

STRENGTHENING RÖDL'S THEOREM

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Rödl's Theorem - General Situation and Statement

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Q. Let H be a fixed graph; what can we say about a graph G that does not contain H as an induced subgraph (H -free)?

EX: $K_{n,n}$ is H -free \rightarrow there are n^2 edges and $n(n-1)$ non-edges.
 \rightarrow This is a weakly independent set.

Def. G is a graph, $X \subseteq V(G)$ is:
 - weakly ϵ -restricted if $e(X) \leq \epsilon |X|^2$ or $e(G[X]) \geq (1-\epsilon) |X|^2$
 - ϵ -restricted if $\Delta(G[X]) \leq \epsilon |X|$ or $S(G[X]) \geq (1-\epsilon) |X|$

EX: $K_{n,n}$ is weakly $\frac{1}{n}$ -restricted but it is not $\frac{1}{n}$ -restricted.

LEM: X ϵ -restricted $\Rightarrow X$ weakly ϵ -restricted $\Leftrightarrow \exists X' \subseteq X, |X'| \geq \frac{|X|}{2}$ with X' ϵ -restricted.

So $e(G[X]) \leq \epsilon |X|^2$ and take $X' = \{x \in X \mid d_{G[X]}(x) \leq \epsilon |X|\}$. We have $|X'| \geq (1-\frac{\epsilon}{2}) |X|$.
 Then $\forall x \in X', d_{G[X]}(x) \leq \epsilon |X| \Rightarrow e(G[X]) \leq \frac{\epsilon}{2} |X|^2$

THM (Rödl) Let G be a H -free graph. We can find an (weakly) ϵ -restricted set $X \subseteq V(G)$

of size at least $|G|$.

($\forall H \exists \epsilon > 0 \exists \delta > 0 \forall G$ H -free...)

Lo If we want an ϵ -restricted set, let $\epsilon' = \frac{\epsilon}{2}$; we can apply the weak version of the theorem with ϵ' and then use the lemma.

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Rödl's Theorem - REMARKS

2

THM (Rödl) Let H be a graph and $\epsilon > 0$; there exists $\delta > 0$ such that every H -free graph G we can find an ϵ -restricted set $X \subseteq V(G)$ of size at least $\delta |G|$.

COR: Every H -free graph G can be partitioned into at most N weakly ϵ -restricted subsets. ($\forall H \forall \epsilon > 0 \exists N \dots$)

\rightarrow Apply Rödl's THM with $\frac{\epsilon}{N}$ repeatedly; then use the pigeon hole to take some of the largest vertices.

\rightarrow THM (CHUDNOVSKY) If G has $< \delta |G|^{1/N}$ induced copies of H , then we can find an equipartition of G into at most N weakly ϵ -restricted sets.

THM COR: Every H -free graph G can be partitioned into at most N ~~weakly~~ ϵ -restricted subsets. ($\forall H \forall \epsilon > 0 \exists N \dots$)

\rightarrow Some of the sets might ~~need~~ to be of cardinality 2.

EX: $K_{n,n}$ with $\epsilon = \frac{1}{n}$.

\rightarrow ϵ -restricted does NOT include $n(n-1)$ missing edges.

\rightarrow The proof does NOT use REGULARITY.

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Rödl's Theorem - PROOF AND CONSEQUENCES

1A

THM (Rödl) Let H be a graph and $\epsilon > 0$; there exists $\delta > 0$ such that in every H -free graph G we can find an (weakly) ϵ -restricted set $X \subseteq V(G)$ of size at least $\delta |G|$.

THM (Rödl) If G is large and if for every $X \subseteq V(G)$ with $|X| \geq \delta |G|$ we have $e(G[X]) \in [c|X|^2, (1+c)|X|^2]$, then G containing all the graphs with k vertices as induced subgraphs. $\forall k \in \mathbb{N}, \forall \epsilon > 0, \exists \delta > 0$

LEMMA If G large enough can be k -equi-partitioned so that all the pairs are ϵ -regular and with density in $(\frac{1}{k}, 1-\frac{1}{k})$.
 Then G containing induced copies of all graphs on k vertices. ($\forall k, \forall \epsilon, \exists \delta$)

\rightarrow REGULARITY lemma

and the REGULARITY lemma to find $R(n, \epsilon, k)$ depending in G , all pairs ϵ -regular.

