VSource interface C++ library

v1.8.3

Table of contents

* [How to make custom implementation](#)

Overview

VSource C++ library provides standard interface as well defines data structures and rules for different video source classes (video capture classes). **VSource** interface class doesn't do anything, just provides interface and provides methods to encode/decode commands and encode/decode params. Also **VSource** class provides data structures for video source parameters. Different video source classes inherit interface form **VSource** C++ class. **VSource.h** file contains contains list of data structures ([VSourceCommand enum](#), [VSourceParam enum](#) and [VSourceParams class](#) class). [VSourceParams class](#) contains video source params and includes methods to encode and decode video source params. [VSourceCommand enum](#) contains IDs of commands supported by **VSource** class. [VSourceParam enum](#) contains IDs of params supported by **VSource** class. All video sources should include params and commands listed in **VSource.h** file. **VSource** class interface class depends on [Frame](#) class (describes video frame and video frame data structures, source code included, Apache 2.0 license) and [ConfigReader](#) library (provides methods to read/write JSON config files, source code included, Apache 2.0 license). It uses C++17 standard. The library is licensed under the **Apache 2.0** license.

Versions

Table 1 - Library versions.

Version	Release date	What's new
1.0.0	13.06.2023	First version
1.0.2	20.06.2023	- Fixed bugs. - Documentation updated.
1.1.0	29.06.2023	- Added new parameters. - Documentation updated.
1.1.1	29.06.2023	- Added license. - Repository made public.
1.2.0	01.07.2023	- Added new methods to encode/decode commands. - Tests updated. - Documentation updated.
1.2.1	01.07.2023	- Params description updated in source code.
1.3.0	05.07.2023	- VSourceParams class updated (initString replaced by source). - decode(...) method in VSourceParams class updated.
1.3.1	06.07.2023	- gain, exposure and focusPos fields of VSourceParams excluded from JSOM reading/writing.
1.3.2	06.07.2023	- Frame library version updated.

Version	Release date	What's new
1.4.0	11.07.2023	- Added VSourceParamsMask structure. - Added params mask in encode(...) method of VSourceParams class.
1.5.0	22.09.2023	- Updated encode(...) and decode(...) methods of VSourceParams. - Added decodeAndExecuteCommand(...) method. - Added example of video source implementation.
1.6.0	26.09.2023	- Signature of getParams(...) method changed.
1.6.1	13.11.2023	- Frame class updated.
1.7.1	14.12.2023	- Virtual destructor added. - Frame class updated.
1.8.1	18.12.2023	- Region of interest params included.
1.8.2	20.04.2024	- Frame class updated. - ConfigReader class updated. - Documentation updated.
1.8.3	20.05.2024	- Submodules updated. - Documentation updated.

Library files

The library supplied by source code only. The user would be given a set of files in the form of a CMake project (repository). The repository structure is shown below:

```
CMakeLists.txt ---------------- Main CMake file of the library.
3rdparty --------------------- Folder with third-party libraries.
    CMakeLists.txt ------------ CMake file which includes third-party libraries.
    ConfigReader -------------- Source code of the ConfigReader library.
    Frame -------------------- Source code of the Frame library.
example ---------------------- Folder with custom video source class.
    CMakeLists.txt ------------ CMake file for example custom video source class.
    CustomVSource.cpp --------- Source code file of the CustomVSource class.
    CustomVSource.h ----------- Header with CustomVSource class declaration.
    CustomVSourceVersion.h ----- Header file which includes CustomVSource version.
    CustomVSourceVersion.h.in -- CMake service file to generate version file.
test ------------------------- Folder with codec test application.
    CMakeLists.txt ------------ CMake file for codec test application.
    main.cpp ------------------ Source code file of VSource class test application.
src -------------------------- Folder with source code of the library.
    CMakeLists.txt ------------ CMake file of the library.
    VSource.cpp --------------- C++ implementation file.
    VSource.h ----------------- Header file which includes VSource class declaration.
    VSourceVersion.h ---------- Header file which includes version of the library.
    VSourceVersion.h.in -------- CMake service file to generate version file.
```

