {1}, ng = 1, nxin = 100, iosp = 3, nqin = 60;
          double qq[] = { 2e0, 1e4}, wt[] = { 1e0, 1e0};
          double q2c = 3, q2b = 25, q0 = 2;
          double x = 1e-3, q = 1e3, qmz2 = 8315.25, pdf[13];
          double def[] =
                                                //input flavour composition
          // tb bb cb sb ub db g d u
                                                s c b
            { 0., 0., 0., 0., 0.,-1., 0., 1., 0., 0., 0., 0., 0.,
                                                                 // 1=dval
                                                                // 2=uval
             0., 0., 0., -1., 0., 0., 1., 0., 0., 0., 0.,
             0., 0., 0.,-1., 0., 0., 0., 0., 0., 1., 0., 0., 0.,
                                                                // 3=sval
             0., 0., 0., 0., 1., 0., 0., 0., 0., 0., 0.,
                                                                // 4=dbar
              0., 0., 0., 0., 1., 0., 0., 0., 0., 0., 0., 0., 0.,
                                                                 // 5=ubar
                                                                 // 6=sbar
             0., 0., 0., 1., 0., 0., 0., 0., 0., 0., 0., 0., 0.,
                                                          // more not shown
              int nx, nq, id1, id2, nw, nfout, ierr; double eps;
          int lun = 6 ; string outfile = " ";
          QCDNUM::qcinit(lun,outfile);
                                                               //initialise
          QCDNUM::gxmake(xmin,iwt,ng,nxin,nx,iosp);
                                                                   //x-grid
          QCDNUM::gqmake(qq,wt,2,nqin,nq);
                                                                 //mu2-grid
          QCDNUM::fillwt(ityp,id1,id2,nw);
                                                          //compute weights
                                                            //LO, NLO, NNLO
          QCDNUM::setord(iord);
          QCDNUM::setalf(as0,r20);
                                                             //input alphas
          int iqc = QCDNUM::iqfrmq(q2c);
                                                          //charm threshold
          int iqb = QCDNUM::iqfrmq(q2b);
                                                         //bottom threshold
                                                      //set VFNS thresholds
          QCDNUM::setcbt(nfin,iqc,iqb,999);
          int iq0 = QCDNUM::iqfrmq(q0);
                                                              //start scale
          QCDNUM::evolfg(ityp,func,def,iq0,eps);
                                                         //evolve all pdf's
          QCDNUM::allfxq(ityp,x,q,pdf,0,1);
                                                    //interpolate all pdf's
          double csea = 2 * pdf[2];
                                                        //charm sea at x,mu2
          double asmz = QCDNUM::asfunc(qmz2,nfout,ierr);
                                                              //alphas(mz2)
          cout << scientific << setprecision(4);</pre>
          cout << "x, q, CharmSea = " << x << " " << q << " " << csea << endl;
          cout << "as(mz2)
                           = " << asmz << endl;
          return 0;
          }
```

Figure 6 – The QCDNUM example program in C++. Note the different indexing of the array pdf and also that the arguments of func are passed as pointers.

independent set (QCDNUM checks this). Note that the flavours are ordered according to the PDG convention d, u, s, ... and not u, d, s, ... as often is the case in other programs.

The x dependence of these momentum densities at μ_0^2 must be coded for each identifier in an if-then-else block in the function func. The sum rules

$$\int_{0}^{1} xg(x)dx + \int_{0}^{1} xq_{s}(x)dx = 1,$$

$$\int_{0}^{1} [d(x) - \bar{d}(x)]dx = 1,$$

$$\int_{0}^{1} [u(x) - \bar{u}(x)]dx = 2,$$

$$\int_{0}^{1} [s(x) - \bar{s}(x)]dx = 0$$
(4.1)

cannot be reliably evaluated by QCDNUM since it has no information on the x-dependence of the pdfs below the lowest grid point in x. These sum rules should therefore be built into the parameterisation of the input densities.¹⁷ The evolution does, of course, conserve the sum rules once they are imposed at μ_0^2 . The easiest way to evolve with a symmetric strange sea is to include $xs_v = x(s - \bar{s})$ in the collection of input densities and set it to zero for all x at the input scale μ_0^2 . In the VFNs at LO or NLO, dynamically generated heavy flavour densities h = (c, b, t) are always symmetric $(xh - x\bar{h} = 0)$ but this is not true anymore at NNLO, which generates a small asymmetry.

After the parton densities are evolved, the results can be accessed by allfxq. This routine transforms the parton densities from the internal singlet/non-singlet basis to the flavour basis and returns the gluon and (anti)quark momentum densities, interpolated to x and μ^2 . Also here the flavours d, u, s, . . . are indexed according to the PDG convention. The last call in the example program evolves the input value of α_s to the scale m_Z^2 . This evolution is completely stand-alone and does not make use of the μ^2 grid. The function asfunc can thus be called at any point after the call to qcinit. We refer to Section 5 for more ways to access the QCDNUM pdfs, and for ways to change the renormalisation scale with respect to the factorisation scale.

C++

From the example code you may notice that the FORTRAN array pdf(-6:6) is declared as pdf[13] in C++, with an index that counts from zero. Thus pdf(-4) in FORTRAN becomes pdf[2] in C++. For more on the FORTRAN versus C++ correspondence see Section 5.1.

QCDNUM has an extensive checking mechanism which maintains internal consistency and verifies that all subroutine arguments supplied by the user are within their allowed ranges. Error messages might pop-up unexpectedly when the renormalisation scale is changed with respect to the factorisation scale because the low end of the μ^2 grid may then map onto values of $\mu_R^2 < \Lambda^2$.

The starting (renormalisation) scale of α_s may coincide with a flavour threshold, either before or after varying the renormalisation scale with respect to the factorisation scale.

These intrinsic heavy flavours must then be included in the momentum sum and satisfy the flavour counting rule, like the strange quark in (4.1).

If this happens, the input value of α_s is assumed to include the matching condition. This is also true for the input pdfs in case μ_0^2 coincides with a threshold. See Section 5.3 for how to change this default behaviour.

4.3 Validation and Performance

The CPU time that is needed to evolve a pdf on a discrete grid grows quadratic with the number of grid points in x. With linear (quadratic) interpolation the accuracy increases linearly (quadratic) with the number of grid points. It follows that an r-fold gain in accuracy will cost a factor of r^2 in CPU for linear interpolation but only a factor of r for quadratic interpolation. This reduction in cost motivated the inclusion of quadratic splines in QCDNUM.

To investigate the performance of the two interpolation schemes, we compare results from QCDNUM to those from the N-space evolution program PEGASUS [17]. In this comparison a default set of initial distributions [27] is evolved at NNLO from $\mu^2 = 2$ to $\mu^2 = 10^4 \text{ GeV}^2$ with $n_{\rm f} = 4$ flavours. The dashed curve in the top plot of Figure 7 shows

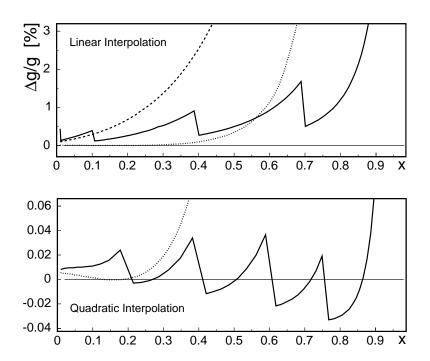


Figure 7 – The relative difference $\Delta g/g$ (in percent) of gluon densities evolved from $\mu^2=2$ to $\mu^2=10^4~{\rm GeV^2}$ by QCDNUM and PEGASUS. Top: Evolution with linear splines on a 200 point single grid down to $x=10^{-5}$ (dashed curve) and on multiple grids (full curve). Bottom: Evolution with quadratic splines on a 100 point single grid (dotted curve, also shown in the top plot) and on multiple grids (full curve). Note the different vertical scales in the two plots.

the relative difference $\Delta g/g$ versus x for QCDNUM evolution with linear splines on a single 200 point grid extending down to $x = 10^{-5}$. The accuracy at low x is satisfactory (few permille) but deteriorates rapidly to $\Delta g/g > 2\%$ for x > 0.35.

The precision is much improved by evolving on multiple grids (Section 3.4) as shown by

the full curve in the top plot of Figure 7. Here the 200 grid points are re-distributed over five sub-grids with lower limits as given in Table 1. For each successive grid the point

Table 1 – Lower x limits of multiple grids used in the evolution with linear and quadratic splines.

	n	x_1	x_2	x_3	x_4	x_5
Linear interpolation	200	10^{-5}	0.01	0.10	0.40	0.70
Quadratic interpolation	100	10^{-5}	0.20	0.40	0.60	0.75
Relative point density		1	2	4	8	16

density is twice that of the previous grid. It is seen from Figure 7 that the precision is now better than 2% for x < 0.85.

The dotted curves in Figure 7 (top and bottom) correspond to evolution with quadratic splines on a single 100 point grid. There is a large improvement in accuracy (more than a factor of 10) compared to linear splines even though the number of grid points is reduced from 200 to 100. However, also here the precision deteriorates with increasing x, reaching a level of 2% at x=0.65. A five-fold multiple grid with lower limits as listed in Table 1 yields a precision $\Delta g/g < 5 \times 10^{-4}$ over the entire range x < 0.9 as can be seen from the full curve in the lower plot of Figure 7. Note that this is for evolution up to $\mu^2 = 10^4$ GeV²; at lower μ^2 the accuracy is even better since it increases (roughly linearly) with decreasing $\ln(\mu^2)$. To fully validate the QCDNUM evolution with PEGASUS, we have made additional comparisons in the FFNS with $n_{\rm f} = 3$, 5 or 6 flavours, in the VFNS with and without backward evolution, and with the renormalisation scale set different from the factorisation scale. This for both un-polarised evolution up to NNLO and polarised evolution up to NLO.

As remarked in Section 3.4, the quadratic spline evolution is not more expensive in CPU time than linear spline evolution. On the contrary: QCDNUM runs 4 times faster since we need only 100 instead of 200 grid points. With the multiple grid definition given in Table 1 for quadratic splines, the density of the first grid $(x > 10^{-5})$ is 12 points per decade. It follows that for evolution down to $x = 10^{-6} (10^{-4})$ a grid with 100 + 12 = 112 (100 - 12 = 88) points should be sufficient.

To investigate the execution speed we did mimic a QCD fit by performing 1000 NNLO evolutions in the VFNS (13 pdfs), using a 60 point μ^2 grid and the 5-fold 100 point x-grid given in Table 1. After each evolution, the proton structure functions F_2 and F_L were computed at NNLO for 1000 interpolation points in the HERA kinematic range. For this test, QCDNUM, MBUTIL, and ZMSTF were compiled with the GFORTRAN compiler, using level 3 optimisation and without array boundary check. The computations took 7.7 CPU seconds on a 2012 MacBook Pro: 3.7 s for the 1000 evolutions and 4.0 s for the 2×10^6 structure function calculations.

¹⁸Similar bench-marking between HOPPET [22] and PEGASUS is given in [27] and [28], where also pdf reference tables can be found. We do not provide here benchmark tables for QCDNUM, but a program that generates such tables and compares them with PEGASUS is available upon request from the author.

5 Subroutine Calls

In this section we describe all out-of-the-box QCDNUM routines, listed in Table 2.

 ${\bf Table} \ {\bf 2} - {\bf Subroutine} \ {\bf and} \ {\bf function} \ {\bf calls} \ {\bf in} \ {\bf QCDNUM}.$

Subroutine or function	Description
Initialisation	
QCINIT (lun, 'filename')	Initialise
SETLUN (lun, 'filename')	Redirect output
NXTLUN (lmin)	Get next free lun
SET GETVAL ('param', val)	Set Get parameters
SET GETINT ('param', ival)	Set Get parameters
QSTORE ('action', i, val)	Store user data
Grid	
GXMAKE (xmi, iwt, n, nxin, *nxout, iord)	Define x grid
IXFRMX (x)	Get grid point from x
XFRMIX (ix)	Get x from grid point
XXATIX (x, ix)	Check x at grid point
GQMAKE (qarr, wt, n, nqin, *nqout)	Define $\mu_{\rm F}^2$ grid
IQFRMQ (q2)	Get grid point from $\mu_{\rm F}^2$
QFRMIQ (iq)	Get $\mu_{\rm F}^2$ from grid point
QQATIQ (q2, iq)	Check $\mu_{\rm F}^2$ at grid point
GRPARS (*nx, *x1, *x2, *nq, *q1, *q2, *io) Get grid definitions
GXCOPY (*array, n, *nx)	Copy x grid
GQCOPY (*array, n, *nq)	Copy μ^2 grid
Weights	
FILLWT (itype, *id1, *id2, *nw)	Fill weight tables
DMPWGT (itype, lun, 'filename')	Dump weight tables
READWT (lun, 'fn', *id1, *id2, *nw, *ie)	Read weight tables
WTFILE (itype, 'filename')	Maintain disk file
NWUSED (*nwtot, *nwuse, *ndummy)	Memory words used
Parameters	
SET GETORD (iord)	Set Get order
SET GETALF (alfs, r2)	Set Get α_s start value
SETCBT (nfix, iqc, iqb, iqt)	Set ffns/vfns params
MIXFNS (nfix, r2c, r2b, r2t)	Set MFNS parameters
GETCBT (*nfix, *q2c, *q2b, *q2t)	Get fns parameters
NFRMIQ (iset, iq, *ithresh)	Get $n_{\rm f}$ at μ^2 grid point
SET GETABR (ar, br)	Set Get $\mu_{\rm R}^2$ scale
RFROMF (fscale)	Convert $\mu_{\rm F}^2$ to $\mu_{\rm R}^2$
FFROMR (rscale)	Convert $\mu_{\rm R}^2$ to $\mu_{\rm F}^2$
SETLIM (ixmin, iqmin, iqmax, dum)	Set cuts
GETLIM (iset, *xmin, *qmin, *qmax, *dum)	Get cuts
CPYPAR (*array, n, iset)	Copy parameter list
KEYPAR (iset)	Get parameter key

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commuted from previous page							
KEYGRP (iset, igroup)	Selective key						
USEPAR (iset)	Activate parameters						
PUSHCP	Push on a stack						
PULLCP	Pull from a stack						
Evolution	Evolution						
ASFUNC (r2, *nf, *ierr)	Evolve $\alpha_{\rm s}(\mu_{\rm R}^2)$						
ALTABN (iset, iq, n, *ierr)	Returns $a_{\rm s}^n(\mu_{\rm F}^2)$						
EVOLFG (itype, func, def, iq0, *eps)	Evolve flavour pdf set						
EVSGNS (itype, func, isns, n, iq0, *eps)	Evolve si/ns pdfs						
PDFCPY (iset1, iset2)	Copy pdf set						
EXTPDF (fun, iset, n, offset, *eps)	Import flavour pdf set						
USRPDF (fun, iset, n, offset, *eps)	Import si/ns pdfs						
NPTABS (iset)	Number of pdf tables						
IEVTYP (iset)	Evolution type						
Interpolation							
BVALXQ IJ (iset, id, x ix, qmu2 iq, ichk)	Get one basis pdf						
<pre>FVALXQ IJ (iset, id, x ix, qmu2 iq, ichk)</pre>	Get one flavour pdf						
ALLFXQ IJ (iset, x ix, qmu2 iq, *pdf, n, ichk)	Get all flavour pdfs						
SUMFXQ IJ (iset, c, isel, x ix, qmu2 iq, ichk)	Linear combination						
FFLIST (iset, c, is, x, q, *f, n, ichk)	Make list of pdfs						
FFTABL (iset, c, is, x, n, q, m, *f, k, ic)	Make table of pdfs						
FFPLOT ('fnam', fun, m, zmi, zma, n, 'txt')	Create plot-file						
FIPLOT ('fnam', fun, m, zval, n, 'txt')	Create plot-file						
SPLCHK (iset, id, iq)	Check spline						
FSPLNE (iset, id, x, iq)	Spline interpolation						
Datacards							
QCARDS (mycards, 'filename', iprint)	Process datacard file						
QCBOOK ('action', 'key')	Manage keycards						

Output arguments are prefixed with an asterisk (*).

In the following we will prefix output variables with an asterisk (*). We use the FORTRAN convention that integer variable and function names start with the letters I—N. Character variables are given in quotes as in 'action'; note that character input arguments are case-insensitive in QCDNUM. All floating-point variables and functions are in double precision unless otherwise stated. It is important that floating-point numbers are entered in double precision format:

```
ix = ixfrmx ( x )     ! ok
ix = ixfrmx ( 0.1D0 )  ! ok
ix = ixfrmx ( 0.1 )  ! wrong!
```

Most QCDNUM functions will, upon error, generate an error message. The inclusion of function calls in **print** or **write** statements can then cause program hang-up in case the function tries to issue a message. Thus:

```
write(6,*) 'Glue = ', fvalxq(1,0,x,q,1) ! not recommended glue = fvalxq(1,0,x,q,1) ! OK write(6,*) 'Glue = ', glue ! OK
```

5.1 C++ Interface

In this section we describe the correspondence between the QCDNUM calls in FORTRAN and C++. For this we also refer to the listings of the example program shown in Figures 5 and 6 of Section 4.2. A few more C++ code examples can be found in the subroutine-by-subroutine descriptions given in the next sections.

1. Unlike FORTRAN, C++ code is case-sensitive. Our convention is that the C++ wrappers have the same name (and argument list) as their FORTRAN counterparts, written in lower case. Furthermore, to avoid possible name-conflicts with other codes, all the wrappers are assigned to the namespace QCDNUM. We thus have

```
\texttt{call SUB(arguments)} \quad \rightarrow \quad \texttt{QCDNUM::sub(arguments);}
```

2. In C++ there is no implicit type declaration so that each variable must be explicitly typed, for example,

```
\begin{array}{ll} \text{implicit double precision (a-h,o-z)} \\ \text{ix = IXFRMX(x)} \end{array} \rightarrow \begin{array}{ll} \text{double x;} \\ \text{int ix = QCDNUM::ixfrmx(x);} \end{array}
```

3. The wrapper for logical functions returns an int and not a bool.¹⁹

```
\begin{array}{lll} \mbox{logical gridpoint, xxatix} & \mbox{double x; int ix;} \\ \mbox{gridpoint = XXATIX(x,ix)} & \rightarrow & \mbox{int gridpoint = QCDNUM::xxatix(x,ix);} \\ \mbox{if(gridpoint) then } & & \mbox{if(gridpoint)} \ \{ \ \dots \ \ \end{array}
```

4. The type of a character input argument should be **string**. String literals are delimited by double quotes in C++ and by single quotes in standard FORTRAN77.

```
character*50 file
file = 'example.log'
call QCINIT(20,file)
call SETVAL('Alim',5.0D0)

string file = "example.log";
QCDNUM::qcinit(20,file);
QCDNUM::setval("Alim",5);
```

5. A FORTRAN array index starts at one unless you specify the index range, as is done for the array pdf(-6:6). However, this is not possible in C++ where arrays always start at index zero. Thus you should account for index shifts between the FORTRAN and C++ arrays as is shown below.

¹⁹In C++ any nonzero (zero) value evaluates as true (false) in logical expressions.

```
\begin{array}{ll} \text{dimension pdf(-6:6)} & \text{double x, q, pdf[13];} \\ \text{call ALLFXQ(1,x,q,pdf,0,1)} & \rightarrow & \text{QCDNUM::allfxq(1,x,q,pdf,0,1);} \\ \text{gluon = pdf(0)} & \text{double gluon = pdf[6];} \end{array}
```

6. Two-dimensional arrays become one-dimensional arrays in the C++ wrappers; see the def array in the listings of Figure 5 and 6. Best is to provide a pointer k(i, j) that maps the indices of a FORTRAN array A(n,m) onto those of a C++ array A[n*m] with k(i+1,j) = k(i,j) + 1, k(i,j+1) = k(i,j) + n and k(1,1) = 0.

```
inline int kij(int i, int j, int n) { return i-1 + n*(j-1); }
```

Here is an example of how to use such a pointer.