(i) in T_1 if $d(C_1, C_2) \geq \frac{1}{2}$
 (ii) in T_2 if $d(C_1, C_2) \leq \frac{1}{2}$ ($\forall k, \forall \epsilon > 0$)
 (iii) in T_3 if $d(C_1, C_2) \geq \frac{1}{2}$

Since $R = R(n, \epsilon, k)$ we find $X \subseteq V(G)$ with $|X| \geq R$ and X is T_1 .

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Rödl's Theorem - PROOF AND CONSEQUENCES

1B

THM (Rödl) Let H be a graph and $\epsilon > 0$; there exists $\delta > 0$ such that every H -free graph G we can find an ϵ -restricted set $X \subseteq V(G)$ of size at least $\delta |G|$.

LEMMA Let H be a graph given $\epsilon, \epsilon_0 > 0$ define $\tilde{S}(G, \epsilon, \epsilon_0)$ as the largest S s.t. every H -free graph G has an induced graph of size $|S|$ with edge density at most ϵ , or at least $1-\epsilon_0$.

THM (Rödl) $\forall H, \forall \epsilon > 0, \exists \delta, \epsilon_0 > 0$

$\forall H, \forall \epsilon > 0, \exists \delta, \epsilon_0 > 0$ s.t. $2^{-O(\log(1/\epsilon))}$

LEMMA (Rödl, Nagel) Let $\epsilon > 0, \epsilon_0 > 0$ and let G be an H -free graph.

Then one $A \subseteq V(G)$ disjoint with $|A| \geq \delta |G|$ such that either every vertex in B has at most $\epsilon |A|$ neighbours in A or every vertex in B has at least $(1-\epsilon_0) |A|$ neighbours in A .

$H = K_2$

and $V_1, B_1, \dots, V_k, B_k$ in an equipartition being, let $V_i \cap B_j = \emptyset$ if $i \neq j$.

CASE 1 $\exists \epsilon > 0, \epsilon_0 > 0$ s.t. $\forall i, j, d(V_i, B_j) \leq \epsilon$ if $i \neq j$ and $d(V_i, B_i) \geq 1-\epsilon_0$

CASE 2 $\forall i \in [k], \exists \epsilon_i > 0$ s.t. $|V_i \cap B_j| \leq \epsilon_i |V_i|$ and $|V_i \cap B_i| \geq (1-\epsilon_i) |V_i|$

We can now take $A = B_1$ and $B = B_2 \cup \dots \cup B_k$ if we choose ϵ carefully.

LEMMA Let $\epsilon, \epsilon_0 > 0$ with $\epsilon, \epsilon_0 < 1$, and let G be an H -free graph. Let $n = |V(G)|$.

$\tilde{S}(G, \epsilon) \geq \left(\frac{\epsilon}{2}\right)^k n^k \min(\tilde{S}_1(G, \epsilon), \tilde{S}_k(G, \epsilon_0))$.

\rightarrow Apply the lemma with $\frac{\epsilon}{2}$ and get A, B .

\rightarrow Take $B \subseteq B$ with $|B| \geq \frac{n}{2}$ and edge density $\leq \frac{\epsilon}{2}$, or $\geq 1-\epsilon_0$.

\rightarrow Let $A_1 = V(A) \cap B_1$ and $A_2 = V(A) \cap B_2$. We get $|A_1| \geq |A|/2$.

\rightarrow Let $A \subseteq A_1$ with edge density $\leq \frac{\epsilon}{2}$, or $\geq 1-\epsilon_0$.

\rightarrow Consider $A \cup B$.

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GENERALIZATION Rödl's Theorem
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Rödl's Theorem - FUNDAMENTAL TOOL

THEM $\forall H, \forall \epsilon > 0 \exists N$ s.t. every H -free graph can be partitioned into at most N ϵ -restricted subsets.

DEF For $A, B \subseteq V(G)$ disjoint and $\epsilon > 0$, we say B is ϵ -sparse to A if every vertex in B has at most $\epsilon |A|$ neighbors in A ; it is ϵ -dense if it is ϵ -sparse in \bar{G} .

LEMMA (GROSS-NAJMAN) $\forall \epsilon > 0 \exists H, \exists \delta > 0$ s.t. $\exists A, B \subseteq V(G)$ with $|A|, |B| \geq \delta |V(G)|$ and B is ϵ -sparse in \bar{G} -dense to A .

