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Below is the definition of the init_timer function I used for configuring the hardware timer. Since its frequency is 25 MHz, I scaled it by 25 000 in order to increment the TC register at a rate of 1000 Hz. This means that the value in MRO corresponds to the desired period of timer interrupts, in milliseconds. When the bottom 2 bits of MCR are set to 1, an interrupt will be generated when the value in the TC register reaches the value stored in MRO, and then the TC register will be reset. To start the timer, I set the TCR's reset and enable bits accordingly in start_timer.

```
void init_timer(int period_ms)
{
    LPC_TIMO->PR = 25000;
    LPC_TIMO->MRO = period_ms;
    LPC_TIMO->MCR = 0x03;
}
```

To enable interrupts for the INTO button, I enabled general-purpose I/O for P2.10 and subsequently configured it for input. Then, I set the appropriate bit of IO2IntEnF to 1 so that interrupts would be fired on the falling edge of the INTO signal. Finally, I enabled interrupts for EINTO on the interrupt controller.

```
void init_int0(void)
{
    LPC_PINCON->PINSEL4 &= ~(3 << 20);
    LPC_GPIO2->FIODIR &= ~(1 << 10);

    LPC_GPIOINT->IO2IntEnF |= (1 << 10);
    NVIC_EnableIRQ(EINT3_IRQn);
}</pre>
```

To configure the LEDs, I set the appropriate GPIO direction bits for output and cleared the output pins.

```
void init_led(void)
{
    LPC_GPIO1->FIODIR |= 0xb0000000;
    LPC_GPIO2->FIODIR |= 0x0000007c;

    LPC_GPIO1->FIOCLR |= ~(0x0);
    LPC_GPIO2->FIOCLR |= ~(0x0);
}
```

To implement strict interrupt scheduling, I disabled EINT3 interrupts and fired a one-shot timer whenever the INTO button was pressed:

```
void EINT3_IRQHandler(void)
{
    LPC_GPIOINT->IO2IntClr |= (1 << 10);
    NVIC_DisableIRQ(EINT3_IRQn);
    flash_message();
    start_timer();
}</pre>
```

When the timer interrupt is received after 5 seconds, I re-enable EINT3 interrupts and disable timer interrupts:

```
void TIMER0_IRQHandler(void)
{
    LPC_TIM0->IR = 0x01; // clear interrupt
    NVIC_DisableIRQ(TIMER0_IRQn);
    NVIC_EnableIRQ(EINT3_IRQn);
}
```

For the bursty scheduler, I followed similar steps, except I only disabled EINT3 interrupts when a counter variable reached a value of 3. Additionally, I used an asynchronous timer to periodically reset this counter and re-enable EINT3 interrupts every 10 seconds.