Heuristics

- 0 heuristic \triangleq UCS
- Heuristics can be a max of multiple heuristics

Graph Search

- Tree search expands out all states including repeats but graph search does not
- Tree search but never expand a state twice
 - Make a list of things we've seen before
- Not always optimal (with inconsistent h(x))

Consistency

- You must underestimate the cost of every action
- $h(A) h(B) \le cost(A, B)$
- Consistency \Longrightarrow admissibility

Constraint Satisfaction Problems (CSPs)

- Identification problem \triangleq the goal is important, not the path
- Subset of search problems
- State defined by $X := \{X_i \ \forall i\}$ with values from a domain D
 - -D is sometimes dependent on i
- Goal test is a set of constraints specifying allowable combinations of values for subsets of variables
- eg: Coloring of states in Australia
 - Variables $\triangleq \{WA, NT, Q, NSW, V, SA, T\}$
 - $-D := \{\text{red}, \text{gren}, \text{blue}\}$
 - Constraints:
 - * Implicit: WA \neq NT
 - * Explicit: $(WA, NT) \in \{(red, green), (red, blue), ...\}$
 - Solutions $\triangleq \{WA \triangleq red, NT \triangleq green, Q \triangleq red, NSW \triangleq green, V \triangleq red, SA \triangleq blue, T \triangleq green\}$
- eg2: Queens chess
 - Variables $\triangleq \{X_{ij} \forall \{i,j\} \in N\}$
 - $-D := \{0, 1\}$
 - Constraints:

$$\begin{cases} (X_{ij}, X_{ik}) \\ (X_{ij}, X_{kj}) \\ (X_{ij}, X_{(i+k)(j+k)}) \\ (X_{ij}, X_{(i+k)(j-k)}) \end{cases} \quad \left| \begin{cases} i, j, k \end{cases} \in N \right\} \in \left\{ (0, 0), (0, 1), (1, 0) \right\} \\ \sum_{i,j} X_{ij} = N \end{cases}$$

- Better approach:
- Variables $\triangleq \{Q_k \forall k \in N\}$
- D := 1, 2, 3, ..., N
- Constraints $\triangleq \forall i, j \mid Q_i \text{ doesnt threaten } Q_j$

Constraint Graph

- Graph where edges are constraints and nodes are the variables
- We make intermediary nodes (depicted as squares) if a constraint applies to multiple nodes
 - The square then becomes the constraint

Solving

- CSVs are a type of search problem, so can use search functions
 - Generally not efficient because there isn't a concept of the rules
- \bullet Backtracking Search
 - Type of DFS
 - Evaluate one variable at a time (fixed ordering)
 - * Tree expands only possible evaluations of one variable instead of all possibilities of all variables
 - Check constraints as you go (consider only values which do not conflict with previous assignments)

Filtering

- Filtering := keep track of domains for unassigned variables and cross off bad options
- Forward checking := cross off values that violate a constraint when added to the existing assignment
- Reason about consequences of actions