```
dimension c(-6:6),x(8),q(5),f(8,5) double c[13],x[8],q[5],f[8*5]; call FTABLE(1,c,0,x,8,q,5,f,1) \rightarrow QCDNUM::ftable(1,c,0,x,8,q,5,f,1); fij = f(i,j) double fij = f[kij(i,j,8)];
```

7. Care has to be taken when passing functions as arguments. An example is the evolution routine evolfg where the pdf values $f_i(x)$ at the input scale μ_0^2 are, in FORTRAN, entered via the user-defined function func(i,x) which should be declared external in the calling routine. To port this to C++ the corresponding function must have its input arguments passed as pointers, as is shown for the input function func in the listing of Figure 6.

C++ wrappers are available for the out-of-the-box routines listed in Table 2 (except the steering by data cards), the toolbox routines (Table 4), and the routines in the ZMSTF, HQSTF, and SPLINT packages. The MBUTIL utility package is only partially interfaced.

5.2 Pdf Sets

The QCDNUM internal memory is a linear array that is dynamically partitioned into sets of tables. Its size is given by the parameter nwf0 in the file qcdnum.inc; if you run out of space (error message), you should increase the value of nwf0 and recompile QCDNUM.

Apart from weight tables, the memory holds a base set (id = 0) that contains an up-to-date list of evolution parameters, α_s tables and pointer tables for fast indexing.

Up to 24 additional pdf sets can be dynamically generated by calling an evolution, copy or import routine.²⁰ These sets 1–24 are classified into 5 different types as follows.

 $^{^{20}}$ Apart from the base set, the maximum number of sets is mset = mst0-6 = 24, where mst0 can be adjusted in qcdnum.inc. The call getint('mset',mset) gives you the current value of mset.

Type-id	Type	Number of tables	Created/filled by
1	Unpolarised	13	EVOLFG
2	Polarised	13	EVOLFG
3	Time-like	13	EVOLFG
4	Imported	13 + n	EXTPDF, EVPCOPY
5	User-defined	1+n	EVSGNS, USRPDF

For types 1–3 the pdfs are stored as the singlet/non-singlet basis functions $|e^{\pm}\rangle$, defined by (2.23) and (2.24) for the active flavours, and by (2.31) for the non-active flavours.

The same is true for a type-4 set, imported via extpdf or evpcopy (toolbox) except that one can include any number of additional pdfs (e.g. a photon pdf) into such a set.

Type 5 is reserved for arbitrary sets of pdfs such as a singlet-gluon set, for instance. A type-5 set is generated by the evolution routine evsgns or the import routine usrpdf.

All pdf sets in memory inherit the parameters and look-up tables from the base set at the moment when they are filled.²¹ Each pdf set in internal memory—and also those in a toolbox workspace—thus remembers exactly how it was created.

5.3 Thresholds

In the VFNs there are one or more flavour thresholds inside the μ^2 -grid. By default, QCDNUM assigns the higher number of flavours to a threshold so that $n_f = (4, 5, 6)$ at iqc,b,t. However, in many subroutines you can enter a negative μ^2 index to select a grid where the lower number of flavours is assigned to the thresholds. Thus $n_f = (3, 4, 5)$ for iq = -iqc,b,t. When not at a threshold it does not matter if you enter +iq or -iq.

The choice between a 456- and a 345-grid affects a VFNS evolution when the input scale coincides with a threshold. It then makes a difference if the evolution starts with the larger (iq0 = +iqh) or smaller number of flavours (iq0 = -iqh); in the first case the pdfs are matched when evolving down, and in the second case when evolving up.

5.4 Initialisation

call QCINIT (lun, 'filename')	
---------------------------------	--

Initialise QCDNUM and define the output stream. Should be called before anything else.

Output logical unit number. When set to 6, QCDNUM messages appear on the standard output. When set to -6, the QCDNUM banner printout is suppressed on the standard output.

'filename' Output file name. Irrelevant when lun is set to 6 or -6.

²¹An exception are copies which inherit from the source set instead of from the base set.

```
call SETLUN ( lun, 'filename' )
```

Redirect the QCDNUM messages. The parameters are as for qcinit above. This routine can be called at any time after qcinit.

```
lun = NXTLUN ( lmin )
```

Returns a free logical number $lun \ge max(lmin, 10)$. This routine can be called before or after qcinit. Returns 0 if there is no free logical unit. Handy if you want to open a file on a unit that is guaranteed to be free.

```
call SETVAL|GETVAL ( 'param', val )
```

Set or get QCDNUM floating point parameters.

- 'null' Result of a calculation that cannot be performed. Default, null = 1.D11.
- 'epsi' The tolerance level in the floating point comparison $|x-y| < \epsilon$, which QCDNUM uses to decide if x and y are equal. Default, epsi = 1.D-9.
- 'epsg' Required numerical accuracy of the Gauss integration in the calculation of weight tables. Default, epsg = 1.D-7.
- 'elim' Allowed difference between a quadratic and a linear spline interpolation midbetween the grid points in x. Default, elim = 0.5; larger values may indicate spline oscillation. To disable the check, set elim < 0.
- 'alim' Maximum allowed value of $\alpha_s(\mu^2)$. When α_s exceeds the limit, a fatal error condition is raised. Default, alim = 10.²²
- 'qmin' Smallest possible lower boundary of the μ^2 grid. Default, qmin = 0.1 GeV².
- 'qmax' Largest possible upper boundary of the μ^2 grid. Default, qmax = 1.D11 GeV².

These parameters can be set and re-set at any time after qcinit.

```
call SETINT|GETINT ( 'param', ival )
```

Set or get QCDNUM integer parameters.

- 'iter' Only relevant when you evolve in the quadratic interpolation scheme. It then sets the number of iterations in the backward evolution, see Section 3.5. When set negative, the backward evolution is quadratic (prone to spline oscillations). When set to zero, the backward evolution is linear, without iterations (numerically stable but less accurate). A value larger than zero gives the number of iterations to perform. Default, iter = 1. Setting iter > 1 is not recommended since this does often worsen instead of improve the accuracy.
- 'tlmc' Switch the time-like matching conditions off (0) or on $(\neq 0)$. Default is on.

²²When you raise alim > 10 then α_s will at some point be limited by internal cuts in QCDNUM.

'nopt' Number of perturbative terms (nopt) in the toolbox evdglap evolution. In standard DGLAP this is 1/2/3 at LO/NLO/NNLO but it may also be something different like 2/3/4 when QED corrections are included in the evolution. The number of perturbative terms at different orders is encoded in an integer such as 123 (default) or 234; see evdglap in Section 7.5 for more on this.

'edbg' Evolution loop debug printout level 0 (default), 1 or 2.

And then for getint only:

'vers'	Returns the current 6-digit version number like 170008. Can be used
	to check if QCDNUM is initialised because the version is set to 0 if not.
'lunq'	Returns the QCDNUM logical unit number. Useful if you want to write
	messages on the same output stream as QCDNUM.
'mset'	Maximum number of pdf sets allowed in internal memory.
'mxg0''nwf0'	Value of a fixed parameter in qcdnum.inc (see Section 4.1).

For instance, getint('nwf0', nwords) will give you the size of the internal memory.

```
call QSTORE ( 'action', i, val )
```

QCDNUM reserves 500 words of memory for the user to store and retrieve data.²³ This is useful to share data between different parts of a program.

C++ In fortran data are usually shared via common blocks but this is rarely done in C++.

Data sharing may be necessary when a function is passed as an argument of a routine. Such a function has a pre-defined argument list so that additional input must be entered via a common block or via qstore, see for instance the C++ example in Section 5.9.

The 'action' argument can be set to any word starting with the letters W, R, L or U.

```
'Write' Write val into qstore(i).
'Read' Read val from qstore(i).
'Lock' Make the store read-only.
'Unlock' Allow to write into the store (default).
```

5.5 Grid

A proper choice of the grid in x and μ^2 is important because it determines the speed and accuracy of the QCDNUM calculations.²⁴ The grid definition also sets the size of the weight and pdf tables and thus the amount of space needed in the internal store.

The x grid must be strictly equidistant in the variable $y = -\ln x$ but in QCDNUM you can generate multiple equidistant grids (Section 3.4) to obtain a finer binning at low y

²³The store size can be set by the parameter mqs0 in qcdnum.inc.

²⁴We refer to Section 4.3 for recommended grids in the linear and quadratic interpolation schemes.

(large x). Multiple grids are generated when the x-range is subdivided into regions with different densities, as is described below.

The μ^2 grid does not need to be equidistant. So you can either enter a fully user-defined grid or let QCDNUM generate one by an equidistant logarithmic fill-in of a given set of intervals in μ^2 .

```
call GXMAKE ( xmin, iwt, n, nxin, *nxout, iord )
```

Generate a logarithmic x-grid.

- xmin Input array containing n values of x in ascending order: xmin(1) defines the lower end of the grid while the other values define the approximate positions where the point density will change according to the values set in iwt. The list may or may not contain x = 1 which is ignored anyway.
- Input integer weights. The point density between xmin(1) and xmin(2) will be proportional to iwt(1), that of the next region will be proportional to iwt(2) and so on. The weights should be given in ascending order and must always be an integer multiple of the previous weight. Thus, to give an example, the triplets {1,1,1} and {1,2,4} are allowed but {1,2,3} is not.
- n The number of values specified in xmin and iwt. This is also the number of sub-grids used internally by QCDNUM.
- nxin Requested number of grid points (not including the point x = 1). Should of course be considerably larger than n for an x-grid to make sense.
- nxout Number of generated grid points. This may differ slightly from nxin because of the integer arithmetic used to generate the grid.
- iord you should set iord = 2 (3) for linear (quadratic) spline interpolation.

With this routine, you can define a (logarithmic) grid in x with higher point densities at large x, where the parton distributions are strongly varying. Thus

```
xmin = 1.D-4
iwt = 1
call gxmake(xmin,iwt,1,100,nxout,iord)
```

generates a logarithmic grid with exactly 100 points in the range $10^{-4} \le x < 1$, while

```
xmin(1) = 1.D-4
iwt(1) = 1
xmin(2) = 0.7D0
iwt(2) = 2
call gxmake(xmin,iwt,2,100,nxout,iord)
```

generates a 100-point grid with twice the point density above $x \approx 0.7$.

A call to gxmake invalidates the weight tables and the pdf store.

```
ix = IXFRMX (x) x = XFRMIX (ix) L = XXATIX (x, ix)
```

The function ixfrmx returns the index of the closest grid point at or below x. Returns zero if x is out of range (note that x = 1 is outside the range) or if the grid is not defined. The inverse function is x = xfrmix(ix). Also this function returns zero if ix is out of range or if the grid is not defined. To verify that x coincides with a grid point, use the logical function xxatix, as in

Note that QCDNUM snaps to the grid, that is, x is considered to be at a grid point i if $|y - y_i| < \epsilon$ with $y = -\ln x$ and, by default, $\epsilon = 10^{-9}$.

```
C++ In the C++ interface a logical function returns an int with 0 (\neq 0) evaluating as false (true). int gridpoint = QCDNUM::xxatix(x,ix); if(gridpoint) { ... }
```

```
call GQMAKE ( qarr, wgt, n, nqin, *nqout )
```

Generate a logarithmic $\mu_{\rm F}^2$ grid on which the parton densities are evolved.²⁵

- qarr Input array containing n values of μ^2 in ascending order: qarr(1) and qarr(n) define the lower and upper end of the grid, respectively. The lower end of the grid should be above 0.1 GeV². If n > 2 then the additional points specified in qarr are put into the grid. In this way, you can incorporate a set of starting scales μ_0^2 , or thresholds $\mu_{c,b,t}^2$.
- Input array giving the relative grid point density in each region defined by qarr. The weights are not restricted by integer multiples as in gxmake but can be set to any value in the range $0.1 \le w \le 10$. With these weights, you can generate a grid with higher density at low values of μ^2 where α_s is changing rapidly.
- n The number of values specified in qarr and wgt $(n \ge 2)$.
- nqin Requested number of grid points. The routine generates these grid points by a logarithmic fill-in of the regions defined above. When nqin = n the grid is not generated but taken from qarr. This allows you to read-in your own μ^2 grid.
- nqout Number of generated grid points. This may differ slightly from nqin because of the integer arithmetic used to generate the grid.

A call to gqmake invalidates the weight tables and the pdf store.

²⁵Note that $\alpha_{\rm s}$ is evolved (without using a grid) on $\mu_{\rm R}^2$ which may or may not be different from $\mu_{\rm F}^2$.

```
iq = IQFRMQ (q2) q2 = QFRMIQ (iq) L = QQATIQ (q2, iq)
```

The function iqfrmq returns the index of the closest grid point at or below μ^2 . The inverse function is qfrmiq. To verify that μ^2 coincides with a grid point, use the logical function qqatiq. As described above for the corresponding x grid routines, a value of zero is returned if q2 and/or iq are not within the range of the current grid, or if the grid is not defined.

```
call GRPARS ( *nx, *xmi, *xma, *nq, *qmi, *qma, *iord )
```

Returns the current grid definitions

nx Number of points in the x grid not including x = 1.

xmi Lower boundary of the x grid.

xma Upper boundary of the x grid. Is always set to xma = 1.

nq Number of points in the μ^2 grid.

qmi Lower boundary of the μ^2 grid.

qma Upper boundary of the μ^2 grid.

iord Order of the spline interpolation (2 = linear, 3 = quadratic).

Copy the x grid to a local array

array Local array containing on exit the x grid but not the value x = 1.

n Dimension of array as declared in the calling routine.

nx Number of grid points copied to the local array. A fatal error occurs if array is not large enough to contain the current grid.

As above, but now for the μ^2 grid.

5.6 Weights

In this section we describe routines to calculate the weight tables, to dump these to disk and to read them back. The weight tables are calculated for all orders (LO,NLO,NNLO) and all number of flavours $n_{\rm f}=(3,4,5,6)$, irrespective of the current QCDNUM settings. There is thus no need to re-calculate the weights when one or more of these settings are changed later on.

Weight tables can be created for un-polarised pdfs, polarised pdfs and fragmentation functions (time-like pdfs) and these can all exist simultaneously in memory.

```
call FILLWT ( itype, *idum1, *idum2, *nwds )
```

Create and fill the weight tables used in the pdf evolution. Both the x and μ^2 grid must have been defined before the call to fillwt.

itype Select un-polarised pdfs (1), polarised pdfs (2) or fragmentation functions (3). Any other input value will select un-polarised pdfs (default).

idum1,2 Integer output variables, now obsolete.

nwds Total number of words used in memory.

You can create more than one set of tables by calling fillwt with different values of itype. For instance, the sequence

```
call fillwt(1,idum1,idum2,nw) !Unpolarised weights
call fillwt(2,idum1,idum2,nw) !Polarised weights
```

makes both the un-polarised and the polarised weights available. If there is not enough space in memory to hold all the tables, fillwt returns with an error message telling how much memory it needs. You should then increase the value of nwf0 in the include file qcdnum.inc, and recompile QCDNUM.²⁶ Note that fillwt acts as a do-nothing when weight tables of a given type already exist:

```
call fillwt(1,idum1,idum2,nw) !Unpolarised weights
call fillwt(1,idum1,idum2,nw) !Do nothing
```

```
call DMPWGT( itype, lun, 'filename' )
```

Dump the weight tables of a given type [1–3] to disk. Fatal error if itype does not exist. Also dumped are the QCDNUM version number, grid definition and some metadata to protect against corruption of the dynamic store when the weights are read back in. The dump is un-formatted so that the output file cannot be exchanged across machines. You can use the function nxtlun of Section 5.4 to find a free logical unit number.

```
call READWT( lun, 'fname', *idum1, *idum2, *nwds, *ierr )
```

Read weight tables from disk. Like in fillwt, you will get a fatal error message if there is not enough space in memory to hold the tables. Otherwise, ierr is set as follows:

- 0 Weights are successfully read in.
- 1 Read error or input file does not exist.
- 2 Input file was written with another QCDNUM version.

²⁶This you may have to repeat several times because fillwt proceeds in stages and will ask you to fulfil the memory needs of the current stage, but not beyond.

- 3 Key mismatch (should never occur).
- 4 Incompatible $x-\mu^2$ grid definition.

When successful (ierr = 0), the routine returns idum1, idum2 and nwds like in fillwt.

Upon failure (ierr $\neq 0$), the routine acts as a do-nothing in which case you should create the weights from scratch, as in

```
lun = nxtlun(0)  !find free logical unit number
call readwt(lun,'polarised.wgt',idum1,idum2,nw,ierr)
if(ierr.ne.0) then
   call fillwt(2,idum1,idum2,nw)
   call dmpwgt(2,lun,'polarised.wgt')
endif
```

The code above thus automatically maintains an up-to-date weight file on disk. For convenience this code is packed into the following routine.

```
call WTFILE( itype, 'filename' )
```

Read weight tables of type 1, 2 or 3 from a disk file. Upon failure (see the error code of readwt) compute the tables from scratch and dump them onto the file. The routine checks that the weights on an existing input file match with itype (fatal error if not).

```
call NWUSED( *nwtot, *nwuse, *ndummy )
```

Returns the size nwtot of the QCDNUM store (the parameter nwf0 in qcdnum.inc) and the number of words used (nwuse). The output argument ndummy is not used at present.

5.7 Parameters

In QCDNUM there are 12 evolution parameters (enumerated in the text boxes below) such as the perturbative order, flavour thresholds, α_s , etc. These all have reasonable defaults but you can re-set them at any time with the routines described below.

The parameter values are stored in the base set (iset = 0), together with α_s tables and pointer tables which depend on the parameters and are always kept up-to-date. The parameters in iset = 0 are called *active* because they steer the α_s and pdf evolution.

When you evolve (Section 5.8) or import (Section 5.9) a pdf set, all parameters and tables are copied to that set. Each pdf set thus fully remembers its own evolution.

```
call SETORD (GETORD (iord) (1)
```

Set (or get) the order of the QCDNUM calculations to 1, 2 or 3 for LO, NLO and NNLO, respectively. Default, iord = 2.

```
call SETALF|GETALF ( alfs, r2 ) (2,3)
```

Set or get for the α_s evolution the starting value alfs and the starting renormalisation scale r2. Default $\alpha_s(m_Z^2) = 0.118$.

Select the FFNS or VFNS, and set thresholds on $\mu_{\rm F}^2$.

- Number of flavours in the FFNS [3-6]. For the VFNS with dynamic (intrinsic) heavy flavours set nfix = 0 (1), see evolfg in Section 5.8 for more on this.
- iqc,b,t Grid indices of the heavy flavour thresholds $\mu_{c,b,t}^2$ in the VFNs. To activate a threshold, set its index within the range of the grid [1-nq]. You can activate a single threshold (c,b,t), two consecutive thresholds (cb,bt), or all three (cbt). They must be given in ascending order and be spaced by at least two grid points. The threshold entries are ignored in case you have selected the FFNs.

By default, QCDNUM runs in the FFNS with $n_{\rm f}=3$.

Select the MFNS mode (see Section 2.5), and set thresholds on $\mu_{\rm R}^2$.

- nfix Fixed number of flavours [3–6] in the pdf evolution.
- r2c,b,t Thresholds defined on the renormalisation scale $\mu_{\rm R}^2$. When crossing a threshold, $n_{\rm f}$ changes in the β -functions but not in the splitting functions.

To activate a threshold, set it to some positive value. You can activate one, two consecutive, or all three thresholds. For instance,

```
call mixfns ( 3, r2c , 0.D0, 0.D0 ) !nf(pdf)=3 nf(as)=3|4 call mixfns ( 4, 0.D0, r2b, r2t ) !nf(pdf)=4 nf(as)=4|5|6
```

When more than one threshold is activated, they should be given in ascending order and be reasonably spaced apart.

```
call GETCBT( *nfix, *q2c, *q2b, *q2t )
```

Return the current threshold settings.

When nfix = 0 (1) on return, QCDNUM runs in the VFNS with dynamic (intrinsic) heavy flavours. Also returned are the threshold values (not the indices) on the μ_F^2 scale.

When nfix = +(3,4,5,6) on return, QCDNUM runs in the FFNS and the values of q2c,b,t are irrelevant.

When nfix = -(3,4,5,6) on return, QCDNUM runs in the MFNS and the routine returns the threshold values on the μ_R^2 scale.

nf = NFRMIQ(iset, iq, *ithresh)

Returns the number of active flavours at a μ^2 grid point.²⁷

iset Pdf set identifier [0-24]. For the current flavour setting put iset = 0.

iq Grid point in μ^2 . The function returns nf = 0 if iq is outside the μ^2 grid.

ithresh Threshold indicator that is set to +1 (-1) if iq is at a threshold with the larger (smaller) number of flavours, to 0 otherwise.

By default **nf** is taken from the 456-grid; set **iq** negative to take it from the 345-grid.

```
nf = nfrmiq( iset, iqc , ithresh ) !nf = 4 and ithresh = 1
nf = nfrmiq( iset, -iqc , ithresh ) !nf = 3 and ithresh = -1
```

Define the relation between the factorisation scale $\mu_{\rm F}^2$ and the renormalisation scale $\mu_{\rm R}^2$

$$\mu_{\rm R}^2 = a_{\rm R} \, \mu_{\rm F}^2 + b_{\rm R}.$$

Default: ar = 1 and br = 0.

Convert the factorisation scale $\mu_{\rm F}^2$ to the renormalisation scale $\mu_{\rm R}^2$ and vice versa.

```
call SETLIM( ixmin, iqmin, iqmax, dum ) (10-12)
```

Restrict the range of a pdf evolution or import to a part of the x- μ^2 grid.

ixmin, iqmin, iqmax Re-define the range of the x- μ^2 grid. To release a cut, enter a value of zero. Fatal error if the cuts result in a kinematic

domain that is too small, or empty.

dum Not used at present.

Use getlim(iset,xmin,qmin,qmax,dum) to read the boundary values (not the grid indices) of a given pdf set. For the current settings put iset = 0 in the call to getlim.

Restricting the evolution to the kinematic range of the data is a nice way to save CPU time in the χ^2 minimisation stage of a QCD fit. When the fit has converged, you can release the cuts and evolve, just once, over the full grid to obtain the final pdf set.

²⁷For backward compatibility we still kept the old routine nflavs(iq,ithresh) which returns $n_{\rm f}$ for the current threshold setting only.

call CPYPAR (*array, n, iset)

Copy the evolution parameters of a pdf set to a local array.

Double precision array, dimensioned to at least array(13) in the calling routine. On exit, the array will be filled with the following parameter values:²⁸

In addition to the evolution parameters is given the pdf type in array(13):

```
1 = \text{unpolarised}, 2 = \text{polarised}, 3 = \text{time-like}, 4 = \text{external}, 5 = \text{user}.
```

n Dimension of array as declared in the calling routine. Fatal error if n < 13. iset Pdf set identifier in the range 0-24. Fatal error if iset does not exist.

