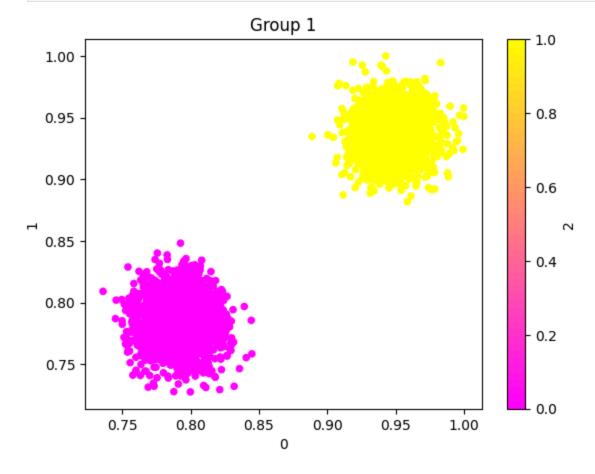
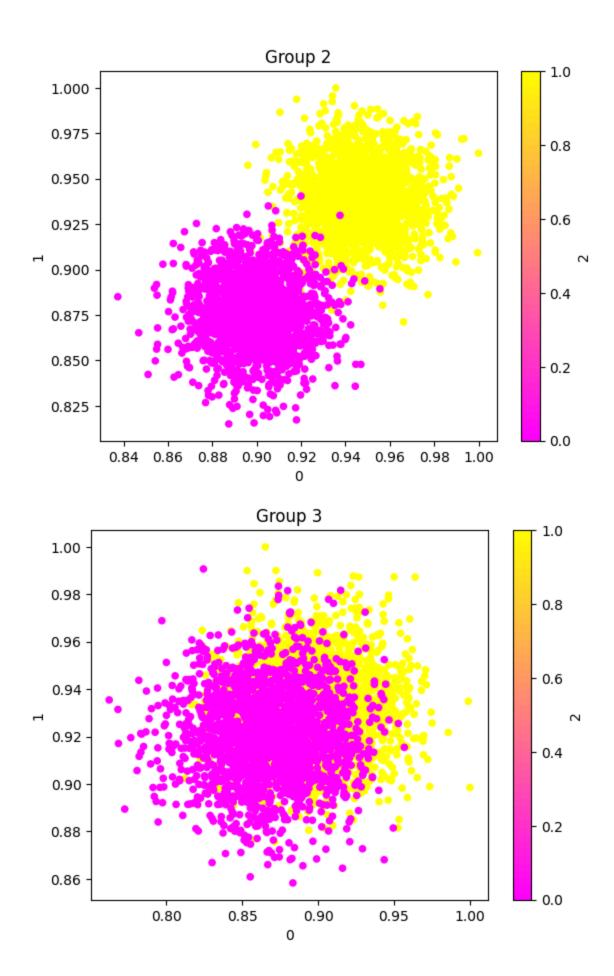
```
In []: import numpy as np
    import pandas as pd
    from matplotlib import pyplot as plt
    # I'm just using this library function to make the matrix look nice, all calculatio
    from sklearn.metrics import ConfusionMatrixDisplay
In []: # download all of the datasets into a list of dataframes

group names = ['groupA', 'groupB', '
```

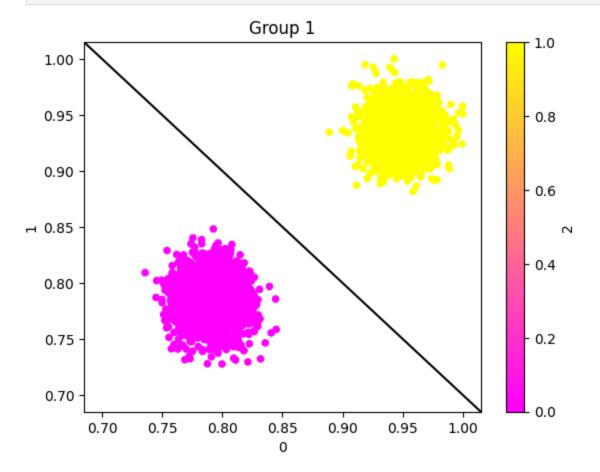
```
In []: # download all of the datasets into a list of dataframes
group_names = ['groupA', 'groupB', 'groupC']
datasets = []
for name in group_names:
    datasets.append(pd.read_csv(f"./Project1_Data/{name}.txt", header=None))
    # normalize each column 0 and 1
    for i in range(2):
        datasets[-1][i] = datasets[-1][i]/max(datasets[-1][i])
```

