The psychological arrow of time drives temporal asymmetries in

inferring unobserved past and future events

Xinming Xu¹, Ziyan Zhu², and Jeremy R. Manning^{1, *}

¹Dartmouth College, Hanover, NH, USA

²Peking University, Beijing, China

*Address correspondence to jeremy.r.manning@dartmouth.edu

September 12, 2023

Abstract

11

13

17

18

19

20

How much can we infer about the past and future, given our knowledge of the present? Unlike temporally symmetric inferences about simple sequences, inferences about our own lives are asymmetric: we are better able to infer the past than the future, since we remember our past but not our future (i.e., the psychological arrow of time). What happens when both the past and future are unobserved, as when we make inferences about *other* people's lives? We had participants view segments of a character-driven television drama. They wrote out what would happen just before or after each just-watched segment. Participants were better at inferring past (versus future) events. This asymmetry was driven by participants' reliance on characters' conversational references in the narrative, which tended to favor the past. Our work reveals a temporal asymmetry in how observations of other people's behaviors can inform us about the past and future.

Keywords: arrow of time, prediction, retrodiction, narrative, conversation

Introduction

What we experience in the current moment tells us about *now*— but what does it tell us about the past or future? And does the current moment tell us, as human observers, *more* about the past or about the future? One way of examining these questions is to consider highly simplified scenarios that are artificially constructed in the laboratory (e.g., Maheu et al., 2022). At one extreme, for deterministic sequences with *known* rules, knowing the current state provides the observer with sufficient information to exactly reconstruct the entire past and future history of the stimulus. At another extreme, for purely random sequences, observing the current state provides no information about the past *or* future.

Sequences generated by stochastic processes fall somewhere between these two extremes. For
Markov processes, where each state is solely dependent on the immediately preceding state,
Shannon entropy may be used to quantify the uncertainty of the past and future states, given the
present state. Cover (1994) showed that, for any stationary process (i.e., processes in equilibrium),
Markov or otherwise, the present state provides equal information (i.e., mutual information) about
past and future states (also see Bialek et al., 2001; Ellison et al., 2009). Further, there is some
evidence that humans are similarly adept at inferring the most likely previous and next items in
sequences governed by stochastic Markov processes (Jones and Pashler, 2007).

Deterministic, random, and probabilistic sequences (in equilibrium) are all symmetric: the present state of these sequences is equally informative about past versus future states. In contrast, our subjective experience in everyday life is that we know more about our own past than our future (e.g., Horwich, 1987). We have memories of our past that we carry with us into the present moment, but we do not have memories of our yet-to-be-experienced future. This temporal asymmetry imposes an "arrow of time" on our subjective experience, known as the *psychological arrow of time* (e.g., Hawking, 1985).

Although the psychological arrow of time implies that we should be better able to infer our past than our future, how generally does this temporal asymmetry hold? And does the asymmetry hold only for our own experiences (due to our memories), or is the asymmetry a general property

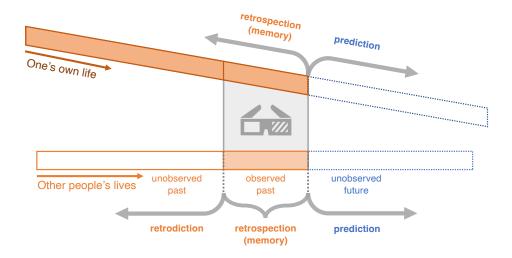


Figure 1: Retrodiction, retrospection, and prediction. In one's own life, one may draw on memory to retrospect (i.e., review or re-evaluate) the past or predict the future. This process is time-asymmetric, since our own past is (typically) observed whereas our future is not. When we make inferences about *other* people's lives, however, we often have uncertainty about both their past and future, since we may have observed neither. We may *retrodict* the unobserved past and predict the unobserved future of other people's lives.

of any real-life event sequence? In real-world situations (and narratives) where we are equally ignorant of the past and future, as for other people's lives where we lack memories of the relevant past, are our inferences about the past and future symmetric or asymmetric? For example, imagine 50 that you are meeting a stranger for the first time. At the moment of your meeting, you lack 51 both memories of their past and knowledge about what they might do in the future. After your 52 first encounter with the stranger, would you be able to more accurately or easily form inferences 53 about what had happened in their past (retrodiction) or what will happen in their future (prediction; 54 Fig. 1)? Or suppose you started watching a movie partway through. Again, you would enter the moment of watching without memories of prior parts of the movie. Given your observations in 56 the present, would your guesses about what had happened before you started watching be more (or less) accurate than your guesses about what will happen next? In general, when the past and future are both unobserved, are we better at inferring the past or the future in real-world settings? Narrative stimuli, such as stories and movies, can provide a useful testbed for exploring several of these questions.

Although narratives are unlikely to be confused with one's own experiences, narratives mirror 62 some of the structure of real-world experiences. Character behaviors and interactions are often 63 designed in a way that helps the audience connect with or relate to the characters. Events in narratives also unfold in ways that are intended to build rapport or engagement with the audience. 65 This might be accomplished by having events follow a believable structure that is reminiscent of real-world experiences, or by designing the audience's experiences in ways that communicate clear 67 "rules" or "features" that help to immerse the audience in the narrative's universe. The characters in a realistic narrative can also be written to behave in ways reminiscent of real-world people. These same aspects of narratives that authors use to drive engagement with events and characters can lead narratives to replicate some core aspects of real-world experiences that are typically lost or 71 overlooked in traditional sequence learning paradigms. Narratives can drive the audience to build 72 situation models (Radvansky and Copeland, 2006; Zwaan and Radvansky, 1998) of the narrative's 73 universe, or to form a theory of mind of and make predictions about the characters (Tamir and Thornton, 2018; Koster-Hale and Saxe, 2013). Events in narratives may unfold in a consistent or 75 logical way, but they also exhibit complex and meaningful interactions across events reminiscent of 76 real-world experiences (but not necessarily the simple sequences traditionally used in the statistical learning literature).

One key difference between simple artificial sequences and more naturalistic (real or narrative)
sequences is that naturalistic sequences often incorporate other people. Despite the past and
future being equally unknown to *the observer* prior to the current moment, other people, and
realistic characters in narratives, have their own psychological arrows of time. Specifically, they
have memories of their own pasts. Other people's asymmetric knowledge about their *own* pasts
and futures might affect their behaviors (e.g., conversations). In turn, this might provide timeasymmetric clues that favor the past (e.g., other people might talk more about their own pasts
than their futures; Demiray et al., 2018). If observers leverage these clues from other people's
asymmetric knowledge, then observers should also be better at inferring the past (versus the future)
of other people's lives. Alternatively, if inferences about other people's lives are more like inferences

about artificial statistical sequences (e.g., perhaps solely relying on statistical regularities like event schemas, scripts, or situation models Radvansky and Copeland, 2006; Zwaan and Radvansky, 1998; Bower et al., 1979; Ranganath and Ritchey, 2012), then the accuracy of inferences about the past and the future of others' lives should be approximately equal.

We designed a naturalistic paradigm for exposing participants to scenarios where the past and 93 future were equally unobserved. We asked our participants to watch a series of movie segments drawn from a character-driven dramatic television show. Across the conditions and trials in the 95 experiment, participants made free-form text responses to either retrodict what had happened in the previous segment, predict what would happen in the next segment, or recall what happened 97 in the just-watched segment. We used manual annotations and sentence-level natural language processing models to characterize participants' responses. To foreshadow our results, we found that participants were overall better at retrodicting the past than predicting the future. This 100 appeared to be driven by two main factors. First, characters more often referred to past events than 101 future (e.g., planned) events, and this influenced participants' responses. Second, associations and 102 dependencies between temporally adjacent events enabled participants to form estimates about 103 nearby events (e.g., to a just-watched scene or a past or future event referenced in an observed 104 conversation). Taken together, our work reveals a temporal asymmetry in how observations of 105 other humans' behaviors inform us about the past versus the future. 106

of Results

Participants in our study (n = 36) watched segments from two storylines, drawn from the CBS television show *Why Women Kill*. Each storyline comprised 11 segments (mean duration: 2.05 min; range: 0.97–3.87 min, Table S1). We asked participants to use free-form (typed) text responses to retrodict what had happened prior to a just-watched segment, predict what would happen next, or recall what they had just watched (Fig. 2, *Task design*). We referred to the to-be-retrodicted, to-be-predicted, or to-be-recalled segment as the *target segment* for each response. We systematically varied whether participants watched the segments in forward or reverse chronological order, and

how many segments they had seen prior to making a response (see *Methods*).