```
key = KEYPAR ( iset ) key = KEYGRP( iset, igroup )
```

The function keypar returns the parameter key (kind of version number) of iset [0-24]. Useful to check if parameter sets are (un)equal since then the keys are (un)equal:

```
if( keypar(iset).eq.keypar(0) ) !pdfs are evolved with current params
```

A key for parameter groups is returned by keygrp(iset,igroup) with igroup set to

```
1 = \text{order}, 2 = \alpha_s, 3 = \text{FNS} and thresholds, 4 = \text{scale}, 5 = \text{cuts}, 6 = \text{all}.
```

```
call USEPAR ( iset )
```

Activate the parameters of iset, that is, copy them to iset = 0 and re-initialise the active look-up tables. Fatal error if iset does not exist.

```
call PUSHCP|PULLCP
```

The routine pushep pushes the current parameters on a LIFO stack (5-deep), and pullcp pulls them out again.²⁹ In this way you can *temporarily* activate your favourite set of parameters, as is shown in the example code below.

```
call pushcp !save the current parameters
.. !set parameters to those of an external pdf set
call EXTPDF( .. ) !import the pdfs (they will inherit correct params)
call pullcp !restore the current parameters
```

²⁸Note that integer parameters are returned as double precision numbers so that you should take care of the type conversion yourself, like iord = array(1) or iord = int(array(1)), etc.

²⁹Because of the LIFO stack, a routine that does a push/pull can call another routine that does a push/pull and so on, up to a nesting of 5-deep which should be more than enough.

5.8 Evolution

Standalone evolution of α_s on the renormalisation scale μ_R^2 (without using the μ^2 grid or weight tables). QCDNUM internally keeps track of α_s so that there is no need to call this function; it is just a user interface that gives access to $\alpha_s(\mu_R^2)$.

r2 Renormalisation scale μ_R^2 where α_s is to be calculated.

nf Returns, on exit, the number of flavours at the scale r2.

ierr = 1 Too low value of r2. Internally, there is a cut r2 > 0.1 GeV² and also a cut on the slope, to avoid reaching Λ^2 . Upon error, alphas is set to 0.

The input scale and input value of α_s , the order of the evolution and the flavour thresholds are those set by default or by the routines described in Section 5.7. Note that although α_s is evolved on the renormalisation scale the result, in the VFNS, may still depend on the relation between μ_R^2 and μ_F^2 . This is because the position of the heavy flavour thresholds depends on this relation.³⁰

It is important to realise, however, that $\alpha_s(\mu_R^2)$ returned by asfunc is *not* the right expansion coefficient in a QCDNUM perturbative series because α_s must then be given at the factorisation scale μ_F^2 instead of at the renormalisation scale μ_R^2 . The relation between $\alpha_s(\mu_R^2)$ and $\alpha_s(\mu_F^2)$ is given by the truncated Fourier series (2.17) where each power of α_s is computed separately (instead of simply raising α_s to some power). Note that the truncation is different for the splitting function expansion $(\alpha_s, \alpha_s^2, \alpha_s^3)$ and the structure function expansion $(1, \alpha_s, \alpha_s^2)$.

To keep track of all this, QCDNUM maintains tables of $\alpha_{\rm s}^n(\mu_{\rm F}^2)$ in terms of powers of $a_{\rm s} \equiv \alpha_{\rm s}/2\pi$ and keeps them always up-to date. The following function gives you access to these internal tables, or to those stored in one of the pdf sets 1-24.

Returns the value of $(\alpha_s/2\pi)^n$, properly truncated, at the factorisation scale μ_F^2 .

iset Identifier of the active α_s table (0) or of a pdf set (1–24). Fatal error if iset does not exist.

iq Index of a μ^2 grid point.

n Power of α_s which should be set as follows for the different perturbative series.

ierr Set, on exit, to 1 if iq is close to or below the value of Λ^2 , and to 2 if iq is outside the grid boundaries. Upon error, the function returns zero.

To have access to the NNLO discontinuities at the thresholds, you can set iq positive (takes n_f above threshold, QCDNUM default) or negative (n_f below threshold), thus:

```
asn = altabn ( iset, iqc, n, ierr ) !result for nf = 4
asn = altabn ( iset, -iqc, n, ierr) !result for nf = 3
```

Note that the QCDNUM expansion parameter is $\alpha_s/2\pi$ but that many convolution kernels found in the literature are defined for an expansion in $\alpha_s/4\pi$, in which case you must be careful to account somewhere for the missing factors of 2^n .

```
call EVOLFG( itype, func, def, iq0, *epsi )
```

Evolve a set of parton momentum densities from an input scale μ_0^2 . The gluon and $2n_{\rm f}$ quark densities must be given as an input, with $n_{\rm f}$ the number of active flavours at μ_0^2 .

Here and in the following the parton densities are written on the flavour basis (note the PDG convention) with an indexing defined by

We will assume below that evolfg runs in the FFNS or in the VFNS with dynamic generation of heavy flavours. More on this at the end of this section.

itype Select un-polarised (1), polarised (2) or time-like (3) evolution. By default, the pdfs are stored in iset = itype = (1,2,3) but you can also select an output pdf set explicitly as follows:

itype
$$\rightarrow$$
 10*iset + itype,

with iset = 1-24. Thus itype = 2 or 22 stores polarised pdfs in set 2 while itype = 52 stores them in set 5. Note that if the pdf set exists it will be overwritten, otherwise it is created (fatal error if not enough space in memory).

func User-defined function func(j,x) (see below) that returns the input parton momentum density $xf_j(x)$ at iq0. Must be declared external in the calling routine. The index j runs from 0 (gluon) to $2n_f$.

Input array dimensioned in the calling routine to def(-6:6,12) which contains in $def(i \neq 0,j)$ the contribution of quark species i to the input distribution j. The indexing of i is given in (5.1) and the structure of def is shown in Figure 8. The evolution routine uses the $2n_f \times 2n_f$ sub-matrix of quark coefficients and tries to invert this matrix. If that fails, the $2n_f$ input quark densities are not linearly independent in flavour space and an error condition is raised.

iq0 Grid index of the starting scale μ_0^2 . The input scale can be anywhere within the μ^2 grid,³¹ but it should be kept as low as possible to avoid backward evolution

³¹If needed, the current cuts will be opened to include iq0, and be closed again after the evolution.

	$\bar{\mathrm{t}}$	$\bar{\mathrm{b}}$	$\bar{\mathbf{c}}$	$\bar{\mathbf{s}}$	ū	$\bar{\mathrm{d}}$	g	d	u	S	$^{\mathrm{c}}$	b	t
i	-6	-5	-4	-3	-2	-1	0	1	2	3	4	5	6
j=1	6	5	4	3	3	3	•	3	3	3	4	5	6
2	6	5	4	3	3	3	٠	3	3	3	4	5	6
3	6	5	4	3	3	3	•	3	3	3	4	5	6
4	6	5	4	3	3	3	٠	3	3	3	4	5	6
5	6	5	4	3	3	3	•	3	3	3	4	5	6
6	6	5	4	3	3	3	٠	3	3	3	4	5	6
7	6	5	4	4	4	4	•	4	4	4	4	5	6
8	6	5	4	4	4	4	•	4	4	4	4	5	6
9	6	5	5	5	5	5		5	5	5	5	5	6
10	6	5	5	5	5	5	•	5	5	5	5	5	6
11	6	6	6	6	6	6	•	6	6	6	6	6	6
12	6	6	6	6	6	6		6	6	6	6	6	6

Figure 8 – The def array specifying the flavour structure of the input pdfs at μ_0^2 . Indicated are the elements that evolfg uses to build the 6×6 coefficient matrix for $n_{\rm f} = 3$, and its extension to 4, 5 and 6 flavours. The $2n_{\rm f} \times 2n_{\rm f}$ coefficient matrix for a given $n_{\rm f}$ at μ_0^2 must be non-singular.

over a large range in μ^2 . By default you evolve on the 456-grid (see Section 5.3). This means that when the input scale coincides with a threshold, the evolution starts with $n_{\rm f}$ above the threshold and the matching is applied when evolving down. Set iq0 negative to use the 345-grid: the evolution then starts with $n_{\rm f}$ below the threshold and the pdfs are matched when evolving up.³²

epsi Maximum deviation of the quadratic spline interpolation from linear interpolation mid-between the grid points (see Section 3.4). By definition, epsi = 0 when QCDNUM is run in the linear interpolation scheme but for quadratic interpolation a large value epsi > elim may indicate spline oscillation and will cause a fatal error message.³³ If that happens, see Section 5.12 for how to proceed.

To illustrate the management of sets, here is code that stores un-polarised and polarised pdfs in the default sets 1 and 2.

```
call evolfg(1, func1, def1, iq01, epsi1) !unpolarised
call evolfg(2, func2, def2, iq02, epsi2) !polarised
```

And here is code that stores LO/NLO/NNLO un-polarised pdfs in sets 1, 2 and 3.

```
do iord = 1,3
  call setord(iord)
  call evolfg(10*iord+1, func, def, iq0, epsi)
enddo
```

The input function func must be coded as follows.

```
double precision func(ipdf,x)
implicit double precision (a-h,o-z)
```

³²You can set a debug print level via setint('edbg',1) to see what evolfg does exactly.

³³If needed, the value of elim can be set by a call to setval.

```
if(ipdf.eq.-1) initialise the function, if needed
if(ipdf.eq. 0) func = xgluon(x)
if(ipdf.eq. 1) func = xquarks1(x)
if(ipdf.eq. 2) func = xquarks2(x)
...
return
end
```

The evolfg routine will first make a dummy call to func with ipdf = -1 which allows you to initialise the function, if needed (e.g. read input parameters from qstore).

```
C++ The C++ function prototype is (see also the listing Figure 6 in Section 4.2):

double func ( int* ipdf, double* x )
```

Because evolfg will call func only at the grid points x_i , it is possible to feed tabulated values into the evolution routine as is illustrated by the following code.

```
double precision func(ipdf,x)
implicit double precision (a-h,o-z)
common /input/ table(0:12,nxx) !table with input values
ix = ixfrmx(x)
func = table(ipdf,ix)
return
end
```

Up to now we have assumed that nfix is set to 3–6 (FFNS) or 0 (VFNS) in the upstream call to setcbt. In both these modes evolsg calls func only for the gluon and the $2n_{\rm f}$ active quarks.³⁴ All other parameterisations in func are ignored as well as all the elements in def beyond the $2n_{\rm f} \times 2n_{\rm f}$ sub-matrix shown in Figure 8. The flavours that are not active at μ_0^2 are set to zero and evolve, in the VFNS, upward from their thresholds $\mu_h^2 > \mu_0^2$ (dynamic heavy flavour evolution).³⁵

Setting nfix = 1 in setcbt causes evolfg to call func also for the non-active heavy flavours. The heavy-flavour parameterisations in func then provide non-zero initial conditions for the evolution above μ_h^2 and scale-independent pdfs for $\mu^2 < \mu_h^2$ (intrinsic heavy-flavour evolution). Intrinsic heavy flavours should be parameterised as follows.

- Use ipdf = 7-8 for charm, 9-10 for bottom, and 11-12 for top.
- Specify the flavour composition of each parameterisation in the corresponding rows of def. The restriction is that, for each flavour, the two input pdfs must be independent linear combinations of xh and $x\bar{h}$, without an admixture of other flavours.
- You can terminate the input by setting an entire row of coefficients to zero; for instance an empty row 9 puts the bottom and top initial condition to zero.³⁶

Finally note that intrinsic heavy flavours do contribute to the proton momentum and should be included in the momentum-sum integral (4.1). They should of course also satisfy the valence counting rule.

³⁴Remember that $n_{\rm f}=(4,5,6)$ for iq0 = +iqc,b,t and (3,4,5) for iq0 = -iqc,b,t.

³⁵Heavy flavours with $\mu_h^2 < \mu_0^2$ are active and therefore intrinsic by definition. Thus they are not set to zero below threshold but, after reverse matching, to the threshold value $f(x, \mu_h^2)$.

³⁶A filled row 9 and empty row 10 yields the complaint that bottom input is not linearly independent.

```
call EVSGNS( itype, func, isns, n, iq0, *epsi )
```

This routine evolves an arbitrary set of singlet/non-singlet pdfs. It is not possible to correctly match such sets at the thresholds so that the evolution can only run in the FFNS or MFNS, without thresholds on the μ_F^2 scale.

The evsgns arguments are as those of evolfg, except that the array def is replaced by

isns Input integer array (see below), dimensioned to at least n in the calling routine. Number of singlet/non-singlet pdfs to evolve.

In isns is specified the type of each of the n evolutions. This type is encoded as

- +1 Singlet evolution. This specifier can only be put in isns(1); fatal error if it occurs elsewhere. The singlet (1) will automatically be coupled to a gluon (0).
- -1 Valence non-singlet evolution.
- +2, -2 Evolution of a $q_{\rm ns}^+$ or $q_{\rm ns}^-$ non-singlet.

The input function func(ipdf,x) will be called with ipdf running from 0 (gluon) to n if a singlet is included in the set, and from 1 to n if not. The routine generates a type-5 set (see Section 5.2) of n + 1 pdfs with always one gluon pdf (0), be it filled or not.

5.9 Pdf Import

Additional pdf sets with identifiers 1–24 can be stored in QCDNUM memory by (i) copying a pdf set to another location, (ii) importing a pdf set from some external source and (iii) importing a pdf set from a toolbox workspace (see Section 7.5).

As mentioned in Section 5.2, pdf sets in QCDNUM contain the gluon, singlet and non-singlet basis tables (13 pdfs) as well as the α_s tables and a list of evolution parameters. It is possible to import additional pdfs into the set like, for instance, a photon pdf.

```
call PDFCPY ( iset1, iset2 )
```

Copy an internal pdf set to another location. Acts as a do-nothing when iset1 = iset2.

iset1 Identifier of a pdf set. Fatal error if iset1 does not exist.

iset2 Identifier 1-24 of the target set. If iset2 does not exist it is created, otherwise it is overwritten. Fatal error if iset2 cannot hold the tables of iset1 or if the internal memory is not large enough to hold iset2.

Here is an example that stores LO/NLO/NNLO un-polarised pdfs in the sets 4, 5 and 6.

```
do iord = 1,3
  call setord(iord)
  call evolfg(1, func, def, iq0, epsi)
  call pdfcpy(1, iord+3)
enddo
```

```
call EXTPDF ( fun, iset, n, offset, *epsi )
```

Import a pdf set from an external source.

fun User function (see below), declared external in the calling routine.

Pdf set identifier in the range 1–24. If iset does not exist it is created (with 13 + n pdf tables), otherwise it is overwritten. Fatal error if there is not enough memory to hold iset or if an existing set cannot hold 13 + n pdfs.

n Number of extra pdfs to be imported, beyond the 13 quark and gluon pdfs.

offset Relative offset δ at the thresholds μ_h^2 used to catch matching discontinuities, if any, by sampling the pdfs at $\mu_h^2(1\pm\delta)$. This offset must be large enough to accommodate the pdf transition over the threshold. It is also important that the thresholds are set correctly in QCDNUM before the call to extpdf. 37

Returns the maximum deviation of the quadratic spline interpolation from linear interpolation mid-between the grid points, as is described for the routine evolfg. In case of problems, see Section 5.12.

The function fun provides the interface between QCDNUM and the external repository.

```
double precision function fun ( ipdf, x, qmu2, first )
implicit double precision (a-h,o-z)
logical first
if(first) some initialisation, if any
if(i .eq. -6) fun = xTopBar(x,qmu2)
if(i .eq. -5) ...
```

C++ The C++ prototype is double fun (int* ipdf, double* x, double* q, bool* first).

The index ipdf runs from -6 to 6, indexed according to (5.1) in the PDG convention. For the extra pdfs, if any, the index is $7 \le ipdf \le 6+n$. The first time func is called by extpdf the flag first is set to true and you can initialise the function, if needed.

C++ Here is a C++ example that calls extpdf to copy a pdf set iset1 to iset2. At function initialisation iset1 is read from qstore; note that it is declared static in the body of fun. This is of course just an example; in practice one should use pdfcpy to copy pdf sets.

```
double fun( int* i, double* x, double* q, bool* first ){
    static int iset1;    double val;
    if(*first) { QCDNUM::qstore("Read",1,val); iset1 = int(val); }
    return QCDNUM::fvalxq(iset1,*i,*x,*q,1);
    }

// Copy iset1 to iset2
    QCDNUM::qstore("Write",1,double(iset1)); //pass iset1 to fun via qstore
    QCDNUM::extpdf(fun,iset2,n,offset,epsi); //can set offset = 0 here
```

³⁷If the external representation produces sharp steps exactly at the thresholds you can set $\delta = 0$ to let QCDNUM tightly bracket the μ_h^2 . This will then yield the best possible representation in QCDNUM.

It is important that the perturbative order, flavour scheme, positions of the thresholds and the input value of α_s are set correctly in QCDNUM before the call to extpdf. Otherwise the pdf set may inherit incorrect evolution parameters and α_s tables, or might suffer from corrupted threshold discontinuities if the thresholds are set wrongly. Note also that the kinematic cuts, if any, will be applied when filling the pdf tables. This allows you to properly define the kinematic range of the imported pdf set.

```
call USRPDF ( fun, iset, n, offset, *epsi )
```

This routine is the same as extpdf except that it creates a type-5 set (see Section 5.2) with n+1 pdf tables. The ipdf index in fun runs from 0 (gluon) to n and the input is transferred directly to the tables without a transformation to the basis functions $|e^{\pm}\rangle$.

```
double precision function fun ( ipdf, x, qmu2, first )
implicit double precision (a-h,o-z)
logical first
if(first) some initialisation, if any
if(i .eq. 0) fun = xGluon(x,qmu2)
if(i .eq. 1) fun = MyPdf1(x,qmu2)
...
```

These functions return the number of pdf tables (nptabs) and the pdf type (ievtyp) in iset = 1-24. The pdf type is defined by

```
1 = \text{unpolarised}, 2 = \text{polarised}, 3 = \text{time-like}, 4 = \text{external}, 5 = \text{user}.
```

Can be used to check if iset exists, because the functions return 0 if not.

5.10 Pdf Interpolation

There are several routines to access the flavour momentum densities $|xg\rangle$, $|xq\rangle$ and $|x\bar{q}\rangle$, or one of the basis pdfs $|xe^{\pm}\rangle$ as defined by (2.23), (2.24) and (2.31). The pdfs can be interpolated to an (x, μ^2) point inside the grid, or just be given at a grid point.³⁸

Below we give the indexing of the flavour pdfs (note the PDG convention)

and that of the basis pdfs

$$\frac{0 \quad 1 \quad 2 \quad 3 \quad 4 \quad 5 \quad 6 \quad 7 \quad 8 \quad 9 \quad 10 \quad 11 \quad 12 \quad 13 \quad \cdots}{g \quad q_{s} \quad e_{2}^{+} \quad e_{3}^{+} \quad e_{4}^{+} \quad e_{5}^{+} \quad e_{6}^{+} \quad q_{v} \quad e_{2}^{-} \quad e_{3}^{-} \quad e_{4}^{-} \quad e_{5}^{-} \quad e_{6}^{-} \quad f_{1} \quad \dots}$$

$$(5.3)$$

Here f_i is an imported pdf beyond the gluon or quarks with an index 6+i on the flavour basis, and 12+i on the internal basis.

³⁸In older QCDNUM versions you could only interpolate pdfs evolved with the current set of parameters. This restriction has disappeared and there is no more need to activate parameters via usepar.

```
pdf = BVALXQ ( iset, id, x, qmu2, ichk )
```

Returns one of the basis pdfs $|xg\rangle$ or $|xe^{\pm}\rangle$, interpolated to x and μ^2 .

iset Pdf set identifier [1-24].

Basis pdf identifier running from 0 to 12+n, indexed as given in (5.3). Here n is the number of additional pdfs in iset, beyond the gluon and the quarks.

x, qmu2 Input value of x and μ^2 .

ichk Input flag that steers the error checking.

- O Return a null value when x or qmu2 are outside the grid or cuts.
- +1 Fatal error message when x or qmu2 are outside the grid or cuts.
- -1 As above, but do not check the input values of iset and id.

Thus ichk = -1 makes the routine faster but see the remark at the end of this section.

This routine can also handle type-5 pdf sets (see Section 5.2) but for these the identifier runs from 0 (gluon) to n.

Returns $|xg\rangle$, $|xq\rangle$ or $|x\bar{q}\rangle$. The arguments are the same as for bvalxq except that the pdf identifier runs from -6 to 6+n, indexed according to (5.2). Note that fvalxq is slower than bvalxq because a linear combination of basis pdfs has to be computed.

This routine cannot handle type-5 pdf sets nor can any of the routines below.

```
call ALLFXQ ( iset, x, qmu2, *pdf, n, ichk )
```

Returns all flavour-pdf values in one call. The arguments are as given above, except

pdf Output array, dimensioned to pdf(-6:6+n) in the calling routine.

n Number of additional pdfs (those beyond the gluon and quarks) to be returned in pdf, provided that they exist in iset (fatal error if not).