PROOF For every graph H and $\epsilon, \delta > 0$ there exists N such that if G is H -free, then we can partition $V(G)$ into $A_1, \dots, A_N, B_1, \dots, B_N, C_1, \dots, C_N$ such that:

- $n \leq N \leq K |H|^2$
- A_1, \dots, A_N and C_1, \dots, C_N are ϵ -restricted,
- $\forall i, |B_i| \leq \delta |A_i|$,
- $\forall i, B_i$ is either δ -sparse in \bar{G} -dense to A_i .

GENERALIZATION: Rödl's Theorem
K. Naor, Alon, Frieze, S. J. Kim

Rödl's Theorem - PROPS AND CONSEQUENCES

THEM (Rödl) Let H be a graph and $\epsilon > 0$; there exists $\delta > 0$ such that every H -free graph G we can find an ϵ -restricted set $X \subseteq V(G)$ of size at least $\delta |G|$.

THEM (BOLEBOV, LARSEN, THORSSON) For every $K, \epsilon > 0$, $\mathbb{R}[X]$ has the Erdős-Rogers property.

LEMMA For $K \geq 2$ and $\epsilon > 0$ and G s.t. every induced subgraph G' satisfies one of the following:

- $\exists v \in V(G), d(v) \leq \epsilon n$,
- $\forall v \in V(G), G'$ contains an induced K -star with ϵn vertices (not necessarily induced).

\Rightarrow 1) Use Rödl and obtain a weakly ϵ -restricted set of size δn (using it is ϵ -stable).

2) Let S be s.t. $\Delta(G[S]) \leq K \epsilon n$ and $|S| \geq \delta n$.

3) We want to find ϵ s.t. G contains no induced K -star.

- If $G[S]$ has many small components we are done.
- Otherwise we can use the lemma.

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Rödl's Theorem - FUNDAMENTAL TOOL

THEM $\forall H, \forall \epsilon > 0 \exists N$ s.t. every H -free graph can be partitioned into at most N ϵ -restricted subsets.

PROOF For every graph H and $\epsilon, \delta > 0$ there exists N such that if G is H -free, then we can partition $V(G)$ into $A_1, \dots, A_N, B_1, \dots, B_N, C_1, \dots, C_N$ such that:

- $n \leq N \leq K |H|^2$
- A_1, \dots, A_N and C_1, \dots, C_N are ϵ -restricted,
- $\forall i, |B_i| \leq \delta |A_i|$,
- $\forall i, B_i$ is either δ -sparse in \bar{G} -dense to A_i .

LEMMA $\forall \epsilon > 0$ let B be ϵ -sparse to A . $\forall p \in [\frac{\epsilon}{2}, \frac{1}{2}]$ there is $P \subseteq A$ of cardinality p s.t. P is ϵ -sparse to B and B is $(2\epsilon - p)$ -sparse to P .

\Rightarrow Let $Q = \{v \in A, |N(v) \cap B| \leq \epsilon |B|, |Q| \geq \frac{1}{2} |A|\}$.

- Take ϵp vertices $\{a_1, \dots, a_{\epsilon p}\}$ indep. w.r.t. at random in Q .
- With positive probability $\{a_1, \dots, a_{\epsilon p}\} \cap P$ and $\forall v \in B, v$ does not have ϵp neighbors in $\{a_1, \dots, a_{\epsilon p}\}$.
- $(\forall v \in B, \epsilon v) \in E \cap \{I \subseteq \{a_1, \dots, a_{\epsilon p}\} : |I| \leq \epsilon p \text{ and } N(v) \cap I \neq \emptyset\} \leq \frac{1}{2} |Q|$.

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Rödl's Theorem - FUNDAMENTAL TOOL

THEM $\forall H, \forall \epsilon > 0 \exists N$ s.t. every H -free graph can be partitioned into at most N ϵ -restricted subsets.

PROOF For every graph H and $\epsilon, \delta > 0$ there exists N such that if G is H -free, then we can partition $V(G)$ into $A_1, \dots, A_N, B_1, \dots, B_N, C_1, \dots, C_N$ such that:

- $n \leq N \leq K |H|^2$
- A_1, \dots, A_N and C_1, \dots, C_N are ϵ -restricted,
- $\forall i, |B_i| \leq \delta |A_i|$,
- $\forall i, B_i$ is either δ -sparse in \bar{G} -dense to A_i .