117

118

119

120

121

123

125

126

127

128

129

130

131

132

133

134

135

136

137

138

139

141

We asked participants to generate four types of responses after watching each video segment: 116 uncued responses, character-cued responses, updated responses, and recalls (Fig. 2, Data overview). To generate *uncued* responses, we asked participants to either retrodict (uncued retrodiction; *u-R*) what happened shortly before or predict (uncued prediction; u-P) what happened shortly after the just-watched segment. To generate *character-cued* responses, we asked participants to retrodict (character-cued retrodiction; c-R) or predict (character-cued prediction; c-P) what came before or after the just-watched segment, but we provided additional information to the participant about which character(s) would be present in the target (to-be-retrodicted or to-be-predicted) segment. We hypothesized that character-cued responses should be more accurate than uncued responses, to the extent that participants incorporate the character information we provided to them into their retrodictions and predictions. To generate updated responses, we asked participants to watch an additional segment that came just prior to or just after the target segment, and then to update their retrodiction (c-RP) or prediction (c-PR) about the target segment. Results on updated responses are not reported in this paper. Finally, we also asked participants to recall what happened in the justwatched segment. We labeled these responses according to which other segments participants had watched prior to the just-watched target. Retrodiction-matched recall (re(R)) responses were made during the retrodiction sequences (B1 and B2; Fig. 2), whereas prediction-matched recall (re(P))responses were made during the prediction sequences (A1 and A2; Fig. 2). Whereas retrodiction and prediction responses reflect what participants estimate they would remember after watching the (inferred) target segment, recall responses provide a benchmark for comparison by measuring what they *actually* remember about the target segment.

For each retrodiction and prediction, participants were asked to generate at least one, and not more than three, responses that constituted "the sorts of things [the participant would] expect to have remembered if [they] had watched the [target] segment." They were asked to generate multiple responses only if those additional responses were (in their judgement) of equal likelihood to occur. On average, participants generated 1.08 responses per prompt; therefore we chose to consider only participants' first ("most probable" or "most important") responses to each prompt.

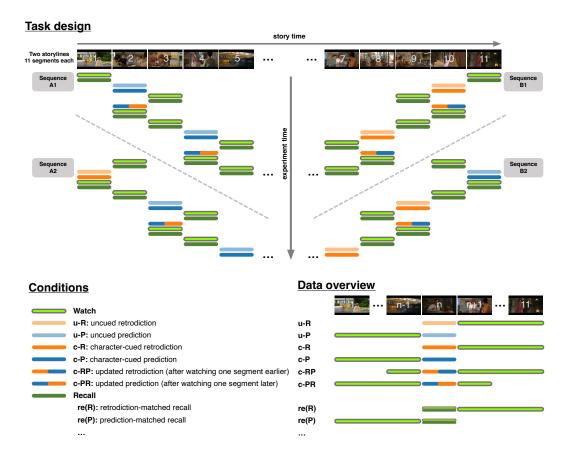


Figure 2: Task overview. Participants watched segments of two storylines from the television series *Why Women Kill*. They made free-form text responses to either retrodict what had happened in the previous segment, predict what would happen in the next segment, or recall what happened in the just-watched segment. Across four counterbalanced sequences, we systematically varied whether participants watched the segments in forward or reverse chronological order, whether (or not) responses were cued using the main characters in the target segment, and which other segments participants had watched prior to making a response. For each segment, we collected several retrodiction, prediction, and/or recall responses across different experimental conditions. Experiment time is denoted along the vertical axis, storyline segments are indicated along the horizontal axis, and the colors denote experimental tasks (conditions).

We also discarded a small number (n = 20) of character-cued responses that did not contain references to all cued characters, along with one additional response due to the participant's misunderstanding of the task instructions during that trial. We carried out our analyses on the remaining 2084 retrodiction, prediction, and recall responses.

144

145

146

We used two general approaches to assess the quality of participants' responses (see Methods, 147 Fig. 3A). One approach entailed manually annotating events in the video and counting the number 148 of matched events in participants' responses. We identified a total of 117 unique events reflected 149 across the 22 video segments (range: 3-9 per segment; see Methods, Table S1). We assigned one "point" to each of these video events. We also identified 23 additional events in participants' 151 responses that were either summaries of several events or that were partial matches to the manually identified video events. We assigned 0.5 point to each of these additional events. This point 153 system enabled us to compute the numbers and proportions (hit rates) of correctly retrodicted, 154 predicted, and recalled events contained in each response. Our second approach entailed using 155 a natural language processing model (Cer et al., 2018) to embed annotations and responses in 156 a 512-dimensional feature space. This approach was designed to capture conceptual overlap 157 between responses that were not necessarily tied to specific events. To quantify this conceptual 158 overlap, we computed the similarities between the embeddings of different sets of responses. 159 Following Heusser et al. (2021), we defined the precision of each participants' retrodictions or 160 predictions about a target segment as the median cosine similarities between the embeddings 161 of (a) the participant's retrodiction or prediction response for the target segment and (b) each 162 other participant's recalls of the same segment. In other words, precision is designed to measure 163 the extent to which retrodictions and predictions captured the conceptual content that (other) 164 participants remembered. We also developed a related measure, which we call convergence, to 165 characterize response similarities across participants. In particular, we defined convergence as the 166 mean cosine similarity between the embeddings of a participant's responses to a target segment 167 and all other participants' responses (of the same type) to the same segment. We analyzed the data using generalized linear mixed models, with participant and stimulus (e.g., target segment) 169 identities as crossed random effects (see Methods).

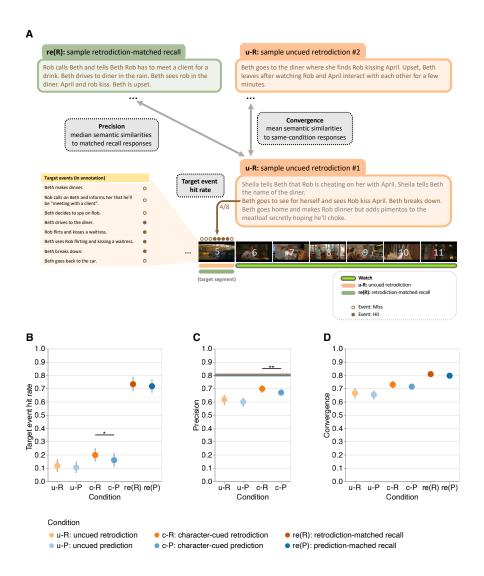


Figure 3: Retrodiction, prediction, and recall performance by experimental condition. A. Methods schematic. For each retrodiction, prediction, and recall response, we calculated the hit rate for events in the target segment, the response precision (see Methods), and the response convergence across participants (see Methods). B. Target event hit rate. Mean proportions of target events that were contained in participants' responses, for each response type, averaged across target segments. C. Response precision. Mean precisions of participants' responses, for each response type, averaged across target segments. The horizontal lines denote the mean pairwise semantic similarities (see Methods) across recall responses (re(R): orange; re(P): blue). D. Response convergence. Mean (across-participant) convergence of participants' responses, for each response type, averaged across target segments. All panels: error bars denote bootstrapped 95% confidence intervals. Asterisks indicate significance in the (generalized) linear mixed models: * denotes p < 0.05 and ** denotes p < 0.01.

