

# Learned versus Hand-Designed Feature Representations for 3d Agglomeration

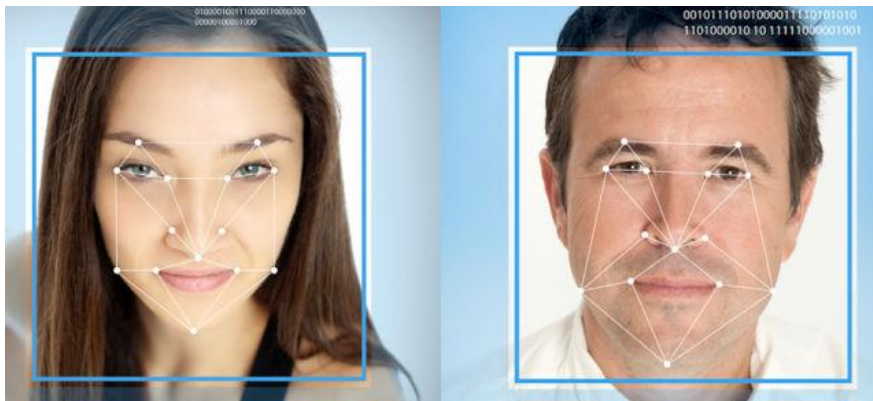
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As presented by Mary Yen



# Terms

- **Machine learning** is a set of algorithms that classify data input.
  - eg: We want to know whether a set of facial images are male or female.
- Algorithms train **classifiers** on a **training set** to identify data input. Classifiers need **quantifiable** data to work. Can test classifier's effectiveness on **testing set**.
  - eg: Assign numerical values to facial shape by edge curvature. Classifiers can identify whether a facial image is male or female depending on whether the image's edge values are closer to male or female edge values.

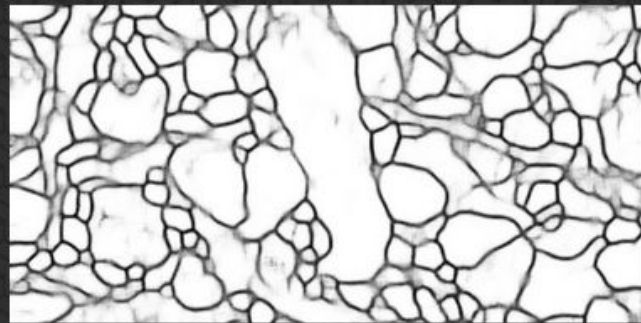
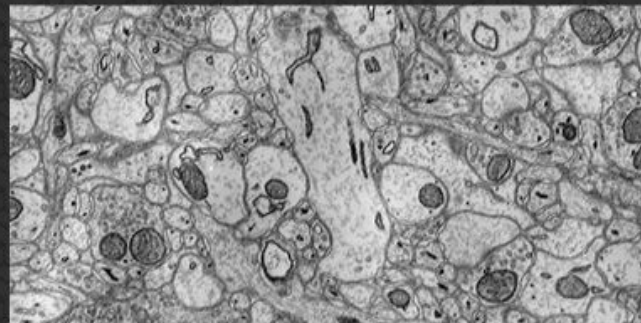


# Opportunity

- Automatic machine learning methods may be more efficient than manually specified methods.
  - Doesn't require domain expertise
  - potentially yields a much larger set of features for a classifier.
  - May find algorithms or features that are more finely tuned for the particular problem and thus lead to improved accuracy.
  - can be easily adapted to new types of data
- Is purely automatic or hand designed better? Is there a balance between the two?

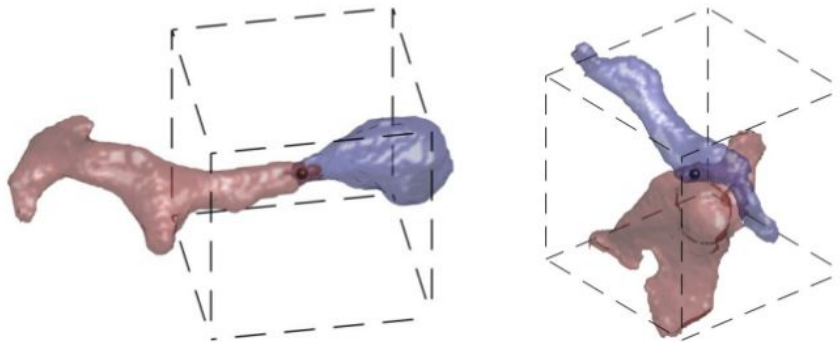
# Challenge

- Specifying 3D features seems easier than using hand-designed representations for more low-level data (such as raw image patches).
- describing a neuron fragment in terms of quantities such as curvature, volume, and orientation seems natural.
- Can easily use this data in learning algorithms whereas hand-designed data takes longer to collect & needs to be quantified.