LEMMA $\forall \epsilon > 0$ let B be ϵ -sparse to A . $\forall p \in [\frac{\epsilon}{2}, \frac{1}{2}]$ there is $P \subseteq A$ of cardinality p s.t. P is ϵ -sparse to B and B is $(2\epsilon - p)$ -sparse to P .

DEF Let G be a graph, $K \in \mathbb{N}$ and $\epsilon > 0$. A (K, ϵ) -PARTITION of G is a partition (W_1, W_2, \dots, W_n) such that $\forall i \in [1, n]$ we have:

- W_i is ϵ -restricted
- $|W_1 \cup \dots \cup W_i| \leq \epsilon |V(G)|$
- $\forall u \in W_i, \dots, W_n$ is either $\frac{\epsilon}{K}$ -sparse in \bar{G} -dense to W_i .

LEMMA Let $\epsilon > 0$; if G admits a $(\frac{1}{K}, \epsilon)$ -PARTITION then G can be partitioned into $1000 \epsilon^2$ ϵ -restricted subsets.

\Rightarrow For $i \in [1, K]$ we find $C_i \subseteq W_i$ s.t.

- $|C_i| \geq |W_i|$
- Either C_i is ϵ -sparse to $C_1 \cup \dots \cup C_{i-1}$ and $C_1 \cup \dots \cup C_{i-1}$ is ϵ -dense to C_i or C_i is ϵ -dense to $C_1 \cup \dots \cup C_{i-1}$ and $C_1 \cup \dots \cup C_{i-1}$ is ϵ -sparse to C_i .

\Rightarrow We find C_1, C_2, \dots, C_n . Assume we have C_1, \dots, C_{i-1} ; then we can use the lemma to find C_i since $C_1, \dots, C_{i-1} \cup C_n$ belongs well to W_i .

\Rightarrow Select $I \subseteq [1, K]$ s.t. C_i is always ϵ -sparse or always ϵ -dense to C_1, \dots, C_n .

Let $C = \bigcup_{i \in I} C_i$. Then C is ϵ -restricted.

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Rödl's Theorem - FUNDAMENTAL TOOL

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THM $\forall H, \forall \epsilon > 0 \exists N$ s.t. every H -free graph can be partitioned into at most N ϵ -regular subgraphs.

LEM For every graph H and $\epsilon, \eta, \delta > 0$ there exists N such that if G is H -free, then we can partition $V(G)$ into

- $A_1, \dots, A_k; B_1, \dots, B_r; C_1, \dots, C_m$ such that:
- $n \leq N; |A_i| \leq \eta n$
 - A_1, \dots, A_k and C_1, \dots, C_m are ϵ -regular,
 - $\forall i, |B_i| \leq \eta |A_i|$,
 - $\forall i, B_i$ is either δ -sparse or δ -dense to A_i .



LEM $\forall \epsilon > 0$ let B be ϵ -sparse to A . $\forall p \in [\frac{\epsilon}{2}, \frac{1-\epsilon}{2}]$ there is $P \subseteq A$ of cardinality $p|A|$.

P is ϵ -sparse to B and B is $(1-\epsilon)$ -sparse to P .

DEF Let G be a graph, $k \in \mathbb{N}$ and $\epsilon > 0$. A (k, ϵ, η) -PATH-PARTITION of G is a partition (W_0, W_1, \dots, W_k)

- such that $\forall i \in \{1, \dots, k\}$ we have:
- W_i is ϵ -regular,
 - $|W_0|, \dots, |W_k| \leq \eta |V(G)|$,
 - $W_0 \cup \dots \cup W_k$ is either $\frac{\epsilon}{2}$ -sparse or $\frac{\epsilon}{2}$ -dense to W_i .

LEM Let $\epsilon > 0$ and H be fixed. If G is an H -free graph that admits a $(k, \frac{\epsilon}{2}, \frac{1}{256k\eta})$ -path partition with $k \leq \frac{1}{\epsilon}$, then $V(G)$ can be partitioned into $O(\frac{1}{\epsilon})$ ϵ -regular subgraphs.

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STERNBERG RÖDL'S THEOREM
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