```
pdf = SUMFXQ ( iset, c, isel, x, qmu2, ichk )
```

Return the gluon or a weighted sum of quark densities, depending on the selection flag isel. The arguments are as given above, except

c Input array, dimensioned to c(-6:6) in the calling routine, containing the coefficients of a linear combination of quarks and antiquarks, indexed according to (5.2). Note that c(0) is ignored since it does not correspond to a quark.

isel Selection flag that determines what is actually returned.

- 0 Return the gluon density $|xq\rangle$.
- 1 Return the linear combination c, summed over the active flavours.
- 2-8 Return a specific singlet/non-singlet quark component (see below).
 - 9 Include intrinsic heavy flavours, if any, in the linear combination c.
- 12+i Return the additional pdf $|xf_i\rangle$, if present in iset (fatal error if not).

To explain isel = 1-8 we write the quark linear combination on the $|e^{\pm}\rangle$ basis as

$$\sum_{i=1}^{n_{\rm f}} \left(c_i | x q_i \rangle + c_{-i} | x \bar{q}_i \rangle \right) = d_1^+ | x e_1^+ \rangle + \sum_{i=2}^{n_{\rm f}} d_i^+ | x e_i^+ \rangle + d_1^- | x e_1^- \rangle + \sum_{i=2}^{n_{\rm f}} d_i^- | x e_i^- \rangle. \quad (5.4)$$

The isel flag selects specific combinations of the singlet and non-singlet components in (5.4). In structure function calculations these appear as terms in singlet/non-singlet expansions where each term is convoluted with its own coefficient function.

A weighted gluon is returned when isel = 8. This is useful since a singlet convolution $C_s \otimes d_1^+|e_1^+\rangle$ is usually accompanied by a gluon convolution $C_g \otimes d_1^+|g\rangle$.³⁹

The components in (5.4) are defined in terms of the *active* quarks participating in the QCD evolution. For iset = 9 also *intrinsic* heavy flavours are included in c, that is,

$$|9\rangle = \sum_{i=1}^{6} \left(c_i |xq_i\rangle + c_{-i} |x\bar{q}_i\rangle \right) = |1\rangle + \sum_{i=n_s+1}^{6} \left(c_i |xq_i\rangle + c_{-i} |x\bar{q}_i\rangle \right).$$

There are also routines that return the value of a pdf at a given grid point (ix,iq). They have the same argument list as their interpolation equivalents, except that x and qmu2 must be replaced by the grid indices ix and iq, as shown below.

These routines are of course faster since no interpolation is required. They have the additional feature that a negative iq will return the pdfs at the flavour thresholds for $n_{\rm f}=(3,4,5)$, instead of the QCDNUM default $n_{\rm f}=(4,5,6)$. This gives access to the threshold discontinuities as is shown below for a pdf at $\mu_{\rm c}^2$.

For
$$F_2$$
 (see Appendix E),
$$\begin{cases} F_2^{(\text{LO})} &= |1\rangle \\ F_2^{(\text{NLO})} &= C_g^{(1)} \otimes |8\rangle + C_s^{(1)} \otimes |2\rangle + C_{\text{ns}}^{(1)} \otimes |3\rangle \\ F_2^{(\text{NNLO})} &= C_g^{(2)} \otimes |8\rangle + C_s^{(2)} \otimes |2\rangle + C_+^{(2)} \otimes |4\rangle + C_-^{(2)} \otimes |5\rangle. \end{cases}$$

39

```
delta_f = fvalij(iset,id,ix,iqc,ichk) - fvalij(iset,id,ix,-iqc,ichk)
```

Note that a routine like bvalij is very fast because it simply transfers a value stored in the internal memory. The CPU time is thus spent in computing a memory address and checking the argument list of the call. Setting ichk = -1 switches-off part of the checking so that you can optimise calls in a loop, as in the example below.

```
pdf(1) = bvalij( iset, id, ix(1), iq(1), 1 ) !check arguments
do i = 2,n
  pdf(i) = bvalij( iset, id, ix(i), iq(i), -1 ) !no check
enddo
```

For bvalij this gives about a factor of two in speed but the gain is much less for the other routines where most of the time is spent in computing weighted sums of pdfs.

5.11 Lists, Tables and Plots

Instead of calling an interpolation routine in a loop over x and μ^2 , you can gain speed by passing to QCDNUM a list of these points so that the program can optimise the loop internally. Here are two fast routines to generate a list or a table of interpolated pdfs.

```
call FFLIST ( iset, c, isel, x, q, *f, n, ichk )
```

Generate a $x-\mu^2$ list of interpolated pdfs.

iset Pdf set identifier [1-24].

c Input array, dimensioned to c(-6:6) in the calling routine, filled with the coefficients of a linear combination of (anti)quarks. The indexing is given in (5.2). Note that the value of c(0) is ignored.

isel Selection flag [0-9,12+i], as is described for the routine sumfxq above.

x, q List of interpolation points, dimensioned to at least n in the calling routine.

f Output array of pdf values, dimensioned to at least n in the calling routine.

n Number of items in x, q and f.

ichk If non-zero, QCDNUM insists that all x-q points are within the grid boundaries or cuts. If zero, a null value is returned for pdfs outside the boundaries.

```
call FFTABL ( iset, c, isel, x, nx, q, nq, *table, n, ichk )
```

Generate a pdf table in x and μ^2 . The parameters are as for fflist, except,

- x, nx Input array, dimensioned to at least x(nx) in the calling routine, and filled with nx values of x in strictly ascending order (no equal values allowed).
- q, nq As above, but now for the μ^2 variable.

table Output table of pdfs, dimensioned to table(n,m) in the calling routine with the second dimension set to $m \ge nq$.

n First dimension $n \ge nx$ of table as declared in the calling routine.

This routine is very fast since it scales with the sum instead of the product of nx and nq.

C++ As mentioned in Section 5.1 the table is stored in a one-dimensional array by the C++ wrapper. To access the table it is best to use the pointer function kij below.

```
inline int kij(int i, int j, int n) { return i-1 + n*(j-1); }
int iset = 1, isel = 1, n = 30, m = 15;
double c[13], x[n], q[m], table[n*m];
QCDNUM::fftabl(iset,c,isel,x,n,q,m,table,n,1);
double tij = table[ kij(i,j,n) ];
```

```
call FFPLOT ('filename', fun, m, zmi, zma, n, 'comment')
```

Generate an ASCII file to be read by a plotting program like GNUPLOT [29].

filename Name of the output file.

fun Input function (see below), declared external in the calling routine.

Number of functions $f_i(z)$ to store on the file [1-50].

zmi, zma Range of the z-coordinate.

n Number of z-point samples [2-500]. By default the sampling is linear; set n

negative for a logarithmic sampling.

comment Optional comment line written on the file. Leave it empty if you do not

want to write a comment line.

The input function should return $f_i(z)$ for i = 1, ..., m and must be coded as follows.

```
double precision function fun( i, z, first )
implicit double precision(a-h,o-z)
logical first
if(first) .. initialise the function, if necessary
if(i.eq.1) fun = fun1(z)
if(i.eq.2) fun = fun2(z) etc.
```

```
C++ The C++ prototype is double fun ( int* i, double* z, bool* first )
```

On the file is written a table with n rows and m+1 columns. The variable z listed in the first column and the functions $f_i(z)$ in the remaining m columns (E13.5 format).

```
call FIPLOT ('filename', fun, m, zval, n, 'comment')
```

As ffplot but the n sample points are now entered via the array zval. In case you set n negative, the routine ignores the input array and assumes zval(i) = dble(i).

5.12 Spline Check

When QCDNUM runs in the quadratic interpolation mode, the routines evolfg and extpdf determine the deviation of quadratic versus linear interpolation in-between the x-grid points, as is described in Section 3.4. This is done for all pdfs at a few values of μ^2 . If the largest deviation exceeds the value of elim (set by a call to setval) an error condition is raised with the message that one or more splines may oscillate.

The reason for such a large deviation could be the following:

- 1. The pdf itself has a strong non-linear variation (x-grid may not be dense enough);
- 2. Discontinuous or otherwise badly behaved pdf input;
- 3. Spline oscillation in the (backward) evolution of a pdf.

In case you get complaints from evolfg or extpdf, the first thing to do is to suppress the error message—and program stop—by setting $elim \leq 0$ in a call to setval. The routines below can then be used to investigate the location and cause of the problem.⁴⁰

```
epsi = SPLCHK ( iset, id, iq )
```

Returns for a basis pdf at a given μ^2 grid-point the maximum deviation between a linear interpolation and the spline interpolation used by QCDNUM (linear or quadratic).

iset Pdf set identifier [1-24].

id Identifier of a basis pdf $|e^{\pm}\rangle$, indexed according to (5.3).

iq Index of a μ^2 grid point.

The value of epsi should be small (like 0.05, say) for quadratic interpolation. Otherwise there may be a spline oscillation at iq, to be investigated with fsplne below.

```
pdf = FSPLNE ( iset, id, x, iq )
```

Spline interpolation of a basis pdf in x, at the grid point iq. This function is provided as a diagnostic tool to investigate quadratic spline oscillations, if any, which may not be visible in the local polynomial interpolation used by bvalxq. For instance the plot shown in Figure 4 of Section 3.5 is made with fsplne.

6 Program Steering with Datacards

It is possible to steer QCDNUM via a datacard input file. A keycard in such a file consists of a keyword followed by a parameter list. Such a card will, upon reading, cause a call to the corresponding QCDNUM routine. As an example we show here a datacard file that steers the example program given in Section 4.2 (the syntax will be described later).

⁴⁰Note that you do not need fsplne or splchk to *detect* spline oscillations, since that is done automatically by evolfg and extpdf.

```
' SETLUN 6 ' '
' GXMAKE 3 100 1 1.D-4 ' '
' GQMAKE 60 2 2. 1.D4 ' '
' FILLWT 1 ' '
' SETORD 3 ' '
' SETALF 0.364 2. ' '
' SETCBT 0 3. 25. 1.D11 '
```

Note that each card is read as a character string and should be embedded in single quotes and that the parameter lists can be given in free format. The corresponding calls in the example program can now be replaced by a call to qcards:

```
external mycards !to be explained later
...
call qcinit( 6, ' ' )
call qcards( mycards, 'example.dcards', 0 )
ityp = 1
q0 = 3.5
call evolfg( ityp, func, def, iqfrmq(q0), eps )
..
```

In the above we have used so-called predefined keycards that can execute QCDNUM routines prior to a pdf evolution; the call to evolfg (and beyond) is, in this example, made in the FORTRAN code itself. We will show in Section 6.3 how to define user keycards that can drive a call to evolfg or to any other routine.

C++

At present there is no C++ interface to the datacard routines described in this section. A solution is to package all datacard handling in a FORTRAN subroutine and interface that routine to C++.

6.1 Datacard File

The input datacard file is a normal text file. Datacards in this file are strings of up to 120 characters long, embedded in single quotes (' . . . '). Blank or unquoted records are allowed on the file as long as the first word of that record is not a valid keyword.

List-directed (*i.e.* free-format) read from a string is not permitted in FORTRAN77 [30],⁴¹ so that the format of each word in a datacard is classified by QCDNUM as logical (L), integer (I), floating point (F), exponential (E or D) or character (A).⁴² After classification the words in a datacard are transferred to memory by a formatted read.

Note that cards are only processed if the first word is a keyword recognised by QCDNUM. Thus it is easy to add comment (or blank) lines to the file, or to comment-out data-cards by inserting some non-blank characters in front of the keyword.

⁴¹Most systems allow for a list-directed read from strings but this is not guaranteed to be portable.

⁴²The string formatter recognises any number in I, F, E or D format. Anything else is classified as a character word (A), except that a single uppercase T or F is classified as logical true or false.

```
'This line is a comment but the next line is a keycard 'SETORD 3'
'And the keycard below is commented out'
'C-- SETORD 2'
```

Inline comments can be put after the closing quote.

```
' SETLUN 6 ' This is an inline comment
```

If a parameter is a string with embedded blanks, you must put it in double quotes ('').

```
' MYCARD Paul Dirac ''Paul Dirac''
```

This card has three parameters: first name (A4), last name (A5) and full name (A10).

In the examples above we have put the keywords in upper case for readability but note that QCDNUM is case-insensitive so that it does not matter if character strings are put in upper, lower, or mixed case. File names are an exception to this since they are passed directly to the operating system which usually is case-sensitive.

A datacard file is processed by a call to qcards.

```
call QCARDS ( mycards, 'filename', iprint )
```

Process all known keycards in a text file.

mycards Subroutine, declared external in the calling routine, that is called when a

user-defined card is encountered, see Section 6.3 for how it should be coded.

Must be supplied as a dummy routine when there are no user cards.

filename Input file name.

iprint No listing (0), listing and processing (1) or listing without processing (-1).

The latter is useful to get in a dummy run a clean datacard listing from which you can check the correct QCDNUM formatting of the parameters. If

you set iprint to ± 2 also the format descriptor will be printed.

A fatal error message is issued if the datacard file does not exist, cannot be read or if there is a problem with decoding a keycard. On exit, the input file will be closed.

6.2 Predefined Keycards

In Table 3 we list the QCDNUM predefined keycards. Optional parameters are given in brackets. Most keycards have exactly the same parameter lists as the subroutine calls given in Table 2 but some of them have a slightly different syntax as is given below.

SETLUN lun <filename>: When lun is set to 6 you can omit the filename parameter; in all other cases a filename must be given.

Table 3 – QCDNUM predefined keycards.

SETLUN	lun	<filename></filename>			
		/III Elique			
SETVAL	${ t chopt}$	dval			
SETINT	chopt	ival			
GXMAKE	iosp	nx	nxlim	xmi(1)	xmi(nxlim)
GQMAKE		nq	nqlim	qsq(1)	qsq(nqlim)
FILLWT	itype	<filename></filename>			
SETORD	iord				
SETALF	alfs	r2			
SETCBT	nfix	q2c	q2b	q2t	
MIXFNS	nfix	r2c	r2b	r2t	
SETABR	ar	br			
SETCUT	xmi	q2mi	q2ma		
QCSTOP					

GXMAKE iosp nx nxlim xmi(1) ... xmi(nxlim): Here the order of the parameters differs from that in the FORTRAN call: we first put the spline order, followed by the requested number of grid points, the number of sub-grids, and then the subgrid limits.

```
'GXMAKE 3 100 1 1.D-4 ' single 100 pt x-grid
'GXMAKE 3 100 3 1.D-4 0.1 0.7 ' 3-fold 100 pt x-grid
'GXMAKE 3 100 2 1.D-4 0.1 0.7 ' 2-fold without xmi = 0.7
```

The point density increases by a factor of two for each subgrid generated.

GQMAKE nq nqlim qsq(1) ... qsq(nqlim): Also here the order of the parameters differs from that in the FORTRAN call. You can inject up to 20 points into the grid (including the end points). The point densities are set equal for all regions in μ^2 .

```
' GQMAKE 60 2 2. 1.D4 ' 60 points in range 2-10^4 GeV2 ' GQMAKE 60 4 2. 3. 25. 1.D4 ' idem with q2c and q2b inserted
```

FILLWT itype <filename>: If a filename is given, an up-to-date disk file of weights is maintained, if not, the weights are calculated from scratch.

```
'FILLWT 1 ../weights/unpolarised.wt '
'FILLWT 2 ../weights/polarised.wt '
```

SETCBT nfix q2c q2b q2t: Here you have to specify the threshold values, and not the grid indices as in the FORTRAN call to setcbt. All three thresholds must be given.

QCSTOP: An input file may contain other data in addition to the keycards (how to read these data is up to you). In this case you can put a QCSTOP card to terminate the search for keycards, which would otherwise continue until an end-of-file is reached.

6.3 User-defined Keycards

Suppose that we want, via a datacard, to run from a scale of $\mu_0^2 = 3.5 \text{ GeV}^2$ an evolution of un-polarised pdfs (itype = 1).

```
' EVOLFG 3.5 1 '
```

Since this card is non-standard we have to do two things to make it active: (i) add EVOLFG to the list of known keys by a call to qcbook and (ii) provide the FORTRAN code to be executed when the key is encountered in a datacard file.

```
call QCBOOK ( 'action', 'key' )
```

Add or delete keys from the list of known keys. 43

'action' First character must be set to 'A' (add) or 'D' (delete). You can also set it to 'L' to get a list of known keys on the QCDNUM output stream.

'key' Name of the key. A new key should not be longer than 7 characters and not be present in the list of known keys.

By default, mky0 = 50 key-names can be held in memory of which 13 are already taken by the predefined keys. The value of mky0 can be changed in qcdnum.inc, if necessary. Thus, in our example program, we have first to make a call to qcbook.

```
call qcbook( 'Add', 'EVOLFG' )
```

The routine qcards will now recognise EVOLFG as a user-defined keyword and will call the subroutine mycards to process the card. This subroutine should be coded as follows.

```
subroutine mycards ( key, nk, pars, np, fmt, nf, ierr )
implicit double precision (a-h,o-z)
character*(*) key, pars, fmt
..
```

The first 6 arguments are presented to you by QCDNUM, the ierr flag you set yourself.

key Character string containing the name of the key in upper case. nk Number of characters in key. Always $1 \le nk \le 7$.

⁴³Note that you can also delete predefined keys. This is useful when you want to inhibit a keycard-driven call or want to replace a key by deleting it and then add it again (it comes back as a user-defined key). In this way you can tailor the predefined keys to your needs, if necessary.

Character string containing the parameter list.

Number of characters in pars (0 = no parameters for this key).

Character string with the FORTRAN format descriptor of pars.

Number of characters in fmt (0 = no format string).

ierr Should be set, on exit, to 0 if all OK, to 1 if the parameters cannot be read, to 2 if the card cannot be processed, and to 3 if the key is unknown.

The pars character string acts as an internal file from which the parameters can be read in the format given by fmt. This is illustrated in the following code which processes the EVOLFG keycard (not all error handling shown).

```
subroutine mycards ( key, nk, pars, np, fmt, nf, ierr )
implicit double precision (a-h,o-z)
character*(*) key, pars, fmt
external func
common /pass/ def(-6:6,12)

if(key .eq. 'EVOLFG') then
    read(unit=pars,fmt=fmt,err=100,end=100) q0, itype
    call evolfg(itype,func,def,iqfrmq(q0),eps)
else
    ierr = 3
endif
return
100 ierr = 1
return
end
```

It is easy to handle optional parameters by checking on read errors. In the modified if-block below we also process EVOLFG with only qO as input, and itype = 1 as default.

```
if(key .eq. 'EVOLFG') then
    read(unit=pars,fmt=fmt,err=10,end=10)    q0, itype
    call evolfg(itype,func,def,iqfrmq(q0),eps)
    return

