# Lecture Note - 07: Neural Network

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# 1 A Single Neuron

An artificial neuron is the basic computing unit in an artificial neural network. There are different way to define a neuron. The most common one is shown in Figure 1.

**Input**: A neuron receives multiple inputs  $x_1, x_2, ..., x_n$ . The signals are summed up after modulated by a set of weights  $w_1, w_2, ..., w_n$ . Let us denote the weighted sum z

$$z = \sum_{i=1}^{n} w_i x_i \tag{1}$$

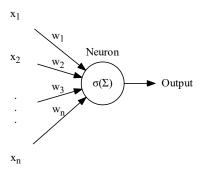


Figure 1: Schema: a single neuron with activation function  $\sigma$ 

Usually a biased term  $w_0$  is added to the summation and we have

$$z = \sum_{i=1}^{n} w_i x_i + w_0 \tag{2}$$

**Output**: The weighted sum is further transferred via an activation function  $\sigma$  and becomes the final output of the neuron

$$a = \sigma(z) = \sigma(\sum_{i=1}^{n} w_i x_i + w_0)$$
(3)

**Activation**: The activation function can of different types. Below is a list of common activation functions. Almost all activation functions have an S-shape except for the ReLu function.

Name	Definition
Step Function	$\sigma(z) = \begin{cases} 0 & \text{for } z < 0 \\ 1 & \text{for } z \ge 0 \end{cases}$
Logistic or sigmoid	$\sigma(z) = \frac{1}{1 + e^{-z}}$
hyperbolic tangent	$\sigma(z) = \frac{(e^z - e^{-z})}{(e^z + e^{-z})}$
ReLU	$\sigma(z) = \begin{cases} 0 & \text{for } z \le 0 \\ z & \text{for } z > 0 \end{cases}$

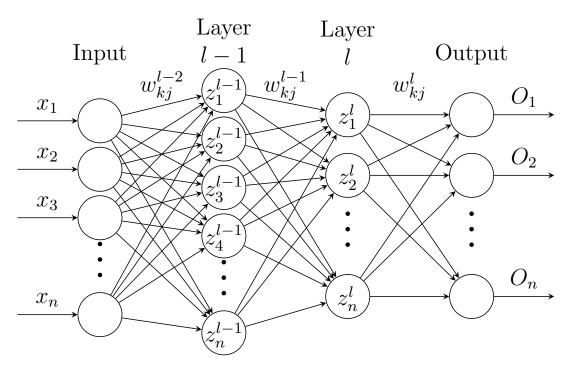


Figure 2: A neural network of multiple layer structures. The hidden layers before layer l-1 and after layer l are not shown.

#### 2 Neural Network: Forward Path

Each neuron at layer l receives inputs from all neuron from the previous layer l-1,

$$z_k^l = \sum_{j} w_{kj}^{l-1} a_j^{l-1} \tag{4}$$

Here,  $a_j^{l-1}$  is the input from jth neuron from l-1 layer. The neurons transfer the input signal  $z_k^l$  via a transfer function  $\sigma$  and send as input to to the next layer

$$a_k^l = \sigma(z_k^l) \tag{5}$$

Inserting equation (4) to (5), we have

$$z_k^l = \sum_j w_{kj}^{l-1} \sigma(z_j^{l-1}) = \sum_j w_{kj}^{l-1} a_j^{l-1}$$
(6)

### 3 The Derivatives of Neural Network

In order to calculate the neural network properly we need to understand a few derivatives.

 $\bullet$  The partial derivatives of  $z_k^l$  against  $z_j^{l-1}$ 

$$\frac{\partial z_k^l}{\partial z_j^{l-1}} = w_{kj}^{l-1} \sigma'(z_j^{l-1}) \tag{7}$$

 $\bullet$  The partial derivatives of  $z_k^l$  against a weight element  $w_{kj}^{l-1}$ 

$$\frac{\partial z_k^l}{\partial w_{kj}^{l-1}} = \sigma(z_j^{l-1}) \tag{8}$$

• Given a function of  $f(z_j^{l-1})$ , we can explicitly express it in terms of  $z^l$ s,

$$f(z_j^{l-1}) = f(z_1^l(z_j^{l-1}), z_2^l(z_j^{l-1})...z_m^l(z_j^{l-1})...)$$

its derivative w.r.t  $z_i^{l-1}$  is

$$\frac{\partial f}{\partial z_j^{l-1}} = \sum_m \frac{\partial f}{\partial z_m^l} \frac{\partial z_m^l}{\partial z_j^{l-1}} = \sum_m \frac{\partial f}{\partial z_m^l} w_{mj}^{l-1} \sigma'(z_j^{l-1})$$
(9)

# 4 Backpropagation

Consider neural network that has N layers, the cost function is dependent on all the zs of neurons in all layers

$$C\left(\vec{z}^{N}(\vec{z}^{N-1}(...\vec{z}^{l}(\vec{z}^{l-1})...)...\vec{z}^{1})\right)$$
 (10)

In order to find the weights that optimize the cost function, we can use gradient descent. Recall the gradient descent methods updates weights of layer l-1 as of the following

$$w_{kj}^{l-1} \leftarrow w_{kj}^{l-1} - \eta \frac{\partial C}{\partial w_{kj}^{l-1}} \tag{11}$$

By using the chain rule, we have

$$\frac{\partial C}{\partial w_{kj}^{l-1}} = \frac{\partial C(\dots(z_k^l(w_{kj}^{l-1},\dots)))}{\partial w_{kj}^{l-1}} = \frac{\partial C}{\partial z_k^l} \frac{\partial z_k^l}{\partial w_{kj}^{l-1}}$$
(12)

There are two terms on the R.H.S. of the equation,

• Using equation (9), the first term becomes

$$\frac{\partial C}{\partial z_k^l} = \sum_m \frac{\partial C}{\partial z_m^{l+1}} w_{mk}^l \sigma'(z_k^l)$$

Use notation  $\delta_k^l = \frac{\partial C}{\partial z_k^l}$  for short, we have

$$\delta_k^l = \sum_m \delta_m^{l+1} w_{mk}^l \sigma'(z_k^l) \tag{13}$$

• Using what we calculated in equation (8), the second term is simply the output from jth neuron in layer l-1

$$\frac{\partial z_k^l}{\partial w_{kj}^{l-1}} = \sigma(z_j^{l-1}) = a_j^{l-1} \tag{14}$$

Finally, we get our iteration methods for calculating the gradient of the cost function w.r.t the weights i.e.

$$\frac{\partial C}{\partial w_{kj}^{l-1}} = \delta_k^l a_j^{l-1} \tag{15}$$

# 5 Neural Network Training Algorithm

So the overall backpropagation algorithm works as the following:

- Initialize all weights  $w_{mk}^l$  in every layer of the neural network
- Feedfoward: use formula (6) to caculate the quantities  $z_k^l$ ,  $a_k^l$  for each neuron in all layers. Note in the input layer  $a_k = x_k$ ,  $x_k$  are he inputs to the 1st layer neurons
- Backpropagation: after calculating the feedforward path, we use the backpropagation to figure out all the  $\delta_k^l$  and update the weights. In contrast to the forward path. The back propagation starts by calculating the  $\delta_k^L$  of the last layer L. The  $\delta_k^l$  is then iteratively calculated using equation (13).
- Calculate the gradient of the cost function w.r.t to all weights  $w_{kj}^{l-1}$
- updates the weights using equation (11)