

$$\frac{\pi}{4} \cdot .5^2 \times .5 = .0982 \text{ in}^3$$

@ 50%

$$= .0491 \text{ in}^3$$

$$8.03E-7 \text{ m}^3$$

$$.25 \times .5 \times .25 = .03125 \text{ in}^3$$

$$4.5 \times .25 \times .5 = .5625 \text{ in}^3$$

$$.75 \times .5 \times .25 = .09375 \text{ in}^3$$

$$\text{Total} = .6875 \text{ in}^3$$

@ 50% infl.

$$= .34375 \text{ in}^3$$

$$5.6E-6 \text{ m}^3$$

Pinion

$$\rho = 1.24 \text{ g/cm}^3 = 1240 \text{ kg/m}^3$$

$$m_p = 8.03E-7 \text{ m}^3 \times 1240$$

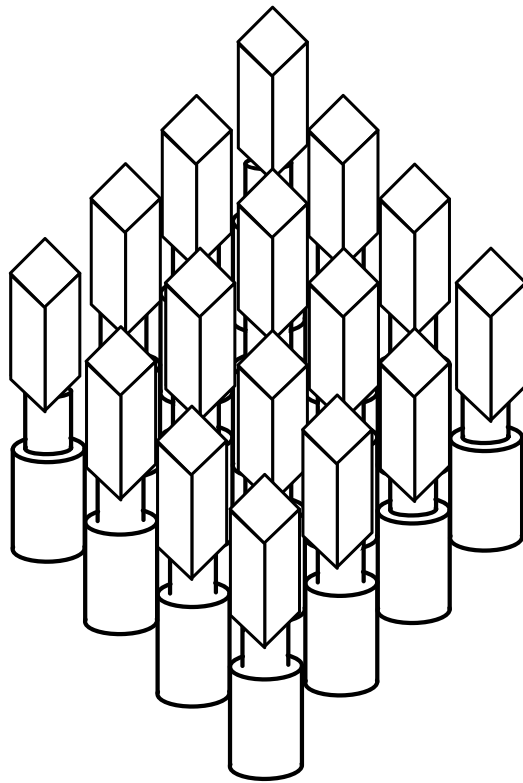
$$m_p = .001 \text{ kg}$$

Rack

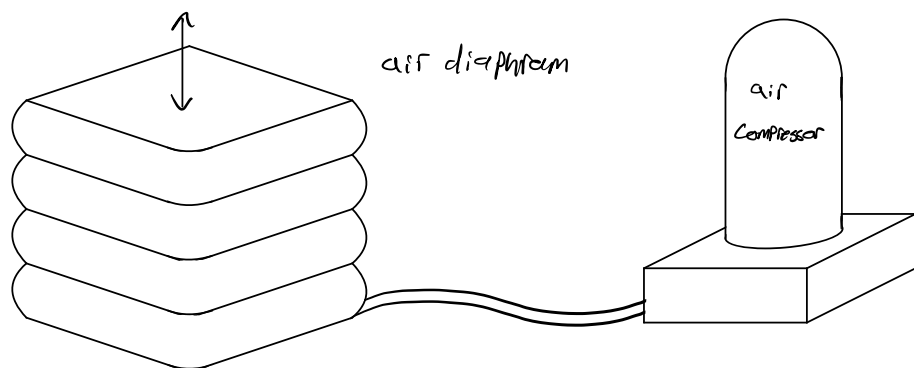
$$m_r = 5.6E-6 \text{ m}^3 \times 1240 \text{ kg/m}^3$$

$$m_r = .0069 \text{ kg}$$

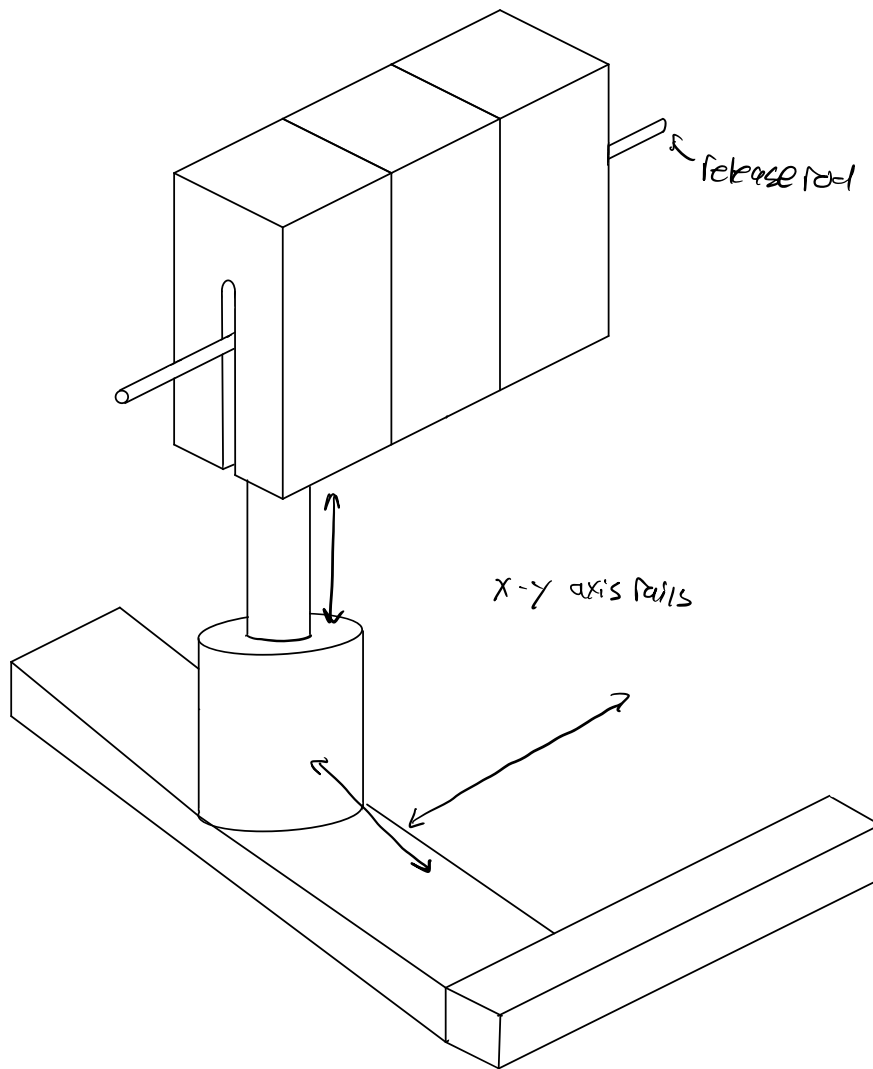
Individual Control



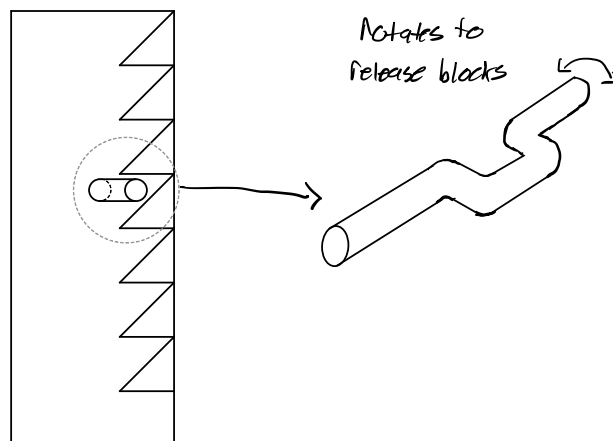
Pneumatic



linear actuator w/ ratchet



Teeth inside blocks



Screw design

