



FLEXURAL-AXIAL SYSTEMS: F R A M E S

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Municipal Stadium,
Florence, 1932, Pier
Luigi Nervi

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Glass House, New Canaan, Conn., 1949, Philip Johnson



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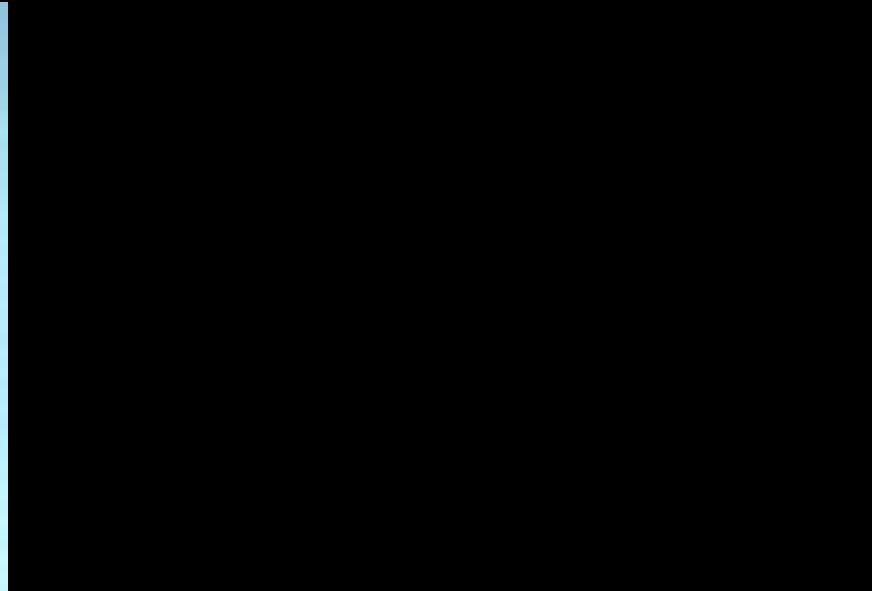


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Republic Newspaper Plant, Columbus,
Indiana, 1971, Myron Goldsmith/ SOM

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Reliance Controls factory
Swindon, 1967, Team 4, Hunt

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Cummins Engine Component Plant
Columbus, IN, 1965, Roche & Dinkeloo



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Lake Shore Drive Apts Chicago, Ludwig Mies van der Rohe, at Chicago, 1948 to 1951
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Museum of Modern Art, Rio de Janeiro, Brazil, 1958, Alfonso Eduardo Reidy



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Beijing, 2006



Beijing, 2006

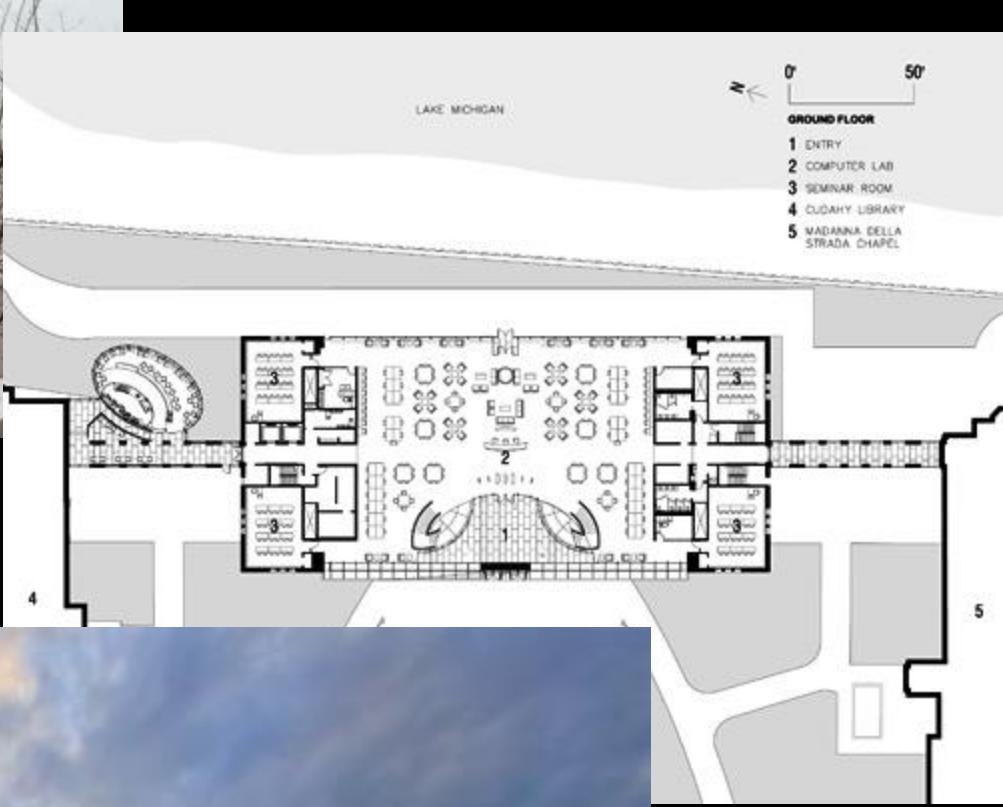
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Richard J. Klarchek Information Commons, Loyola University Chicago,
2007, Solomon Cordwell Buenz,
Halvorson and Partners Struct.



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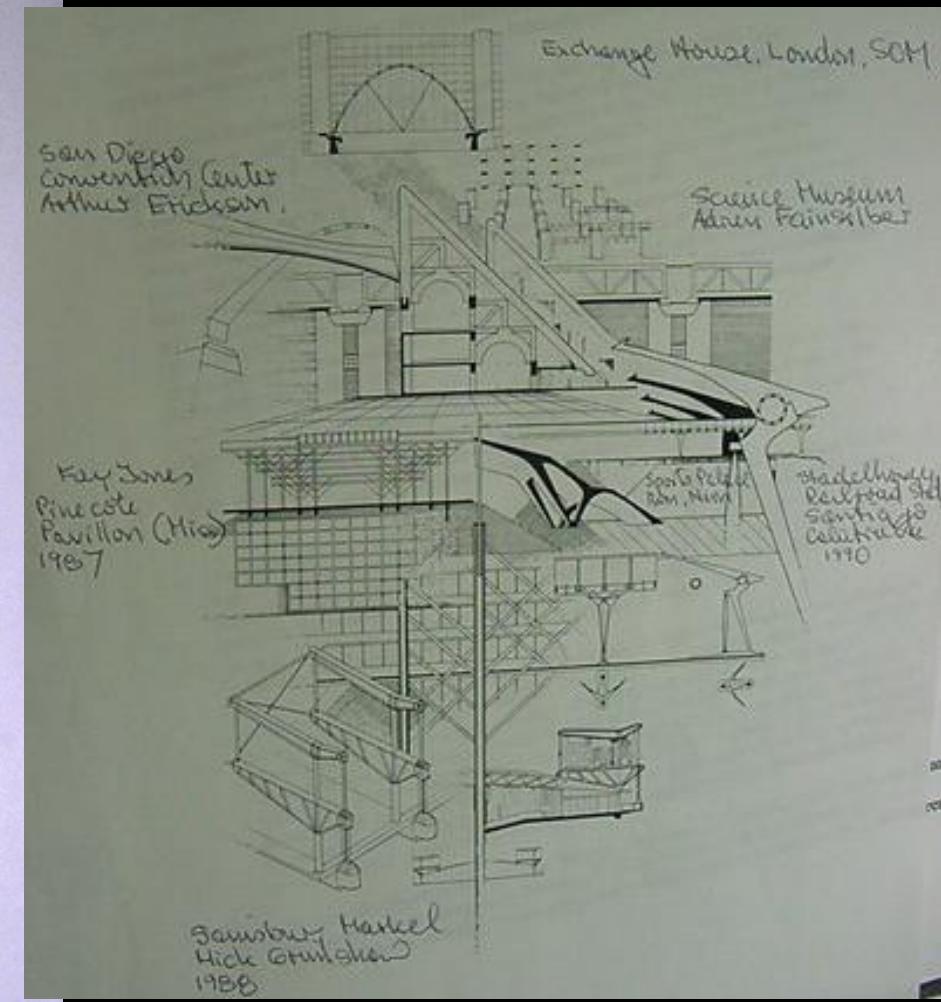
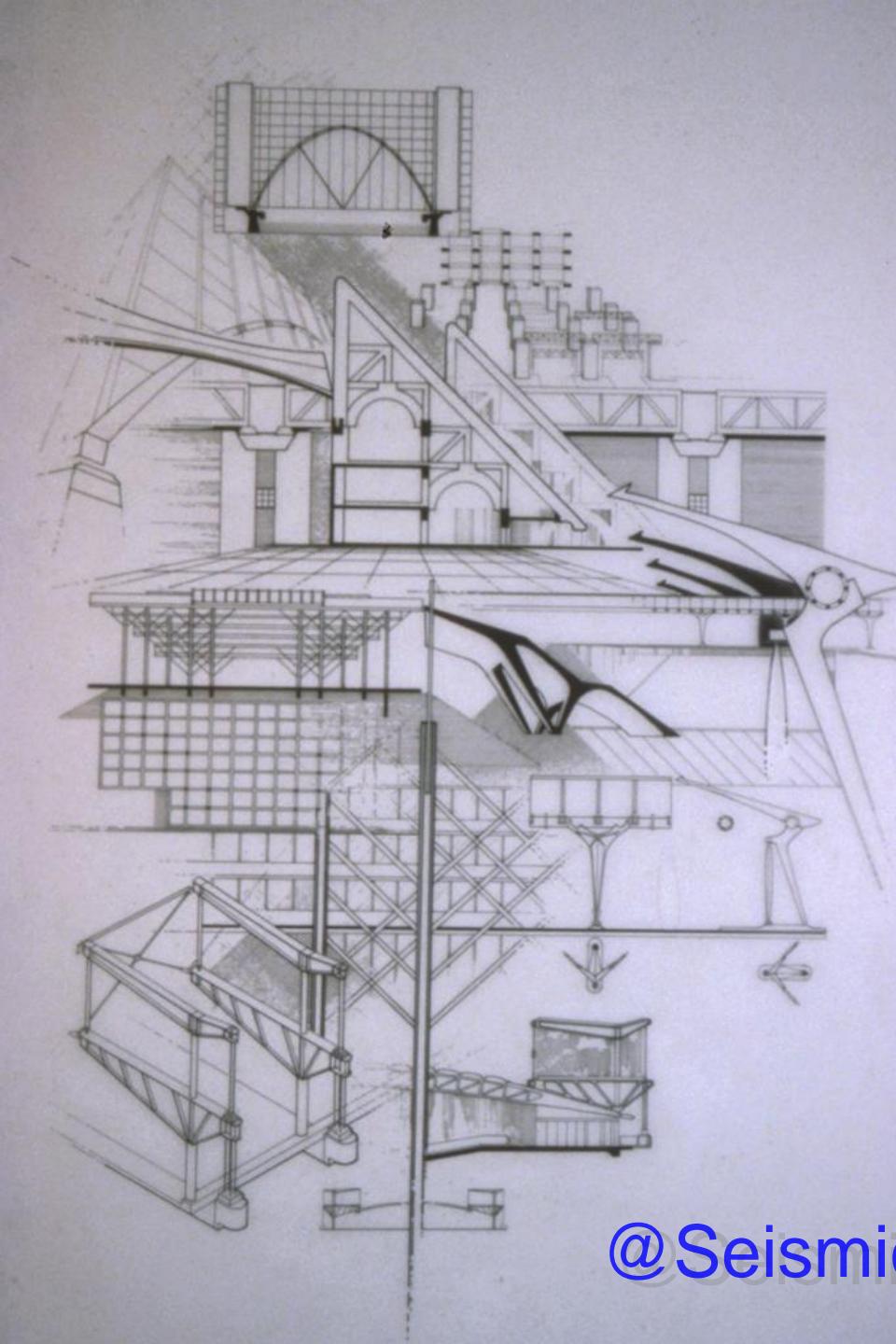


Richard J. Klarchek Information
Commons, Loyola University Chicago,
2007 Selman Cordwell Buenz, Halvorson
and Partners Struct.



**Richard J. Klarchek
Information
Commons**, Loyola
University Chicago,
2007, Solomon
Cordwell Buenz,
Halvorson and Partners
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Frames, arches, trusses
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Structure Systems & Structure Behavior

INTRODUCTION TO STRUCTURAL CONCEPTS

SKELETON STRUCTURES

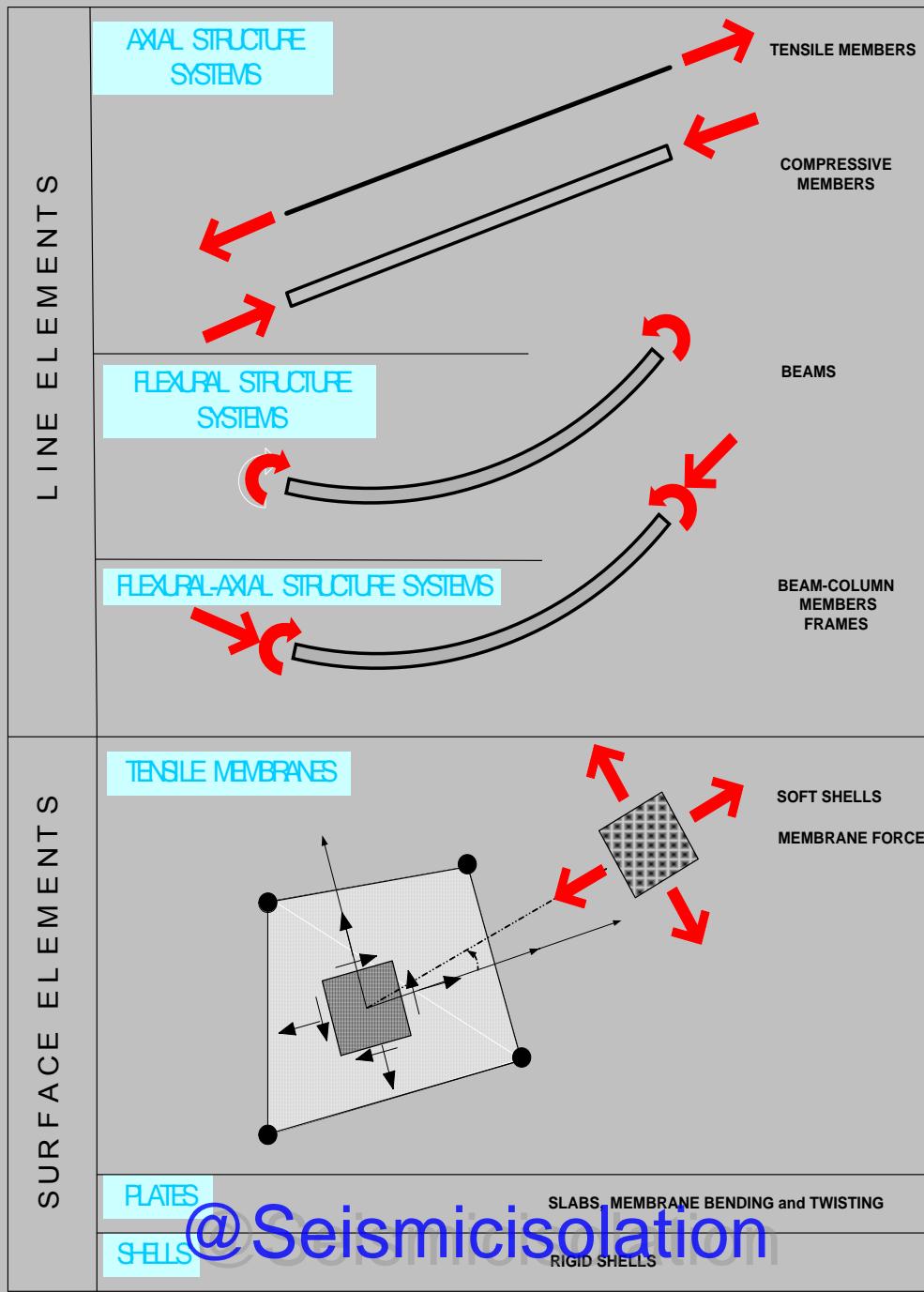
- Axial Systems
- Beams
- Frames
- Arches
- Cable-supported Structures

SURFACE STRUCTURES

- Membranes: beams, walls
- Plates: slabs
- Hard shells
- Soft shells: tensile membranes
- Hybrid tensile surface systems: tensegrity

SPACE FRAMES

LATERAL STABILITY OF STRUCTURES
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FRAMES are **flexural-axial systems** in contrast to **hinged trusses**, which are axial systems, and **beams**, which are flexural systems. Flexural-axial systems are identified by **beam-column behavior** that includes the effects of biaxial bending, torsion, axial deformation, and biaxial shear deformations.

Here, **two-dimensional skeleton structures composed of linear elements** are briefly investigated. The most common group of planar structure systems includes

post-beam structures,
bent and folded beams,
rectangular portal frames,
cantilever frames,
braced frames,
pitched frames,
arches,
and so on.

These structures may form

**short-span or long-span,
single-story or multi-story,
single-bay or multi-bay systems.**

They range from low-rise to

**single, open, large volume buildings
cellular massive buildings
skyscrapers.**

Primary emphasis here is on the investigation of simple, but common single-story enclosure systems to develop a feeling for the behavior of structures under gravity and lateral loads. Investigated are the

- response and effect of the frame profile on **uniform gravity action**
and on **lateral loading**.
- the magnitude of the internal member forces is determined so that the computer results can be checked.

Uniform Loading on Inclined Members

Simple Folded and Bent Beams

Single-bay Frames

Three-Hinged Frames

Indeterminate Frames

Cantilever Frames

Braced frames

Pitched Frames

Arches

The Geometry of the Arch

Construction of a Circular Arch with SAP

The Response of Roof Arches to Loading

Composite Systems and Form-Resistant Arches

Arches with Tensile Webs

Multi-bay Frames

Multi-bay, Single-Story Frames

Multi -Story Frames

Vierendeel Trusses

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The loading on a simply supported inclined beam is investigated in with a pin support at the base and a roller support at the top, which however may have different orientations.

The typical gravity loading of an inclined member consists of the dead load w_D acting along the structure, and the live load w_L , which is usually given by codes on the horizontal projection of the structure (a). To determine the maximum moment, it is convenient to transfer the dead load to the horizontal projection of the beam (b), since **the maximum moment of a simply supported inclined beam is equal to that for an equivalent beam on the horizontal projection carrying the same loading as the inclined beam**. In other words, the moment is independent of beam slope and support conditions.

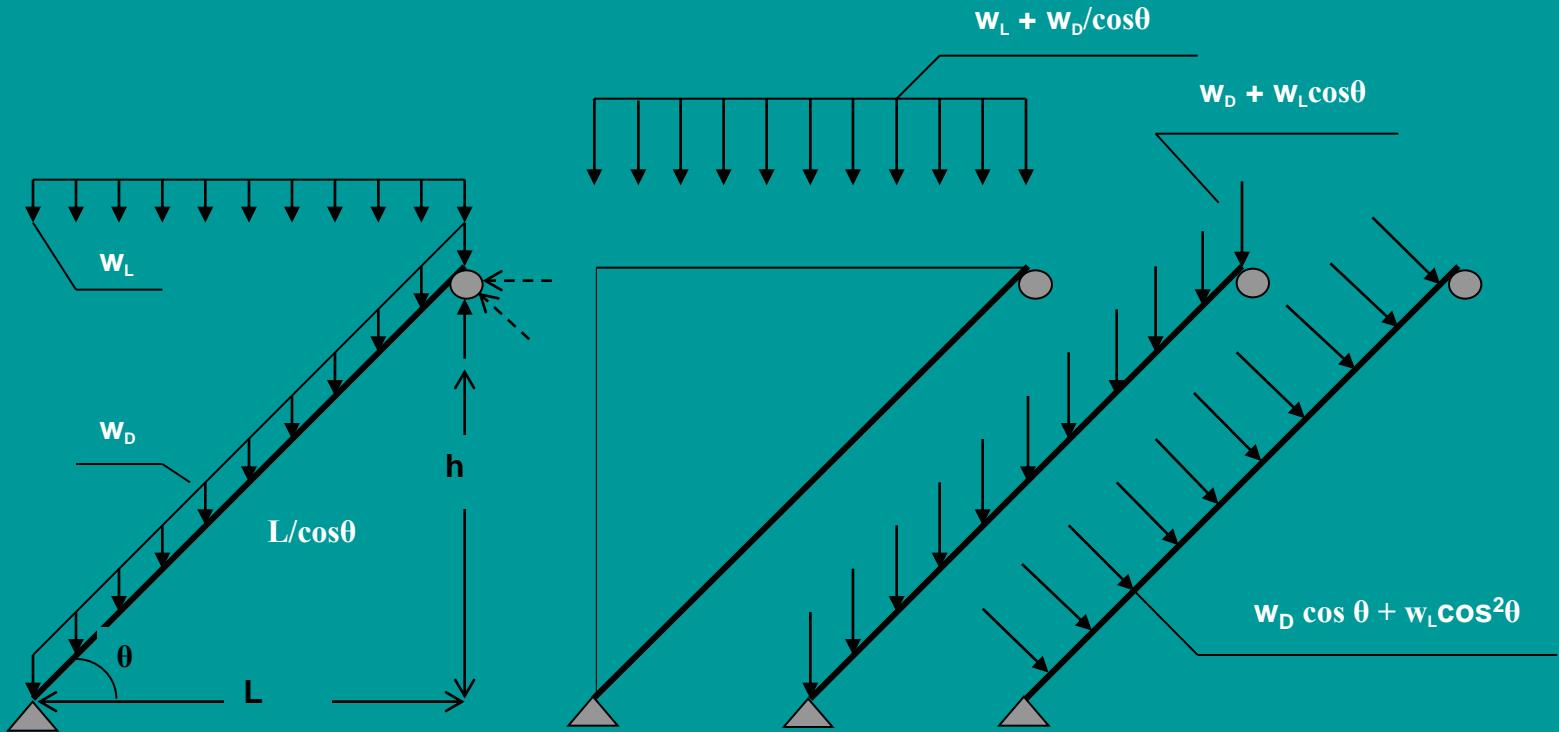
The shear depends on the beam inclination but not on the orientation of the top support. It is equal to the shear of the beam on the horizontal projection multiplied by $\cos\theta$. The parallel load components cause axial forces along the beam and are equal to the load on the horizontal projection multiplied by $\sin\theta$. The axial force flow depends on the beam inclination and on the reaction condition of the top support.

The uniform lateral loading case is analogous to the uniform gravity loading case; just visualize the span L and height h to be exchanged. For example, the maximum moment due to the wind pressure q on the vertical projection of the beam is,

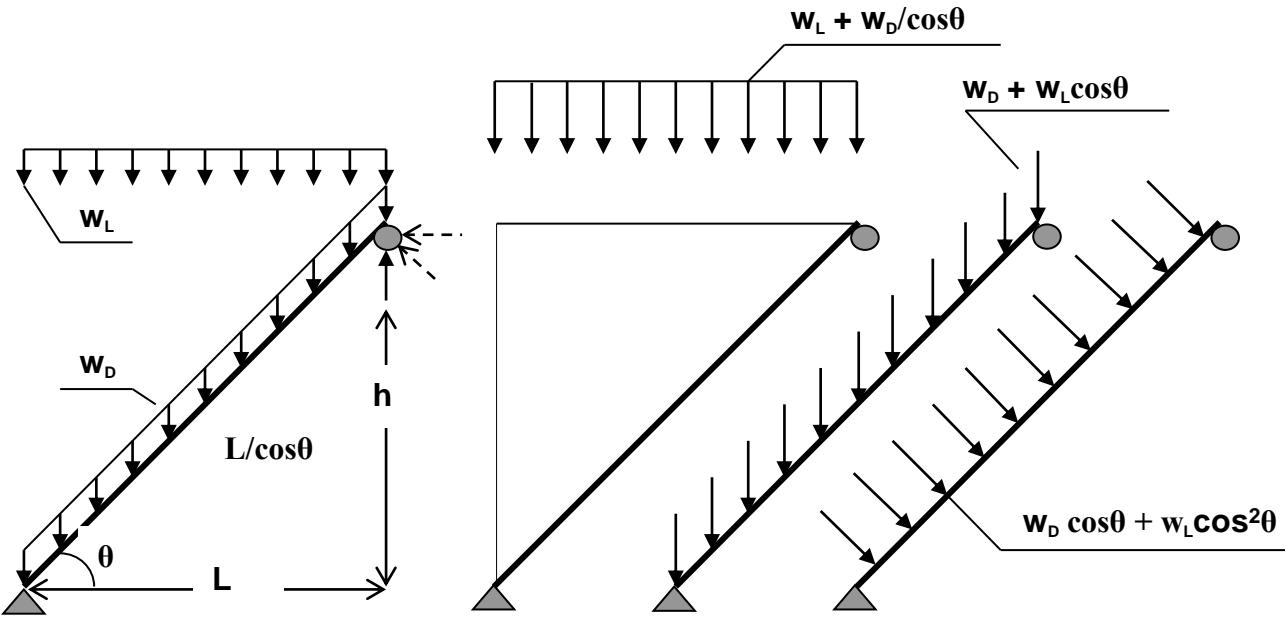
The fact that **the moment is independent of the geometry of the bent or folded beam for vertical support conditions**, is demonstrated in the drawing.

Various folded beam systems are investigated in the following drawing ranging from a simple inclined beam (B), a stair (E.), to other roof frame shapes.

Notice SAP automatically transfers the loads from the projection to an equivalent load along the member!



The parallel load component causes axial force action in the member: $(w_D + w_L\cos\theta) \sin\theta$
 and from the perpendicular load component the shear is determined: $(w_D + w_L\cos\theta) \cos\theta$



a.

b.

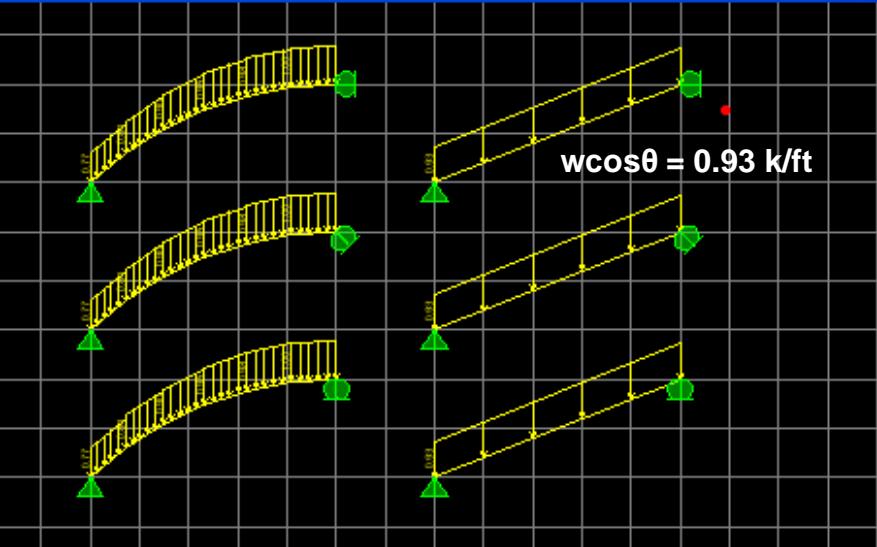
c.

d.

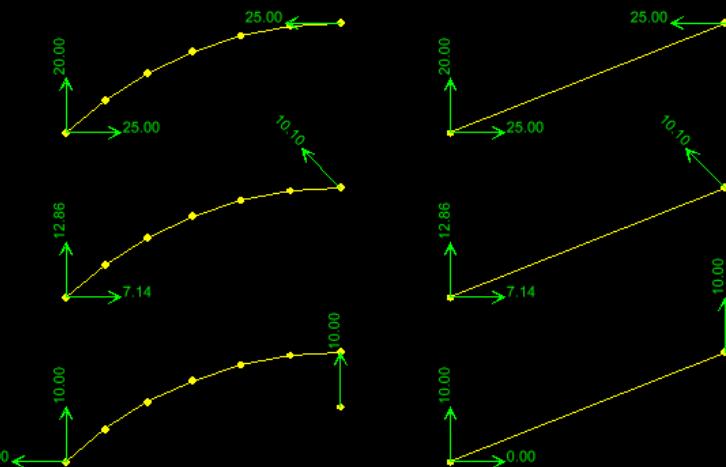
The parallel load component causes axial force action in the member: $(w_D + w_L \cos\theta) \sin\theta$ and from the perpendicular load component the shear is determined: $(w_D + w_L \cos\theta) \cos\theta$



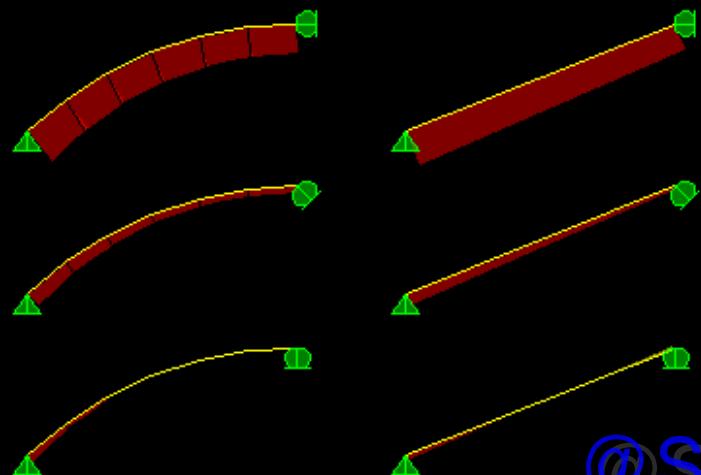
Frame Span Loads (LIVE) (As Defined)



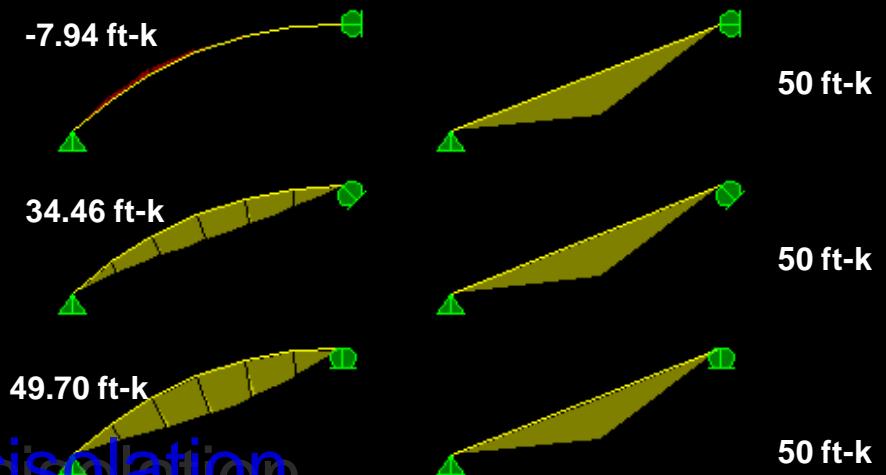
Restraint Reactions (Live)



Axial Force Diagram (Live)



Moment 3-3 Diagram (Live)



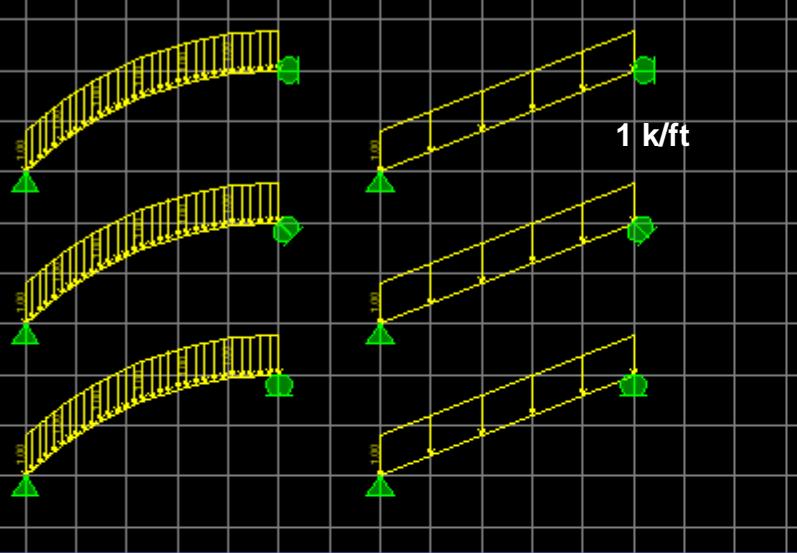
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P2000 - Fig. 7.1

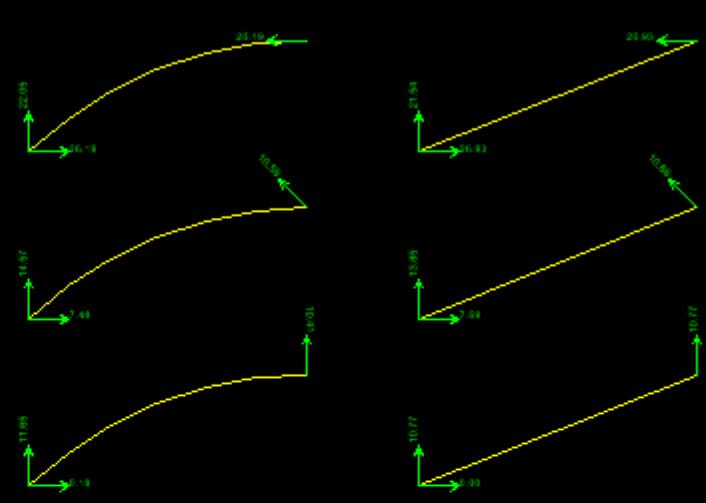
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Frame Span Loads (GRAVITY) (As Defined)



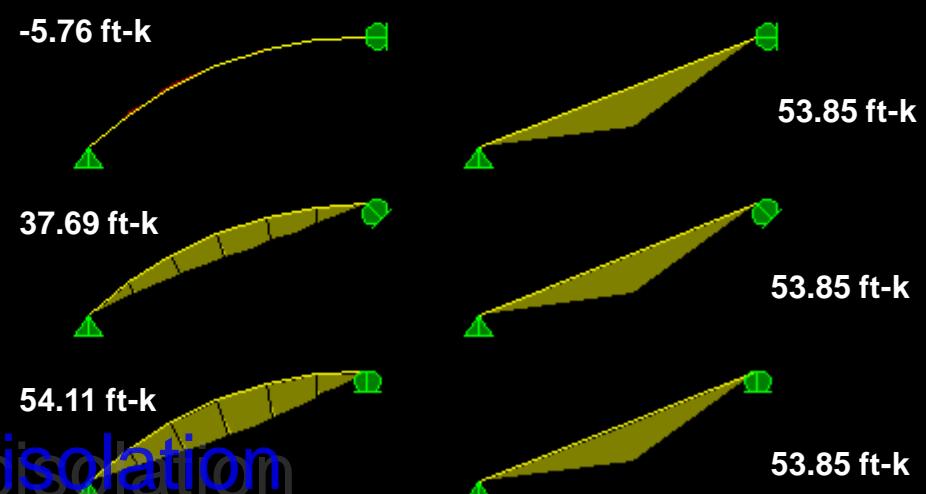
Restraint Reactions (GRAVITY)



Axial Force Diagram (GRAVITY)



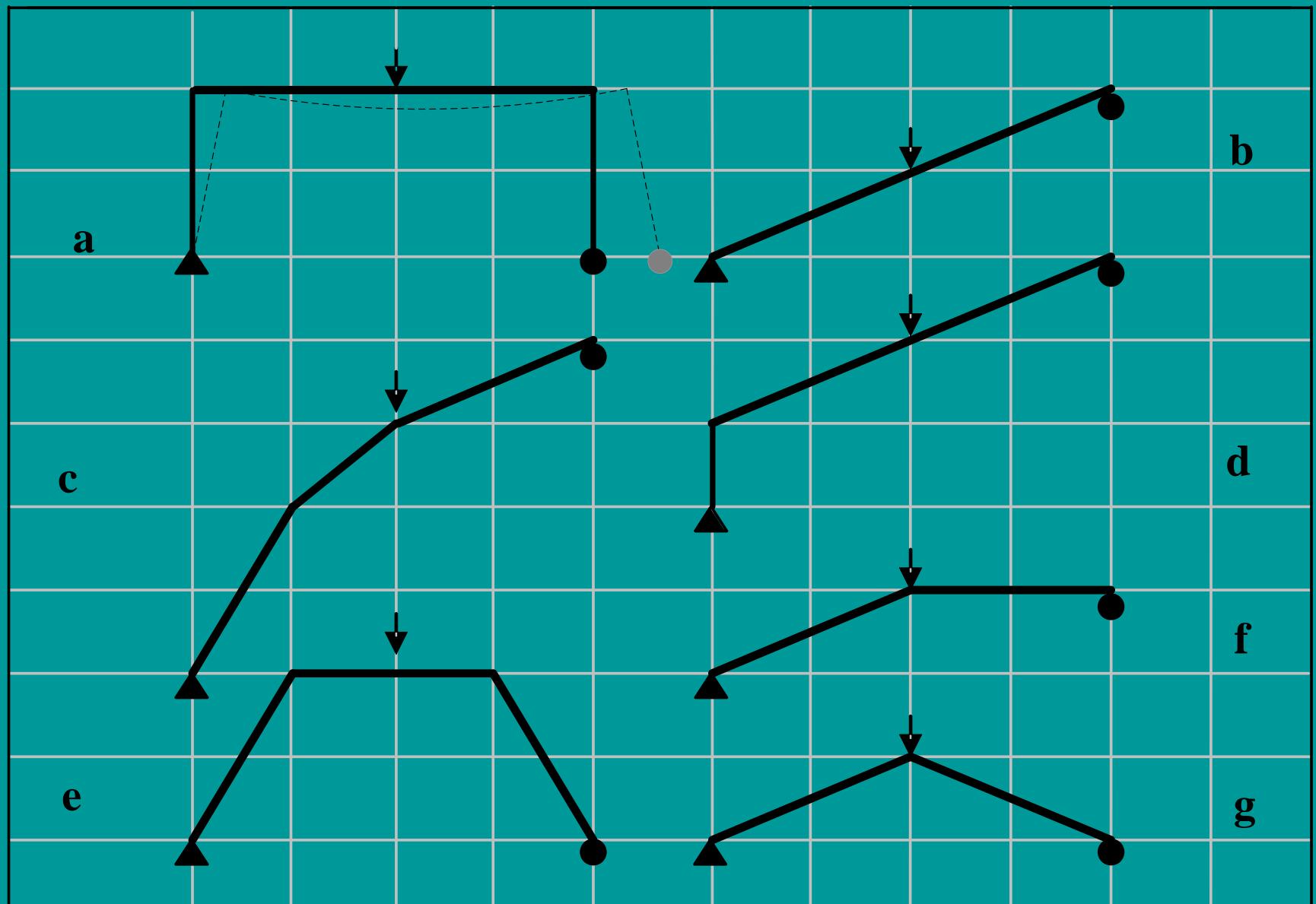
Moment 3-3 Diagram (GRAVITY)

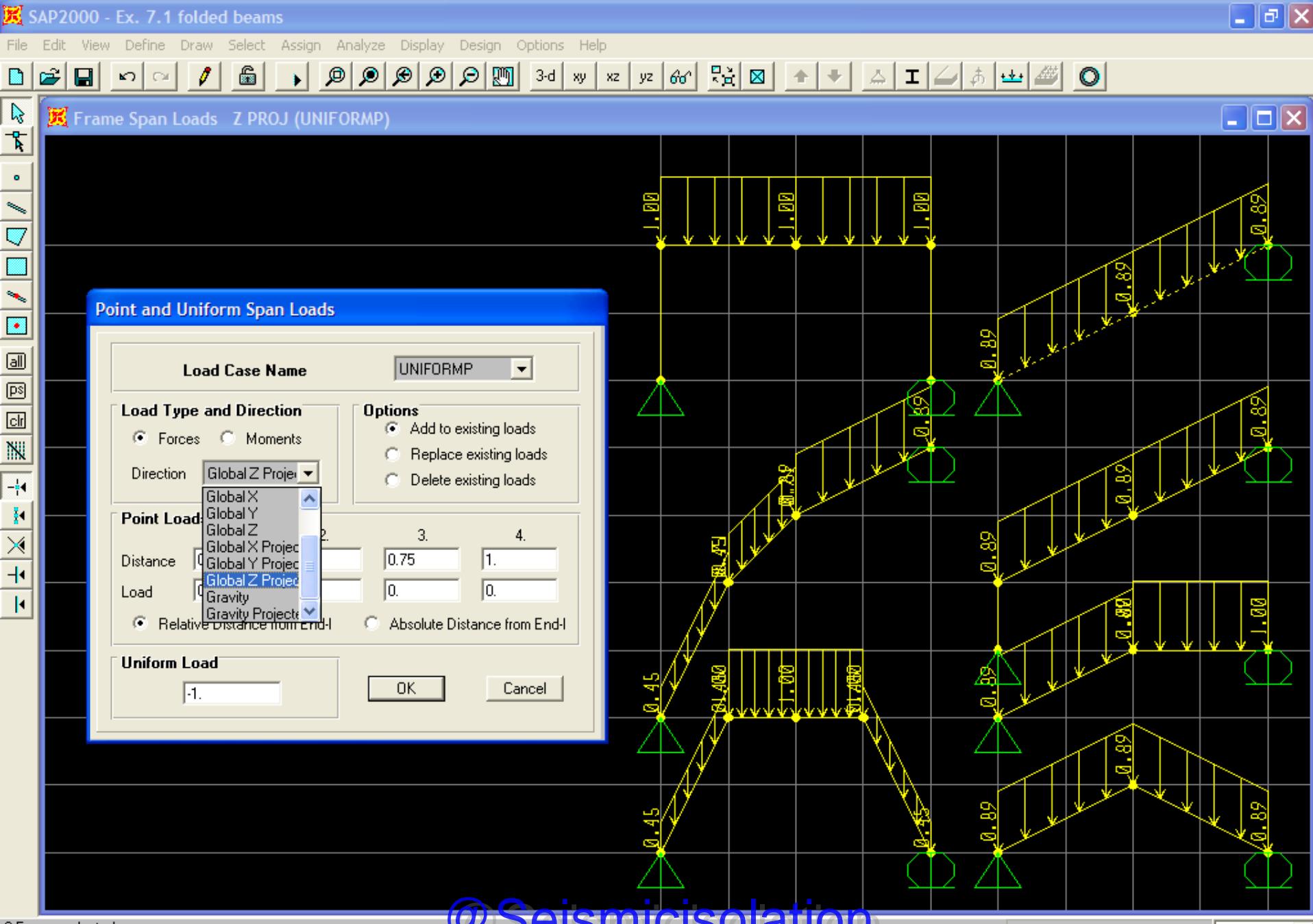


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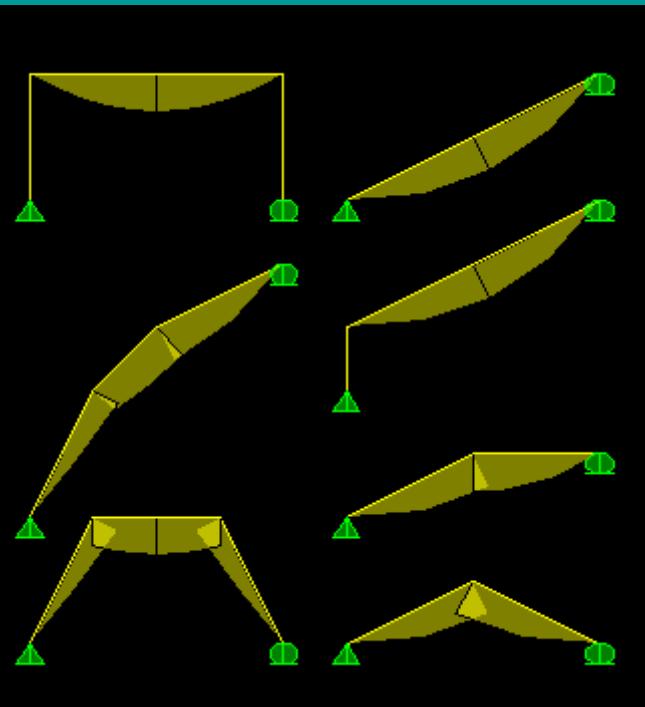
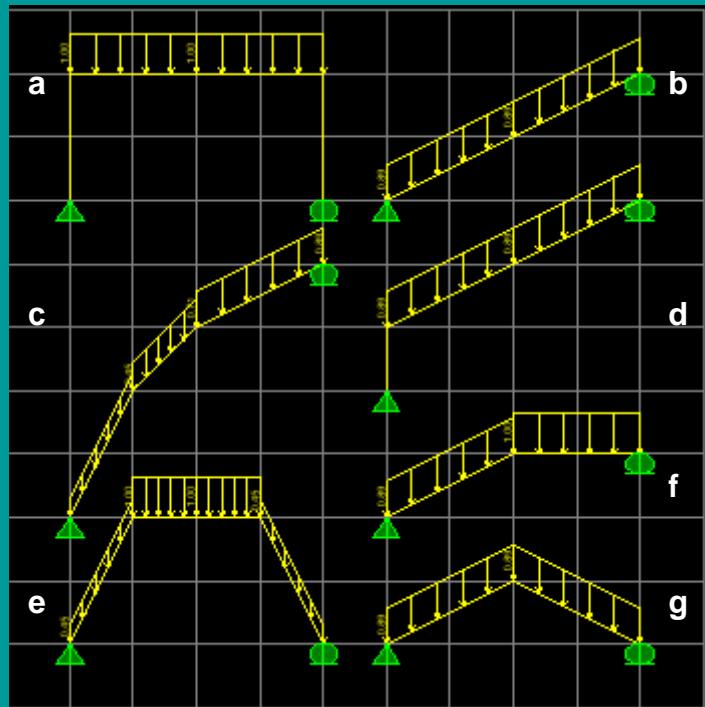


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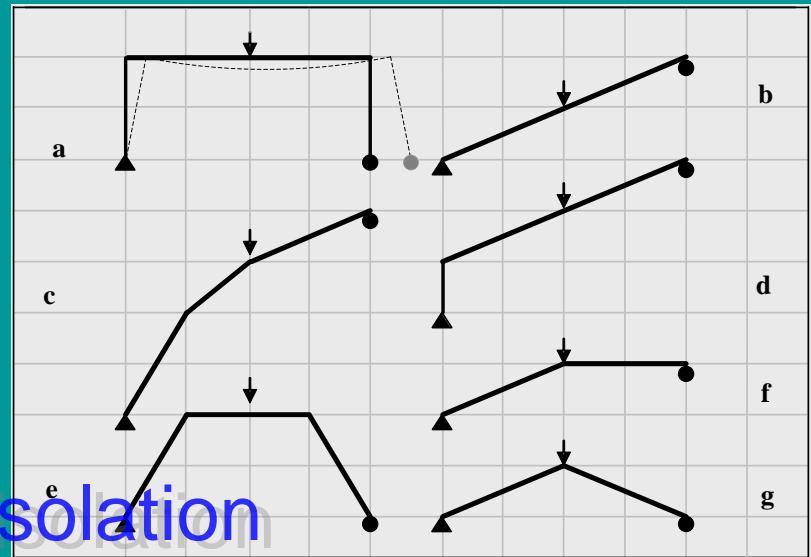




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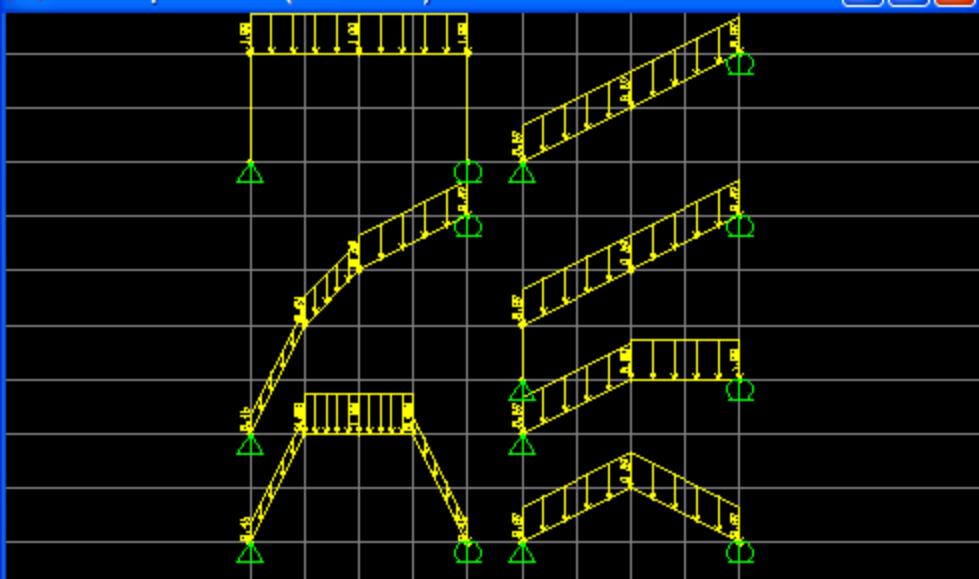
$$M_{\max} = wL^2/8$$



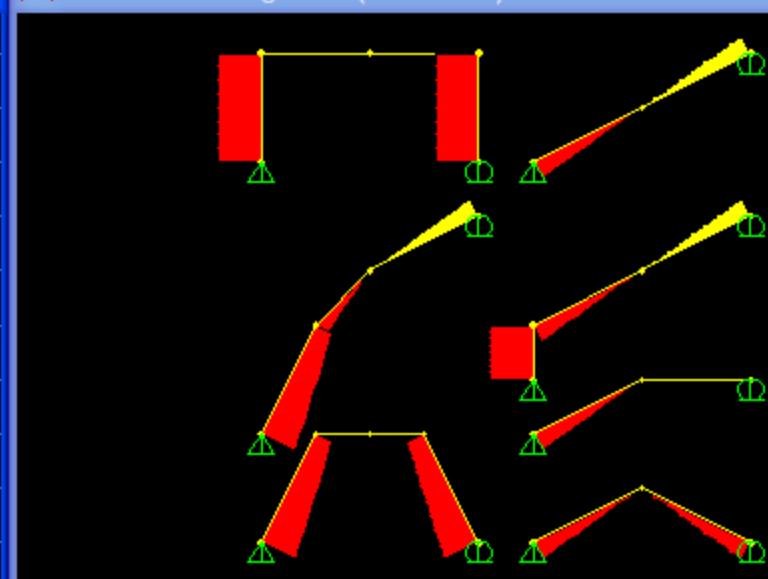
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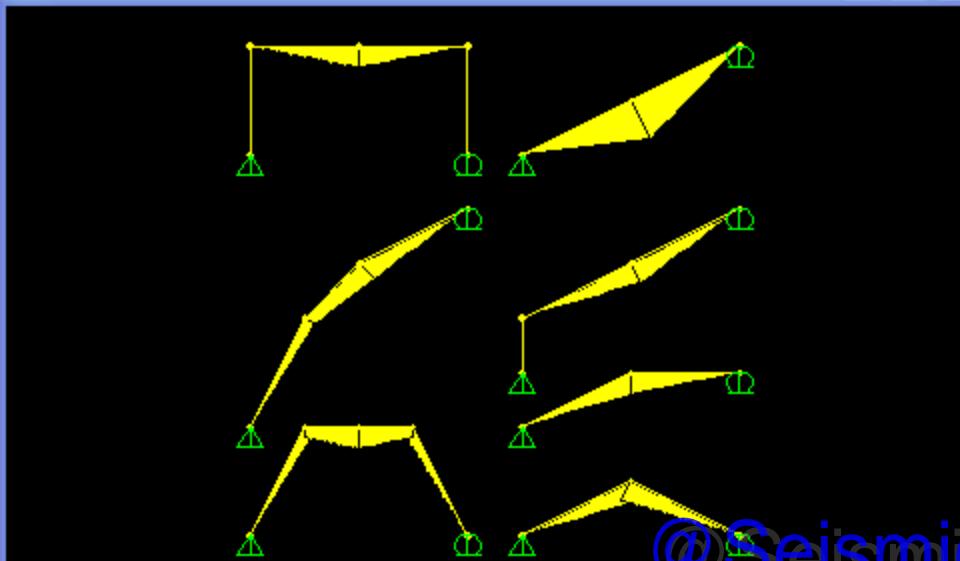
Frame Span Loads (UNIFORMP)



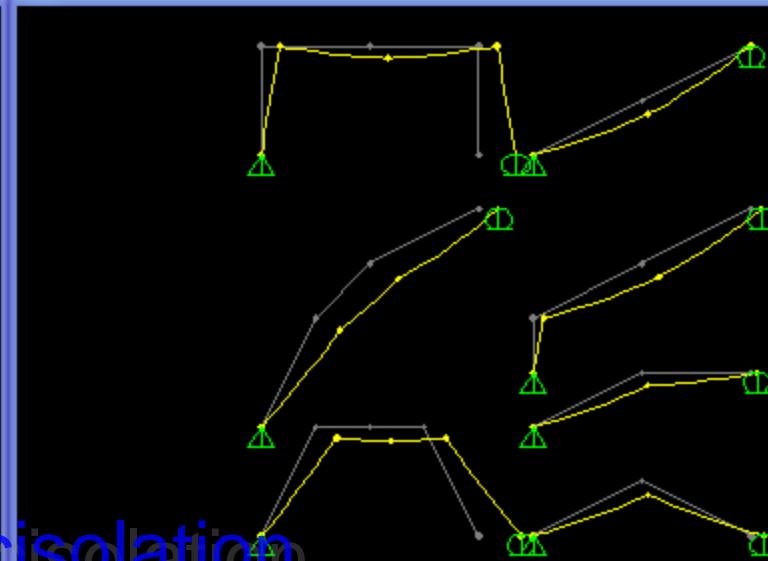
Axial Force Diagram (UNIFORMP)



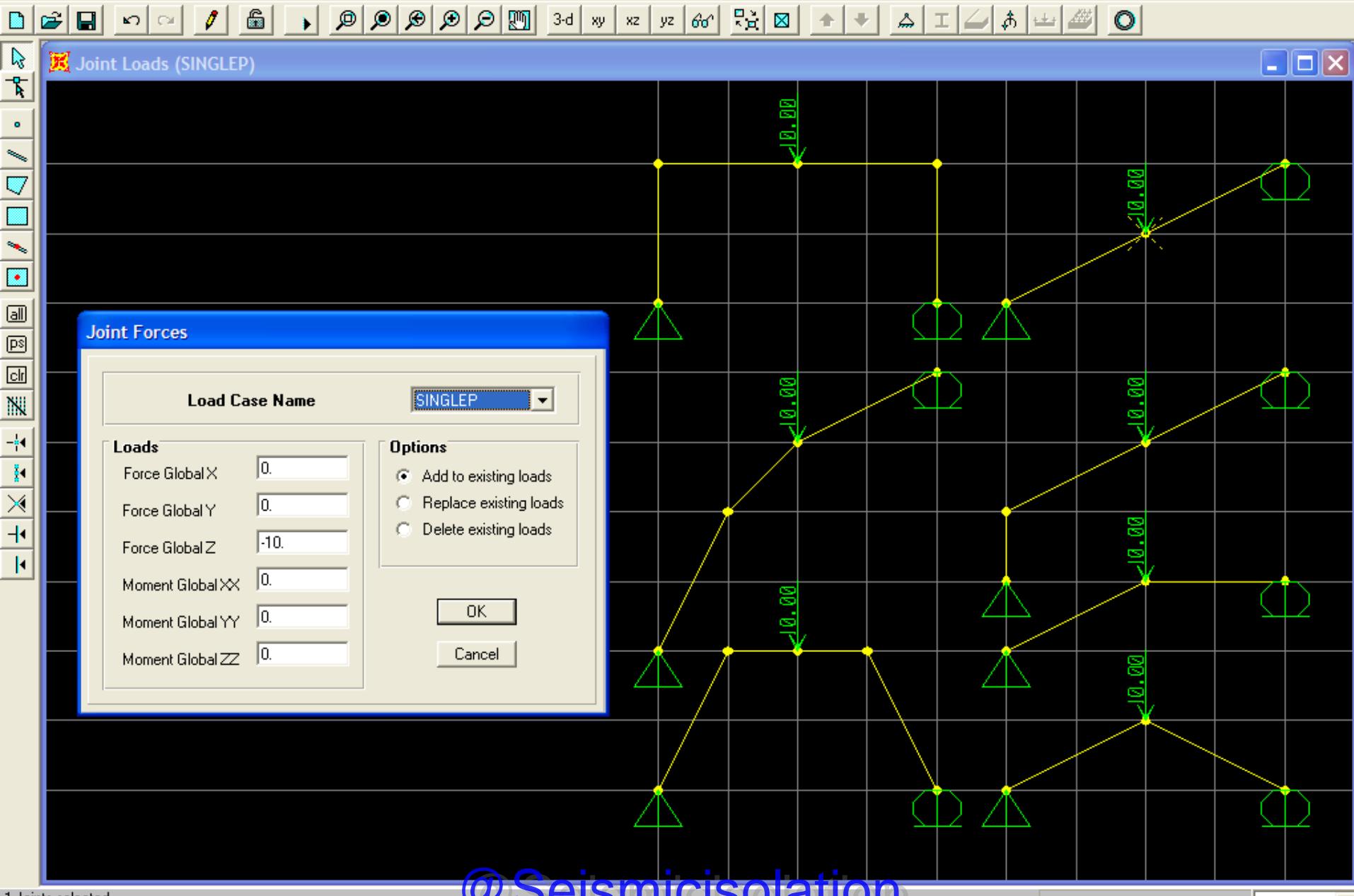
Moment 3-3 Diagram (SINGLEP)



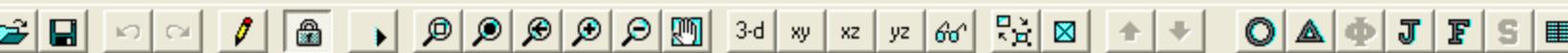
Deformed Shape (UNIFORMP)



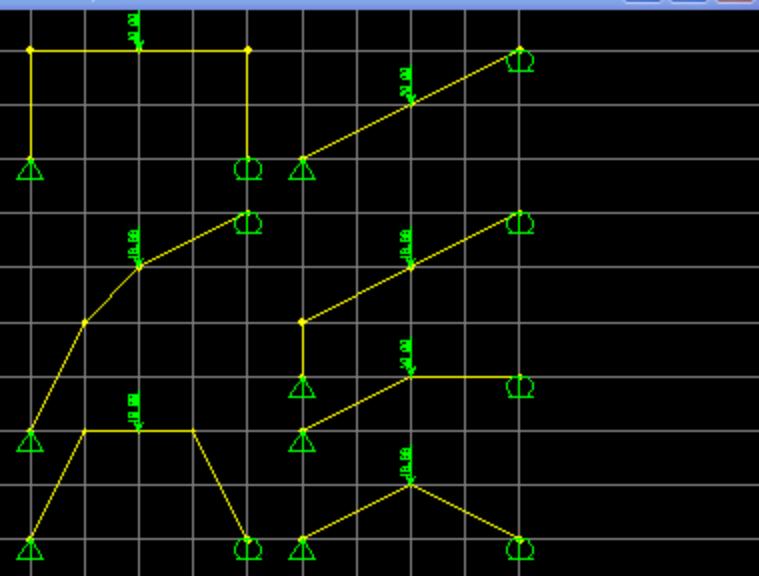
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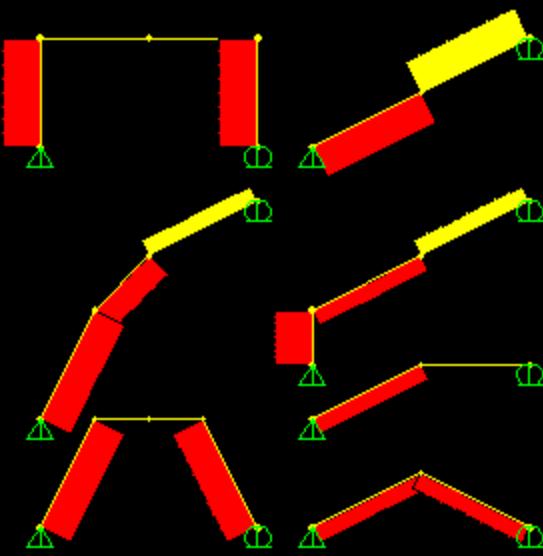
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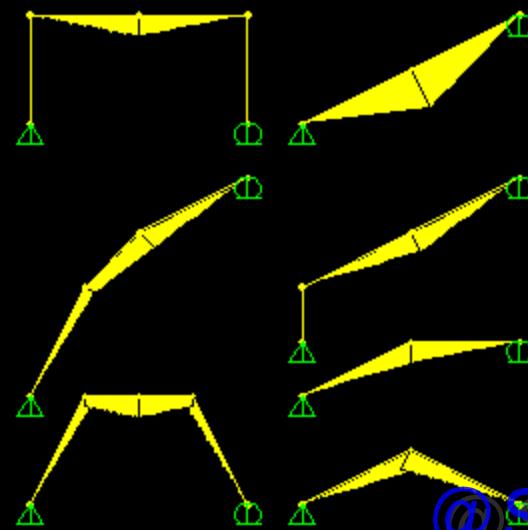
Joint Loads (SINGLEP)



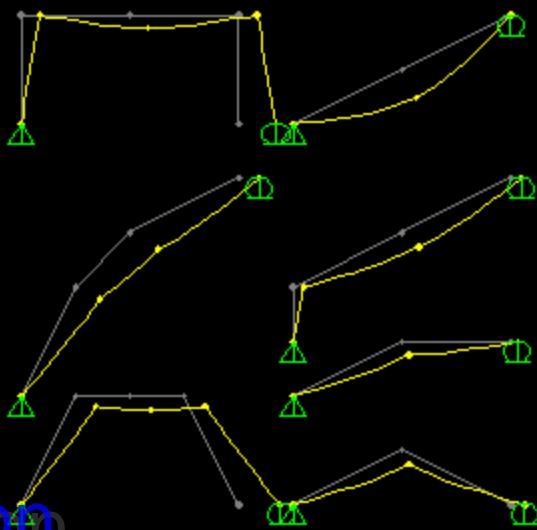
Axial Force Diagram (SINGLEP)



Moment 3-3 Diagram (SINGLEP)



Deformed Shape (SINGLEP)

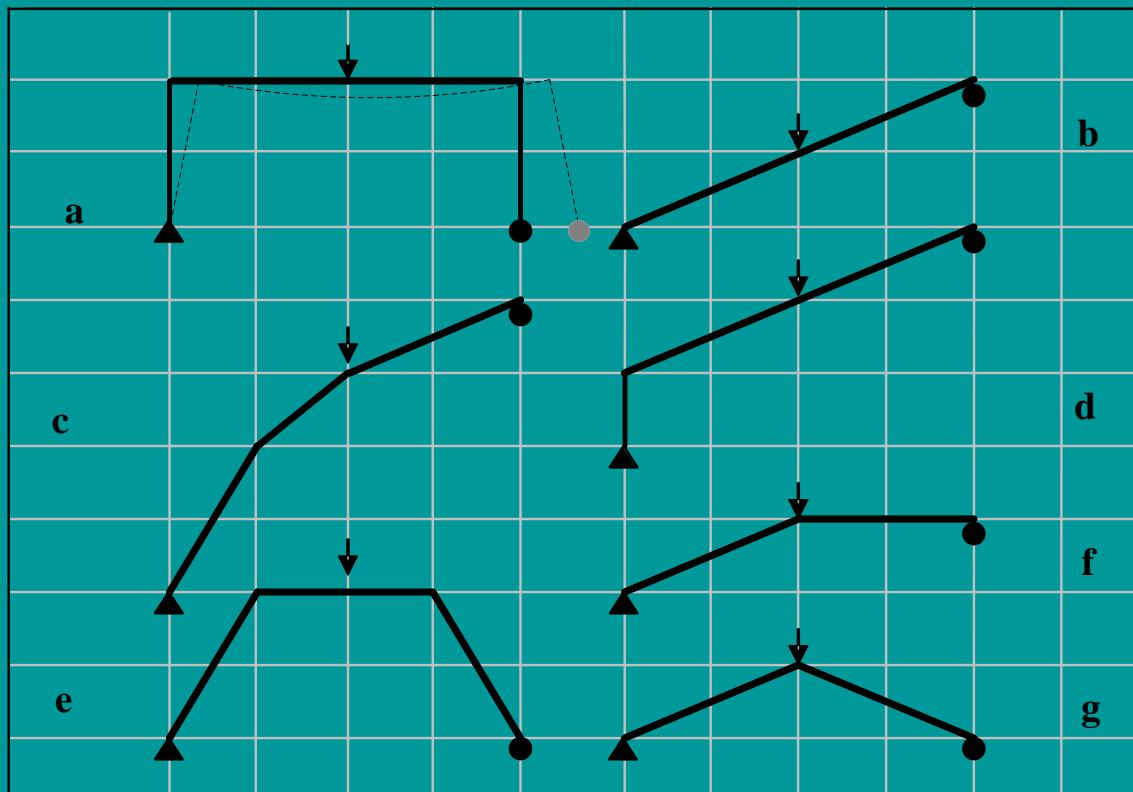


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Click on any Frame Element for detailed diagram

Kip-ft

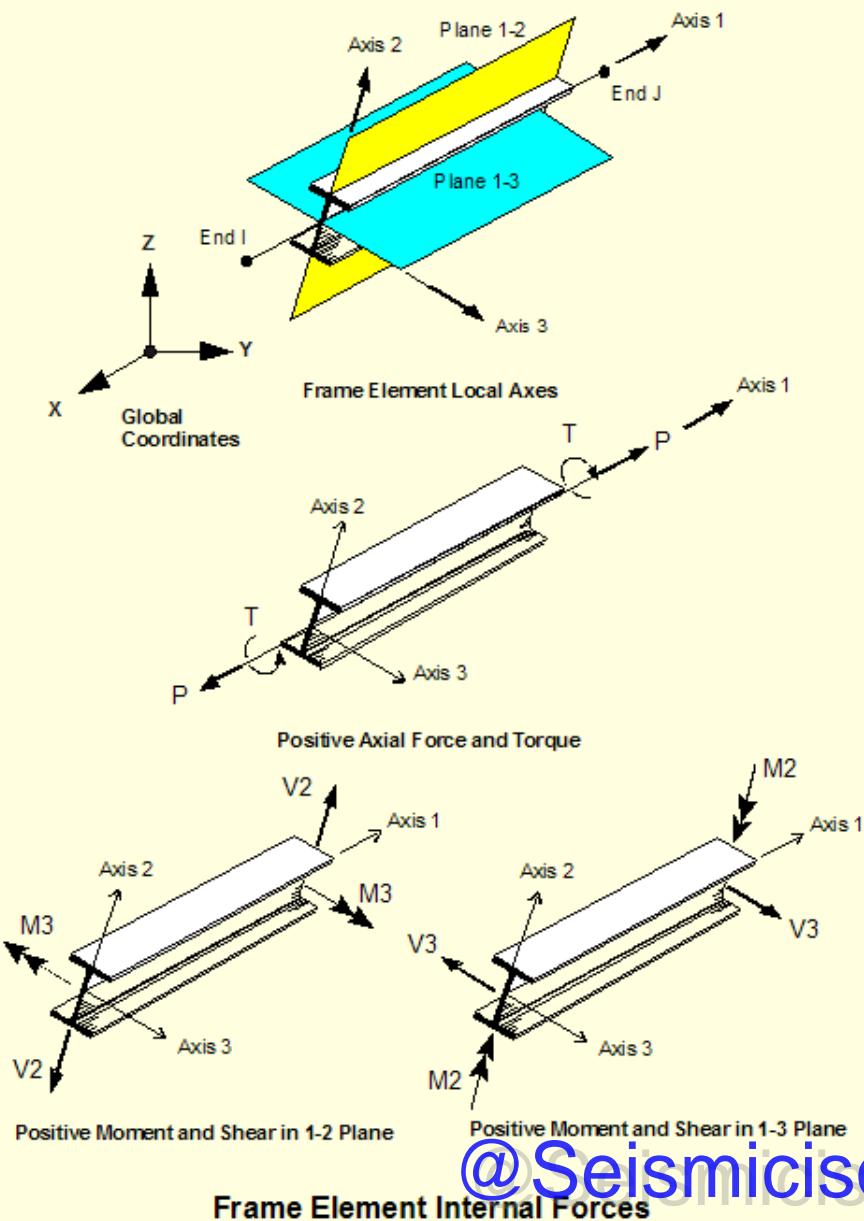
Folded Beam Structures



The magnitude of the maximum moment for simple folded or bent beams under uniform vertical loads does not change when the load is applied **on the horizontal projection** of the beams. Naturally, the magnitude of the axial forces will change.