# Challenge

- Is this intuitive appeal is a good justification for feature representation in specific tasks such as neuron fragment agglomeration?



- Intuitively makes sense, but is it effective in practice?

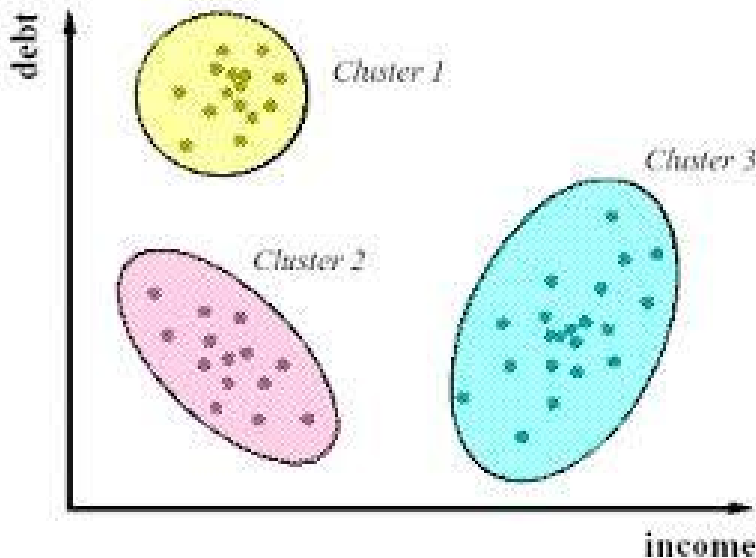
# Action

Compared the performance of the following:

1. A large set of diverse hand-designed 3d shape descriptors.
2. An end-to-end supervised learning approach for deriving 3d feature descriptors.
3. An unsupervised learning approach for deriving 3d feature descriptors.

# Supervised vs. Unsupervised Learning

- **supervised:** examples must be *labeled*
  - You tell the algorithm which faces are female or male
- **unsupervised:** examples are *unlabeled*
  - You hand algorithm faces but don't tell which faces are male or female
  - Algorithm will plot features about input and look at what features cluster together to classify data