10    read(unit=pars,fmt=fmt,err=100,end=100)    q0
    call evolfg( 1 ,func,def,iqfrmq(q0),eps)
    else
    ierr = 3
    endif
```

Note that user keys are strictly local in the sense that they can only be defined in the program that calls qcards to read the datacard file. It thus does not make sense to define keys in an add-on package: packages should provide subroutines and not keys. Of course you can easily define your own key that calls a package (or any other) routine.

7 Tools

In this section we describe a large set of tools that can be used to evolve a set of pdfs, or to compute convolution integrals needed for the calculation of structure functions or parton luminosities. With these tools you can write QCDNUM add-on packages that will extend the functionality of the program. For instance, the ZMSTF and HQSTF structure function packages are entirely based on the QCDNUM toolbox.

C++ In QCDNUM18 there are C++ wrappers available for all toolbox routines.

All toolbox routines operate on a workspace which is nothing else than a sufficiently large linear array that you declare in your application program. This workspace is partitioned into sets of tables after which you can call toolbox routines that act on these tables in various ways. It is important to note that the toolbox inherits from the QCDNUM main program the x- μ^2 grid and also the evolution parameters like the perturbative order, flavour thresholds etc., as set by the routines described in Section 5.7. Note also that, like in the main program, pdfs can only be accessed when they are evolved with the current set of parameters, see Section 5.10.

In the next section we show how to partition the toolbox workspace, followed by a description of the table indexing (Section 7.2), weight filling routines (7.3), combined weights (7.4), coupled DGLAP evolution (7.5), pdf access (7.6), pdf transformations (7.7), convolution tools (7.9) and the fast convolution engine (7.10).

All toolbox routines are listed in Table 4.

Table 4 - Routines in the QCDNUM toolbox.

Subroutine or function	Description					
Workspace						
MAKETAB (w, nw, itypes, np, new, *iset, *nwu)	Create tables					
SETPARW (w, iset, upars, n)	Store user information					
GETPARW (w, iset, *upars, n)	Read user information					
DUMPTAB (w, iset, lun, 'filename', 'key')	Dump to disk					
READTAB (w, nw,, *iset, *nwu, *ierr)	Read from disk					
Identifiers						
IDSPFUN ('pij', iord, iset)	Internal weight table					
IPDFTAB (iset, id)	Internal pdf table					
Weights						
MAKEWTA (w, id, afun, achi)	Regular piece $A(x)$					
MAKEWTB (w, id, bfun, achi, nodelta)	Singular piece $[B(x)]_+$					
MAKEWRS (w, id, rfun, sfun, achi, nodelta)	Product $R(x)[S(x)]_+$					
MAKEWTD (w, id, dfun, achi)	δ -Function $D(x)\delta(1-x)$					
MAKEWTX (w, id)	Weights for $x[f_a \otimes f_b]$					
Combined weights						
SCALEWT (w, c, id)	Scale weight table					
COPYWGT (w, id1, id2, iadd)	Copy weight table					
WCROSSW (w, ida, idb, idc, iadd)	Convolution of weights					

continued on next page

WTIMESF (w, fun, id1, id2, iadd)	Multiply by $f(\mu^2, n_{\rm f})$					
Evolution	1 0 0 0 (1) 1/					
EVFILLA (w, id, func)	Fill table of coefficients α					
EVGETAA (w, id, iq, *nf, *ithresh)	Get coefficients					
EVDGLAP (w, iw, ia, if,, *nf, *e)	Coupled evolution					
Access to pdfs						
EVPDFIJ (w, id, ix, iq, ichk)	Pdf at a grid point					
EVPLIST (w, id, x, qmu2, *pdf, n, ichk)	List of interpolated pdfs					
EVTABLE (w, id, x, nx, q, nq, *table, ichk)	Table of interpolated pdfs					
EVPCOPY (w, id, def, n, iset)	Copy to internal memory					
Evolution parameters						
CPYPARW (w, *array, n, iset)	Copy parameter list					
KEYPARW (w, iset)	Get parameter key					
KEYGRPW (w, iset, igroup)	Selective parameter key					
USEPARW (w, iset)	Activate parameters					
Transformations						
EFROMQQ (qvec, *evec, nf)	Transform from q, \bar{q} to e^{\pm}					
QQFROME (evec, *qvec, nf)	Transform from e^{\pm} to q, \bar{q}					
Access scope						
IDSCOPE (w, idf)	Restrict pdf access					
Convolution						
FCROSSK (w, idw, idum, idf, ix, iq)	Convolution $x[f \otimes K]$					
FCROSSF (w, idw, idum, ida, idb, ix, iq)	Convolution $x[f_a \otimes f_b]$					
STFUNXQ (stfun, x, qmu2, stf, n, ichk)	Interpolation					
Fast convolution						
FASTINI (x, qmu2, n, ichk)	Pass a list of x and μ^2					
FASTCLR (ibuf)	Clear buffer					
FASTINP (w, idf, coef, ibuf, iadd)	Store a pdf in a buffer					
FASTEPM (idum, idf, ibuf)	Store $ g, e^{\pm}\rangle$ in a buffer					
FASTSNS (iset, def, isel, ibuf)	Store singlet or non-singlet					
FASTSUM (iset, coef, ibuf)	Store weighted sum of $ e^{\pm}\rangle$					
FASTFXK (w, idw, ibuf1, ibuf2)	Convolution $x[f \otimes K](x)$					
FASTFXF (w, idw, ibuf1, ibuf2, ibuf3)	Convolution $x[f_a \otimes f_b](x)$					
FASTKIN (ibuf, fun)	Scale by a kinematic factor					
FASTCPY (ibuf1, ibuf2, iadd)	Copy or accumulate result					
FASTFXQ (ibuf, *f, n) Output arguments are prefixed with an actoricle (*)	Interpolate final result					

Output arguments are prefixed with an asterisk (*).

7.1 Toolbox Workspace

The first step in using the toolbox is to declare a large double precision array w(nw) in your application program.⁴⁴ This toolbox workspace must be partitioned into one or more sets of tables that, depending on your application, will contain evolution or

 $^{^{44}}$ How large should w be? Just put nw = 1 and get the answer from the maketab error message.

convolution weights, collections of pdfs, and tables of perturbative expansion coefficients.

All tables in the workspace depend on the $x-\mu^2$ grid as defined by upstream calls to gxmake and gqmake; a downstream re-definition of the grid invalidates all your toolbox workspaces and makes them inaccessible (see Section 7.11 for more on toolbox errors).

Internally these tables have up to 6 dimensions but you are exposed to only a few of these, depending on what the table is used for. This leads to six different type of table:

itype = 1 Weight tables that depend only on x. Identifiers run from 101–199;

itype = 2 Weight tables that depend on x and n_f . Identifiers run from 201–299;

itype = 3 Weight tables that depend on x and μ^2 . Identifiers run from 301–399;

itype = 4 Weight tables that depend on x, μ^2 and n_f . Identifiers run from 401–499;

itype = 5 Pdf tables that depend on x and μ^2 . Identifiers run from 501-599;

itype = 6 Tables that depend on μ^2 only. Identifiers run from 601–699.

The $n_{\rm f}$ dependence of weight tables should not be confused with that of the pdfs. For pdfs it means that they are evolved with a certain number of active flavours that may, in the VFNS, depend on μ^2 . For the weight tables it means that $n_{\rm f}$ is a parameter of the convolution kernel so that there are four look-up tables, one for each $n_{\rm f}=3,4,5,6$.

Below we describe a routine (maketab) that creates a set of tables. Additional calls to maketab will create additional sets, numbered in sequence, up to a maximum of 30 sets. Organising tables into sets can much simplify your bookkeeping because the same table identifiers can be used in different sets, as is done internally in QCDNUM for the un-polarised (1), polarised (2) and time-like sets (3) where the gluon always has id = 0, the singlet id = 1, etc.

In the following we describe the routines that partition the toolbox workspace, store extra information into a set of tables, dump a set of tables to disk, and read them back.

```
call MAKETAB ( w, nw, itypes, np, new, *iset, *nwused )
```

Add a set of tables to a workspace w.

w Double precision array declared in the calling routine.

nw Dimension of w as declared in the calling routine.

itypes Integer array dimensioned to itypes(6) in the calling routine which contains in itypes(i) the number of tables (≤ 99) of type i to be generated. When itypes(i) = 0 then no tables of type i will be generated.

np Number of words reserved to store user information (see setparw below).

new If new = 0 the set is added to those already present in the workspace and the iset identifier is incremented up to a maximum of iset ≤ mst0 = 30 sets. 45 If new = 1, then the existing sets, if any, are overwritten by the new set.

⁴⁵For more than 30 sets please update the parameter mst0 in qcdnum.inc, and recompile QCDNUM.

Gives, on exit, the identifier that QCDNUM has assigned to the set of tables.

Gives, on exit, the total number of words used in the workspace. If nwused is negative, then the workspace is not sufficiently large (fatal error) and should be re-dimensioned in the calling routine to at least -nwused.

Note that maketab initialises all tables in the set to zero.⁴⁶

By default, the weight tables (type 1-4) can be used in both the evolution (evdglap) and convolution routines (fcrossk, fcrossf, fastfxk, fastfxf). However, if your convolution kernels are not splitting functions, you can flag the tables as such by putting a negative number in itypes(i). Such type-i tables can then only be used in a convolution routine and not in evdglap (fatal error if you try) but have the advantage that they are much smaller. This can lead to considerable savings in space and filling time, in particular when the tables are type-3 or 4.

```
call SETPARW ( w, iset, upars, n )
```

Store extra information such as quark masses or other parameters that you want to dump to disk, along with the tables.⁴⁷

w Workspace, partitioned by a previous call to booktab.

iset Table set identifier.

upars Array, dimensioned to at least upars (n) in the calling routine. On entry the array must be filled with the extra information you want to store.

n Number of items to store, $n \le np$, where np is set in the call to maketab.

The user data can be retrieved by a call to getparw(w,iset,upars,n).

```
call DUMPTAB ( w, iset, lun, 'filename', 'key' )
```

Dump the table set iset to disk. Fatal error if iset does not exist. You can use the function nxtlun of Section 5.4 to find a free logical unit number. Apart from the tables, information is written about the QCDNUM version, the x- μ^2 grid definition and the current spline interpolation order. The key text string can be used to stamp the file with some identifier like a package name and version number. The dump is un-formatted so that the file cannot be exchanged across machines. Note that a disk file can contain only one set of tables so that different sets must be dumped on different files.

```
call READTAB ( w, nw, lun, 'fn', 'key', new, *iset, *nwu, *ierr )
```

Read a set of tables from disk into the workspace w(nw). Like in maketab, the input flag new controls the overwriting of existing tables. The parameter iset is, on exit, set to the identifier that QCDNUM has assigned to the set of tables read in. The total number

⁴⁶You can use also the routine scalewt (Section 7.4) to explicitly zero a table, if needed.

⁴⁷When you evolve a pdf set with evdglap (Section 7.5) the evolution parameters are automatically stored so that you do not have to do this explicitly by a call to setparw. See also Section 7.6.

of words used in the workspace is returned in nwu. You will get a fatal error message if w(nw) is not large enough to contain the tables or if the maximum number of table sets mst0 = 30 is exceeded. On exit, the error flag is set as follows (non-zero means that nothing has been read in so that it is up to you to take the appropriate action).

- O Set of tables successfully read in.
- 1 Read error or input file does not exist.
- 2 File written by another QCDNUM version.
- 3 Key mismatch.
- 4 Incompatible $x-\mu^2$ grid definition.

QCDNUM insists that the key written on the file matches the key entered as an argument to readtab.⁴⁸ Thus if, for instance, the key is set to a package name and version number then the user of the package cannot read obsolete files written by earlier versions, or read files written by another package. If you don't want to use keys, just enter an empty string as a key in the calls to dumptab and readtab.

Note that the table set identifier iset is dynamically allocated so that it usually is not preserved in a write-read sequence: if you dumped iset = 2 to disk, it may very well be read back as iset = 5. Please be aware of this when addressing tables in your toolbox workspace (see the next section).

7.2 Table Identifiers

A table in the workspace w is characterised by three numbers:

iset The table set number assigned by QCDNUM in the call to maketab or readtab;
itype The index 1-6 that differentiates between the various type of table;
n The table number in the range 1-99.

These numbers serve to build a so-called *global* identifier that uniquely identifies a table.

$$id_global = 1000*iset + 100*itype + n.$$
 (7.1)

Thus id = 3206 refers to the 6^{th} type-2 table of set 3 in the toolbox workspace.

If you store tables on disk please note that the iset identifier is dynamically allocated so that only the last three digits of a global identifier are guaranteed to be preserved between disk dump and a disk read. You have thus to construct, after a read, the global identifier with (7.1) using the value of iset returned by readtab, and not use the table identifier as it was before the dump.

Most toolbox routines allow you to use tables in the internal memory, in addition to those in the toolbox workspace. To address the internal tables, QCDNUM provides two functions that return the identifiers of weight tables (idspfun) and pdf tables (ipdftab).⁴⁹

⁴⁸Note that the key matching is case insensitive and that leading and trailing blanks are ignored.

⁴⁹The internal α_s tables can be accessed by the function altabn described in Section 5.8.

```
id = IDSPFUN ( 'pij', iord, iset )
```

Returns the global identifier of a weight table in internal memory (negative number).

'pij' Name of the splitting function. Valid input strings are

PQQ, PQG, PGQ, PPL, PMI, PVA, AGQ, AGG, AQQ, AHQ, AHG

iord Select LO (1), NLO (2) or NNLO (3).

iset Select un-polarised (1), polarised (2) or fragmentation function (3).

Returns the global identifier of a pdf table in internal memory (negative number).

iset Pdf set identifier as is defined in Section 5.2 [1–24].

id Pdf identifier of an $|e^{\pm}\rangle$ basis function, indexed according to (5.3) [0–98].

Both functions return -(1000*iset+100*itype+n) with iset, itype and n the internal table identifiers (which are hidden from you). The minus sign tells QCDNUM to address the internal memory instead of the toolbox workspace. Upon error, the functions return an error code that is understood by downstream toolbox routines which will then generate the appropriate error message.

7.3 Weight Tables

To calculate convolution integrals, the convolution kernels must first be turned into weight tables. Note that the kernels presented to QCDNUM must be defined by convolution with a parton number density f, and not with a momentum density xf.⁵⁰

The convolution kernels may contain singularities ('plus' prescriptions), as is described in Appendix B. To deal with such singularities, we formally decompose a kernel into a regular part (A), a singular part (B), a product (RS) and a delta function

$$C(x) = A(x) + [B(x)]_{+} + R(x)[S(x)]_{+} + D(x)\delta(1-x).$$
(7.2)

For each term in (7.2) there exists a separate filling routine that will add its contribution to the weight table of C.

The generalised mass (GM) form of a convolution integral is given by (3.23) in Section 3.3:

$$\mathcal{F}(x,Q^2) = x \int_{\chi}^{1} \frac{dz}{z} f(z,\mu^2) C\left(\frac{\chi}{z},\mu^2,Q^2,m_h^2\right),$$
 (7.3)

⁵⁰The weight table conversion from number to momentum density is done internally in QCDNUM.

where $\chi = ax$ is a so-called rescaling variable and the factor $a \ge 1$ is a function of Q^2 . In the code examples below we will assume, for definiteness, that the relation between μ^2 and Q^2 is given by

$$Q^2 = \alpha \mu^2 + \beta \tag{7.4}$$

and that the rescaling variable is defined by

$$\chi = ax = \left(1 + \frac{4m_h^2}{Q^2}\right)x. \tag{7.5}$$

To the table generating routines must be supplied a function that defines the rescaling variable (achi), together with one or more functions that provide the interface to the convolution kernel (cfun). These functions must be coded as follows.

```
double precision function achi(qmu2)
implicit double precision (a-h,o-z)
common /pass/ alfa, beta, hmass, ....
Q2 = alfa*qmu2 + beta
achi = 1.D0 + 4.D0*hmass*hmass/Q2
return
end
```

```
double precision function cfun(chiz,qmu2,nf)
implicit double precision (a-h,o-z)
common /pass/ alfa, beta, hmass, ....
Q2 = alfa*qmu2 + beta
cfun = some_function_of(chiz,qmu2,Q2,nf,hmass,...) !chiz = chi/z
return
end
```

Although one should take out as many μ^2 -dependent factors (e.g. powers of α_s) as possible from the convolution kernel, it is clear from the above that quark mass parameters and the relation between μ^2 and Q^2 may enter via the rescaling variable χ and that such a dependence can never be factored out of the convolution integral. Therefore the weight tables of the GM schemes will, in general, depend on x and μ^2 and must be stored in type-3 or 4 tables. The code below, for example, fills a type-4 table with the regular part of a convolution kernel.

```
external cfun, achi call MakeWtA(w,6402,cfun,achi) !fill table 402 of set 6
```

When you work in a mass-less scheme where $\chi = x$ and a = 1 then (7.3) reduces to the familiar Mellin form $\mathcal{F} = x[f \otimes C]$. In this case you may code for the achi function

```
double precision function achi(qmu2)
implicit double precision (a-h,o-z)
achi = 1.D0
return
end
```

Here your weight table will most likely depend on x only, or on x and n_f , and can thus be stored in type-1 or 2 tables.

QCDNUM calculates by Gauss quadrature (CERNLIB routine D103) the integrals that define the weights. In case the default accuracy of $\epsilon = 10^{-7}$ cannot be reached (fatal error message), this limit can be raised by a call to setval('epsg',value). Note, however, that problems with the Gauss integration will most likely be caused by problems with the integrand—such as near-singular behaviour somewhere in the integration domain—and that this cannot be cured by relaxing the required accuracy.

We emphasise once more that convolution integrals found in the literature must, if necessary, be brought into the general form (7.3) by modifying the published convolution kernel. An example of such a modification can be found in Appendix F.1.

```
call MAKEWTA ( w, id, afun, achi )
```

Calculate the weights for the regular contribution A(x) to a convolution kernel and add these to table id in the workspace w.

- w workspace declared in the calling routine and previously partitioned by maketab.
- id Weight table identifier, given in the global format (7.1).
- afun Name of a function (see above) that returns the regular piece of the convolution kernel. Should be declared external in the calling routine.
- achi Name of a function (see above), declared external in the calling routine, that returns the value a of the rescaling variable $\chi = ax$. QCDNUM insists that always achi ≥ 1 ; you will get a fatal error if not.

```
call MAKEWTB ( w, id, bfun, achi, nodelta )
```

Calculate the weights for the singular contribution $[B(x)]_+$ to a convolution kernel and add these to a table in the workspace w. The arguments and the coding of **bfun** and **achi** are as for **makewta**. Thus, if a kernel has both a regular and a singular part, then do

```
call MakeWtA(w,1201,afun,achi) !put regular part in id = 1201
call MakeWtB(w,1201,bfun,achi,0) !add singular part to id = 1201
```

It is seen from Appendix B, equation (B.3), that a '+' prescription generates a $\delta(1-x)$ contribution. By default, makewtb includes this contribution, unless you set nodelta = 1. In that case the $\delta(1-x)$ contribution is not calculated and must be entered, perhaps combined with other such contributions, via a call to makewtd, see below.

```
call MAKEWRS ( w, id, rfun, sfun, achi, nodelta )
```

Calculate the weights for the product contribution $R(x)[S(x)]_+$ to a convolution kernel and add these to a table in the workspace w. The arguments and the coding of rfun, sfun and achi are as for makewta.

Calculate the weights for the $\delta(1-x)$ contribution to a convolution kernel and add these to a table in the workspace w. The delta function is multiplied by the function dfun. The arguments and the coding of dfun and achi is as for makewta.

Calculate the weights (3.20) for the convolution $x[f_a \otimes f_b](x)$.

- w workspace declared in the calling routine and previously partitioned by maketab.
- Table identifier. Because the weight table depends only on x, it can be stored in a type-1 table, but equally well in types-2, 3 or 4, if desired.

7.4 Combined Weights

Sometimes it is necessary to combine weight tables into another weight table. An example of this is the coefficient function

$$C_{2,+}^{(2,1)} = C_{2,q}^{(0)} \otimes P_{+}^{(1)} + C_{2,+}^{(1)} \otimes P_{qq}^{(0)} - \beta_0 C_{2,+}^{(1)}$$

$$(7.6)$$

taken from expression (E.7) in Appendix E. Here we see convolutions of coefficient and splitting functions, multiplication by a β -function, and, of course, the addition or subtraction of terms. Below we will describe a set of routines that allow you to calculate expressions like (7.6) and store the result in a combined weight table.

One feature of these routines is that you can combine tables of different type, provided that this does not lead to a loss of information. Thus you can copy a type-1 table to a type-3 table but not the other way around. All routines check that you use a correct combination of types, and issue a fatal error condition if this is not the case.

Multiply the contents of a weight table id by a constant c. Obviously, id cannot refer to a table in internal memory. You can use this routine to explicitly set a table to zero.

Copy the contents of table id1 to id2. You can copy weight tables (type-1-4), but also pdf tables (type-5) or tables with expansion coefficients (type-6).

- w Workspace declared in the calling routine.
- id1 Input weight table identifier, given in the global format (7.1).
- Output table identifier with $id2 \neq id1$. The output table type may be different from the input table type, as is described above.

iadd If set to 0 copy id1 to id2, if set to +1 (-1) add (subtract) id1 to (from) id2.

You can use this routine to import a weight table from internal memory into the toolbox workspace by setting id1 to an identifier that is generated by idspfun. Internal splitting function tables are type-1 or type-2 (you can see this from the second but last digit of the idspfun identifier) so that you can avoid errors simply by always importing to type-2. Importing pdf tables from internal memory does not make sense and is not allowed.

This routine generates a weight table for the convolution of two kernels K_a and K_b . The weight table is calculated with (3.18) from two input tables \mathbf{W}_a and \mathbf{W}_b .

- w Workspace declared in the calling routine.
- ida Table identifier containing the weights of kernel K_a .
- idb As above for the weights of kernel K_b .
- idc Output table identifier. Cannot be set equal to ida or idb.
- iadd If set to 0 store the result of the convolution in idc, if set to +1 (-1) add (subtract) the result to (from) the contents of idc.

Both ida and idb can refer to splitting functions in internal memory, with identifiers constructed with idspfun. The table types of ida and idb may be different, but the type of idc must be such that it can contain either input table. Thus if ida is type-2 (x, n_f) and idb is type-3 (x, μ^2) , then idc must be type-4 (x, μ^2, n_f) .

Multiply a weight table by a function of μ^2 and n_f and store the result in another table.

- w Workspace declared in the calling routine.
- fun Double precision function fun(iq,nf) declared external in the calling routine.
- id1 Input identifier of a weight table in the workspace w, or in internal memory.
- id2 Identifier of the output table. It is allowed to have id1 = id2 (in-place modification of a table), unless id1 is an internal splitting function table. The table type of id2 must be such that no information is lost, fatal error otherwise.
- iadd Store the result in id2 in case iadd = 0 or add (subtract) the result to (from) id2 in case iadd = +1 (-1).

The routine loops over iq and nf and calls fun(iq,nf) with the following argument ranges, depending on the *output* table type:

$_{\mathrm{type}}$	variables	iq range	nf range
1	x	1-1	3–3
2	x, n_{f}	1-1	3–6
3	x, μ^2	1-nq	3–3
4	x, μ^2, n_{f}	1-nq	3–6

QCDNUM checks that the output table type matches the μ^2 and n_f dependence of both id1 and fun, and will produce a fatal error if this is not the case.

As an example, we give below the code to construct a table corresponding to the combination of convolution kernels (7.6).

```
external beta0 !beta function
...
call WcrossW ( w, idC2Q0, idSpfun('PPL',2,1), idC2P21, 0 )
call WcrossW ( w, idC2P1, idSpfun('PQQ',1,1), idC2P21, +1 )
call WtimesF ( w, beta0 , idC2P1 , idC2P21, -1 )
```

7.5 Coupled DGLAP Evolution

In this section we describe routines to solve n coupled evolution equations

$$\frac{\partial f_i(x,\mu^2)}{\partial \ln \mu^2} = \sum_{j=1}^n \left[P_{ij} \otimes f_j \right](x,\mu^2).$$

The routines operate on a toolbox workspace w that should contain the $n \times n$ weight tables, tables of expansion coefficients, and also the n pdf tables.

After partitioning the workspace (Section 7.1) and computing the weight tables (Section 7.3), look-up tables of perturbative expansion coefficients must be filled with the routine evfilla below. Such a look-up table (type-6) should contain one of the coefficients a_i versus μ^2 of the perturbative expansion

$$P_{ij} = a_0 P_{ij}^{(0)} + a_1 P_{ij}^{(1)} + a_2 P_{ij}^{(2)} + \cdots$$

Examples of expansion coefficients are powers α^n , α_s^m or products $\alpha^n \alpha_s^m$.

```
call EVFILLA ( w, id, func )
```

Fill a type-6 look-up table with a perturbative expansion coefficient.

w Toolbox workspace with at least one type-6 table.

id Type-6 table identifier, in the global format (7.1).

func User supplied function (see below), declared external in the calling routine.

The function func is called by evfilla in a loop over the μ^2 grid points iq, and should be coded as follows.