Frame and Nllink Element

FRAME element follows the designer's convention.



MEMBER ORIENTATION

Is defined by local coordinate system

Each part of the structure (e.g. joint, element) has its own **LOCAL** coordinate system **1-2-3**.

The joint local coordinate system is normally the same as the global X-Y-Z coordinate system.

For the elements, one of the element local axes is determined by the geometry of the individual element; the orientation of the remaining two axes is defined by specifying a single angle of rotation.

For frame elements, for example, the local axis **1** is always the longitudinal axis of the element with the positive direction from **I** to **J**. The default orientation of the local **1-2** plane in SAP is taken to be vertical (i.e. parallel to the Z-axis). The local **3**-axis is always horizontal (i.e. lies in the X-Y plane).



Siam Square, Bangkok

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Ningbo downtown, 2002,
Qingyun Ma

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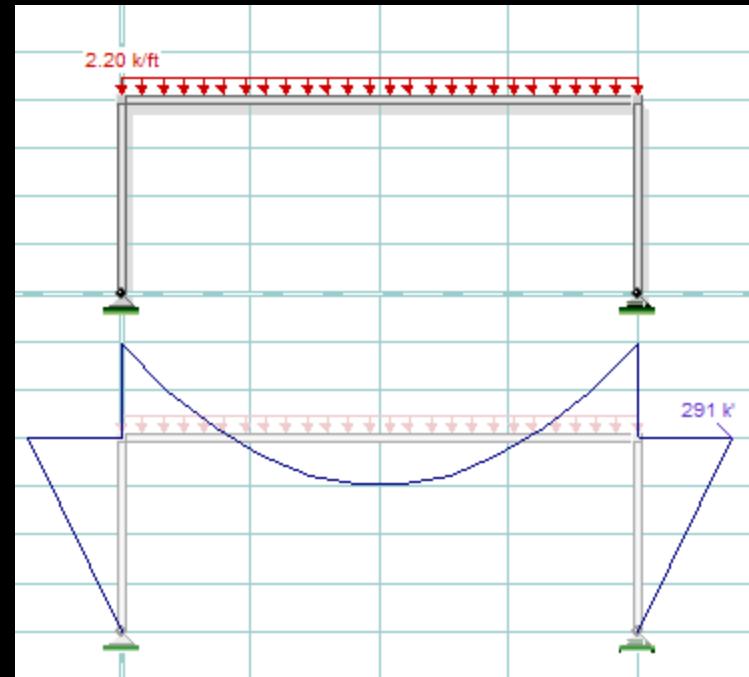
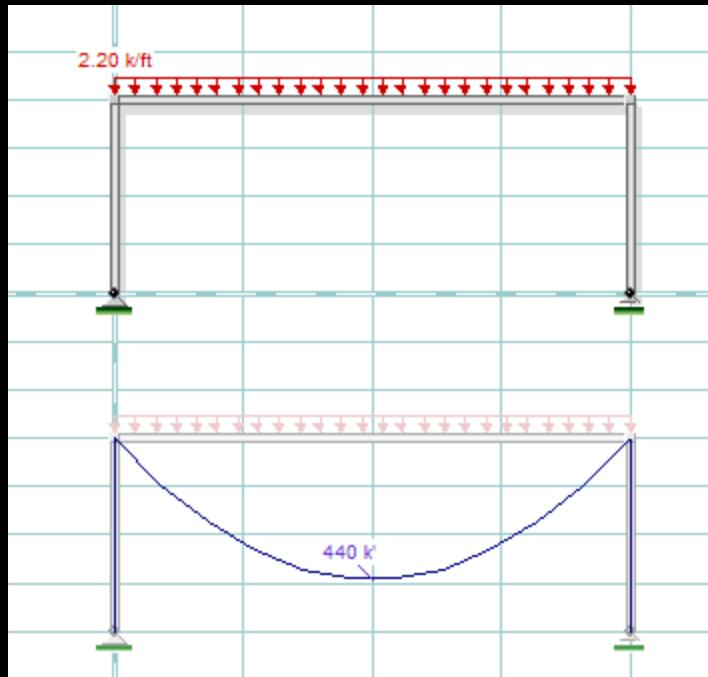


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If the **roller** in the simple folded beams is replaced by a **pin support**, horizontal thrust or kickout forces are generated by the gravity loads at the base (since the boundary conditions do not allow outward displacement), which in turn cause bending of the columns and beam.

By providing two pin supports, the structure is once indeterminate and cannot be solved directly with the equations of equilibrium as is discussed further in the next section of this book. But when an **internal hinge** is introduced somewhere along the frame one more known condition is introduced because the moment must be zero at this point, so the frame can be solved by statics.

Quite common are **three-hinged frame systems** where the hinge is placed at mid-span of the beam as demonstrated in the following drawing for various one-story, single-bay frame shapes.

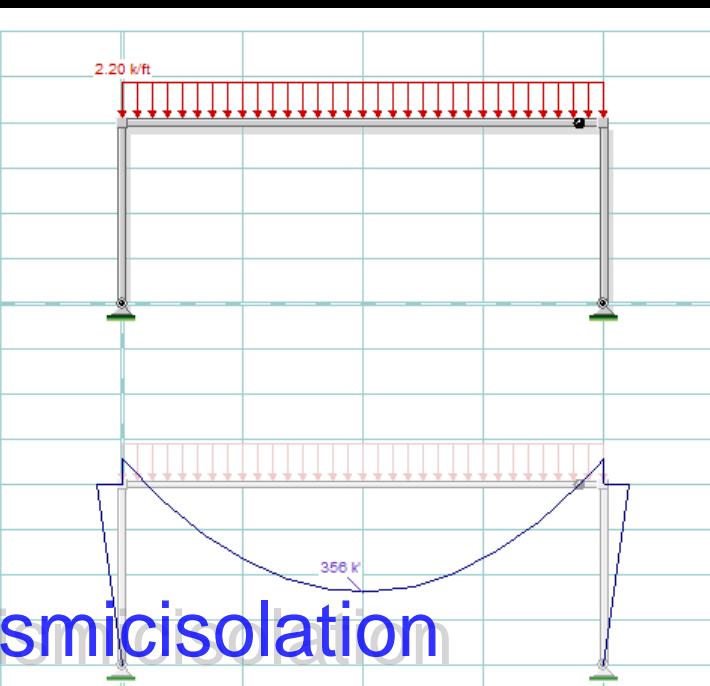
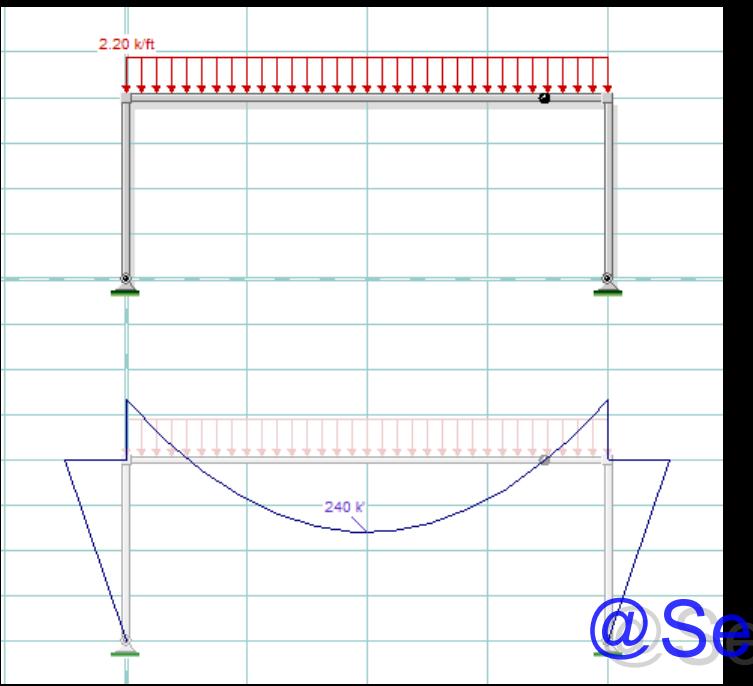
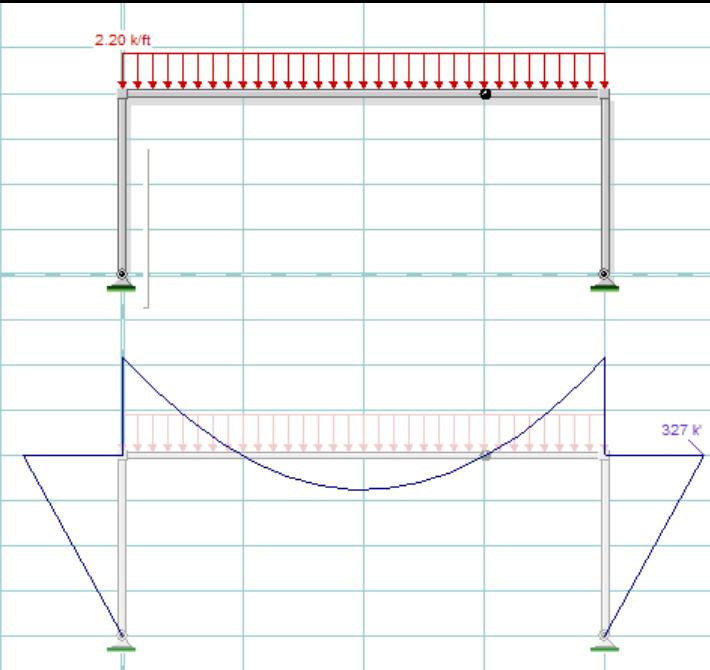
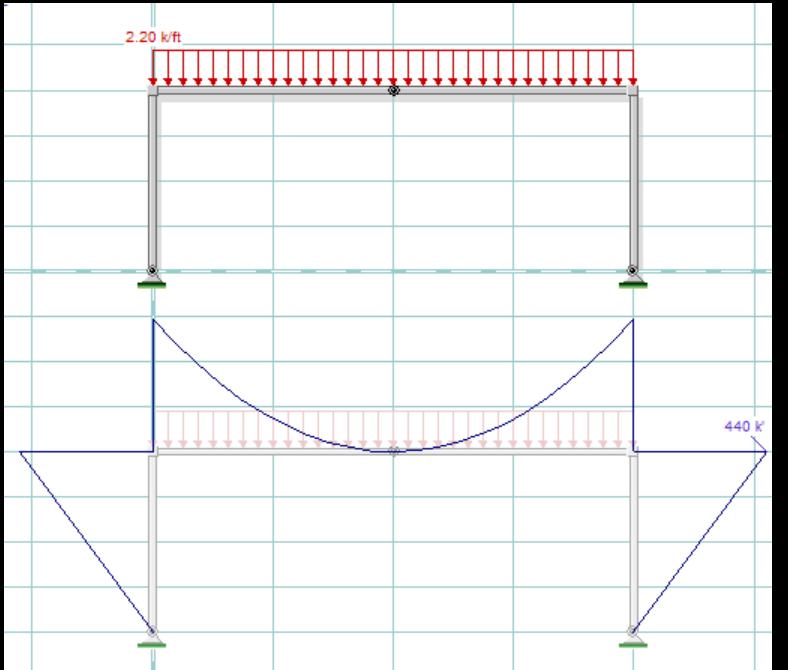


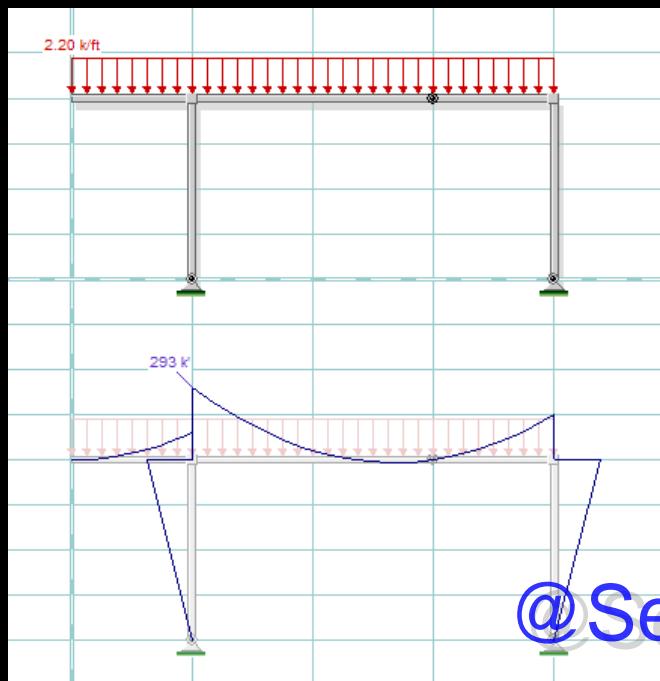
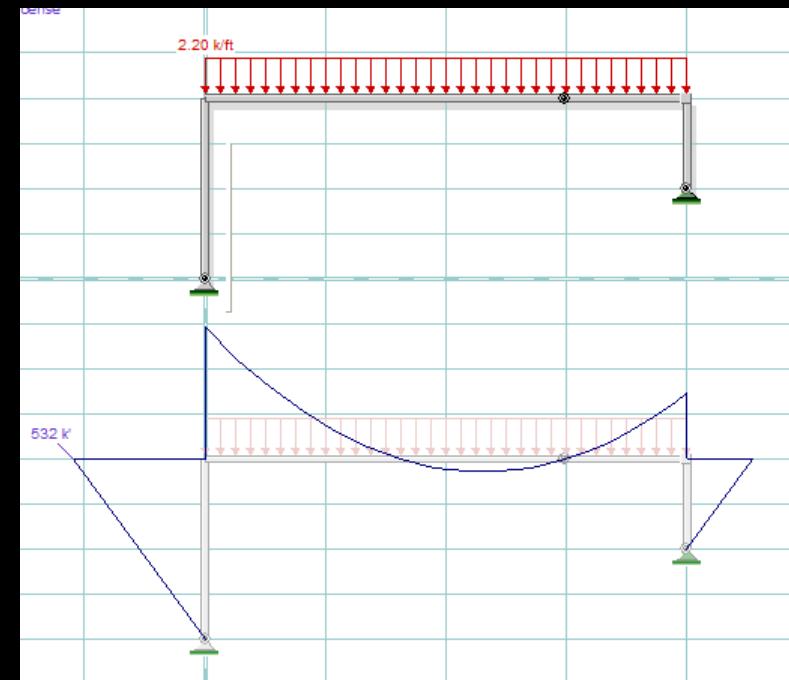
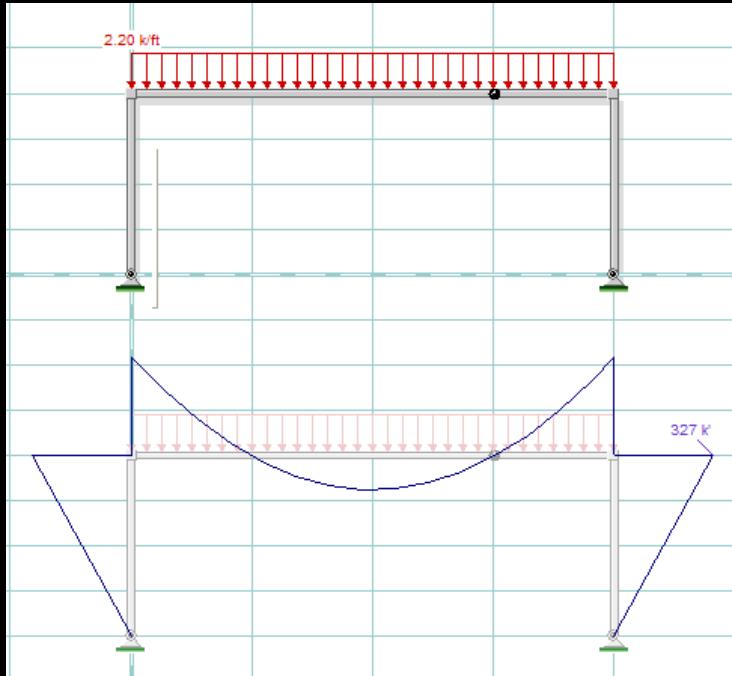
FOLDED BEAM vs. FRAME

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THE EFFECT OF HINGE LOCATION

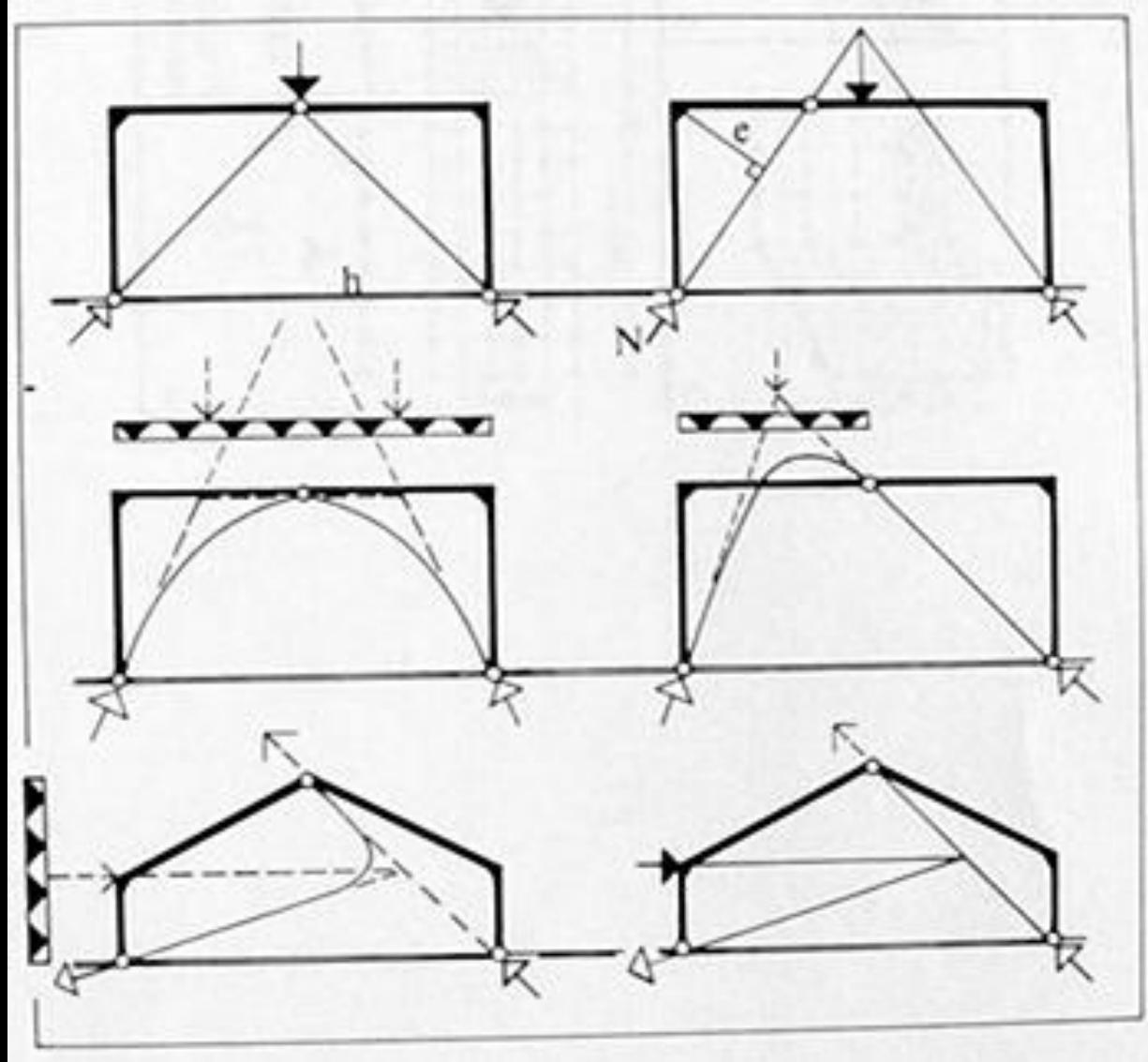
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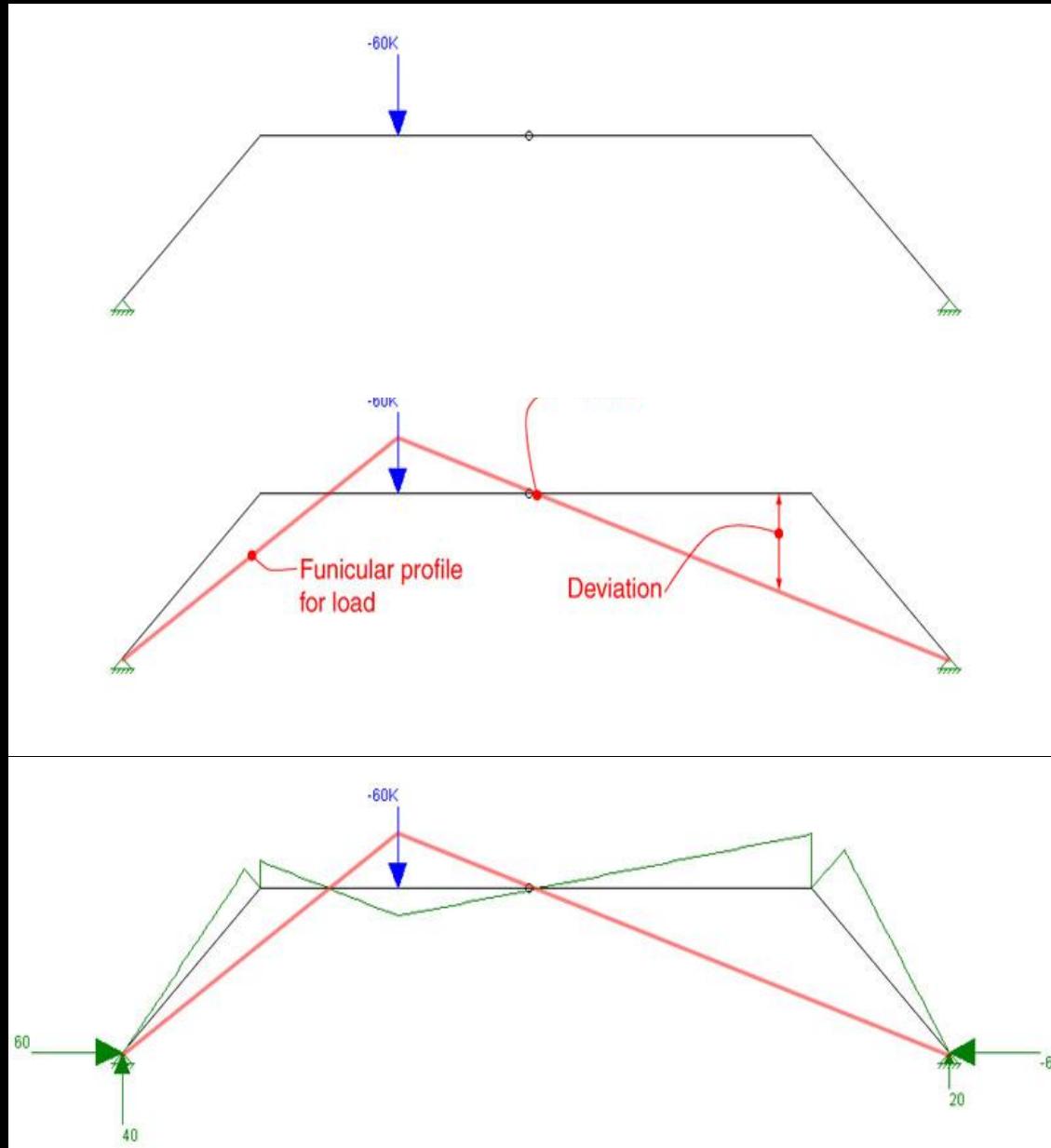


GEOMETRY - THE EFFECT OF CHANGE :
shorter column and cantilever

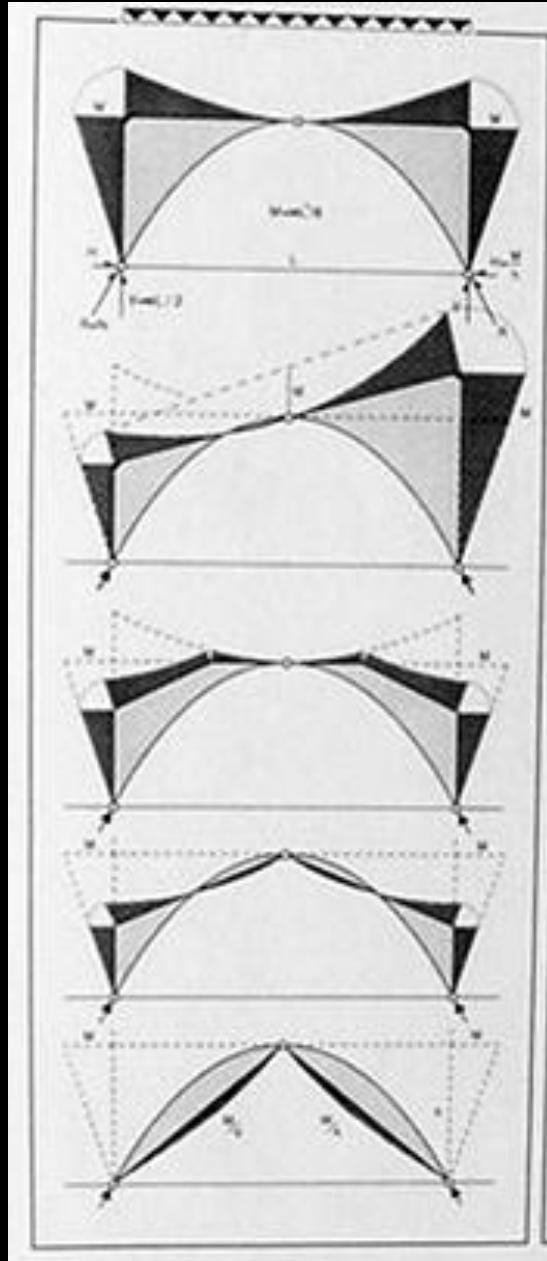
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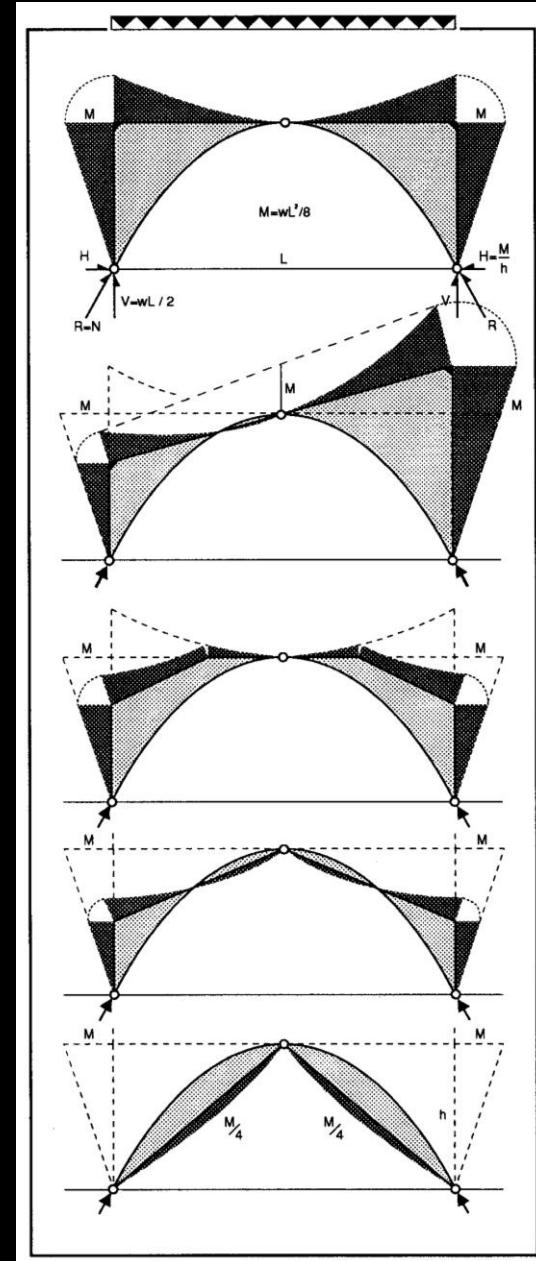
PRESSURE LINE RESPONSES TO VARIOUS LOAD ACTIONS:
@Seismicisolation
funicular shapes

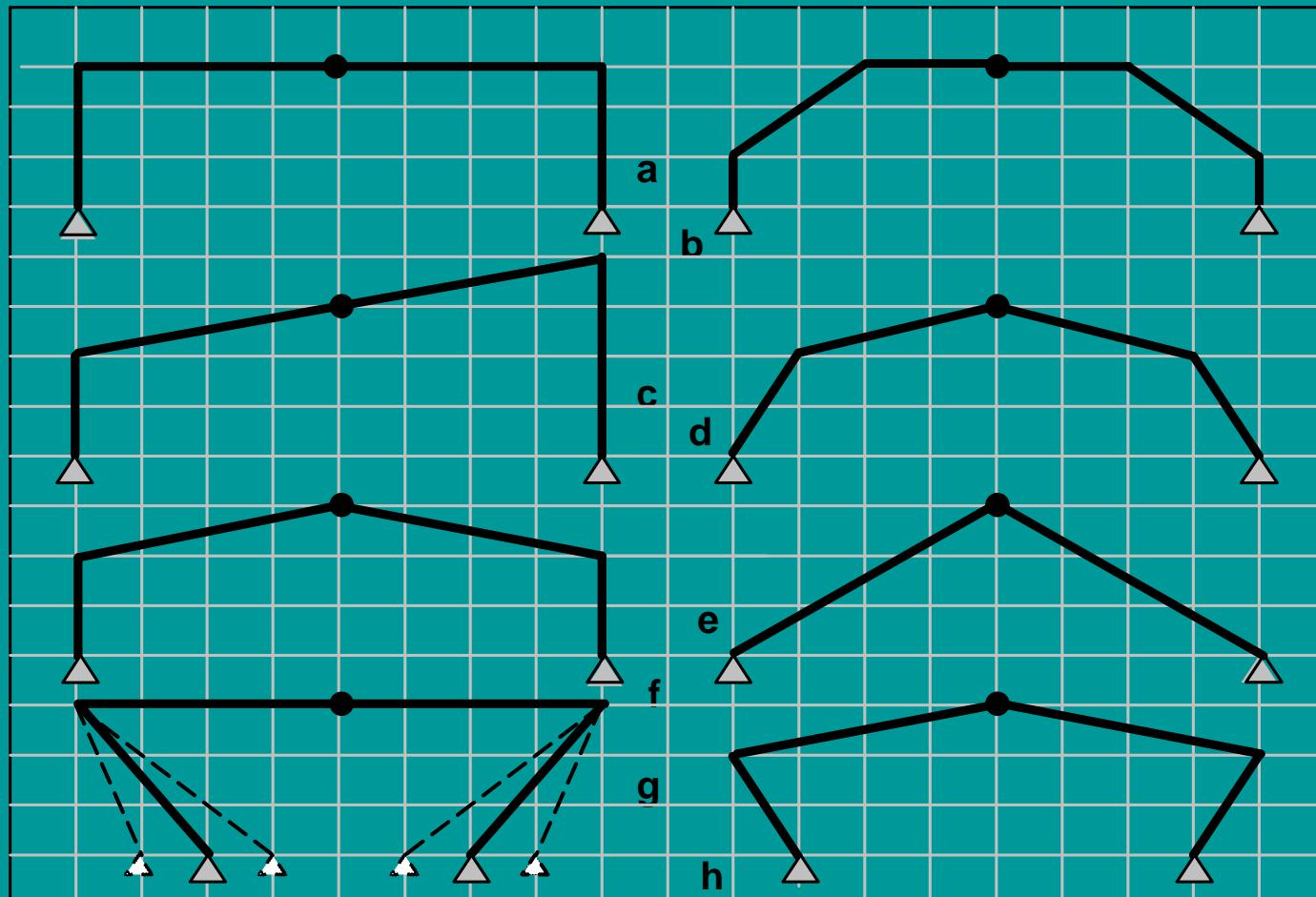


PRESSURE IN THE FRAMES VS. M-diagram
@ Seismic isolation



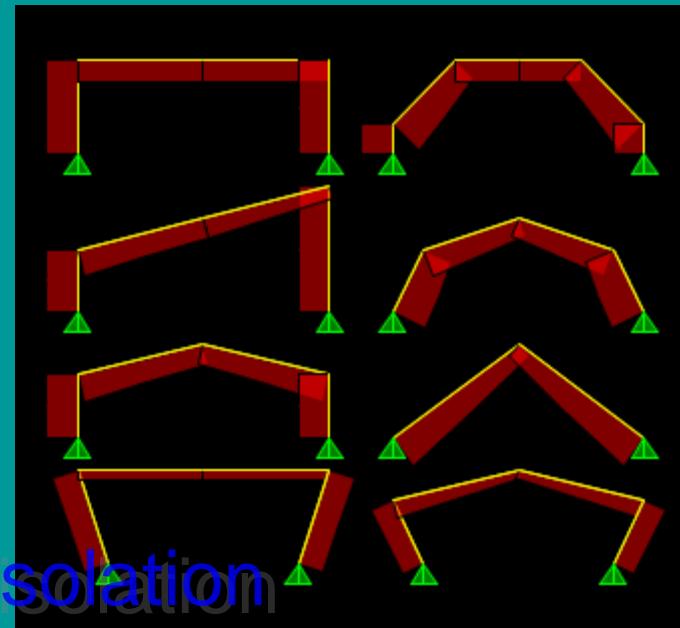
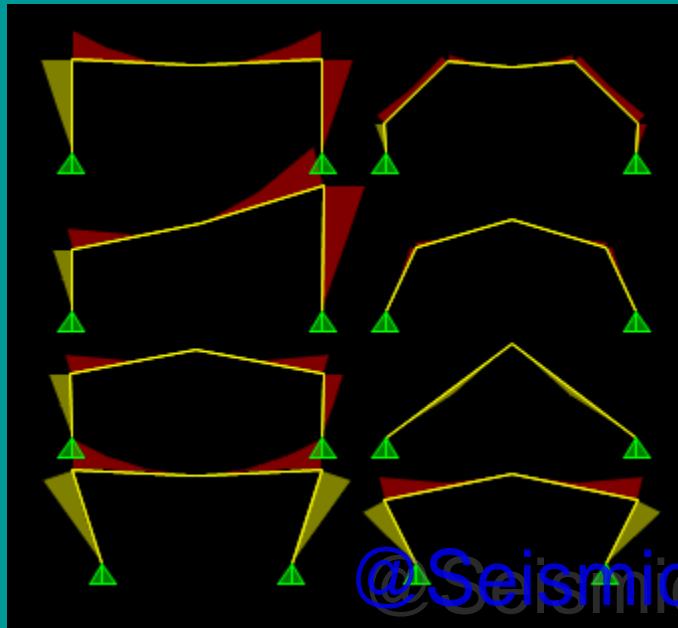
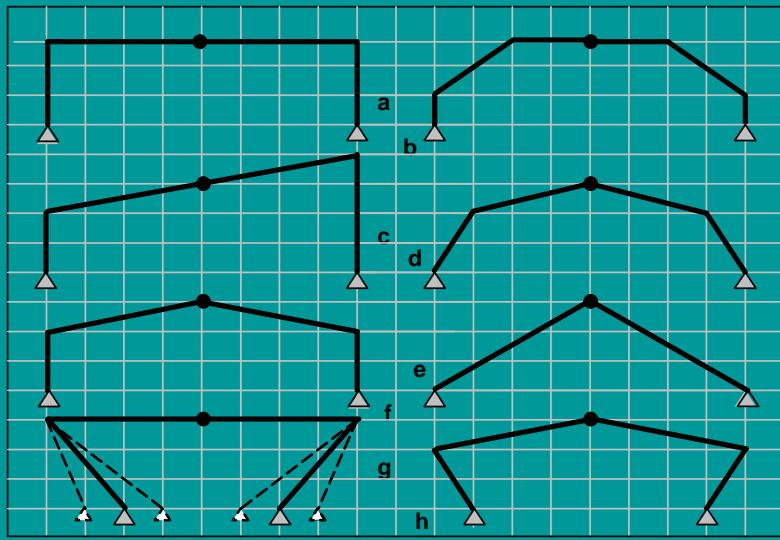
TOPIC 10:
Seismic Isolation
3-HINGE FRAMES



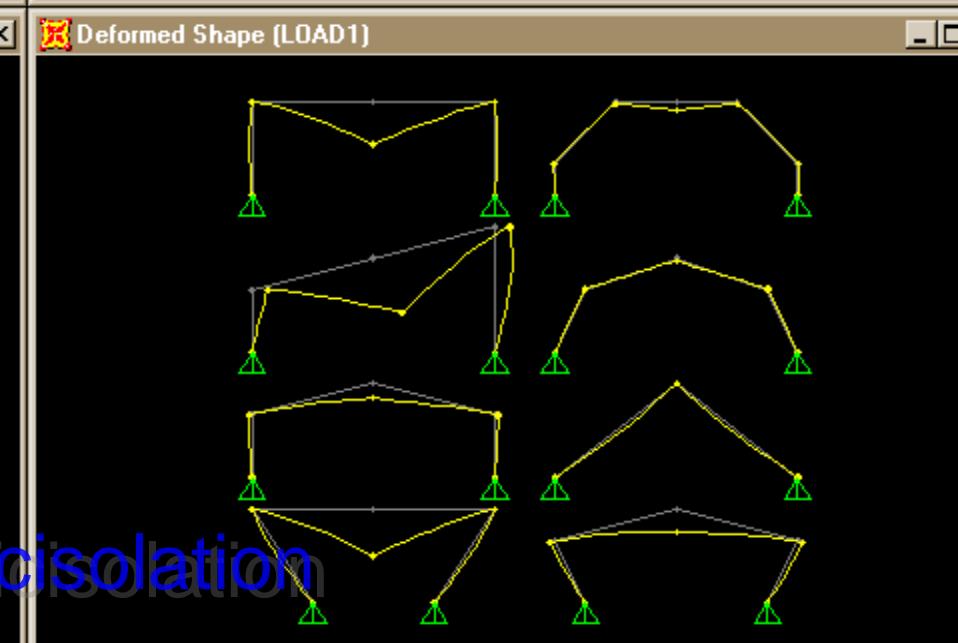
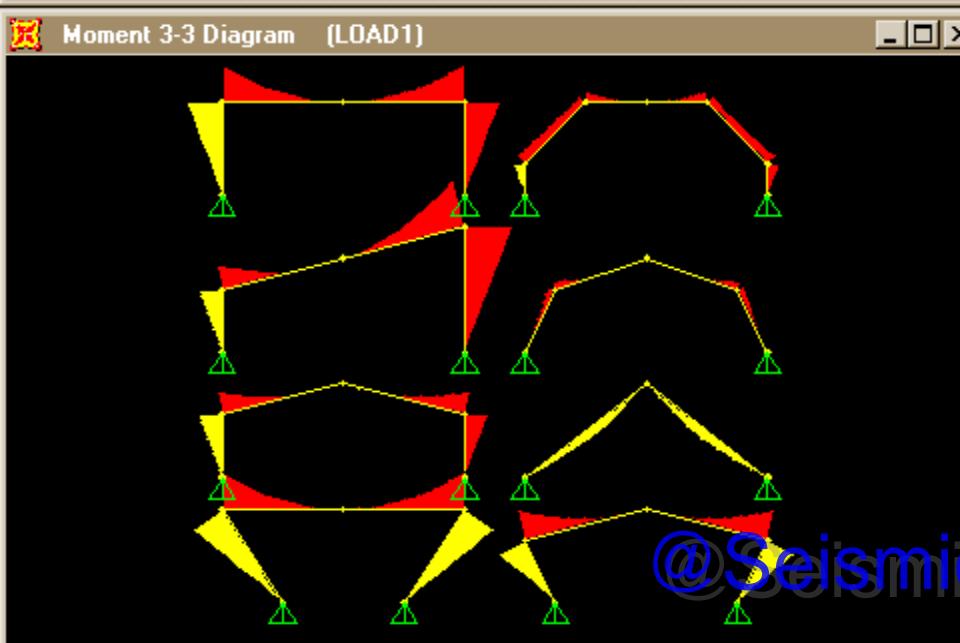
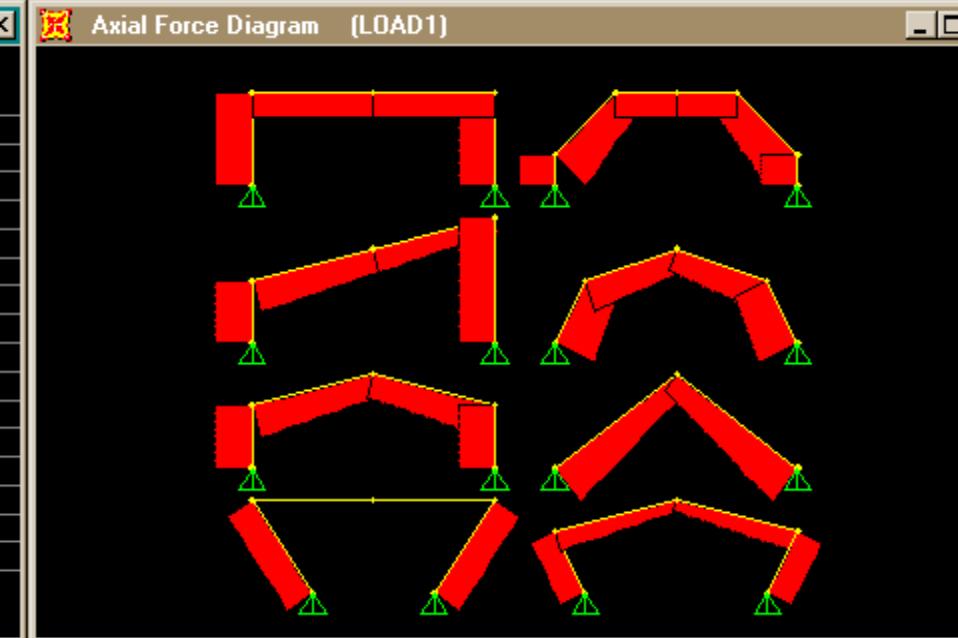
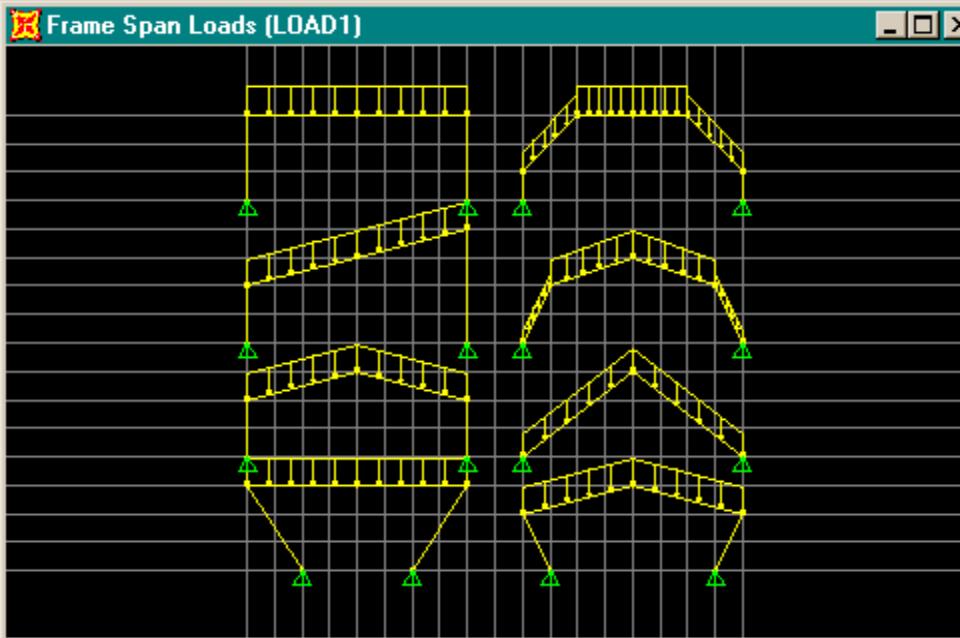
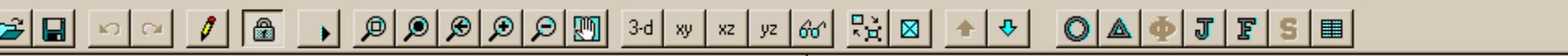


Three-Hinged Frames

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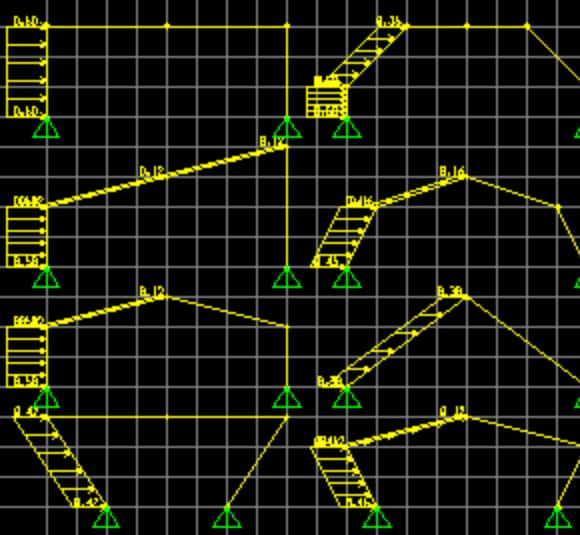


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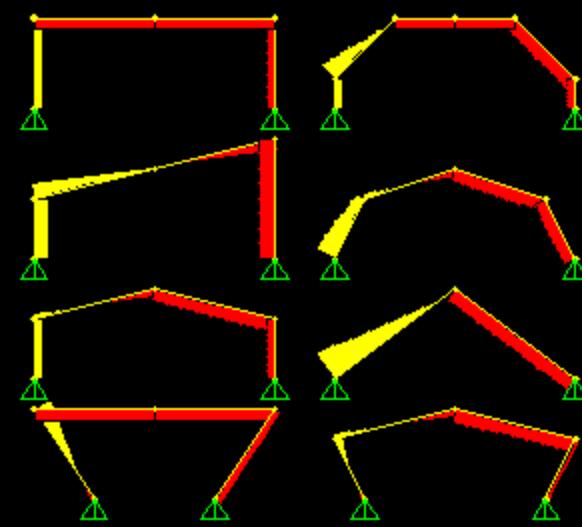
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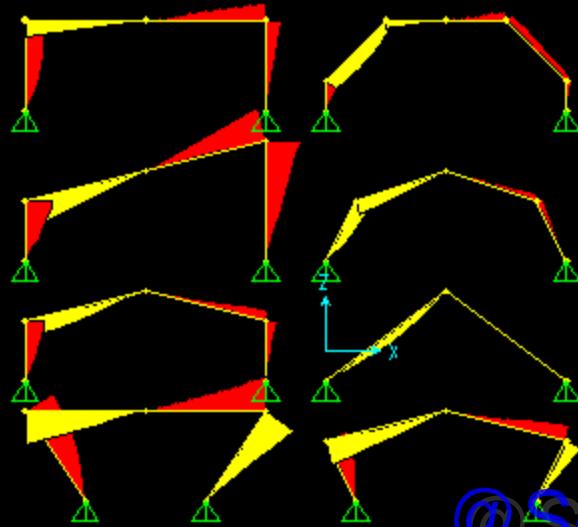
Frame Span Loads (WIND)



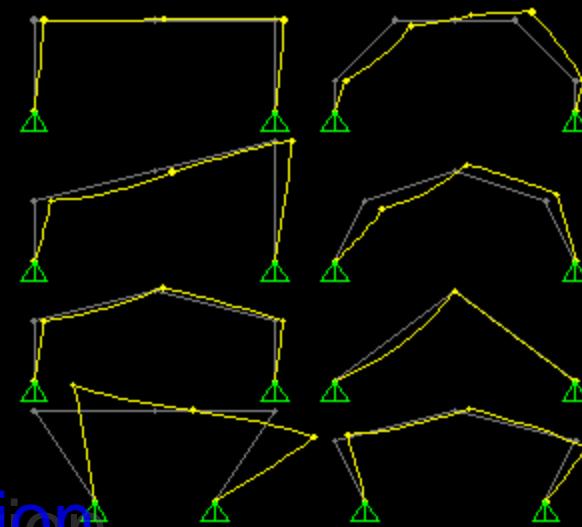
Axial Force Diagram (WIND)



Moment 3-3 Diagram (WIND)



Deformed Shape (WIND)



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Click on any joint for displacement values

Start Animation

Kip-ft

In general, a structure is **statically determinate** when the three equations of static equilibrium are sufficient for solving the unknown forces. When, however, the conditions of the structure are such that the three equations are not sufficient for determining the magnitude of the force flow, additional equations related to member properties, are required, and the structure is said to be **statically indeterminate**, **hyperstatic** or **redundant**. It is apparent that the structure must be in static equilibrium and **stable**, whether it is statically determinate or indeterminate.

The degree of indeterminacy may be found by making the structure statically determinate and stable by removing supports and/or cutting members. The number of force-resisting conditions taken away is equal to the degree of indeterminacy or redundancy, so named after the number of forces that are needed to ensure static equilibrium.

Redundancy is an important phenomenon because it allows the force flow to take an alternate path if the structure should be failing at a certain location, thus not necessarily resulting in a **progressive collapse** of the building as for determinate structures.

Crown Hall, IIT, Chicago, 1956, Mies van der Rohe



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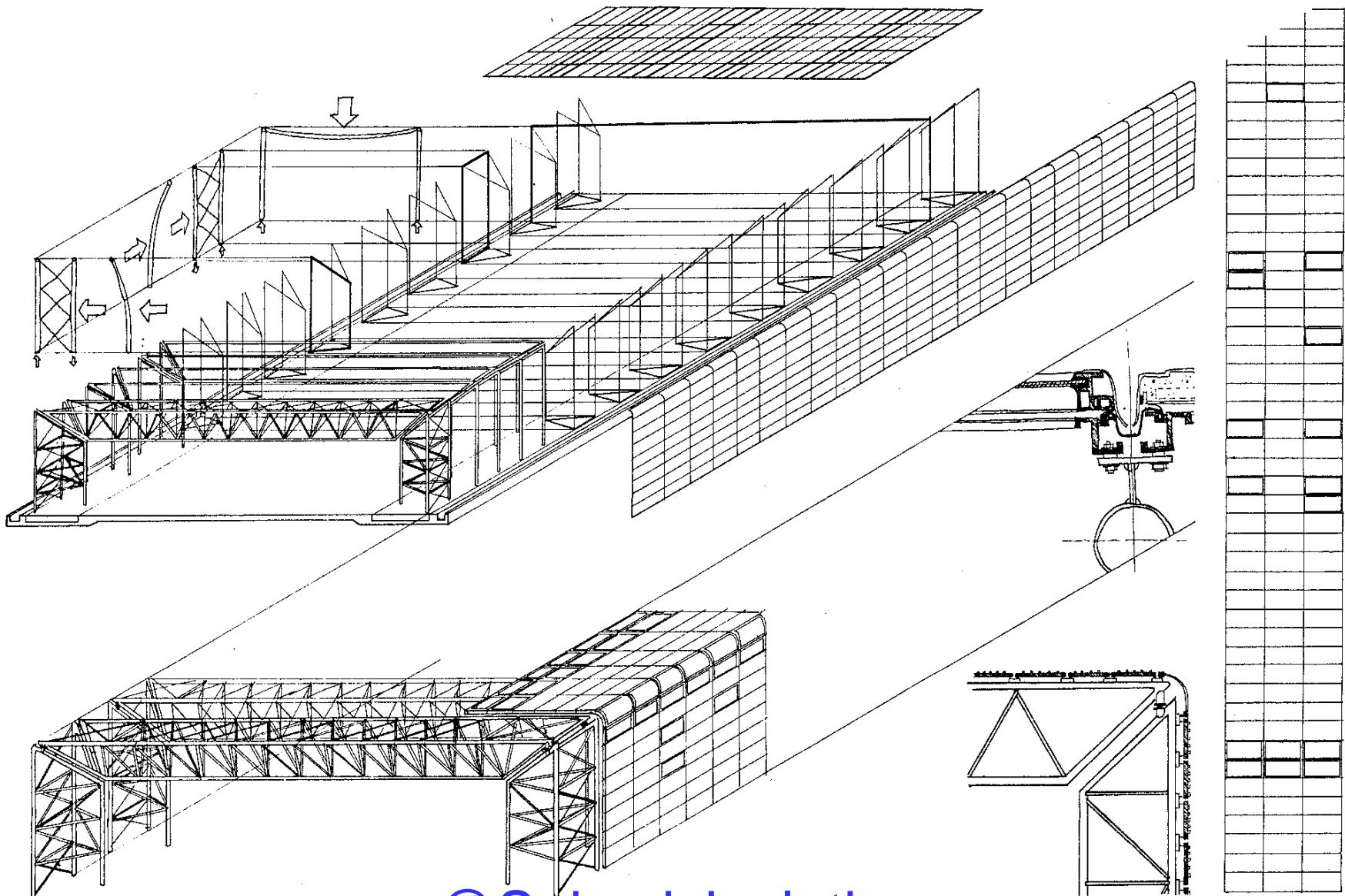
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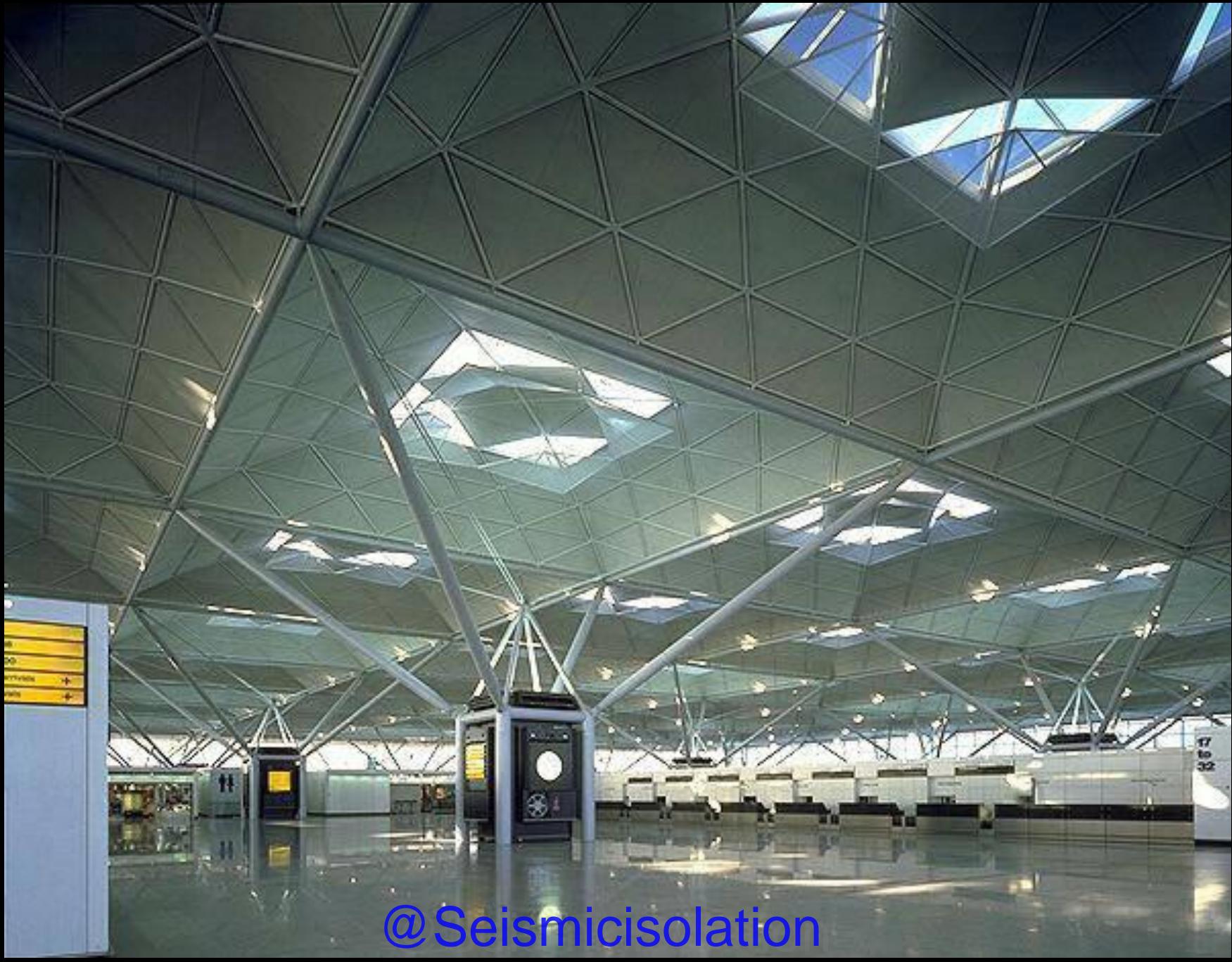
Sainsbury Centre
Norwich UK 1977 Norman Foster



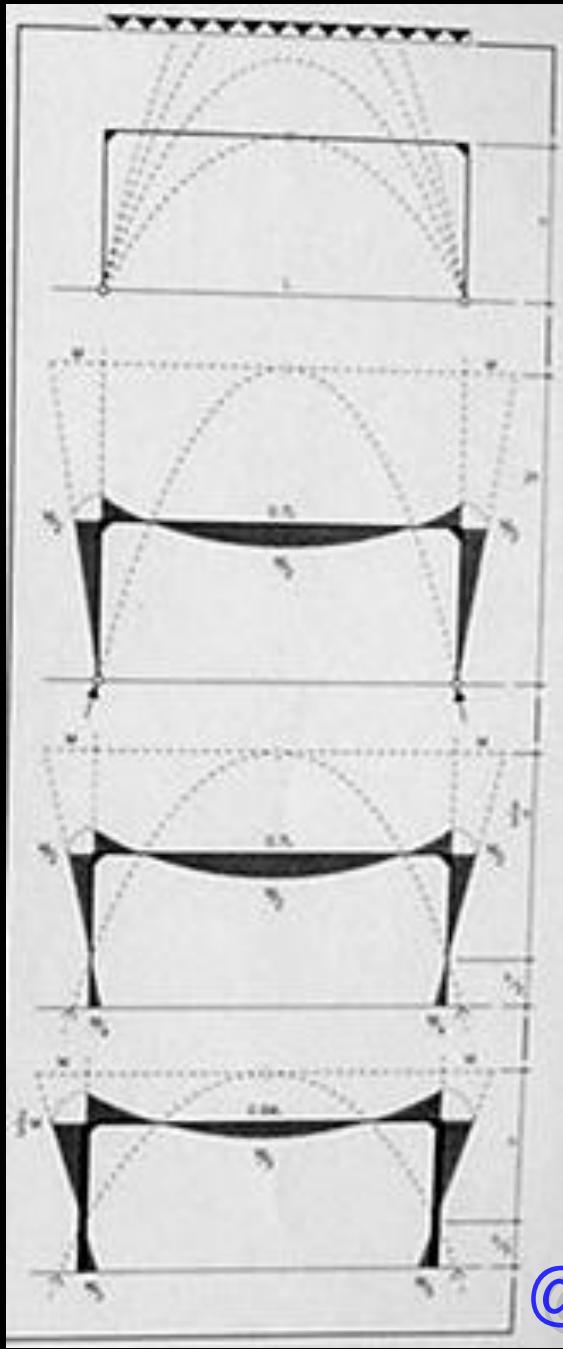
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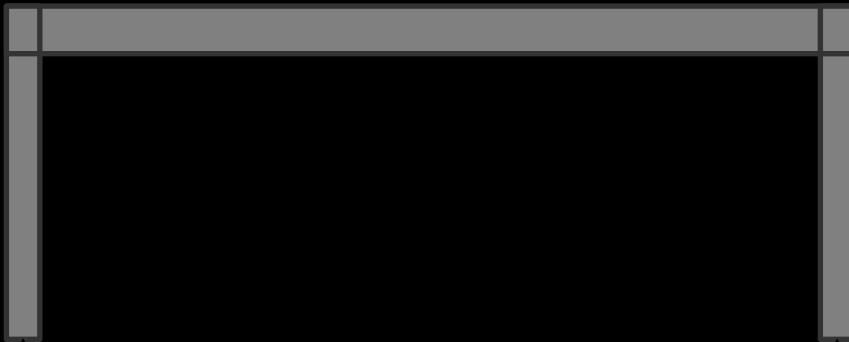
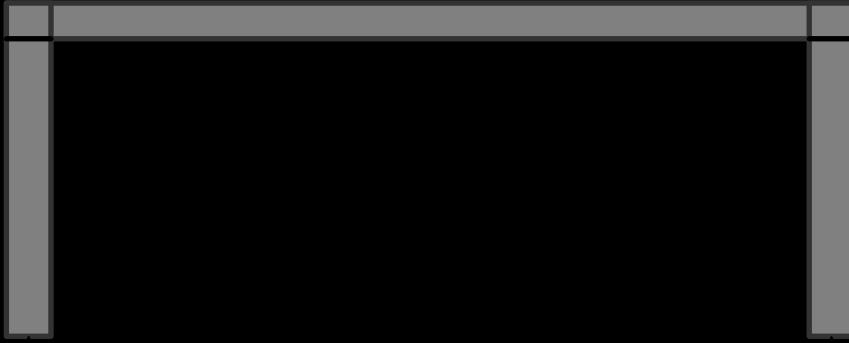
Stansted Airport, London, 1991, Norman Foster
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THE EFFECT OF BEAM AND COLUMN STIFFNESS FOR CONTINUOUS FRAMES



THE EFFECT OF CHANGE
OF MEMBER STIFFNESS:
conceptual drawing

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When the hinge in the three-hinged portal frame is taken out, then the two-hinged frame becomes once statically indeterminate; now the force flow cannot be found anymore simply by statics, the **bending stiffness EI** of the members must be considered. For example, the support moment M_s in the two-hinge frame **of one material** ($E_c = E_b$) is dependent on the stiffness of the beam (I_b/L_b) and column (I_c/L_c) that is the **stiffness factor k** .

$$M_s = -[wL^2/12]/[3/(3+2k)]$$

where, $k = (I/L)_b/(I/L)_c = (I_b/L_b)L_c/I_c = n(L_c/L_b)$, where, $I_b = nI_c$

For some typical conditions, the support or column moment M_s is,

$k = 1.0$ (i.e. equal beam and column stiffness):

$$M_s = -wL^2/20$$

$k = 0.5$:

$$M_s = -wL^2/16$$

$k = 0.3$ (same column and beam section, $k = L_c/L_b$, say 1/3):

$$M_s \approx -wL^2/14$$

Fortunately, not the **actual stiffness** but the **relative stiffness** is used to determine the force flow along the members. Since the material does not generally vary, the stiffness factor for the two-hinged portal frame can be expressed simply in terms of **nL_c/L_b** .

$$k = (I/L)_b/(I/L)_c = (I_b/L_b)L_c/I_c = n(L_c/L_b) \quad \text{where, } I_b = nI_c$$

In general, the magnitude of the frame moments in indeterminate frame structures depends on the relative stiffness of the adjacent beams (**$\Sigma I_b/L_b$**) and columns (**$\Sigma I_c/L_c$**). First, relative member sizes are assumed that is member sizes are expressed in terms of each other using the default sections in SAP and modifying the frame section to take the change of **I** into account by going to the **Modification Factors**, and then filling in the appropriate factor (e.g. 2, 3) for the *Moment of inertia about 3 axis*, for example. Now the structure can be analyzed and can then be designed. Then, the structure has to be reanalyzed with the new member sections and be redesigned. Keep in mind that in the computer program design is an iterative process, where the analysis and design must be run multiple times to complete the design process.