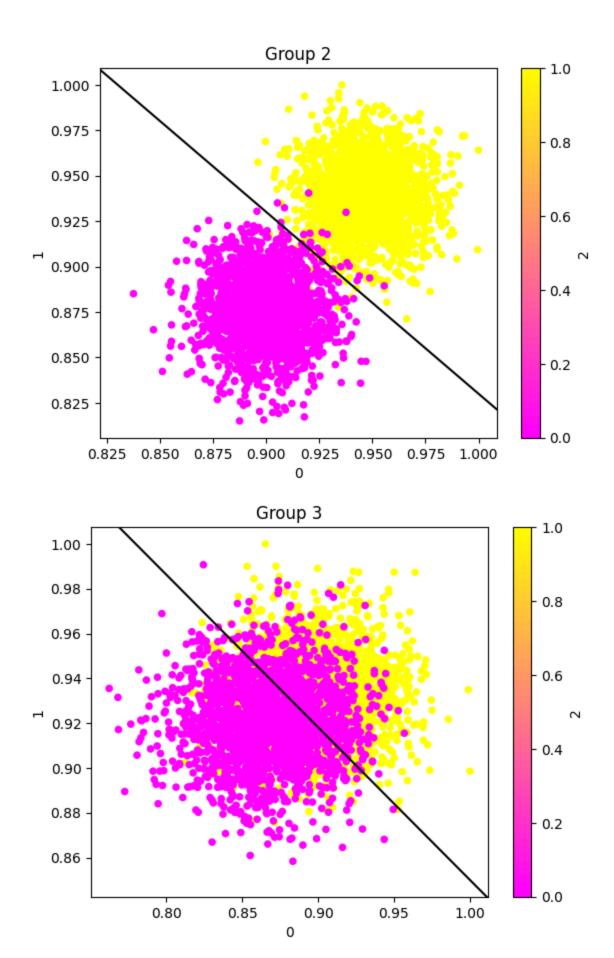
```
In [ ]: # plot all 3 datasets
for i in range(3):
    datasets[i].plot.scatter(x=0, y=1, c=2, cmap="spring")
    plt.title(f"Group {i+1}")
    plt.savefig(f"group{i+1}_vis.png")
```