Video source interface class description

VSource class declaration

VSource interface class declared in **VSource.h** file. Class declaration:

```cpp
class VSource
{
public:

    /// Class destructor.
    virtual ~VSource();

    /// Get string of current library version.
    static std::string getVersion();

    /// Open video source.
    virtual bool openVSource(std::string& initString) = 0;

    /// Init video source.
    virtual bool initVSource(VSourceParams& params) = 0;

    /// Get open status.
    virtual bool isVSourceOpen() = 0;

    /// Close video source.
    virtual void closeVSource() = 0;

    /// Get new video frame.
    virtual bool getFrame(Frame& frame, int32_t timeoutMsec = 0) = 0;

    /// Set video source param.
    virtual bool setParam(VSourceParam id, float value) = 0;

    /// Get video source param value.
    virtual float getParam(VSourceParam id) = 0;

    /// Get video source params structure.
    virtual void getParams(VSourceParams& params) = 0;

    /// Execute command.
    virtual bool executeCommand(VSourceCommand id) = 0;

    /// Encode set param command.
    static void encodeSetParamCommand(
            uint8_t* data, int& size, VSourceParam id, float value);

    /// Encode command.
    static void encodeCommand(
            uint8_t* data, int& size, VSourceCommand id);
```

```
    /// Decode command.
    static int decodeCommand(uint8_t* data,
                             int size,
                             VSourceParam& paramId,
                             VSourceCommand& commandId,
                             float& value);

    /// Decode and execute command.
    virtual bool decodeAndExecuteCommand(uint8_t* data, int size) = 0;
};
```

getVersion method

The **getVersion()** method returns string of current version of **VSource** class. Particular video source class can have it's own **getVersion()** method. Method declaration:

```
static std::string getVersion();
```

Method can be used without **VSource** class instance:

```
std::cout << "VSource class version: " << VSource::getVersion() << std::endl;
```

Console output:

```
VSource class version: 1.8.3
```

openVSource method

The **openVSource(...)** method initializes video source. Instead of **openVSource(...)** method user can call initVSource(...) method. Method declaration:

```
virtual bool openVSource(std::string& initString) = 0;
```

Parameter	Value
initString	Initialization string. Format depends on implementation but it is recommended to keep default format: [video device or ID or file];[width];[height];[fourcc]. Example: "/dev/video0;1920;1080;YUYV".

Returns: TRUE if the video source open or FALSE if not.

initVSource method

The **initVSource(...)** method initializes video source by set of parameters. Instead of **initVSource(...)** method user can call openVSource(...) method. Method declaration:

```cpp
virtual bool initVSource(VSourceParams& params) = 0;
```

Parameter	Value
params	VSourceParams structure (see VSourceParams class description). The video source should set parameters according to params structure. Particular video source can support not all parameters listed in VSourceParams class.

Returns: TRUE if the video source initialized or FALSE if not.

isVSourceOpen method

The **isVSourceOpen()** method returns video source initialization status. Initialization status also included in VSourceParams class. Method declaration:

```cpp
virtual bool isVSourceOpen() = 0;
```

Returns: TRUE if the video source open (initialized) or FALSE if not.

closeVSource method

The **closeVSource()** method closes video source. Method declaration:

```cpp
virtual void closeVSource() = 0;
```

getFrame method

The **getFrame(...)** method intended to get input video frame. Video source should support auto re-initialization in case connection loss. Method declaration:

```cpp
virtual bool getFrame(Frame& frame, int32_t timeoutMsec = 0) = 0;
```

Parameter	Value
frame	Output video frame (see Frame class description). Video source class determines output pixel format. Pixel format can be set in initVSource(...) or openVSource(...) methods if particular video source supports it.

Parameter	Value
timeoutMsec	Timeout to wait new frame data: - timeoutMs == -1 - Method will wait endlessly until new data arrive. - timeoutMs == 0 - Method will only check if new data exist. - timeoutMs > 0 - Method will wait new data specified time. **Each video source implementation must provide described behavior.**

Returns: TRUE if new data exists and copied or FALSE if not.

setParam method

The **setParam(...)** method sets new video source parameters value. The particular implementation of the video source must provide thread-safe **setParam(...)** method call. This means that the **setParam(...)** method can be safely called from any thread. Method declaration:

```cpp
virtual bool setParam(VSourceParam id, float value) = 0;
```

Parameter	Description
id	Video source parameter ID according to VSourceParam enum.
value	Video source parameter value.