0.851
0.841

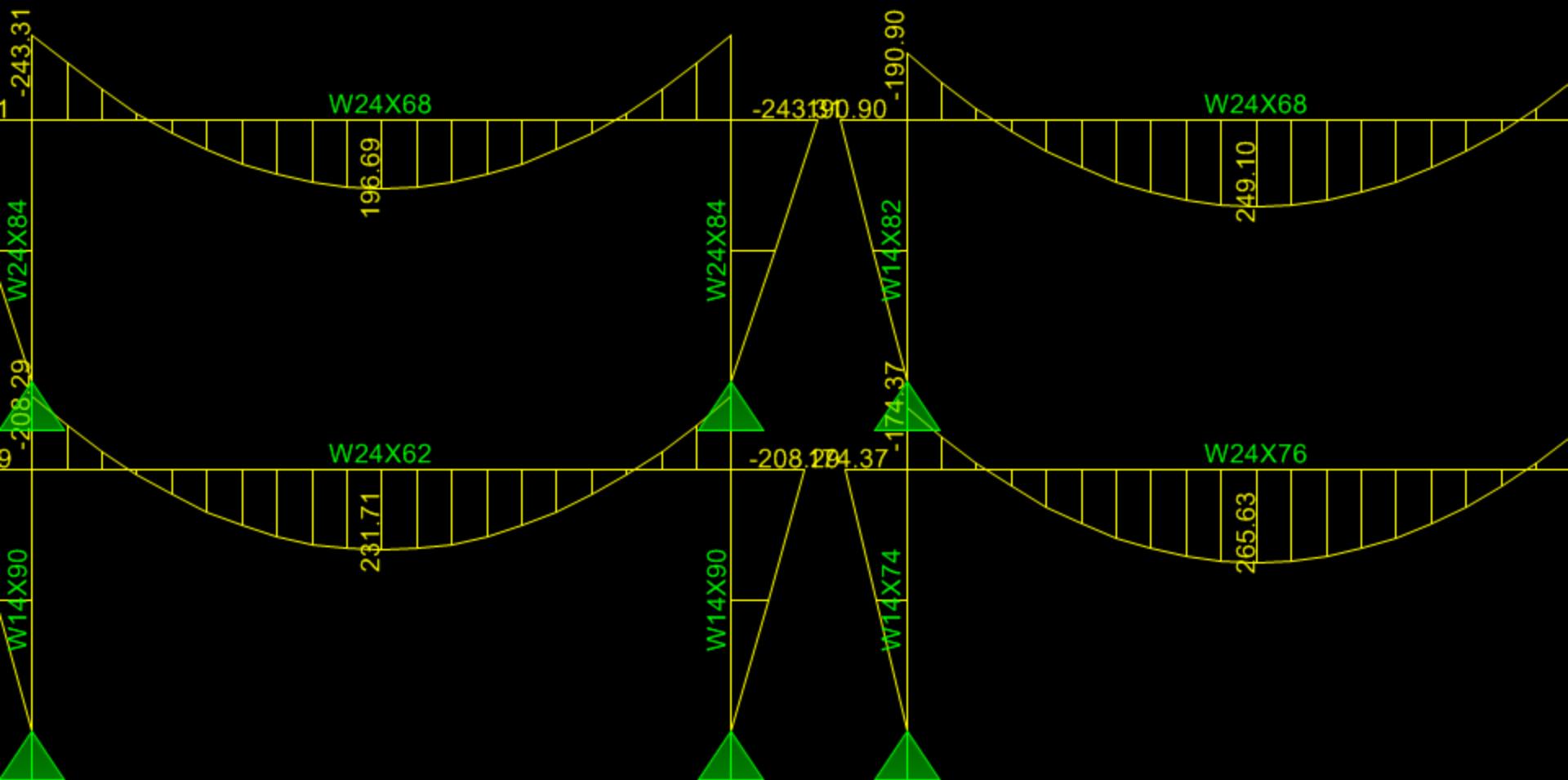
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0.840

W24X84
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W14X90
0.841

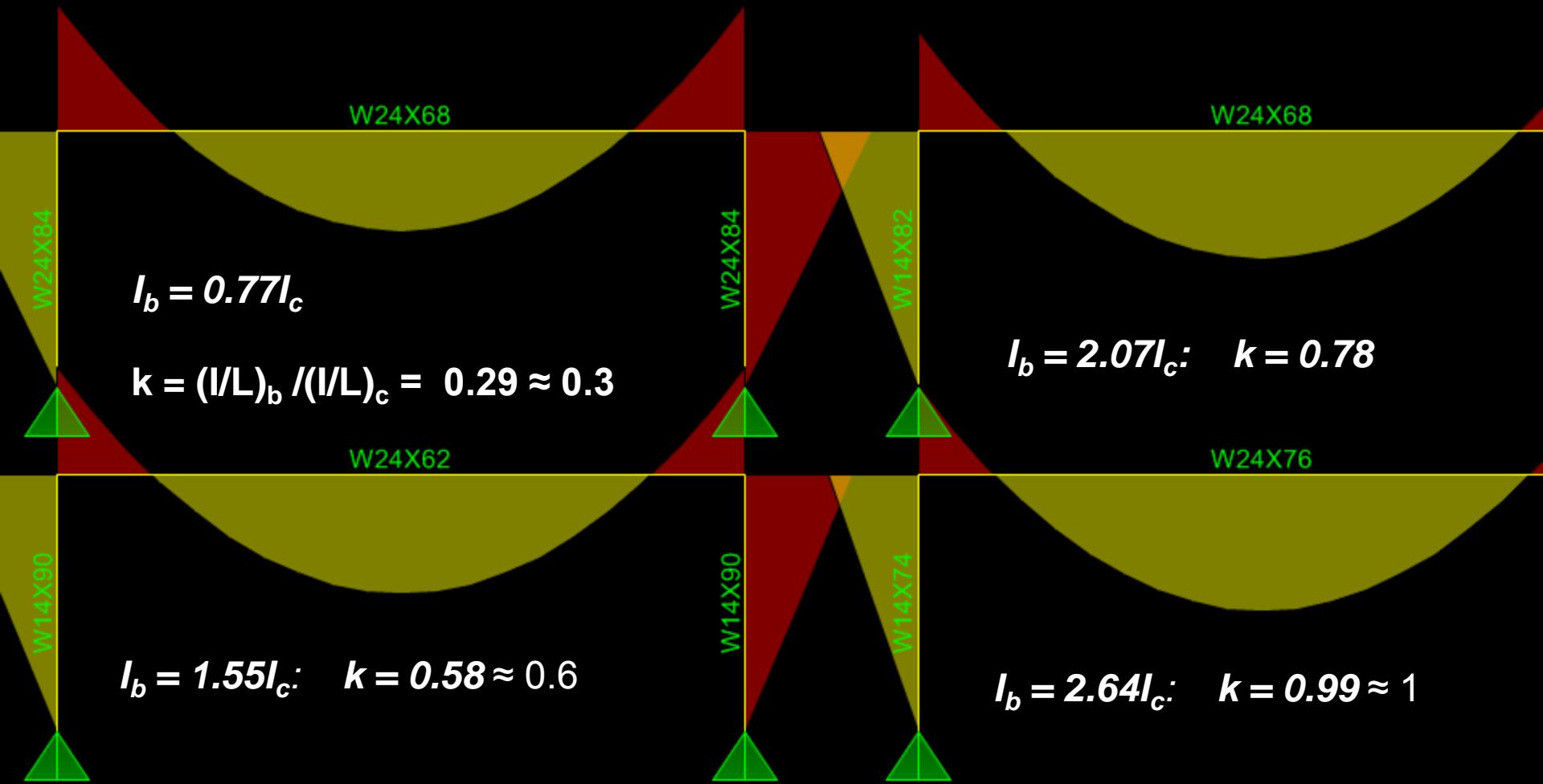
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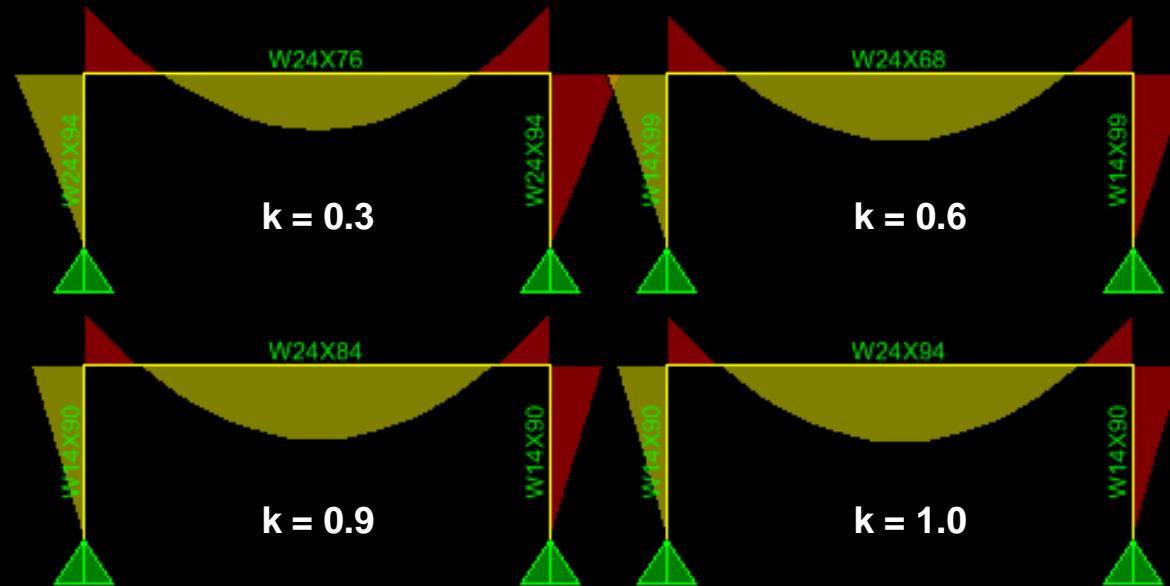
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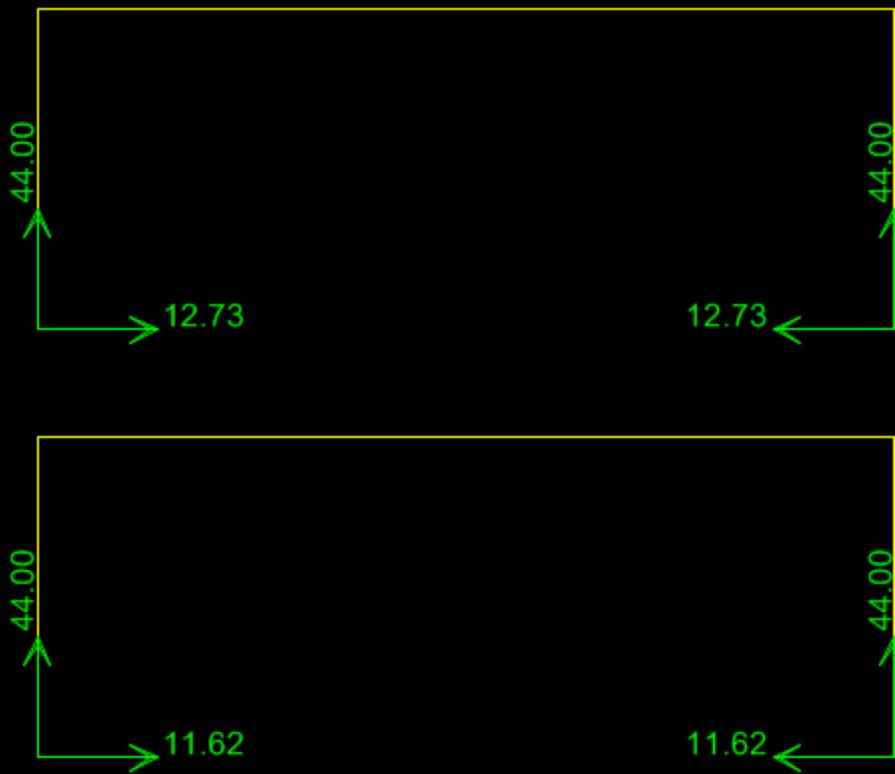
W14X82
W14X74



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A typical frame must support a roof area of one-half of a bay on each side; that is, the joists on each side of the frame transmit to the frame one-half of the gravity roof load.

$$w = w_D + w_L = 40(0.025 + 0.030) = 1.0 + 1.2 = 2.2 \text{ k/ft}$$

The curtain panels transmit the lateral wind load to the spandrel beams and roof *diaphragm*, which in turn apply a single load P_w to the frame at the beam-column intersection.

$$P_w = 40(15/2)0.017 = 5.1 \text{ k}$$

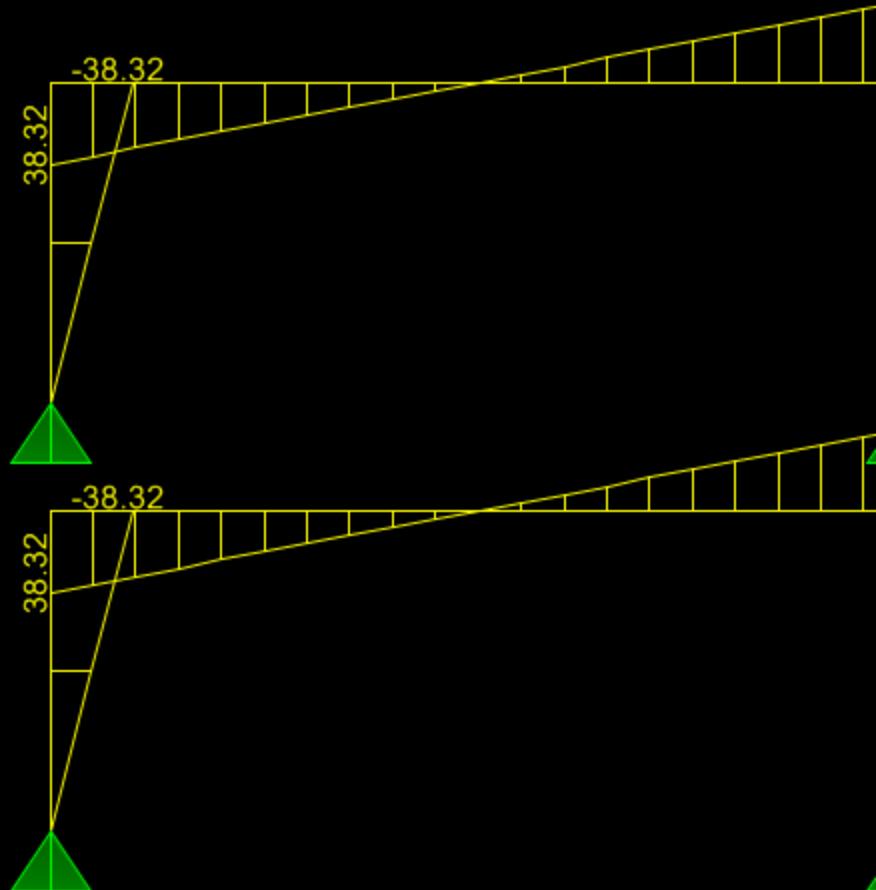
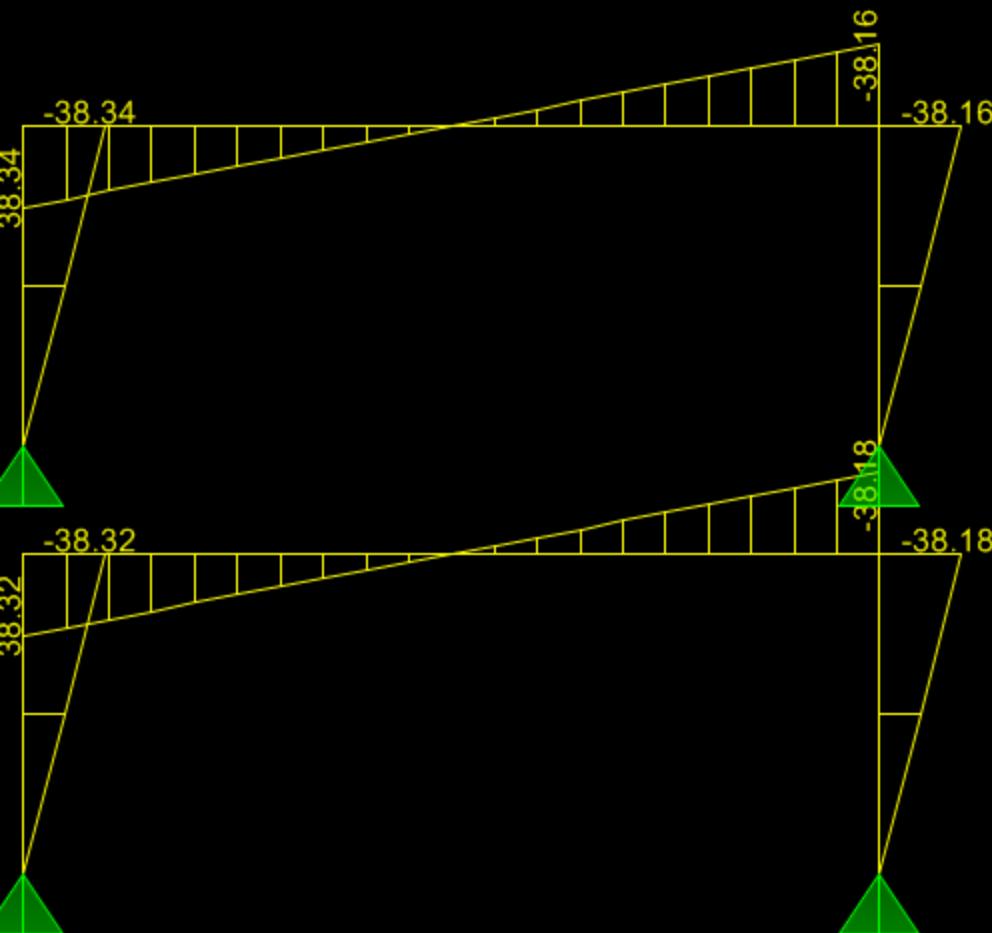
Here the total beam moment to be distributed to column is,

$$M = wL^2/8 = 2.2(40)2/8 = 440 \text{ ft-k}$$

Checking approximately the computer solutions for equal beam and column stiffness ($k = 1$), for

$$M_s = -wL^2/20 = 2.2(40)2/20 = 176 \text{ ft-k} \text{ (SAP gives } 174.37 \text{ ft-k)}$$

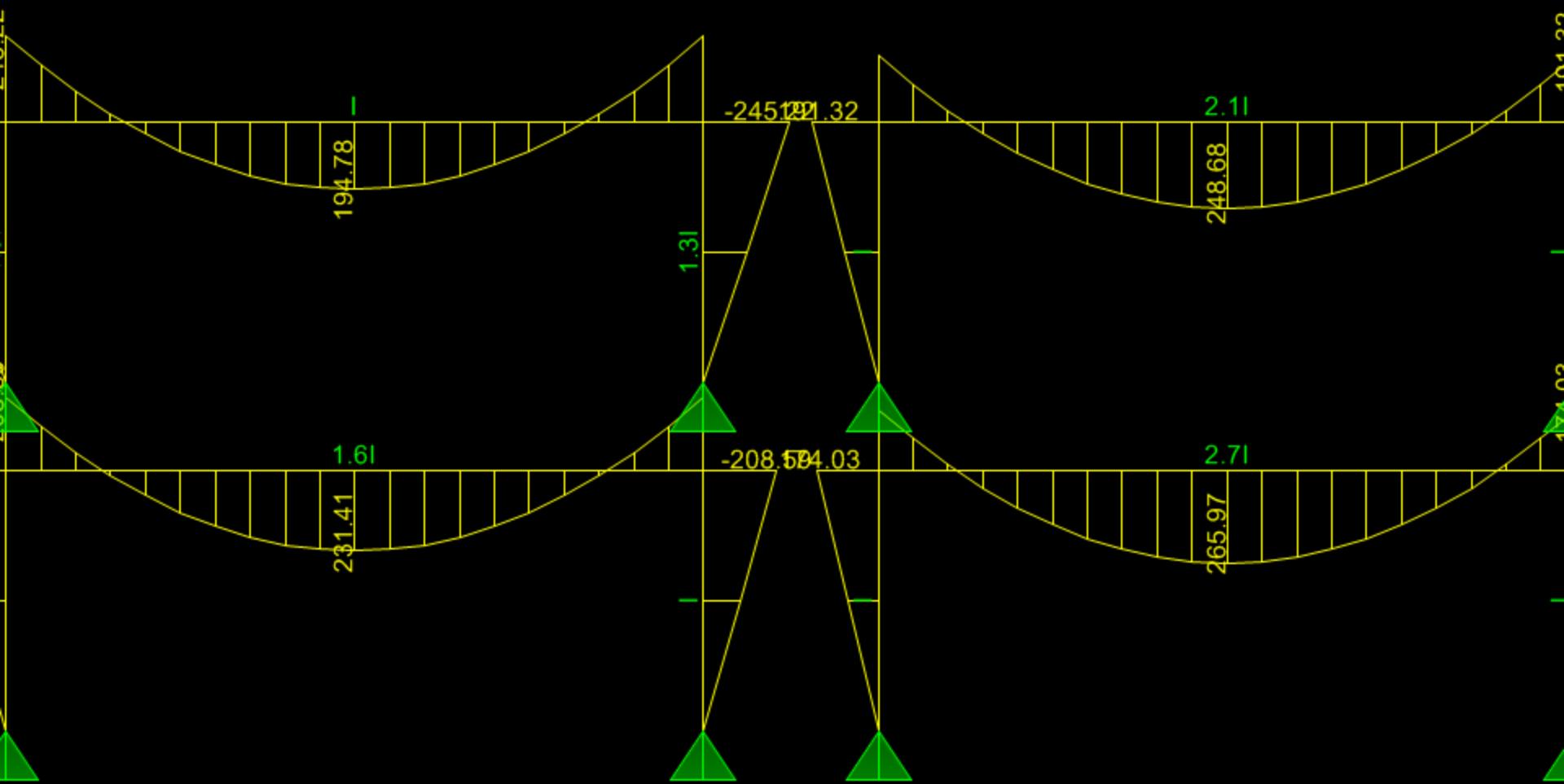
or the maximum girder moment of $M_g = wL^2/8 - M_s = 440 - 176 = 264 \text{ ft-k}$



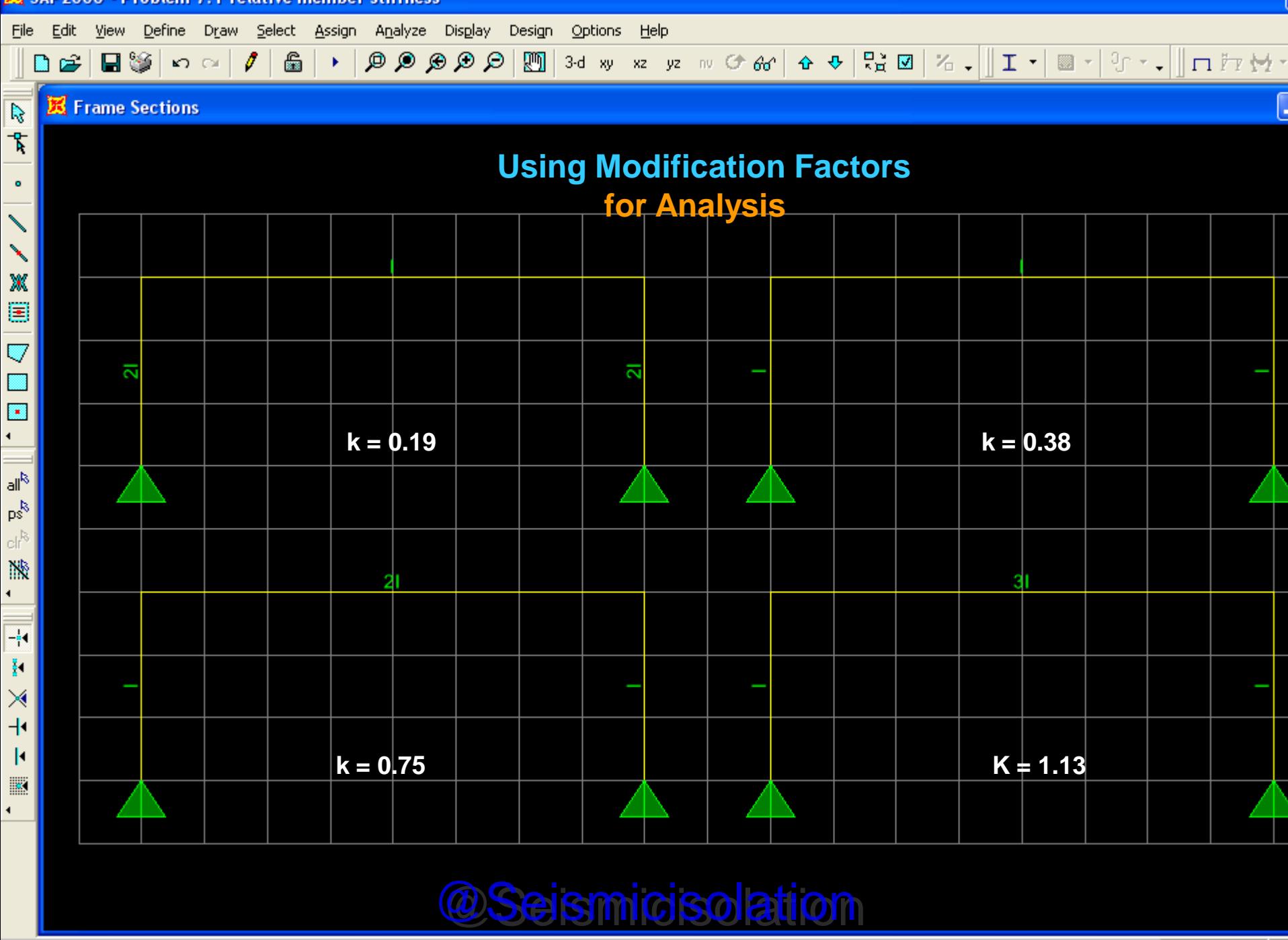
$$R_h = P/2 = 5.1/2 = 2.55 \text{ k}$$
$$M_{sw} = 2.55(15) = 38.25 \text{ ft-k}$$

Member stiffness does not influence lateral force distribution.
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Using Modification Factors for Analysis

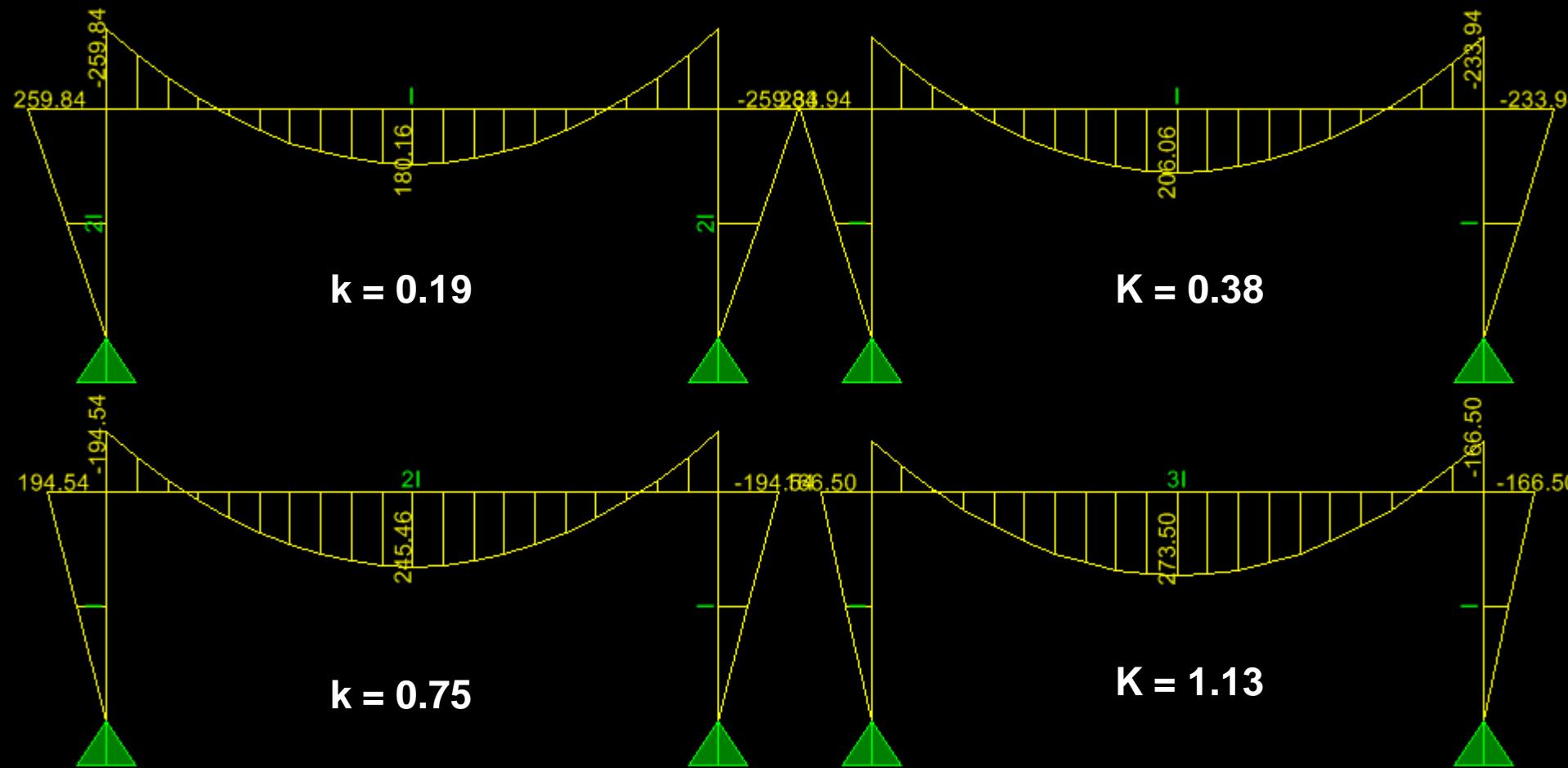


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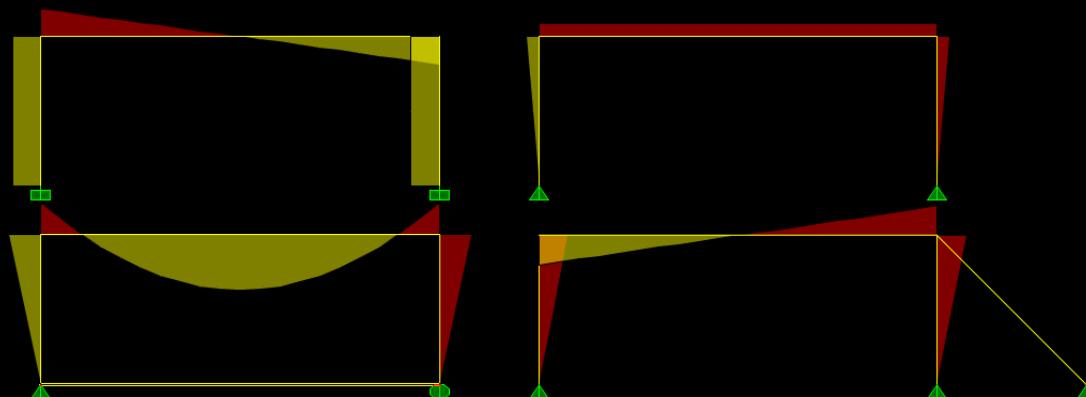
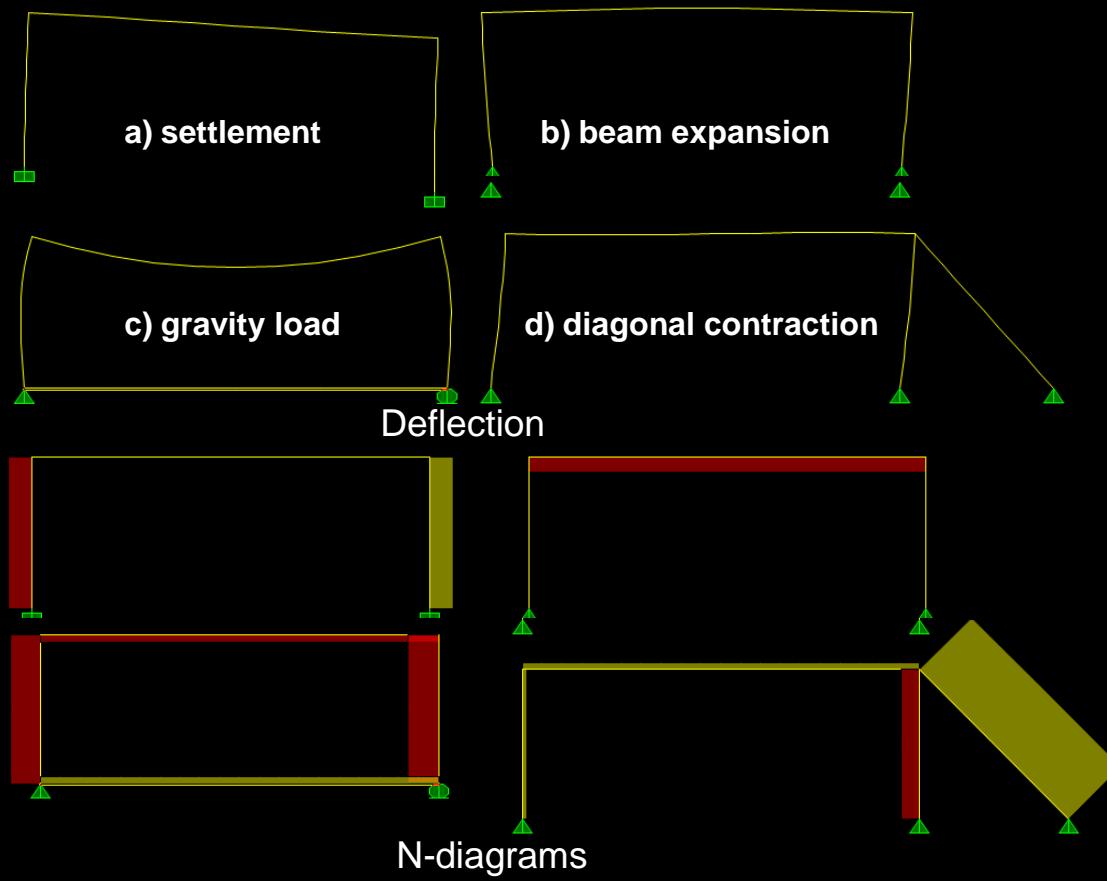




Moment 3-3 Diagram (COMB1)



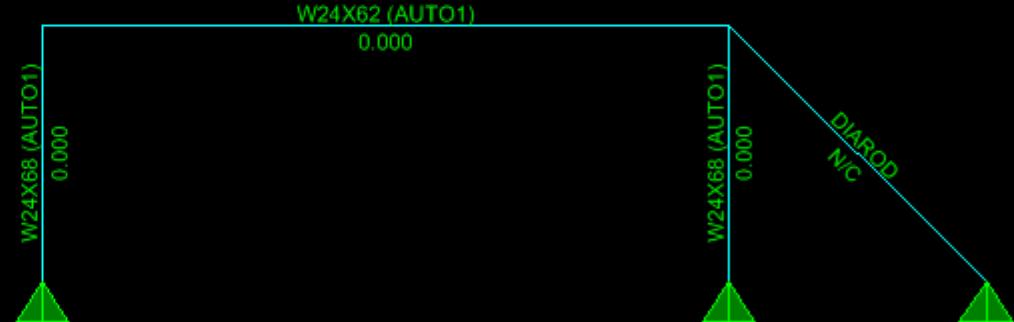
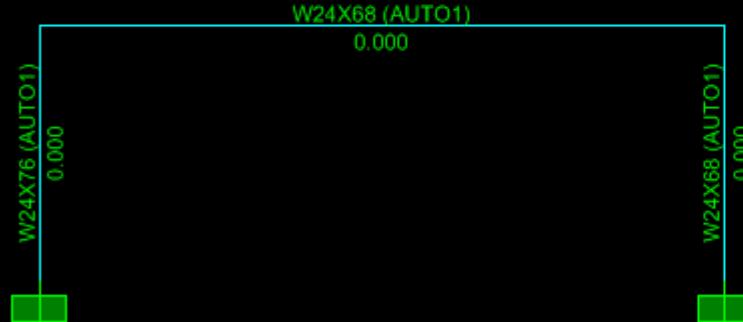
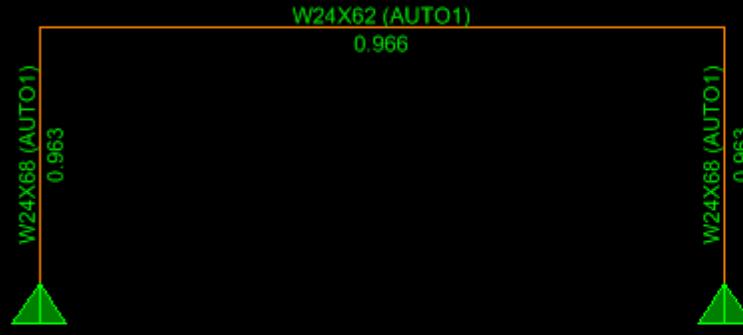
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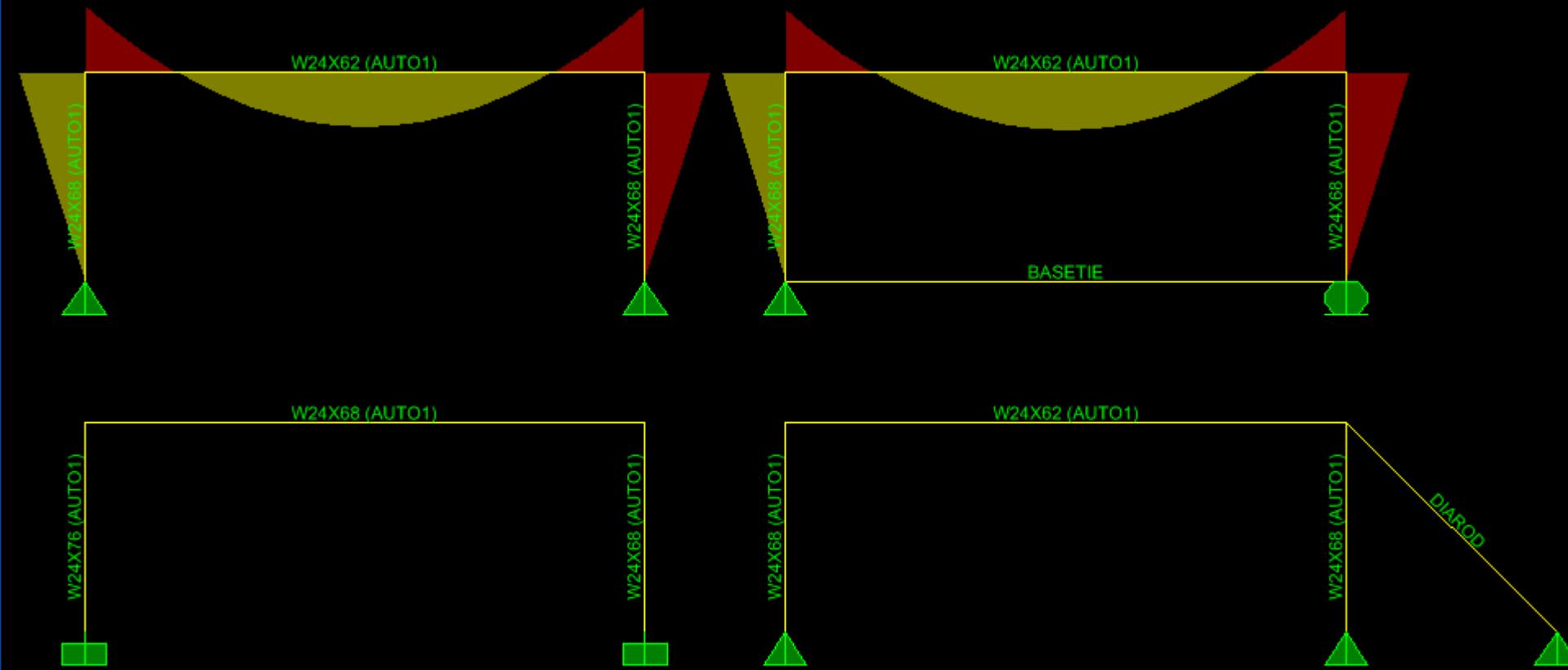
Steel P-M Interaction Ratios (AISC-ASD89)



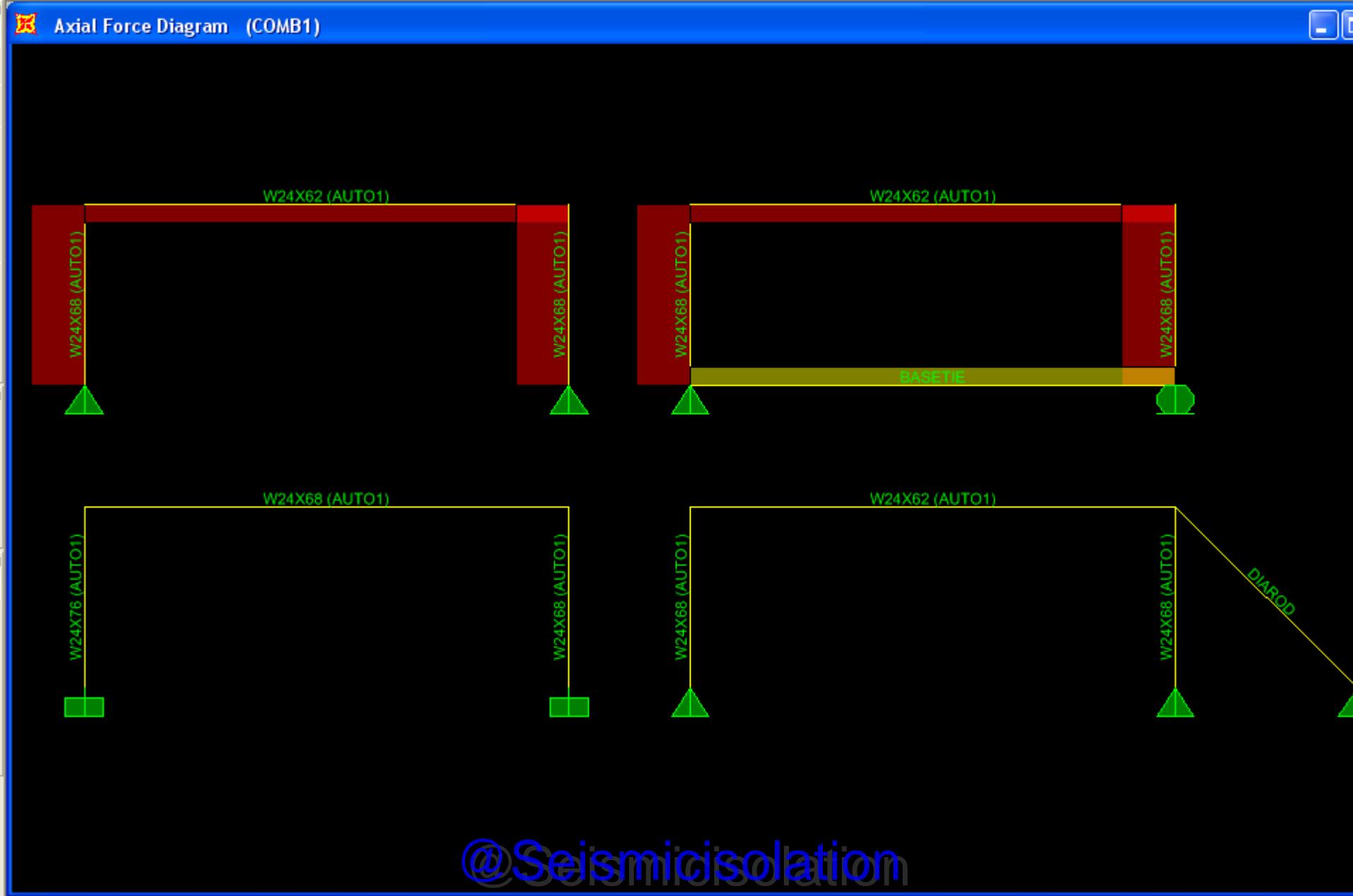
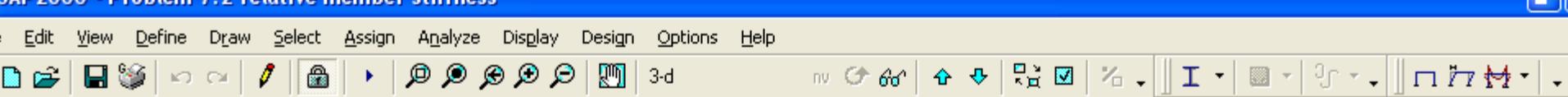
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Moment 3-3 Diagram (COMB1)



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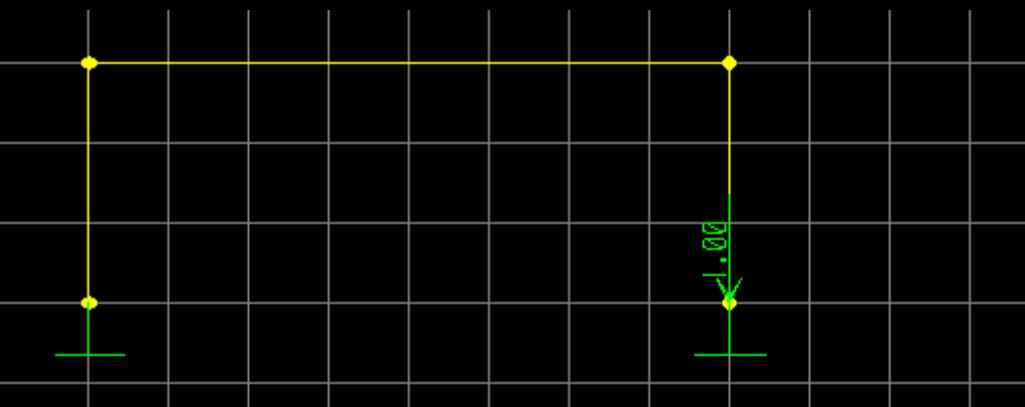




Frame Temperature Loading

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Options	<input checked="" type="radio"/> Add to existing loads <input type="radio"/> Replace existing loads <input type="radio"/> Delete existing loads
Temperature	<input checked="" type="radio"/> By Element Temperature: -100
By Joint Pattern	<input type="radio"/> Pattern: <input type="button" value="..."/> Multiplier: <input type="button" value="..."/>

OK Cancel

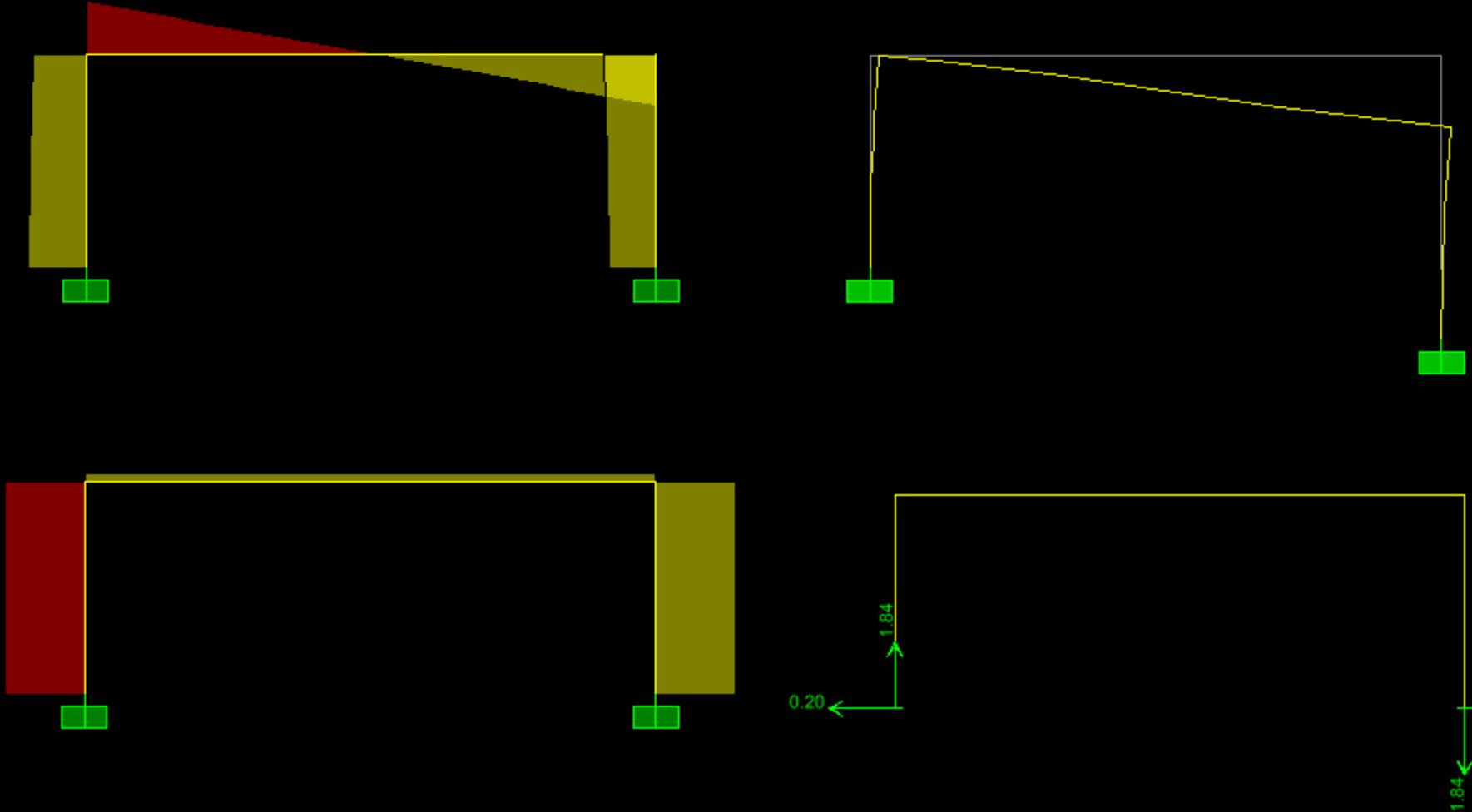


Ground Displacements

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Displacements	Translation X: 0. Translation Y: 0. Translation Z: -1. Rotation about XX: 0. Rotation about YY: 0. Rotation about ZZ: 0.
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OK Cancel

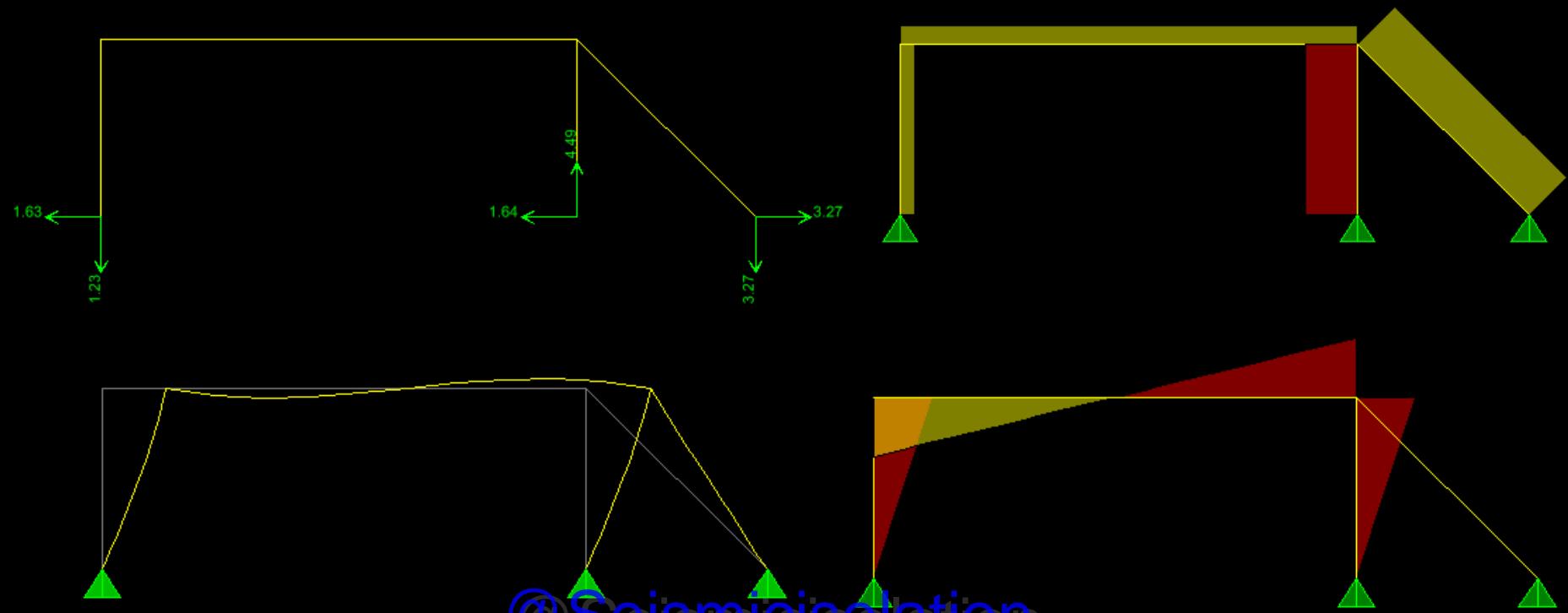
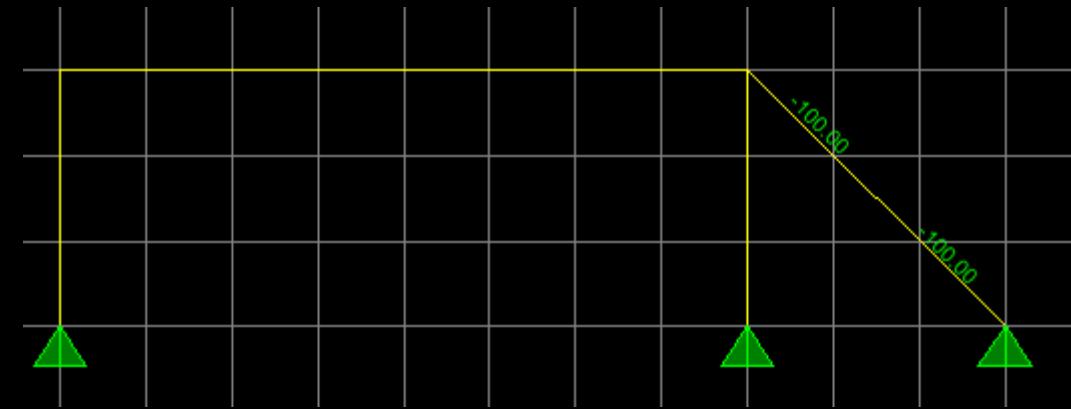
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SUPPORT SETTLEMENT

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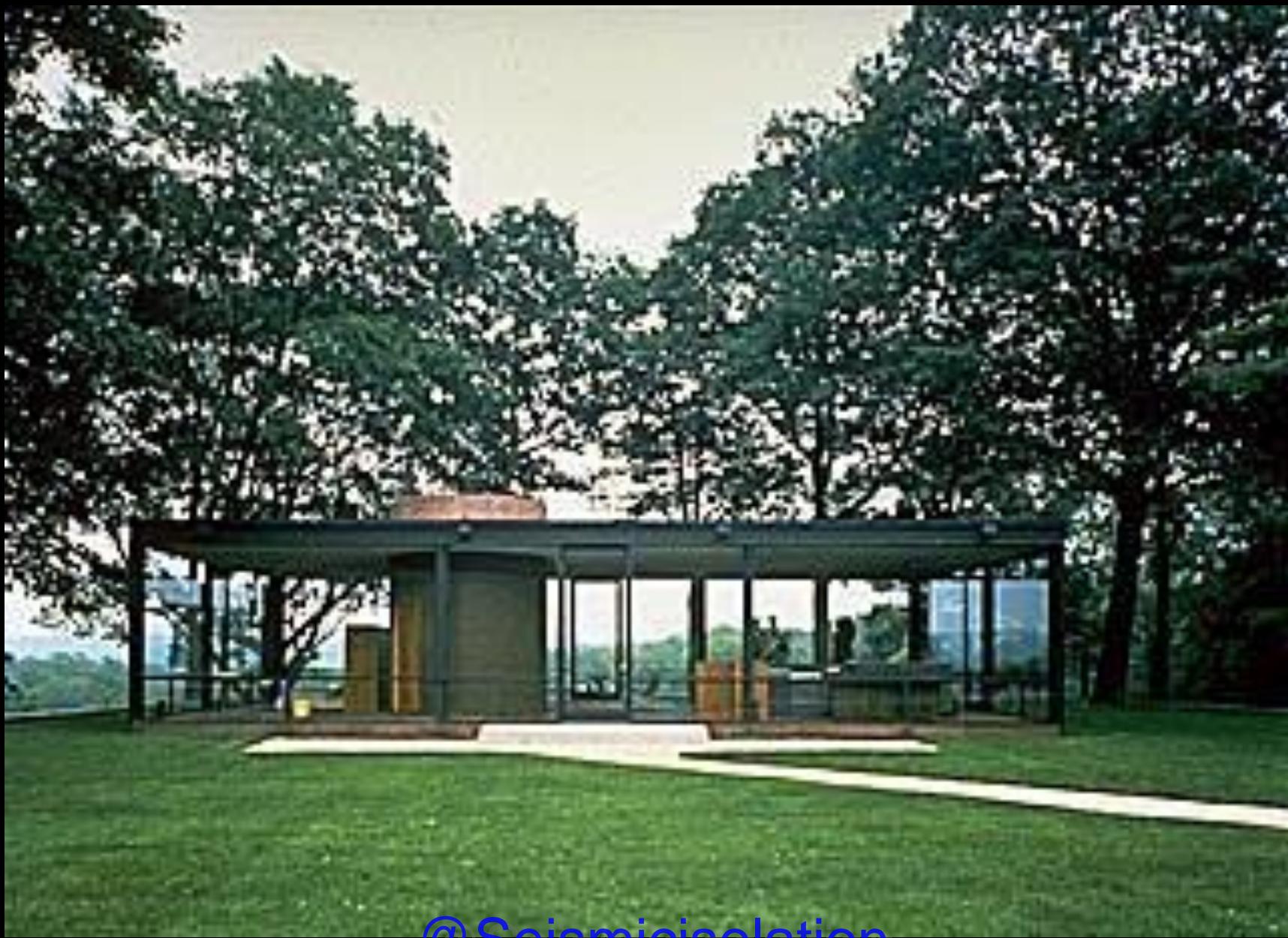
THERMAL LOADING



