# Chameleon: Adaptive Code Optimization for Expedited Deep Neural Network Compilation

(arXiv: 2001.08743)

Taehee Jeong



**Chameleon** is an animal that is capable of Adapting to their environments which helps them survive.

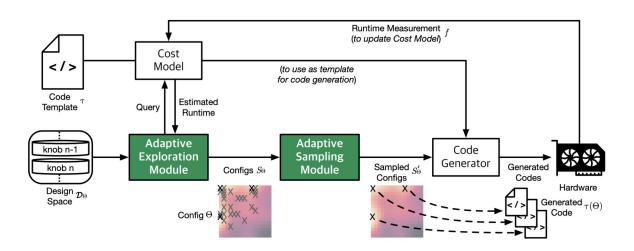


Figure 3: Overall design and compilation overview of the CHAMELEON.

Chameleon is an animal that is capable of Adapting to their environments which helps them survive. In our work, **CHAMELEON** is an entity that Adapts to the **variations in the design space** and the distribution of the candidate configurations, enabling expedited deep neural network compilation.

(arXiv: 2001.08743)

#### 2.1 Compilation Workflow for Deep Neural Networks

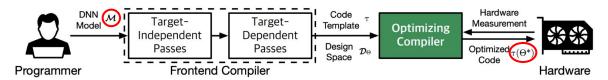


Figure 1: Overview of our model compilation workflow, and highlighted is the scope of this work.

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#### 2.1 COMPILATION WORKFLOW FOR DEEP NEURAL NETWORKS

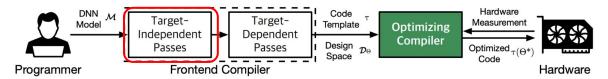


Figure 1: Overview of our model compilation workflow, and highlighted is the scope of this work.

#### Target-independent pass

- Optimizations in code model semantics + traditional compiler frontend optimizations
- Operator fusion, data layout transformation
- o Dead code elimination, constant folding, ...

(arXiv: 2001.08743, 1805.08166)

#### 2.1 COMPILATION WORKFLOW FOR DEEP NEURAL NI

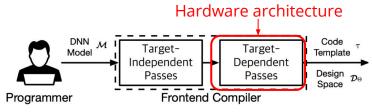
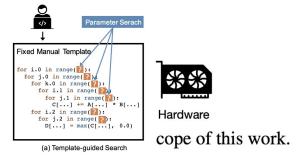


Figure 1: Overview of our model compilation workflow, ar



- Target-dependent pass
  - $\circ$  Template code( $\tau$ ) generation based on target hardware architecture
  - Traditional compiler backend optimizations
  - Cost of execution time is not taken into account yet

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#### 2.1 COMPILATION WORKFLOW FOR DEEP NEURAL NETWORKS

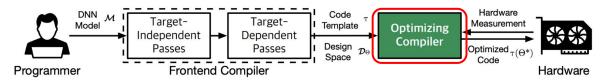


Figure 1: Overview of our model compilation workflow, and highlighted is the scope of this work.

- "Black-box" optimization pass: Optimizing Compiler
  - Generate optimal code, given design space  $D_{\Theta}$ , find  $\Theta^* \in D_{\Theta}$  that minimizes runtime.
  - $\circ$   $\tau(\Theta^*)$ : optimal code given template and configurations
  - Leverages actual runtime measurements from HW to get data points

# Optimizing Compiler: Components and Requirements

#### **Configuration Exploration**

- Configuration ("Knobs"): optimization parameters (tiling, loop unrolling)
- Search space should be **diverse** enough. (10<sup>10</sup>? design space)
- Algorithm should be effective at navigating large design space
- Reduce costly hardware measurements

#### **Cost Estimation**

- Estimate runtime (fitness) based on code. (Same as AutoTVM)
- Avoid overfitting to specific set of configurations

# Optimizing Compiler: **Previous approaches**

#### **Configuration Exploration**

- Hand-optimized libraries, compiler heuristics
- Genetic algorithm (TensorComprehension)
- Stochastic methods (Simulated annealing AutoTVM)
- Diversity-aware exploration (AutoTVM)