Returns: TRUE is the parameter was set or FALSE if not.

getParam method

The **getParam(...)** method designed to obtain video source parameter value. The particular implementation of the video source must provide thread-safe **getParam(...)** method call. This means that the **getParam(...)** method can be safely called from any thread. Method declaration:

```cpp
virtual float getParam(VSourceParam id) = 0;
```

Parameter	Description
id	Video source parameter ID according to VSourceParam enum.

Returns: parameter value or -1 of the parameters doesn't exist in particular video source class.

getParams method

The **getParams(...)** method designed to obtain video source params structure. The particular implementation of the video source must provide thread-safe **getParams(...)** method call. This means that the **getParams(...)** method can be safely called from any thread. Method declaration:

```
virtual void getParams(VSourceParams& params) = 0;
```

Parameter	Description
params	Video source params class object (VSourceParams).

executeCommand method

The **executeCommand(...)** method designed to execute video source command. The particular implementation of the video source must provide thread-safe **executeCommand(...)** method call. This means that the **executeCommand(...)** method can be safely called from any thread. Method declaration:

```
virtual bool executeCommand(VSourceCommand id) = 0;
```

Parameter	Description
id	Video source command ID according to VSourceCommand enum.

Returns: TRUE is the command was executed or FALSE if not.

encodeSetParamCommand method

The **encodeSetParamCommand(...)** static method designed to encode command to change any parameter for remote video source. To control video source remotely, the developer has to design his own protocol and according to it encode the command and deliver it over the communication channel. To simplify this, the **VSource** class contains static methods for encoding the control command. The **VSource** class provides two types of commands: a parameter change command (SET_PARAM) and an action command (COMMAND). **encodeSetParamCommand(...)** designed to encode SET_PARAM command. Method declaration:

```
static void encodeSetParamCommand(uint8_t* data, int& size, VSourceParam id, float
value);
```

Parameter	Description
data	Pointer to data buffer for encoded command. Must have size >= 11.
size	Size of encoded data. Will be 11 bytes.
id	Parameter ID according to VSourceParam enum.
value	Parameter value.

encodeSetParamCommand(...) is static and used without **VSource** class instance. This method used on client side (control system). Command encoding example:

```
// Buffer for encoded data.
uint8_t data[11];
// Size of encoded data.
int size = 0;
// Random parameter value.
float outValue = (float)(rand() % 20);
// Encode command.
VSurce::encodeSetParamCommand(data, size, VSourceParam::EXPOSURE, outValue);
```

encodeCommand method

The **encodeCommand(...)** static method designed to encode command for remote video source. To control a video source remotely, the developer has to design his own protocol and according to it encode the command and deliver it over the communication channel. To simplify this, the **VSource** class contains static methods for encoding the control command. The **VSource** class provides two types of commands: a parameter change command (SET_PARAM) and an action command (COMMAND). **encodeCommand(...)** designed to encode COMMAND (action command). Method declaration:

```
static void encodeCommand(uint8_t* data, int& size, VSourceCommand id);
```

Parameter	Description
data	Pointer to data buffer for encoded command. Must have size >= 7 bytes.
size	Size of encoded data. Will be 7 bytes.
id	Command ID according to VSourceCommand enum.

encodeCommand(...) is static and used without **VSource** class instance. This method used on client side (control system). Command encoding example:

```
// Buffer for encoded data.
uint8_t data[11];
// Size of encoded data.
int size = 0;
// Encode command.
VSource::encodeCommand(data, size, VSourceCommand::RESTART);
```

decodeCommand method

The **decodeCommand(...)** static method designed to decode command on video source side (edge device). Method declaration:

```
static int decodeCommand(uint8_t* data, int size, VSourceParam& paramId, VSourceCommand&
commandId, float& value);
```

Parameter	Description
data	Pointer to input command.
size	Size of command. Should be 11 bytes for SET_PARAM and 7 bytes for COMMAND.
paramId	Parameter ID according to [VSourceParam enum](). After decoding SET_PARAM command the method will return parameter ID.
commandId	Command ID according to [VSourceCommand enum](). After decoding COMMAND the method will return command ID.
value	Parameter value (after decoding SET_PARAM command).