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Glass House, New Canaan, Conn., 1949, Philip Johnson



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Farnsworth House, Plano, Illinois, 1950, Mies van der Rohe



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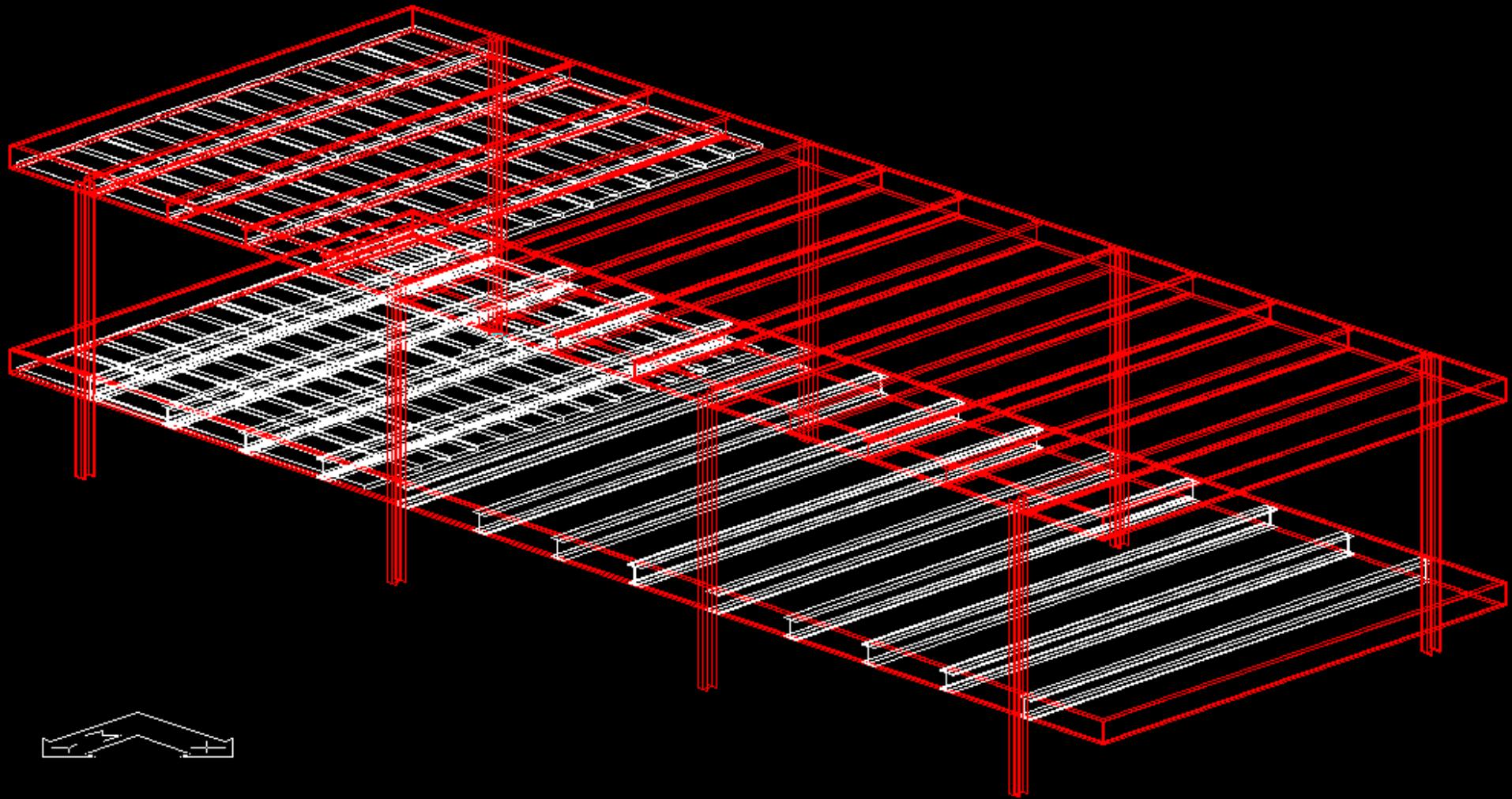
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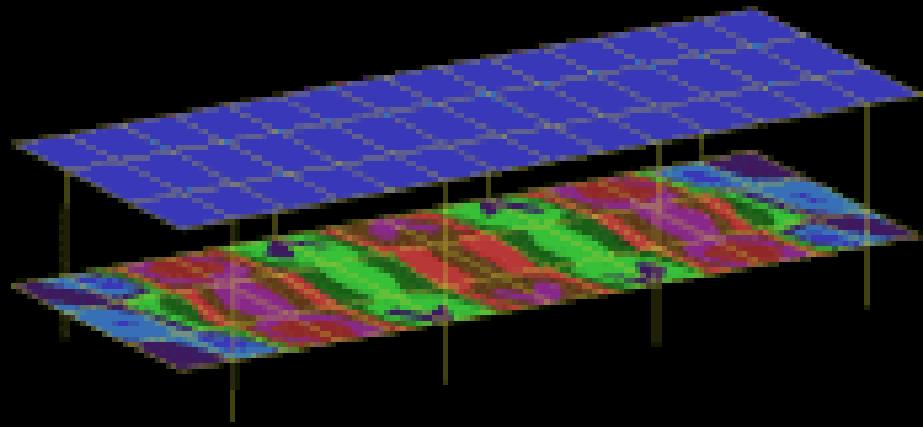
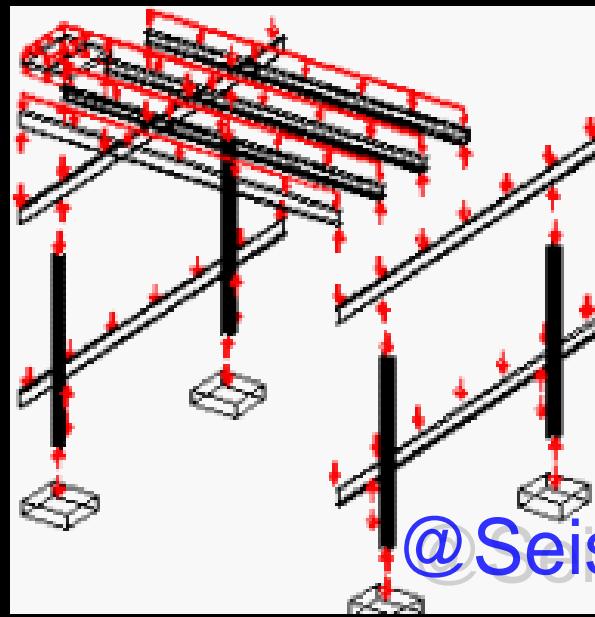
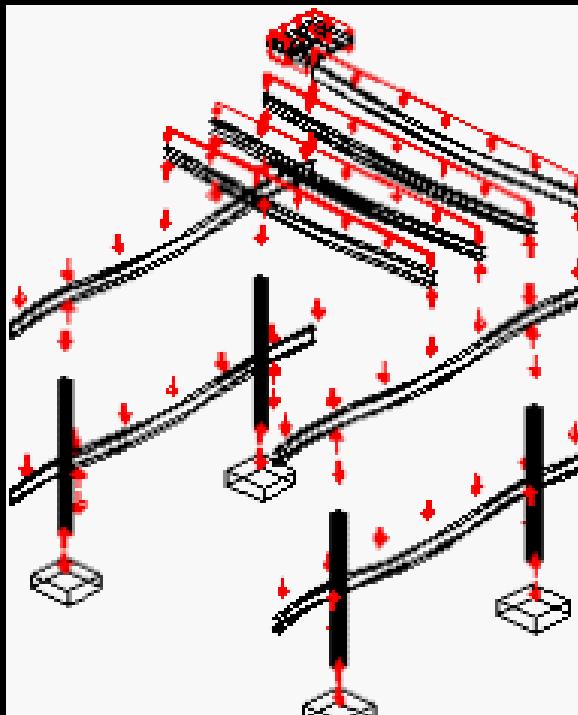
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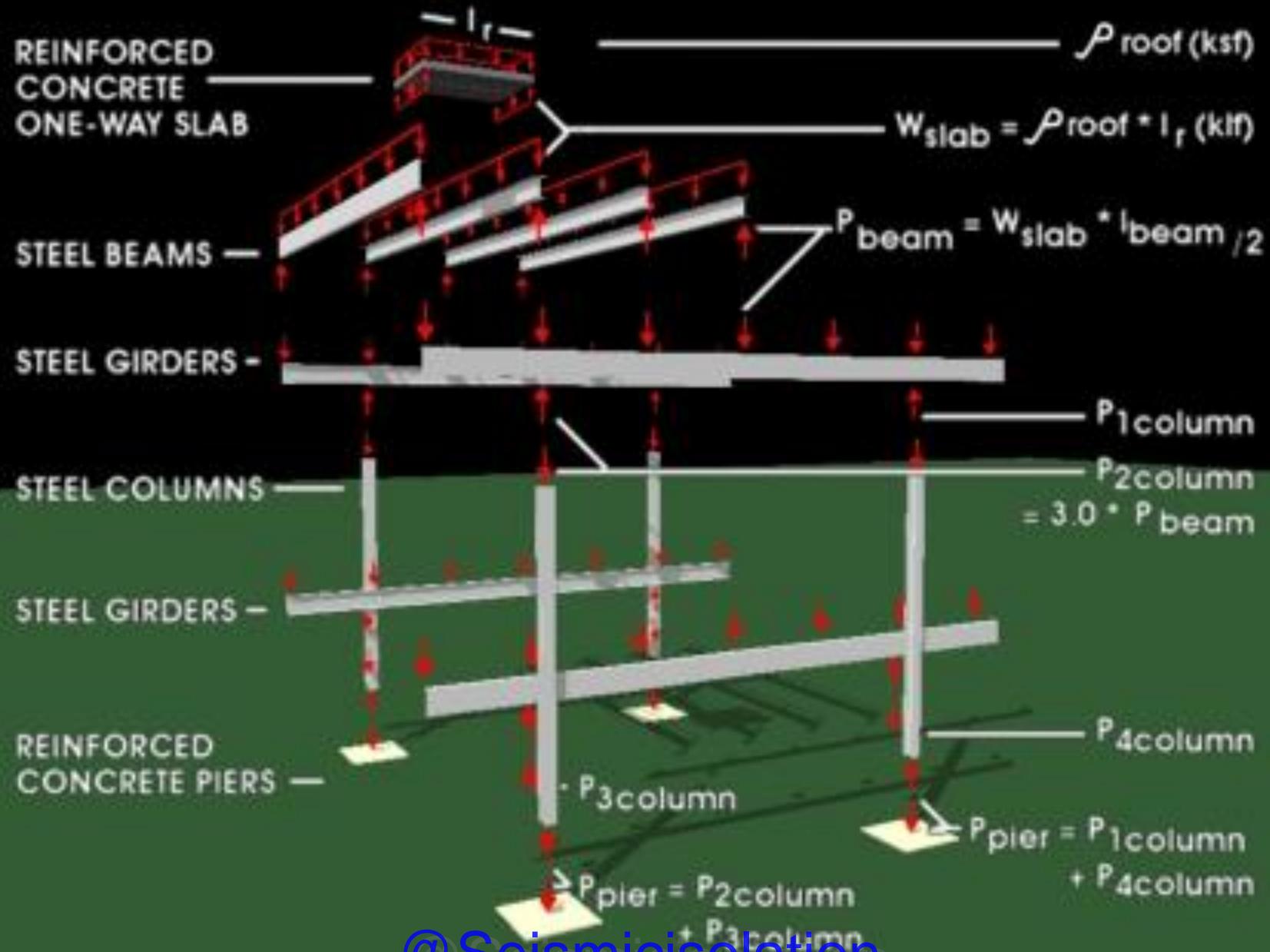
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Restaurant Bangkok



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Siam, Bangkok



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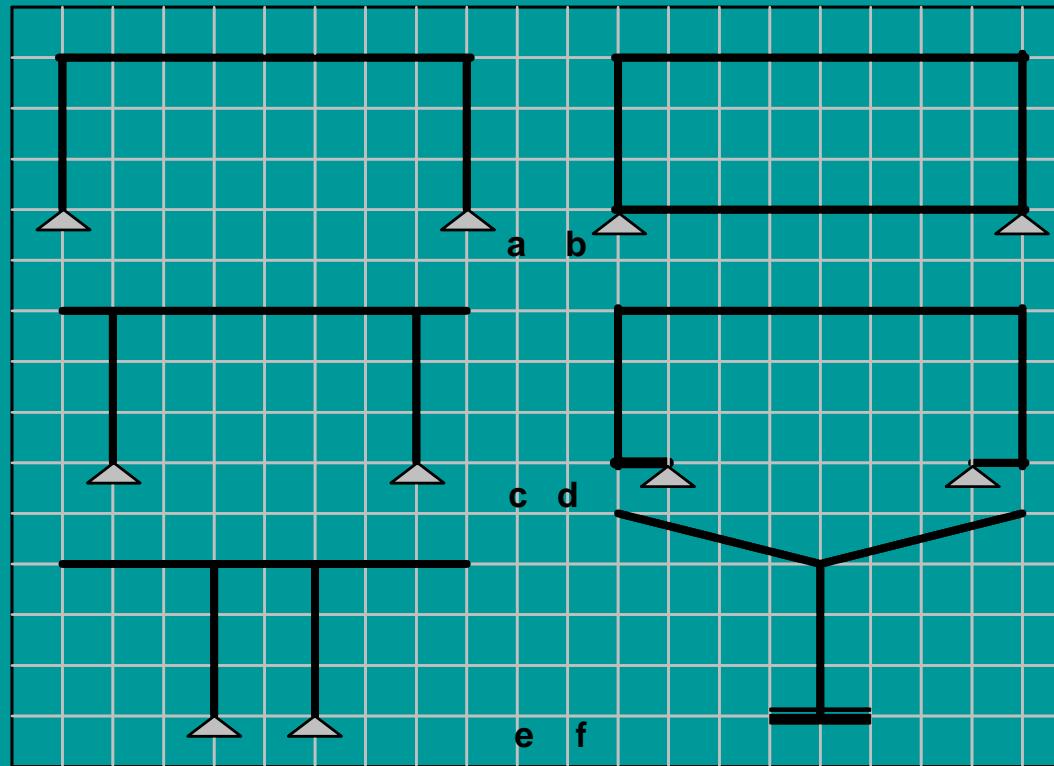


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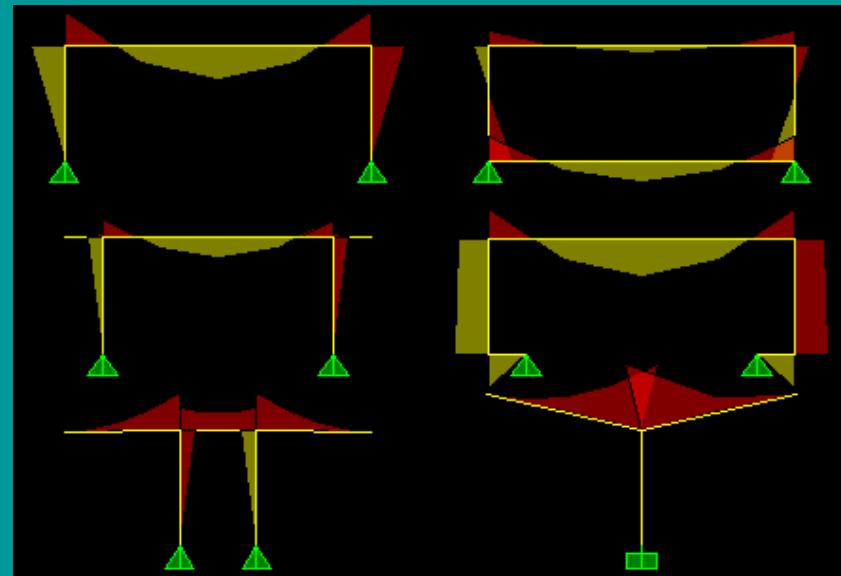
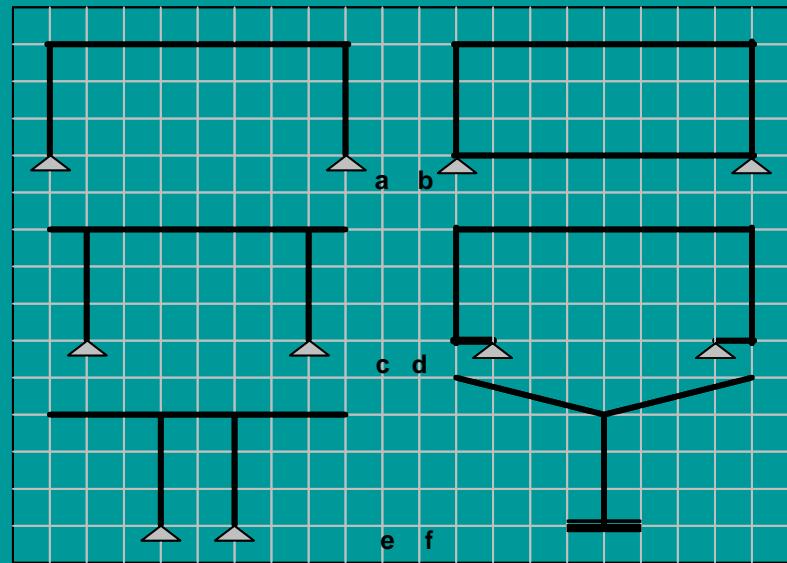


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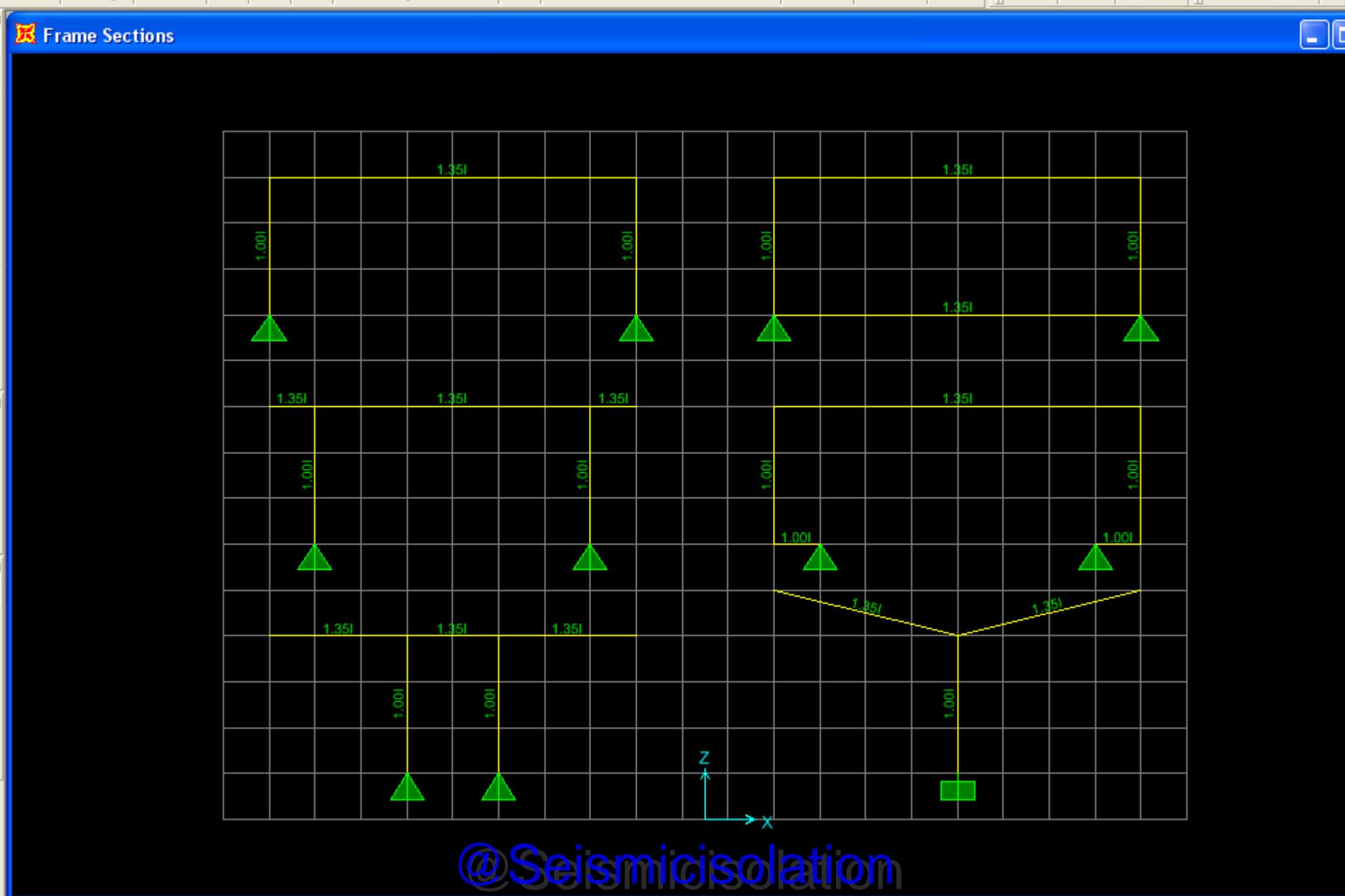
CANTILEVER FRAMES

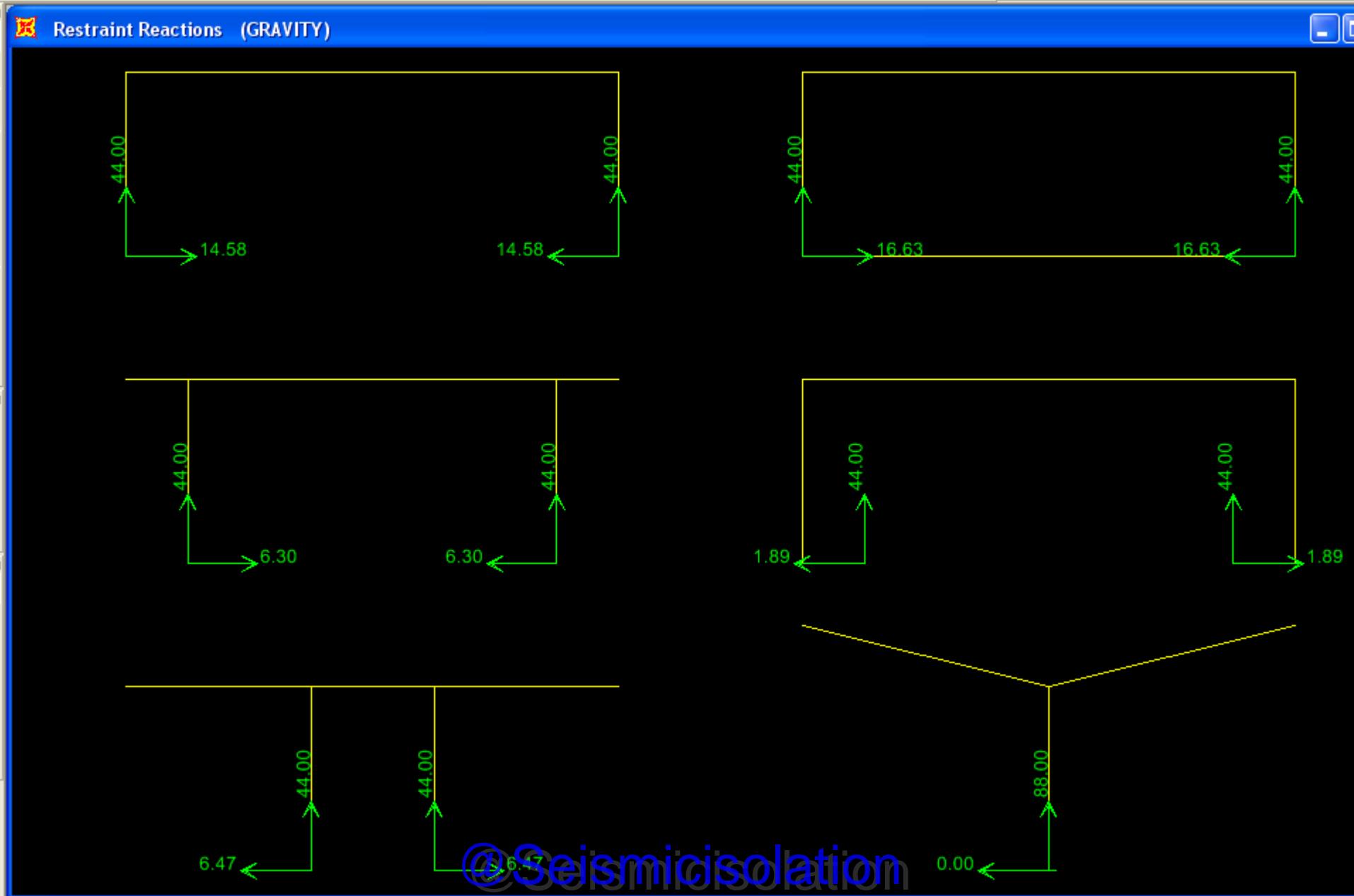
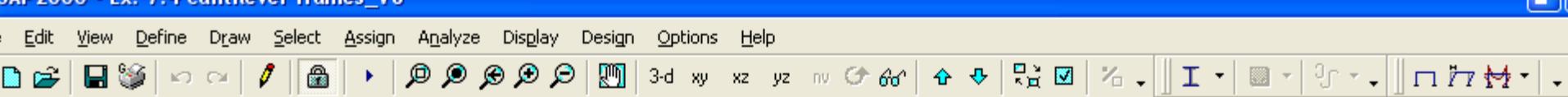


With increase of span the single-span concept becomes less efficient because of the rapid increase in moment and deflection that is increase in dead weight. The magnitude of the bending stresses is very much reduced by the cantilever type of construction.



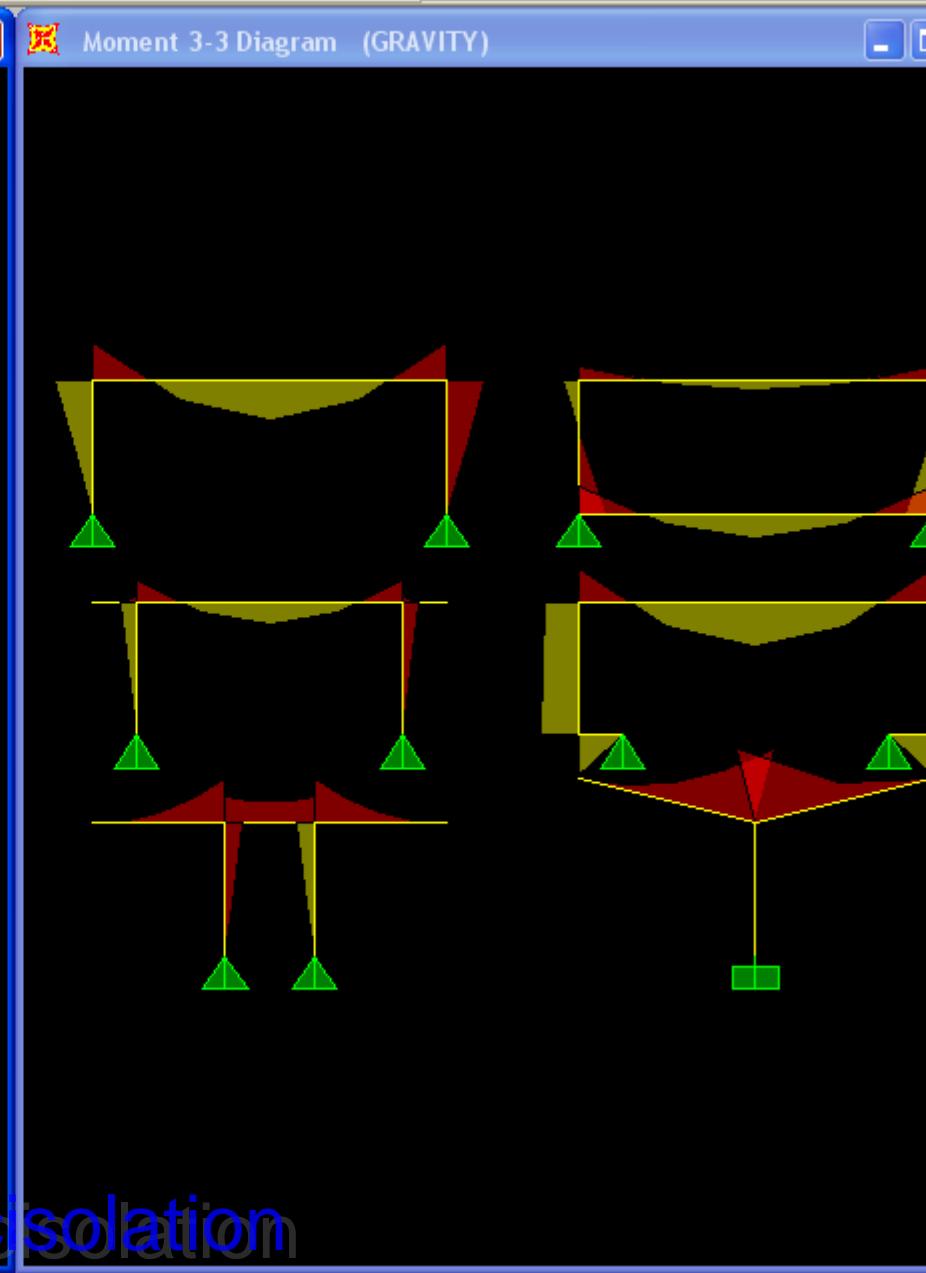
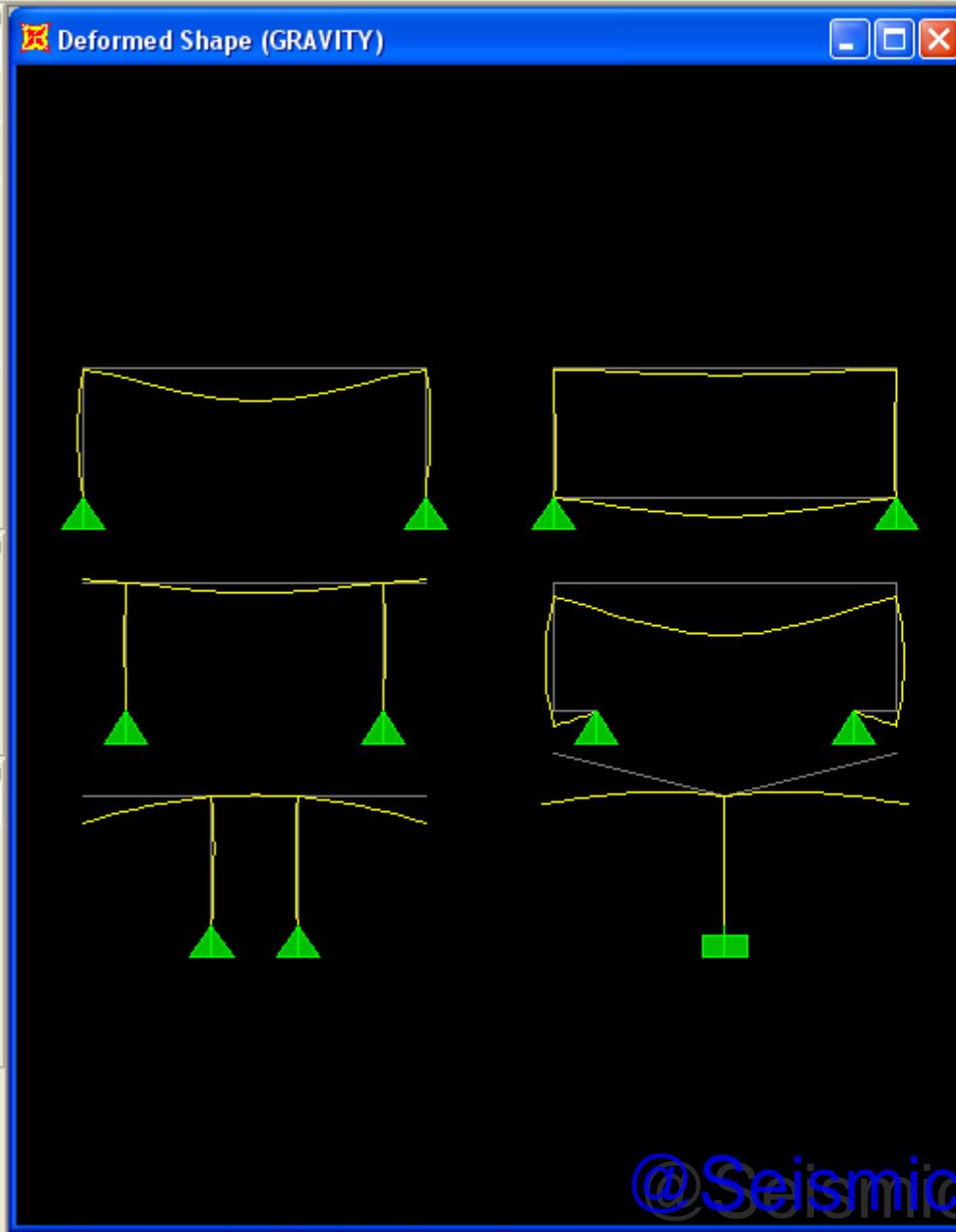
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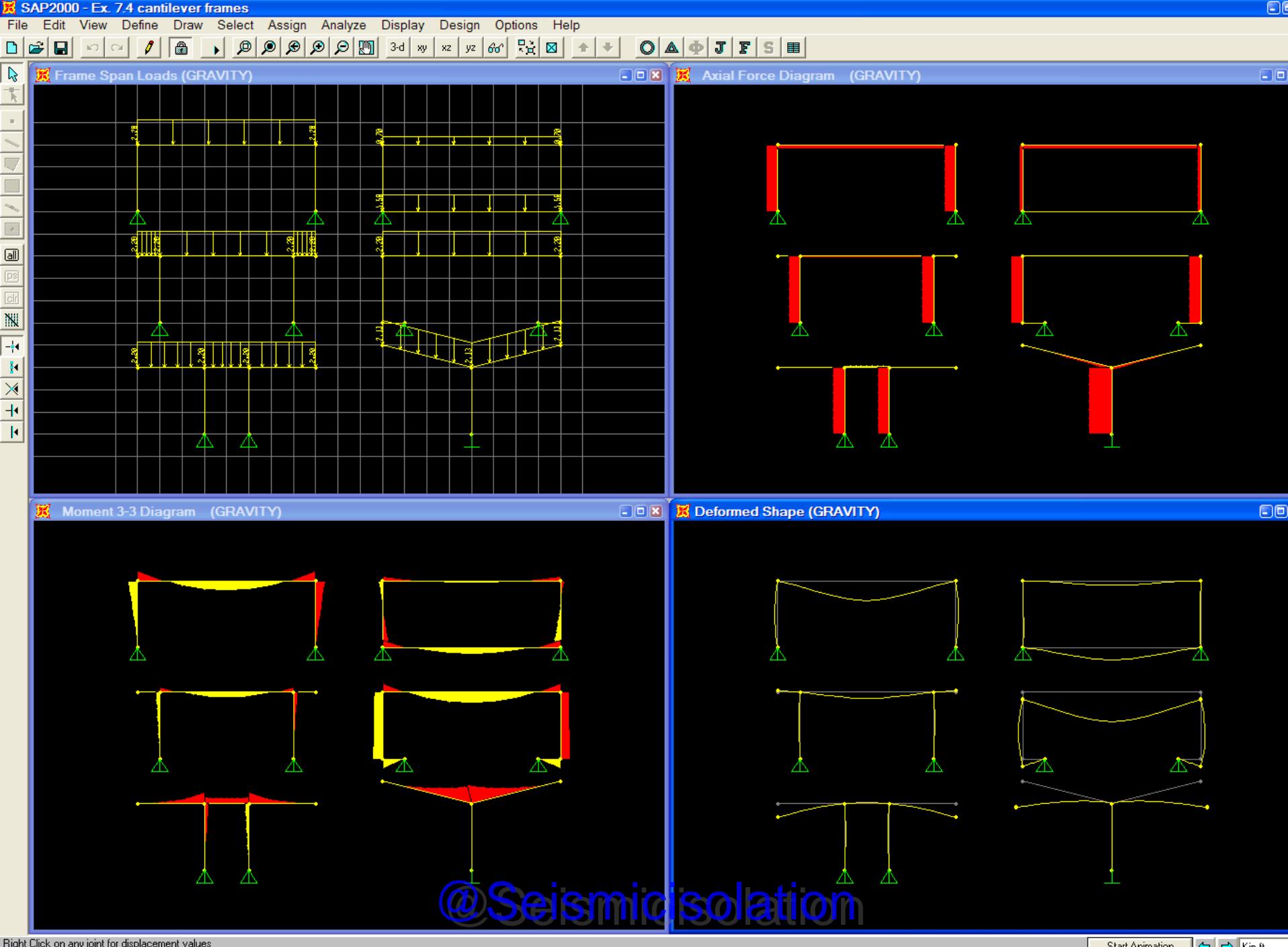


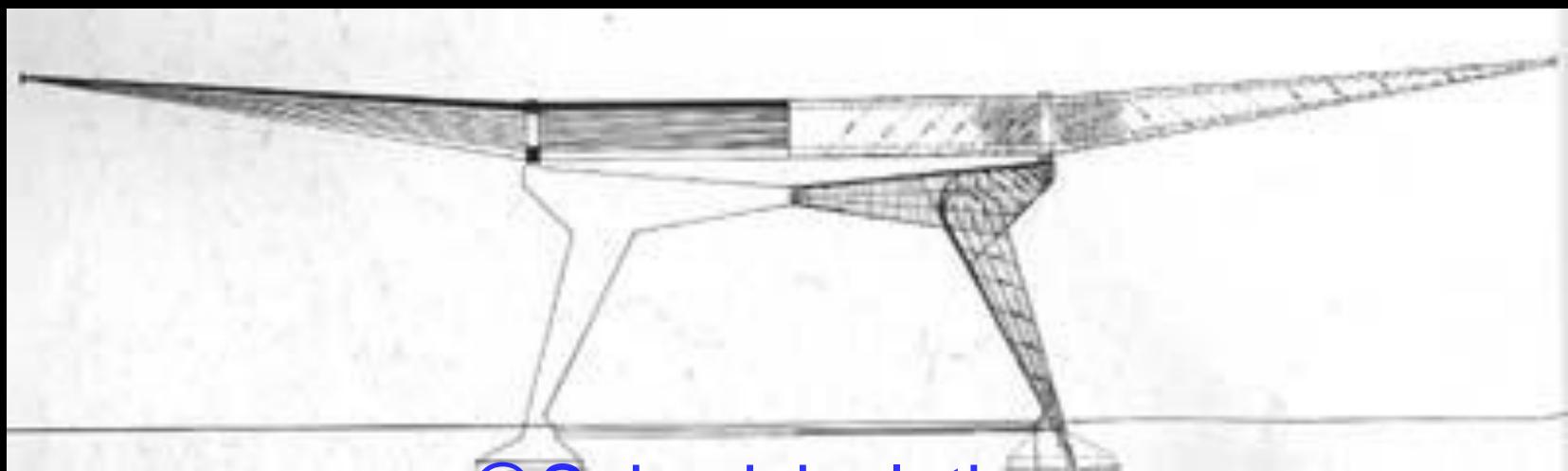
Click on any Joint for reaction values

GLOBAL Saturday, April 1



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International Airport, Rome, Italy, 1957, Pier Luigi Nervi



San Diego Library, 1970, William L. Pereira

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Palau de les Arts, Valencia Opera House, 2005, Santiago Calatrava



Ciudad de las Artes.
Valencia, Spain, 2002,
Santiago Calatrava



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*Stadelhofen Station, Zurich, Switzerland,
1990, Santiago Calatrava*

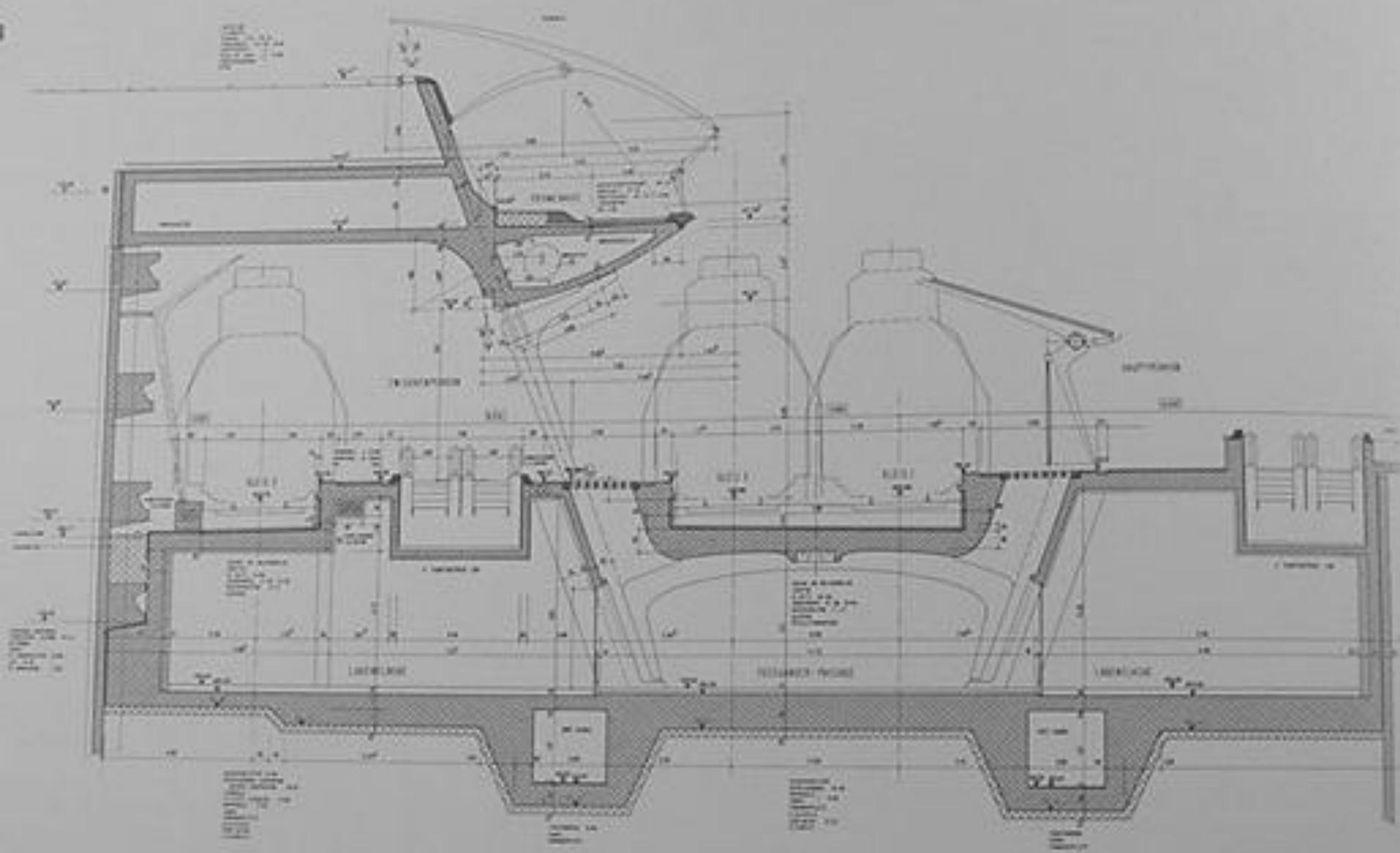
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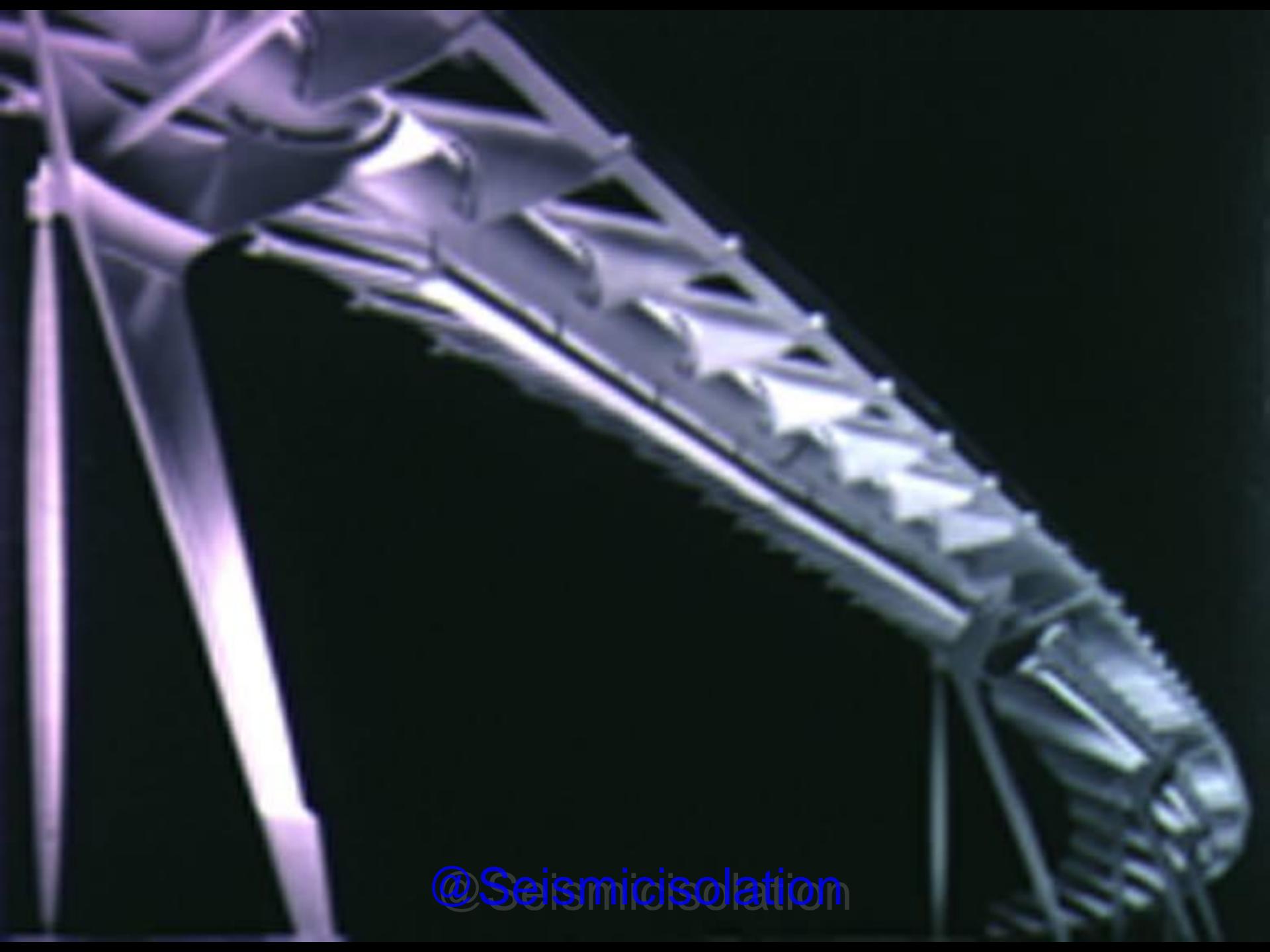
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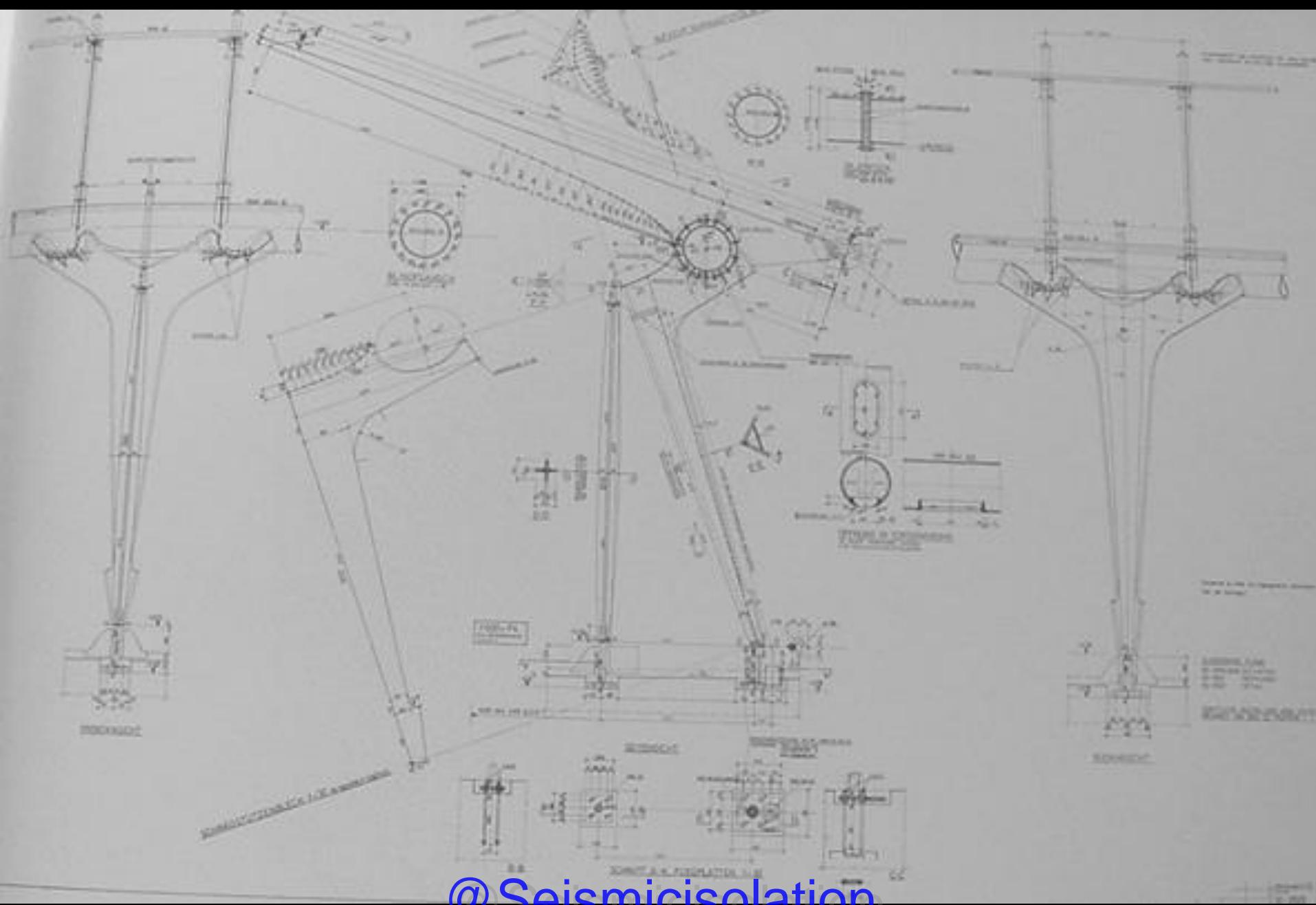
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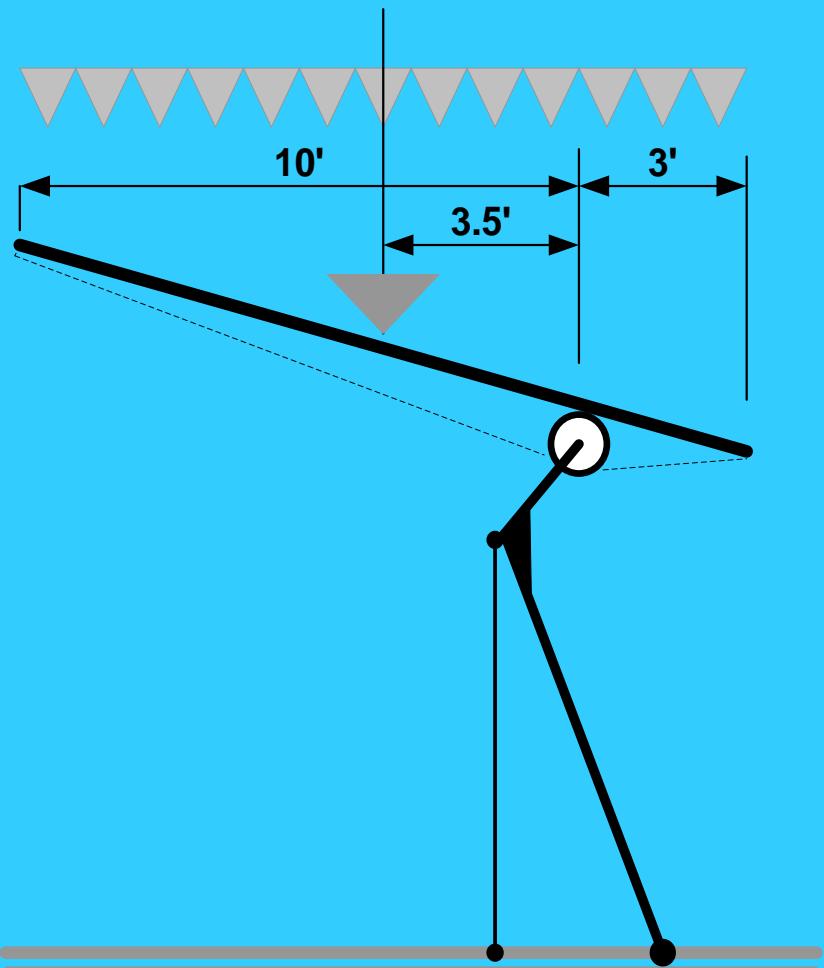
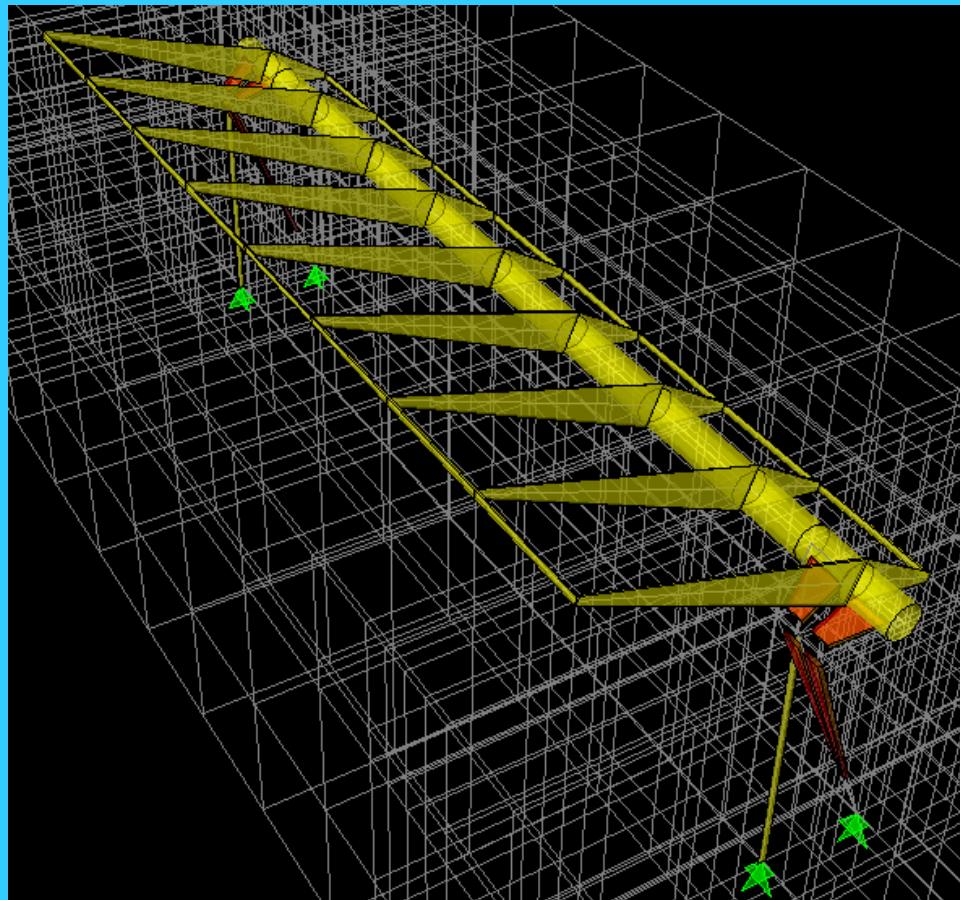
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A blurred, high-angle view of a bridge or elevated roadway structure at night. The structure is illuminated by artificial lights, creating streaks of light against a dark background. The perspective is looking down the length of the bridge.

