

Approximate Inference Queries

Sampling

- A lot like repeated simulation
- Basic Idea
 1. Draw N samples from a sampling distribution S
 2. Compute an approximate posterior probability
 3. Show this converges to the true probability P

Sampling from a Given Distribution

1. Get sample u from uniform distribution over $[0, 1)$ (use PRNG or something)
2. Convert this sample u into an outcome for the given distribution by having each target outcome associated with a sub-interval of $[0, 1)$ with sub-interval size equal to probability of the outcome

C	P(C)
red	0.6
green	0.1
blue	0.3

$$\begin{aligned}0 \leq u < 0.6, &\rightarrow C = \text{red} \\0.6 \leq u < 0.7, &\rightarrow C = \text{green} \\0.7 \leq u < 1, &\rightarrow C = \text{blue}\end{aligned}$$

- eg:

Prior Sampling

- Sample topologically in order of bayes net
- All sub-samples taken given the parents
- Return $(x_1, x_2, \dots, x_n) \mid x_i := \text{sample}(x_i, \mathbb{P}(X_i \mid \text{parents}(X_i)))$
- Generates samples with probability $S_{PS}(x_1, \dots, x_n) = \prod_{i=1}^n \mathbb{P}(x_i \mid \text{parents}(X_i))$
 - Same as $\mathbb{P}(x_1, \dots, x_n)$
 - The probability of a sample is equal to the probability of the sample in the joint distribution
- $$\lim_{n \rightarrow \infty} \hat{P}(x_1, \dots, x_n) = \frac{\lim_{n \rightarrow \infty} N_{PS}(x_1, \dots, x_n)}{N} = S_{PS}(x_1, \dots, x_n) = \mathbb{P}(x_1, \dots, x_n)$$
 - $N_{PS} :=$ number of samples of an event
 - Basically as your samples increase, you get more accurate
- Consistent := the samples match the frequencies in the joint distribution
- To get the probability from the samples, you normalize the counts for the variable you're looking for
- Good because you can estimate any probability in the BN given the samples
- Good because you can choose the amount of samples you want to take
- If you don't have any samples for something, you don't know what it is and need more samples (no answer)
 - Bad if evidence is rare

Rejection Sampling

- Like prior sampling
- Just keep a count of the amount of times things show up
 - Means you don't have to maintain a long list of samples

- If there is a given (evidence provided) and the sample does not fulfill the evidence, then ignore the sample and do not add it to the counts
- Bad if evidence is rare
- Consistent

Likelihood Weighting

- Fix evidence variables and sample the rest
- Problem: sample distribution is not consistent
- Solution: weight by probability of evidence given parents
 - Each sample also has a weight
 - Weight is initially 1 and then multiplied by the weights of the fixed variables in the sample
- Sample Values:

$$S_{WS}(z, e) := \prod_{i=1}^l \mathbb{P}(z_i \mid \text{parents}(Z_i)) \left| \begin{array}{l} z := \text{sampled values} \\ e := \text{evidence values fixed} \\ l := \text{number of samples retained} \end{array} \right.$$

- Sample weights:

$$w(z, e) := \prod_{i=1}^m \mathbb{P}(e_i \mid \text{parents}(E_i)) \left| \begin{array}{l} m := \text{number of samples 'rigged'} \end{array} \right.$$

- Weighted sampling distribution is consistent:

$$S_{WS}(z, e) * w(z, e) = \prod_{i=1}^l \mathbb{P}(z_i \mid \text{parents}(z_i)) \prod_{i=1}^m \mathbb{P}(e_i \mid \text{parents}(e_i))$$

- Good when evidence is at the top of the BN
 - Generally lower weight the further ‘downstream’ something is in a BN
 - Evidence influences the choice of downstream variables, but not upstream ones

Gibbs Sampling

- Mostly not required to know
- Keep track of a full instantiation of x_1, x_2, \dots, x_n . Start with an arbitrary instantiation consistent with the evidence. Sample one variable at a time, conditioned on all the rest, but keep evidence fixed. Keep repeating this for a long time.
- In the limit of repeating this infinitely many times, the resulting samples come from the correct distribution
- Both upstream and downstream variables condition on evidence
 - Have to compute the cost of all non-fixed elements conditioned on every other element
 - * Note: Only need to consider CPTs with S remain

■ Sample from $P(S \mid +c, +r, -w)$

$$\begin{aligned}
 P(S \mid +c, +r, -w) &= \frac{P(S, +c, +r, -w)}{P(+c, +r, -w)} && \text{def. of conditional probability} \\
 &= \frac{P(S, +c, +r, -w)}{\sum_s P(s, +c, +r, -w)} && \text{introduce summation} \\
 &= \frac{P(+c)P(S \mid +c)P(+r \mid +c)P(-w \mid S, +r)}{\sum_s P(+c)P(s \mid +c)P(+r \mid +c)P(-w \mid s, +r)} && \text{def. of Bayes' Nets} \\
 &= \frac{P(+c)P(S \mid +c)P(+r \mid +c)P(-w \mid S, +r)}{P(+c)P(+r \mid +c) \sum_s P(s \mid +c)P(-w \mid s, +r)} && \text{move summation term out} \\
 &= \frac{P(S \mid +c)P(-w \mid S, +r)}{\sum_s P(s \mid +c)P(-w \mid s, +r)} && \text{cancel out terms}
 \end{aligned}$$

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