```
double precision function func(iq,nf,ithresh)
implicit double precision (a-h,o-z)
func = value_of_expansion_coefficient_at_iq
return
end
```

Passed to func are iq, the number of flavours nf, and a threshold indicator ithresh that is set to 0 if iq is not at a threshold, and to +1 (-1) if iq is at a threshold with the larger (smaller) number of flavours. Thus, at the charm threshold iqc the function is called twice, once with nf = 3 and ithresh = -1, and once with nf = 4 and ithresh = +1. To fill the tables with powers of $a_s(\mu^2)$, properly truncated, you can use the routine altabn that is described in Section 5.8.

QCDNUM cannot keep track of your coupling constant so that you must yourself update the tables when it changes (in a fit), when the flavour thresholds change, or when the relation between the renormalisation and the factorisation scale changes.

```
alfa = EVGETAA ( w, id, iq, *nf, *ithresh )
```

Returns the value of the expansion coefficient at the μ^2 grid point iq, as is stored in the look-up table id. Also returned are the value nf of the number of flavours at iq, and the threshold indicator ithresh as described above. By default QCDNUM always takes the larger number of flavors (4,5,6) at $(\mu_c^2,\mu_b^2,\mu_t^2)$ but you can force the routine to take the smaller number of flavours by prefixing iq with a minus sign, thus:

```
alfa = EVGETAA(w,id, iqc,iord,nf,ithresh) !nf = 4, ithresh = 1
alfa = EVGETAA(w,id,-iqc,iord,nf,ithresh) !nf = 3, ithresh = -1
```

Upon error (non-existing table, iq out of range, etc.) a null value is returned for alfa.

After filling the weight tables (Section 7.3) and the tables of expansion coefficients, a set of pdfs can be simultaneously evolved with the routine evdglap. This routine can only evolve with a fixed number of flavours so that in the VFNS you have to implement yourself the loop over the flavour thresholds, as will be explained later.

```
call EVDGLAP ( w, idw, ida, idf, !start, m, n, !iqlim, ,*nf, *epsi )
```

Coupled fixed-flavour *n*-fold DGLAP evolution of the pdfs f_i , i = 1, ..., n.

- w Toolbox workspace, previously filled with weights and expansion coefficients. The workspace should also contain the pdf tables to be evolved.
- Integer array that contains in idw(i,j,k) the weight table identifier of P_{ij} at order k. In the calling routine it must be dimensioned to idw(m,m,nk) with $m \ge n$. The third dimension nk should be at least as large as the maximum number of perturbative terms in the evdglap evolution (see below).
- As above, but now ida(i,j,k) contains the identifier of the look-up table of the expansion coefficient that multiplies P_{ij} at order k.
- idf Integer array, with in idf(i) the identifier of the pdf f_i to be evolved. The array must be dimensioned to at least n in the calling routine. It is required that all pdfs reside in the same table set (fatal error otherwise).⁵¹

⁵¹This is because the evolution parameters are stored as an attribute of a *set* and not of a table.

Double precision array that in the calling routine should be dimensioned to $\mathtt{start(m,nx)}$ with the second dimension \mathtt{nx} at least as large as the number of x-grid points. On entry, $\mathtt{start(i,j)}$ must be filled with the start value of $f_i(x_j)$. On exit, the array contains the pdfs at the end point of the evolution.

m First two dimensions of idw and ida and the first dimension of start, as declared in the calling routine.

n The number of pdfs to evolve simultaneously, $n \leq m$.

iqlim Integer array, declared iqlim(2) in the calling routine. On entry, iqlim(1) must be set to the start point of the evolution and iqlim(2) to the requested end point. If iqlim(2) ≥ iqlim(1) there is upward evolution, downward evolution otherwise. On exit, iqlim(2) is set to the actual endpoint of the evolution which QCDNUM puts at the next threshold, cut or grid boundary.

On exit, abs(nf) is set to the number of flavours used in the evolution. A negative nf signals that the evolution has hit a cut or grid boundary. If the start point iqlim(1) is outside the grid or cuts then evdglap acts as a do-nothing and returns nf = -1.

epsi Maximum difference between quadratic and linear interpolation in-between the grid points, as is described for the routine evolfg.

The order of the evolution (iord), the flavour thresholds (iqc,b,t) and the kinematic cuts are those set by upstream calls to setord, setcbt and setlim, respectively. All evolution parameters and cuts will be stored along with the evolved pdfs.

By default, the number of perturbative terms (nopt) in the evolution is set equal to 1/2/3 at LO/NLO/NNLO. But this may not always be the case: for QCD-QED evolution, for instance, this may be 2/3/4, depending on the truncation of the $\alpha_s^n \alpha^m$ terms in the expansion. You can set the number of perturbative terms nopt by call to setint upstream of evdglap. For example,

call setint ('nopt', 234) !2/3/4 terms at LO/NLO/NNLO

The number of digits of nopt defines the maximum order that evdglap can handle. Thus if you coded a QCD-QED evolution at LO, the setting of nopt = 2 means that evdglap can only be run at LO (error message otherwise), with two perturbative terms.

The weight tables must all reside in the toolbox workspace so that internal weight tables can only be used when they are first copied to the workspace with copywgt. Be aware, however, that $P_{\rm qg}$ in QCDNUM contains a factor $2n_{\rm f}$, see (B.2), which may not be what you want. It might very well be that splitting functions are missing, either because they don't exist like $P_{\rm q\bar{q}}$ at LO, or simply because they have never been calculated at higher orders. In this case you should set the table identifier to zero which causes evdglap to skip over the entry in the $n \times n$ splitting function matrix.

The evdglap routine cannot, like evolfg, transparently handle VFNs evolution, simply because it has no information about the flavour composition of the pdfs to be evolved. Instead, it automatically restricts the evolution to a fixed number of flavours by, if necessary, limiting the end point of the evolution to the next flavour threshold, cut, or grid boundary above (below) μ_0^2 in case of upward (downward) evolution.

In the VFNs you thus have to chain yourself the evolutions in the different threshold regions. Several features of the evdglap interface do facilitate such a chaining: after the evolution the actual endpoint is passed via iqlim(2) and the values of the pdfs at this endpoint via the start array. The number of flavours is passed via nf, but it is pre-pended by a minus sign when you hit the limits of the μ^2 grid, or cuts, indicating that no further evolution is possible.

These features make the VFNS chaining quite easy as is shown below by code for upward evolution (for downward evolution set $iqlim(2) \leq 0$, also inside the while loop).

```
iqlim(1) = iq0
iqlim(2) = 99999
call evdglap(w,idw,ida,idf,start,m,n,iqlim,nf,epsi)
do while(nf.gt.0)
  iqlim(1) = iqlim(2)
  iqlim(2) = 99999
  start = start + discontinuity (code not shown)
  call evdglap(w,idw,ida,idf,start,m,n,iqlim,nf,epsi)
enddo
```

This method of carrying the pdfs over the threshold via the start array causes a small bias when you evolve on multiple x-grids. This is because the pdfs returned at the end of the evolution are a composite of the pdfs evolved on the individual sub-grids.

The bias is eliminated when you run evdglap in the so-called internal transfer mode where the pdfs are, subgrid-by-subgrid, carried over the threshold internally. You can select this mode by setting n negative. On entry, only the discontinuity should be passed via the start array which, on exit, is set to zero by evdglap.

The VFNS code now becomes (note that the first call to evdglap remains the same).

```
iqlim(1) = iq0
iqlim(2) = 99999
call evdglap(w,idw,ida,idf,start,m,+n,iqlim,nf,epsi)
do while(nf.gt.0)
  iqlim(1) = iqlim(2)
  iqlim(2) = 99999
  start = discontinuity (code not shown)
  call evdglap(w,idw,ida,idf,start,m,-n,iqlim,nf,epsi)
enddo
```

The bias is usually quite small (about a per-mille or less) so that in practice it will be mostly a matter of taste if you transfer via the start-array or internally.

7.6 Pdf Interpolation and Export

In this section we describe routines to access the pdfs evolved with evdglap.

Like for the pdfs in the internal memory, the evolution parameters are stored along with the pdfs in the toolbox. The parameter routines are as those described in Section 5.7 except that you have to also supply the workspace w as an argument to the call.

```
call CPYPARW(w,*array,n,iset) key = KEYPARW(w,iset)
call USEPARW(w,iset) key = KEYGRPW(w,iset,igroup)
```

You can access the internal memory by setting w(1) to zero, thus:

```
KEYPARW(w,iset) .eq. KEYPARW(0.D0,0) !pdfs evolved with current parameters
```

```
pdfij = EVPDFIJ ( w, id, ix, iq, ichk )
```

Return the value of a toolbox pdf at a grid point.

- w Workspace, with pdfs previously evolved with evdglap.
- id Pdf identifier in the global format (7.1).
- ix, iq Grid point. Negative iq selects the 345-grid with lower $n_{\rm f}$ at the thresholds.
- ichk Yes (1) or no (0) check that (ix, iq) is within the grid boundaries or cuts.

To make the routine run faster in a loop, you can set ichk = -1 to skip the check on the identifier id, but you should always check the identifier on entry:

```
pdf(1) = EvPdfij( w, id, ix(1), iq(1), 1 ) !check id
do i = 2,n
   pdf(i) = EvPdfij( w, id, ix(i), iq(i), -1 ) !do not check id
enddo
```

```
call EVPLIST ( w, id, x, qmu2, *pdf, n, ichk )
```

Generate a list of interpolated toolbox pdfs.

- w Workspace, with pdfs previously evolved with evdglap.
- id Pdf identifier in the global format (7.1).
- x, qmu2 Arrays, dimensioned to at least x(n) and qmu2(n) in the calling routine.
- pdf Array, dimensioned to at least pdf(n) in the calling routine. On exit the array is filled with the list of interpolated pdfs.
- n Number of interpolation points.
- ichk As above (without the option to set ichk = -1).

```
call EVTABLE ( w, id, x, nx, q, nq, *table, ichk )
```

As above but now fill an $nx \times nq$ table of interpolated values. In the calling routine the arrays must be dimensioned x(nx), q(nq) and table(nx,nq). This routine is about a factor of two faster than evplist.

With this routine you can copy the 13 + n pdf tables from the toolbox workspace to the QCDNUM internal memory.⁵² Such an export is useful because you can then use any routine that works with internal pdfs such as the built-in interpolation routines or the structure function packages ZMSTF and HQSTF.

For this export it is required that you supply the flavour composition of the toolbox quark pdfs so that QCDNUM can transform them to the singlet/non-singlet basis (2.23).

In the description below, n_f is the largest number of flavours encountered in the evdglap evolution. You do not have to actually enter this number since it is known to QCDNUM.

w Workspace, with pdfs previously evolved with evdglap.

Integer array, dimensioned to idf(0:12+n) in the calling routine. The gluon identifier must be stored in idf(0), the $2n_f$ quark identifiers in idf(i), $i = 1, ..., 2n_f$ and the extra n identifiers in idf(12+i). The identifiers should be given in the global format (7.1) and all pdfs must be in the same table set.

Double precision array, dimensioned def(-6:6,12) in the calling routine. In def(i,j) should be stored the contribution of flavour i, indexed as given in (5.1), to the quark density $j = 1, ..., 2n_f$. The $2n_f \times 2n_f$ sub-matrix of (anti)quark coefficients must be invertible, see also evolfg in Section 5.8.

n The number of additional pdfs to be exported.

Pdf set identifier [1–24] to which the pdfs should be copied. If iset does exist its contents are overwritten, provided that it can hold 13 + n pdfs (fatal error if not).⁵³ Otherwise the set is created, provided that there is enough space in the QCDNUM internal memory (fatal error if not).

The evolution parameters associated with the pdfs are also copied to internal memory.

7.7 Transformations

The routines in this section allow you to make pdf transformations from the singlet/non-singlet basis (2.23) to the flavour basis, and *vice versa*.

We can write an arbitrary pdf in two ways as

$$|f\rangle = \sum_{i=1}^{n_{\rm f}} (\alpha_i |q_i\rangle + \beta_i |\bar{q}_i\rangle) = \sum_{i=1}^{n_{\rm f}} (d_i^+ |e_i^+\rangle + d_i^- |e_i^-\rangle),$$
 (7.7)

where the first term on the right-hand side represents the pdf written on the flavour basis and the second term that on the singlet/non-singlet basis. To translate the coefficients α and β into d^+ and d^- , and *vice versa*, the routines efromqq and qqfrome are provided.

⁵²You can also use pdfext for this, but evpcopy is more convenient and also faster.

⁵³You can call nptabs(iset) beforehand to check if the pdf set exists and has enough pdf tables.

For convenience we show here again the indexing (5.2) of the flavour basis

$$\frac{-6 \quad -5 \quad -4 \quad -3 \quad -2 \quad -1 \quad 0 \quad 1 \quad 2 \quad 3 \quad 4 \quad 5 \quad 6}{\bar{t} \quad \bar{b} \quad \bar{c} \quad \bar{s} \quad \bar{u} \quad \bar{d} \quad a \quad d \quad u \quad s \quad c \quad b \quad t},\tag{7.8}$$

and the indexing (5.3) of the singlet/non-singlet basis

$$\frac{0}{q} \frac{1}{q_s} \frac{2}{e_s^+} \frac{3}{e_s^+} \frac{4}{e_s^+} \frac{5}{e_s^+} \frac{6}{e_s^+} \frac{7}{e_s^+} \frac{8}{e_s^-} \frac{9}{e_s^-} \frac{10}{e_s^-} \frac{11}{e_s^-} \frac{12}{e_s^-} \frac{12}$$

Transform the coefficients of a linear combination of quarks and anti-quarks from the flavour basis to the singlet/non-singlet basis.

qvec Input array, dimensioned qvec(-6:6), filled with the coefficients α and β of a linear combination of quarks and antiquarks, indexed according to (7.8).

evec Output array, dimensioned to evec(12), filled with the singlet/non-singlet coefficients d^+ and d^- , indexed according to (7.9).

Active number of flavours. This parameter is needed to construct the appropriate $2n_f \times 2n_f$ transformation matrix that acts on qvec(-nf:nf).

Transform the coefficients of a linear combination of basis vectors from the singlet/non-singlet basis to the flavour basis. The arguments are as for efromqq.

7.8 Pdf Access Scope

With the convolution tools presented in the next sections you can convolute any pdf from internal memory or a toolbox workspace. Some of these routines depend on one or more evolution parameters (e.g. thresholds) which are known if the pdfs are read from (toolbox) memory, but not if they are read from a temporary buffer, or entered via a user function. Routines with such a pdf input must be told beforehand which set of evolution parameters to use. By default, the current (active) set is used and access is restricted to pdfs evolved with this set. You can call idscope to select another parameter set.

Restrict pdf access to those evolved with the same parameters as iset.

w Toolbox workspace. If iset refers to a pdf set in internal memory then w must be a dummy variable or non-workspace array, preferably set to w or w(1) = 0. iset Pdf set identifier.

Call idscope (0.D0,0) to return to the default of using the current parameter settings. Which routines restrict access via the scope, and which do not, will be mentioned below.

7.9 Convolution Tools

With the convolution tools you can calculate convolution integrals like

$$x[f \otimes K](x)$$
 and $x[f_a \otimes f_b](x)$,

where f is a parton number density, and K is a convolution kernel; see Section 3.2 for how convolution integrals are computed and where the factor x in front comes from. Such convolutions are the building blocks to compute structure functions in deep inelastic scattering, or parton luminosities in hadron-hadron scattering.

Calculate the convolution $x[f \otimes K](x)$ at a grid point in x and μ^2 .

w Toolbox workspace.

idw Weight table identifier in the global format (7.1). You can use a weight table from internal memory, provided its identifier is constructed by a call to idspfun.

idum Not used.

idf Pdf identifier in the global format (7.1). You can use a pdf from internal memory, provided its identifier is constructed by a call to ipdftab.

ix, iq Indices of an $x-\mu^2$ grid point (456-grid). Set iq negative to use the 345-grid.

Pdf access is not restricted by the scope.

```
val = FCROSSF ( w, idw, idum, ida, idb, ix, iq )
```

Calculate the convolution $x[f_a \otimes f_b](x)$ at a grid point in x and μ^2 .

w Toolbox workspace.

idw Identifier of a weight table in w, previously filled by a call to makewx.

idum Not used.

ida, idb Pdf identifiers in the global format (7.1). You can use a pdf from internal memory, provided its identifier is constructed by a call to ipdftab.

ix, iq Indices of an $x-\mu^2$ grid point (456-grid). Set iq negative to use the 345-grid.

The evolution parameters of ida and idb must be the same but otherwise access is not restricted by the scope.

The convolution routines above can be used to build a structure function or a parton luminosity at a grid point (ix,iq) in x and μ^2 . The idea is to pack this calculation into a function fun(ix,iq) which is then passed to the routine stfunxq that takes care of the interpolation to any value of x and μ^2 .

call STFUNXQ (fun, x, qmu2, stf, n, ichk)

Interpolate a function fun(ix,iq) to a list of x and μ^2 values. In fact, any function of the grid points ix and iq can be interpolated by this routine. Because interpolation depends on the thresholds the routine restricts pdf access to the current settings (default) or to those defined by idscope.

fun Double precision function, declared external in the calling routine.

x, qmu2 List of interpolation points, dimensioned to at least n in the calling routine.

stf Contains, on exit, the list of interpolated results.

n Number of items in x, qmu2 and stf.⁵⁴

ichk If set to 0 the routine returns a null value if x or μ^2 are outside the grid

boundaries or cuts; if set non-zero it will issue a fatal error message.

The routine will construct interpolation meshes for all interpolation points and then call fun in a loop over all mesh points. It may happen that one hits a threshold with the lower number of flavours—causing a call to fun(ix,-iq)—or with the upper number of flavours—causing a call to fun(ix,+iq). The function may also be called for ix = nx+1 (x = 1) in which case fun must return zero. Note that all build-in QCDNUM functions of ix and iq correctly handle negative iq and the limit x = 1.

This scheme of calculating structure functions or parton luminosities is fairly straightforward and therefore suitable for prototyping and debugging. However, there is a considerable amount of overhead so that it is recommended to ultimately move the computation to a fast calculation scheme that is described in the next section. By this you will gain at least an order of magnitude in speed.

7.10 Fast Convolution Engine

The convolution routines provided up to now are slow because there is quite a lot of overhead when the calculation is repeated at more than one interpolation point. In this section we describe a set of routines that does bulk calculations on selected points in the x- μ^2 grid. In this way, loops are internally optimised, redundant calculations are eliminated, and user interface checks are reduced to a minimum. This usually leads to large speed gains of more than an order of magnitude.

The engine works as follows. First, you have to pass a list of interpolation points in x and μ^2 so that the engine can construct an interpolation mesh. Next you should copy pdfs onto the mesh in one or more scratch buffers. A set of fast routines then allows you to operate on these buffers. The final result is accumulated in an end-buffer which is passed to an interpolation routine that produces the list of interpolated structure functions or parton luminosities (or whatever else you want to calculate with the engine).

 $^{^{54}}$ In principle you can set n = 1 and call stfunxq in a loop over interpolation points. However, it is better to avoid such loops and enter the *list* of points. This usually leads to very large gains in speed.

One feature of the engine is that the calculations can be chained so that all kind of convolution integrals can be computed, such as

$$x[f \otimes K](x), \quad x[f \otimes K_a \otimes K_b](x), \quad x[f_a \otimes f_b](x), \quad x[f_a \otimes f_b \otimes K](x), \quad etc.$$

In principle, the output buffer of any fast routine can serve as the input buffer of any other fast routine. There is, however, a little complication related to the amount of information stored in a buffer. For interpolation purposes, it is sufficient to store results only at the mesh points; such a buffer is called *sparse*. A convolution routine, on the other hand, does not only need the values at the mesh points x_i , but also the values at all points $x_j > x_i$. An input buffer with such a storage pattern is called *dense*; a dense buffer is of course more expensive to generate than a sparse buffer. Usually you do not have to worry about sparse and dense buffers, because QCDNUM has reasonable defaults for what kind of buffer is accepted as input, and what kind of buffer is generated on output. You can always override the output default and force a routine to generate a dense or a sparse buffer, as needed.

To guarantee internal consistency, the engine only accepts pdfs evolved with the current parameter settings (default) or with those defined by idscope.

Pass a list of interpolation points and link the engine to the current set of evolution parameters (default) or to those defined by idscope.

x Array, dimensioned to at least n in the calling routine, filled with x values.

qmu2 As above, but for μ^2 (not Q^2).

n Number of entries in x and gmu2 (< 5000).

ichk If non-zero, fastini insists that all interpolation points are within the grid boundaries or cuts.

By default, 10 scratch buffers⁵⁵ (ibuf = 1–10) are generated at the first call (or cleared if they exist) provided, of course, that there is enough space for the buffers in the QCDNUM internal memory (error message if not). The number of interpolation points is limited to 5000 which means that longer lists have to be processed in batches of 5000. The example program longlist.f has a compact while-loop that does this.

call FASTCLR (ibuf)

Clear a scratch buffer. Setting ibuf = 0 will clear all buffers and re-link the engine to the current set of evolution parameters (default), or to those defined by idscope.

⁵⁵This number can be changed by setting mbf0 in qcdnum.inc.

|--|

Copy a pdf from the toolbox workspace w or from internal memory into a scratch buffer.

w Workspace with pdfs previously evolved by evdglap.

idf Pdf identifier in the global format (7.1). You can also read a pdf from

internal memory, provided its identifier is constructed with ipdftab.

coef Array, dimensioned coef(3:6) in the calling routine, containing an $n_{\rm f}$ -

dependent factor by which the pdf will be multiplied.

ibuf Output scratch buffer identifier [1–10].

iadd Store (0), add (1) or subtract (-1) the weighted pdf to ibuf.

By default, fastinp generates a dense buffer; a sparse buffer is generated when you prefix ibuf with a minus sign.