First we sought to validate a main effect of response type (i.e., uncued responses, character-171 cued responses, and recalls), irrespective of the temporal direction (retrodiction versus prediction). 172 Across these three types of responses, participants have access to increasing amounts of infor-173 mation about the target segment. Therefore, across these response types, we hypothesized that 174 participants' responses should become both more accurate and more convergent across individ-175 uals. Consistent with this hypothesis, participants' character-cued retrodictions and predictions 176 were associated with higher target event hit rates than uncued retrodictions and predictions (odds 177 ratio (OR): 2.65, Z = 4.24, p < 0.001, 95% confidence interval (CI): 1.69 to 4.16; Fig. 3B). These character-cued responses were also more precise (b = 0.13, t(18.1) = 9.43, p < 0.001, CI: 0.10 to 179 0.16; Fig. 3C) and convergent across individuals (b = 0.11, t(18.6) = 6.21, p < 0.001, CI: 0.07 to 0.15; Fig. 3D). Relative to character-cued responses, participants' recalls showed higher target event hit 181 rates (OR = 21.83, Z = 10.61, p < 0.001, CI: 12.35 to 38.59) and were more convergence across 182 individuals (b = 0.20, t(19.4) = 9.10, p < 0.001, CI: 0.16 to 0.25). These results are consistent with 183 the common-sense notion that access to more information about a target segment yields better 184 performance (i.e., higher hit rates, precision, and convergence across individuals). 185

Next we carried out a series of analyses specifically aimed at characterizing temporal direc-186 tion effects— i.e, the relative quality of retrodictions versus predictions across different types of 187 responses. We hoped that these analyses might provide insights into our central question about 188 whether inferences about the past and future are equally accurate. Across both uncued and 189 character-cued responses (Fig. 2), retrodictions had numerically higher hit rates than predictions 190 (Fig. 3B). However, these differences were only statistically reliable for character-cued responses 191 (uncued responses: OR = 1.17, Z = 0.35, p = 0.73, CI: 0.47 to 2.92; character-cued responses: OR = 192 1.93, Z = 2.15, p = 0.03, CI: 1.06 to 3.52). We observed a similar pattern of results for the precisions 193 of participants' responses (Fig. 3C). Specifically, their responses tended to be numerically more 194 precise for retrodictions versus predictions, but the differences were only statistically reliable for 195 character-cued responses (uncued responses: b = 0.03, t(20.9) = 1.09, p = 0.29, CI: -0.03 to 0.10; character-cued responses: b = 0.06, t(20.8) = 3.01, p = 0.007, CI: 0.02 to 0.11). We also consistently 197 observed numerically higher convergence across participants for retrodictions versus predictions

(Fig. 3D), but neither of these differences were statistically reliable (uncued responses: b = 0.03, t(17.9) = 0.75, p = 0.46, CI: -0.05 to 0.11; character-cued responses: b = 0.04, t(17.4) = 1.46, p = 0.16, 200 CI: -0.02 to 0.09). Taken together, these results suggest that participants are generally better at 201 making retrodictions than predictions. We also verified that this was not solely a consequence of 202 how participants' memory performance might have been affected by watching different segments 203 (or making different responses to other segments) across conditions by comparing recall responses 204 in the retrodiction-matched recall (re(R)) and prediction-matched recall (re(P)) conditions. Recall 205 performance was similar in both conditions (target event hit rate: OR = 1.12, Z = 1.07, p = 0.29, CI: 0.91 to 1.39; convergence: b = 0.03, t(19.3) = 1.89, p = 0.07, CI: 0.00 to 0.07). 207

208

209

210

211

212

213

214

216

217

218

219

220

221

222

223

224

225

The above analyses were focused solely on the target segment (i.e., retrodiction of segment nafter watching segments (n + 1)...11, or prediction of segment n after watching segments 1...(n - 1). We wondered whether participants' responses might also contain longer-range information about preceding or proceeding events. In order to carry out this analysis properly, we reasoned that participants might reference past or future events that were implied to have occurred offscreen, but not explicitly shown onscreen. For example, a character in location A during one scene might appear in location B during the immediately following scene. Although it wasn't shown onscreen, we can infer that the character traveled between locations A and B sometime between the time intervals separating the scenes (Bordwell, 2008). In all, we manually identified a set of 74 implicit offscreen events that were implied to have occurred given what was (explicitly) depicted onscreen (Fig. 4A), plus one additional partial event and one additional summary event. We defined the just-watched segment as having a lag of 0. We assigned the target segment of a participant's retrodiction or prediction (i.e., the immediately preceding or proceeding segment) a lag of -1 or +1, respectively. The segment following the next was assigned a lag of 2, and so on. We tagged offscreen events using half steps. For example, an offscreen event that occurred after the prior segment but before the just-watched segment would be assigned a lag of -0.5.

Because there is no "ground truth" number of offscreen events, we could not compute the hit rates for offscreen events. Instead, we counted up the absolute *number* of retrodicted or predicted events as a function of lag. In other words, given that the participant had just watched segment *i*,

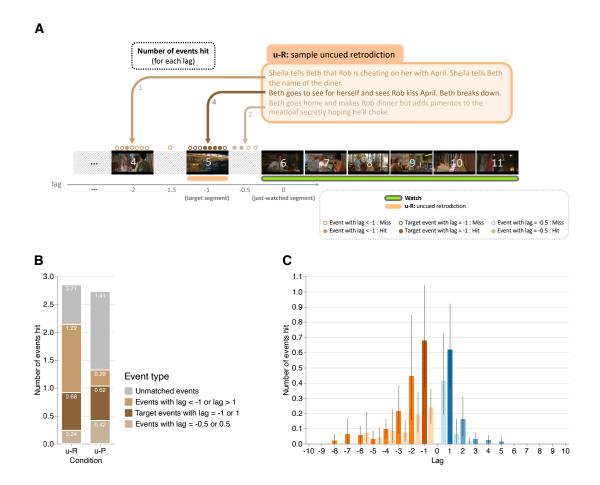


Figure 4: Retrodictions and predictions of temporally near and distant events. A. Illustration of annotation approach. For each uncued retrodiction and prediction response, we calculated the number of (retrodicted or predicted) events as a function of temporal distance from the target segment, or lag. Onscreen (explicit) events are tagged using integer-valued lags, whereas offscreen (implicit) events are tagged using half-step lags (± 0.5 , ± 1.5 , etc.). B. Number of events hit in participants' uncued retrodictions and predictions for each event type. Here we separated events we identified in participants' responses according to whether they occurred in the target segment (lags of ± 1), during the interval between the target segment and the just-watched segment (lags of ± 0.5), at longer temporal distances (|lag| > 1), or were incorrect (unmatched with any past or future events in the narrative). The counts displayed in the panel are averaged across just-watched segments. C. Number of events hit as a function of temporal distance. Here the (across-segment) mean numbers of events hit in participants' uncued retrodictions (orange) and predictions (blue) are displayed as a function of temporal distance to the just-watched segment (lag). Error bars denote bootstrapped 95% confidence intervals. Colors denote temporal direction (orange: past; blue: future) and distance (darker shading: onscreen events from segments adjacent to the target segment; lighter shading: offscreen events).