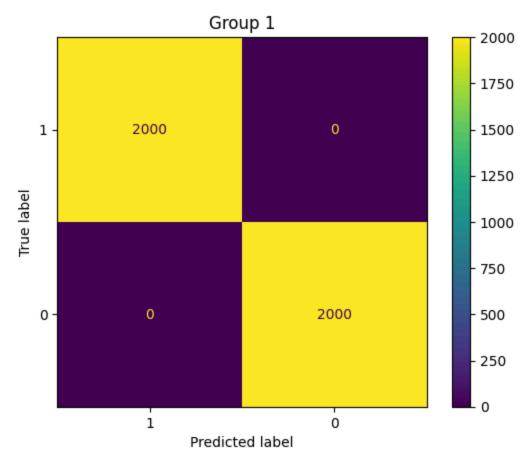


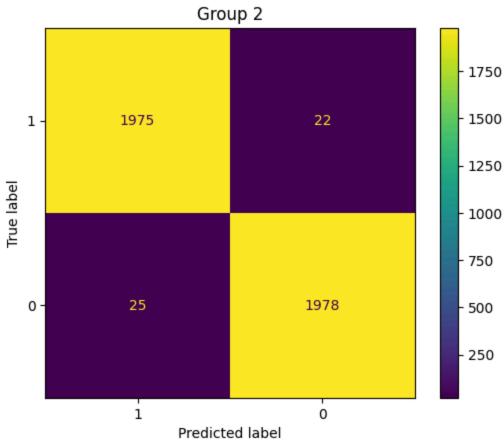
```
In [ ]: # the 2 points that define these lines (I came up with these points by eyeballing t
    pointsx1 = [1,1,1]
    pointsy1 = [0.7,0.83,0.85]
    pointsx2 = [0.7,0.83,0.78]
    pointsy2 = [1,1,1]
    for i, x1, y1, x2, y2 in zip(range(3), pointsx1, pointsy1, pointsx2, pointsy2):
        datasets[i].plot.scatter(x=0, y=1, c=2, cmap="spring")
        plt.axline(xy1=(x1, y1), xy2=(x2,y2), color='black', linestyle='-')
        plt.title(f"Group {i+1}")
        plt.savefig(f"group{i+1}_vis_with_line.png")
```

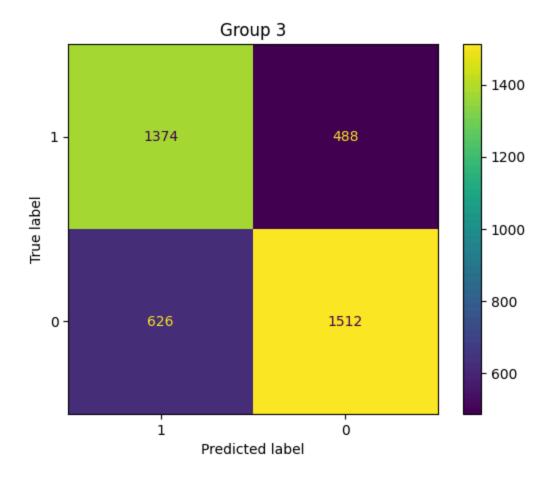




```
In [ ]: # using the points I have above, I will find the line equations that describe each
        lines = []
        for i in range(3):
            m = (pointsy2[i] - pointsy1[i]) / (pointsx2[i] - pointsx1[i])
            b = pointsy1[i] - (m * pointsx1[i])
            print(f"For group \{i+1\}: y = \{m:.2f\}x + \{b:.2f\}")
            lines.append([m,b])
       For group 1: y = -1.00x + 1.70
       For group 2: y = -1.00x + 1.83
       For group 3: y = -0.68x + 1.53
        The weights are the slopes and the treshholds are the intercepts times -1
In [ ]: # calculating the predicted category and the accurucy of it
        for i in range(3):
            dataset = datasets[i]
            m, b = lines[i]
            # the value is predicted to be 1 if the point is above the line, else 0
            dataset['pred'] = (dataset[1] > m * dataset[0] + b).astype(int)
            # record if the values are in the right category or not
            dataset['correct'] = dataset['pred'] == dataset[2]
In [ ]: # generate the confusion matrix
        i = 1
        for dataset in datasets:
            true_pos = len(dataset[(dataset['correct']) & (dataset['pred'] == 1)])
            true_neg = len(dataset[(dataset['correct']) & (dataset['pred'] == 0)])
            false_pos = len(dataset['correct']) & (dataset['pred'] == 1)])
            false_neg = len(dataset[(~dataset['correct']) & (dataset['pred'] == 0)])
            matrix = np.array([[true_pos, false_pos], [false_neg, true_neg]])
            print(matrix)
            ConfusionMatrixDisplay(confusion_matrix=matrix, display_labels=[1,0]).plot()
            plt.title(f"Group {i}")
            plt.savefig(f"group{i}_confusion_mat.png")
            i += 1
       [[2000
                 0]
       [ 0 2000]]
       [[1975 22]
       [ 25 1978]]
       [[1374 488]
        [ 626 1512]]
```







```
In [ ]: # Calculating accuracy, error, TPR, TNR, FPR, FNR for all the datasets
        metrics = []
        for i, dataset in enumerate(datasets, start=1):
            TP = len(dataset[(dataset['pred'] == 1) & (dataset[2] == 1)])
            TN = len(dataset[(dataset['pred'] == 0) & (dataset[2] == 0)])
            FP = len(dataset[(dataset['pred'] == 1) & (dataset[2] == 0)])
            FN = len(dataset[(dataset['pred'] == 0) & (dataset[2] == 1)])
            total = len(dataset)
            accuracy = (TP + TN) / total
            error = (FP + FN) / total
            tpr = TP / (TP + FN) if (TP + FN) > 0 else 0
            tnr = TN / (TN + FP) if (TN + FP) > 0 else 0
            fpr = FP / (FP + TN) if (FP + TN) > 0 else 0
            fnr = FN / (FN + TP) if (FN + TP) > 0 else 0
            metrics.append({
                "Group": i,
                "Accuracy": accuracy,
                "Error": error,
                "TPR": tpr,
                "TNR": tnr,
                "FPR": fpr,
                "FNR": fnr
            })
        # Put results in a table
```

```
import pandas as pd
metrics_df = pd.DataFrame(metrics)
print(metrics_df)
```

```
        Group
        Accuracy
        Error
        TPR
        TNR
        FPR
        FNR

        0
        1
        1.00000
        0.00000
        1.0000
        1.000
        0.000
        0.0000

        1
        2
        0.98825
        0.01175
        0.9875
        0.989
        0.011
        0.0125

        2
        3
        0.72150
        0.27850
        0.6870
        0.756
        0.244
        0.3130
```