```
call FastInp(w, coef, 1502, 1, 0) !1=dense buffer
call FastInp(w, coef, 1502, -1, 0) !1=sparse buffer
```

Repeated calls to this routine⁵⁶ allow you to store $n_{\rm f}$ -dependent linear combinations of pdfs from the workspace or the internal memory.

Alternatively you can use the input routines fastepm, fastsns and fastsum below, which do work only for pdfs in internal memory. You may find them quite handy but note that everything you can do with these routines, you can also do with fastinp.

```
call FASTEPM ( idum, idf, ibuf )
```

Copy the gluon density or one of the basis pdfs $|e^{\pm}\rangle$ to a scratch buffer.

idum Not used

idf Global pdf identifier constructed with ipdftab.

ibuf Output scratch buffer identifier [1–10].

By default, fastepm generates a dense buffer; a sparse buffer is generated when you prefix ibuf with a minus sign.

```
call FASTSNS ( iset, def, isel, ibuf )
```

Decompose a given linear combination of quarks and anti-quarks into singlet and non-singlet components and copy a specific component to a scratch buffer. This the same selection mechanism as described for the routine sumfxq in Section 5.10.

iset Identifier of a pdf set in internal memory [1–24].

 $^{^{56}}$ Note that once you have selected a sparse output in one of these calls, the output buffer will remain flagged as sparse until you start a new accumulation by setting iadd = 0.

def Input array, dimensioned to def(-6:6) and filled with the coefficients of a linear combination of quarks and anti-quarks, indexed according to (7.8). The value of def(0) corresponds to the gluon and is ignored by this routine.

isel Selection flag [0-7], see below.

ibuf Output scratch buffer identifier [1–10].

The selections are the same as in sumfxq but, for historical reasons, the numbering of isel is different. Here is the conversion table.

pdf component	fastsns	sumfxq	pdf component	fastsns	sumfxq
weighted gluon	0	8	ns ⁻	4	6
singlet	1	2	$valence + ns^-$	5	5
ns^+	2	4	all non-singlet	6	3
valence	3	7	all quarks	7	1

By default, fastsns generates a dense buffer; a sparse buffer is generated when you prefix ibuf with a minus sign.

```
call FASTSUM ( iset, coef, ibuf )
```

Copy a linear combination of basis pdfs $|e^{\pm}\rangle$ to a scratch buffer.

iset Identifier of a pdf set in internal memory [1–24].

coef Array of coefficients dimensioned coef (0:12,3:6) in the calling routine.

ibuf Output scratch buffer identifier [1–10].

The array coef(i,nf) is indexed according to (7.9). Here is code that fills coef by transforming a set of quark coefficients from flavour space to singlet/non-singlet space:

```
dimension qvec(-6:6), coef(0:12,3:6)
do nf = 3,6
  coef(0,nf) = 0.D0     !no gluon, thank you
  call efromqq(qvec, coef(1,nf), nf)  !quark coefficients
enddo
```

By masking-out coefficients, you can copy the singlet component, or various combinations of non-singlets; this is exactly what fastsns does. To copy the gluon distribution, you must set all coefficients to zero, except coef(0,nf).

By default, fastsum generates a dense buffer; a sparse buffer is generated when you prefix ibuf with a minus sign.

```
call FASTFXK ( w, idw, ibuf1, ibuf2 )
```

Calculate the convolution $x[f \otimes K](x)$ at all selected grid points.

Workspace, previously filled with weights.
 idw Array of weight table identifiers declared idw(4) in the calling routine. Identifiers must be given in the global format (7.1) and cannot refer to those in internal memory. See below for what should be stored in idw(i).
 ibuf1 Input buffer, previously filled by fastinp, fastepm, fastsns or fastsum.
 ibuf2 Output buffer with ibuf2 ≠ ibuf1.

You can either convolute with a given weight table or with a perturbative expansion of weight tables, depending on what you put in the array idw.

- To convolute with a given weight table, set idw(1) to the identifier of that weight table and set idw(2), (3) and (4) to zero.
- To convolute with a perturbative expansion in α_s ,
 - Store the (LO,NLO,NNLO) weight table identifiers in idw(1), idw(2) and idw(3). Set the identifier to zero if no such table exists (e.g. for F_L at LO);
 - Declare in idw(4) the leading power of α_s , that is, multiply (LO,NLO,NNLO) by $(1,\alpha_s,\alpha_s^2)$ if idw(4) = 0 and by $(\alpha_s,\alpha_s^2,\alpha_s^3)$ if idw(4) = 1.

Note that the expansion is summed up to the current perturbative order. Thus you do not have to specify the identifiers in idw(2) and (3) when you run in LO.

The routine only accepts a dense buffer as input (otherwise fatal error) and will, by default, generate a sparse buffer as output. If you prefix ibuf2 with a minus sign, the output buffer will be dense. The output table can then serve as an input to another convolution so that you can calculate multiple convolutions in a chain. For example, ⁵⁷

```
call FASTFXF ( w, idx, ibuf1, ibuf2, ibuf3 )
```

Calculate the convolution $x[f_a \otimes f_b](x)$ at all selected grid points.

Workspace, previously filled with weights.

idx Identifier of a weight table, previously filled by a call to makewtx.

ibuf1, 2 Input buffers, filled with pdfs. It is allowed to have ibuf1 = ibuf2.

ibuf3 Output buffer with ibuf3 \neq ibuf1 or ibuf2.

The routine accepts only dense buffers as input, and generates a sparse buffer as output, unless the ibuf2 is prefixed by a minus sign, thus,

⁵⁷It is more efficient, however, to first calculate with wcrossw a weight table for $K_3 = K_1 \otimes K_2$, and use that table to convolute f with K_3 .

```
call FASTKIN ( ibuf, fun )
```

Multiply the contents of a buffer by a kinematic factor.

ibuf Identifier of the input buffer.

fun Double precision function, declared external in the calling routine, that should return the kinematic factor.

The routine fastkin loops over the selected grid points and passes these to fun via the argument list, together with the current number of flavors and a threshold indicator:

double precision function fun (ix, iq, nf, ithresh)

ix, iq Grid point indices.

nf Number of flavors at iq. This number is bi-valued at the thresholds so that at the charm threshold, for instance, nf can be either 3 or 4.⁵⁸

ithresh Set to 0 if iq is not at a threshold and to +1 (-1) if iq is at a threshold with the upper (lower) number of flavours. This variable can be used to take NNLO discontinuities into account, as is shown in the example function below which returns $\alpha_{\rm s}/2\pi$ as the kinematic factor.

```
double precision function fun(ix,iq,nf,ithresh)
...
if(ithresh.ge.0) then
  fun = altabn(0, iq,1,ierr) !alfas/2pi with discontinuity
else
  fun = altabn(0,-iq,1,ierr) !without discontinuity
endif
...
```

```
call FASTCPY ( ibuf1, ibuf2, iadd )
```

Copy or accumulate a result in an output buffer.

ibuf1 Identifier of the input buffer.

ibuf2 Identifier of the output buffer with ibuf2 \neq ibuf1.

iadd Store (0), add (1) or subtract (-1) the result to ibuf2.

The type of output buffer (sparse or dense) is the same as that of the input buffer, except that once you have used a sparse input buffer, the output buffer is flagged as sparse and will remain so until you set iadd = 0 to start a new accumulation in ibuf2.

⁵⁸You may wonder when QCDNUM returns the value 3, and when the value 4. This depends on the interpolation point μ^2 to which iq is associated: if μ^2 is below (above) μ_c^2 , then nf = 3 (4).

```
call FASTFXQ ( ibuf, *f, n )
```

Interpolate the contents of ibuf to the list of x and μ^2 values that was previously passed to QCDNUM by the call to fastini.

ibuf Identifier of an input buffer.

f Array dimensioned to at least n in the calling routine that will contain, on

exit, the interpolated values.

n Number of interpolations requested.

The routine works through the list of interpolation points given in the call to fastini and exits when it reaches the end of that list or when the number of interpolations is equal to n, whatever happens first. Best is to have a sparse input buffer because a dense buffer, although allowed, contains a lot of mesh points that are not used by fastfxq.

The fast convolution engine is designed for structure function, cross-section or parton luminosity calculations but can also be used for simple tasks like efficient pdf interpolation, as is illustrated by the following code.

```
dimension xx(150), qq(150), pdf(150)

idg = ipdftab(iset,0)     !gluon in internal memory
call fastini(xx,qq,150,ichk) !pass list of interpolation points
call fastepm(idum,idg,-1)    !copy gluon to buffer #1 (sparse!)
call fastfxq(1,pdf,150)    !interpolate gluon
```

7.11 Error Messages in Add-On Packages

QCDNUM error messages refer to the QCDNUM routine and not to the calling routine. This may become confusing for the user of an add-on package who expects error messages to be issued by the package routines and not by what is inside.

One solution would be that a package catches errors before QCDNUM does, but this would duplicate a good checking mechanism which is already in place. An easier solution is to pass a string to QCDNUM which contains the name of the package routine so that it will be printed together with the error message. For this, the routines setumsg and clrumsg are provided. For instance one of the first calls in the zmfillw routine of the ZMSTF package is

```
call setUmsg('ZMFILLW')
```

so that, upon error, the user gets additional information:

```
Error in MAKETAB ( W, NW, ITYPES, NP, NEW, ISET, NWDS ) ---> STOP

No x-grid available
```

Please call GXMAKE

Error was detected in a call to ZMFILLW

The last call in zmfillw is

call clrUmsg

that wipes the additional message. This is important because downstream QCDNUM errors would otherwise appear to have always come from zmfillw.

8 Acknowledgements

I am of course indebted to the original authors of QCDNUM, in particular to M. Virchaux who introduced me to the program in 1991.⁵⁹

I greatly benefited from the many clarifying discussions with A. Vogt and thank him for the code of the NNLO splitting and coefficient functions.

I also thank the xFitter development team who implemented QCDNUM as one of their evolution engines and thereby prompted me to keep the program alive.

The C++ interface would not exist without the help of V. Bertone who wrote the first version of the interface and got it going.

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⁵⁹It was sad to hear that Marc Virchaux passed away in November 2004.

A Space-like and Time-like Singlet Evolution

In this Appendix we specify which splitting functions from ref. [14] enter in the space-like and time-like singlet evolution. For this purpose (2.9) is written as

$$\frac{\partial \boldsymbol{V}}{\partial \ln \mu^2} = \boldsymbol{M} \otimes \boldsymbol{V} \quad \text{with} \quad \boldsymbol{V} = \begin{pmatrix} F \\ G \end{pmatrix} \quad \text{and} \ \boldsymbol{M} = \begin{pmatrix} P_{\mathrm{qq}} & P_{\mathrm{qg}} \\ P_{\mathrm{gq}} & P_{\mathrm{gg}} \end{pmatrix}.$$

For space-like evolution F and G are the singlet and gluon pdfs while for time-like evolution they stand for the corresponding fragmentation functions. Here we are concerned with the expansion of the splitting functions up to NLO:

$$M = a_{\rm s} M^{(0)} + a_{\rm s}^2 M^{(1)} + O(a_{\rm s}^3)$$
 with $a_{\rm s} = \alpha_{\rm s}/2\pi$.

The following four functions are defined in [14]

$$p_{\text{FF}} = (1+x^2)/(1-x)$$
 $p_{\text{GF}} = x^2 + (1-x)^2$
 $p_{\text{FG}} = [1+(1-x)^2]/x$ $p_{\text{GG}} = 1/(1-x) + 1/x - 2 + x - x^2$.

The four LO splitting functions are then written as

$$P_{\rm FF}^{(0)} = C_{\rm F} [p_{\rm FF}]_+ \quad P_{\rm GF}^{(0)} = 2T_{\rm R}n_{\rm f} p_{\rm GF}$$

 $P_{\rm FG}^{(0)} = C_{\rm F} p_{\rm FG} \qquad P_{\rm GG}^{(0)} = 2C_{\rm G}x^{-1}[xp_{\rm GG}]_+ - \frac{2}{3}T_{\rm R}n_{\rm f} \delta(1-x)$

with the colour factors and the regularisation prescription given by

$$C_{\rm F} = \frac{4}{3}$$
, $C_{\rm G} = 3$, $T_{\rm R} = \frac{1}{2}$ and $[f(x)]_+ \equiv f(x) - \delta(1-x) \int_0^1 f(y) dy$.

The NLO splitting functions for space-like (S) and time-like (T) processes are

$$\begin{split} P_{\mathrm{FF}}^{(1,\mathrm{U})} &= \hat{P}_{\mathrm{FF}}^{(1,\mathrm{U})} - \delta(1-x) \int_{0}^{1} \mathrm{d}x \ x \left[\hat{P}_{\mathrm{FF}}^{(1,\mathrm{T})} + \hat{P}_{\mathrm{FG}}^{(1,\mathrm{T})} \right] \\ P_{\mathrm{GF}}^{(1,\mathrm{U})} &= \hat{P}_{\mathrm{GF}}^{(1,\mathrm{U})} \\ P_{\mathrm{FG}}^{(1,\mathrm{U})} &= \hat{P}_{\mathrm{FG}}^{(1,\mathrm{U})} \\ P_{\mathrm{GG}}^{(1,\mathrm{U})} &= \hat{P}_{\mathrm{GG}}^{(1,\mathrm{U})} - \delta(1-x) \int_{0}^{1} \mathrm{d}x \ x \left[\hat{P}_{\mathrm{GG}}^{(1,\mathrm{T})} + \hat{P}_{\mathrm{GF}}^{(1,\mathrm{T})} \right], \end{split}$$

where $U = \{S,T\}$. The functions $\hat{P}_{AB}^{(1,U)}$ are given in Eqs. (11) and (12) of [14].

The space-like splitting function matrices in QCDNUM are

$$m{M}^{(0,\mathrm{S})} = egin{pmatrix} P_{\mathrm{FF}}^{(0)} & P_{\mathrm{GF}}^{(0)} \ P_{\mathrm{FG}}^{(0)} & P_{\mathrm{GG}}^{(0)} \end{pmatrix} \qquad m{M}^{(1,\mathrm{S})} = egin{pmatrix} P_{\mathrm{FF}}^{(1,\mathrm{S})} & P_{\mathrm{GF}}^{(1,\mathrm{S})} \ P_{\mathrm{FG}}^{(1,\mathrm{S})} & P_{\mathrm{GG}}^{(1,\mathrm{S})} \end{pmatrix}.$$

The LO time-like matrix is the transpose of the space-like matrix [16]. The NLO matrix is also transposed [32]. Accounting for factors $2n_{\rm f}$, we then have

$$\boldsymbol{M}^{(0,\mathrm{T})} = \begin{pmatrix} P_{\mathrm{FF}}^{(0)} & 2n_{\mathrm{f}}P_{\mathrm{FG}}^{(0)} \\ \frac{1}{2n_{\mathrm{f}}}P_{\mathrm{GF}}^{(0)} & P_{\mathrm{GG}}^{(0)} \end{pmatrix} \qquad \boldsymbol{M}^{(1,\mathrm{T})} = \begin{pmatrix} P_{\mathrm{FF}}^{(1,\mathrm{T})} & 2n_{\mathrm{f}}P_{\mathrm{FG}}^{(1,\mathrm{T})} \\ \frac{1}{2n_{\mathrm{f}}}P_{\mathrm{GF}}^{(1,\mathrm{T})} & P_{\mathrm{GG}}^{(1,\mathrm{T})} \end{pmatrix}.$$

B Singularities

In this appendix we denote by f(x) a parton momentum density and not a number density. In terms of f the convolution integrals in the evolution equations read

$$I(x) = \int_{x}^{1} dz \ P(z) \ f\left(\frac{x}{z}\right). \tag{B.1}$$

The splitting functions of the LO splitting matrix $P_{ij}^{(0)}$ in (2.14) can be written as

$$P_{qq}^{(0)}(x) = \frac{4}{3} \left[\frac{1+x^2}{(1-x)_+} + \frac{3}{2} \delta(1-x) \right]$$

$$P_{qg}^{(0)}(x) = 2n_f \frac{1}{2} \left[x^2 + (1-x)^2 \right]$$

$$P_{gq}^{(0)}(x) = \frac{4}{3} \left[\frac{1+(1-x)^2}{x} \right]$$

$$P_{gg}^{(0)}(x) = 6 \left[\frac{x}{(1-x)_+} + \frac{1-x}{x} + x(1-x) + \left(\frac{11}{12} - \frac{n_f}{18} \right) \delta(1-x) \right].$$
(B.2)

The '+' prescription in (B.2) is defined by

$$[f(x)]_{+} = f(x) - \delta(1-x) \int_{0}^{1} f(z) dz$$
 (B.3)

so that

$$\int_{x}^{1} f(z)[g(z)]_{+} dz = \int_{x}^{1} [f(z) - f(1)] g(z) dz - f(1) \int_{0}^{x} g(z) dz.$$
 (B.4)

For reference we give the expressions for $I_{\rm qq}$ and $I_{\rm gg}$ obtained from (B.2) and (B.3)

$$I_{qq}^{(0)}(x) = \frac{4}{3} \int_{x}^{1} dz \, \frac{1}{1-z} \left[(1+z^{2}) f\left(\frac{x}{z}\right) - 2f(x) \right] + \frac{4}{3} f(x) \left[\frac{3}{2} + 2\ln(1-x) \right]$$

$$I_{gg}^{(0)}(x) = 6 \int_{x}^{1} dz \, \frac{1}{1-z} \left[z f\left(\frac{x}{z}\right) - f(x) \right] + 6 \int_{x}^{1} dz \, \left[\frac{1-z}{z} + z(1-z) \right] f\left(\frac{x}{z}\right) + 6 \int_{x}^{1} dz \, \left[\ln(1-x) + \frac{11}{12} - \frac{n_{f}}{18} \right].$$
(B.5)

To write down a generic expression we decompose a splitting (or coefficient) function into a regular part (A), singular part (B), product of the two (RS) and a delta function

$$P(x) = A(x) + [B(x)]_{+} + R(x)[S(x)]_{+} + K(x)\delta(1-x)$$
(B.6)

where, of course, not all terms have to be present. The following functions are defined in the logarithmic scaling variable $y = -\ln(x)$:

$$h(y) = f(e^{-y}), \ Q(y) = e^{-y}P(e^{-y}), \ \bar{A}(y) = e^{-y}A(e^{-y})$$
 (B.7)

with similar definitions for \bar{B} and \bar{S} . Furthermore, $\hat{R}(y) = R(e^{-y})$ and $\hat{K}(y) = K(e^{-y})$ without a factor e^{-y} in front. With these definitions (B.1) can be written as

$$I(y) = \int_{0}^{y} du \ Q(u) \ h(y-u) = I_{1}(y) + I_{2}(y) + I_{3}(y) + I_{4}(y) \quad \text{with}$$

$$I_{1}(y) = \int_{0}^{y} du \ \bar{A}(u) \ h(y-u);$$

$$I_{2}(y) = \int_{0}^{y} du \ \bar{B}(u) \ [h(y-u) - h(y)] - h(y) \int_{0}^{x} dz \ B(z);$$

$$I_{3}(y) = \int_{0}^{y} du \ \bar{S}(u) \ [\hat{R}(u)h(y-u) - \hat{R}(0)h(y)] - \hat{R}(0)h(y) \int_{0}^{x} dz \ S(z);$$

$$I_{4}(y) = \hat{K}(y)h(y),$$
(B.8)

where the last integrals of I_2 and I_3 are still expressed in the variable $x = \exp(-y)$ to avoid integration extending to infinity in our expressions. Note that we are free to swap the arguments u and y - u in (B.8).

The four integrals in (B.8) are tabulated by calls to the toolbox weight routines makewta, makewtb, makewts and makewtd, respectively. In these calls the functions (B.6) are passed as arguments; the transformations (B.7) are done internally in QCDNUM.

C Forward and Reverse Matching

In this appendix we describe how QCDNUM matches the basis pdfs $|e^{\pm}\rangle$ both in the forward and reverse direction. First of all, we find directly from (2.35) the NNLO matching equations for the unpolarised active quark basis functions $|e_{2...n}^{\pm}\rangle$

$$e_i^{\pm}(x,\mu_h^2,n+1) = \left[(A_0 + a_s^2 A_{qq}) \otimes e_i^{\pm} \right] (x,\mu_h^2,n) \quad i = 2,\dots,n,$$
 (C.1)

where n is the number of flavours below threshold and where we have introduced the delta-function kernel $A_0(z) = \delta(1-z)$ with $[A_0 \otimes f](x) = f(x)$. It is easy to compute the forward matching while in the reverse case we have to solve (C.1) for the $e_i^{\pm}(n)$, given the $e_i^{\pm}(n+1)$; in Appendix D we show how QCDNUM does this numerically.

The matching of the gluon $|e_0\rangle$, singlet $|e_1^{\pm}\rangle$, and the heavy quark basis function $|e_{n+1}^{\pm}\rangle$ proceeds via more complicated coupled equations so that it is better to first transform to a basis that maximally decouples them. To simplify notation we will denote the basis pdfs $|e_0\rangle$ and $|e_i^{\pm}\rangle$ by G and E_i , respectively, and introduce the pdfs

$$S = \sum_{i=1}^{n} q_i^+, \qquad V = \sum_{i=1}^{n} q_i^- \quad \text{and} \quad H = h^{\pm}.$$

In the following the un-primed (primed) pdfs are those before (after) forward matching. Transformation of the E_i to the set (G, S, V, H) and *vice versa* is easily computed. From (2.23), (2.24) and (2.31) we get for the $|e^+\rangle$ basis below threshold, setting $H = h^+$,

$$E_0 = G, \quad E_1 = S, \quad E_{n+1} = H.$$
 (C.2)

After matching we have above threshold (note that S' is summed over n and not n+1)

$$E'_0 = G', \quad E'_1 = S' + H', \quad E'_{n+1} = S' - nH' = E'_1 - (n+1)H',$$
 (C.3)

and, inverting (C.3),

$$H' = (E'_1 - E'_{n+1})/(n+1), \quad S' = E'_1 - H', \quad G' = E'_0.$$
 (C.4)

The above also applies to $|e^-\rangle$ provided that we replace S by V and set $H=h^-$.

Finally we introduce, above threshold, the reduced gluon and heavy quark pdfs, without the matching contribution from S

$$\tilde{G}' = G' - a_s^2 A_{gq} \otimes S$$
 and $\tilde{H}' = H' - a_s^2 A_{hq} \otimes S$. (C.5)

Now we are in a position to do the matching in terms of G, S, V and H.

a. Unpolarised with intrinsic heavy flavours at NNLO

We start with the matching of the gluon, singlet and heavy flavour $H = h^+$. Here the matching equations are given by

$$S' = (A_0 + a_s^2 A_{qq}) \otimes S \tag{C.6}$$

and

$$\begin{pmatrix} \tilde{G}' \\ \tilde{H}' \end{pmatrix} = \begin{pmatrix} A_0 + a_s^2 A_{gg} & a_s A_{gh} \\ a_s^2 A_{hg} & A_0 + a_s A_{hh} \end{pmatrix} \otimes \begin{pmatrix} G \\ H \end{pmatrix}. \tag{C.7}$$

Forward matching now proceeds as follows: First G and H are matched with (C.7). Then \tilde{G}' and \tilde{H}' are transformed to G' and H' using (C.5). Finally S is matched with (C.6).

Backward matching proceeds in reverse: First S is obtained from S' by solving (C.6) and \tilde{G}' and \tilde{H}' are computed from (C.5). Solving (C.7) then yields G and H.⁶⁰

The heavy quark component h^- does not receive a matching contribution from the gluon and the quarks so that we find for V and $H = h^-$ the equations

$$V' = (A_0 + a_s^2 A_{qq}) \otimes V \quad \text{and} \quad H' = (A_0 + a_s A_{hh}) \otimes H$$
 (C.8)

from which the forward and reverse matching of V and h^- are easily computed.

b. Unpolarised with intrinsic heavy flavours at NLO

In this case all terms proportional to a_s^2 vanish so that we get the $|e^+\rangle$ matching equations

$$S' = S$$
, $G' = G + a_s A_{gh} \otimes H$ and $H' = (A_0 + a_s A_{hh}) \otimes H$. (C.9)

It is easy to calculate the forward matching with (C.9) while for the reverse matching we solve the last equation in (C.9) for H and then compute $G = G' - a_{\rm s} A_{\rm gh} \otimes H$.

The $|e^{-}\rangle$ matching equations read the same as for $|e^{+}\rangle$,

$$V' = V$$
 and $H' = (A_0 + a_s A_{hh}) \otimes H$. (C.10)

c. Unpolarised with dynamic heavy flavours at NNLO

Here H=0 and the $|e^{+}\rangle$ matching equations for the gluon, singlet, and h^{+} reduce to

$$S' = (A_0 + a_s^2 A_{qq}) \otimes S, \quad \tilde{G}' = (A_0 + a_s^2 A_{gg}) \otimes G \quad \text{and} \quad \tilde{H}' = a_s^2 A_{hg} \otimes G. \quad (C.11)$$

For h^- there is no matching so that we have

$$V' = (A_0 + a_s^2 A_{qq}) \otimes V$$
 and $H' = H = 0$.

Again it is straight-forward to compute the forward matching while reverse matching does not occur: when QCDNUM crosses a threshold from above the corresponding heavy flavour is by definition intrinsic with a matching as given in subsection (a) or (b) above.

Notice that the matching discontinuities are entirely $O(a_s^2)$ and vanish at lower orders.

d. Time-like at NLO and beyond

In this case there is only one matching equation for h^+ , forward and reverse,

$$H' = H + a_s A_{hg} \otimes G$$
 and $H = H' - a_s A_{hg} \otimes G'$ with $G' = G$.

⁶⁰Directly solving (C.7) turns out to be numerically unstable. See Appendix D for a work-around.

D Triangular Systems in the DGLAP Evolution

For the non-singlet evolution we have to solve the equation (see Section 3.4)

$$\boldsymbol{Va} = \boldsymbol{b}.\tag{D.1}$$

The matrix V is a lower triangular Toeplitz matrix, that is, a matrix with the elements V_{ij} depending only on the difference i-j as is shown in the 4×4 example (3.15). This matrix is uniquely determined by storing the first column in a one-dimensional vector \mathbf{v} so that $V_{ij} = v_{i-j+1}$ for $i \geq j$, and zero otherwise. Eq. (D.1) is, like any other lower triangular system, iteratively solved by forward substitution

$$a_1 = b_1/v_1$$

$$a_i = \frac{1}{v_1} \left[b_i - \sum_{j=1}^{i-1} v_{(i-j+1)} \ a_j \right] \text{ for } i \ge 2.$$
(D.2)

There is no recursion relation between a_{i-1} and a_i so that in each iteration the sums must be accumulated, giving an operation count of n(n+1)/2 for a system of n equations. This is as expensive (or cheap) as multiplying the triangular matrix by a vector.

The substitution algorithm can be extended to solve the coupled singlet-gluon equation

$$\begin{pmatrix} V_{qq} & V_{qg} \\ V_{gq} & V_{gg} \end{pmatrix} \begin{pmatrix} f \\ g \end{pmatrix} \equiv \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} f \\ g \end{pmatrix} = \begin{pmatrix} r \\ s \end{pmatrix}, \tag{D.3}$$

where \boldsymbol{a} is a short-hand notation for $\boldsymbol{V}_{\rm qq}$, etc. These matrices are all lower triangular $n \times n$ Toeplitz matrices. Writing out this equation in components it is easy to see that for the first elements f_1 and g_1 we have to solve the 2×2 matrix equation

$$\begin{pmatrix} a_1 & b_1 \\ c_1 & d_1 \end{pmatrix} \begin{pmatrix} f_1 \\ g_1 \end{pmatrix} = \begin{pmatrix} r_1 \\ s_1 \end{pmatrix} \rightarrow \begin{pmatrix} f_1 \\ g_1 \end{pmatrix} = \frac{1}{D} \begin{pmatrix} d_1 & -b_1 \\ -c_1 & a_1 \end{pmatrix} \begin{pmatrix} r_1 \\ s_1 \end{pmatrix}$$
(D.4)

with the determinant $D = a_1d_1 - b_1c_1$. For $i \geq 2$ we have to accumulate the sums

$$R_{i} = r_{i} - \sum_{j=1}^{i-1} \left[a_{(i+1-j)} f_{j} + b_{(i+1-j)} g_{j} \right]$$

$$S_{i} = s_{i} - \sum_{j=1}^{i-1} \left[c_{(i+1-j)} f_{j} + d_{(i+1-j)} g_{j} \right]$$
(D.5)

and solve, for each i, the equations

$$\begin{pmatrix} a_1 & b_1 \\ c_1 & d_1 \end{pmatrix} \begin{pmatrix} f_i \\ g_i \end{pmatrix} = \begin{pmatrix} R_i \\ S_i \end{pmatrix} \tag{D.6}$$

The operation count of this algorithm is four times that of (D.2), plus some little overhead to solve the 2×2 matrix equations for each i. It is straight-forward to generalise the algorithm to $n \times n$ coupled equations (used by evdglap in Section 7.5).

D.1 Numerical stability

The equations (D.1) and (D.3) are routinely solved in the DGLAP evolution without any numerical problem. However, this does not mean that the substitution algorithm given above is *robust*. For instance, it is found that solving the matching equations (C.7) and (C.8) for H (see Appendix C) suffers from a spectacular exponential loss of precision in the forward substitution.

There is no easy way to predict when the substitution algorithm will break-down but in the case of reverse matching it is clearly related to the presence of the A_0 delta-function kernels; removing these does restore the numerical stability.

Because such numerical problems cannot be cured in the substitution algorithm itself,⁶¹ we resort to an iterative procedure. For this, write (C.7) in vector notation as

$$\tilde{\boldsymbol{F}}' = \boldsymbol{V} \otimes \boldsymbol{F} = \boldsymbol{F} + \boldsymbol{W} \otimes \boldsymbol{F} = \boldsymbol{F} + \boldsymbol{D},$$

where V is the 2×2 matrix of matching kernels in (C.7), and W is the same matrix without the A_0 kernels on the diagonal. In this notation the iteration algorithm reads

$$F = F'$$
; do n times { $D = W * F$; $F = F' - D$; }

Like most iterative un-foldings this procedure does not really converge so that we compute, after each step, the deviation $\Delta = \tilde{F}' - V \otimes F$ and stop when the norm $\|\Delta\|$ is at its minimum, usually after a few iterations.

⁶¹For instance promoting from double to quadruple precision has no effect. We have found that (C.7) can be solved by Gauss-Jordan elimination but this option is, at present, not followed-up in QCDNUM.

E Zero Mass Structure Functions

In this appendix we describe the formalism to compute zero-mass structure functions in un-polarised deep inelastic scattering. We refer to the write-up of the ZMSTF package for a description of the FORTRAN/C++ routines.

E.1 General Formalism

The zero-mass structure functions $F_2(x, Q^2)$, $F_L(x, Q^2)$ and $xF_3(x, Q^2)$ in un-polarised deep inelastic scattering are calculated from (3.21) with $\chi = x$. The Wilson coefficients are functions of x (and sometimes n_f) only. We set, for the moment, the physical scale Q^2 equal to the factorisation and renormalisation scale μ^2 and write the singlet/gluon contribution to F_2 and F_L as (there is no contribution to xF_3 since this structure function is a pure non-singlet)

$$\frac{1}{x}\mathcal{F}_i^{(s)}(x,Q^2) = [C_{i,s} \otimes q_s](x,\mu^2) + [C_{i,g} \otimes g](x,\mu^2) \qquad i = 2, L.$$
 (E.1)

Likewise, non-singlet contributions to the structure functions are given by

$$\frac{1}{r}\mathcal{F}_{i}^{(\text{ns})}(x,Q^{2}) = [C_{i,\text{ns}} \otimes q_{\text{ns}}](x,\mu^{2}) \qquad i = 2, L, 3$$
 (E.2)

where the label 'ns' stands for the non-singlet indices '+', '-' and 'v' as defined by (2.11). To be precise on notation: $\mathcal{F}_2 = F_2$, $\mathcal{F}_L = F_L$ and $\mathcal{F}_3 = xF_3$ in (E.1) and (E.2). A structure function is calculated by adding the singlet/gluon and non-singlet parts, weighted by the appropriate combination of electroweak couplings; we refer to [31] for how to compute neutral and charged current cross sections and structure functions in deep inelastic charged lepton and neutrino scattering.

Like the splitting functions, the coefficient functions are expanded in powers of α_s ,

$$C_{i,j}^{N^{\ell}LO} = \sum_{k=0}^{\ell} a_s^k C_{i,j}^{(k)} \qquad i = 2, L, 3 \qquad j = g, s, +, -, v$$
 (E.3)

where $\ell = (0, 1, 2)$ denotes (LO, NLO, NNLO) and $a_s = \alpha_s/2\pi$. The LO coefficient functions are either zero or trivial delta functions:

$$C_{2,g}^{(0)} = 0 C_{2,s}^{(0)} = \delta(1-x) C_{2,ns}^{(0)} = \delta(1-x)$$

$$C_{L,g}^{(0)} = 0 C_{L,s}^{(0)} = 0 C_{L,ns}^{(0)} = 0$$

$$C_{3,g}^{(0)} = 0 C_{3,s}^{(0)} = \delta(1-x).$$
(E.4)

The NLO coefficient functions can be found in [10]. For those at NNLO we refer to [33, 34, 35, 36] and the parameterisations given in [37] and [38].

The LO coefficient functions for $F_{\rm L}$ are zero so that the longitudinal structure function vanishes at LO. An alternative, which we call $F'_{\rm L}$, is calculated from the expansion

$$C_{\mathrm{L},j}^{\mathrm{N}^{\ell}\mathrm{LO}} = \sum_{k=1}^{\ell+1} a_{\mathrm{s}}^{k} C_{\mathrm{L},j}^{(k)}.$$
 (E.5)

In this way, $C_{L,j}^{(1)}$ is used already at LO (giving a non-zero F_L) and $C_{L,j}^{(2)}$ at NLO. At NNLO the 3-loop coefficient function $C_{L,j}^{(3)}$ is taken from [39]. As stated in [39], this 3-loop calculation applies only to electromagnetic current exchange so that Z^0 or W^{\pm} contributions to F'_L at NNLO are, at present, not available.

E.2 Renormalisation and Factorisation Scale Dependence

To calculate the renormalisation scale dependence ($\mu_{\rm R}^2 \neq \mu_{\rm F}^2$) we replace, in the expansion of the coefficient functions, the powers of $a_{\rm s}$ by the Taylor series given in (2.17). If the expansion (E.3) is used, the truncation of the right-hand side of (2.17) is to order $a_{\rm s}$ in NLO and $a_{\rm s}^2$ in NNLO. If, for $F_{\rm L}'$, the expansion (E.5) is used, the truncation is to order $a_{\rm s}$ in LO, $a_{\rm s}^2$ in NLO and $a_{\rm s}^3$ in NNLO, like for the splitting functions.

To calculate the factorisation scale dependence $(Q^2 \neq \mu_F^2)$, the coefficient functions in (E.3) and (E.5) are replaced by [37, 38]

$$C_{i,j}^{(0)} \to C_{i,j}^{(0)}$$
 and $C_{i,j}^{(k)} \to C_{i,j}^{(k)} + \sum_{m=1}^{k} C_{i,j}^{(k,m)} L_{\mathrm{F}}^{m}$ $k \ge 1$, (E.6)

where $L_{\rm F} = \ln(Q^2/\mu_{\rm F}^2)$ and $\mu_{\rm F}^2 = \mu_{\rm R}^2$. To write compact expressions for the $C_{i,j}^{(k,m)}$, we introduce the following vector notation. In the non-singlet sector we have a one-dimensional vector $\mathbf{C}_i = C_{i,\rm ns}$ and a 1×1 matrix $\mathbf{P} = P_{\rm ns}$. In the singlet/gluon sector we have a 2-dimensional row-vector and a 2×2 matrix that are given by

$$C_i = (C_{i,s} \ C_{i,g})$$
 and $P = \begin{pmatrix} P_{qq} & P_{qg} \\ P_{gq} & P_{gg} \end{pmatrix}$.

In this vector notation, the functions $C_{i,j}^{(k,m)}$ in (E.6) are written as

$$C_{i}^{(1,1)} = C_{i}^{(0)} \otimes P^{(0)}$$

$$C_{i}^{(2,1)} = C_{i}^{(0)} \otimes P^{(1)} + C_{i}^{(1)} \otimes \left[P^{(0)} - \beta_{0} I \right]$$

$$C_{i}^{(2,2)} = \frac{1}{2} C_{i}^{(1,1)} \otimes \left[P^{(0)} - \beta_{0} I \right]$$

$$C_{i}^{(3,1)} = C_{i}^{(0)} \otimes P^{(2)} + C_{i}^{(1)} \otimes \left[P^{(1)} - \beta_{1} I \right] + C_{i}^{(2)} \otimes \left[P^{(0)} - 2\beta_{0} I \right]$$

$$C_{i}^{(3,2)} = \frac{1}{2} \left\{ C_{i}^{(1,1)} \otimes \left[P^{(1)} - \beta_{1} I \right] + C_{i}^{(2,1)} \otimes \left[P^{(0)} - 2\beta_{0} I \right] \right\}$$

$$C_{i}^{(3,3)} = \frac{1}{3} C_{i}^{(2,2)} \otimes \left[P^{(0)} - 2\beta_{0} I \right]. \tag{E.7}$$

For F_2 , F_L and xF_3 , the coefficients are calculated up to $C_i^{(2,2)}$. For F'_L , on the other hand, all coefficients in (E.7) are computed. Note, however, that quite some convolutions are trivial because the LO coefficient functions are either zero or δ -functions, see (E.4).

As mentioned above, the expression (E.6) applies only when $\mu_{\rm F}^2 = \mu_{\rm R}^2$. It is therefore not possible to vary both scales $\mu_{\rm R}^2$ and Q^2 at the same time.

F Heavy Quark Structure Functions

In this appendix we describe the formalism to compute heavy quark contributions to structure functions in charged lepton-proton deep inelastic scattering. We refer to the write-up of the HQSTF package for a description of the FORTRAN/C++ routines.

F.1 General Formalism

A NLO calculation of the heavy quark contributions to the F_2 and F_L structure functions in deep inelastic charged lepton-proton scattering is given in [40]. Only electromagnetic exchange contributions are taken into account. In this calculation, a heavy flavour h is not taken to be a constituent of the incoming proton but is, instead, assumed to be exclusively produced in the hard scattering process. Quarks with pole mass $m < m_h$ are taken to be mass-less so that the input light quark densities should have been evolved in the FFNS with $n_f = (3, 4, 5)$ for h = (c, b, t) [41].

A heavy flavour contribution to F_2 or F_L is calculated from

$$F_k^h(x, Q^2) = \frac{\alpha_s}{2\pi} \left\{ e_h^2 g \otimes \mathcal{C}_{k,g}^{(0)} + \frac{\alpha_s}{2\pi} \left(e_h^2 g \otimes \mathcal{C}_{k,g}^{(1)} + e_h^2 q_s \otimes \mathcal{C}_{k,q}^{(1)} + q_p \otimes \mathcal{D}_{k,q}^{(1)} \right) \right\}, \quad (\text{F.1})$$

where e_h is the charge of the heavy quark (in units of the positron charge), g is the gluon density, q_s is the singlet density and

$$q_{\rm p} = \sum_{i=1}^{n_{\rm f}} e_i^2 (q_i + \bar{q}_i)$$

is the charge-weighted proton quark distribution for $n_{\rm f}$ light flavours. The first term in (F.1) is the LO contribution from the photon-gluon fusion process $\gamma^* g \to h\bar{h}$. The last three terms correspond to the NLO sub-process $\gamma^* g \to h\bar{h}g$ and $\gamma^* q \to h\bar{h}q$. For the heavy quark coefficient functions \mathcal{C} and \mathcal{D} in (F.1) we refer to [40].

In terms of a number density $f(x, \mu^2)$, the convolution integrals in (F.1) are defined by

$$f \otimes \mathcal{C} = \int_{ax}^{1} \frac{dz}{z} z f(z, \mu^2) \, \mathcal{C}(x/z, Q^2, \mu^2, m_h^2)$$
 (F.2)

where $a=1+4m_h^2/Q^2$ and μ^2 is the factorisation (equals renormalisation) scale which is usually set to $\mu^2=Q^2$ or $\mu^2=Q^2+4m_h^2$. The kinematic domain where the heavy quarks contribute is restricted by the requirement that the square of the γ^* p centre of mass energy must be sufficient to produce the $h\bar{h}$ pair: $W^2=M^2+Q^2(1-x)/x\geq M^2+4m_h^2$ so that the lower integration limit $ax\leq 1$ in (F.2). It turns out that the dependence of

 $^{^{62}}$ In the LO and the first two NLO terms the virtual photon couples to the heavy quark, hence the factor e_h^2 in (F.1). The last NLO term describes the process where the virtual photon couples to a light quark which subsequently branches into a $h\bar{h}$ pair via an intermediate gluon: hence the appearance of the charge weighted sum, $q_{\rm p}$, of light quark distributions.

⁶³Some of these coefficient functions are given as interpolation tables (taken from code provided by S. Riemersma) since they are too complex to be cast into analytic form. Note that in [40] the coefficient functions are convoluted with parton momentum densities and not with number densities [41].

the coefficient functions on the relation between Q^2 and μ^2 cannot be factorised so that each setting of the scale parameters needs its own set of weight tables. To calculate the renormalisation scale dependence, the powers of $a_{\rm s}=\alpha_{\rm s}/2\pi$ in (F.1) are replaced by the Fourier expansion (2.17), truncated to $a_{\rm s}$ in LO, and to $a_{\rm s}^2$ in NLO. Note that you can vary either $\mu_{\rm R}^2$ or Q^2 with respect to $\mu_{\rm F}^2$, but not both at the same time.

The convolution integral (F.2) is not of the general form (3.21): (i) the factor x in front is missing; (ii) the pdf is xf(x) and not f(x) and (iii) the argument of C is x/z and not χ/z . This mismatch is cured by presenting to QCDNUM the modified kernel

$$C_{\rm modified}(\chi,\mu^2,Q^2,m_h^2) \equiv \frac{a}{\chi} \; C_{\rm published}\left(\frac{\chi}{a},\mu^2,Q^2,m_h^2\right), \; {\rm with} \; \; \chi \equiv ax. \label{eq:C_modified}$$

G QCDNUM18 Releases and Updates

18-rr/uu dd-mm-yy - Description

18-00/00 08-03-22 – Initial release. Same as 17-01/15 except some minor fixes of compiler complaints. Added are the SPLINT package to create cubic spline interpolation functions and the WSTORE memory manager used in SPLINT and in future QCDNUM versions.

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