we asked how many events from segment i + lag they retrodicted or predicted, on average, given that they were aiming to retrodict or predict events at lags of ±1. We also counted the numbers of 228 unmatched events in participants' responses that did not correspond to any events in the relevant 229 segments of the narrative. We focused specifically on uncued retrodictions and predictions, which 230 we hypothesized would provide the cleanest characterizations of participants' initial estimates of 231 the unobserved past and future (i.e., without potential biases introduced by additional character 232 information, as in the character-cued responses). The numbers of uncued retrodicted and predicted 233 target (lag = ± 1) events were not reliably different (OR = 0.92, Z = -0.15, p = 0.88, CI: 0.30 to 2.84). In other words, uncued retrodictions and predictions over short timescales did not exhibit reliable 235 asymmetries. However, when retrodicting, participants mentioned events from the distant past 236 (lag < -1) more often than participants predicted events from the distant future (lag > 1; OR =237 9.10, Z = 3.80, p < 0.001, CI: 2.92 to 28.39; Fig. 4B, C; for results from the character-cued conditions, 238 see Fig. S2). Despite this asymmetry in the accuracies of participants' long-range retrodictions 239 versus predictions, there were no reliable differences in the *numbers* of uncued retrodicted versus 240 predicted events (across all lags; OR = 1.05, Z = 0.75, p = 0.45, CI: 0.93 to 1.18). Nor did we find any 241 reliable differences in the numbers of offscreen events immediately before or after the just-watched 242 segment ($lag = \pm 0.5$; OR = 0.75, Z = -0.36, p = 0.72, CI: 0.15 to 3.59). The apparent discrepancy between participants' asymmetric accuracy but symmetric event counts was due to participants' 244 tendencies to reference "unmatched" events (i.e., events that did not correspond to any explicit or implicit event in the story) more in their predictions than retrodictions (OR = 0.36, Z = -4.53, 246 p < 0.001, CI: 0.23 to 0.56). We confirmed that the retrodiction advantage held when controlling 247 for absolute lag (OR = 34.31, Z = 3.28, p = 0.001, CI: 4.16 to 283.20), for onscreen events alone (OR 248 = 47.54, Z = 3.74, p < 0.001, CI: 6.27 to 360.60), and marginally for offscreen events alone (OR = 249 24.76, Z = 1.71, p = 0.09, CI: 0.63 to 975.27). Taken together, these analyses show that (in generating 250 uncued responses) participants tend to reach "further" into the unobserved past, and with greater 251 accuracy, than the unobserved future.

What might be driving participants to retrodict further and more accurately into the unobserved past, compared with their predictions of the unobserved future? By inspecting the video

253

content, we noticed that characters in the television show frequently referenced both past events and (planned or predicted) future events in their spoken conversations. We wondered whether the 256 characters' references might show temporal asymmetries that might explain participants' behav-257 iors. Across all of the characters' conversations, and across all of the video segments, we manually 258 identified a total of 82 references to past or future events (i.e., that occurred onscreen or offscreen 259 before or after the events depicted in the current segment; Fig. 5A, S3A). Characters tended to 260 reference the past (52 references) more than the future (30 references), consistent with previous 261 work (Demiray et al., 2018). References to the past were also skewed to more temporally distant events compared with references to the future (Figs. 5B, S3B). These observations indicate that the 263 characters in the stimulus display a preference for the past (versus future) in their conversations. Might this asymmetry be driving the asymmetries in participants' retrodictions versus predictions? 265 Controlling for temporal distance (lag), past and future events that story characters referenced 266 in their conversations were associated with higher hit rates than unreferenced events (uncued 267 retrodiction: OR = 12.70, Z = 10.94, p < 0.001, CI: 8.06 to 20.03; uncued prediction: OR = 8.29, 268 Z = 6.83, p < 0.001, CI: 4.52 to 15.20; Fig. 5E). This indicates that participants' responses are at least 269 partially influenced by the characters' conversations. To estimate the contributions of characters' 270 references on hit rates, we computed the difference in hit rates between all events (which comprised both referenced and unreferenced events) and unreferenced events, as a function of lag. These 272 differences exhibited a temporal asymmetry in favor of retrodiction (Fig. 5C). This indicates that the 273 asymmetries in participants' retrodictions versus predictions are also at least partially influenced by 274 the characters' conversations. However, these temporal asymmetries in participants' retrodictions 275 and predictions persisted even for events that characters never referenced in their conversations 276 (hit rates of uncued retrodicted versus predicted unreferenced events: OR = 2.00, Z = 2.40, p = 0.02, 277 CI: 1.14 to 3.51; Fig. 5D). When we further separated the unreferenced events into onscreen events 278 and offscreen events, we found that these asymmetries held only for the onscreen events (onscreen: 279 OR = 2.65, Z = 2.59, p = 0.01, CI: 1.27 to 5.54; offscreen: OR = 1.50, Z = 0.91, p = 0.36, CI: 0.63 to 3.62). Taken together, these analyses suggest that asymmetries in the number of references 281 characters make to past and future events partially (but not entirely) explain why participants tend

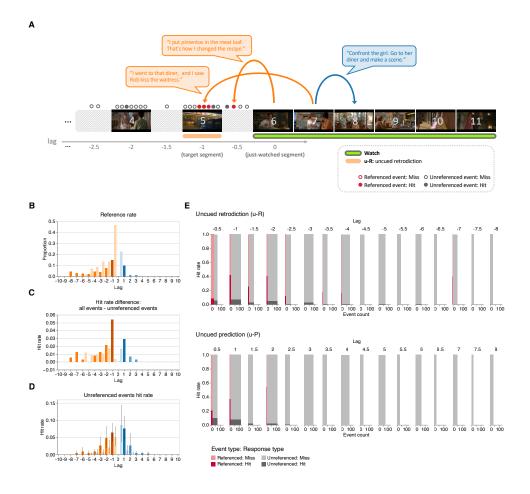


Figure 5: Characters' references drive participants' retrodiction and prediction performance. A. Illustration of annotation approach. We manually annotated references to events in past or future segments in characters' spoken conversations. We matched each such reference with its corresponding storyline event (and its corresponding segment number for onscreen events, or half-step segment number for offscreen events). We then tracked the hit rate separately for referenced versus unreferenced events in participants' uncued retrodictions and predictions. B. Reference rate as a function of lag. Across all possible just-watched segments (lag 0), the bar heights denote the average proportions of events referenced in other past (orange, negative lags) or future (blue, positive lags) segments. C. Difference in hit rates between all events and unreferenced events. To highlight the effect of characters' references to past and future events on participants' retrodictions and predictions, here we display the difference in across-segment mean hit rates between all events and unreferenced events, as a function of temporal distance (lag) to the just-watched segment. D. Hit rates for unreferenced events. The average response hit rates for unreferenced events are displayed as a function of temporal distance to the just-watched segment. Error bars denote bootstrapped 95% confidence intervals. Panels B-D: colors are described in the Figure 4 caption. E. Hit rates and counts of referenced and unreferenced events. As a function of temporal distance to the just-watched segment, the sub-panels display the across-segment mean numbers (x-axes) and hit rates (y-axes) of referenced (red) and unreferenced (gray) events that participants hit (darker shading) or missed (lighter shading) in their uncued retrodictions (top sub-panel) and uncued predictions (bottom sub-panel).

to retrodict the past further and more accurately than they predict the future.

If characters' direct references cannot fully account for the temporal asymmetry in retrodicting the unobserved past versus predicting the unobserved future, what other factors might explain this phenomenon? The results above indicate that characters' references to specific unobserved events in the past or future boost participants' estimates of these events. But might characters' references have other effects on participants' responses *beyond* the referenced events? For example, real-world experiences and events in realistic narratives are often characterized by temporal autocorrelations (i.e., what is "happening now" will likely relate to what happens "a moment from now," and so on). Real-world experiences and realistic narratives are also often structured into "schemas" whereby experiences unfold according to a predictable pattern or formula that characterizes a particular situation, such as going to a restaurant or catching a flight at the airport (Baldassano et al., 2018). If there are associations or temporal dependencies between temporally nearby events in the television show participants watched, participants might be able to pick up on these patterns in forming their responses. This would be reflected in an inference "boost" for events that were nearby in time to events that characters referred to in their conversations, in addition to the referenced events themselves (Fig. 6A).