#### **Cost Estimation**

- Actual HW measurements
- ML-based approach
  - XGBoost(GBT)/TreeGRU- AutoTVM, Chameleon
  - GNN + LSTM/Transformer XLA

# Optimizing Compiler: **Existing problems**

#### **Configuration Exploration**

- Takes too much iterations and time
- Similar configurations -> redundant calculations -> waste of computing resource
- Invalid randomly sampled configuration -> hardware failure -> reset time needed

#### **Cost Estimation**

Greedy sampling based on cost model -> hard to explore untried configs

# Chameleon: Key contributions in Configuration Exploration

#### **Adaptive Exploration**

- RL based approach novel method in this domain
- Adapt to unseen design space

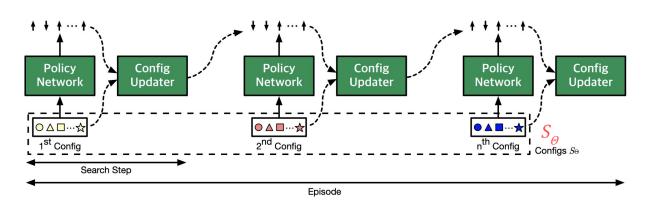
#### **Adaptive Sampling**

- Clustering of similar configurations: reduce redundant calculations
- Sample synthesis w/ domain knowledge: generate novel configurations that are non-invalid, by taking "safe" choices

#### Result:

- 4.45x improvement in optimizing compilation time
- 5.56% improvement in inference time (vs. AutoTVM)

# **Adaptive Exploration**



Policy

Actor

Value
Function

reward

Environment

Cost model

Figure 4: Adaptive Exploration Module of CHAMELEON in action.

#### Actor-critic style RL

- "actor" proposes config updates (turn each "knob" up/down/stay)
- "critic" gets fitness (predicted execution time) as reward, and then gives "actor" a feedback.
  - Critic **learns design space** while getting reward and giving feedback

# **Adaptive Exploration**

- Policy network suggests good configurations as the iteration goes
- Value network assists this by learning value function: design space -> fitness
- Used **PPO**(Proximal policy optimization) algorithm
- Performed architecture search to find tradeoff between performance vs network latency

#### Output

•  $S_{\vec{r}}$  set of **all configurations** emitted from policy network each step.

# **Adaptive Sampling**

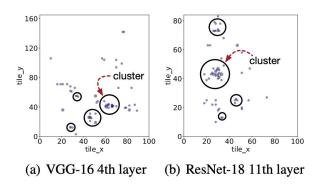


Figure 5: Clusters of candidate configurations.

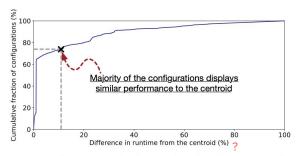
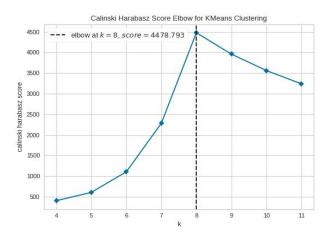


Figure 6: Cumulative Distribution Function (CDF) of the difference in runtime among the configurations in the cluster.

- 1. Explored configurations are **clustered**
- 2. For each cluster, most of configurations has **runtime really close to the centroid** configuration (80% of configs has 20% diff Pareto?!)

