

```
function [J] = doubleSimpson(a, b, m, n, c, d, f)
```

```
    syms x y
```

```
    c(x) = c;
```

```
    d(x) = d;
```

```
    f(x, y) = f;
```

```
    h = (b - a)/n;
```

```
    J1 = 0;
```

```
    J2 = 0;
```

```
    J3 = 0;
```

```
    for i = 0:n
```

```
        x = a + i*h;
```

```
        HX = (d(x)-c(x))/m;
```

```
        K1 = f(x, c(x)) + f(x, d(x));
```

```
        K2 = 0;
```

```
        K3 = 0;
```

```
        for j = 1:m-1
```

```
            y = c(x) + j*HX;
```

```
            Q = f(x, y);
```

```
            if (mod(j, 2) == 0)
```

```
                K2 = K2 + Q;
```

```
            elseif (mod(j, 2) == 1)
```

```
                K3 = K3 + Q;
```

```
            end
```

```
        end
```

```
        L = (K1 + 2*K2 + 4*K3)*HX/3;
```

```
        if (i == 0 || i == n)
```

```
            J1 = J1 + L;
```

```
        elseif (mod(i, 2) == 0)
```

```
            J2 = J2 + L;
```

```
        else
```

```
            J3 = J3 + L;
```

```
        end
```

```
    end
```

```
    J = h*(J1 + 2*J2 + 4*J3)/3;
```

```
end
```