Because characters tended to refer to past events more often than future events, the proportions of unreferenced events that were adjacent to referenced events should show a similar temporal asymmetry in favor of the past. We tested this intuition by computing the proportions of unreferenced events in the stimulus that were temporally adjacent to past or future events referenced by the characters during a given segment. Here we defined *temporally adjacent* as any event within an absolute lag of one relative to a referenced onscreen event, or within an absolute lag of 0.5 to a referenced offscreen event. We also defined *remaining* events as unreferenced events that were not temporally adjacent to any referenced events. As shown in Figure 6B, we observed higher proportions of unreferenced past than future events that were temporally adjacent to referenced events. Further, these reference-adjacent events had higher hit rates than remaining events after controlling for absolute lag (uncued retrodiction: OR = 7.15, Z = 2.40, p = 0.02, CI: 1.44 to 35.58; uncued prediction: OR = 3.11, Z = 2.30, p = 0.02, CI: 1.18 to 8.21; Fig. 6E). To estimate the contributions

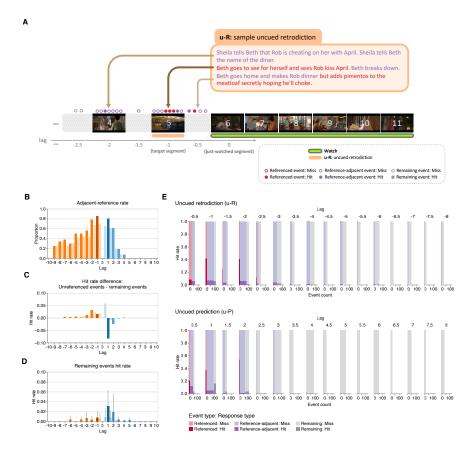


Figure 6: Reference-adjacent events are associated with higher hit rates. A. Illustration of annotation approach. We extended the annotation procedure depicted in Figure 5A to also label unreferenced events that were either temporally adjacent to (i.e., immediately preceding or proceeding) a referenced event (referenceadjacent events) or not (remaining events). B. Adjacent reference rate for unreferenced events as a function of lag. Across all possible just-watched segments (lag 0), the bar heights denote the average proportion of unreferenced events in other past (orange, negative lags) or future (blue, positive lags) segments that were temporally adjacent to any referenced event. C. Difference in hit rates between unreferenced events and remaining events. To highlight the effect of reference adjacency on retrodiction and prediction of unreferenced events, here we display the difference in across-segment mean hit rates between unreferenced events and remaining events, as a function of temporal distance (lag) to the just-watched segment. D. Hit rates for remaining events. The across-segment mean response hit rates for unreferenced events that were not temporally adjacent to any referenced events are displayed as a function of temporal distance to the justwatched segment. Error bars denote bootstrapped 95% confidence intervals. Panels B-D: colors are described in the Figure 4 caption. E. Hit rates and counts of referenced, reference-adjacent, and remaining events. As a function of temporal distance to the just-watched segment, the sub-panels display the numbers (x-axes) and proportions (y-axes) of referenced (red), reference-adjacent (purple), and remaining (gray) events that participants hit (darker shading) or missed (lighter shading) in their uncued retrodictions (top sub-panel) and uncued predictions (bottom sub-panel).

of reference adjacency on hit rates, we computed the difference in hit rates between unreferenced events (which comprised both reference-adjacent and remaining events) and remaining events, as a function of lag. These differences exhibited a temporal asymmetry in favor of retrodiction. This suggests that reference-adjacent events also contribute to participants' retrodiction advantage. Remaining events did *not* exhibit a reliable temporal asymmetry (OR = 0.75, Z = 0.33, p = 0.74, CI: 0.14 to 4.08; Fig. 6D), suggesting that, after accounting for temporal adjacency, character's references to past and future events can explain participants' retrodiction advantage.

The preceding analyses show that when characters reference past or future events, those refer-318 enced events, and other events that are temporally adjacent to the referenced events, are more likely 319 to be retrodicted and predicted. In other words, referring to a past or future event in conversation leads to a "boost" in that event's hit rate. We wondered whether this boost was bi-directional. In 321 particular: when a character refers (during a referring event) to another event (i.e., the referenced 322 event), does this boost only the referenced event's hit rate, or does the referring event also receive 323 a boost? We labeled each event as a "referring event," a "referenced event," or a "other event" 324 (i.e., not referring or referenced; Fig. 7A, B). We limited our analysis to references to onscreen 325 (explicit) events. Consistent with our analysis of the proportions of referenced events (Fig. 5B), the 326 proportions of referring events exhibited a forward temporal asymmetry (Fig. 7C). Controlling for 327 absolute lag, we found that referring events were associated with lower hit rates than referenced 328 events (uncued retrodiction: OR = 0.03, Z = -4.81, p < 0.001, CI: 0.01 to 0.11; uncued prediction: 329 OR = 0.04, Z = -5.84, p < 0.001, CI: 0.01 to 0.12; Fig. 7D) and had no reliable differences in hit 330 rates compared with other events (uncued retrodiction: OR = 0.37, Z = -1.46, p = 0.15, CI: 0.10 to 331 1.41; uncued prediction: OR = 2.16, Z = 1.68, p = 0.09, CI: 0.88 to 5.30). This indicates that only 332 referenced events received a hit rate boost (relative to other events), suggesting that the retrodictive 333 and predictive benefits of references are directed (i.e., asymmetric). 334



Figure 7: Referenced events are associated with higher hit rates, but referring events are not. A. Illustration of annotation approach. We extended the annotation procedure depicted in Figure 5A to also label which events *contained* references to events in other segments. **B. Referenced versus referring events.** During event *i*, when a character makes a reference to another event (*j*), we define *i* as the *referring* event and *j* as the *referenced* event. **C. Referring rate as a function of lag.** Across all possible just-watched segments (lag 0), the bar heights denote the across-segment mean proportions of events containing references to events in other past (orange, negative lags) or future (blue, positive lags) segments. The bar colors are described in the Figure 4 caption. **D. Hit rates and counts of referenced, referring, and other events.** As a function of temporal distance to the just-watched segment, the sub-panels display the numbers (*x*-axes) and hit rates (*y*-axes) of referenced (red), referring (green), and other (gray) events that participants hit (darker shading) or missed (lighter shading) in their uncued retrodictions (top sub-panel) and uncued predictions (bottom sub-panel).

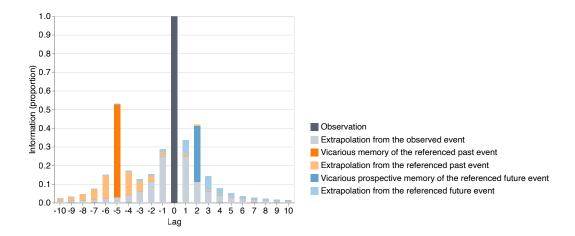


Figure 8: How much information about the past and future can be inferred by observing the present? By definition, let us say that the present moment (lag 0) contains all information about itself (dark gray). Given learned statistical regularities, one might extrapolate from the present moment into the past or future (light gray). As illustrated in this schematic, the information contained in the present about other moments in time falls off with absolute lag. This falloff is approximately time-symmetric. References in the present to past events (dark orange) or future events (dark blue) provide additional information about those referenced moments in time, beyond what could be inferred solely from statistical regularities. This additional information about those referenced moments can also be extrapolated to other moments that are temporally nearby to *them* (light orange and blue).

Discussion

We asked participants to watch sequences of movie segments from a character-driven television drama and then either retrodict what had happened prior to a just-watched segment, predict what would happen next, or recall what they had just watched. We found that participants tended to more accurately and more readily retrodict the unobserved past than predict the unobserved future. We traced this temporal asymmetry to (a) characters' tendencies to refer to past events more than future events in their ongoing conversations, and (b) associations between temporally proximal events (Fig. 8). Essentially, associations between temporally proximal events serve to enhance asymmetries in inferences driven by conversational references (light orange and blue bars in Fig. 8). Our findings show that other peoples' psychological arrows of time can affect external observers' inferences about the unobserved past and future.

When people communicate through language or other observable behaviors, they can transmit their knowledge and memories to others (Hirst and Echterhoff, 2012; Mahr and Csibra, 2018; Dessalles, 2007; Zadbood et al., 2017). A consequence of this sharing across people is that biases or limitations in one person's knowledge and memories may also be transmitted to external observers. Although people *can* communicate their intentions and future plans (i.e., information about their future), because people know *more* about their pasts than their futures, the knowledge transmitted to observers is inherently biased in favor of the past (Fig. 8; Demiray et al., 2018). Since observers leverage communicated knowledge to reconstruct the unobserved past and future, this explains why observers' inferences about observed people's lives also favor the past.