# Adaptive Sampling: K-means clustering

- Threshold-based Swift Meta-Search
  - L2\_loss \* threshold > prev\_loss? break
- Determine optimal K by getting "elbow point" from L2 loss.
  - Choose "just enough" amount of hardware measurements



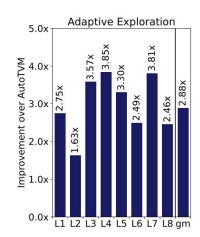
# Adaptive Sampling: Sample Synthesis

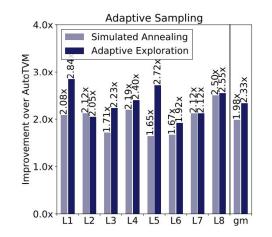
- K-means remove redundancy within iteration
- Overfit cost model preferes already seen configurations -> redundancy among iterations when greedily sampling best configurations.
  - Unvisited regions will usually have lower fitness, and thus ignored
- Randomly generated new samples would be often invalid. ex) too large tile -> memory error. -> H/W reset required
- When a config is **already explored** replace with **mode(최빈값)** of proposed configurations( $S_{\rho}$ )

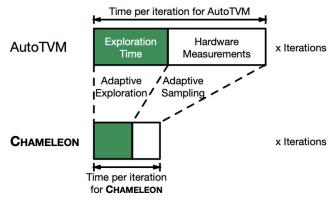
# **Sample Synthesis**

```
Algorithm 1 Adaptive Sampling and Sample Synthesis
                                                               \triangleright s_{\Theta}: candidate configs, v_{\Theta}: visited configs
 1: procedure ADAPTIVE SAMPLING (s_{\Theta}, v_{\Theta})
        new_candidates \leftarrow \emptyset, previous_loss \leftarrow \infty
 3:
        for k in range(8, 64) do
             new_candidates, clusters, L2_loss \leftarrow K-means.run(s_{\Theta}, k)
 4:
             if Threshold \times L2_loss \geq previous_loss then break
 5:
                                                                            Exit loop at knee of loss curve
             previous loss \leftarrow L2 loss
 6:
 7:
        end for
 8:
        for candidate in new_candidates do
                                                                  ▶ Replace visited config with new config
             if candidate in v_{\Theta} then new_candidates.replace(candidate, mode(s_{\Theta}))
 9:
        end for
10:
        return new_candidates
                                         ▶ Feed to Code Generator to make measurements on hardware
11:
12: end procedure
```

### Results







(a) Reduction in number of steps for convergence.

(b) Reduction in number of hardware measurements.

(c) Illustration of how the each component of **CHAMELEON** reduces the optimization time.

**CHAMELEON** significantly reduces optimization time

Figure 7: Component evaluation of CHAMELEON.

=> Adaptive sampling (obviously) reduces H/W measurements. (better w/ RL)

# Results

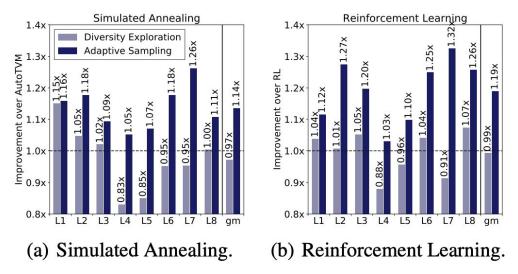


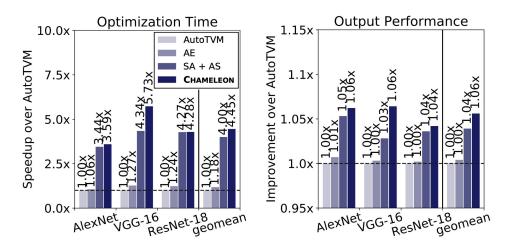
Figure 8: Comparison to AutoTVM's diversity exploration.

Compared with AutoTVM's diversity exploration.

Adaptive sampling works better in all cases, possibly due to domain knowledge  $(S_{\rho})$ 

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# Results



(b) End-to-end evaluation.

**Adaptive sampling** is the more effective improvement RL also have notable impact, but less impressive than adaptive sampling.

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# **Limitations** (My opinion)

- RL seems noble, but not so much improvement (1.18x) compared to significant reduction in number of steps (2.88x)
- Runtime performance improvement is also not impressive with RL only. Value network can't generalize its value function beyond what it has seen.
- Limited result in pretty simple convolution models. Not sure if it can be generalized to more complex models (e.g. NASNet, Inception)
- Only convolution performance is considered maybe MatMul is already highly optimized?

# THANKS!

