

# Andrew Vernier

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## EDUCATION

### University of Michigan

*Bachelor of Science in Engineering – Computer Science*  
*Minor in Multidisciplinary Design*

GPA: 3.93 / 4.00

Coursework: Machine Learning, Conversational Artificial Intelligence, Operating Systems, Programming Languages, Artificial Intelligence (Fall 2019), Web Systems (Fall 2019)

Ann Arbor, MI  
December 2019

### University of Navarra – Tecnun

*Engineering Study Abroad*

San Sebastian, Spain  
May – June 2017

## EXPERIENCE

### Garmin International

*Outdoor Department, Software Engineer Intern*

Olathe, KS

May – August 2019

- Developed graphical representations of in-activity metrics for use on multiple smartwatch devices.
- Implemented privacy mode to hide GPS data from external use in order to comply with military regulations while still allowing all on-device features to remain intact.

*Automotive OEM, Software Engineer Intern*

April – August 2018

- Designed a framework for automated GUI testing of the navigation application via simulating interactions between the application and the client's API.
- Implemented asynchronous tasks for the navigation application using Qt framework such as providing locations details and generating map previews to fulfill requirements set by client's API.
- Created developer tools to increase testing and debugging efficiency such as automatic log recordings and automatic library downloading using GDB given a core dump file.

### University of Michigan CROMA Lab

Research Assistant

January 2019 – present

- Achieved 30% increase in accuracy of image annotation tool by improving user interface for crowd workers used for recreating 3D scenes from 2D images for training autonomous vehicles.
- Fabricated a test harness for guiding design of generalizable image annotation tools and testbeds and facilitating the verification of such tools; work will be presented at UIST 2019.

## LEADERSHIP

### University of Michigan Mars Rover Team

*Technical Advisor*

Sept. 2017 – present

June 2019 – present

- Assisted team growth by mentoring members and setting design requirements.

*Autonomous Navigation Lead*

March 2018 – June 2019

- Designed state machine for autonomous mode of the rover and maintained corresponding simulator.
- Organized workshops and delegated projects to increase new member involvement and retention.
- Coded path planning algorithms for autonomous search and obstacle avoidance tasks to interface with the rover's computer vision.
- Developed sensor fusion algorithms to increase accuracy of position and orientation estimates.

## PROJECTS

### University of Michigan Coursework

September 2016 - present

- Built virtual assistant to tutor elementary aged students in basic math for senior design project.
- Engineered machine learning program to recognize landmarks using both CNNs and autoencoders.

### Personal Projects

- Constructed personal website ([amverni.github.io](http://amverni.github.io)) for documenting my experiences.

## SKILLS

*Computer:* C/C++, Python, JavaScript, HTML, CSS

*Language:* Spanish (medium writing and speaking fluency)