People's knowledge asymmetries are not always directly observable. For example, in a conversation where someone talks exclusively about their future plans, a passive observer might gain more insight into the speaker's unobserved future than their unobserved past. However, because the speaker is also guided by their own psychological arrow of time, the "upper limit" of knowledge about their past is still higher than that of their future. Therefore, after accounting for knowledge that *could* be revealed through active participation in the conversation, the seemingly future-biased conversation masks an underlying knowledge asymmetry in favor of the past. This hypothesized "unmasking" effect of interaction implies that the influence of other people's psychological arrows of time should be more robust when the receiver is an active participant in the conversation. Other social dimensions, such as trust, motivation or level of engagement, personal goals, and beliefs, might serve to modulate the effective "gain" of the communication channel— i.e., how much the speaker's knowledge influences the observer's knowledge.

In typical statistical sequences used in laboratory studies, there is no temporal asymmetry, either theoretically (Cover, 1994; Bialek et al., 2001; Ellison et al., 2009), or empirically (Jones and Pashler, 2007). What makes narratives and real-world event sequences time-asymmetric? Of course there are many superficial differences between simple laboratory-manufactured sequences and real-world experiences. As one example, real-world experiences often involve other people who have their own memories and goals. At a deeper level, however, are our subjective experiences essentially more complicated versions of laboratory-manufactured sequences? Or are there

fundamental differences? One possibility is that real-life event sequences are not stationary (i.e., not in equilibrium, Cover, 1994). For example, real-life events might start from a special initial condition (Albert, 2000; Feynman, 1965; Cover, 1994) and proceed through a series of transitions from more-ordered to less-ordered states, thus exhibiting an arrow time. When we retrodict, it is 377 possible that we only consider possible past events that are compatible with the highly-ordered special initial state (Carroll, 2010, 2016). For example, when we see a broken egg we might infer that the egg had been intact at some point in the past. But it would be difficult to guess at what states or forms the broken egg might take in the future (Carroll, 2010, 2016). In other words, the procession from order to disorder might result in better retrodiction performance compared with that of (implicitly less-restricted) prediction tasks. The special initial state might also explain why we remember the past, but not the future. Some recent work suggests that the psychological arrow of time might be explained by a related concept in the statistical physics literature, termed the "thermodynamic" arrow of time (Mlodinow and Brun, 2014; Rovelli, 2022). However, the relation between the thermodynamic and psychological arrows of time is still under debate (Gołosz, 2021; Hemmo and Shenker, 2019). 388

375

376

378

379

380

382

384

385

386

387

389

390

391

392

393

394

395

396

397

398

400

In our study, we explicitly designed participants' experiences such that both the past and future were unobserved. How representative is this scenario of everyday life? For example, we might try to speculate about the unobserved future when making plans or goals, but when might we encounter situations where the past is unobserved but still useful for us to speculate about? Real-life events have long-range dependencies. In general, because the future depends on what happened in the past, discovering or estimating information about the unobserved past can help us form predictions about the future. We illustrate this point in Figure 8 by showing that the additional information contributed by a referenced past event can also extend into the future (light orange bars at lags > 0). This might explain why humans devote substantial effort and resources to attempting to figure out what happened in the unobserved past: history, anthropology, geology, detective and forensic science, and other related fields are each primarily focused on understanding, retrodicting, or reconstructing unobserved past events.

Methods

Participants

A total of 36 participants (25 female, mean age 21.47 years, range 19–50 years) were recruited from
the Dartmouth College community. All participants had self-reported normal or corrected-tonormal vision, hearing, and memory, and had not watched any episodes of *Why Women Kill* before
the experiment. Participants gave written consent to enroll in the study under a protocol approved
by the Committee for the Protection of Human Subjects at Dartmouth College. Participants received
course credit or monetary compensation for their time. Two participants completed only the first
half of the study and one participant's data from the second half of their testing session was lost
due to a technical error. All available data were used in the analyses.

411 Stimuli

The stimulus used in the study were segments of the CBS television series Why Women Kill Season 1. The TV series contained three distinct storylines depicting three women's marital relationships. 413 The three storylines, which took place in the 1960s, 1980s, and 2019, were shown in an interleaved fashion in the original episodes. The first 11 segments from the 1960s and 1980s storylines, across 415 the first and second episodes, were used in our study. Segments were divided based on major 416 scene cuts, which primarily corresponded to storyline shifts in the original episodes. The mean 417 length of the segments was 2.05 min (range 0.97–3.87 min). We chose this TV series based on 418 its strictly linear storytelling (within each storyline) and its realistic settings where most events 419 depicted everyday life. The plots were focused on the main characters (Beth in storyline 1 and 420 Simone in storyline 2), who were present in all the segments in the corresponding storylines. 421

Task design and procedure

Our experimental paradigm was divided across two testing sessions. In each session, participants performed a sequence of tasks on segments from one storyline (Fig. 2). For each storyline, there

were four different task sequences: two forward chronological order sequences and two backward chronological order sequences. Participants completed one task sequence in forward chronological 426 order for one storyline, and one in backward chronological order for the other storyline. The order 427 of the two sessions (forward chronological order sequence first or backward chronological order 428 sequence first), and the pairing of task sequences with storylines, were counterbalanced across 429 participants. 430

431

433

435

436

437

438

439

440

444

445

446

448

449

451

Tasks in each sequence alternated between watching, recall, and retrodiction or prediction, with the specific order of tasks differing across the four sequences. For example, in sequence A1, participants first watched segment 1, followed by an immediate recall of segment 1. Then they predicted what would happen in segment 2 (first uncued and then character-cued). Participants then watched segment 3 and recalled segment 3. After that, participants guessed what happened in segment 2 again, which we termed "updated prediction". Then they watched segment 2, recalled segment 2, and so on as depicted in Figure 2. This procedure was repeated to cover all possible segments. We also note several edge cases at the start and end of the narrative sequences. Since no segments precede the first segment, participants could never make "prediction" responses with the first segment as their target. For analogous reasons, participants never made "retrodiction" responses with the last segment as their target. Another edge case occurred in task sequences B2 and A2 (Fig. 2). In the A1 and A2 sequences, participants experience the narrative in the 442 original (forward) order, predicting one segment ahead along the way. In the B1 and B2 sequences, participants experience the narrative in the reverse order, retrodicting one segment ahead along the way. However, because A2 and B2 are offset from A1 and B2 by one segment, the initial A2 responses are retrodictions, and the initial B2 responses are predictions (i.e., they conflict with the temporal directions of the remaining responses in those conditions). We therefore excluded from our analysis those initial retrodiction responses from the A2 condition, and the initial prediction responses from the B2 condition.

Before watching each segment, participants were given the following task instructions. After watching the video, participants were instructed to type their responses (retrodiction, prediction, or recall) in 1-4 sentences. Participants were also asked to specify the characters' names in their

responses, i.e., avoiding use of characters' pronouns. For the recall task, the names of the characters in the recall segment were displayed, and participants were asked to summarize the major plot 454 points in the present tense. For the retrodiction and prediction tasks, participants were instructed 455 to retrodict or predict the major plot points of the segment (also in the present tense), as though 456 they had watched the segment and were writing a plot synopsis. They were also instructed to 457 avoid speculation words (e.g., "I think Beth will..."). For the uncued retrodiction and prediction 458 tasks, participants made retrodictions or predictions without any cues provided, so they had to 459 guess which of the characters would be present in the segment. For character-cued retrodictions and predictions, the characters in the target segment were revealed on the screen, alongside 461 participants' previous responses. Participants were instructed to include or incorporate those characters into their character-cued responses, if their previous responses did not contain all the 463 characters provided. They were also told that the characters were not necessarily listed in their 464 order of appearance in the segment, and that only the main characters would be given. Also, the 465 characters given did not necessarily interact with each other in that segment, and they could appear 466 in successive events in that segment. If participants' previous responses included all the characters 467 given, then they could directly proceed to the next task without updating their responses. For 468 all of the prediction and retrodiction tasks, participants were instructed to provide at least one response, but they were given the opportunity enter up to three responses if they felt that multiple 470 possibilities were more or less equally likely. Each response (including recall) was followed by a confidence rating on a 1-5 point scale. However, these confidence data were not analyzed in the 472 present study. 473