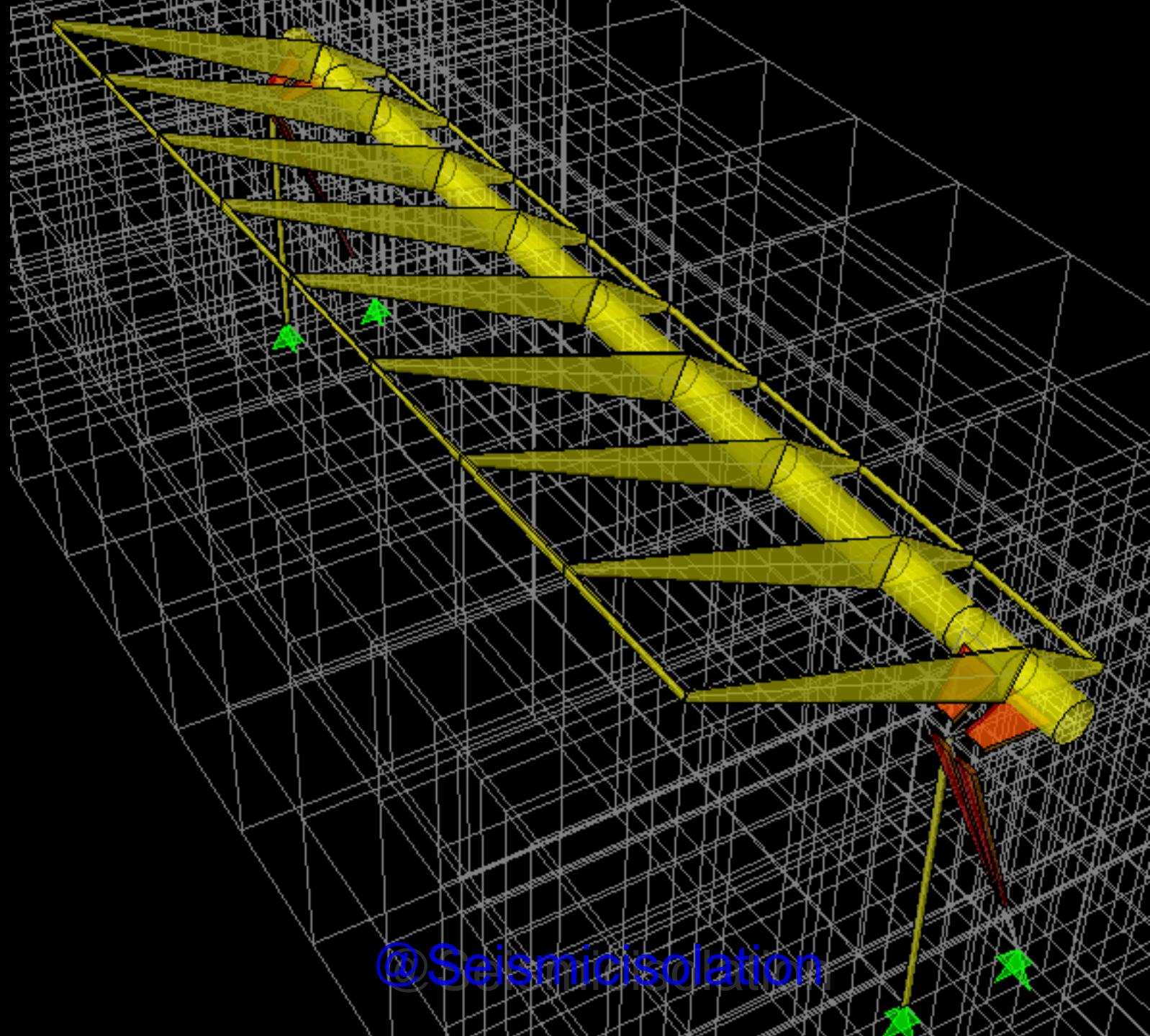
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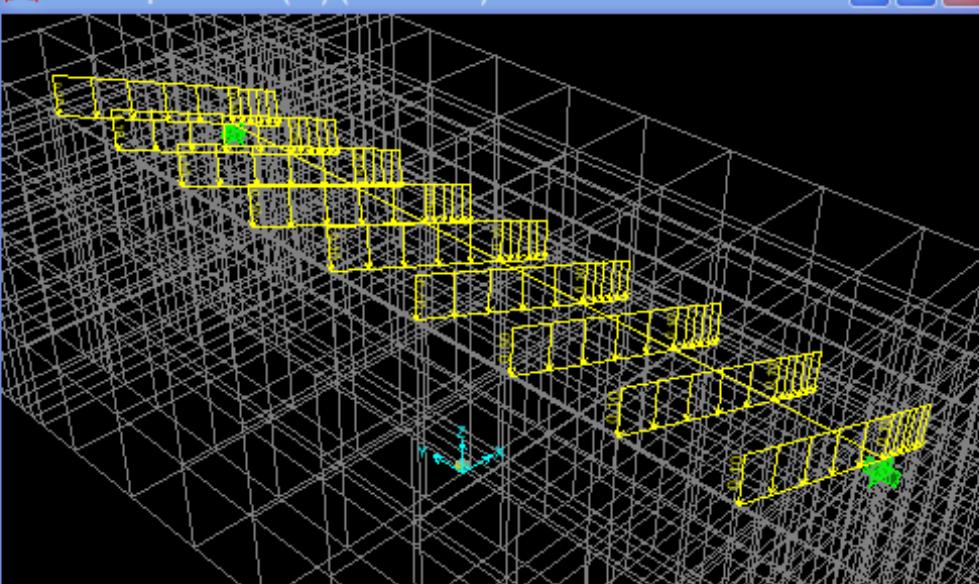


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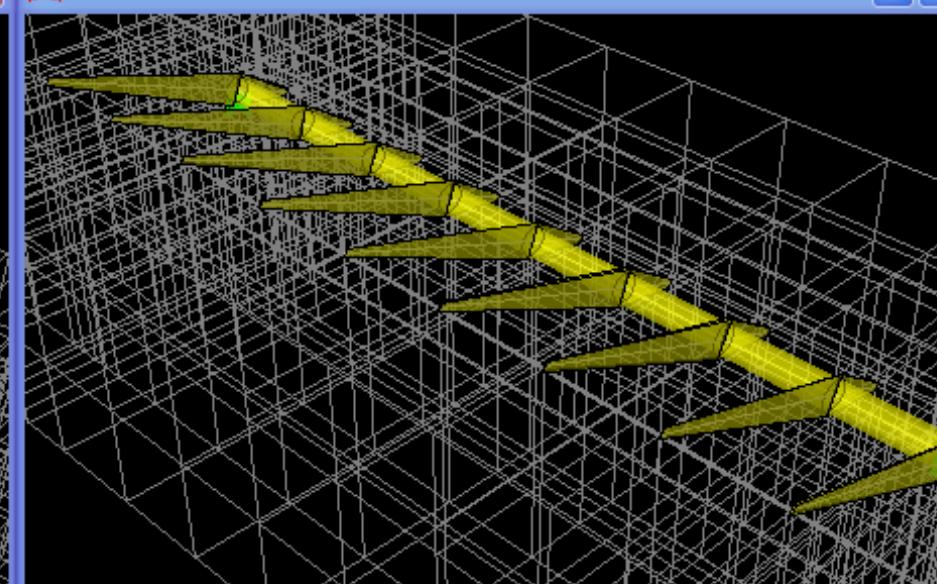
Edit View Define Draw Select Assign Analyze Display Design Options Help



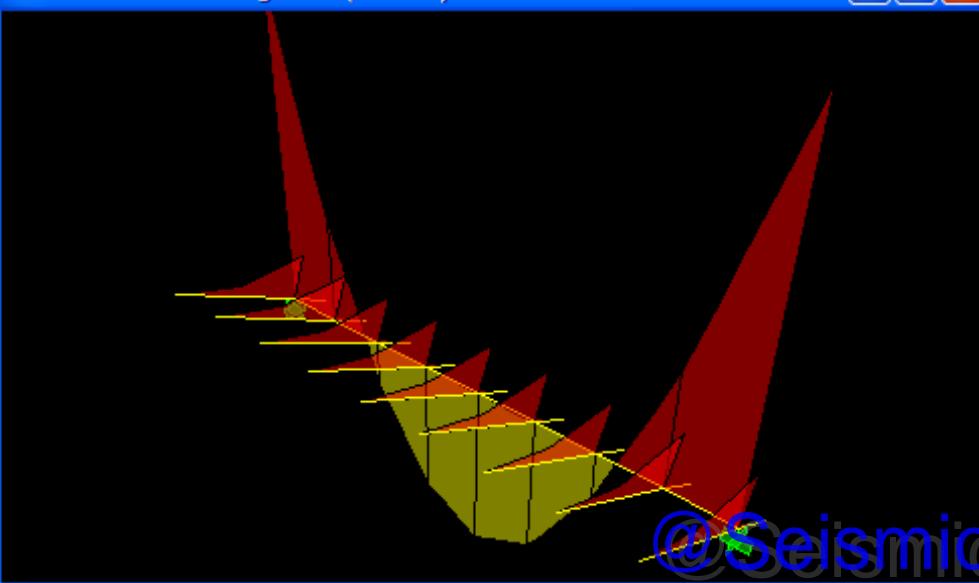
Frame Span Loads (DL) (As Defined)



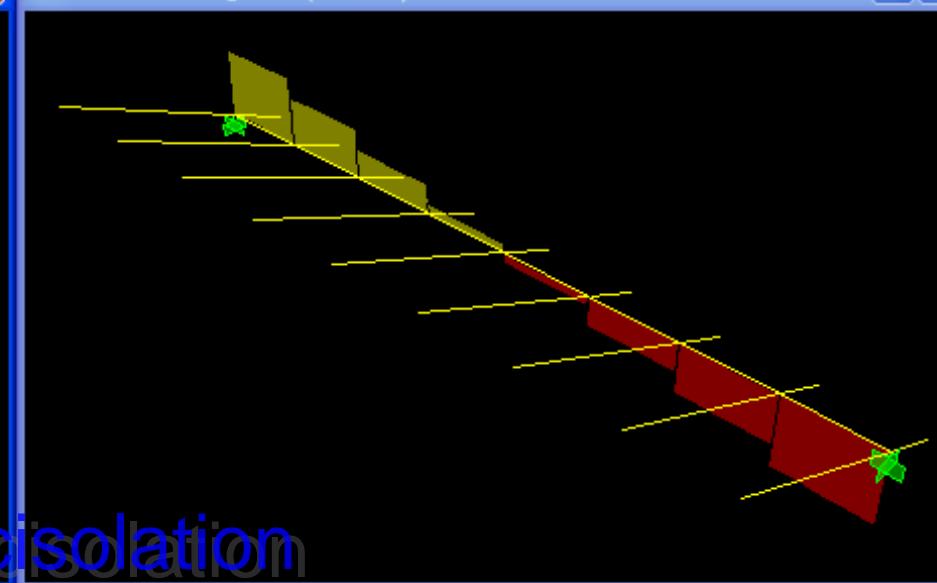
3-D View



Moment 3-3 Diagram (COMB1)



Torsion Diagram (COMB1)



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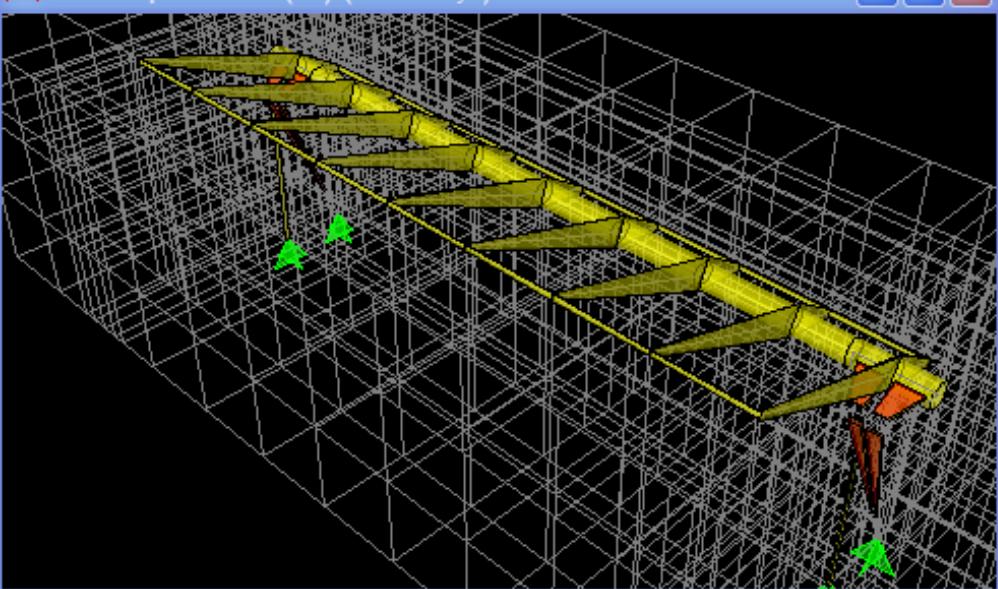
Click on any Frame Element for detailed diagram

GLOBAL Kip, ft, F

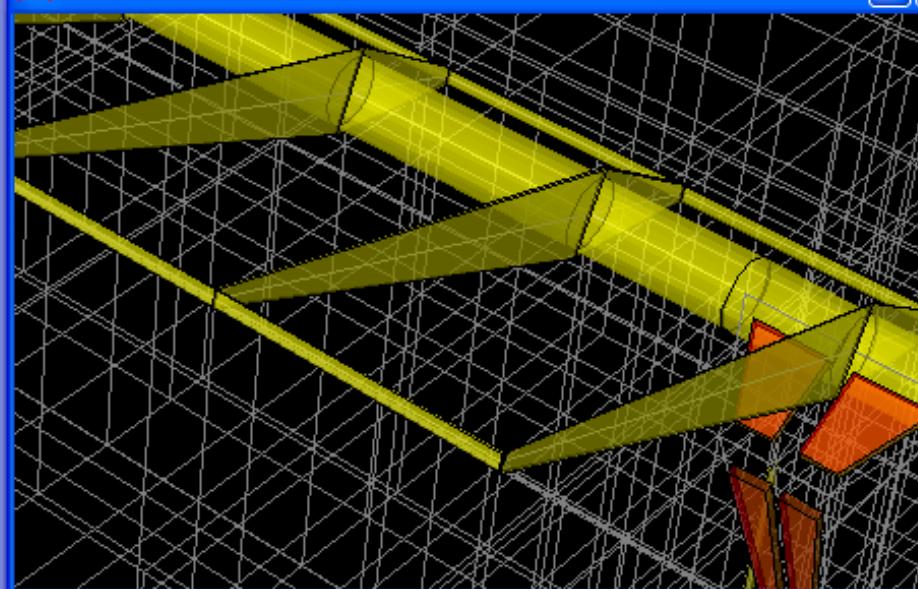
Edit View Define Draw Select Assign Analyze Display Design Options Help



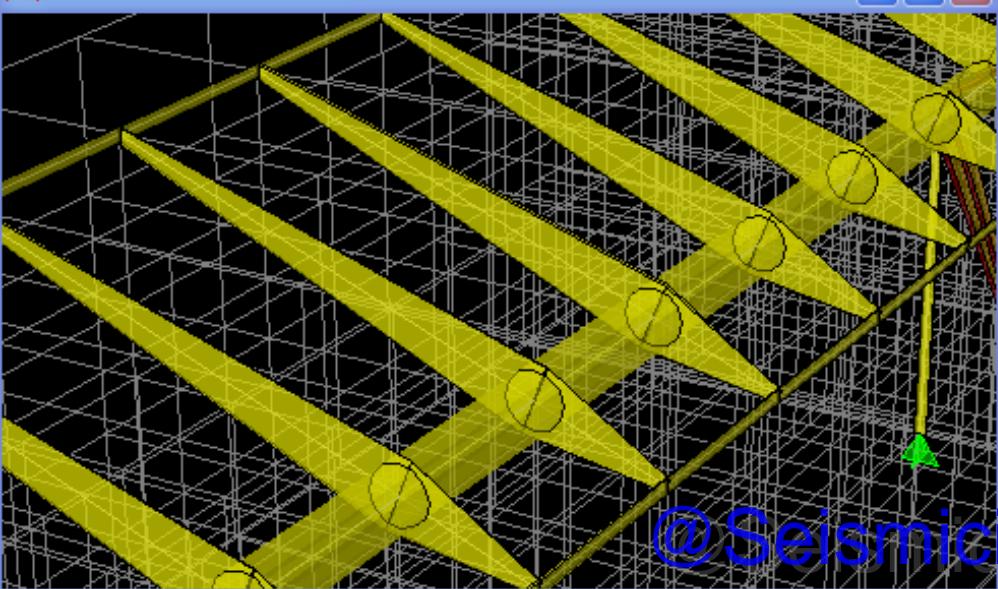
Frame Span Loads (DL) (Local CSys)



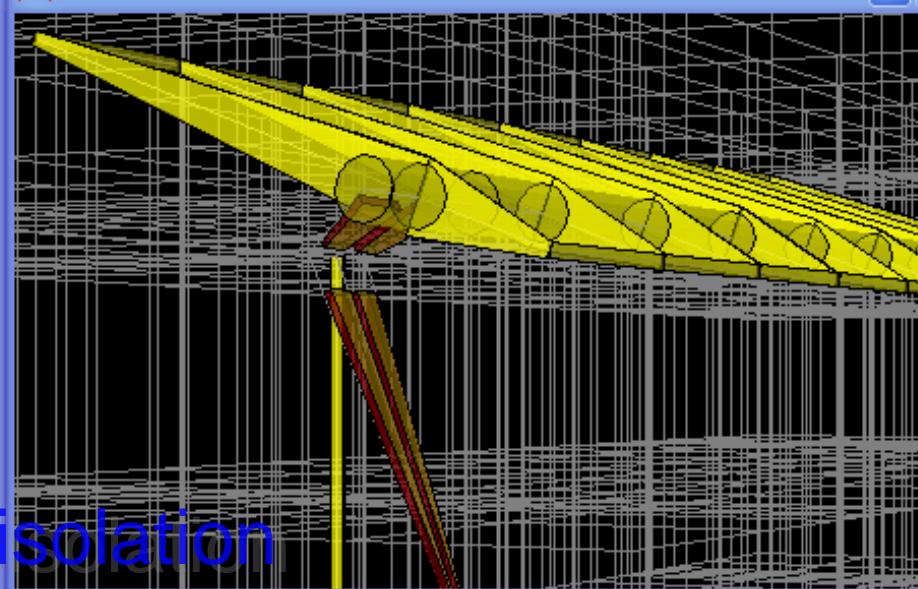
3-D View



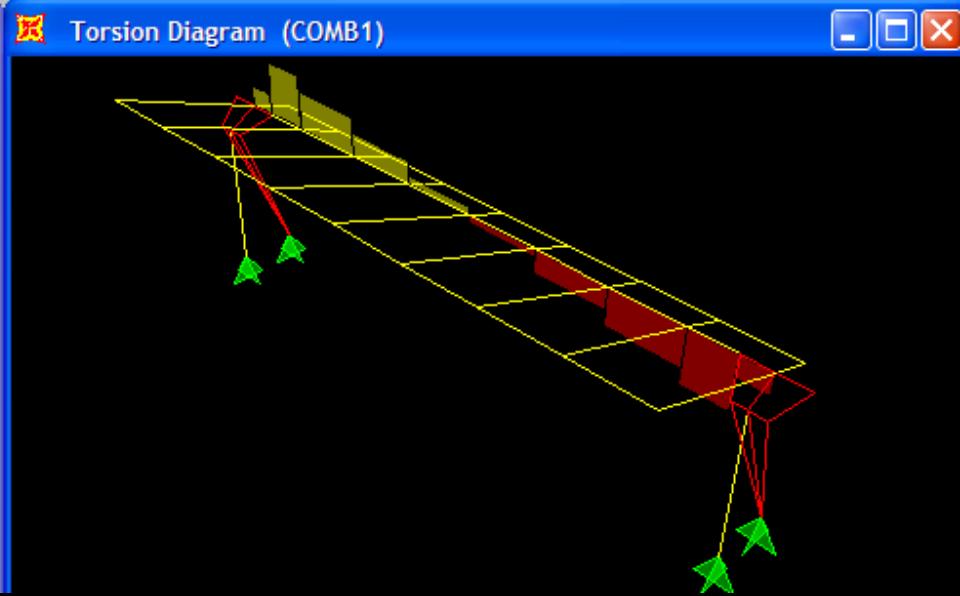
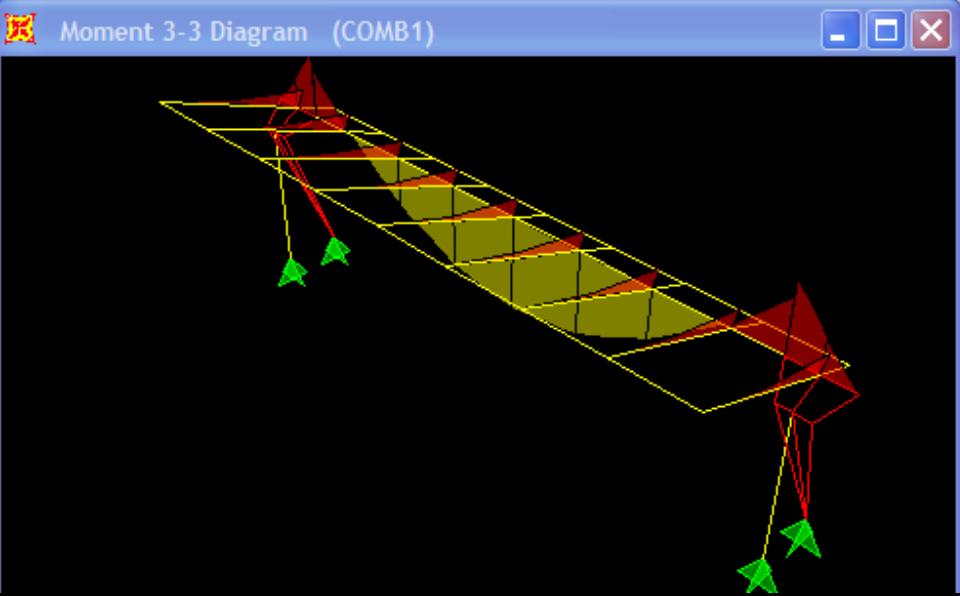
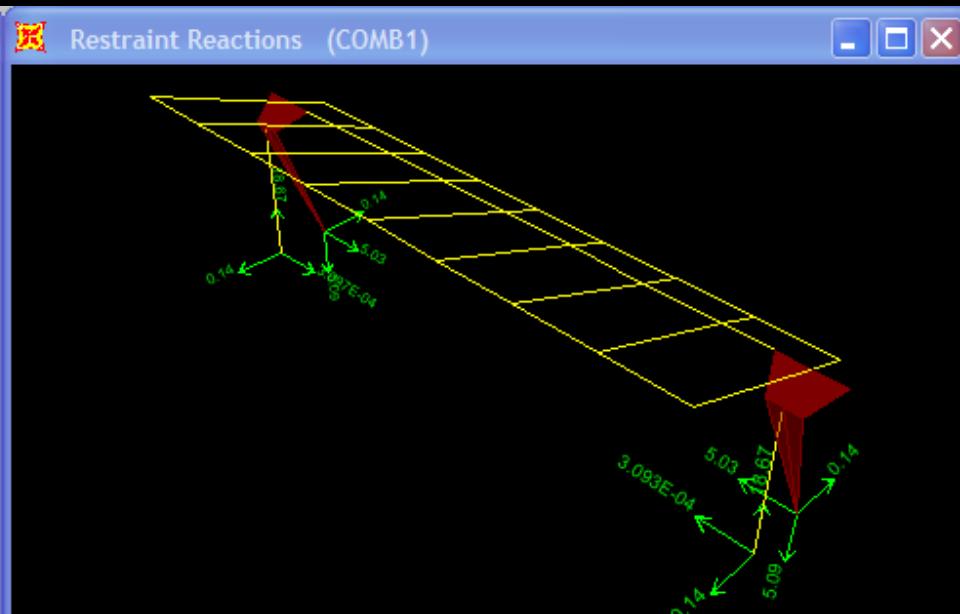
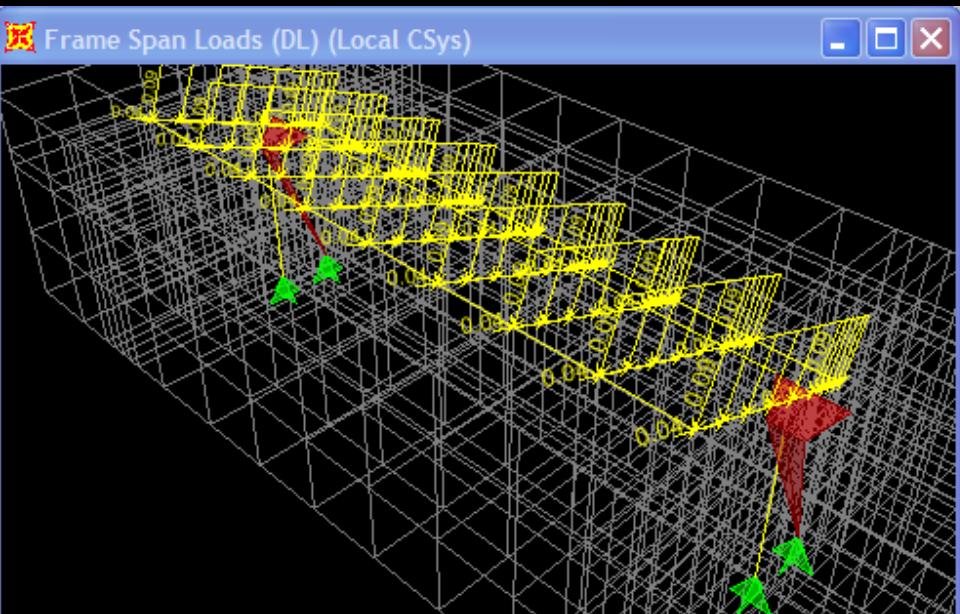
3-D View



3-D View



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BRACED FRAMES

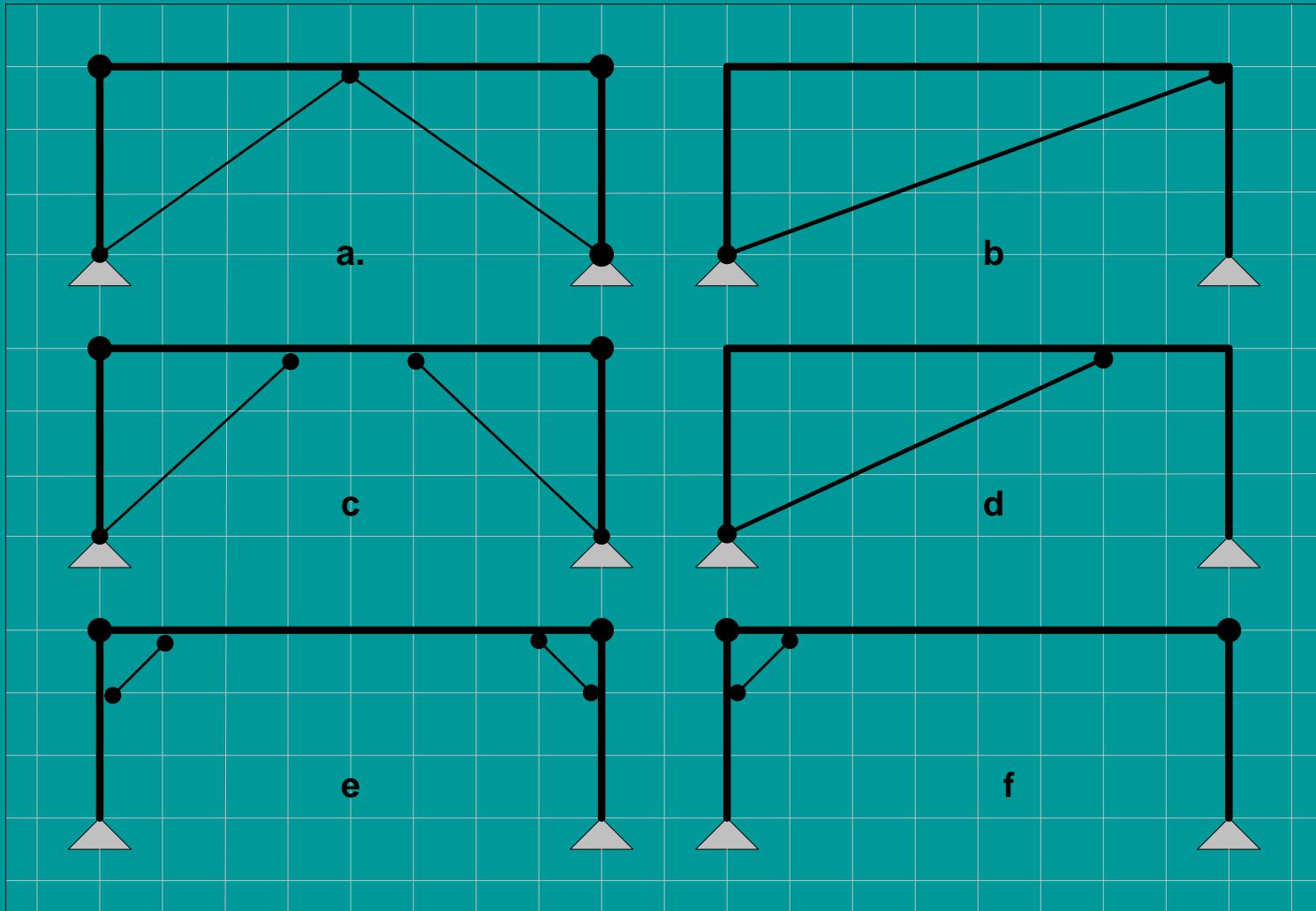
Frames can be braced in a concentric or eccentric manner as indicated for portal bents. Cases A. and B. are **concentrically braced**, while cases C. and D. are **eccentrically braced**, and cases E. and F. have **knee bracing**. In the **symmetrical post-beam structures** (A., C., and E.) the braces change from K-bracing, to eccentric bracing to knee bracing. In the **asymmetrical frames** (B. and D.) the change is similar from diagonal bracing to the beam-column intersection, to a single eccentric bracing, and then to knee bracing for the post-beam structure.

The knee braces as often found in wood construction, do not provide a rigid support to the beam; the support settlement is a function of the column stiffness. **The knee-braced corners of frames can be visualized as rigid frame connections.**

In earthquake regions the use of eccentric bracing should be considered. While the conventional concentrically braced frames are very stiff because the forces are transmitted directly in axial fashion, under severe cyclic loading the braces may buckle because of the lack of ductility and cause an unbalance of loading, which may result in failure. However, when the brace is connected eccentrically to the beam, rather than concentrically to the beam-column intersection, then the diagonal force is transmitted in shear and bending along the beam segment, forming a **ductile link**, where the plastic deformations prevent the brace from buckling.

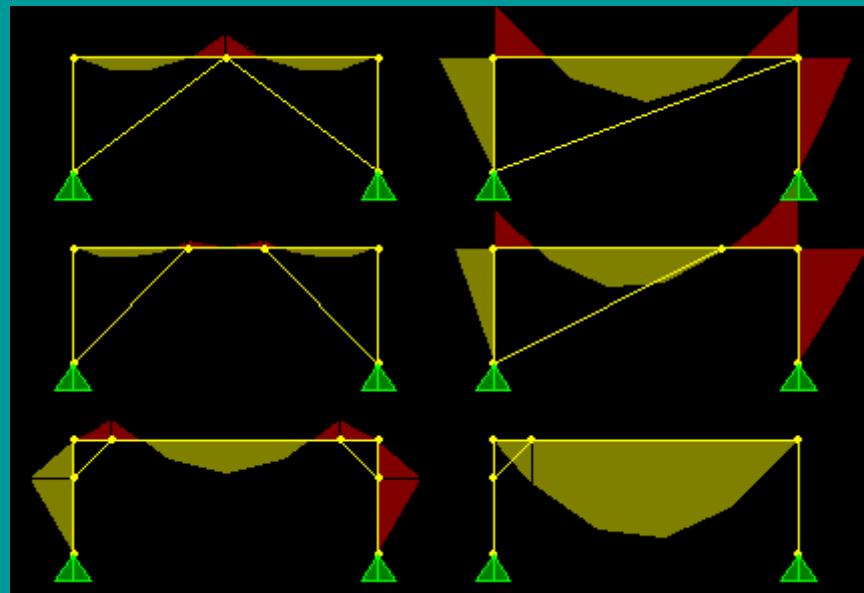
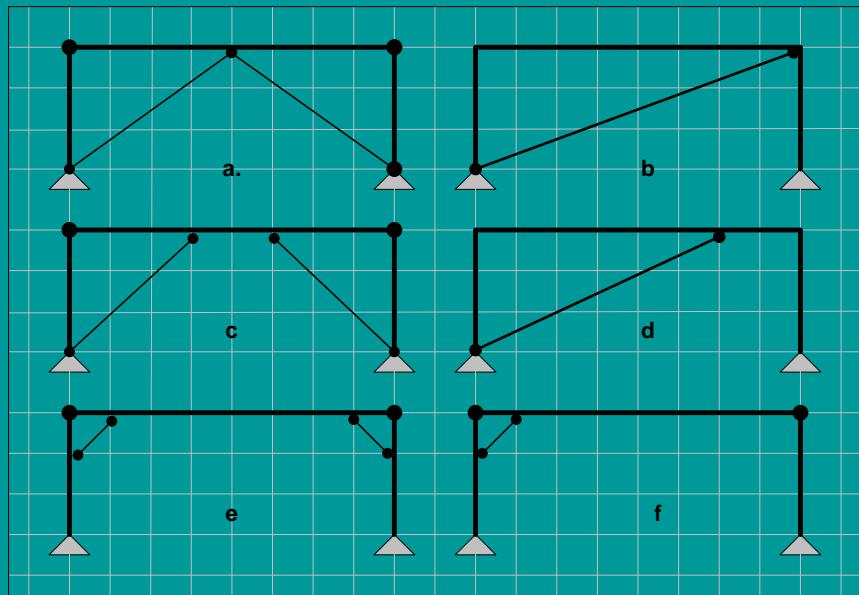


Eccentric, braced frame
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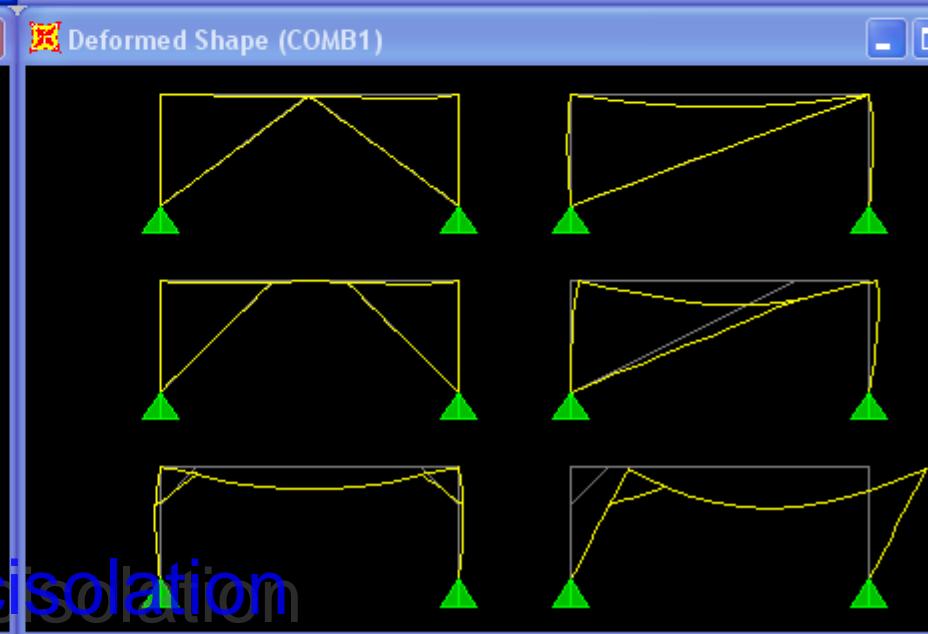
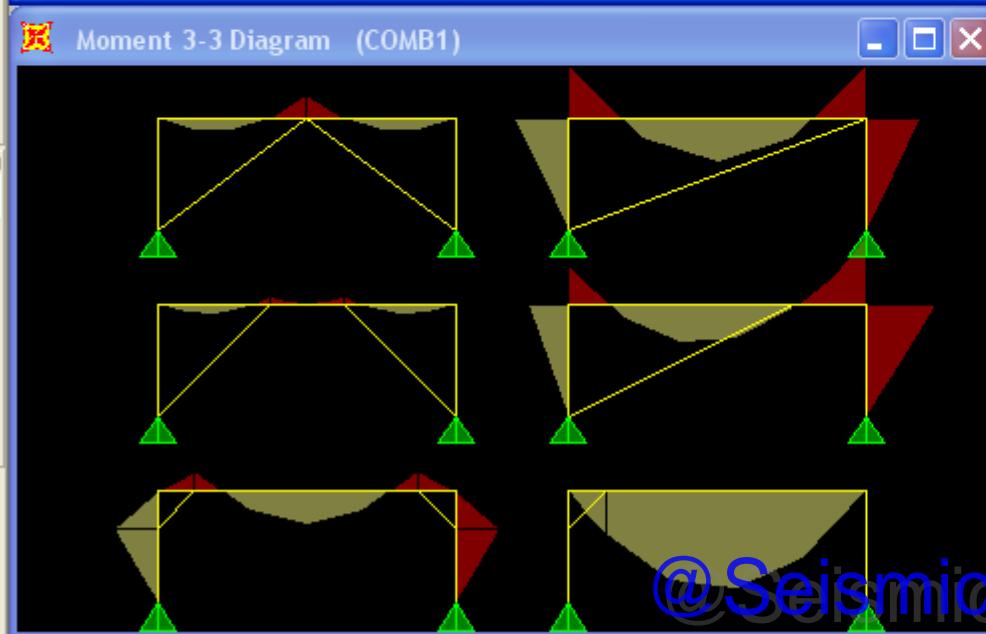
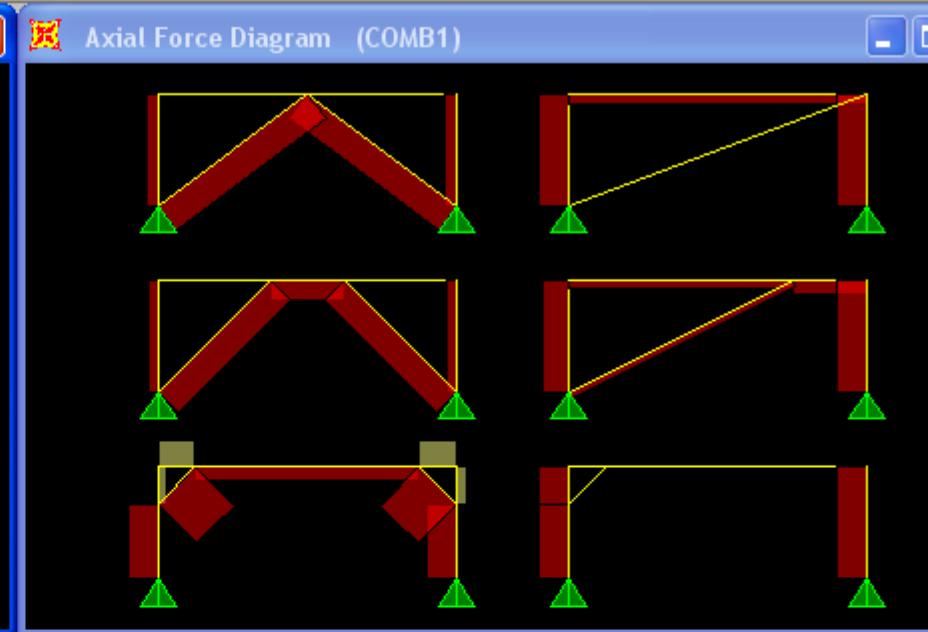
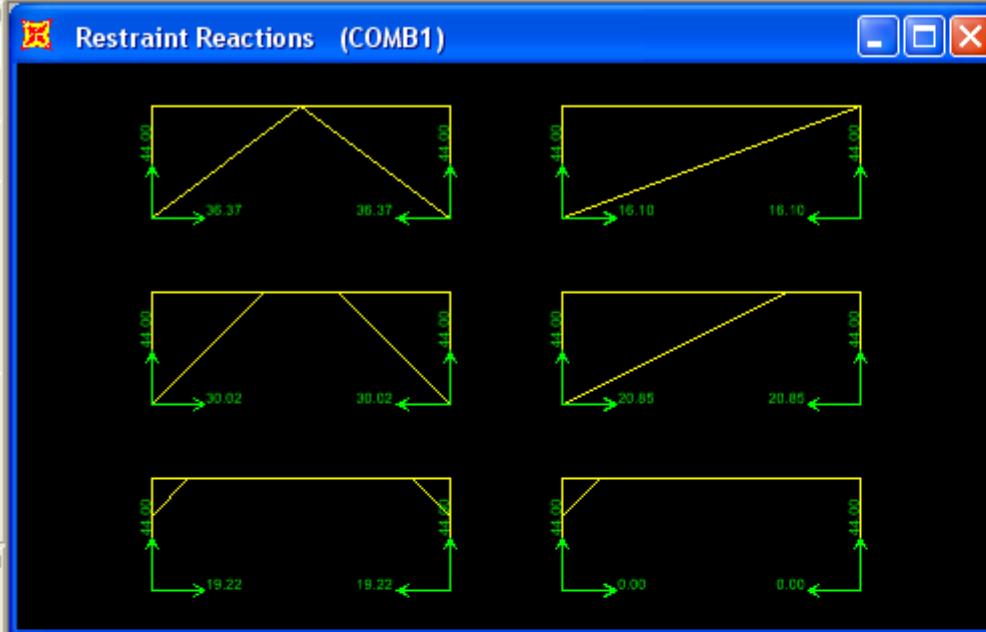


BRACED FRAMES

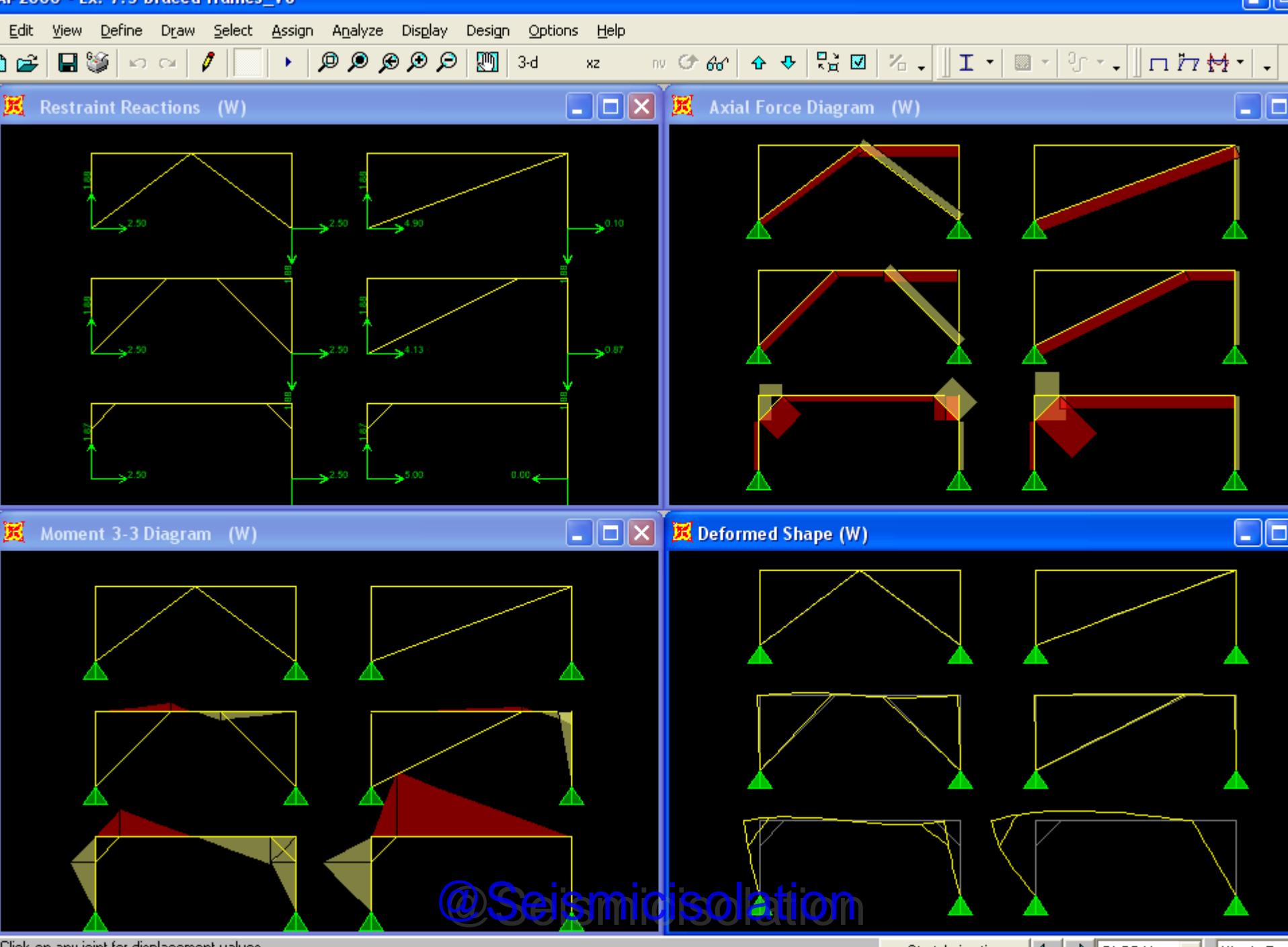
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Pitched Frames

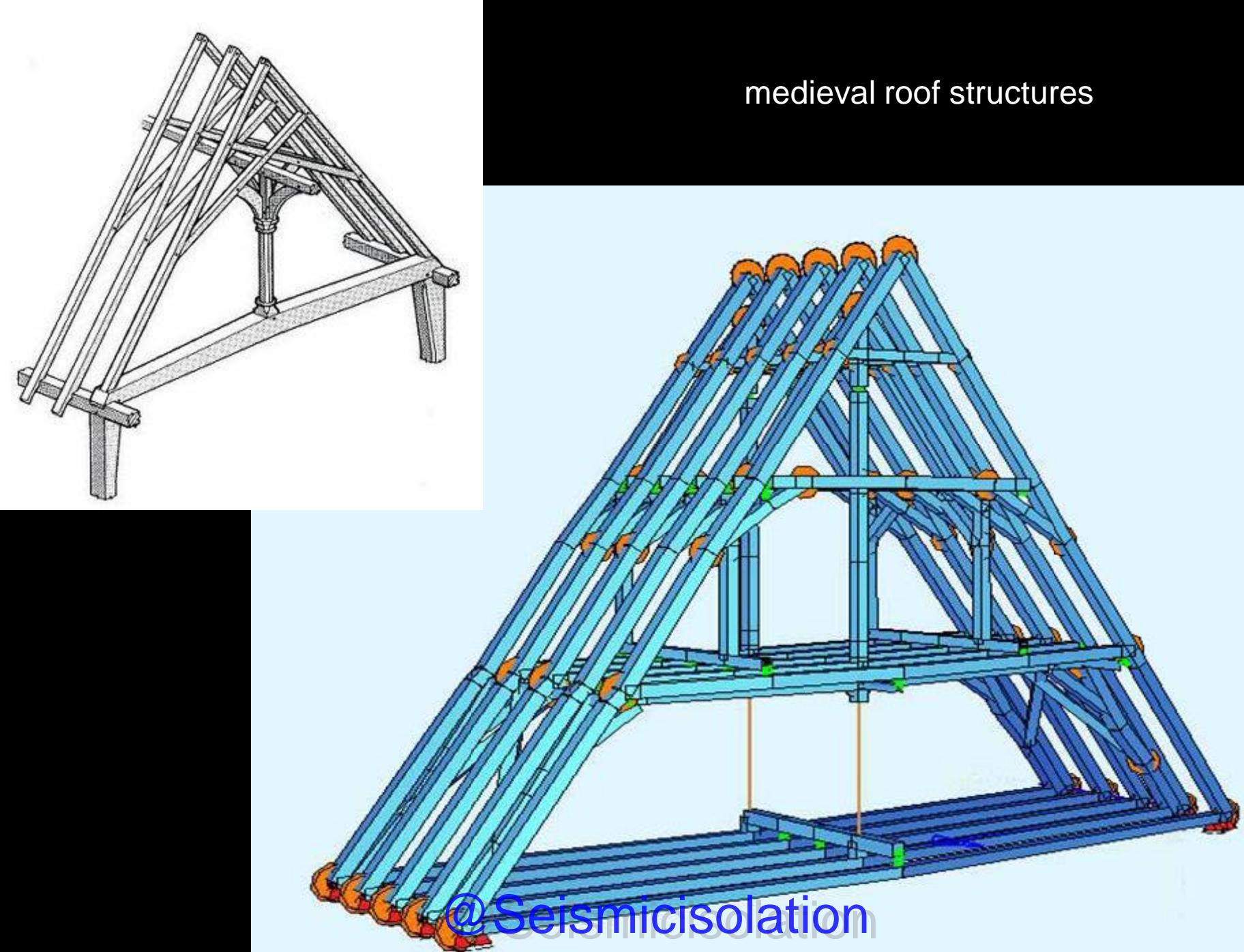
The pitched frame concept ranges from residential roof construction to the folded frame for industrial buildings. Several typical examples are shown in Fig. 7.7.

Case (A.) is **basic triangular truss unit**; when the tie is taken out and the roller support is replaced by a pin support, then the structure forms a **three-hinge A-frame**. In wood construction the inclined beams are called rafters. A statically indeterminate **collar frame** is shown in case (C.), where the simple A-frame is internally braced by a collar strut to reduce the bending in the beams, w. For the strut to be truly effective, floor decking or horizontal bracing should connect the various collar ties together to form a horizontal deep beam, which must be supported by shear walls or vertical trussing. For this method of construction, the collar strut provides a rigid support to the beams; otherwise, a flexible support would only be available under unsymmetrical load action, requiring much larger member sizes.

Case (B.) represents a **post-beam structure** as is typical for residential construction. In contrast to A-frame construction, where the beams support each other at the crown to form a continuous frame, in the post-beam structure the inclined beams or joists (if they are closely spaced) function independently as inclined simple bending members, supported on ridge beams. For the post-beam structure there are no ties at the base support required because there is no thrust under gravity action. In case (D.) **intermediate beam supports** are introduced to reduce bending and deflection.

Case (E.) is a **three-hinge gable frame** whereas in case (F.) a tie rod is added to frame knees to reduce the thrust and thus reduce bending in the frame.

The critical moment for the gable frame is at the knee, the field moments along the inclined frame beam are rather small when compared with the support moments so they do not play an important role during the preliminary design process.



RSTAB 5.12 - [3D_HALLE, Rendering]

Datei Bearbeiten Ansicht Einfügen Berechnung Ergebnisse Extras Makro Zusatzmodule Fenster Hilfe

LF1-Eigentags

RSTAB

- Kaoping2 [Präsent]*
- Winter Garden [3400]
- 3D_HALLE [Präsent]

Strukturdaten

- Knoten
- Materialien
- Querschnitte
- Gelenke
- Teilungen
- Stäbe
- Auflager
- Elektrische Bettungen
- Nichtlineare Federn
- Stahl-Kopplungen
- Exzentrische Anschlüsse
- Stabzüge

Belastungen

- Lastfälle
- LF-Gruppen
- LF-Kombinationen
- Super-Kombinationen

Ergebnisse

Ausdruckprotokolle

Zusatzmodule

- STAHL
- ASD
- EL-PL
- BGDK
- FE-BGDK
- FE-BDL
- BETON
- HOLZ
- DEFORM
- B-ZU-T
- STIRNL
- RAHMECK
- DSTV
- STARDBÜBEL
- DYNAM
- RSKNICK

1.1 Knotenkoordinaten

Knot-Nr.	Koordinaten-System	Bezugsknoten	Knotenkoordinaten			Kommentar
			X [m]	Y [m]	Z [m]	
1	Kartesisch	0	0.000	0.000	0.000	Gelagert
2	Kartesisch	0	0.000	-2.700	0.000	Gelagert
3	Kartesisch	0	0.000	-8.500	0.000	Gelagert
4	Kartesisch	0	0.000	-18.000	0.000	Gelagert

Knoten Material Querschnitte Gelenke Teilungen Stäbe Auflager Bettung Federn Kopplung Exz-Anschlüsse Stabzüge

Drücken Sie F1, um Hilfe zu erhalten.

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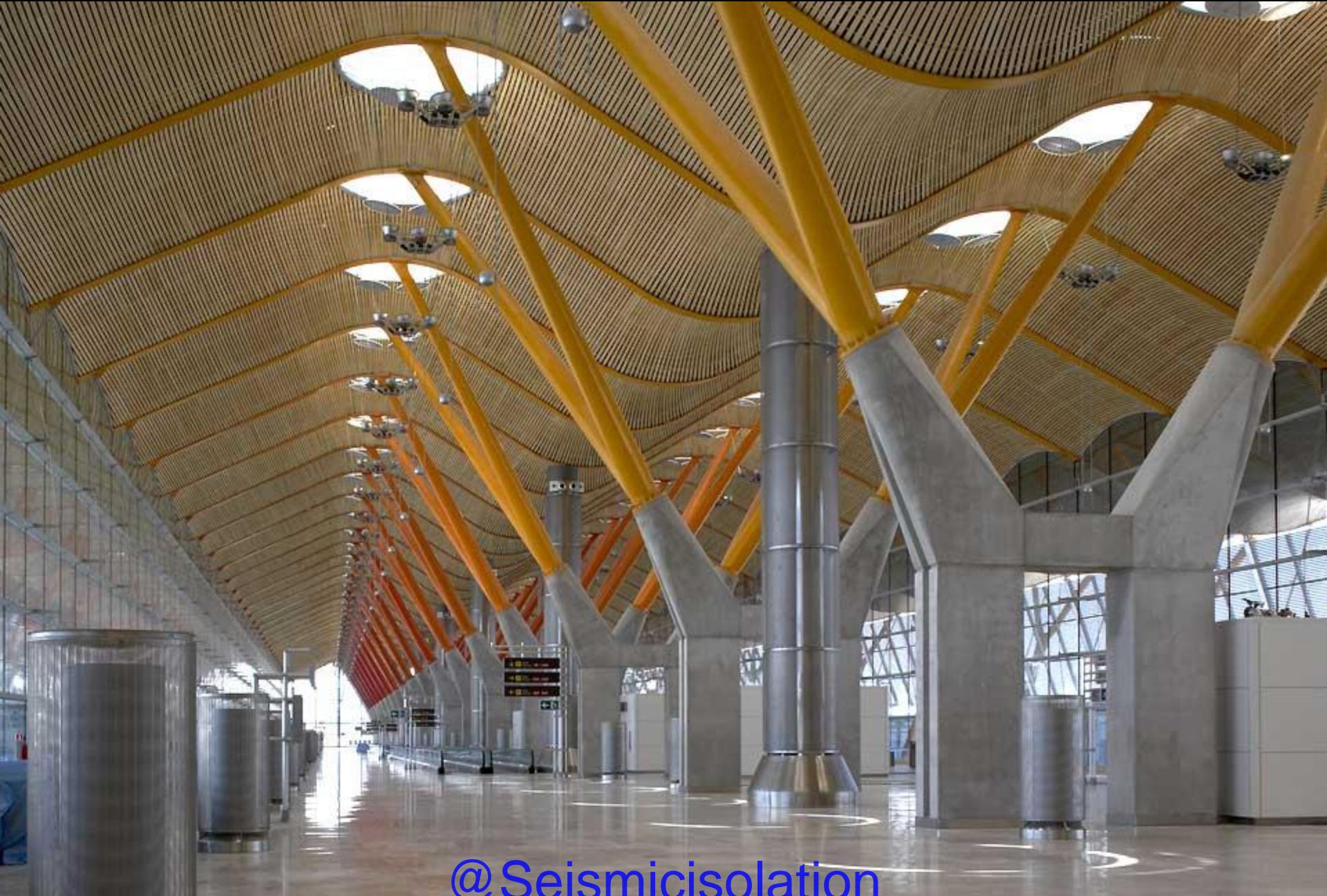


BMW Plant Leipzig, Central Building, 2004, Zaha Hadid

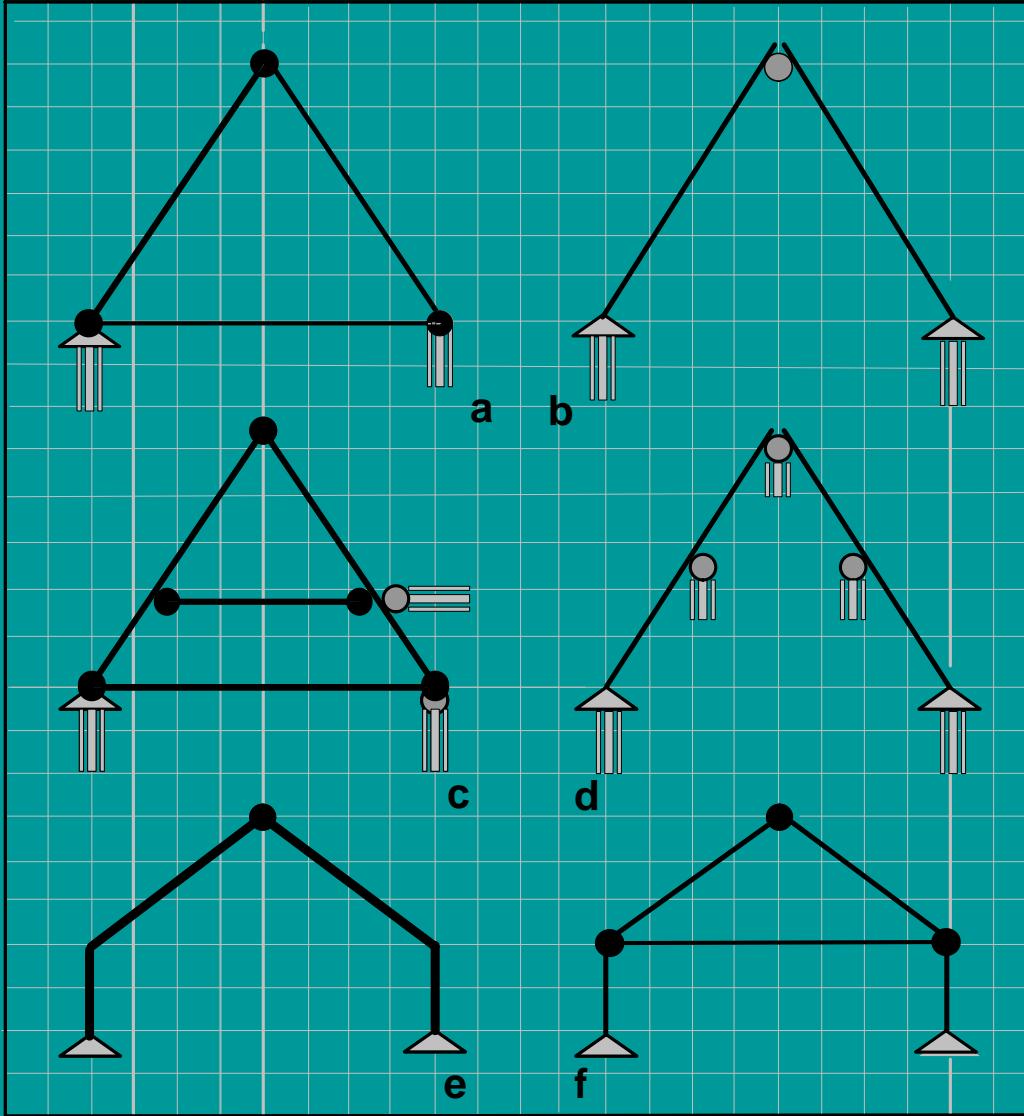


Airport Madrid,
Spain, Richard
Rogers, 2005

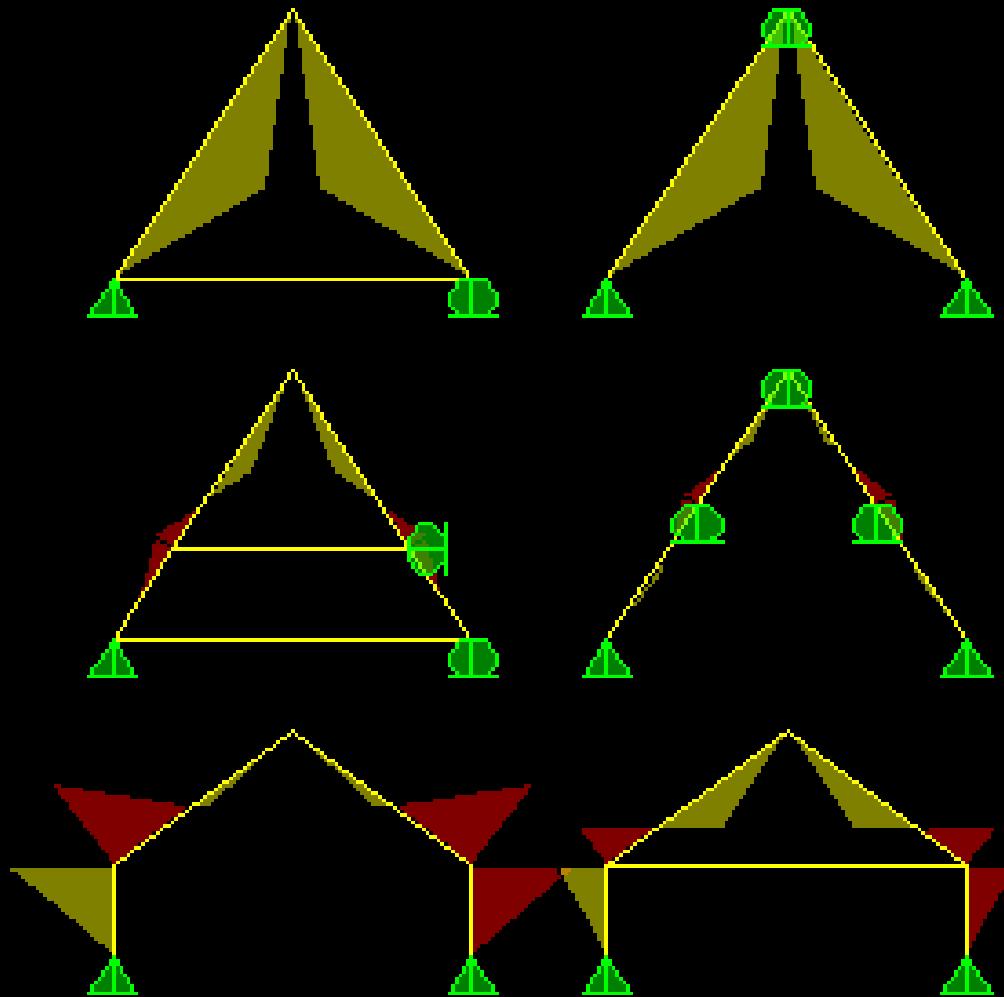
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PITCHED FRAMES
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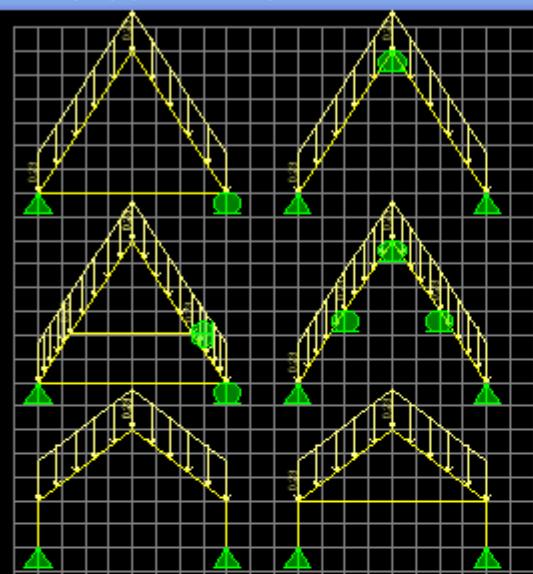
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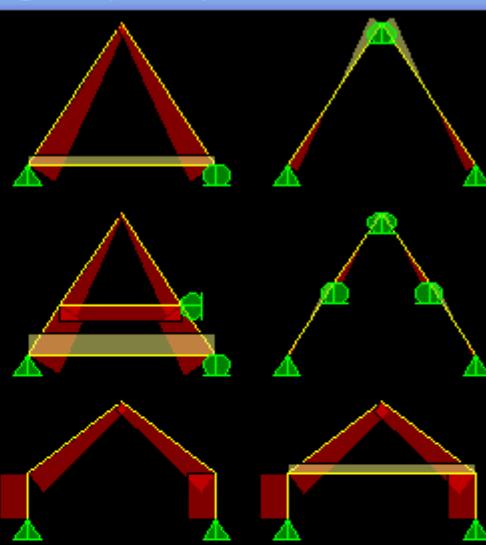
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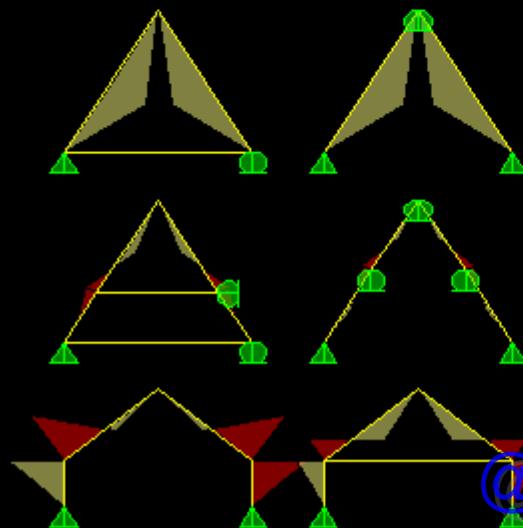
Frame Span Loads (DL) (As Defined)



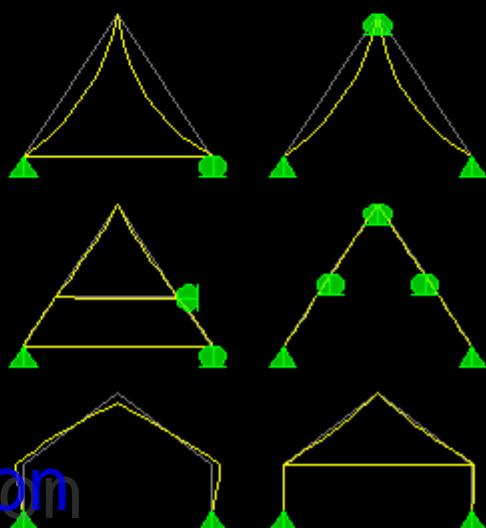
Axial Force Diagram (COMB1)



Moment 3-3 Diagram (COMB1)



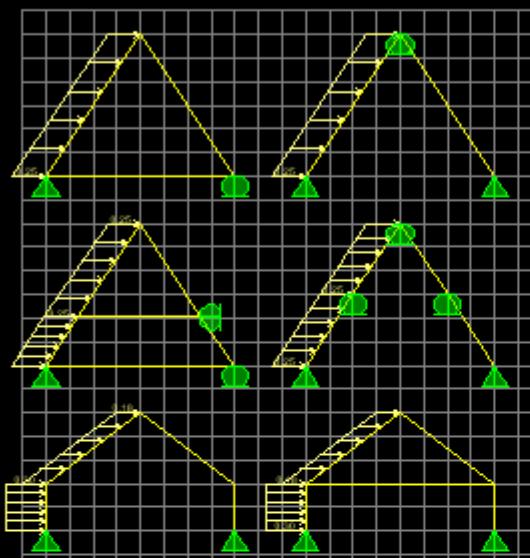
Deformed Shape (COMB1)



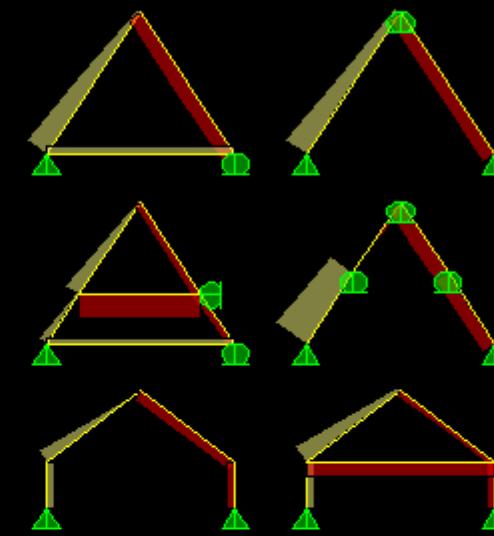
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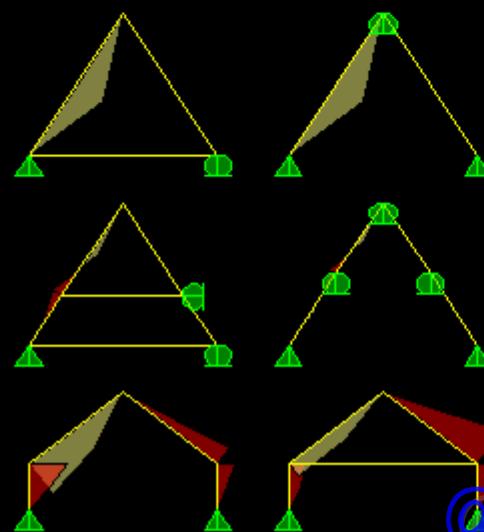
Frame Span Loads (W) (As Defined)



