· FOR AN ISOLATED SYSTEM THE "NATURAL"

INDEPENDENT VARIABLES ARE É, V, N (BECAUXE THESE ARE THE VARIABLES WE CONTROL &

THEY ARE FIXED).

THE ENTROPY IS "NATURALLY" A FYNCTION OF THESE VARIABLES (AS DEPENDS ON AE, AV AND AND ANI, USING CONSERVATION OF ENERGY).

FOR AN ISOCATED SYSTEM, S(E, V, N)

DETERMINES THE PIRECTION OF SPANTANEOUS

CHANGE IF WE REMOVE AN INTERNAL

CONSTRAINT — CHANGE ONLY OCCURS IF S

INCREASES.

• WE NEED TO BE ABLE TO DETERMINE

THE PRECTION OF SPONTANEOUS CHANGE FOR

OPEN! (ie NON-ISOLATED) SYSTEMS (SYSTEMS

WHICH CAN INTERACT WITH THEIR ENVIRONMENT,

WHERE ONE OR MORE OF E, V, N ARE

NO LONGER FIXED).

FOR OPEN SYSTEMS THE "NATURAL"

TRIDEPENDENT VARIABLES (THE ONES WE

ARE CONTROLLING) INCLUDE ONE OR MORE OF

P, T, Mi.

THE DIRECTION OF SPONTANEOUS CHANGE FOR

OPEN SYSTEMS IS DETERMINED BY THE FACT

THAT THE SYSTEM WILL SEEK A MAXIMUM

OR MINIMUM FOR A CERTAIN THEORYMANK

POTENTIAC WHICH IS "NATURALLY" A FUNCTION

OF THE "NATURAL VARIABLES"

• FOR ISOLATED SYSTEMS: THE NATURAL VARIANCES ARE $E, V, \overline{N} \rightarrow THE THEOMOGRAPHIC$ POTENTIAL IS $S(E, V, \overline{N})$

OTHER THENMODYNAMIC POTENTIALS

1. THE (HELMHOLTZ) PREE ENERGY E

F := E - TS

FOR AN INFINITESIMAL CHANGE FROM ONE
EQUILIBRIUM STATE TO ANOTHER

dF = dE - TdS - SdT

FOR A QUASISTATIC MOCESS, CONSERVATION OF

 $dE = TdS - pdV + \sum_{i} m_{i}dN_{i}$

=> dF = (TdS-pdV+&midNi)-Tds-SdT

=) AF = - SdT - pdV + \(\int_{i} dN_{c'} \) -(1)

$$= F(T, Y, \vec{N})$$

USING THE DEFINITION OF THE DIFFERENTIAL

$$AF(T,V,N') = \frac{\partial F}{\partial T} dT + \frac{\partial F}{\partial V} dV + \underbrace{\sum \frac{\partial F}{\partial N_i} dN_i'}_{i'}$$

$$L(2)$$

Companina (1) 9 (2)

$$\frac{\partial F(\tau, v, \vec{N})}{\partial T} = -S$$

$$\frac{\partial F(\tau, v, \vec{N})}{\partial V} = -P$$

$$\frac{\partial F(\tau, v, \vec{N})}{\partial V} = M_i$$

= 3 EQUATIONS OF STATE

2 THE GIBBS FREE ENERGY G

$$G := E - TS + pV$$

PRACTICE PROBLEM: COMPUTE DE USING

THE EXPRESSION FOR DE FOR CONSERVATION

OF ENIGICY

FIND:
$$AG = -SdT + Vdp + \leq midNi$$

$$\Rightarrow G = G(T, p, N)$$

$$\frac{\partial G(T_{i}P_{i}N)}{\partial T} = -5$$

$$\frac{\partial G(T_{i}P_{i}N)}{\partial P} = V$$

$$\frac{\partial G(T_{i}P_{i}N)}{\partial N_{i}} = M_{i}$$

3 EQUATIONS OF STATE

SAME TRICK: COMPUTE SH USING CONSERVATIONS
OF ENERGY TO SUBSTITUTE FOR SE

$$=) dH = TdS + Vdp + \leq nidNi$$

$$=) H = H(S, P, N)$$

APPLY THE DEFINITION OF THE DIFFERENTIAL

 $\frac{\partial H(s, p, \vec{N})}{\partial s} = T$ $\frac{\partial H(s, p, \vec{N})}{\partial p} = V$ $\frac{\partial H(s, p, \vec{N})}{\partial N_i} = M_i$

$$F = E - TS$$

$$G = E - TS + pV$$

$$TRANSFORMS$$

$$H = E + pV$$

$$("TRICK" PD$$

$$CHANGE VARIANCES)$$