Returns: 0 - in case decoding COMMAND, **1** - in case decoding SET_PARAM command or **-1** in case errors.

decodeAndExecuteCommand method

The **decodeAndExecuteCommand(...)** method decodes and executes command on video source side. The particular implementation of the video source must provide thread-safe **decodeAndExecuteCommand(...)** method call. This means that the **decodeAndExecuteCommand(...)** method can be safely called from any thread. Method declaration:

```cpp
virtual bool decodeAndExecuteCommand(uint8_t* data, int size) = 0;
```

Parameter	Description
data	Pointer to input command.
size	Size of command. Must be 11 bytes for SET_PARAM and 7 bytes for COMMAND.

Returns: TRUE if command decoded (SET_PARAM or COMMAND) and executed (action command or set param command).

Data structures

VSource.h file defines IDs for parameters (**VSourceParam** enum) and IDs for commands (**VSourceCommand** enum).

VSourceCommand enum

Enum declaration:

```cpp
enum class VSourceCommand
{
    /// Restart.
    RESTART = 1
};
```

Table 2 - Video source commands description. Some commands maybe unsupported by particular video source class.

Command	Description
RESTART	Restart video source (close and open again).

VSourceParam enum

Enum declaration:

```cpp
enum class VSourceParam
{
    /// [read/write] Logging mode. Values: 0 - Disable, 1 - Only file,
    /// 2 - Only terminal, 3 - File and terminal.
    LOG_LEVEL = 1,
    /// [read/write] Frame width. User can set frame width before initialization
    /// or after. Some video source classes may set width automatically.
    WIDTH,
    /// [read/write] Frame height. User can set frame height before
    /// initialization or after. Some video source classes may set height
    /// automatically.
    HEIGHT,
    /// [read/write] Gain mode. Value depends on implementation but it is
    /// recommended to keep default values: 0 - Manual control, 1 - Auto.
    GAIN_MODE,
    /// [read/write] Gain value. Value: 0(min for particular video source class)
    /// - 65535(max for particular video source class).
    GAIN,
    /// [read/write] Exposure mode. Value depends on implementation but it is
    /// recommended to keep default values: 0 - Manual control, 1 - Auto.
    EXPOSURE_MODE,
    /// [read/write] Exposure value. Value: 0(min for particular video source
    /// class) - 65535(max for particular video source class).
    EXPOSURE,
    /// [read/write] Focus mode. Value depends on implementation but it is
    /// recommended to keep default values: 0 - Manual control, 1 - Auto.
    FOCUS_MODE,
    /// [read/write] Focus position. Value: 0(full near) - 65535(full far).
    FOCUS_POS,
    /// [read only] Video capture cycle time. **VSource** class sets this value
    /// automatically. This parameter means time interval between two captured
    /// video frame.
    CYCLE_TIME_MKS,
    /// [read/write] FPS. User can set frame FPS before initialization or after.
    /// Some video source classes may set FPS automatically.
    FPS,
    /// [read only] Open flag. 0 - not open, 1 - open.
    IS_OPEN,
    /// Region of intrest upper left corner x coordinate.
    ROI_X,
    /// Region of intrest upper left corner x coordinate.
    ROI_Y,
```

```
    /// Region of intrest upper left corner x coordinate.
    ROI_WIDTH,
    /// Region of intrest upper left corner x coordinate.
    ROI_HEIGHT,
    /// [read/write] Custom parameter. Depends on implementation.
    CUSTOM_1,
    /// [read/write] Custom parameter. Depends on implementation.
    CUSTOM_2,
    /// [read/write] Custom parameter. Depends on implementation.
    CUSTOM_3
};
```

Table 3 - Video source params description. Some params maybe unsupported by particular video source class.