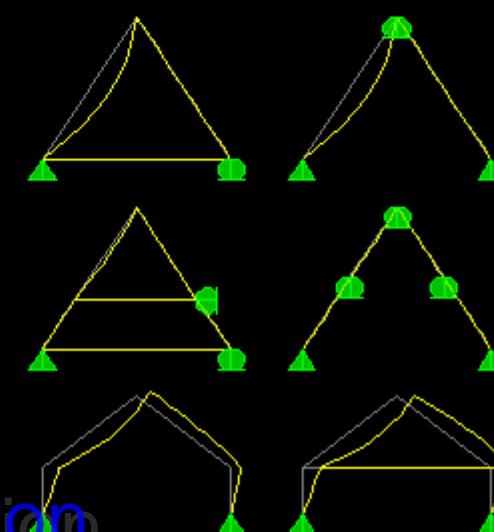
Axial Force Diagram (W)



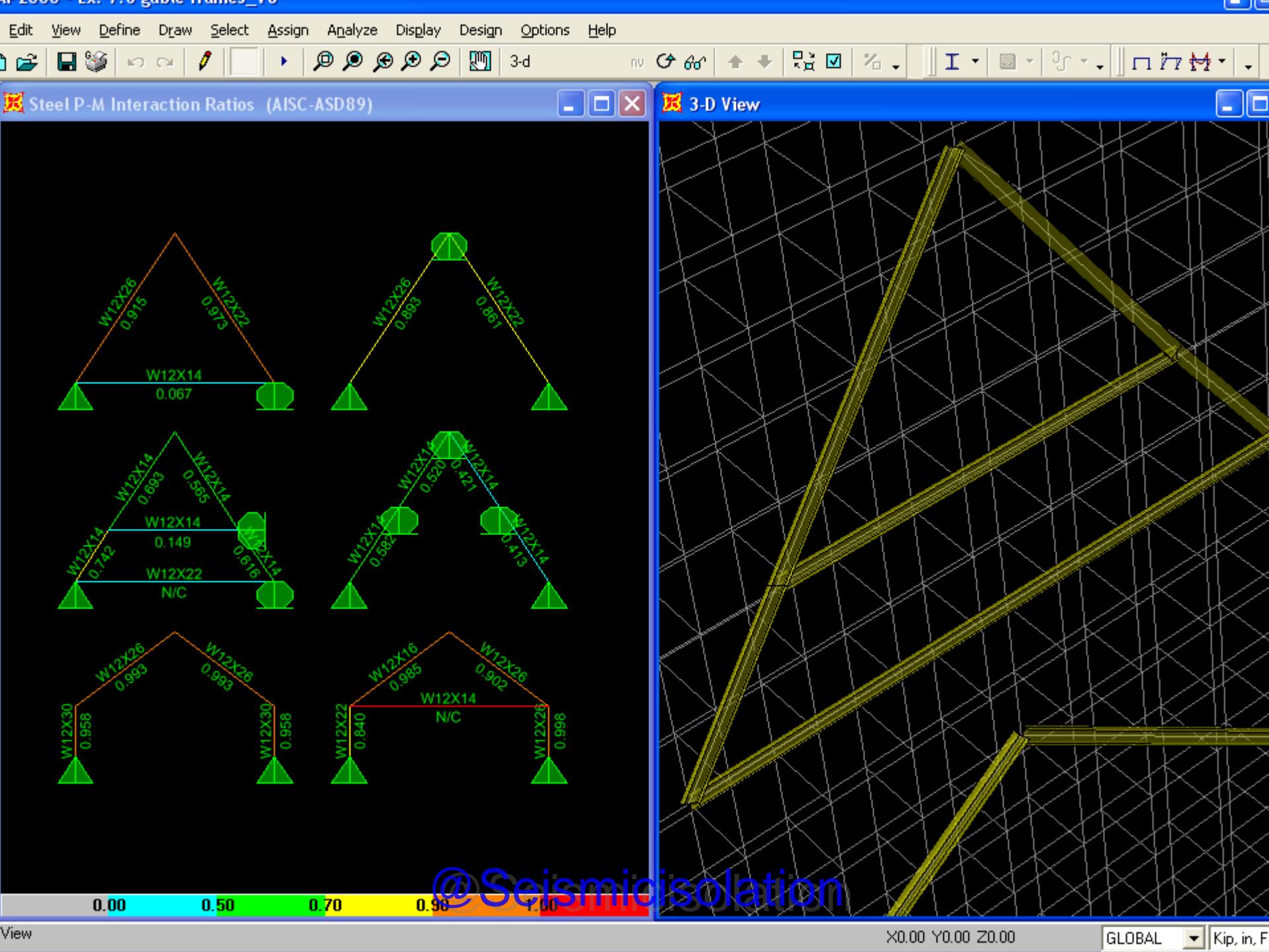
Moment 3-3 Diagram (W)



Deformed Shape (W)



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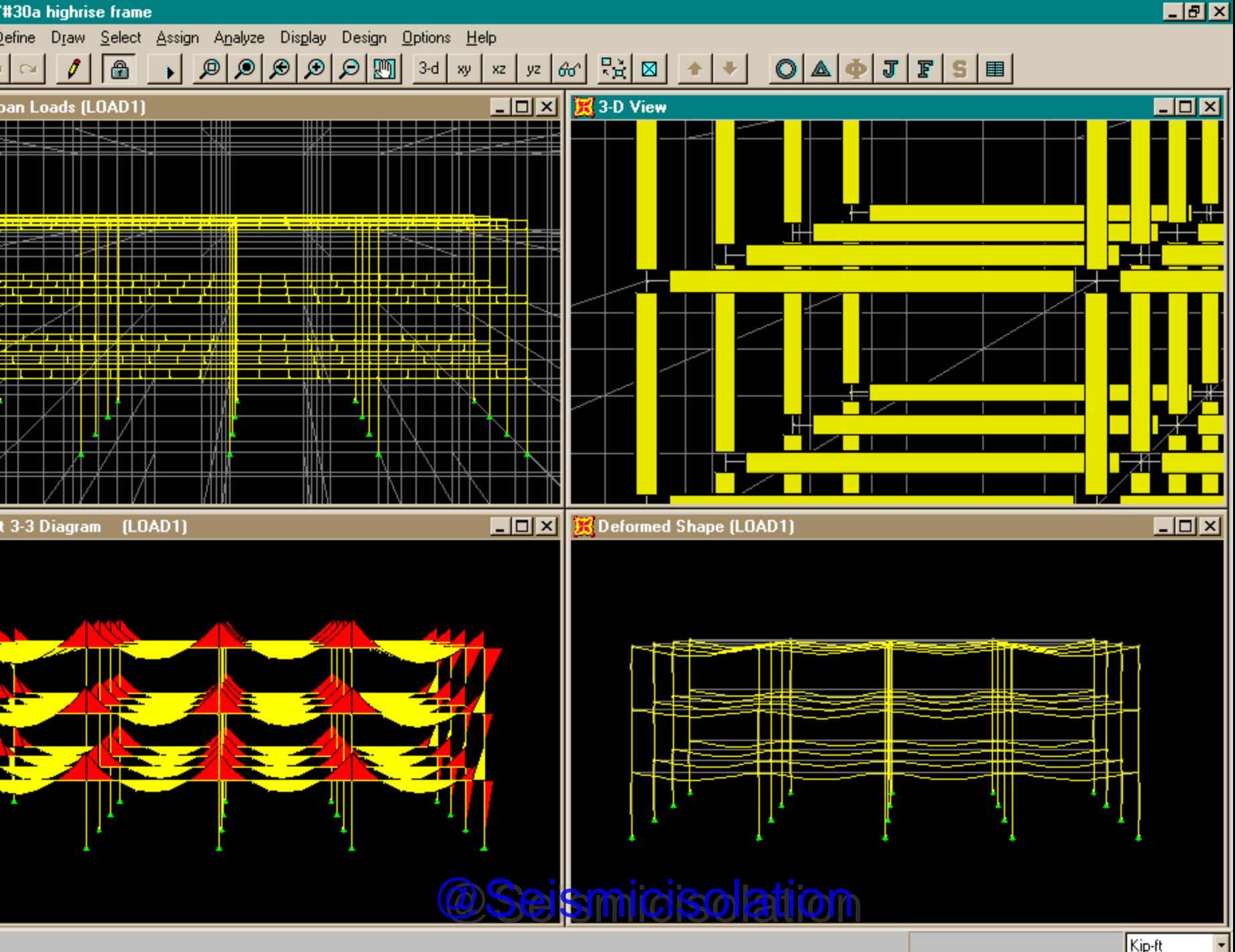




Miyagi Stadium, Sendai City, Japan, 2000, Atelier Hitoshi Abe
@Seismicisolation



@Seismicisolation
Dalian, China





SWISSBAU
1999

@Seismicisolation



Xiangguo Si temple
complex, Kaifeng

@Seismicisolation



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Da Qingzhen Si (Great Mosque) originally built in 742 and then rebuilt in the Qing dynasty, Xi'an



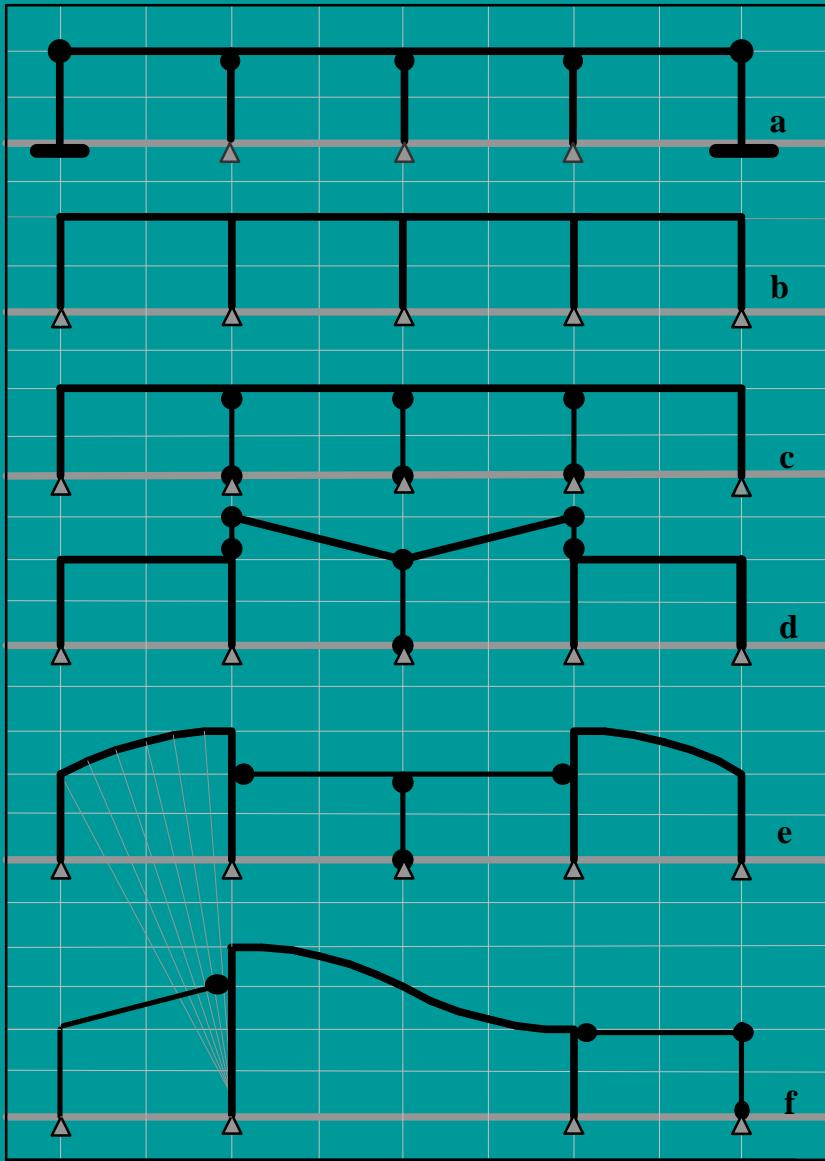
Factory 798 , art district, [@Seismicisolation](#) area, previously factory buildings built by East German architects in the 1950's



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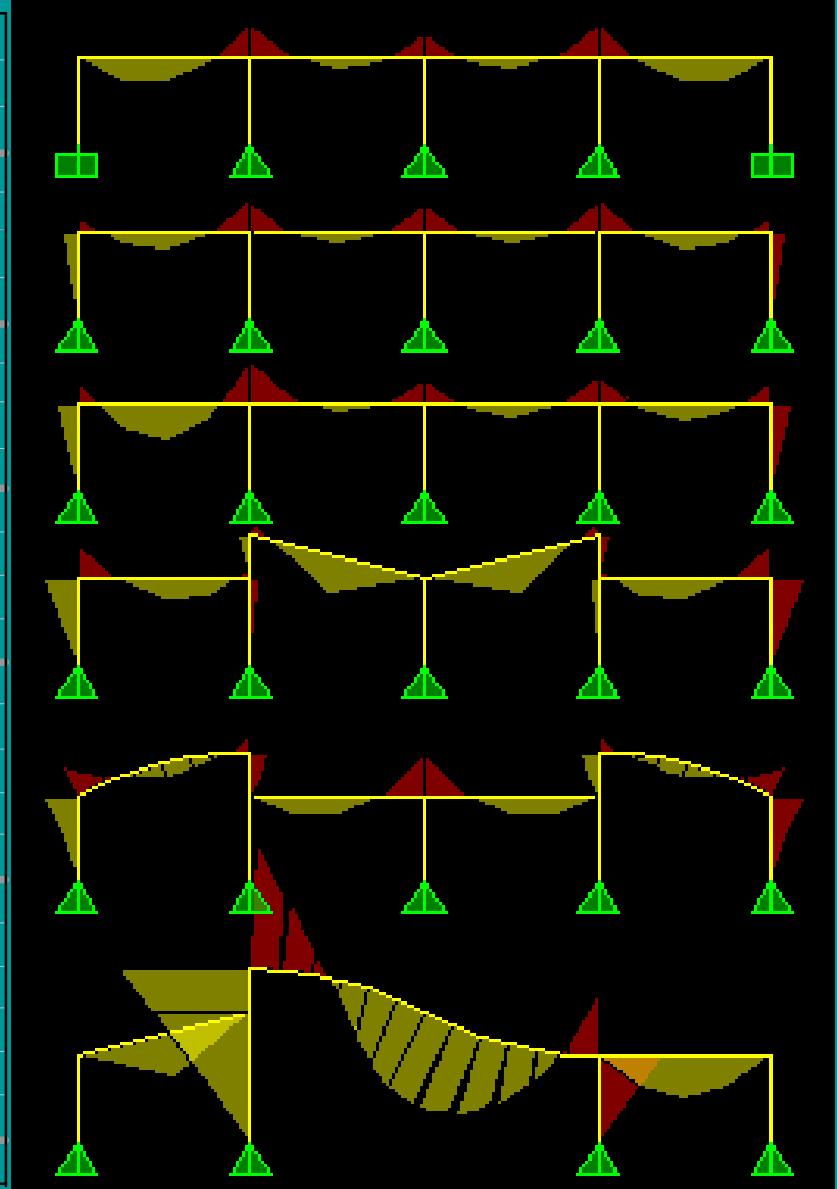
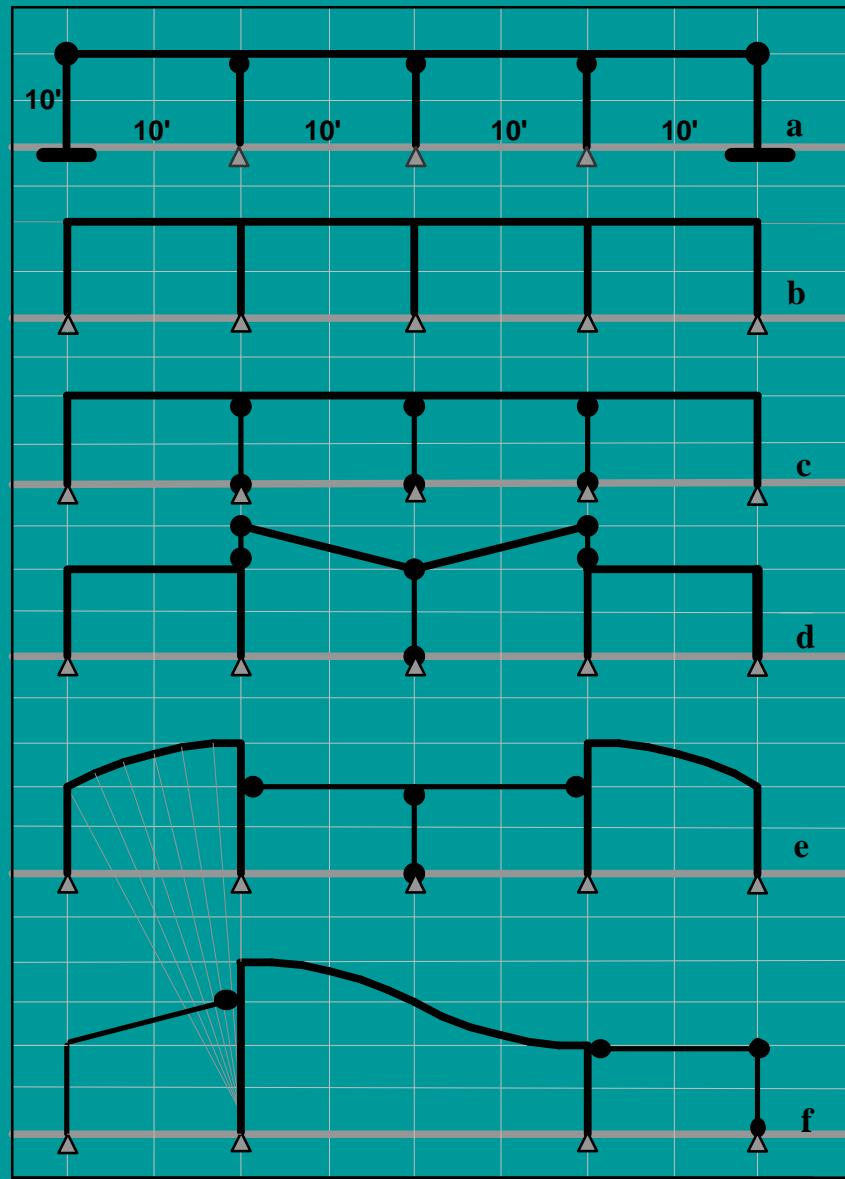


Multi-Bay, Single-Story Frames
@Seismicisolation

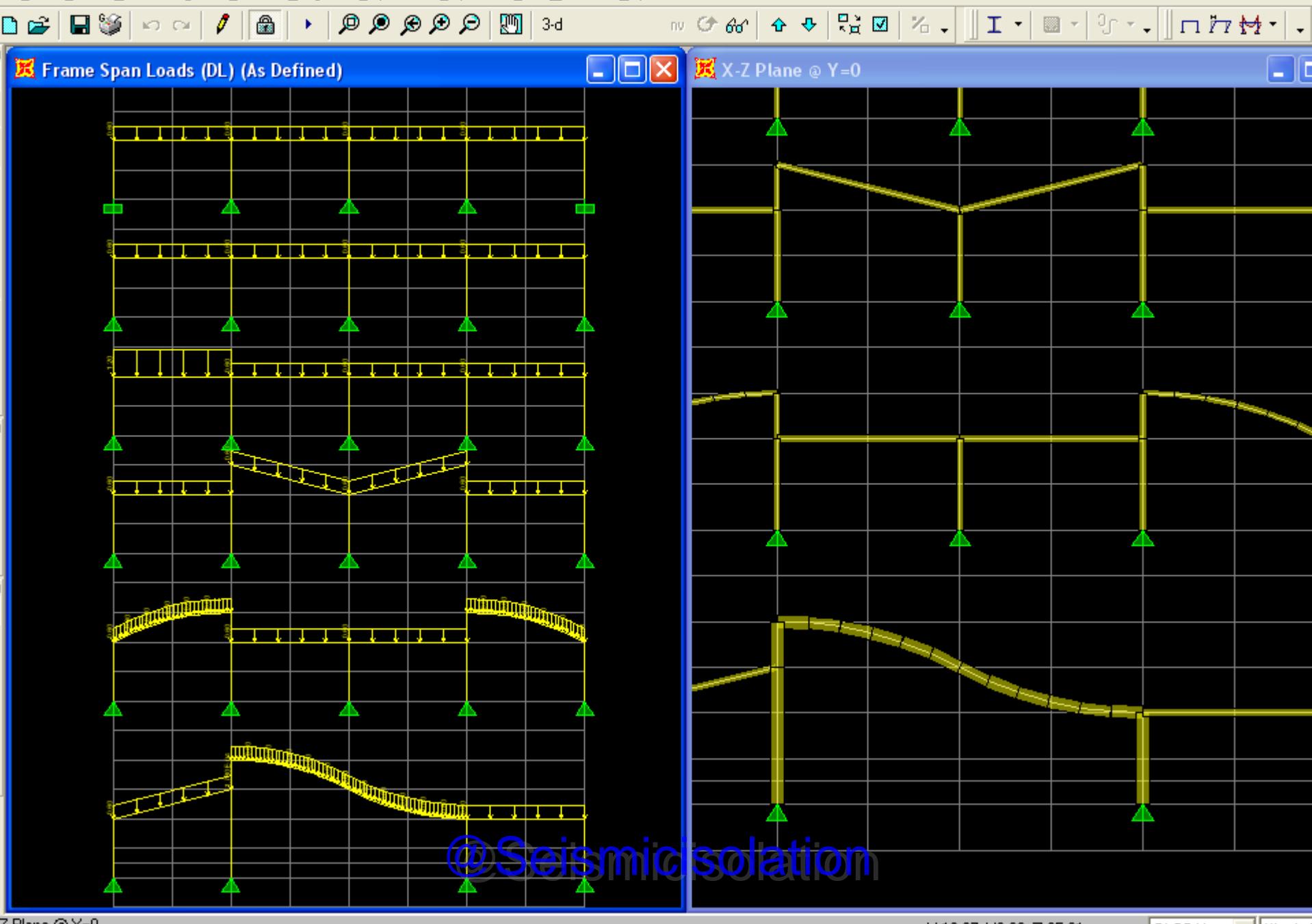
post-beam structure

rigid frames

combinations of the above



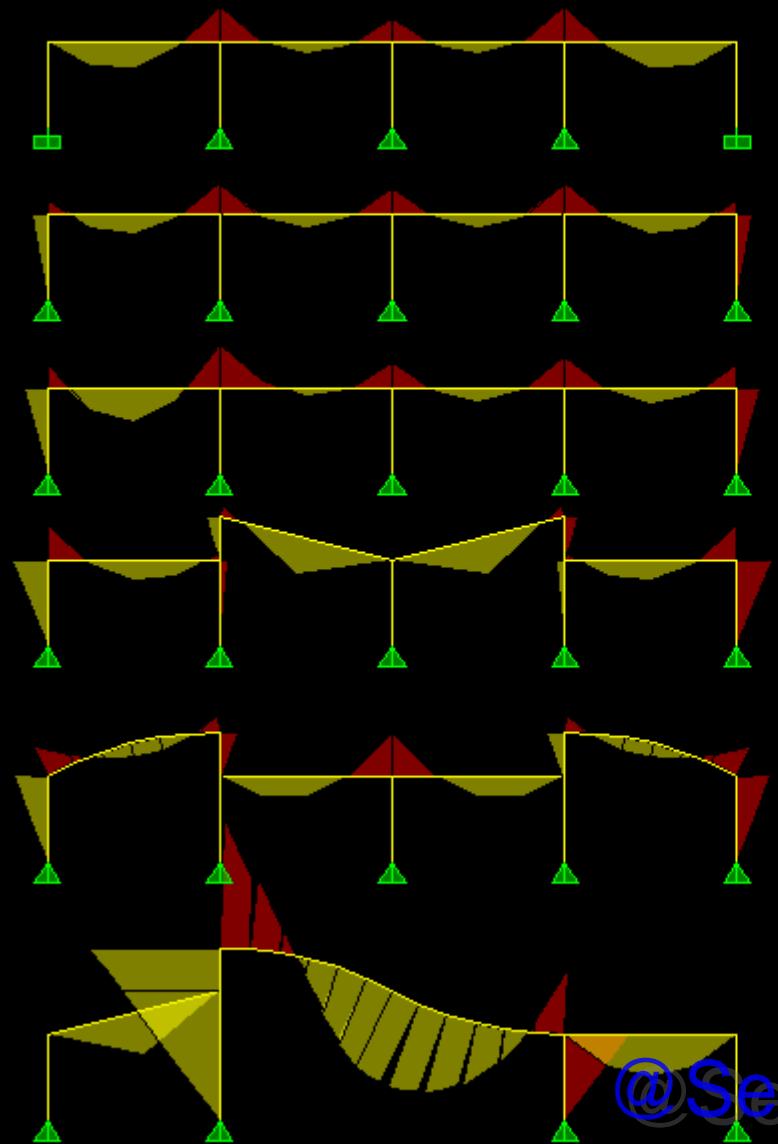
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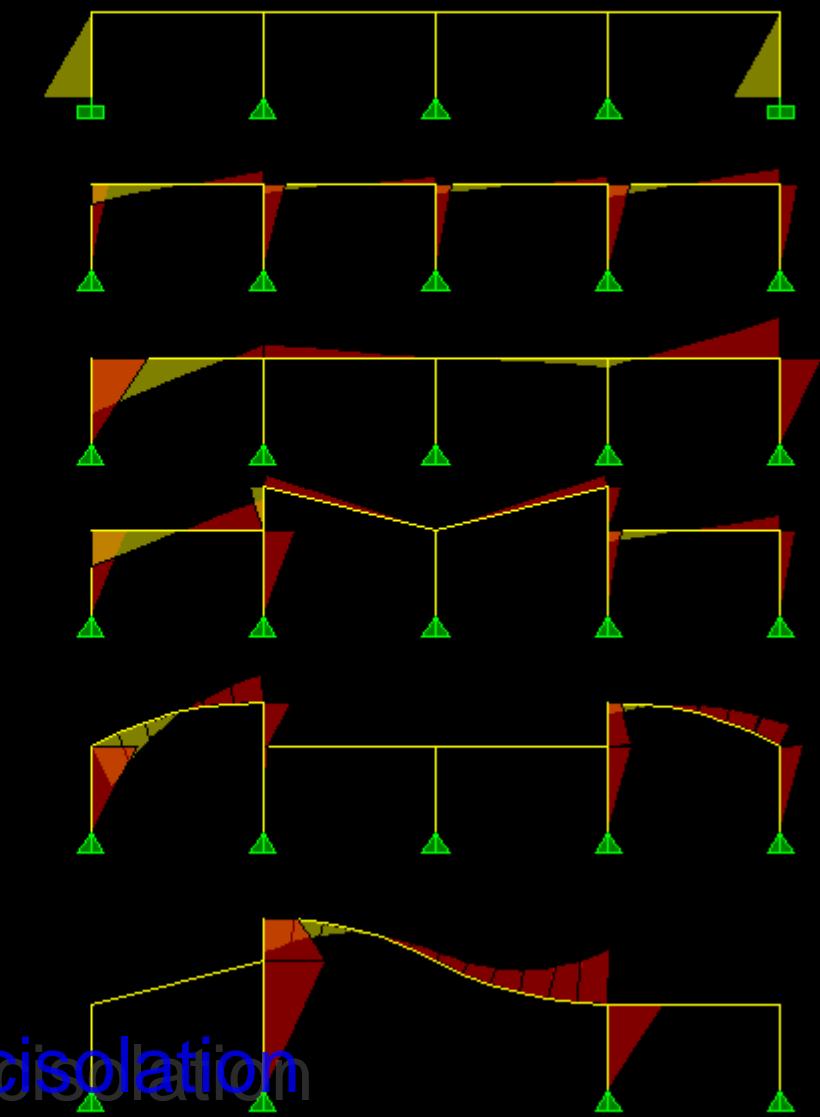
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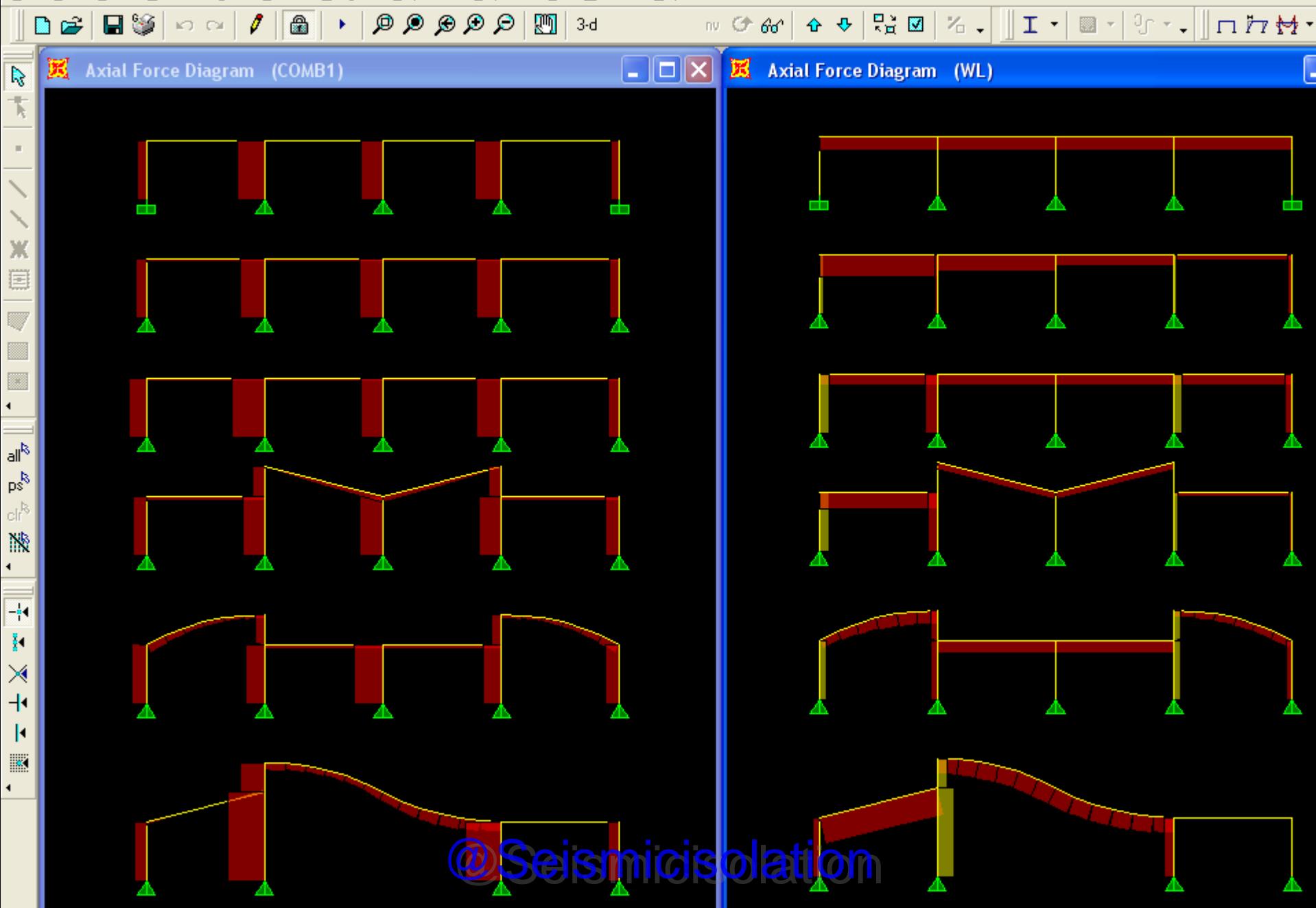
Moment 3-3 Diagram (COMB1)



Moment 3-3 Diagram (WL)

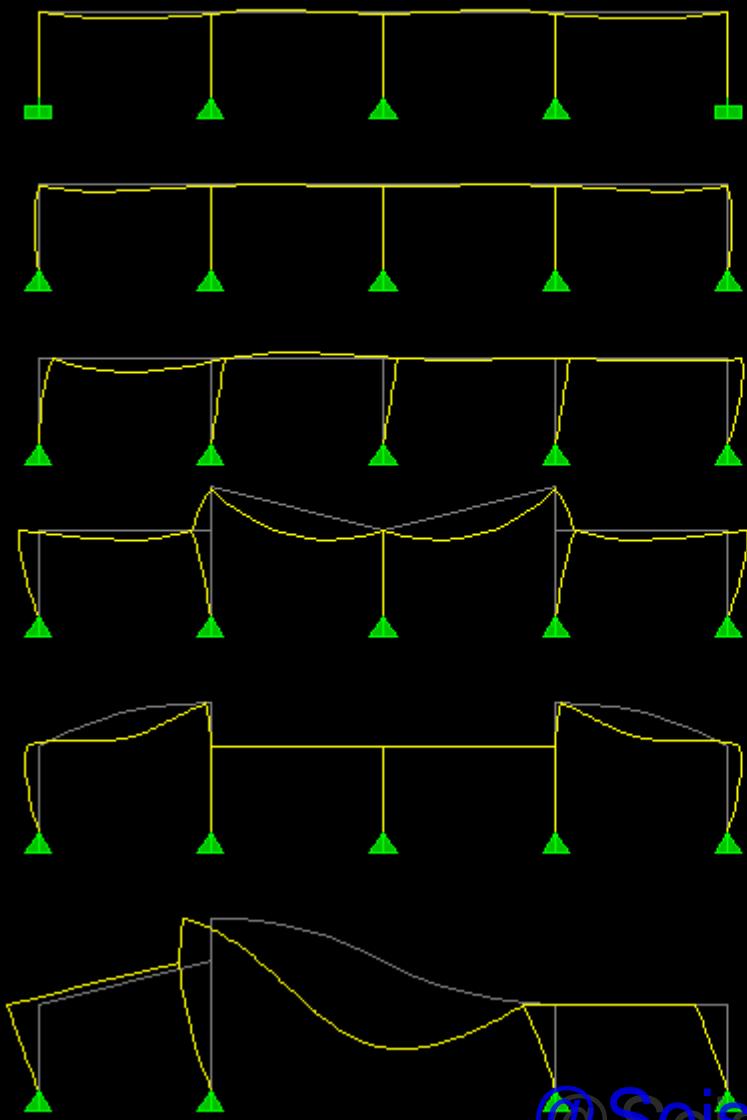


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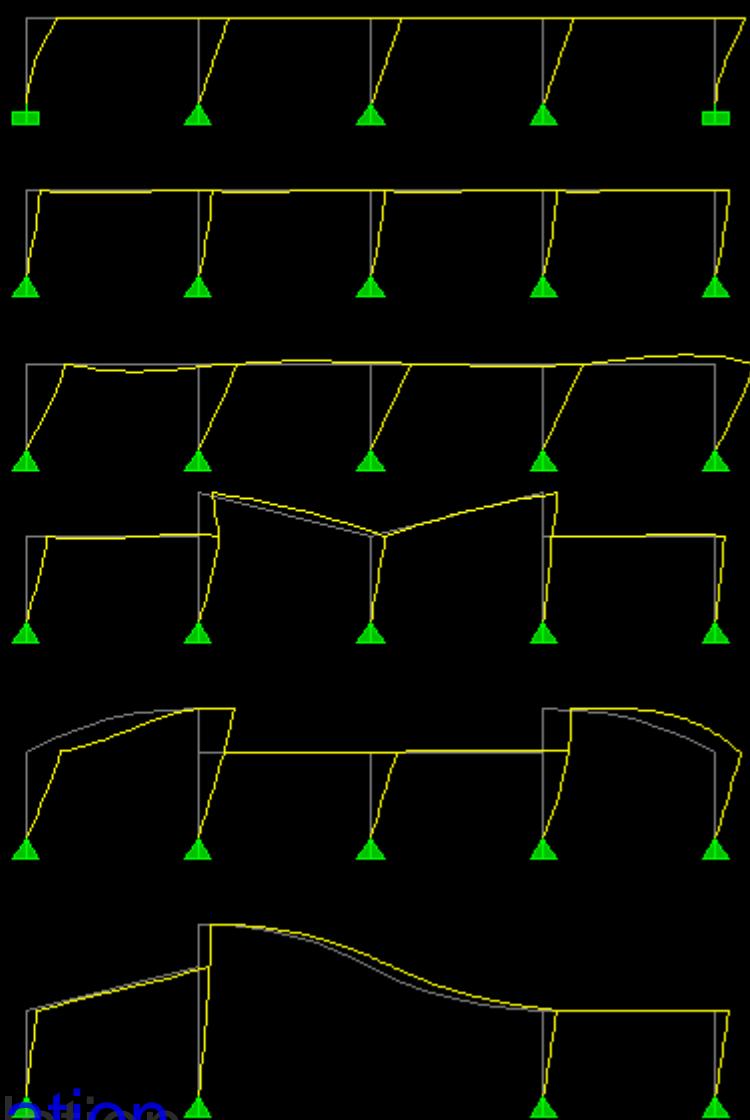




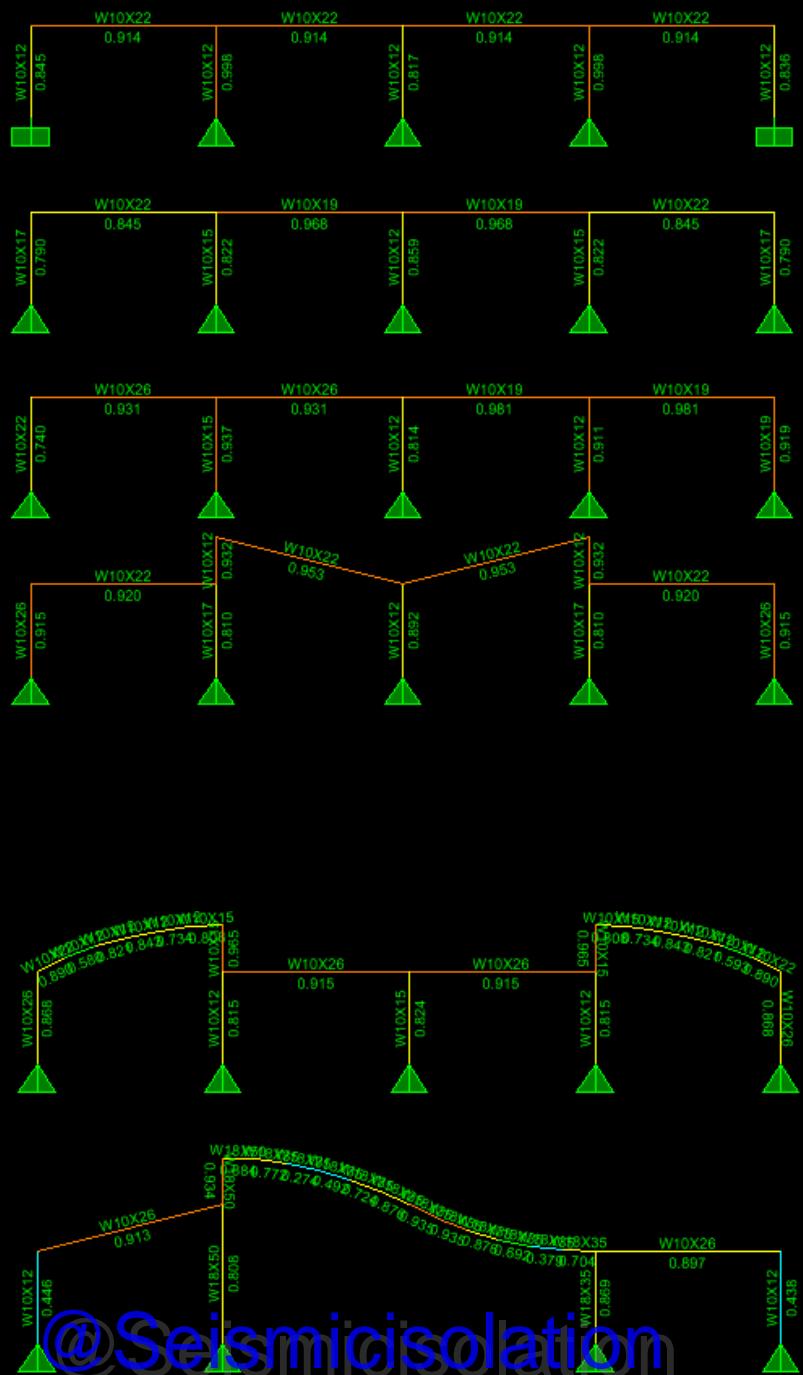
Deformed Shape (COMB1)



Deformed Shape (WL)



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European Court of Justice, Luxemburg, 2008, *Dominique Perrault*

@Seismicisolation



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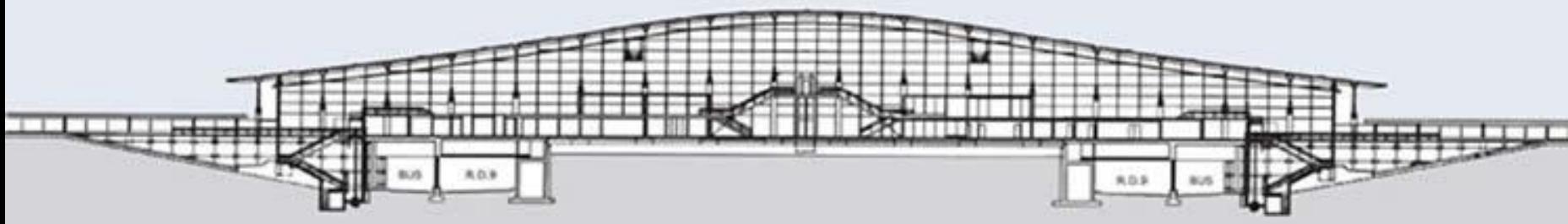
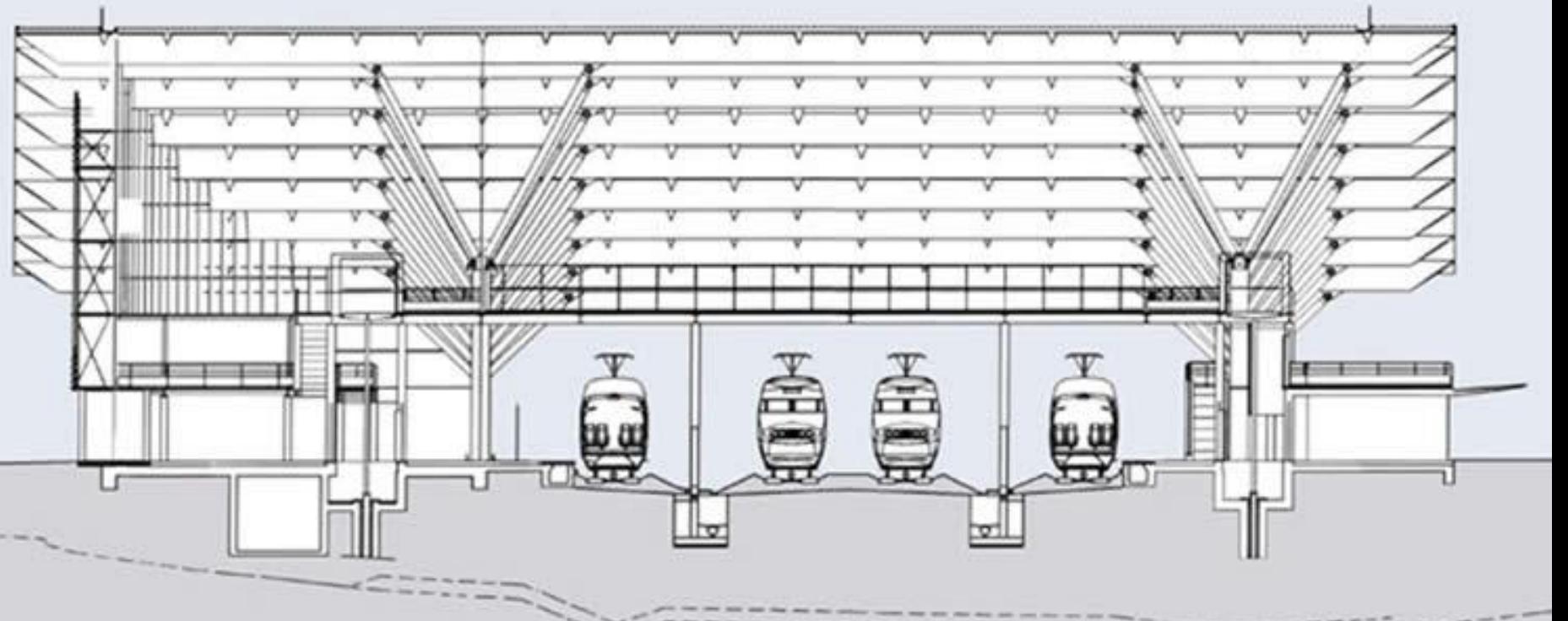
European Court of Justice,
Luxemburg, 1994, Atelier
d'Architecture Paczowski
Fritsch & Associés



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Gare TGV, Aix en Provence, France, 2001, Jean-Marie Dutilleul

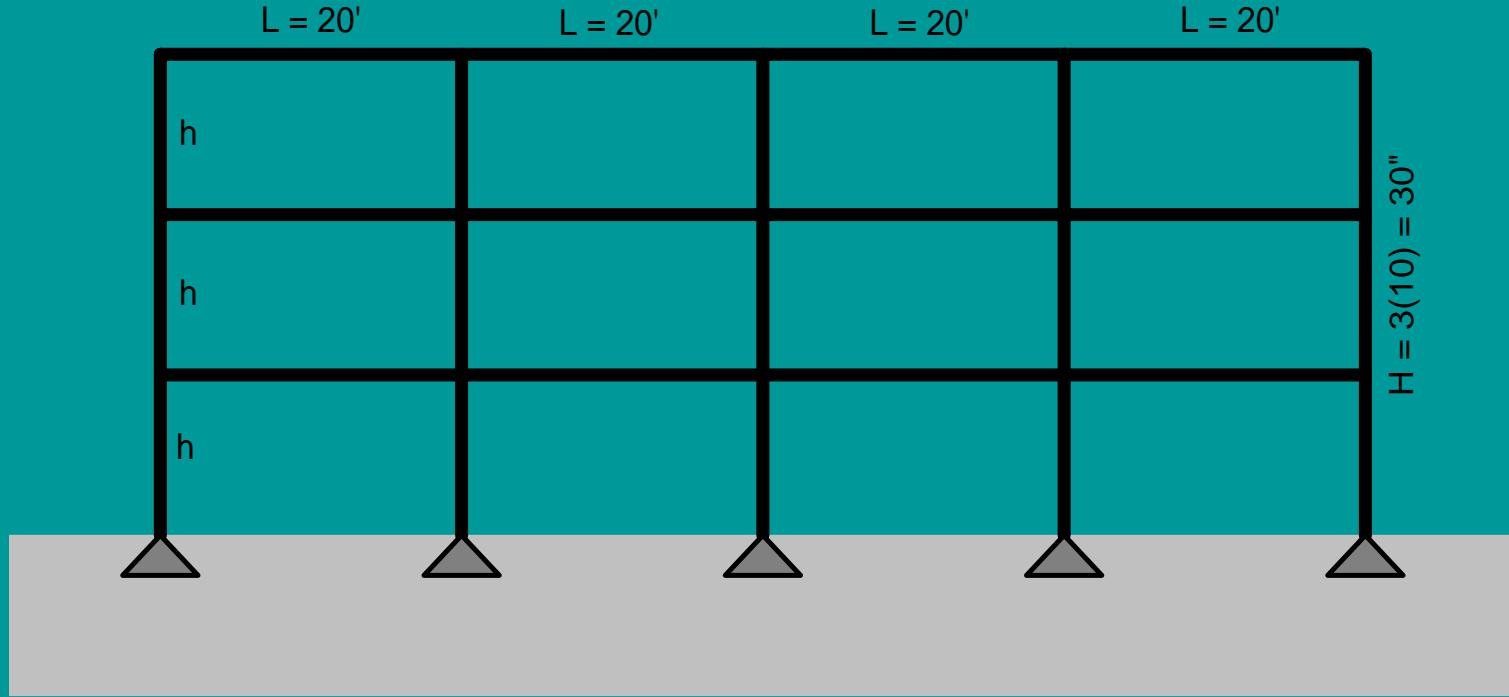




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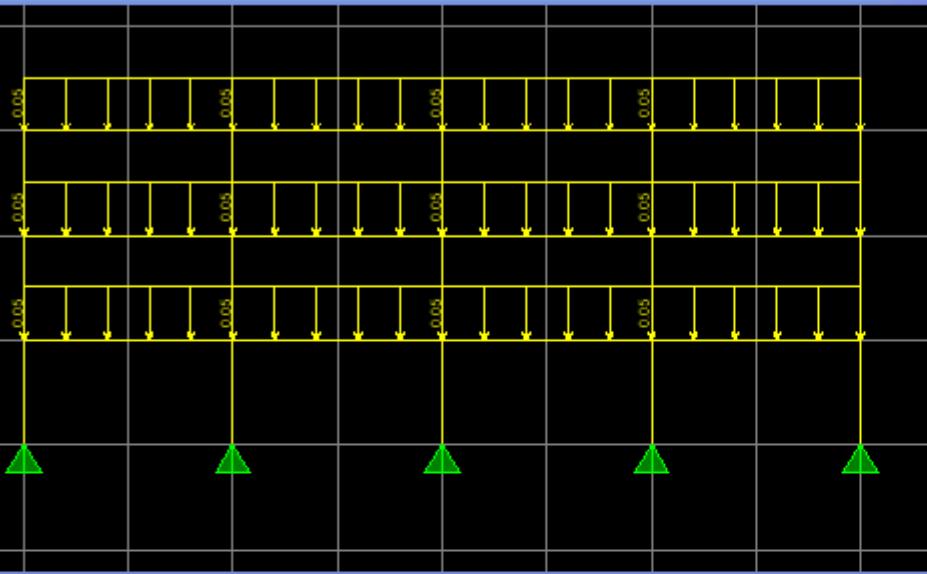


LOW-RISE, MULTI-STORY, MULTI-BAY RIGID FRAME

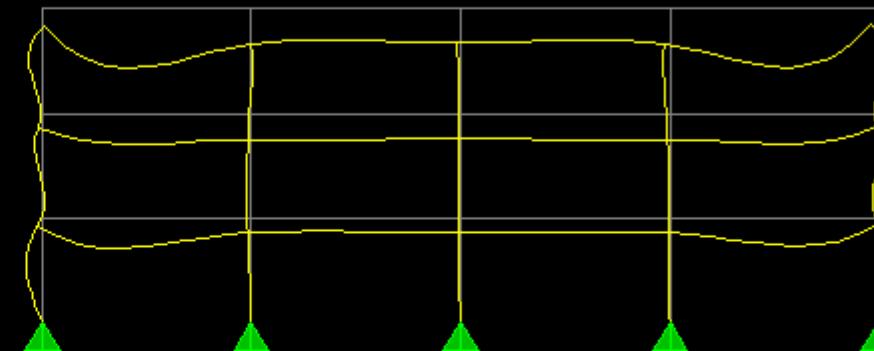
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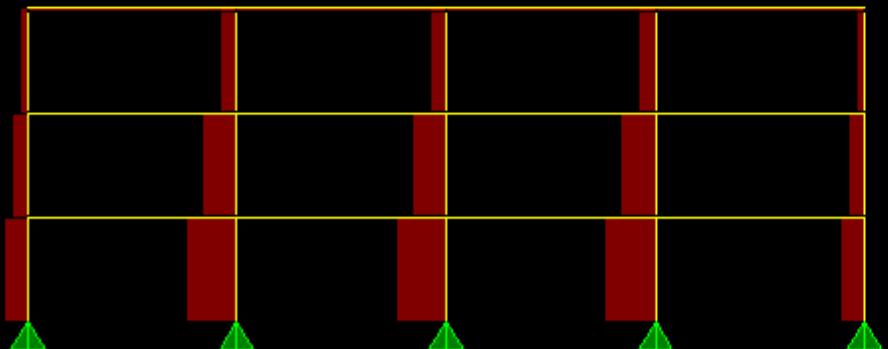
Frame Span Loads (D) (As Defined)



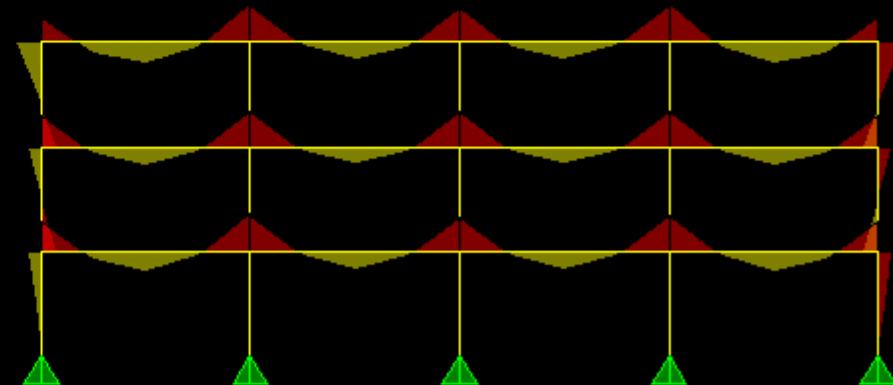
Deformed Shape (COMB1)



Axial Force Diagram (COMB1)



Moment 3-3 Diagram (COMB1)



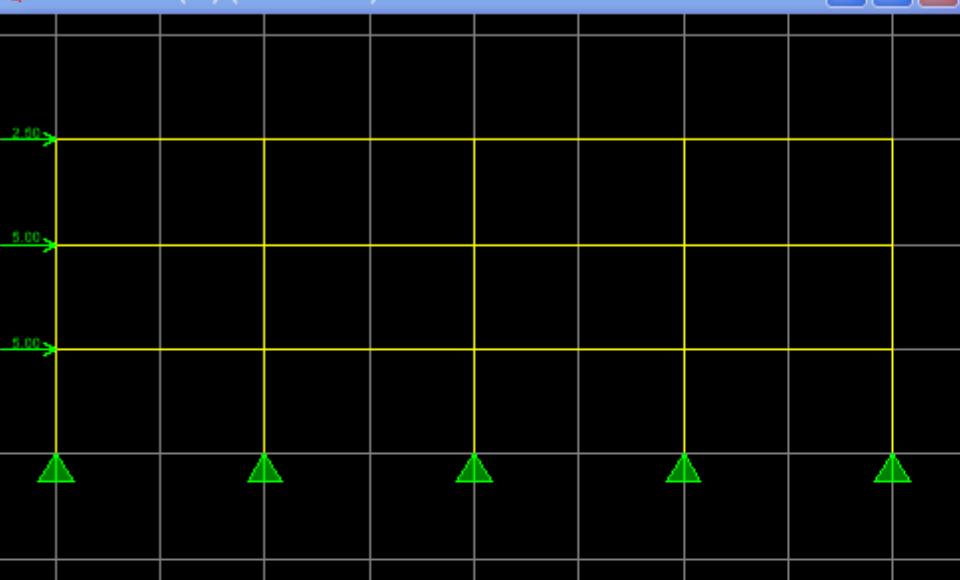
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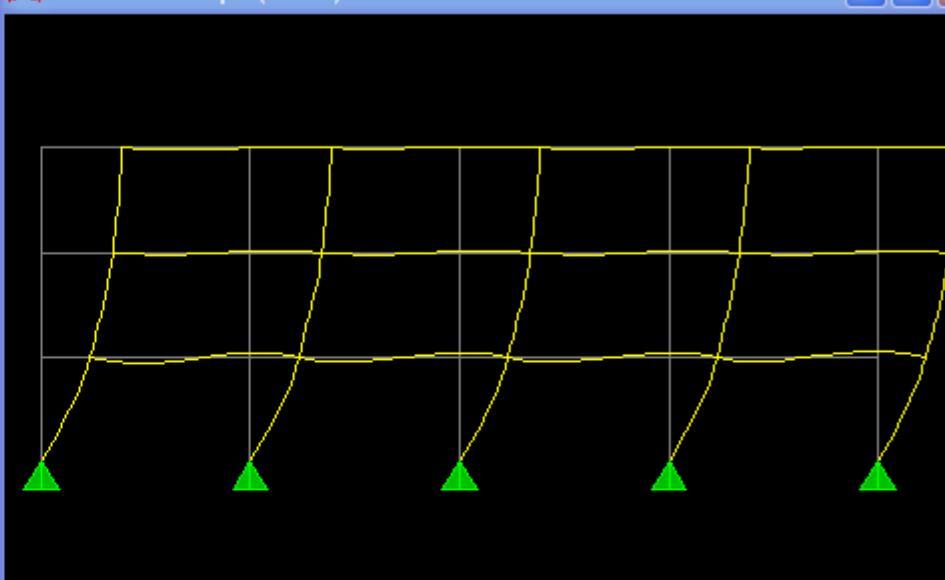
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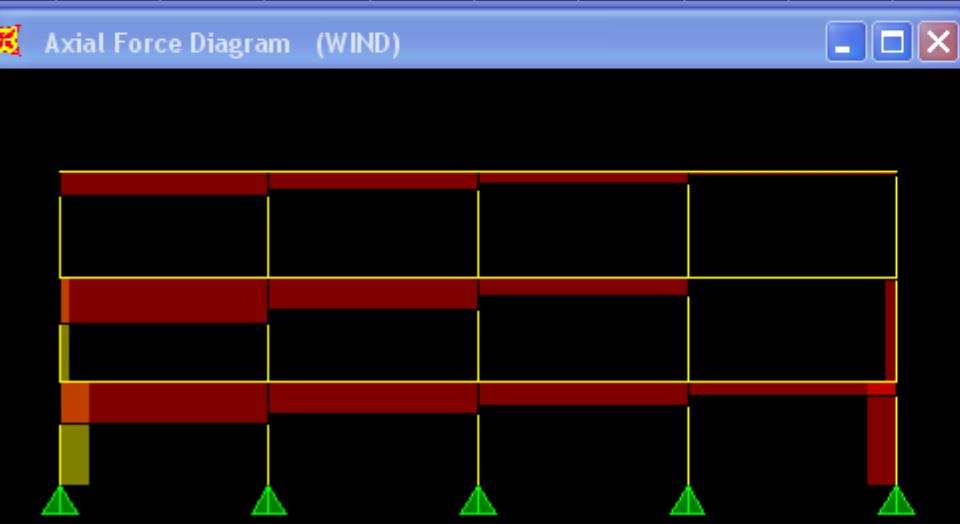
Joint Loads (W) (As Defined)



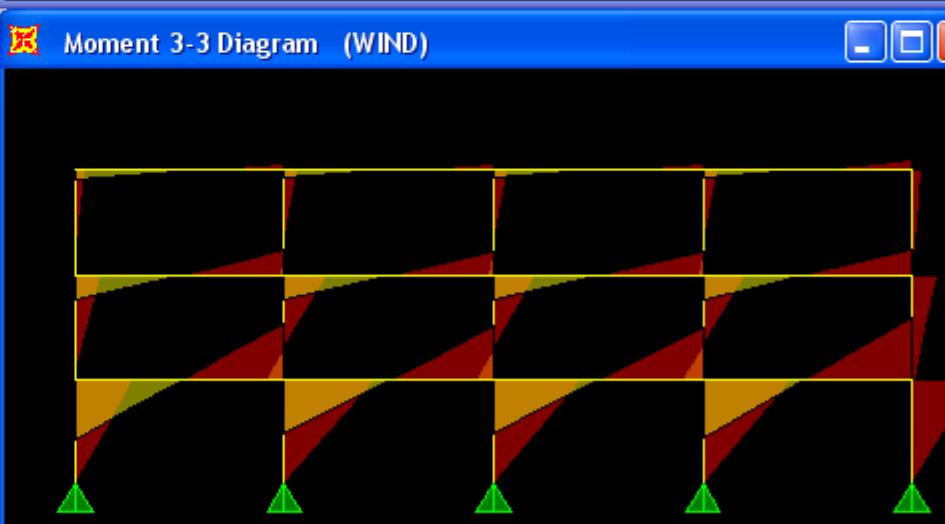
Deformed Shape (WIND)



Axial Force Diagram (WIND)



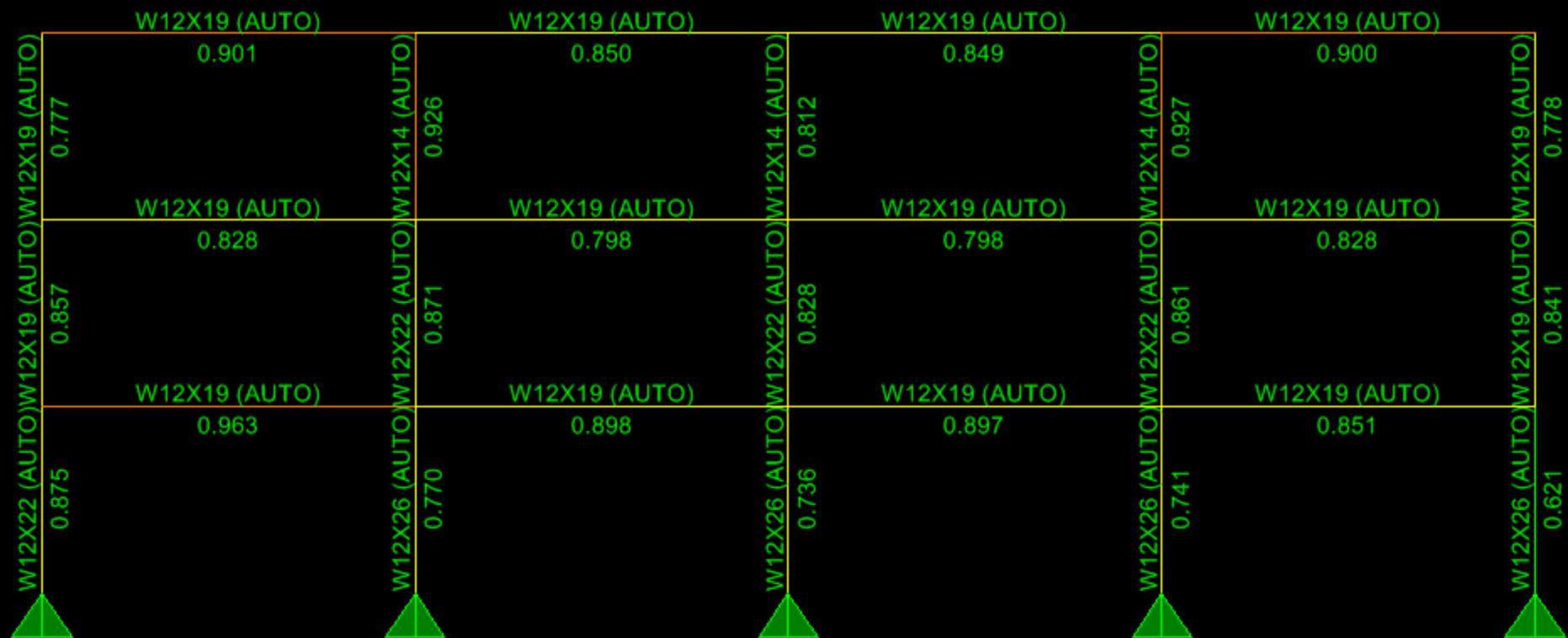
Moment 3-3 Diagram (WIND)