Part 1.6: Comparison of Results and Impact of Normalization

Comparison Across Datasets

The performance of the linear separator varied significantly between the three datasets:

- Group 1 achieved perfect classification with 100% accuracy. This means the separation line cleanly divided small and big cars without errors.
- **Group 2** also performed very well, with about 98.8% accuracy. There were very few misclassifications, reflected in the low error rate (1.2%).
- **Group 3** was much more challenging. Its accuracy dropped to about **72%**, and both false positives (≈24%) and false negatives (31%) were high compared to the other groups. This indicates significant overlap between the two car types in this dataset, making a simple linear separator much less effective.

These differences come from how the data was generated, some datasets are more linearly separable than others. Group 1 was the easiest to classify, Group 2 was nearly as good, and Group 3 highlighted the limitations of linear separation.

Why Normalization Helps

Normalization was essential because price (USD) and weight (pounds) originally exist on very different scales. Without normalization, price would dominate the decision boundary due to its larger numeric range. By scaling both features into the same [0,1] range, each contributes equally to the separation line.

This not only makes the classification results more balanced but also ensures that the neuron's weights and thresholds are meaningful and comparable across datasets.

Part B

Part 1: Neuron Definition

Weights:

• $(w_X = -3)$

•
$$(w_Y = +3)$$

•
$$(w_Z = +1)$$

Threshold: (T = -1)

The net input is:

$$net = -3X + 3Y + Z$$

Output rule:

$$o = \left\{ egin{array}{ll} 1, & ext{if } net \geq -1 \ 0, & ext{if } net < -1 \end{array}
ight.$$

X	Υ	Z	¬X+Y	Inequality (net vs T)	Output
0	0	0	1	0 ≥ -1	1
0	0	1	1	1 ≥ -1	1
0	1	0	1	3 ≥ -1	1
0	1	1	1	4 ≥ -1	1
1	0	0	0	-3 ≥ -1 (false)	0
1	0	1	0	-2 ≥ -1 (false)	0
1	1	0	1	0 ≥ -1	1
1	1	1	1	1 ≥ -1	1

Boolean function implemented by this neuron:

$$f(X,Y,Z) = \neg X + Y$$

(equivalent to $X\Rightarrow Y$)

Part 2: Threshold Range

The threshold can take any value in the range:

$$-2 < T \leq 0.$$