Parameter	Access	Description
LOG_LEVEL	read / write	Logging mode. Values: 0 - Disable, 1 - Only file, 2 - Only terminal, 3 - File and terminal.
WIDTH	read / write	Frame width. User can set frame width before initialization or after. Some video source classes may set width automatically.
HEIGHT	read / write	Frame height. User can set frame height before initialization or after. Some video source classes may set height automatically.
GAIN_MODE	read / write	Gain mode. Value depends on implementation but it is recommended to keep default values: 0 - Manual control, 1 - Auto.
GAIN	read / write	Gain value. Value: 0(min for particular video source class) - 65535(max for particular video source class).
EXPOSURE_MODE	read / write	Exposure mode. Value depends on implementation but it is recommended to keep default values: 0 - Manual control, 1 - Auto.
EXPOSURE	read / write	Exposure value. Value: 0(min for particular video source class) - 65535(max for particular video source class).
FOCUS_MODE	read / write	Focus mode. Value depends on implementation but it is recommended to keep default values: 0 - Manual control, 1 - Auto.
FOCUS_POS	read / write	Focus position. Value: 0(full near) - 65535(full far).
CYCLE_TIME_MKS	read only	Video capture cycle time. **VSource** class sets this value automatically. This parameter means time interval between two captured video frame.
FPS	read / write	FPS. User can set frame FPS before initialization or after. Some video source classes may set FPS automatically.
IS_OPEN	read only	Open flag. 0 - not open, 1 - open.

Parameter	Access	Description
ROI_X	read / write	Region of interest x coordinate.
ROI_Y	read / write	Region of interest y coordinate.
ROI_WIDTH	read / write	Region of interest width.
ROI_HEIGHT	read / write	Region of interest height.
CUSTOM_1	read / write	Custom parameter. Depends on implementation.
CUSTOM_2	read / write	Custom parameter. Depends on implementation.
CUSTOM_3	read / write	Custom parameter. Depends on implementation.

VSourceParams class description

VSourceParams class declaration

VSourceParams class used for video source initialization (**initVSource(...)** method) or to get all actual params (getParams(...) method method). Also **VSourceParams** provide structure to write/read params from JSON files (**JSON_READABLE** macro, see ConfigReader class description) and provide methods to encode and decode params. Class declaration:

```
class VSourceParams
{
public:
    /// Logging mode. Values: 0 - Disable, 1 - Only file,
    /// 2 - Only terminal, 3 - File and terminal.
    int logLevel{0};
    /// Video source: file, video stream, video device, camera num, etc.
    std::string source{"/dev/video0"};
    /// FOURCC: RGB24, BGR24, YUYV, UYVY, GRAY, YUV24, NV12, NV21, YU12, YV12.
    /// Value says to video source class which pixel format preferable for
    /// output video frame. Particular video source class can ignore this params
    /// during initialization. Parameters should be set before initialization.
    std::string fourcc{"YUYV"};
    /// Frame width. User can set frame width before initialization
    /// or after. Some video source classes may set width automatically.
    int width{1920};
    /// Frame height. User can set frame height before
    /// initialization or after. Some video source classes may set height
```

```cpp
    /// automatically.
    int height{1080};
    /// Gain mode. Value depends on implementation but it is
    /// recommended to keep default values: 0 - Manual control, 1 - Auto.
    int gainMode{1};
    /// Gain value. Value: 0(min for particular video source class)
    /// - 65535(max for particular video source class).
    int gain{0};
    /// Exposure mode. Value depends on implementation but it is
    /// recommended to keep default values: 0 - Manual control, 1 - Auto.
    int exposureMode{1};
    /// Exposure value. Value: 0(min for particular video source
    /// class) - 65535(max for particular video source class).
    int exposure{1};
    /// Focus mode. Focus mode. Value depends on implementation but it is
    /// recommended to keep default values: 0 - Manual control, 1 - Auto.
    int focusMode{1};
    /// Focus position. Value: 0(full near) - 65535(full far).
    int focusPos{0};
    /// Video capture cycle time. **VSource** class sets this value
    /// automatically. This parameter means time interval between two captured
    /// video frame.
    int cycleTimeMks{0};
    /// FPS. User can set frame FPS before initialization or after.
    /// Some video source classes may set FPS automatically.
    float fps{0};
    /// Open flag. 0 - not open, 1 - open.
    bool isOpen{false};
    /// Region of intrest upper left corner x coordinate.
    int roiX{0};
    /// Region of intrest upper left corner y coordinate.
    int roiY{0};
    /// Region of intrest width.
    int roiWidth{0};
    /// Region of intrest heigth.
    int roiHeight{0};
    /// Custom parameter. Depends on implementation.
    float custom1{0.0f};
    /// Custom parameter. Depends on implementation.
    float custom2{0.0f};
    /// Custom parameter. Depends on implementation.
    float custom3{0.0f};

    JSON_READABLE(VSourceParams, logLevel, source, fourcc,
                  width, height, gainMode, exposureMode,
                  focusMode, fps, custom1, custom2, custom3);

    /// operator =
    VSourceParams& operator= (const VSourceParams& src);

    /// Encode params.
    bool encode(uint8_t* data, int bufferSize, int& size,
                VSourceParamsMask* mask = nullptr);

    /// Decode params.
    bool decode(uint8_t* data, int dataSize);
```

```
};
```