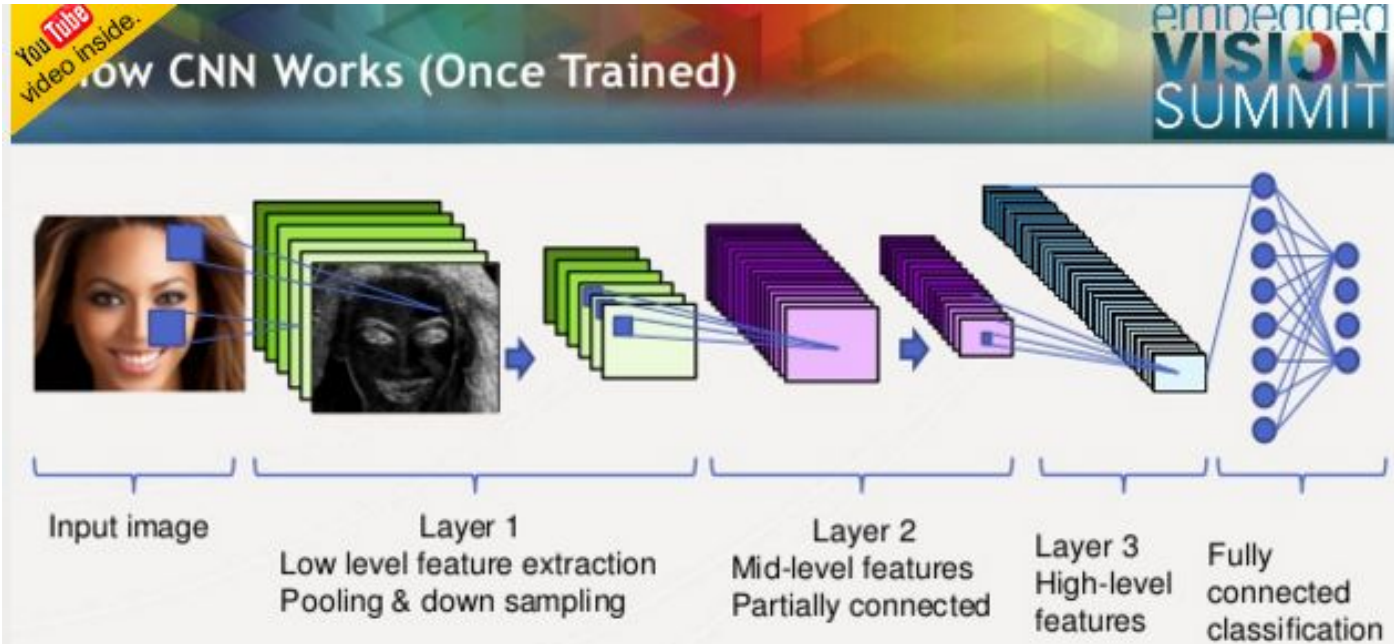


# Supervised Learning

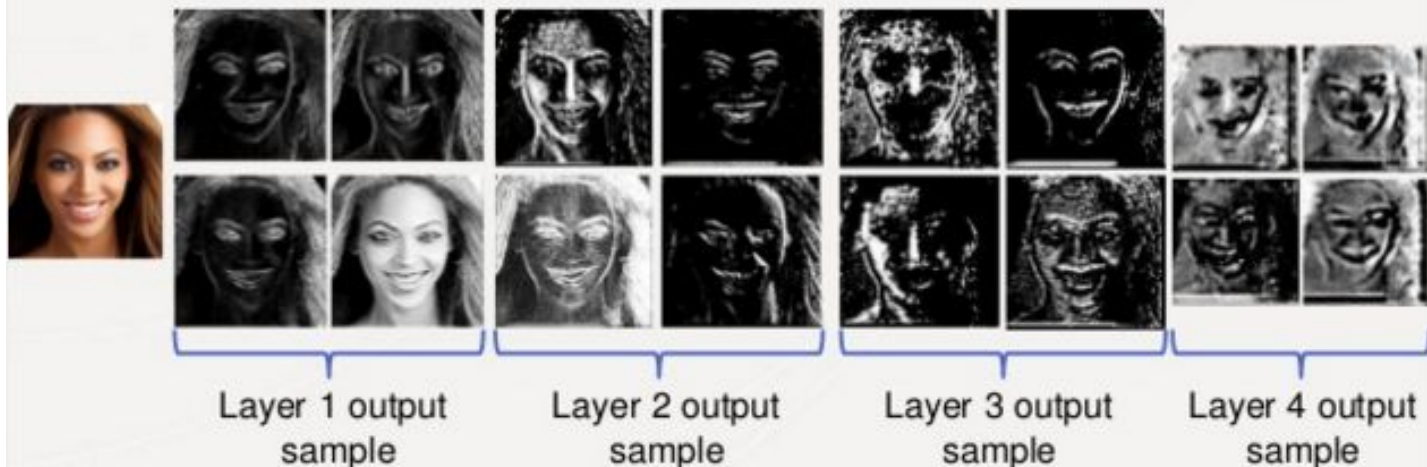
- End-to-End Learning
- Algorithm derives its own features from the labeled data
- Requires no hand-designed features
- provide the raw input signal values to the classifier
- Used convolutional neural network