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Steel P-M Interaction Ratios (AISC-ASD89)



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0.00

0.50

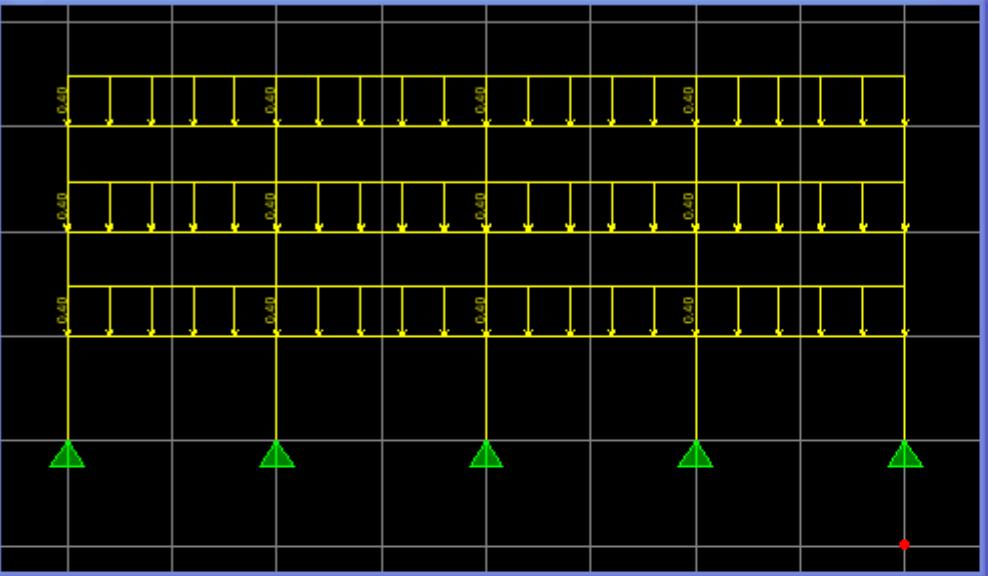
1.00

0.90

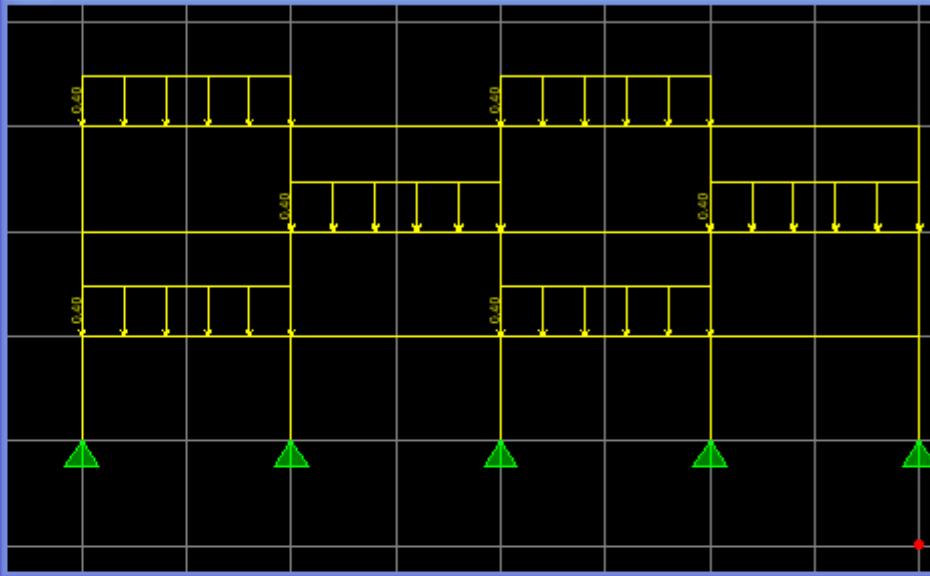
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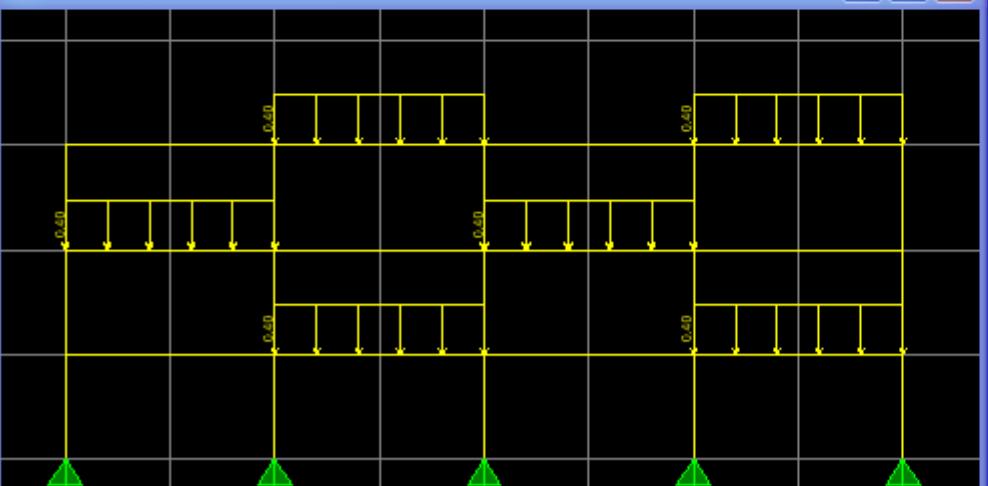
Frame Span Loads (L1) (As Defined)



Frame Span Loads (L2) (As Defined)



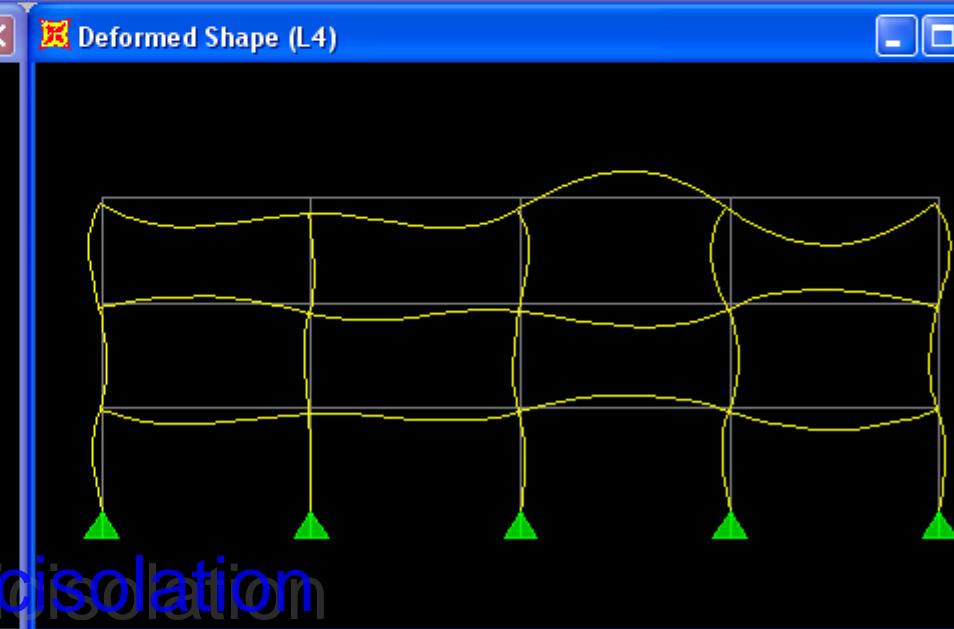
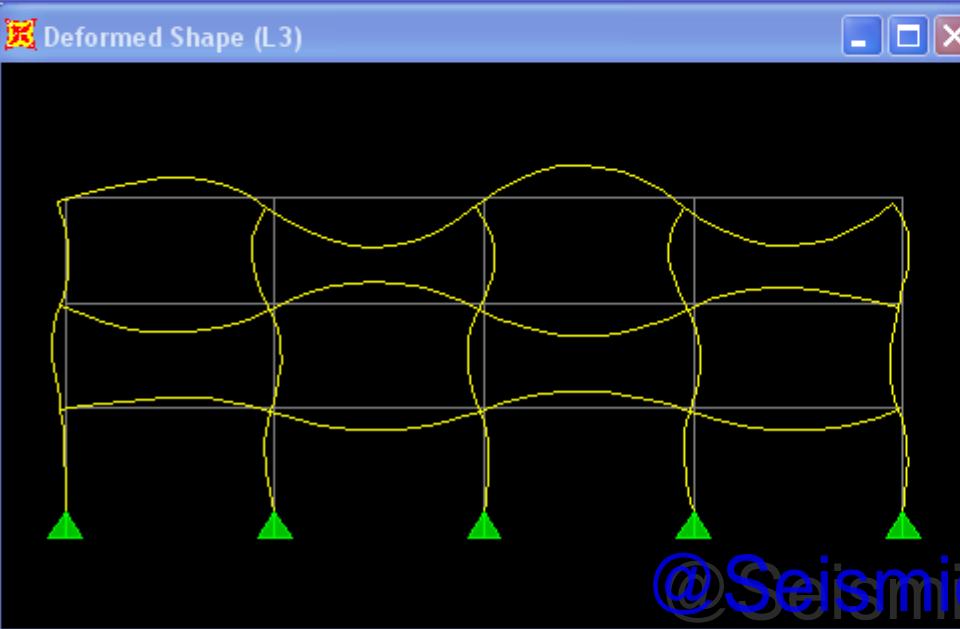
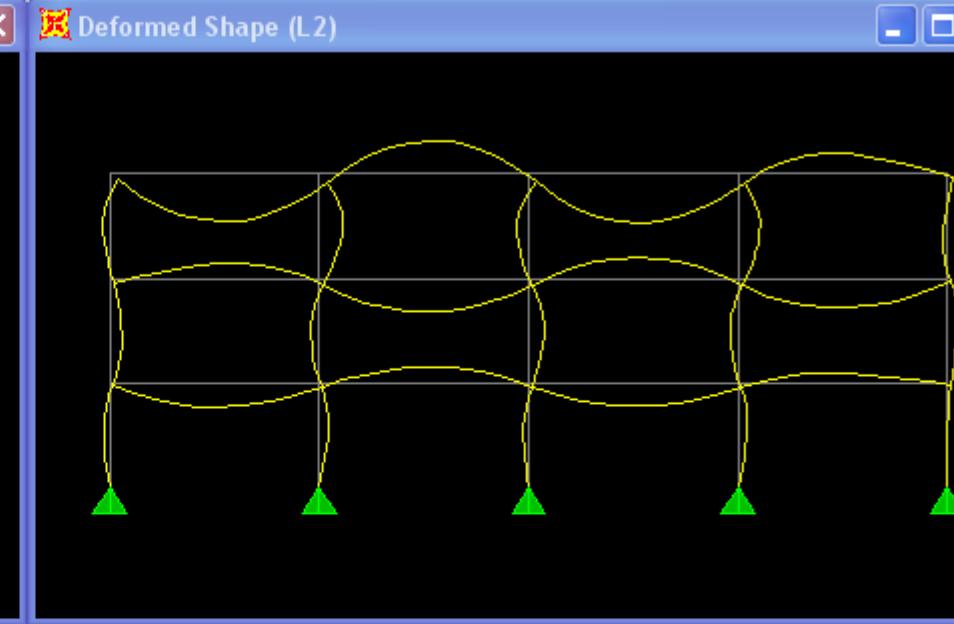
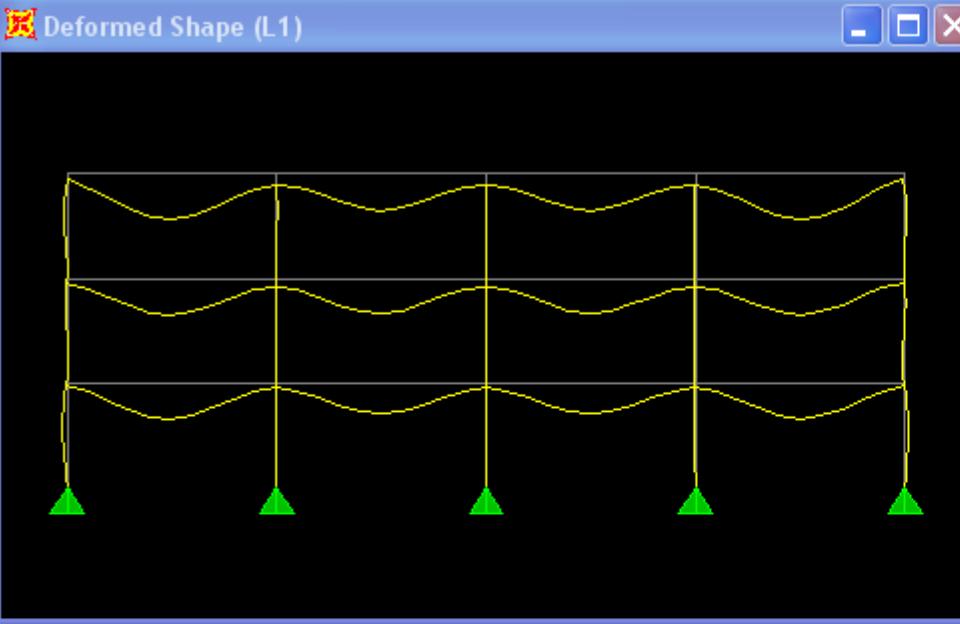
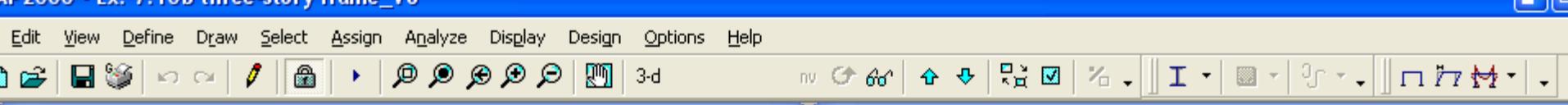
Frame Span Loads (L3) (As Defined)



Frame Span Loads (L4) (As Defined)



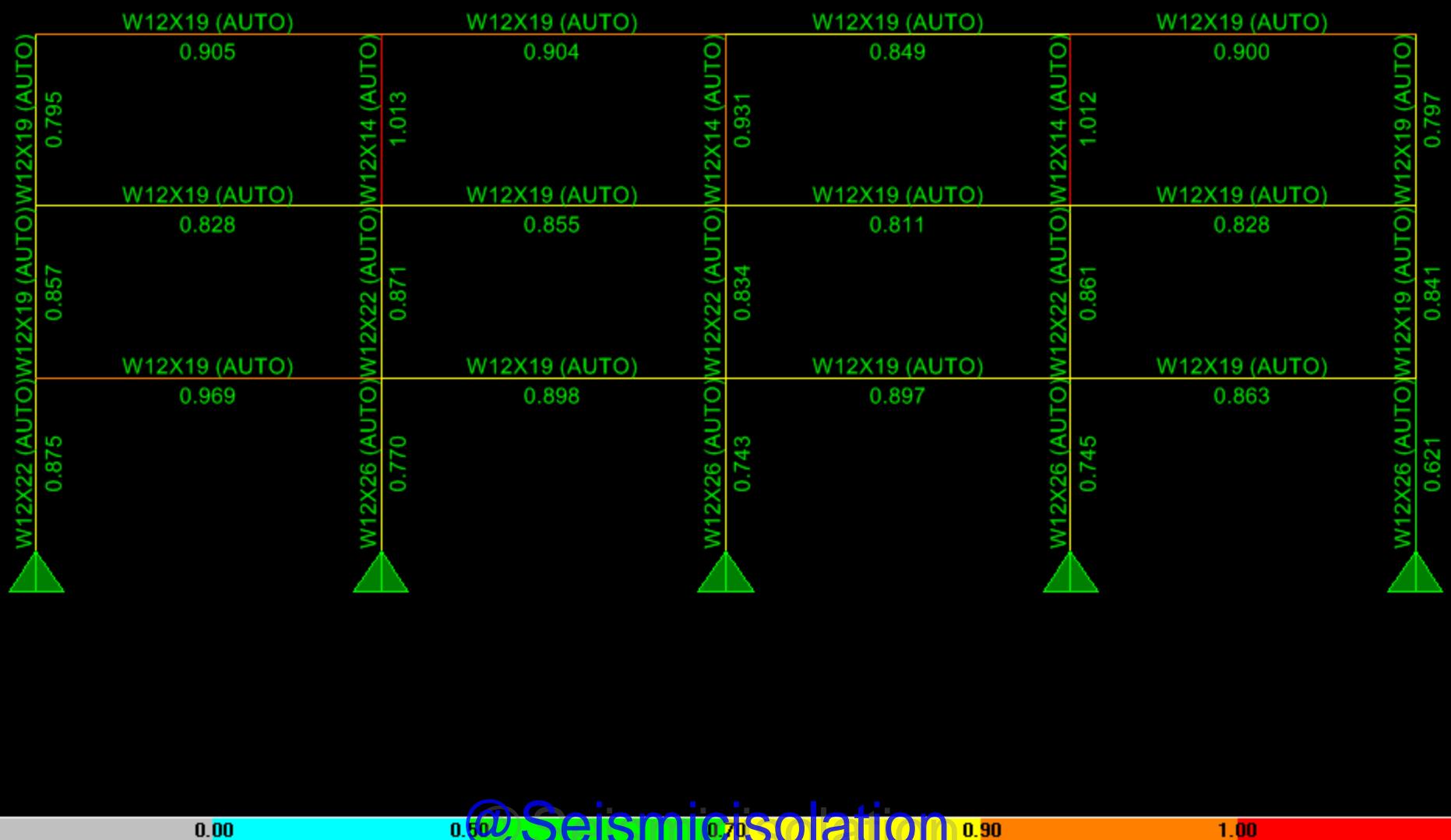
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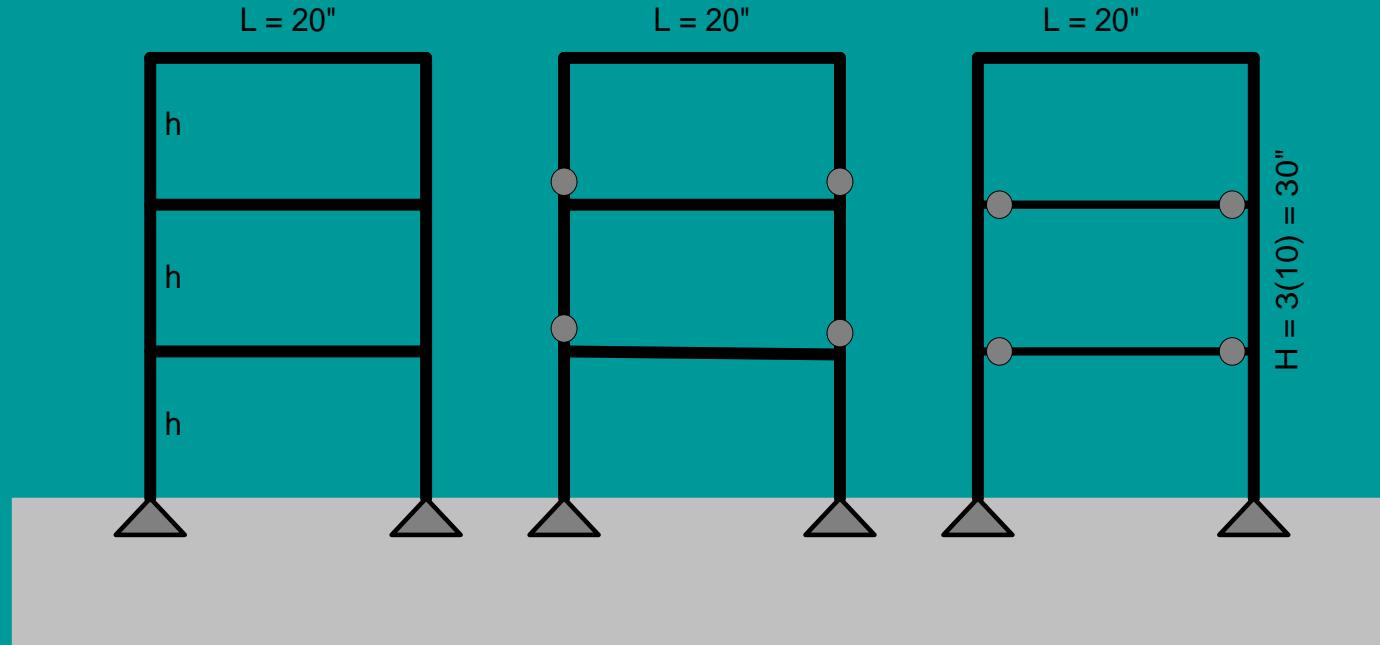
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Steel P-M Interaction Ratios (AISC-ASD89)

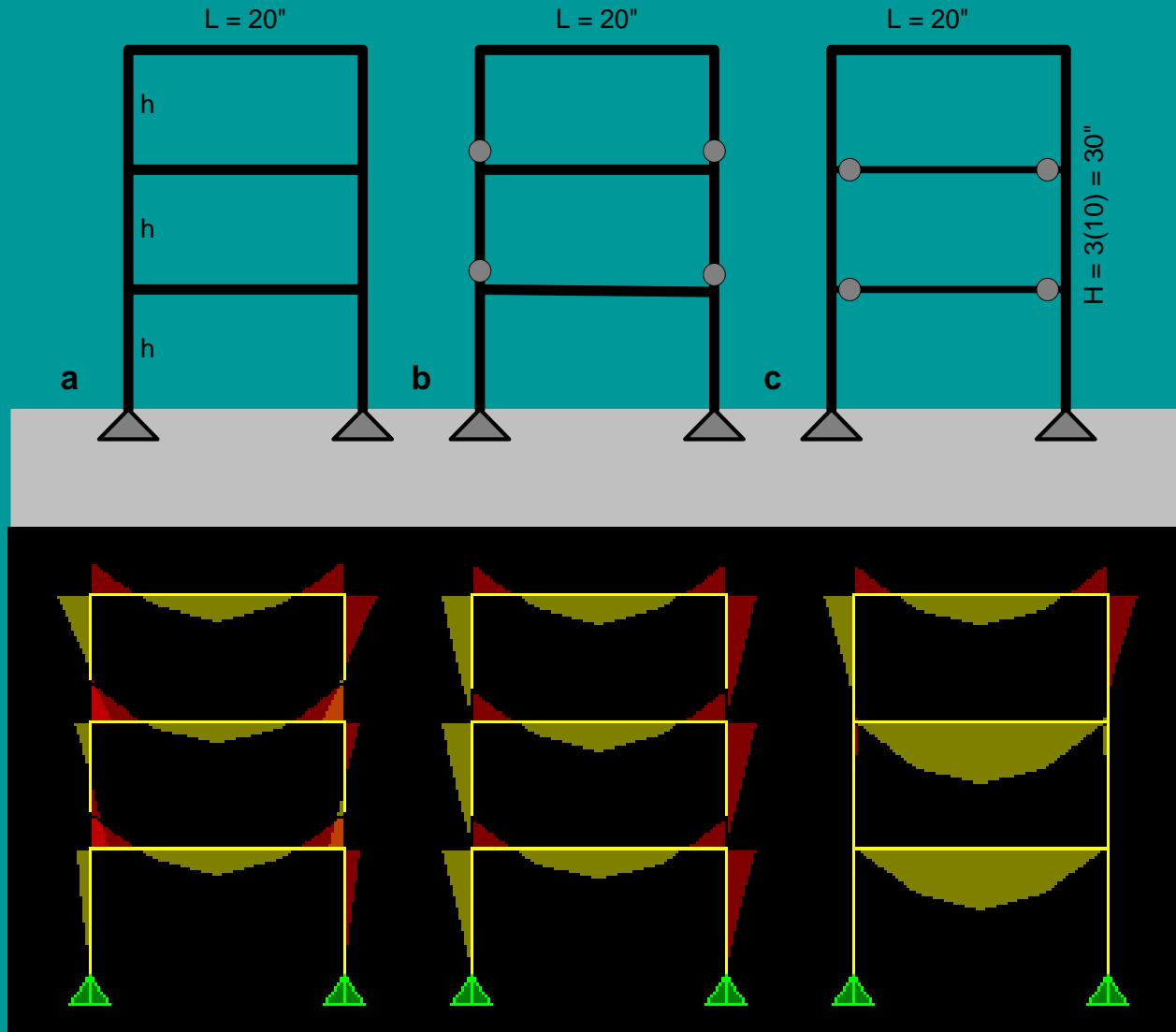


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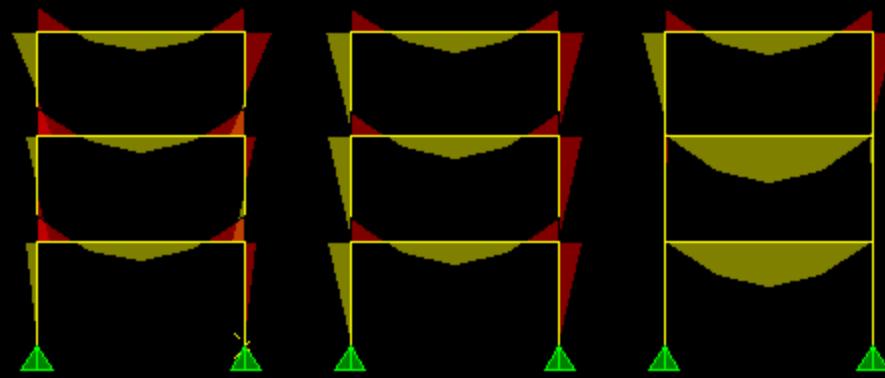


LOW-RISE, SINGLE-BAY, MULTI-STORY FRAMES

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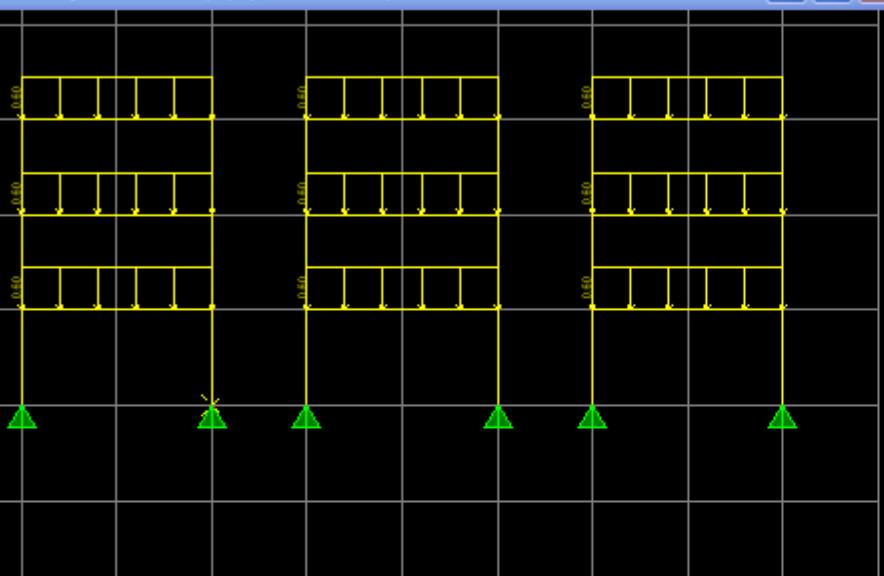
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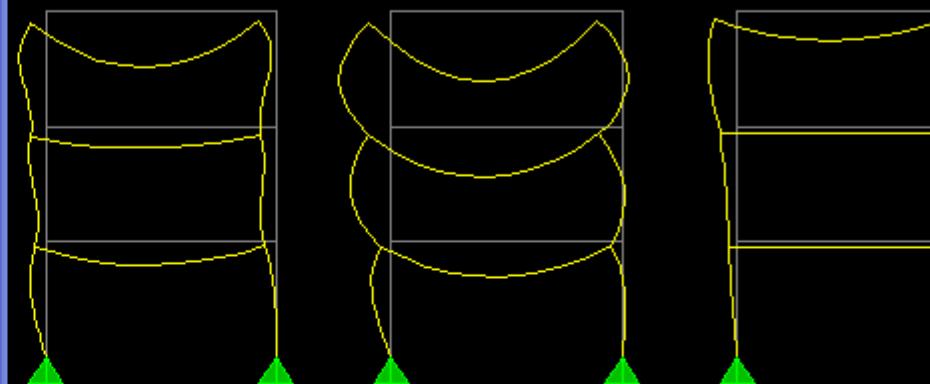
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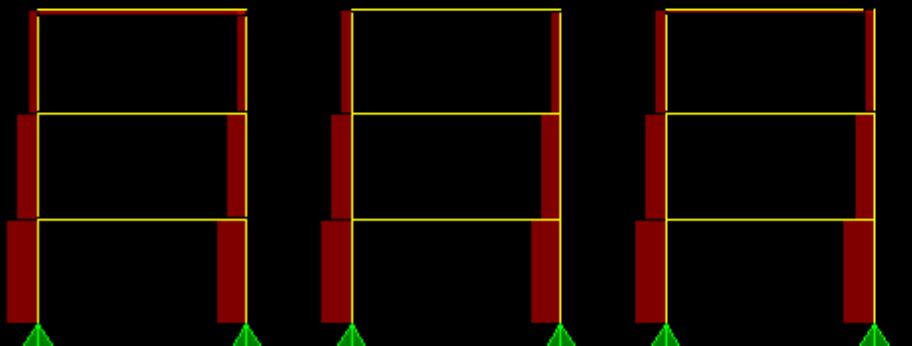
Frame Span Loads (D) (As Defined)



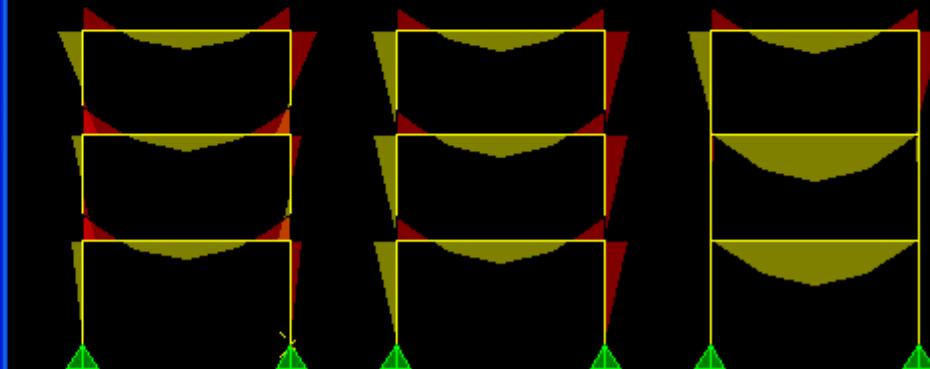
Deformed Shape (COMB1)



Axial Force Diagram (COMB1)



Moment 3-3 Diagram (COMB1)

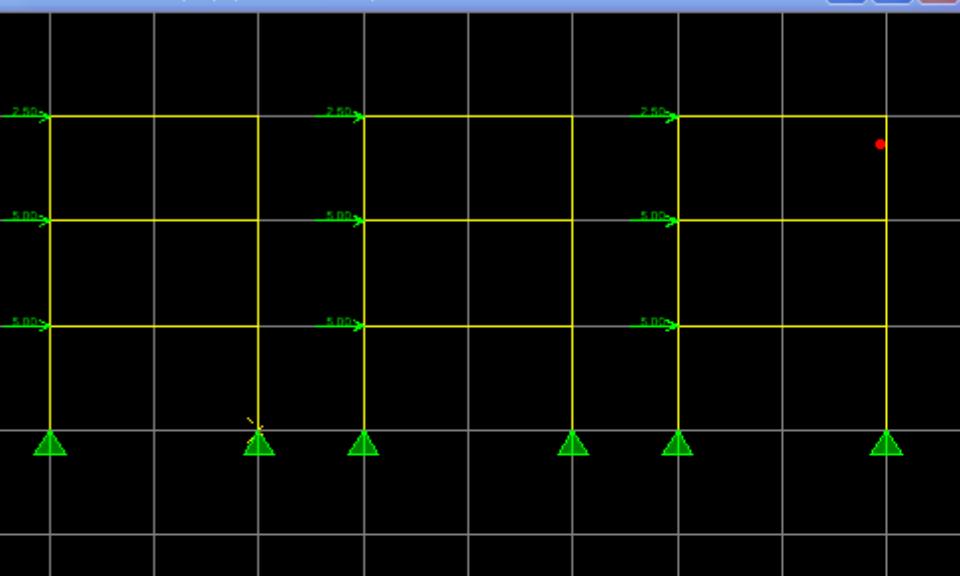


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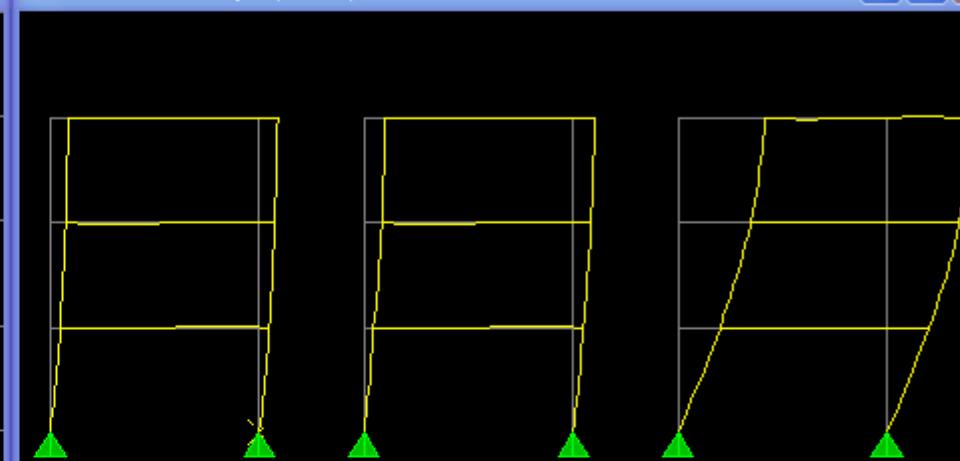
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Joint Loads (W) (As Defined)



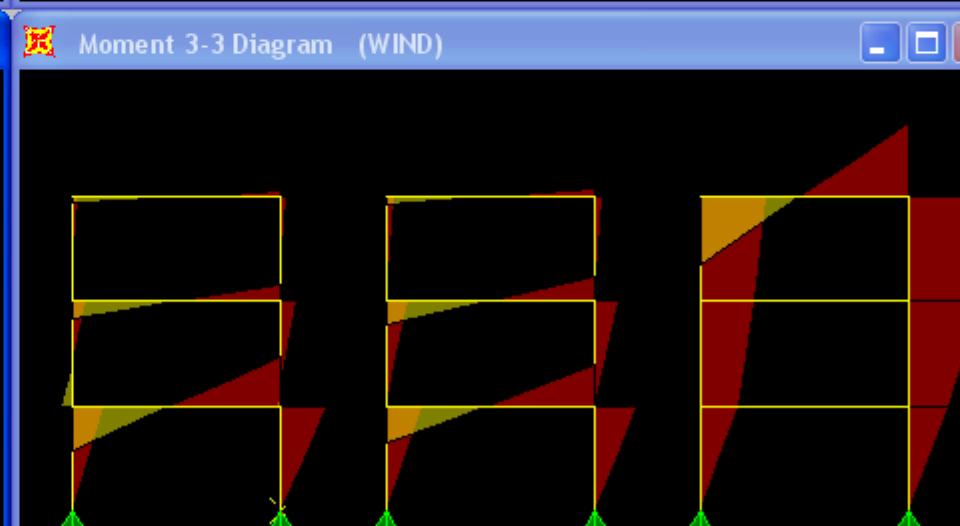
Deformed Shape (WIND)



Axial Force Diagram (WIND)



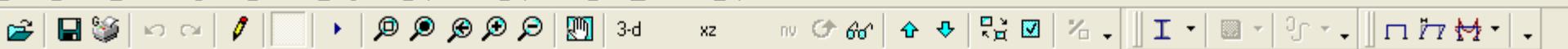
Moment 3-3 Diagram (WIND)



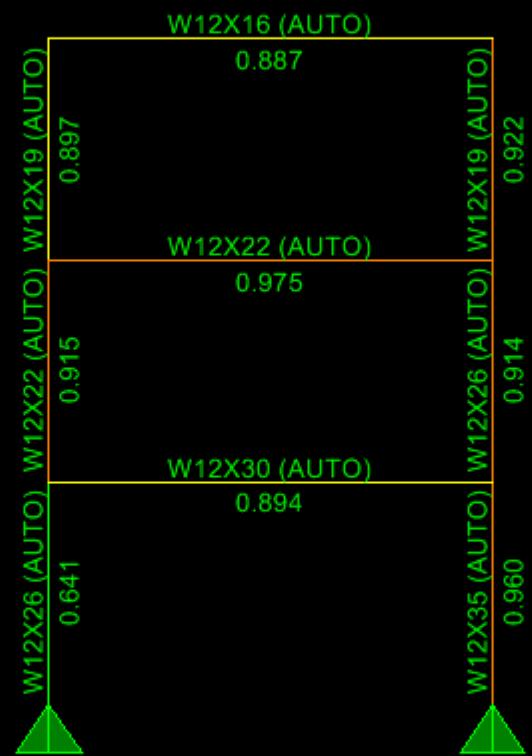
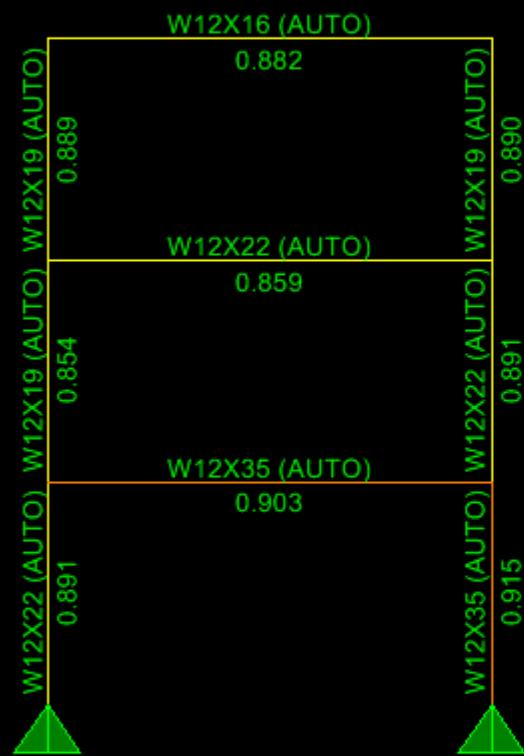
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Selected

GLOBAL Kip, ft, F

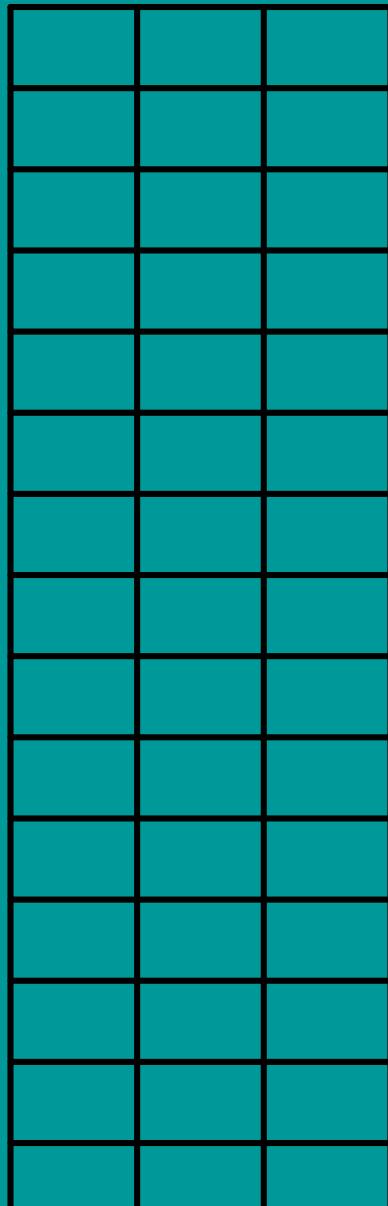


Steel P-M Interaction Ratios (AISC-ASD89)

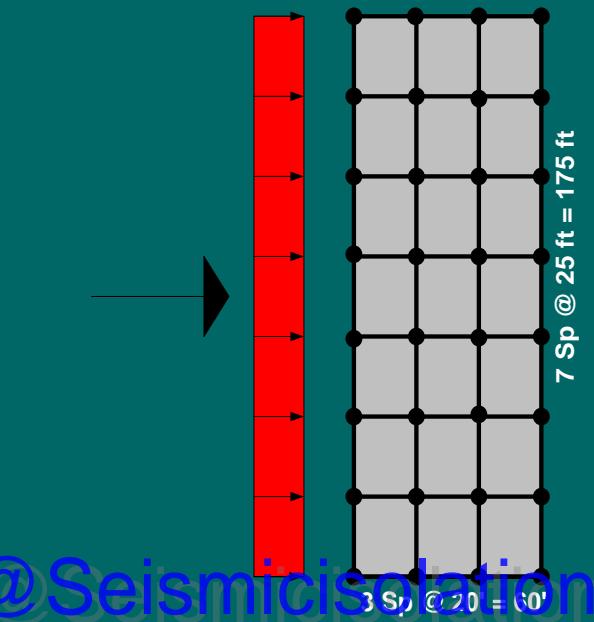
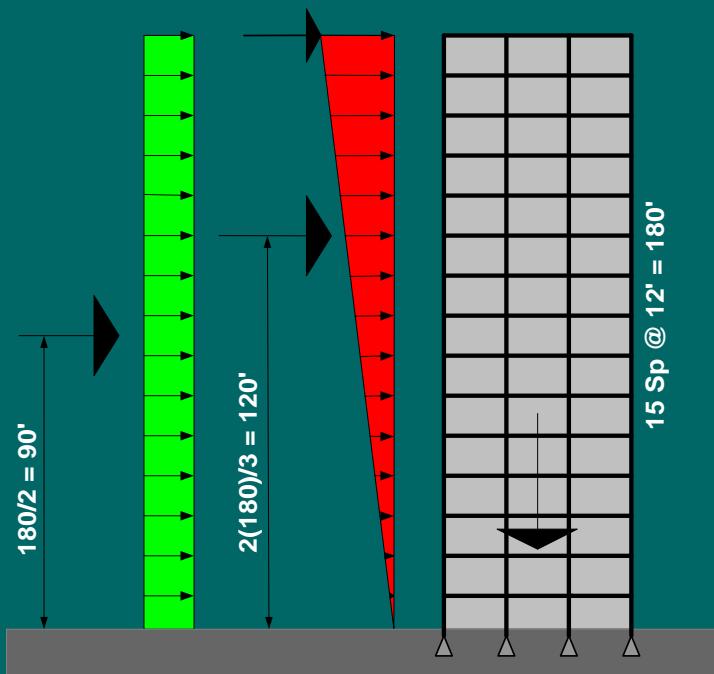


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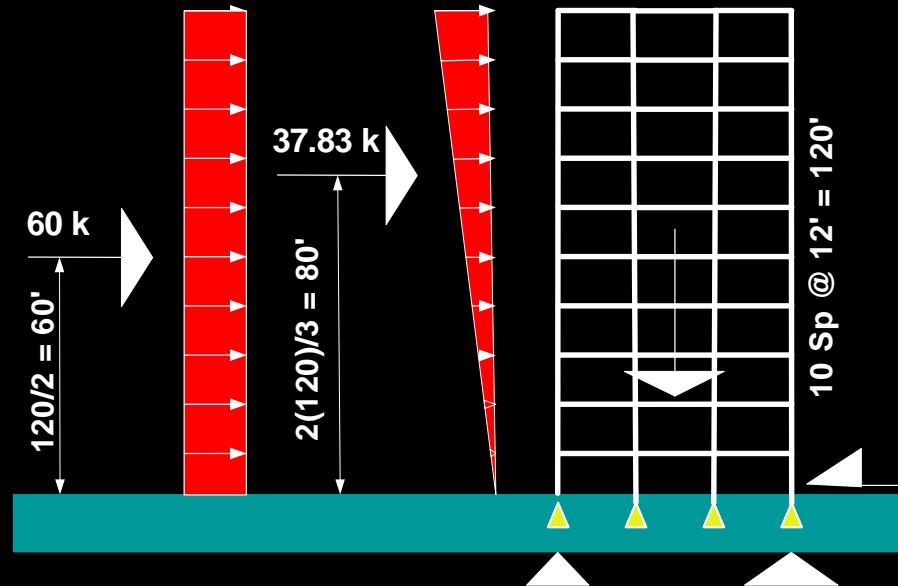
3 Sp @ 20' = 60'



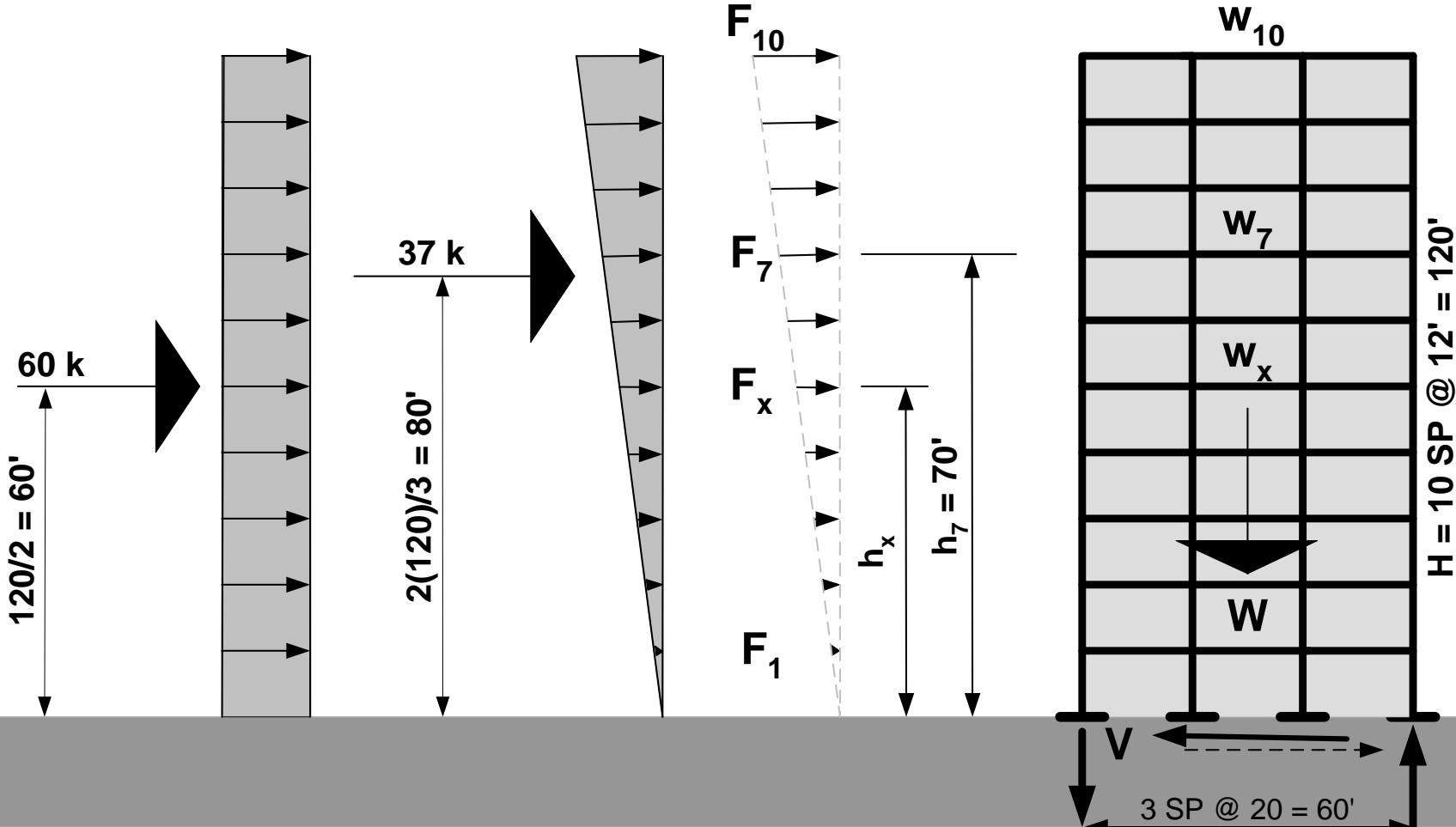
15 Sp @ 12' = 180'

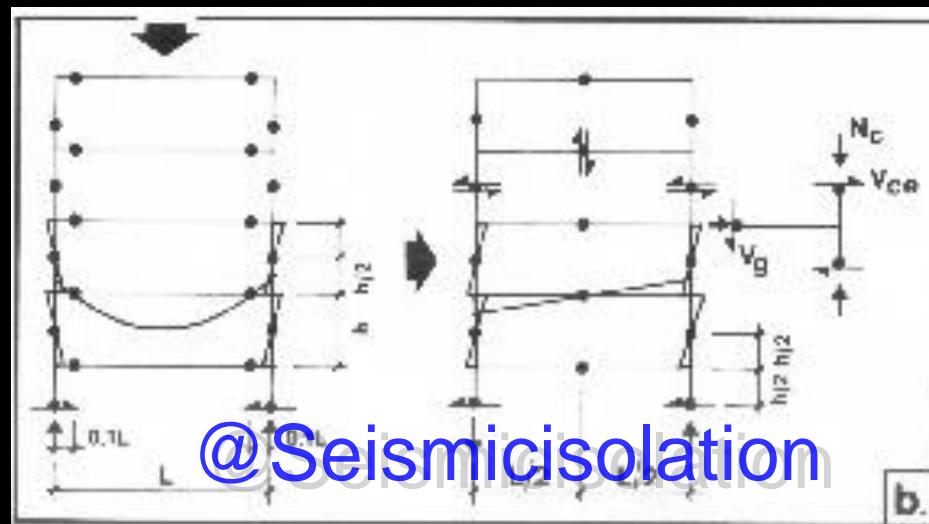
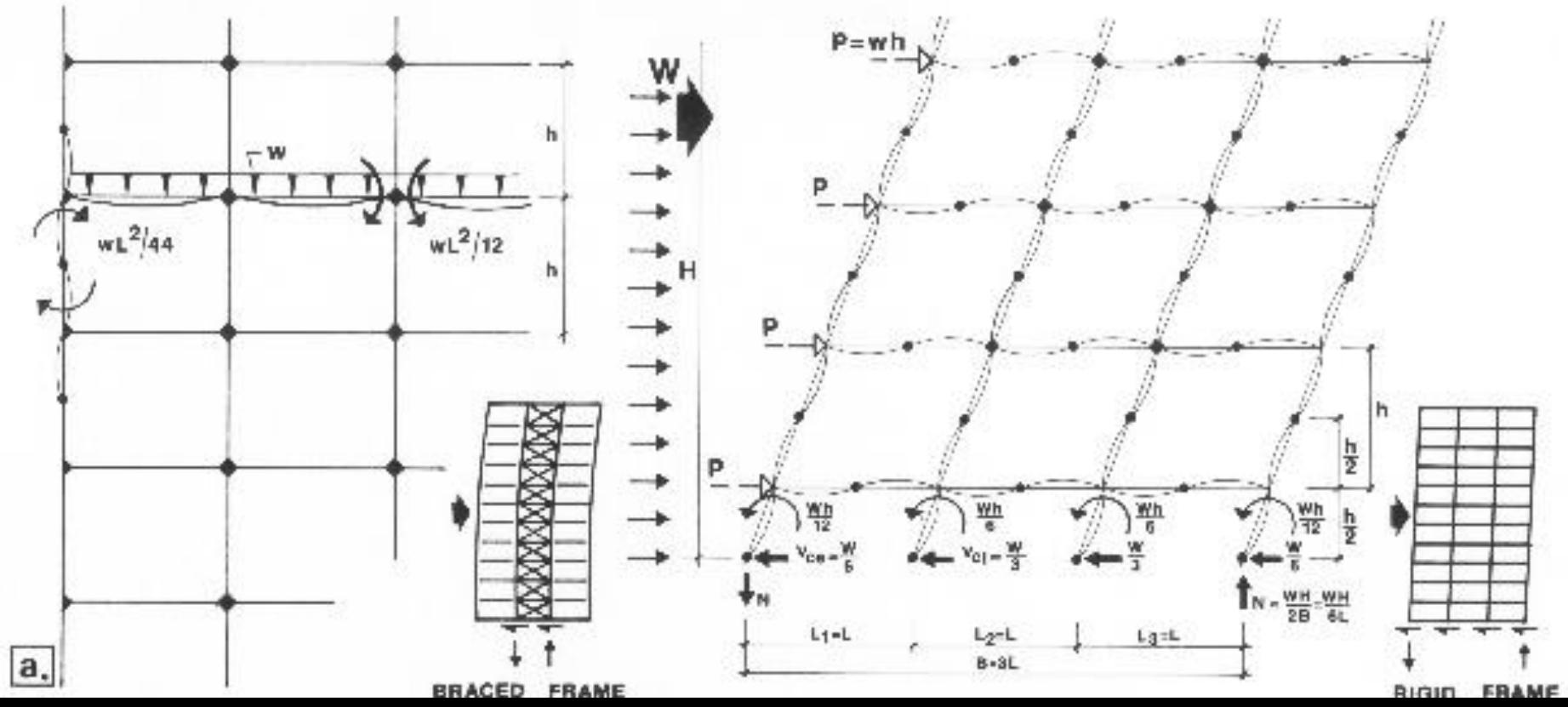


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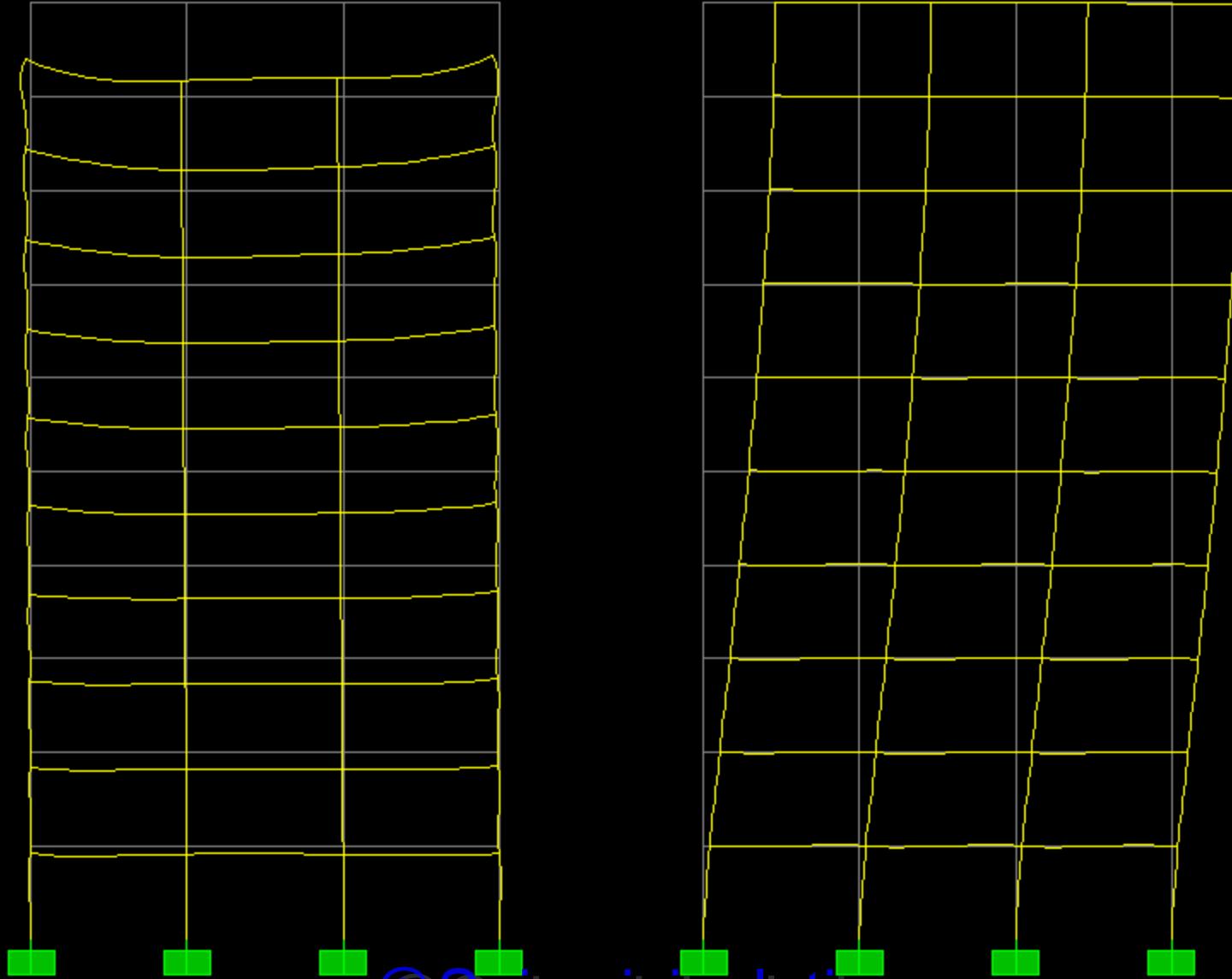
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3 Sp @ 20' = 60'



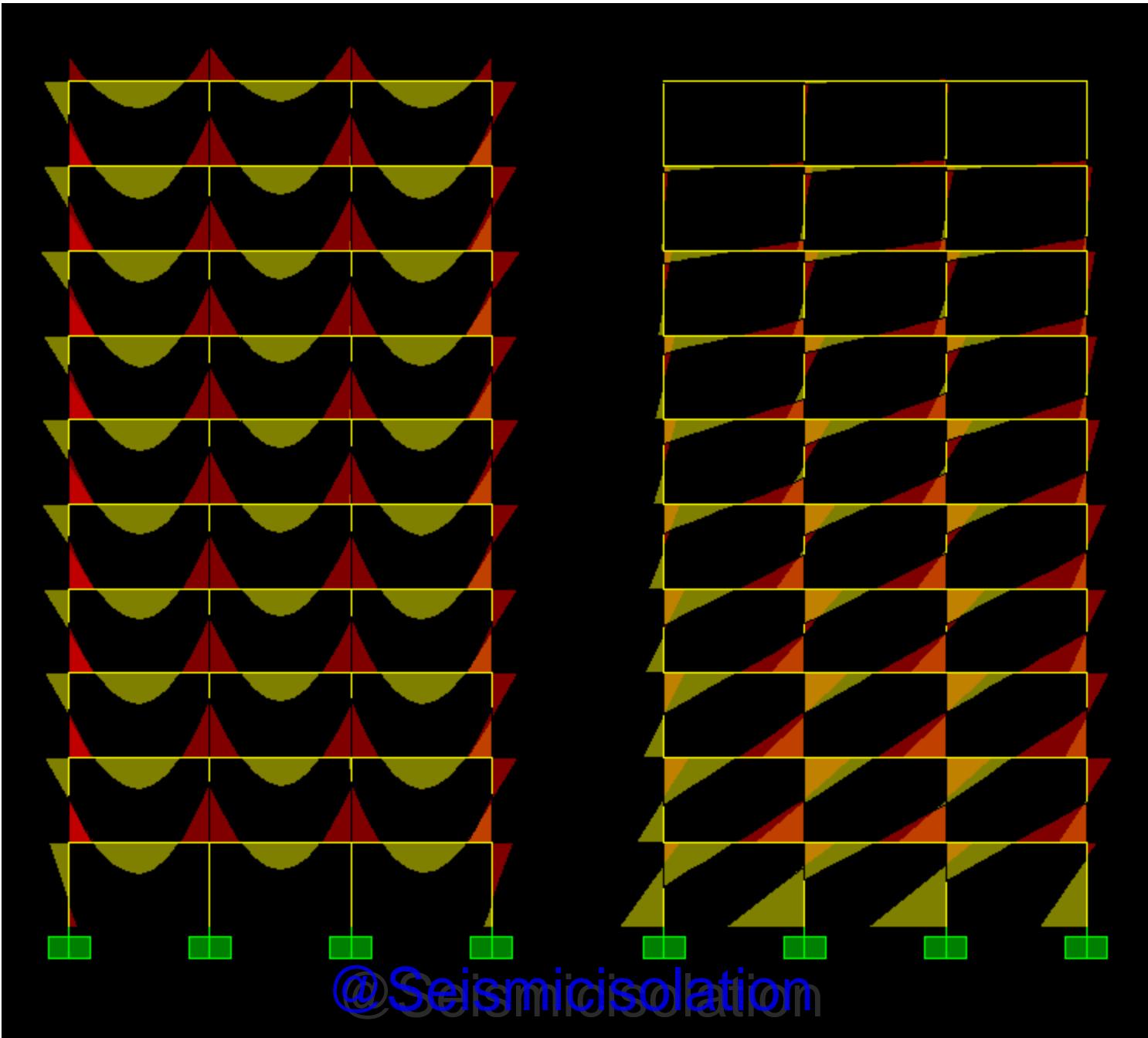


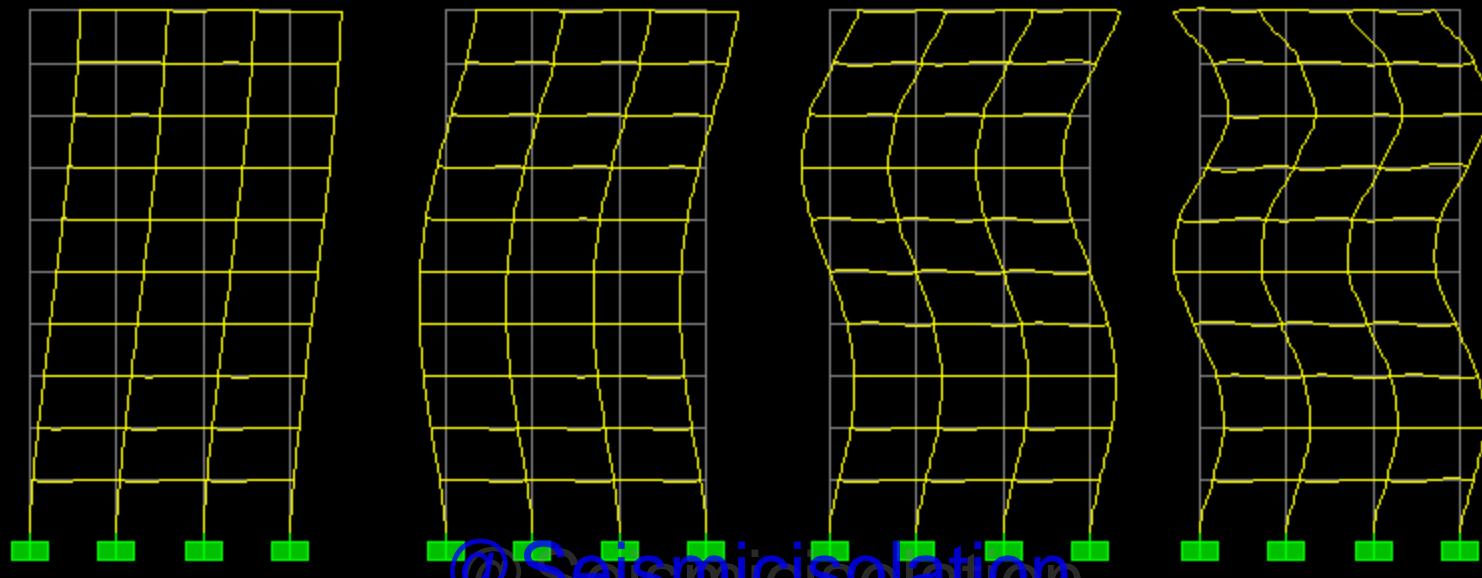
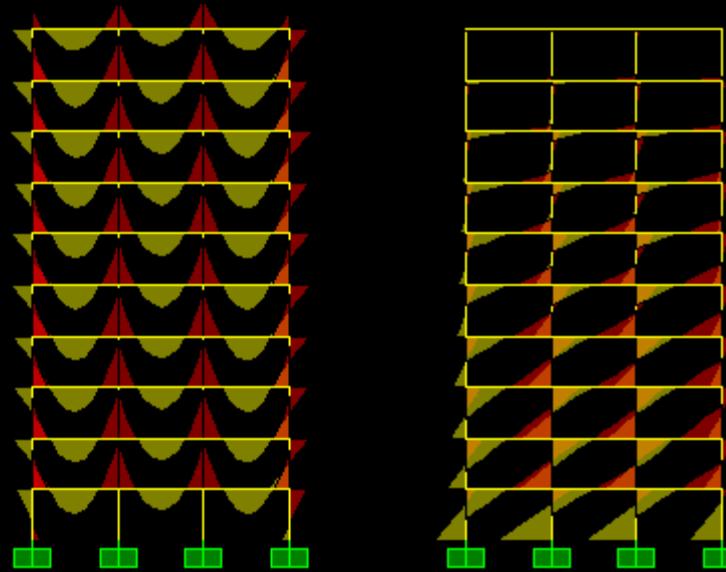
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b.