Table 4 - VSourceParams class fields description.

Field	type	Description
logLevel	int	Logging mode. Values: 0 - Disable, 1 - Only file, 2 - Only terminal, 3 - File and terminal.
source	string	Video source: file, video stream, video device, camera num, etc.
fourcc	string	FOURCC: RGB24, BGR24, YUYV, UYVY, GRAY, YUV24, NV12, NV21, YU12, YV12. Value says to video source class which pixel format preferable for output video frame. Particular video source class can ignore this params during initialization. Parameters should be set before initialization.
width	int	Frame width. User can set frame width before initialization or after. Some video source classes may set width automatically.
height	int	Frame height. User can set frame height before initialization or after. Some video source classes may set height automatically.
gainMode	int	Gain mode. Value depends on implementation but it is recommended to keep default values: 0 - Manual control, 1 - Auto.
gain	int	Gain value. Value: 0(min for particular video source class) - 65535(max for particular video source class).
exposureMode	int	Exposure mode. Value depends on implementation but it is recommended to keep default values: 0 - Manual control, 1 - Auto.
exposure	int	Exposure value. Value: 0(min for particular video source class) - 65535(max for particular video source class).
focusMode	int	Focus mode. Value depends on implementation but it is recommended to keep default values: 0 - Manual control, 1 - Auto.
focusPos	int	Focus position. Value: 0(full near) - 65535(full far).
cycleTimeMks	int	Video capture cycle time. **VSource** class sets this value automatically. This parameter means time interval between two captured video frame.
fps	float	FPS. User can set frame FPS before initialization or after. Some video source classes may set FPS automatically.
isOpen	bool	Open flag. false - not open, true - open.
roiX	int	Region of intrest x coordinate.
roiY	int	Region of intrest y coordinate.
roiWidth	int	Region of intrest width.
roiHeight	int	Region of intrest heigth.
custom1	float	Custom parameter. Depends on implementation.

Field	type	Description
custom2	float	Custom parameter. Depends on implementation.
custom3	float	Custom parameter. Depends on implementation.

None: *VSourceParams class fields listed in Table 4* **must** *reflect params set/get by methods setParam(...) and getParam(...).*

Serialize video source params

VSourceParams class provides method **encode(...)** to serialize video source params (fields of VSourceParams class, see Table 4). Serialization of video source params necessary in case when you need to send video source params via communication channels. Method doesn't encode fields: **initString** and **fourcc**. Method provides options to exclude particular parameters from serialization. To do this method inserts binary mask (2 bytes) where each bit represents particular parameter and **decode(...)** method recognizes it. Method declaration:

```cpp
bool encode(uint8_t* data, int bufferSize, int& size, VSourceParamsMask* mask = nullptr);
```

Parameter	Value
data	Pointer to data buffer.
size	Size of encoded data. 78 bytes by default.
bufferSize	Data buffer size. If buffer size smaller than required, buffer will be filled with fewer parameters.
mask	Parameters mask - pointer to **VSourceParamsMask** structure. **VSourceParamsMask** (declared in VSource.h file) determines flags for each field (parameter) declared in **VSourceParams** class. If the user wants to exclude any parameters from serialization, he can put a pointer to the mask. If the user wants to exclude a particular parameter from serialization, he should set the corresponding flag in the VSourceParamsMask structure.