Before their first testing session, participants were given a practice session, where they watched the first segment of storyline 3 followed by a recall trial, an uncued prediction trial, and a charactercued prediction trial. Participants' responses were checked by the experimenter to ensure compliance with the instructions. To provide participants with sufficient background information about the storyline (especially for the backward chronological sequences), at the beginning of each session, participants were shown the time, location, and the main characters (with pictures) of the storyline. The first session was approximately 1.5 h long and the second session was approximately

474

475

476

477

479

1 h long. We allowed participants, at their own discretion and convenience, to sign up for two consecutive testing time-slots (i.e., with their testing sessions occurring in immediate succession), or for testing sessions on two different days. The mean inter-session interval was 0.73 days (range: 0–4 days). The experiment was conducted in a sound- and light-attenuated testing room. Videos were displayed using a 27-inch iMac desktop computer (resolution: 5120 × 2880) and sound was presented using the iMac's built-in speakers. The experiment was implemented using jsPsych (de Leeuw, 2015) and JATOS (Lange et al., 2015).

Video annotation

Events in the first 11 segments of the two storylines were identified by the first author (X.X.), 489 corresponding to major plot points (total: 117; mean: 5.32 per segment; range 3-9). Additionally, 490 74 offscreen events were identified. Of these 74 offscreen events, 43 events were identified from 491 references in conversations during onscreen events. Another 16 events were identified based on characters' implied movements and travels. For example, if in segment 1 character A was in place 493 A and in segment 2 she was in place B, then the transit from place A to B for character A would be identified as an offscreen event. The remaining 15 offscreen events were identified based on logical 495 inferences. For example, if a photograph was shown in an onscreen event (but not the act of the photograph being taken), then the action that someone took the photograph would be identified 497 as an offscreen event. Offscreen events always occurred between two contiguous segments, or 498 before the first segment. The purpose of identifying offscreen events was to match participants' 499 responses to video events; thus our identification of these offscreen events was not intended to be 500 exhaustive. 501

Response analyses

Participants' retrodiction, prediction, and recall responses were minimally processed to correct obvious typos (e.g., in characters' names) and remove speculation descriptions (e.g., "I predict that..."). All responses were manually coded and matched to events from the video annotations.

Retrodiction and prediction responses were coded by two coders (X.X. and Z.Z.). Recall responses were coded by one coder (X.X.). While most responses were clearly identifiable as either matching 507 specific storyline events or as not matching any storyline events, several ambiguous cases arose. 508 First, some responses combined or summarized over several (distinct) storyline events. Second, 509 some responses lacked any specific detail (e.g., "character A and B talk" without describing the 510 specific topic(s) of conversation or providing other relevant details). Based on participants' re-511 sponses, in addition to the original 117 onscreen events and 74 offscreen events, we added 25 new 512 events (23 onscreen, 2 offscreen) that either summarized across several events or partially matched the annotated events. Whereas the original events were each assigned a value of one point, we 514 assigned these additional events a half point. This point system enabled us to directly match events in participants' responses to the annotated events. In our analyses of retrodictions, predictions, 516 and recalls, we added up the number of points earned for each response to estimate participants' 517 event hit rates. 518

We coded only the first retrodiction or prediction response in each trial. For these responses, we also only considered storyline events that were in the same temporal direction as the target segment. For example, if a participant was asked to retrodict what happened in segment n, only events from segments 1...n were considered in our analysis. When coding recall responses, we considered only events from the target segment.

519

520

521

523

525

526

527

528

520

530

532

An additional ambiguous case arose in one participant's responses pertaining to segment 12, storyline 2, whereby the participant correctly identified an onscreen event that had not been included in our original annotations. To account for this participant's response, we retroactively added that event to our annotations of that segment. We also identified and counted unmatched events in participants' responses (i.e., events that did not match any annotated events). Cases where the two coders' independent scoring disagreed were resolved through discussions between the two coders.

To estimate the semantic similarities between pairs of responses, we first transformed each response into a 512-dimensional vector (embedding) using the Universal Sentence Encoder (Transformer USE, Cer et al., 2018). We defined *similarity* as the cosine of the angle formed by the

responses' vectors. Following Heusser et al. (2021), we defined the *precision* of participants' responses as the median similarity between that response's vector and the embedding vectors for all other participants' recalls of the target segment. We defined the *convergence* of a given response as the mean similarity between that response's vector and all other participants' responses to the corresponding segment, in the same condition. To compute these median or mean similarities we first applied the Fisher *z*-transformation to the similarity values, then took the median or mean of the *z*-transformed similarities, and finally applied the inverse *z*-transformation to obtain the precision or convergence score.

To test the validity and reliability of the USE embeddings, we performed a classification analysis of recall responses using a leave-one-out approach. For each recall response, we calculated its semantic similarity with all other recall responses for the same storyline. We took the segment with the highest median semantic similarity (to the recall response) as the "predicted" segment. Across all responses, the predicted segments matched the true recalled segments' labels 98.6% of the time (1088 out of 1103 predictions; chance level: 9%).

548 Reference coding

535

536

537

538

539

540

542

544

545

559

Two coders (X.X. and Z.Z.) identified character dialogues in the narrative that referred to past events or future (onscreen or offscreen) events. Only references to events that occurred in a different 550 segment were included in this tagging procedure. For each reference, the source (referring) segment 551 and the referred event number were recorded. A total of 82 references were identified. Of these, 30 552 referred to onscreen events and 52 referred to offscreen events. For these referenced events, their 553 corresponding summary events or partial events were also labelled as referenced. In instances where the coders disagreed about a given tag, disagreements were resolved through discussions 555 between the two coders. In our analyses, each storyline event was coded according to whether 556 or not it had been referenced in the segment(s) that the participant had viewed thus far in the 557 experiment.

In principle, a given event could receive multiple labels. For example, during event *A*, a character might speak about another event, *B*, during which a reference to a third event (*C*) was

made. In this scenario, event B could be both a "referring event" ($B \to C$) and a referenced event ($A \to B$). In practice, however, this scenario was quite rare, accounting for only one out of a total of 30 onscreen events.

564 Statistical analysis

We used (generalized) linear mixed models to analyze the hit rates and numbers of events retrodicted, predicted, and recalled, as well as the precisions and convergences of participants' responses.

Our models were implemented in R using the afex package. We carried out comparisons or contrasts, and extracted *p*-values, using the emmeans package. Participants and stimuli (e.g., segment
identity) were modeled as crossed random effects (as specified below). Random effects were selected as the maximal structure that allowed model convergence. All of our statistical tests were
two-sided.

For our tests of the target event hit rates across four levels (uncued, character-cued, updated, and recall; Fig. 3B), we fit a generalized linear mixed model with a binomial link function:

```
cbind(thp, ttp - thp) ~ direction * level * seg_cnt * storyline +

(direction * level | target) +

(direction * level * seg_cnt | subject)
```

where thp was the number of points hit for the target segment, ttp was the total number of points for the target segment (from its annotations), direction was either retrodiction or prediction, level 578 had four levels (uncued, character-cued, updated, and recall), seg_cnt represented the number of 579 segments in the storyline that had been watched (1-10, centered), storyline had two levels (1 580 or 2), and target had 22 levels according to the identity of the target segment. For our tests of 581 precision and convergence (Fig. 3C, D), we fit linear mixed models using the same formula. To test the effect of direction (retrodiction or prediction) on target event hit rates, precision, and 583 convergence, we fit a (generalized) linear mixed model separately for each of the three levels 584 (uncued, character-cued, and recall). 585

For our tests comparing the numbers of hits for different types of events (Fig. 4B), we fit

generalized linear mixed models using the same formula, but with a Poisson link function. For these models, we manually doubled the point counts to ensure that half points were mapped onto integers, ensuring compatibility with the Poisson link function.