# convolutional neural network



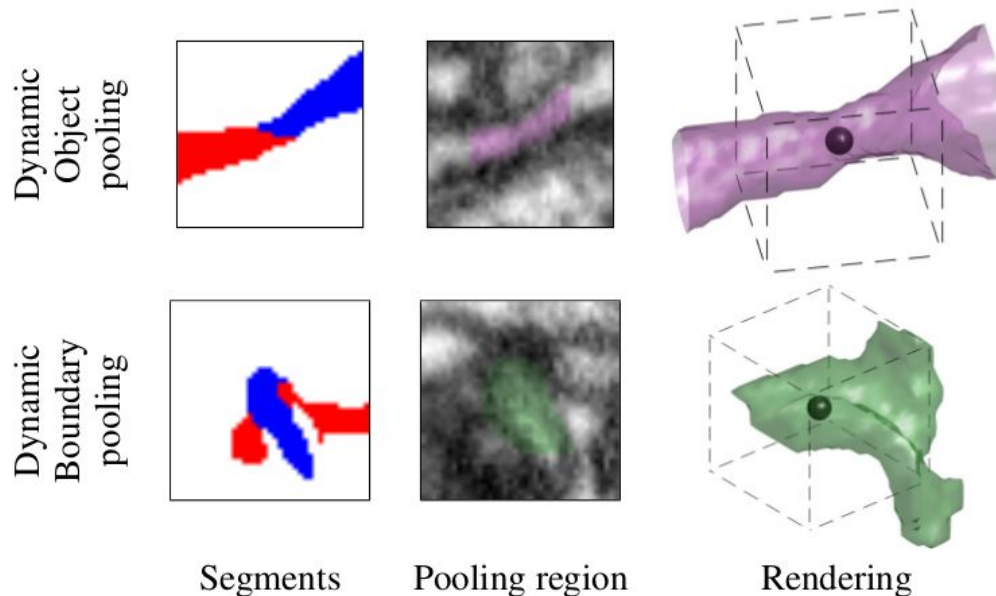
- Multiple feature extraction layers
  - Progressive refinement process
  - Each successive layer extracts more complex features (higher level)
- Last layer performs classification
- Same computation (neuron) replicated multiple times



- Each layer of convolutions extract progressively higher level features
  - Subsampling / max pooling to “zoom out” and detect bigger objects with smaller convolutions
  - Non-linear function on each neuron to activate it

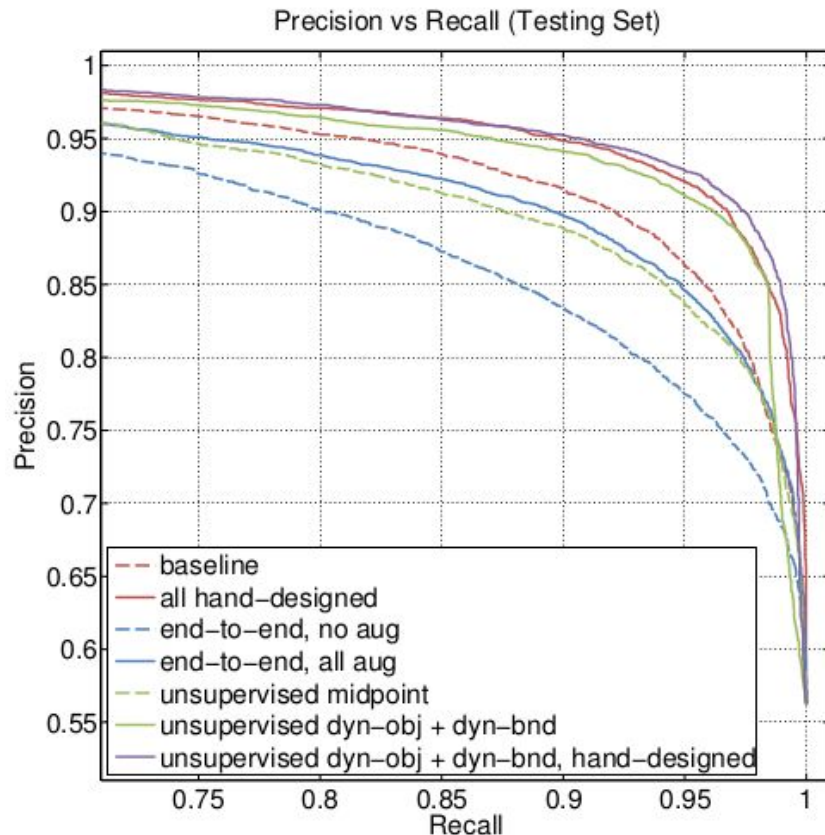
# Unsupervised Learning

- Similar CNN technique as supervised learning
- **dynamic pooling:** the region to pool over is dependent on the segments themselves.
  - we can restrict the average pooling to be over only features corresponding to locations in either of the two segments
  - improves accuracy by eliminating unneeded data



# Resolution

- unsupervised learning, when combined with a novel dynamic pooling scheme, yields performance comparable to an ensemble set of all hand-designed features.
- To our knowledge, this is the first time purely learned features have been shown to provide competitive performance on a task involving analysis or classification of 3d shapes
- Substantial improvement in performance results as the feature set increases from a simple set of 6 features derived from boundary map values to the combined set of all hand-designed features



# Future

- Found methods that can act as starting points for future feature learning methods
- a more sophisticated end-to-end strategy
- dynamic pooling
  - optimize pool sampling