VSourceParamsMask structure declaration:

```cpp
struct VSourceParamsMask
{
    bool logLevel{true};
    bool width{true};
    bool height{true};
    bool gainMode{true};
    bool gain{true};
    bool exposureMode{true};
    bool exposure{true};
    bool focusMode{true};
    bool focusPos{true};
    bool cycleTimeMks{true};
    bool fps{true};
```

```cpp
    bool isOpen{true};
    bool roiX{true};
    bool roiY{true};
    bool roiWidth{true};
    bool roiHeight{true};
    bool custom1{true};
    bool custom2{true};
    bool custom3{true};
};
```

Example without parameters mask:

```cpp
// Prepare random params.
VSourceParams in;
in.initString = "alsfghljb";
in.logLevel = 0;

// Encode data.
uint8_t data[1024];
int size = 0;
in.encode(data, 1024, size);
cout << "Encoded data size: " << size << " bytes" << endl;
```

Example without parameters mask:

```cpp
// Prepare random params.
VSourceParams in;
in.initString = "alsfghljb";
in.logLevel = 0;

// Prepare params mask.
VSourceParamsMask mask;
mask.logLevel = false; // Exclude logLevel. Others by default.

// Encode data.
uint8_t data[1024];
int size = 0;
in.encode(data, 1024, size, &mask);
cout << "Encoded data size: " << size << " bytes" << endl;
```

Deserialize video source params

VSourceParams class provides method **decode(...)** to deserialize video source params (fields of VSourceParams class, see Table 4). Deserialization of video source params necessary in case when you need to receive video source params via communication channels. Method doesn't decode fields: **initString** and **fourcc**. Method automatically recognizes which parameters were serialized by **encode(...)** method. Method declaration:

```cpp
bool decode(uint8_t* data, int dataSize);
```

Parameter	Value
data	Pointer to encode data buffer. Data size should be at least **62** bytes.
dataSize	Size of data.

Returns: TRUE if data decoded (deserialized) or FALSE if not.

Example:

```
// Encode data.
VSourceParams in;
uint8_t data[1024];
int size = 0;
in.encode(data, 1024, size);

cout << "Encoded data size: " << size << " bytes" << endl;

// Decode data.
VSourceParams out;
if (!out.decode(data, size))
    cout << "Can't decode data" << endl;
```

Read params from JSON file and write to JSON file

VSource library depends on **ConfigReader** library which provides method to read params from JSON file and to write params to JSON file. Example of writing and reading params to JSON file:

```
// Write params to file.
VSurceParams in;
cr::utils::ConfigReader inConfig;
inConfig.set(in, "vSourceParams");
inConfig.writeToFile("TestVSourceParams.json");

// Read params from file.
cr::utils::ConfigReader outConfig;
if(!outConfig.readFromFile("TestVSourceParams.json"))
{
    cout << "Can't open config file" << endl;
    return false;
}
```

TestVSourceParams.json will look like:

```
{
    "vSourceParams": {
        "custom1": 150.0,
        "custom2": 252.0,
        "custom3": 30.0,
        "exposureMode": 226,
        "focusMode": 89,
        "fourcc": "skdfjhvk",
```

```
        "fps": 206.0,
        "gainMode": 180,
        "height": 61,
        "logLevel": 17,
        "roiHeight": 249,
        "roiWidth": 167,
        "roiX": 39,
        "roiY": 223,
        "source": "alsfghljb",
        "width": 35
    }
}
```

Build and connect to your project

Typical commands to build **VSource** library:

```
git clone https://github.com/ConstantRobotics-Ltd/VSource.git
cd VSource
git submodule update --init --recursive
mkdir build
cd build
cmake ..
make
```

If you want connect **VSource** library to your CMake project as source code you can make follow. For example, if your repository has structure:

```
CMakeLists.txt
src
    CMakeList.txt
    yourLib.h
    yourLib.cpp
```