For our analyses of the numbers of events hit, controlling for lag (Fig. 4C), we fit a generalized linear mixed model with a Poisson link function:

```
hp_lag ~ direction * full_stp * lag * storyline +

(direction | base_seg) + (1 | base_seg_pair) +

(direction * full_stp * lag * storyline | subject)
```

where hp_lag is the number of "points" earned (for each lag) in each trial (we manually doubled
the point counts to ensure that half points were mapped onto integers, for compatibility with the
Poisson link function), full_stp denoted whether the given events (of the given lag) were onscreen
(i.e., full step) or offscreen (i.e., half step), lag denotes the (centered) absolute lag, base_seg denotes
the identity of the just-watched segment (22 levels), and base_seg_pair denotes the pairing of the
just-watched segment and the segment at each lag (440 levels).

For our analyses of the proportions of events hit for referenced versus unreferenced events (Fig. 5D, E), we fit a generalized linear model with a binomial link function:

```
cbind(hp_lag, tp_lag - hp_lag) ~ direction * reference * full_stp +

lag + (direction | base_seg) +

(1 | base_seg_pair) +

(direction * reference * full_stp + lag | subject)
```

where hp_lag denotes the number of earned hit points for each reference type (referenced or unreferenced) at each lag, tp_lag denotes the total number of possible hit points for each reference type at each lag, and the other variables adhered to the same notation used in the above formulas.

For our tests of the proportions of events hit for all three reference types (referenced, reference-

For our tests of the proportions of events hit for all three reference types (referenced, referenced adjacent, and remaining: Fig. 6D, E; or referenced, referring, and other: Fig. 7D), we fit a generalized linear mixed model using the same formula as above, but with three (rather than two) reference levels.

611

612

614 Code and data availability

- All of the code and data generated for the current manuscript are available online at:
- https://github.com/ContextLab/prediction-retrodiction-paper

References

- Albert, D. Z. (2000). Time and chance. Harvard University Press, Cambridge, Mass.
- Baldassano, C., Hasson, U., and Norman, K. A. (2018). Representation of real-world event schemas
- during narrative perception. *The Journal of Neuroscience*, 38(45):9689–9699.
- Bialek, W., Nemenman, I., and Tishby, N. (2001). Predictability, complexity, and learning. Neural
- 622 Computation, 13(11):2409–2463.
- Bordwell, D. (2008). Poetics of cinema, chapter Three dimensions of film narrative, pages 85–134.
- Routledge.
- Bower, G. H., Black, J. B., and Turner, T. J. (1979). Scripts in memory for text. Cognitive Psychology,
- 626 11(2):177–220.
- 627 Carroll, S. (2010). From eternity to here: the quest for the ultimate theory of time. Penguin.
- 628 Carroll, S. (2016). The big picture: on the origins of life, meaning, and the universe itself. Dutton.
- Cer, D., Yang, Y., Kong, S. Y., Hua, N., Limtiaco, N., John, R. S., Constant, N., Guajardo-Cespedes,
- M., Yuan, S., Tar, C., Sung, Y.-H., Strope, B., and Kurzweil, R. (2018). Universal sentence encoder.
- *arXiv*, 1803.11175.
- 632 Cover, T. M. (1994). Which processes satisfy the second law? In Halliwell, J. J., Pérez-Mercader,
- J., and Zurek, W. H., editors, Physical Origins of Time Asymmetry, pages 98-107. Cambridge
- University Press, Cambridge, UK.
- de Leeuw, J. R. (2015). jsPsych: A JavaScript library for creating behavioral experiments in a web
- browser. Behavior Research Methods, 47(1):1–12.

- Demiray, B., Mehl, M. R., and Martin, M. (2018). Conversational time travel: evidence of a retrospective bias in real life conversations. *Frontiers in Psychology*, 9:2160.
- Dessalles, J.-L. (2007). Storing events to retell them. Behavioral and Brain Sciences, 30(3):321–322.
- 640 Ellison, C. J., Mahoney, J. R., and Crutchfield, J. P. (2009). Prediction, retrodiction, and the amount of
- information stored in the present. Journal of Statistical Physics, 136(1005):doi.org/10.1007/s10955—
- 642 009–9808–z.
- Feynman, R. (1965). The character of physical law. MIT Press.
- Gołosz, J. (2021). Entropy and the direction of time. *Entropy*, 23(4):388.
- Hawking, S. W. (1985). Arrow of time in cosmology. *Physical Review D*, 32(10):2489–2495.
- Hemmo, M. and Shenker, O. (2019). The second law of thermodynamics and the psychological arrow of time. *The British Journal for the Philosophy of Science*.
- Heusser, A. C., Fitzpatrick, P. C., and Manning, J. R. (2021). Geometric models reveal behavioral
- and neural signatures of transforming naturalistic experiences into episodic memories. Nature
- 650 Human Behavior, 5:905–919.
- Hirst, W. and Echterhoff, G. (2012). Remembering in conversations: the social sharing and reshaping of memories. *Annual Review of Psychology*, 63(1):55–79.
- 653 Horwich, P. (1987). Asymmetries in time: problems in the philosophy of science. MIT Press.
- Jones, J. and Pashler, H. (2007). Is the mind inherently forward looking? comparing prediction and retrodiction. *Psychonomic Bulletin and Review*, 14(2):295–300.
- Koster-Hale, J. and Saxe, B. (2013). Theory of mind: A neural prediction problem. *Neuron*, 79(5):836–848.
- 658 Lange, K., Kühn, S., and Filevich, E. (2015). "Just Another Tool for Online Studies" (JATOS): an
- easy solution for setup and management of web servers supporting online studies. PLoS One,
- 660 10(6):e0130834.

- Maheu, M., Meyniel, F., and Dehaene, S. (2022). Rational arbitration between statistics and rules in human sequence processing. *Nature Human Behaviour*, pages 1–17.
- Mahr, J. B. and Csibra, G. (2018). Why do we remember? the communicative function of episodic memory. *Behavioral and Brain Sciences*, 41:e1.
- Mlodinow, L. and Brun, T. A. (2014). Relation between the psychological and thermodynamic arrows of time. *Physical Review E*, 89(5):052102.
- Radvansky, G. A. and Copeland, D. E. (2006). Walking through doorways causes forgetting: situation models and experienced space. *Memory and Cognition*, 34(5):1150–1156.
- Ranganath, C. and Ritchey, M. (2012). Two cortical systems for memory-guided behavior. *Nature Reviews Neuroscience*, 13:713–726.
- 671 Rovelli, C. (2022). Memory and entropy. *Entropy*, 24(8):1022.
- Tamir, D. I. and Thornton, M. A. (2018). Modeling the predictive social mind. *Trends in Cognitive*Sciences, 22(3):201–212.
- Zadbood, A., Chen, J., Leong, Y. C., Norman, K. A., and Hasson, U. (2017). How we transmit mem ories to other brains: constructing shared neural representations via communication. *Cerebral Cortex*, 27(10):4988–5000.
- Zwaan, R. A. and Radvansky, G. A. (1998). Situation models in language comprehension and
 memory. *Psychological Bulletin*, 123(2):162–185.

679 Acknowledgements

- We thank Luke Chang, Yi Fang, Paxton Fitzpatrick, Caroline Lee, Meghan Meyer, Lucy Owen, and
- 681 Kirsten Ziman for feedback and scientific discussions. Our work was supported in part by NSF
- 682 CAREER Award Number 2145172 to J.R.M. The content is solely the responsibility of the authors
- and does not necessarily represent the official views of our supporting organizations. The funders

had no role in study design, data collection and analysis, decision to publish, or preparation of the
 manuscript.

Author contributions

- 687 Conceptualization: X.X. and J.R.M.; Methodology: X.X. and J.R.M.; Software: X.X.; Analysis: X.X.
- and Z.Z.; Writing, Reviewing, and Editing: X.X., Z.Z., and J.R.M.; Supervision: J.R.M.

Competing interests

The authors declare no competing interests.