

Grab your broom

Friday, January 18, 2019 1:53 PM

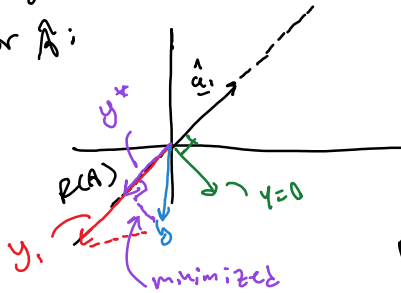
"Hide your birds, hide your wife"

"Sprite cranberry"

"Aaaaaaahhhhh"

Ax will always belong to $R(A)$ so looking for some vector y that is in $R(A)$

Consider for \hat{A} :



$$\text{For } \min_{x \in \mathbb{R}^n} \|Ax - b\| = \min_{y \in R(A)} \|y - b\|$$

So y is NO GOOD

Instead y^* is BEST

RESULT: The minimizer, y^* , in $R(A)$ satisfies $(y^* - b, r) = 0$ for any $r \in R(A)$ dot product

GREAT! But how to compute?

- Use a basis for the $R(A)$
- y^* can be written as $y^* = \sum_{j=1}^u \alpha_j s_j$ BUT WHAT ARE s_j 's?

$$(y^* - b, r) = 0 \quad (1)$$

$$y^* = \sum_{j=1}^u \alpha_j s_j \quad (2) \rightarrow \left(\sum_{j=1}^u \alpha_j s_j - b, s_i \right) = 0 \quad (3)$$

$$\sum_{j=1}^u \alpha_j (s_j, s_i) - (b, s_i) = 0$$

$$\sum_{j=1}^u [\alpha_j (s_j, s_i)] = (b, s_i) \quad i = 1, \dots, u \rightarrow$$

$$\begin{bmatrix} (s_1, s_1) & (s_1, s_2) & \dots & (s_1, s_u) \\ \vdots & \vdots & & \vdots \\ (s_u, s_1) & (s_u, s_2) & \dots & (s_u, s_u) \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_u \end{bmatrix} = \begin{bmatrix} (b, s_1) \\ \vdots \\ (b, s_u) \end{bmatrix}$$

Best App.

$$y^* = \sum_{j=1}^u \alpha_j s_j$$

What About Numerical Sensitivity of Solutions

• Case studies

$$A = \begin{bmatrix} 1 & 1 \\ 0 & \epsilon \end{bmatrix} \quad \epsilon \geq 0, \epsilon \ll 1$$

Ill-conditioned

columns are nearly collinear

$$Ax = b? \rightarrow \begin{bmatrix} 1 \\ 0 \end{bmatrix} x_1 + \begin{bmatrix} 1 \\ \epsilon \end{bmatrix} x_2 = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} \quad \text{Gotta get } \epsilon \text{ very right}$$

$$\text{So } x_2 = b_2 / \epsilon, \quad x_1 = b_1 - x_2 = b_1 - b_2 / \epsilon$$

• Now :-

$$A = \begin{bmatrix} 1 & \epsilon \\ 0 & 1 \end{bmatrix} \rightarrow Ax = b \Rightarrow \begin{bmatrix} 1 \\ 0 \end{bmatrix} x_1 + \begin{bmatrix} \epsilon \\ 1 \end{bmatrix} x_2 = \begin{bmatrix} b_1 \\ b_2 \end{bmatrix} \quad \text{columns are nearly linearly dependent}$$

$$x_2 = b_2$$

$$x_1 = b_1 - \epsilon x_2 = b_1 - \epsilon b_2 \quad \text{small changes in } \epsilon \text{ small change in solution}$$

Want to choose basis as close to lin. ind. as possible

• The "condition # at a matrix formalizes this idea

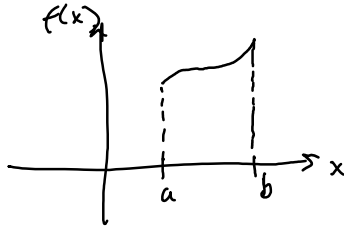
- Just use MATLAB: $\kappa(A)$

$\kappa(A) = \text{condition \#}$, $\kappa(A)$ (depends on your problem)

- large $\kappa(A)$, poorly conditioned

Function Interpolation = Approximation

Goal:



C means space of continuous functions on $a \leq x \leq b$

$$f(x) \in C_{[a,b]}$$