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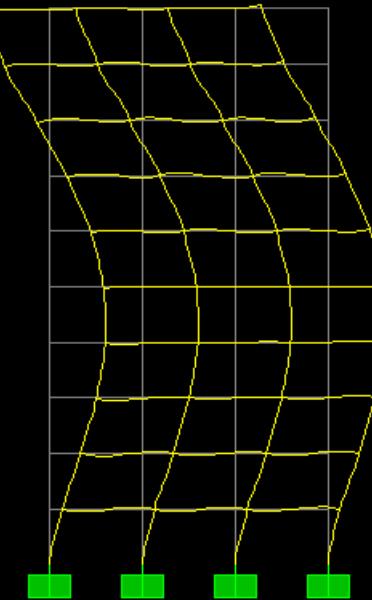
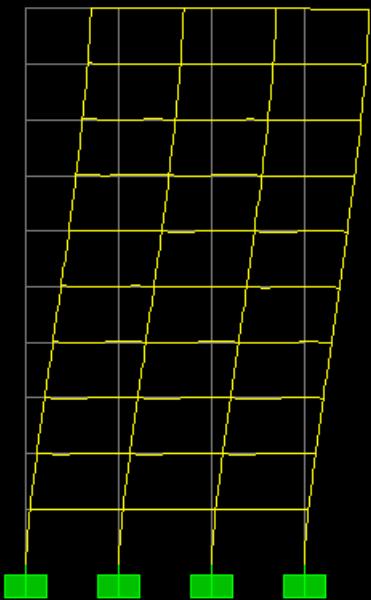


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Deformed Shape (MODAL) - Mode 1 - Period 2.13043



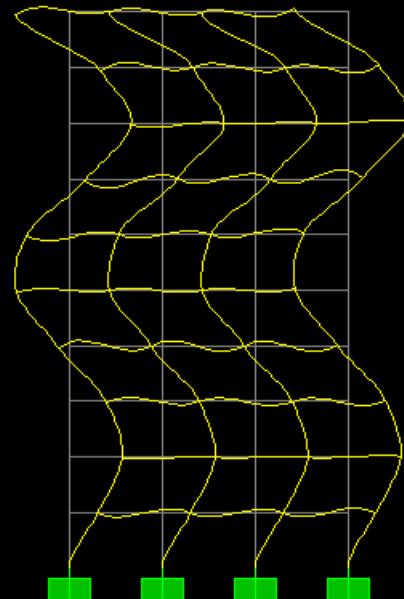
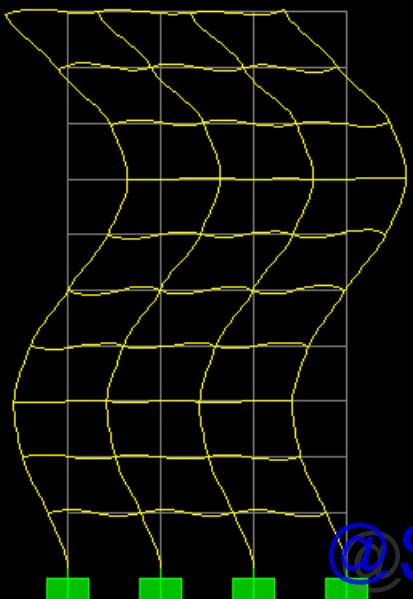
Deformed Shape (MODAL) - Mode 2 - Period 0.75951



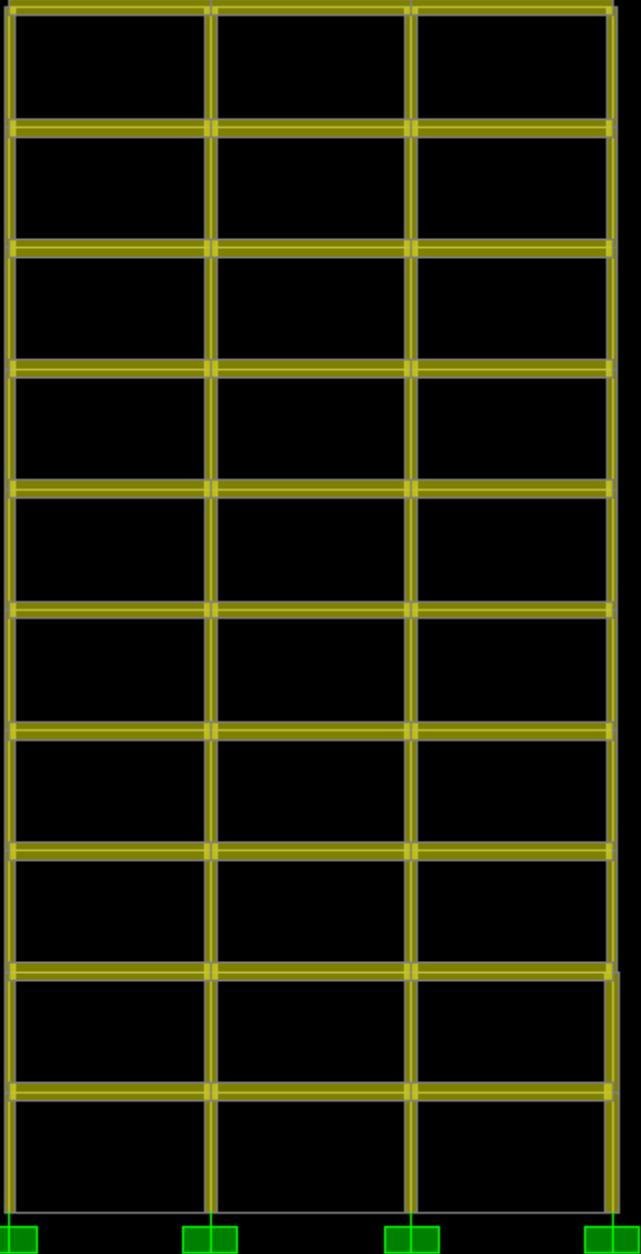
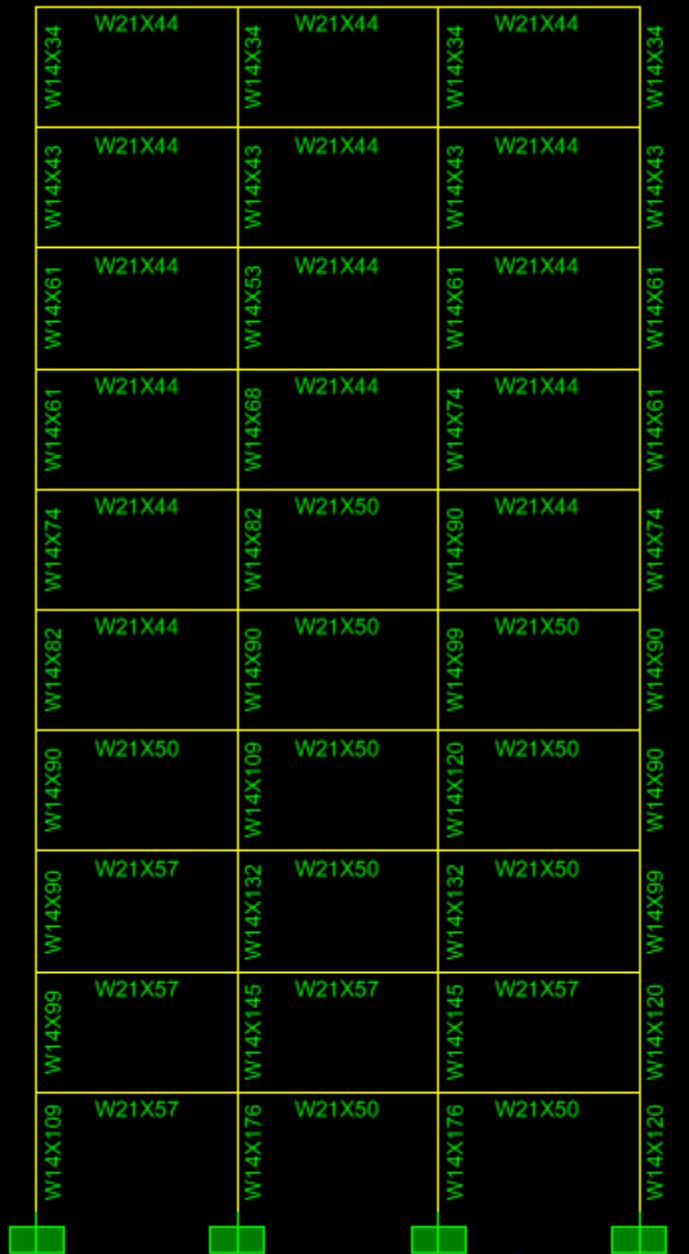
Deformed Shape (MODAL) - Mode 3 - Period 0.44562



Deformed Shape (MODAL) - Mode 4 - Period 0.30950



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0.50

0.70

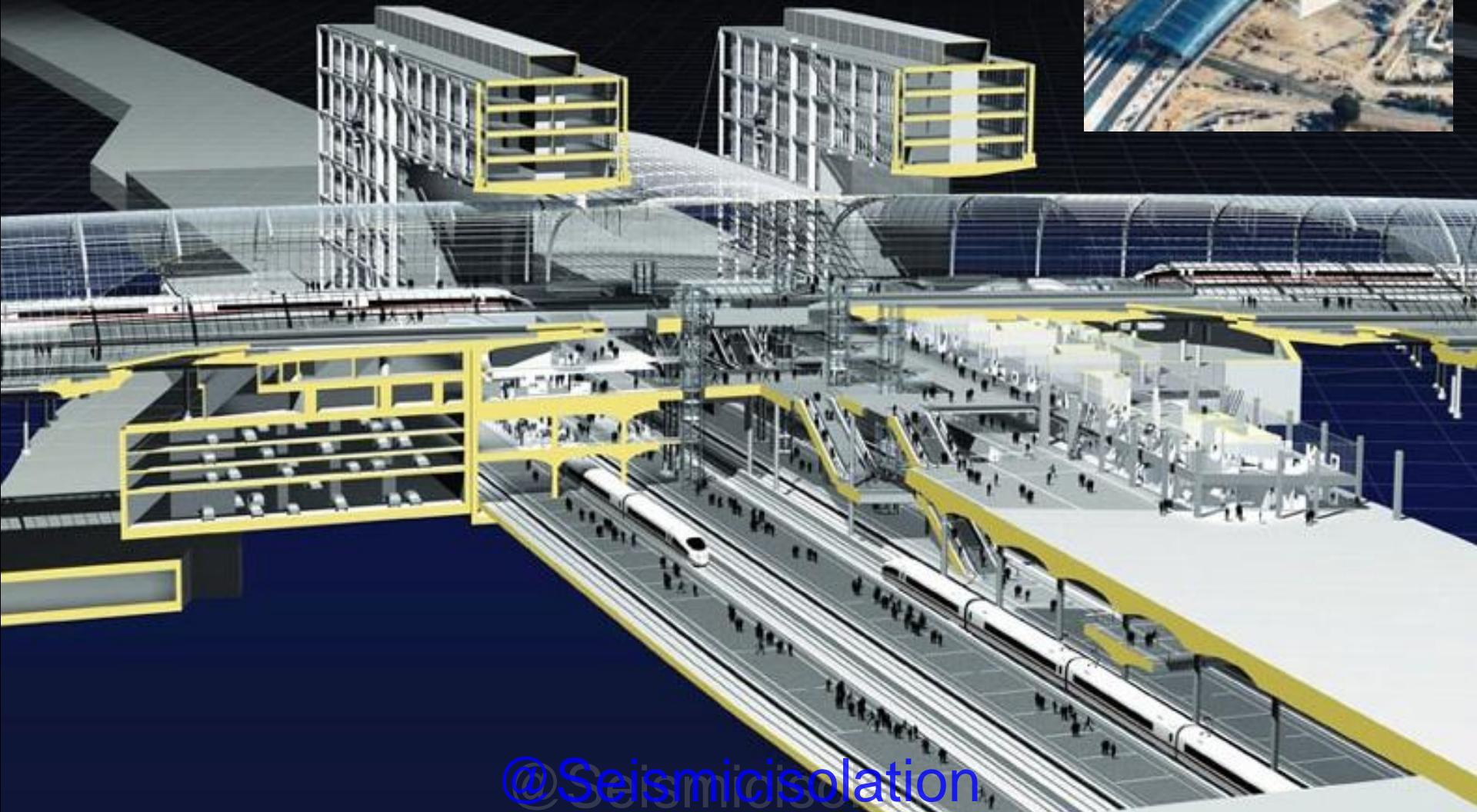
0.90

1.00



Beijing Jian Wa Seismic Isolation
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Hamamoto, 2004

Lehrter Bahnhof, Berlin, 2002, Gerkan,
Marg & Partner, Mero





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Dresdner Bank, Verwaltungszentrale, Engel und Zimmermann Arch
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@Seismicisolation
House, Nuremberg, Germany



Design Museum, @Seismicisolation, Volker Staab



@Seismicisolation
House, Nuremberg, Germany



@Seismicisolation
Parkinggarage Otto Schillstr., Leipzig, Germany



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Umspannwerk Mediapark, Köln, 1996, Sandro Graf von Einsiedel Arch.
Seismisolierung



Ningbo downtown, 2002,
Qingyun Ma

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@Seismicisolation, 2002, Qingyun Ma

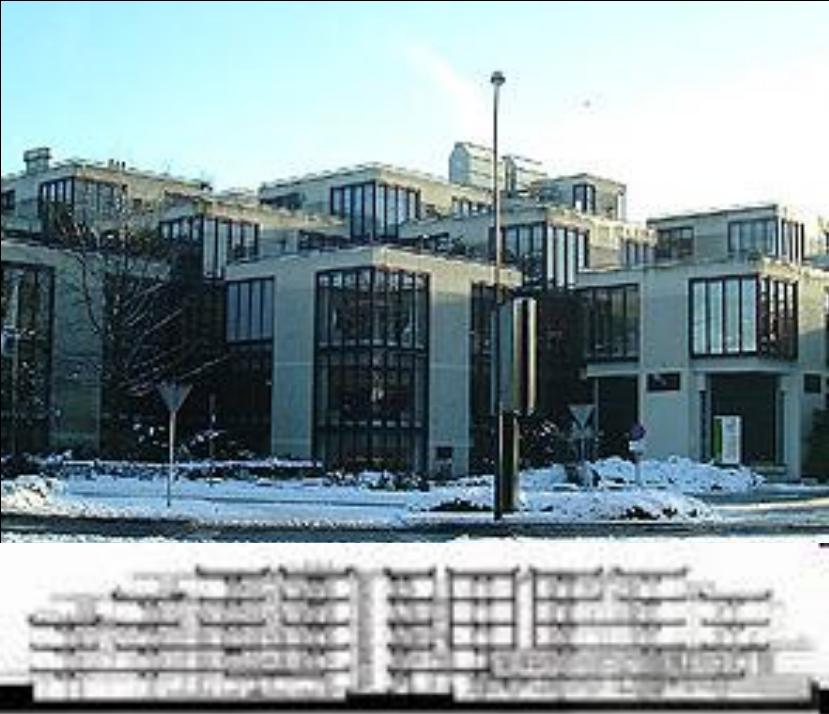


@Seismicisolation Residential complex, Berlin, Herman Herzberger, 1997



@Seismicisolation

26 9 2001



**Centraal
Beheer
Insurance
Company,
Apeldoorn,
The
Netherlands,
1972, Herman
Herzberger**

@Seismicisolation



Administration Building, Ningbo Institute of Technology, Zhejiang University, Ningbo, 2002, Qingyun Ma

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**WDR
Arcades/Broad
casting House,
Cologne, 1996,
Gottfried Böhm**

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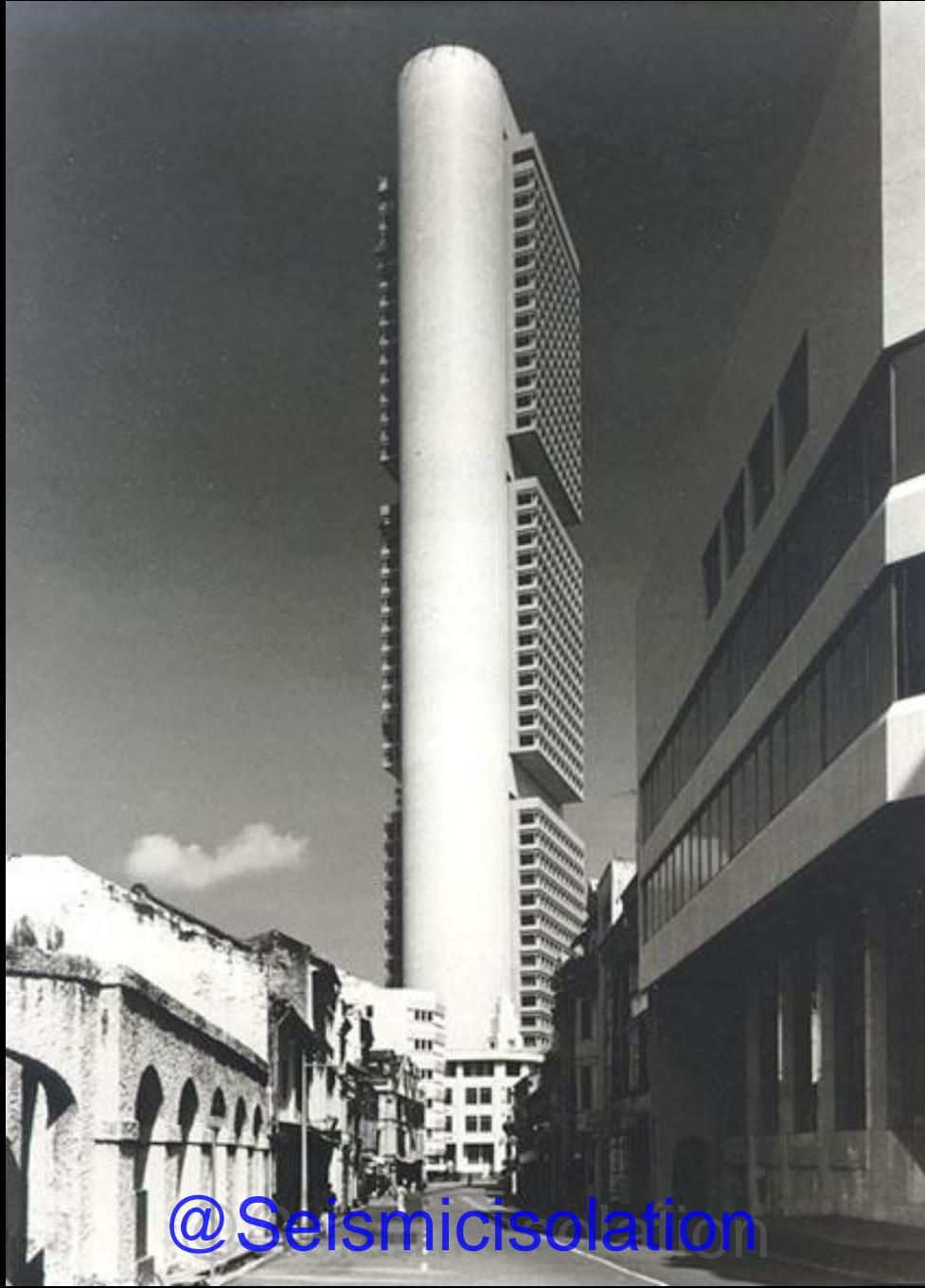


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**OCBC Center, Singapore,
1976, I.M. Pei, Arup,,
concrete mega-frame**



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Tsinghua University, 2006

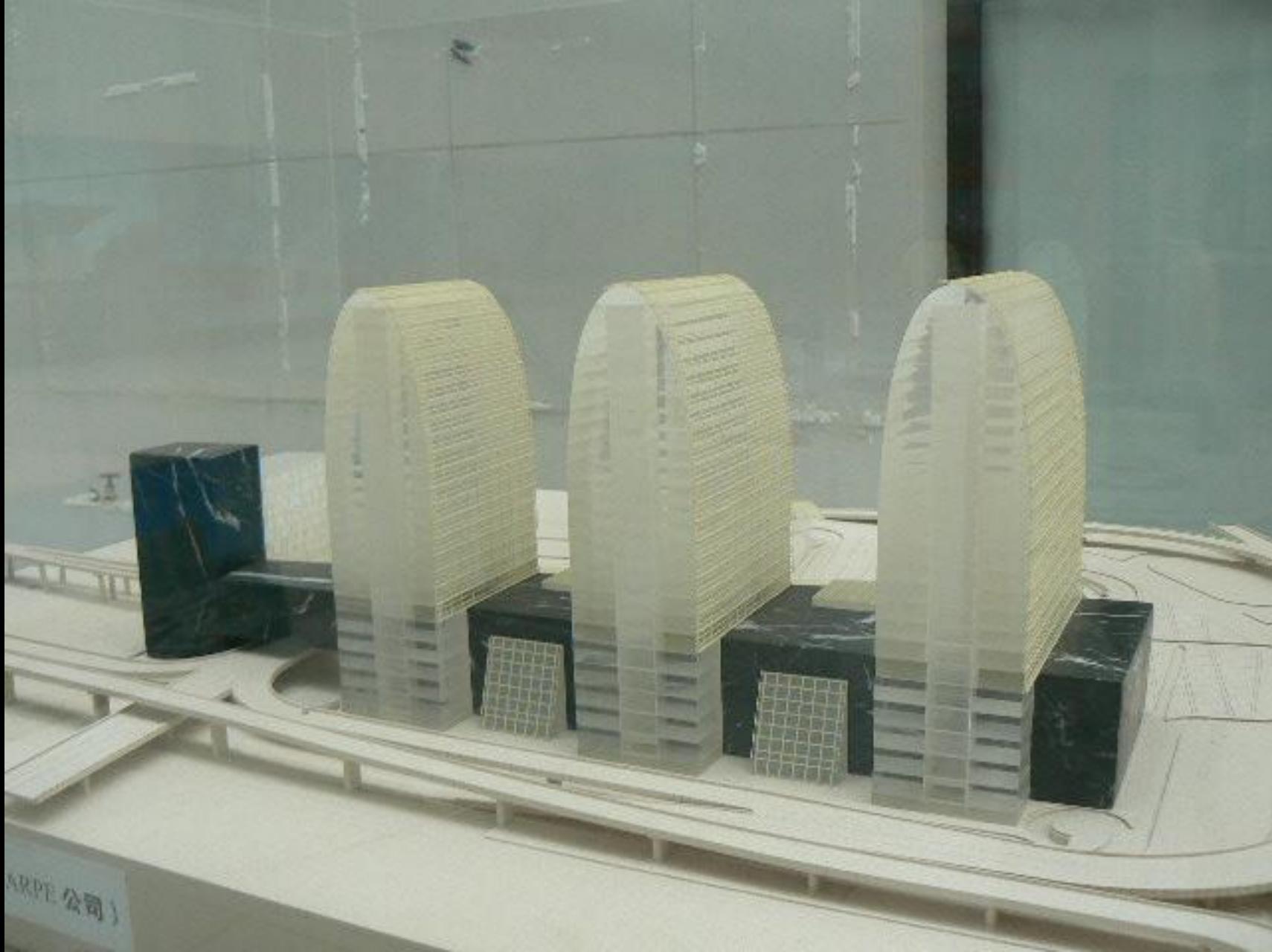
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? , Beijing



Beijing

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Dokumenta Urbana, Kassel, 1984, Otto Seidle
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Vierendeel bridge, Berlin



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Vierendeel bridge, Berlin



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House, Nuremberg

@Seismicisolation





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Landesvertretung von Baden-Wuertemberg, Berlin, 2000, Dietrich Bangert



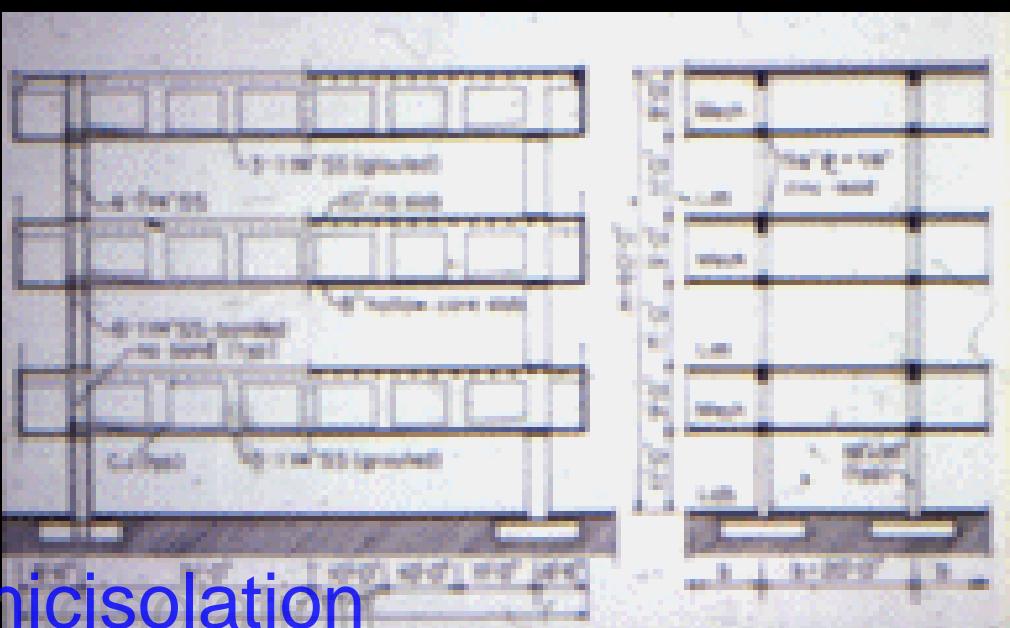
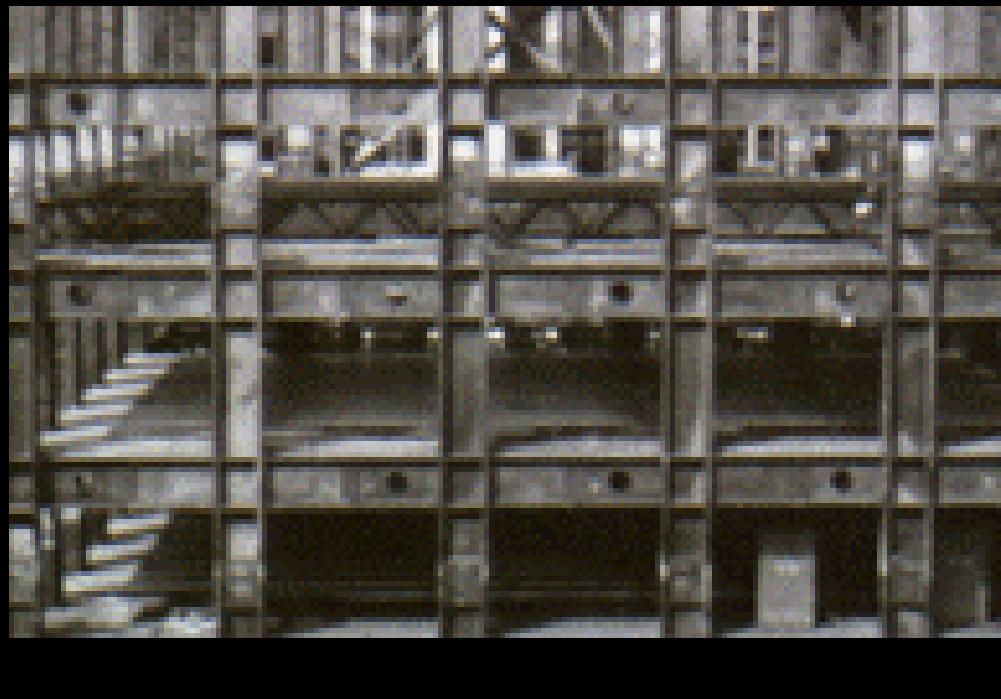
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Embassy UK, Berlin, 2000, Michael Wilford



Incheon International Airport, Seoul, 2001, Fentress Bradburn Arch.
Seismic isolation



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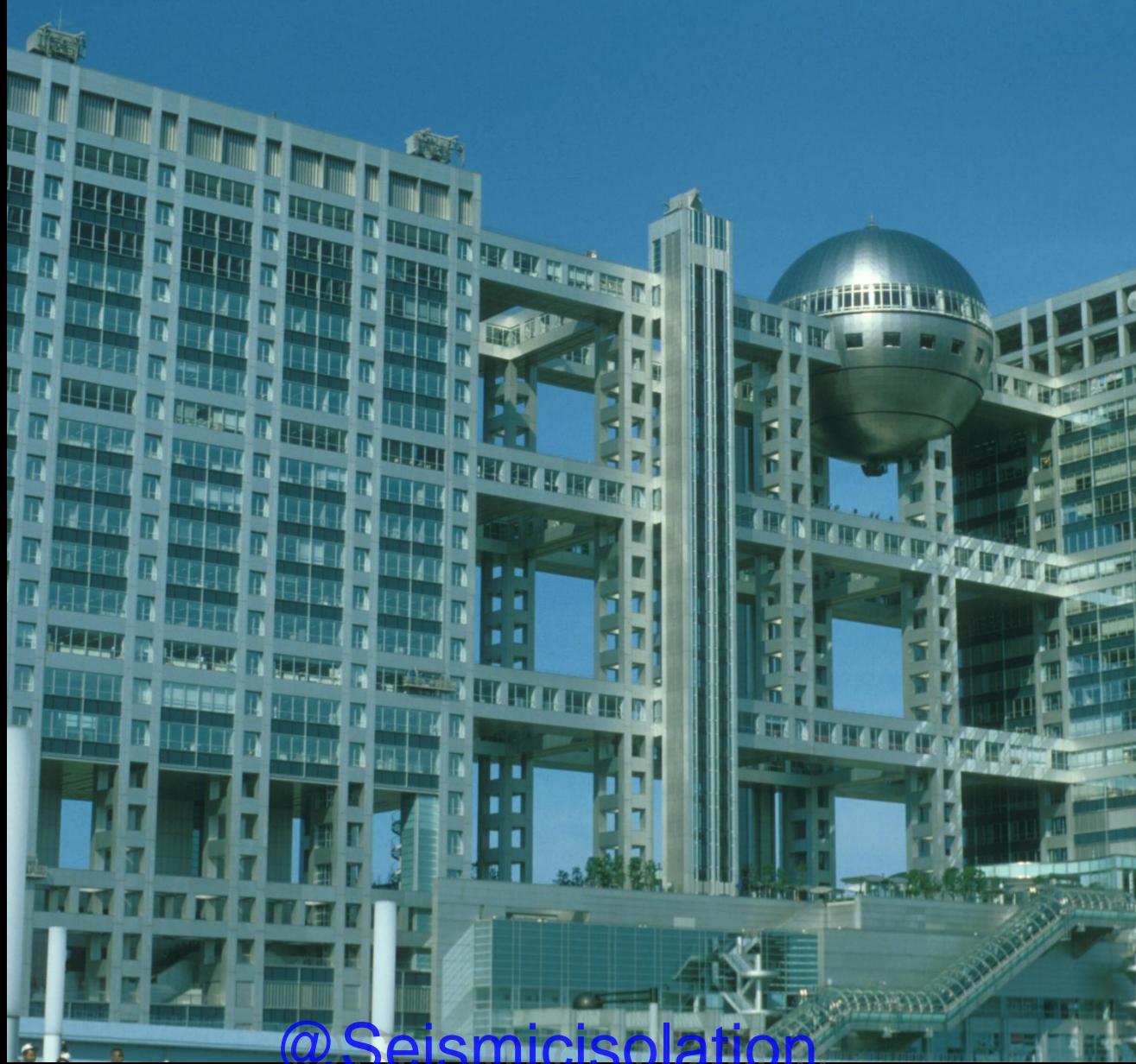
Salk Institute, La Jolla, California, 1966, Louis Kahn



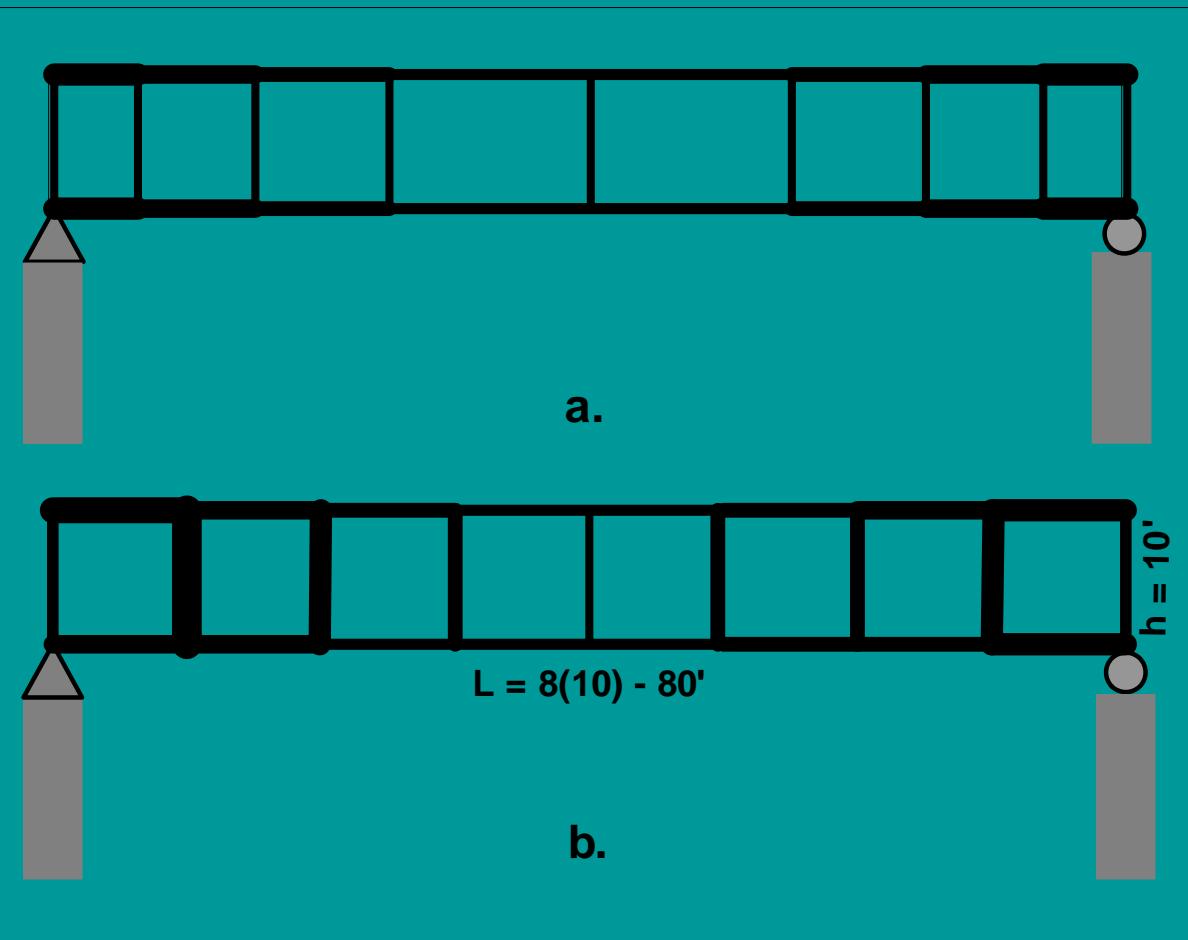
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Fuji Television Headquarters, Tokyo, 1996, Kenzo Tange
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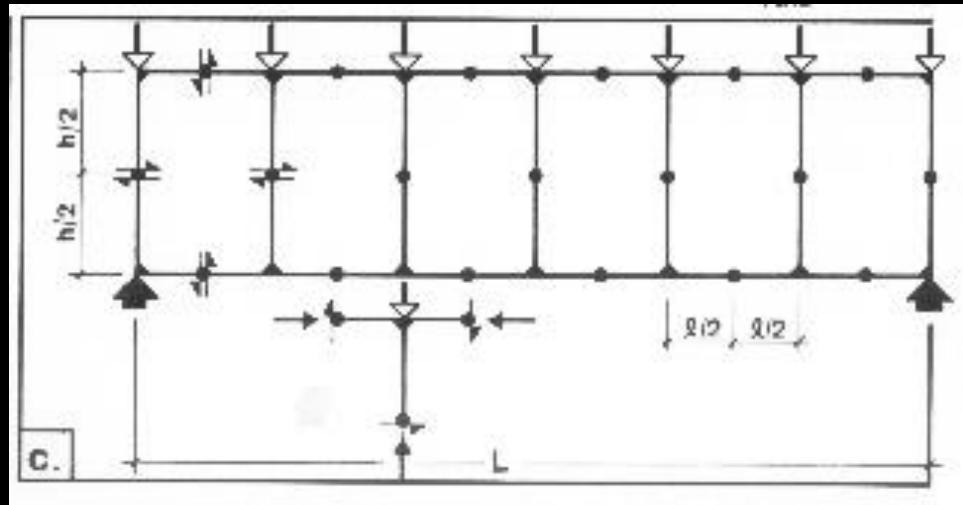
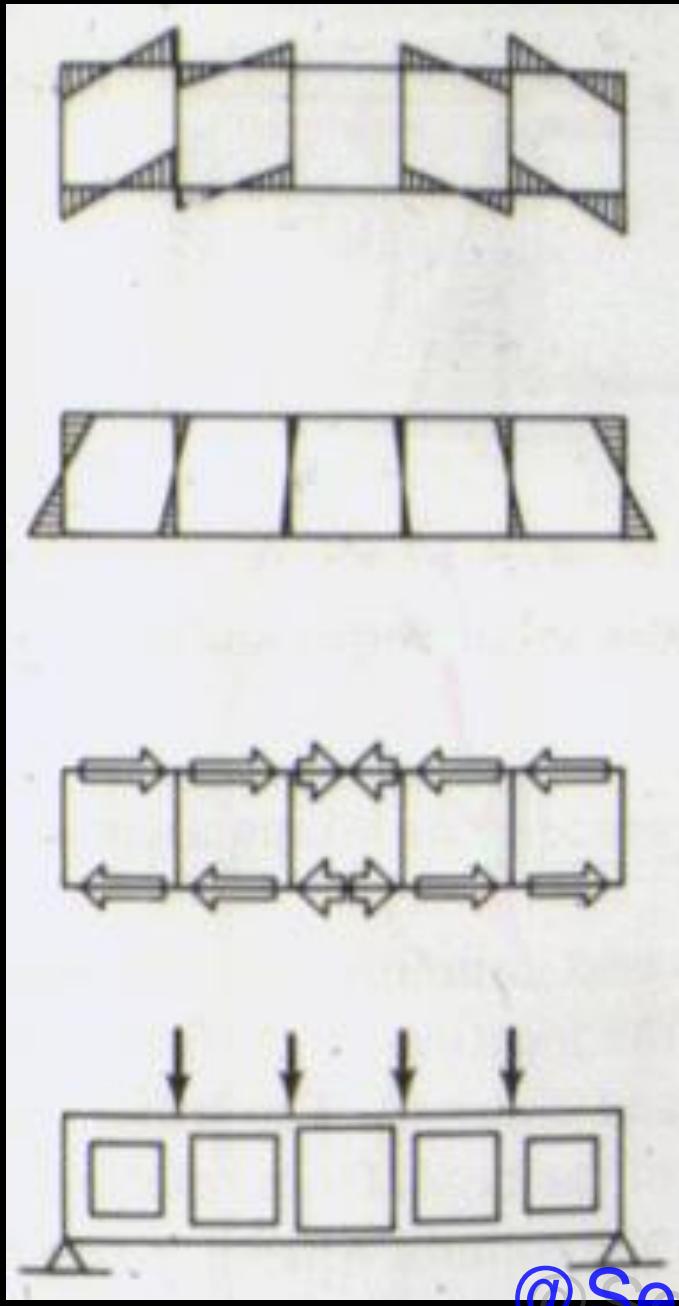
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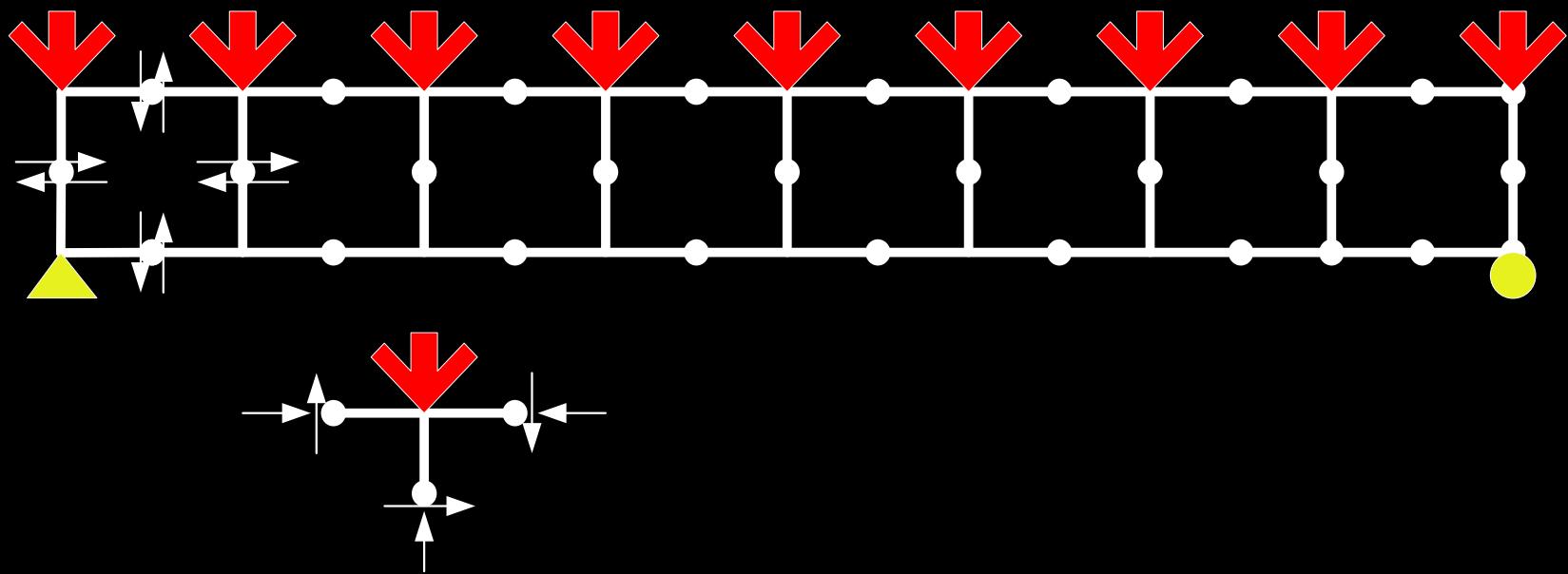
same member size

equal bay size

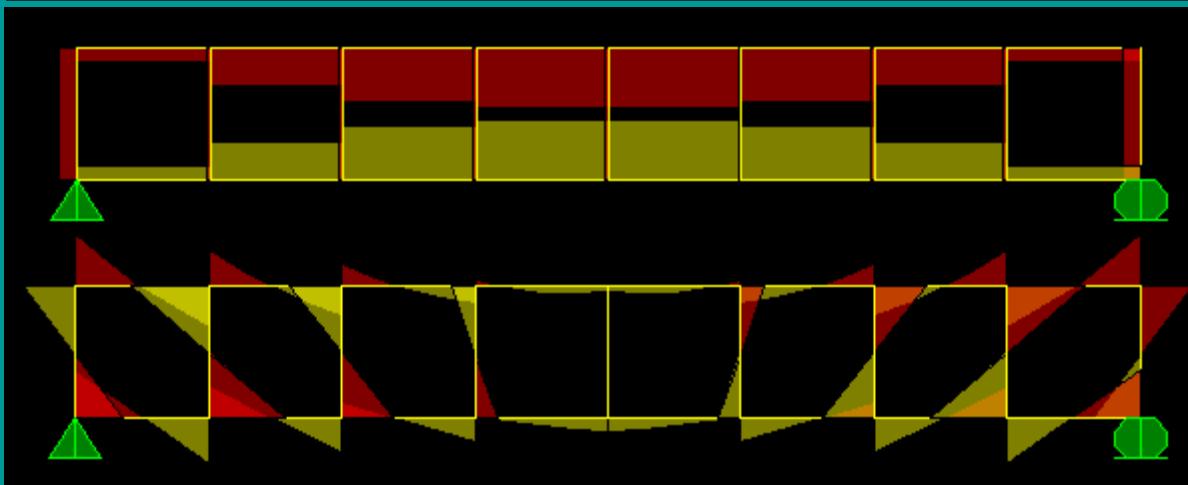
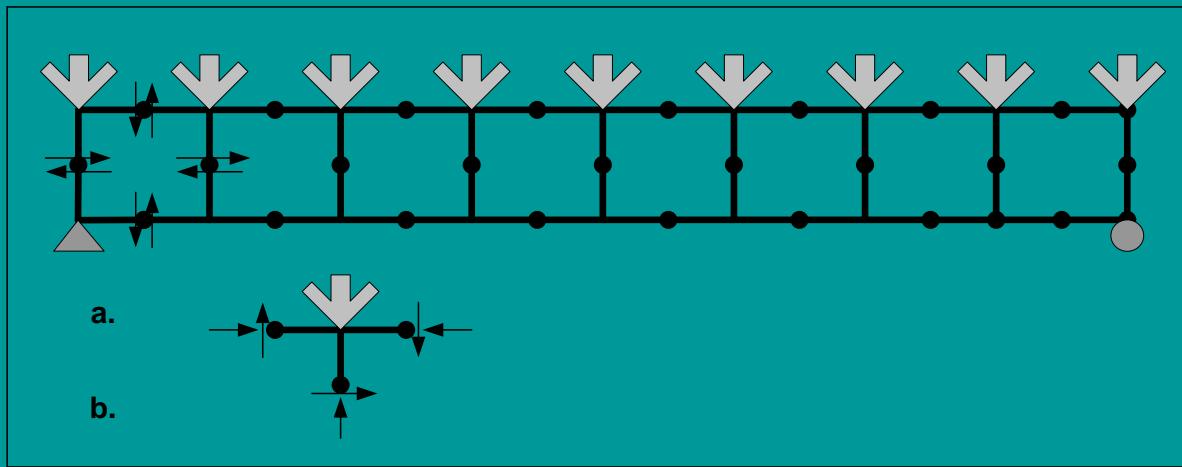
VIERENDEEL TRUSSES
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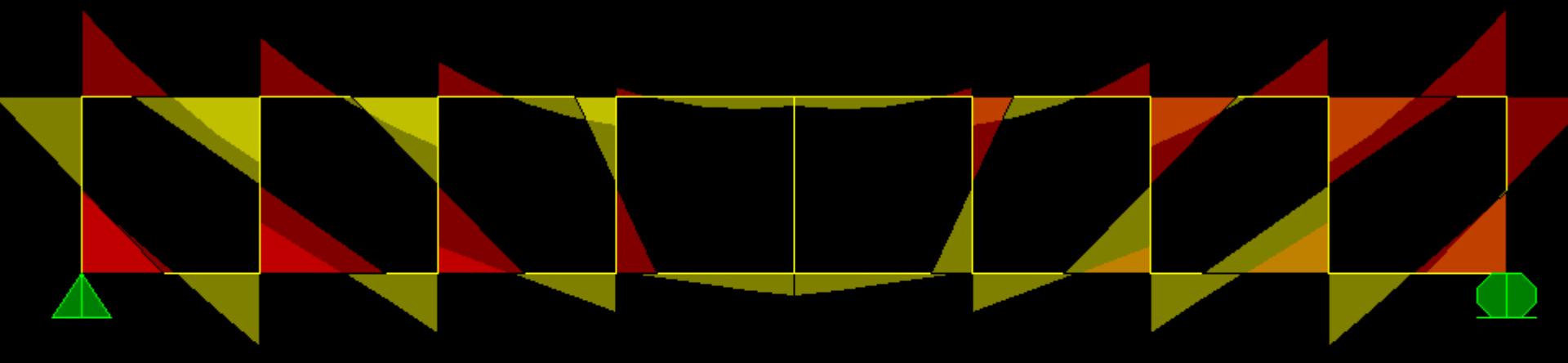
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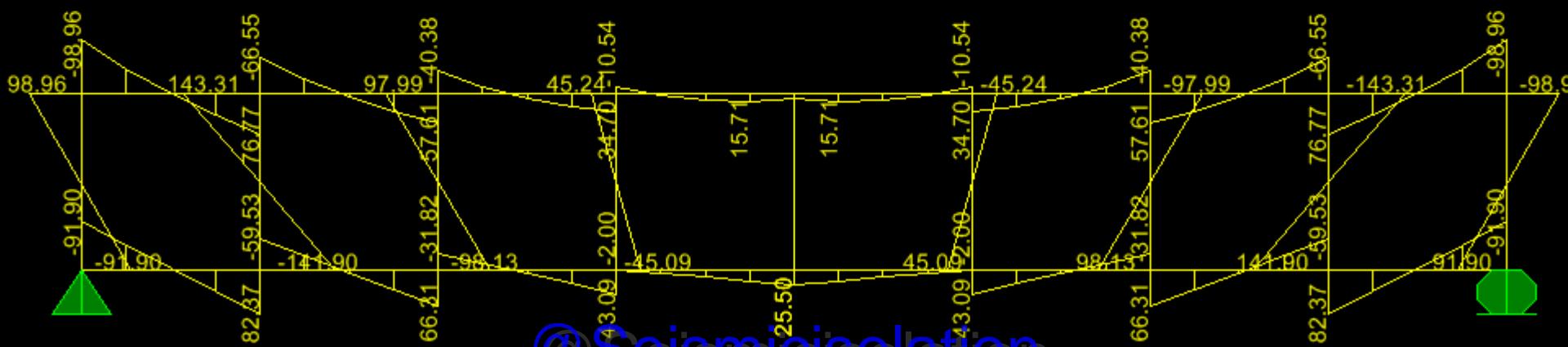
Edit View Define Draw Select Assign Analyze Display Design Options Help



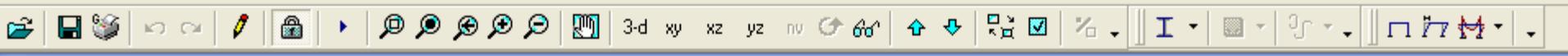
Moment 3-3 Diagram (COMB1)



Moment 3-3 Diagram (COMB1)



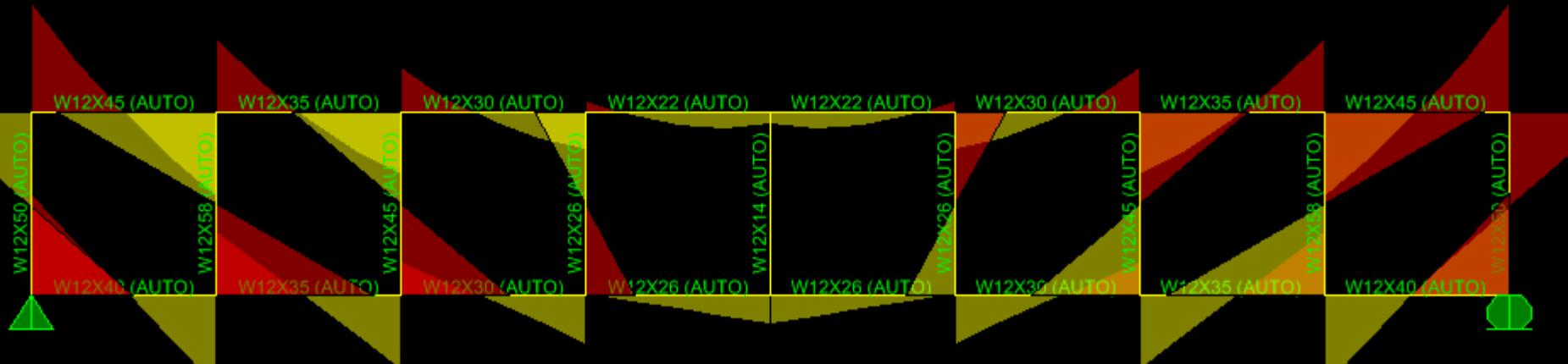
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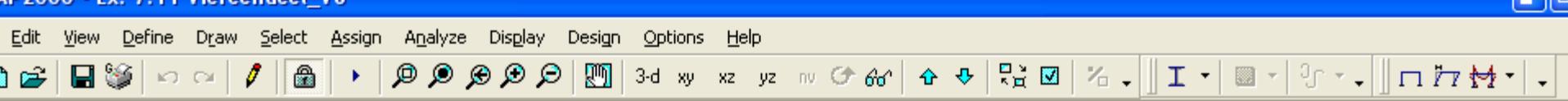
Axial Force Diagram (COMB1)



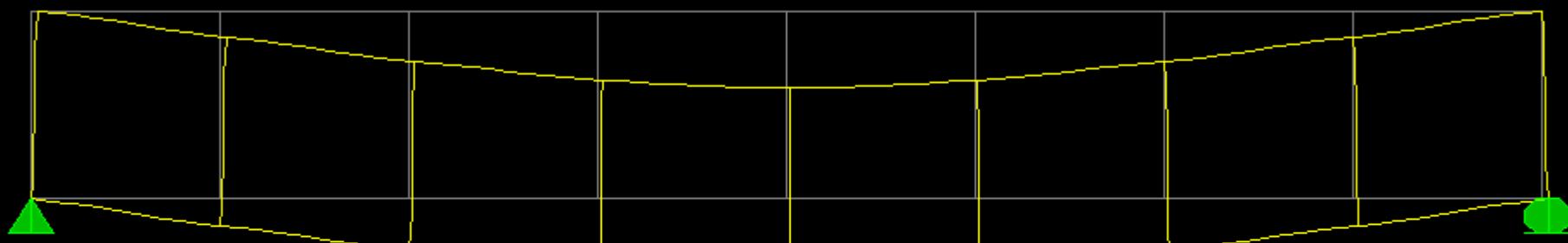
Moment 3-3 Diagram (COMB1)



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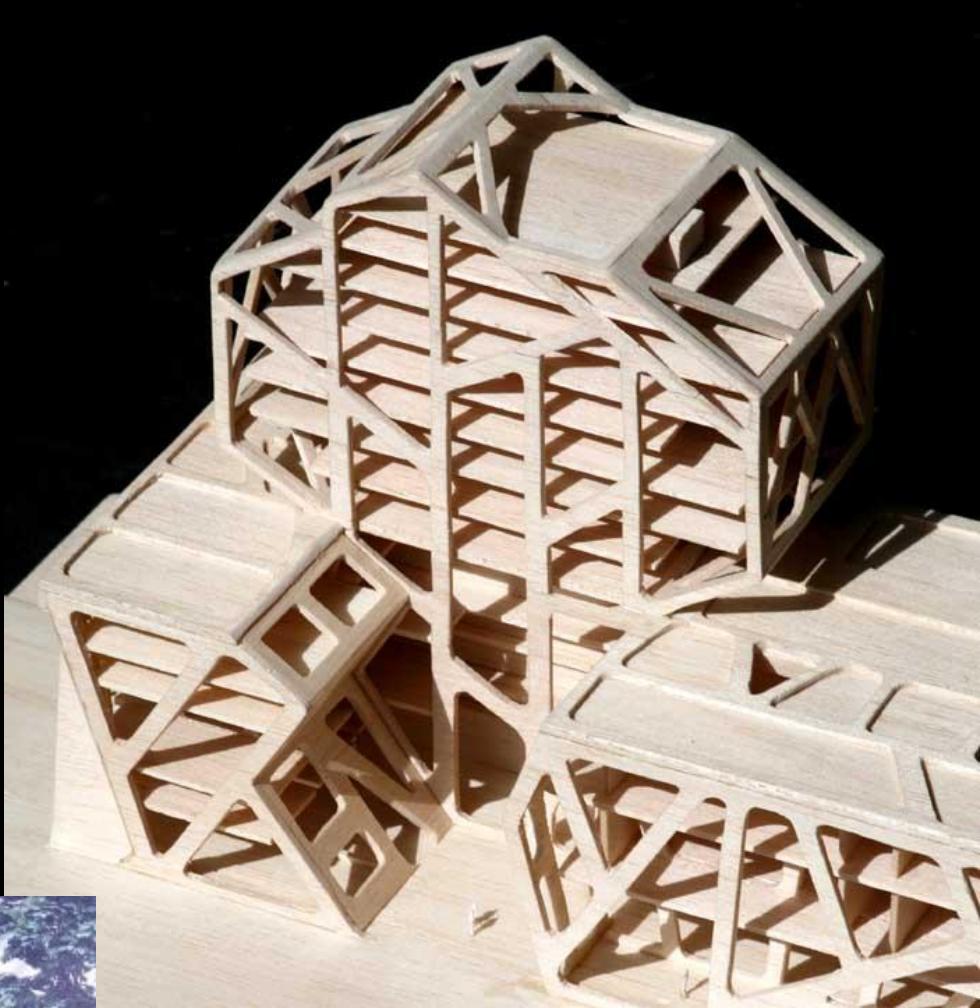
Deformed Shape (COMB1)



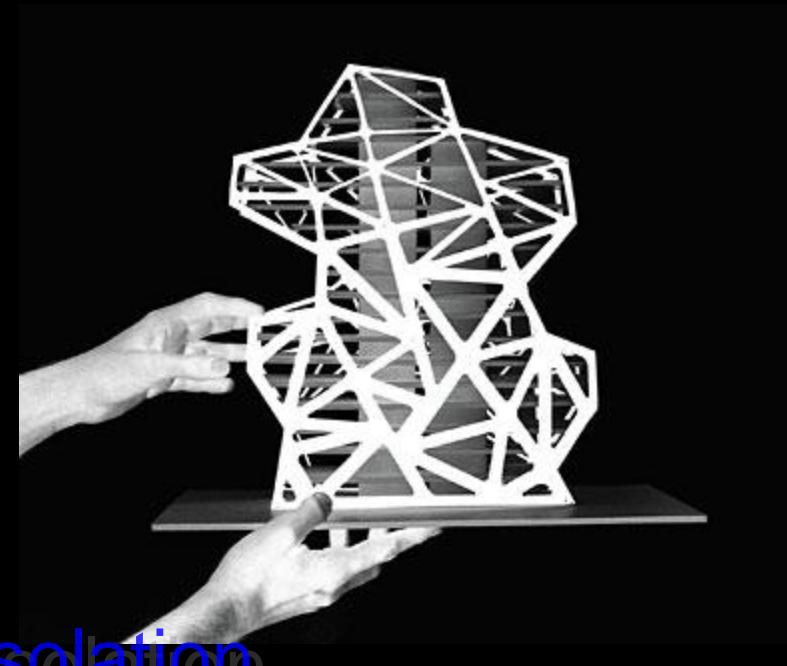
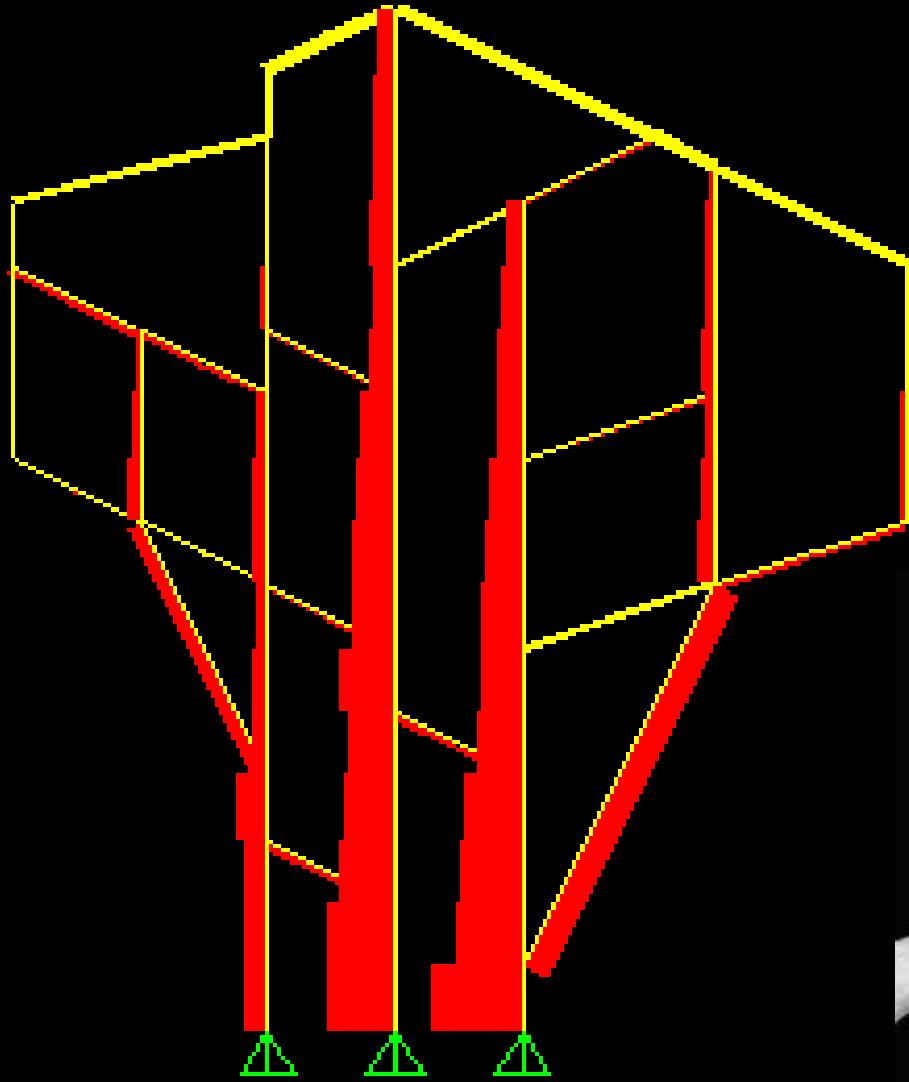
Steel P-M Interaction Ratios (AISC-ASD89)



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Court of Justice, Hasselt, Belgium, 2011, J. MAYER H. Architects



Axial Gravity Flow in Irregular Frame
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