You can add repository **VSource** as submodule by commands:

```
cd <your respository folder>
git submodule add https://github.com/ConstantRobotics-Ltd/VSource.git 3rdparty/VSource
git submodule update --init --recursive
```

In you repository folder will be created folder **3rdparty/VSource** which contains files of **VSource** repository with subrepositories **Frame** and **ConfigReader**. New structure of your repository:

```
CMakeLists.txt
src
    CMakeList.txt
    yourLib.h
    yourLib.cpp
3rdparty
    VSource
```

Create CMakeLists.txt file in **3rdparty** folder. CMakeLists.txt should contain:

```cmake
cmake_minimum_required(VERSION 3.13)

################################################################################
## 3RD-PARTY
## dependencies for the project
################################################################################
project(3rdparty LANGUAGES CXX)

################################################################################
## SETTINGS
## basic 3rd-party settings before use
################################################################################
# To inherit the top-level architecture when the project is used as a submodule.
SET(PARENT ${PARENT}_YOUR_PROJECT_3RDPARTY)
# Disable self-overwriting of parameters inside included subdirectories.
SET(${PARENT}_SUBMODULE_CACHE_OVERWRITE OFF CACHE BOOL "" FORCE)

################################################################################
## CONFIGURATION
## 3rd-party submodules configuration
################################################################################
SET(${PARENT}_SUBMODULE_VSOURCE                    ON  CACHE BOOL "" FORCE)
if (${PARENT}_SUBMODULE_VSOURCE)
    SET(${PARENT}_VSOURCE                          ON  CACHE BOOL "" FORCE)
    SET(${PARENT}_VSOURCE_TEST                     OFF CACHE BOOL "" FORCE)
    SET(${PARENT}_VSOURCE_EXAMPLE                  OFF CACHE BOOL "" FORCE)
endif()

################################################################################
## INCLUDING SUBDIRECTORIES
## Adding subdirectories according to the 3rd-party configuration
################################################################################
if (${PARENT}_SUBMODULE_VSOURCE)
    add_subdirectory(VSource)
endif()
```

File **3rdparty/CMakeLists.txt** adds folder **VSource** to your project and excludes test application and example (VSource class test applications and example of custom video source class implementation) from compiling. Your repository new structure will be:

```
CMakeLists.txt
src
    CMakeList.txt
    yourLib.h
    yourLib.cpp
3rdparty
    CMakeLists.txt
    VSource
```

Next you need include folder 3rdparty in main **CMakeLists.txt** file of your repository. Add string at the end of your main **CMakeLists.txt**:

```
add_subdirectory(3rdparty)
```

Next you have to include VSource library in your **src/CMakeLists.txt** file:

```
target_link_libraries(${PROJECT_NAME} VSource)
```

Done!

How to make custom implementation

The **VSource** class provides only an interface, data structures, and methods for encoding and decoding commands and params. To create your own implementation of the video source, you must include the VSource repository in your project (see Build and connect to your project section). The catalogue **example** (see Library files section) includes an example of the design of the custom video source. You must implement all the methods of the VSource interface class. Custom video source class declaration:

```cpp
class CustomVSource: public VSource
{
public:

    /// Class constructor.
    CustomVSource();

    /// Class destructor.
    ~CustomVSource();

    /// Get string of current library version.
    static std::string getVersion();

    /// Open video source.
    bool openVSource(std::string& initString);

    /// Init video source.
    bool initVSource(VSourceParams& params);

    /// Get open status.
    bool isVSourceOpen();

    /// Close video source.
    void closeVSource();

    /// Get new video frame.
    bool getFrame(Frame& frame, int32_t timeoutMsec = 0);

    /// Set video source param.
    bool setParam(VSourceParam id, float value);

    /// Get video source param value.
    float getParam(VSourceParam id);

    /// Get video source params structure.
```

```cpp
    void getParams(VSourceParams& params);

    /// Execute command.
    bool executeCommand(VSourceCommand id);

    /// Decode and execute command.
    bool decodeAndExecuteCommand(uint8_t* data, int size);

private:

    /// Video source params.
    VSourceParams m_params;
    /// Output frame.
    Frame m_outputFrame;
};
```