High-order dynamic neural correlations reflect naturalistic processing in humans

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5 Abstract

Our thoughts arise from coordinated activity patterns across our brain. We examined high-order dynamic correlations in functional neuroimaging data collect as human participants listened to different auditory stimuli varying in cognitive richness, along with an additional resting state condition. Our approach combines a kernel-based method for estimating the dynamic functional correlations that are similar (within task) across participants, along with a dimensionality reduction approach that enables us to efficiently compute high-order correlations in the data. We trained classifiers to decode the precise time, relative to the start of the stimulus, when a given neural pattern was recorded. We trained these classifiers using the neural activity timeseries, first-order dynamic correlations, and higher-order correlations (up to tenth-order correlations), and asked which types of features led to the highest decoding accuracy. We found that second-order correlations consistently yielded the highest decoding accuracy in all of the listening conditions of the experiment, whereas first-order correlations yielded the highest decoding accuracy at rest.

Introduction

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- The dynamics of the observable universe are meaningful in three respects. First, the behaviors of the *atomic*
- 20 units that exhibit those dynamics are highly interrelated. The actions of one unit typically have implications
- 21 for one or more other units. In other words, there is non-trivial correlational structure defining how different
- units interact with and relate to each other. Second, that correlational structure is hierarchical in the sense
- that it exists on many spatiotemporal scales. The way one group of units interacts may relate to how another
- 24 group of units interact, and the interactions between those groups may exhibit some rich structure. Third,
- the structure at each level of this correlational hierarchy changes from moment to moment, reflecting the
- ²⁶ "behavior" of the full system.
- These three properties (rich correlations, hierarchical organization, and dynamics) are major hallmarks
- of many complex systems. For example, within a single cell, the cellular components interact at many
- spatiotemporal scales, and those interactions change according to what that single cell is doing. Within a

single human brain, the individual neurons interact within each brain structure, and the structures interact to form complex networks. The interactions at each scale vary according to the functions our brains are carrying out. And within social groups, interactions at different scales (e.g., between individuals, family units, communities, etc.) vary over time according to changing goals and external constraints.

Although many systems exhibit rich dynamic correlations at many scales, a major challenge to studying 34 such patterns is that typically neither the correlations nor the hierarchical organizations of those correlations may be directly observed. Rather, these fundamental properties must be inferred indirectly by examining the observable parts of the system- e.g., the behaviors of the individual atomic units of that system. In 37 the Methods section, we propose a series of mathematical operations that may be used to recover dynamic correlations at a range of scales (i.e., orders of interaction). In the Results section, we demonstrate how our approach may be applied to multi-dimensional timeseries data: a synthetic dataset where the underlying dynamic correlations are known (we use this dataset to validate our approach), and a neuroimaging dataset comprising data collected as participants listened to a story (Simony et al., 2016). In different experimental conditions in the neuroimaging study, participants listened to altered versions of the story that varied in 43 cognitive richness: the intact story (fully engaging), a scrambled version of the story where the paragraphs 44 were presented in a randomized order (moderately engaging), a second scrambled condition where the words were presented in a random order (minimally engaging), and a "rest" condition where the participants did not listen to any version of the story (control condition). We use the neuroimaging dataset to examine 47 how higher-order structure in brain data varies as a function of the cognitive richness of the stimulus.

49 Methods

There are two basic steps to our approach (Fig. 2). In the first step, we take a number-of-timepoints (T) by number-of-features (F) matrix of observations (X) and we return a T by $\frac{F^2-F}{2}$ matrix of dynamic correlations (Y).

Here Y_0 describes, at each moment, how all of the features (columns of X) are inferred to be interacting. (Since the interactions are assumed to be non-recurrent and symmetric, only the upper triangle of the full correlation matrix is computed.) In the second step, we project Y_0 onto an F-dimensional space, resulting in a new T by F matrix Y_1 . Note that Y_1 contains information about the correlation dynamics present in X, but represented in a compressed number of dimensions. By repeatedly applying these two steps in sequence, we can examine and explore higher order dynamic correlations in X.

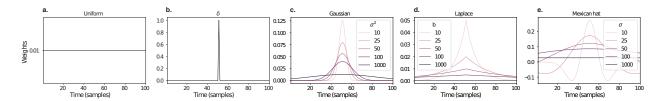


Figure 1: Examples of time-varying weights. Each panel displays per-timepoint weights at t=50, evaluated for 100 timepoints (1, ..., 100). a. Uniform weights. The weights are timepoint-invariant; observations at all timepoints are weighted equally, and do not change as a function of t. This is a special case of weight function that reduces dynamic correlations to static correlations. b. Dirac delta function. Only the observation at timepoint t is given weight (of 1), and weights for observations at all other timepoints are set to 0. c. Gaussian weights. Each observation's weights fall off in time according to a Gaussian probability density function centered on $\mu = t$. Weights derived using several different example variance parameters (σ^2 are displayed. d. Laplace weights. Each observation's weights fall off in time according to a Laplace probability density function centered on $\mu = t$. Weights derived using several different example scale parameters (b) are displayed. e. Mexican hat (Ricker wavelet) weights. Each observation's weights fall off in time according to a Ricker wavelet centered on t. This function highlights the *contrasts* between local versus surrounding activity patterns in estimating dynamic correlations. Weights derived using several different example width parameters (σ) are displayed.

58 Dynamic correlations

Given a matrix of observations, we can compute the (static) correlations between any pair of observations, X_i and X_j using:

$$\operatorname{corr}(\mathbf{X}_{i}, \mathbf{X}_{j}) = \frac{\sum_{t=1}^{T} (\mathbf{X}_{i}(t) - \bar{\mathbf{X}}_{i}) (\mathbf{X}_{j}(t) - \bar{\mathbf{X}}_{j})}{\sqrt{\sum_{t=1}^{T} \sigma_{\mathbf{X}_{i}}^{2} \sigma_{\mathbf{X}_{j}}^{2}}}, \text{ where}$$
(1)

$$\bar{\mathbf{X}}_k = \sum_{t=1}^T \mathbf{X}_k(t), \text{ and}$$
 (2)

$$\sigma_{\mathbf{X}_k}^2 = \sum_{t=1}^T \left(\mathbf{X}_k - \bar{\mathbf{X}}_k \right)^2 \tag{3}$$

- We can generalize this formula to compute time-varying correlations by incorporating a weight function
- that takes a time t as input, and returns how much the observed data every timepoint (including t) contribute
- to the correlations at time t (Fig. 1).

Given a weight function w(t) for timepoint t, evaluated at timepoints in the interval [1, ..., T], we can

extend the static correlation formula in Equation 2 to reflect an *instantaneous correlation* at timepoint t:

timecorr(
$$\mathbf{X}_{i}, \mathbf{X}_{j}, t$$
) =
$$\frac{\sum_{t=1}^{T} \left(\mathbf{X}_{i}(t) - \widetilde{\mathbf{X}}_{i}(t) \right) \left(\mathbf{X}_{j}(t) - \widetilde{\mathbf{X}}_{j}(t) \right)}{\sqrt{\sum_{t=1}^{T} \widetilde{\sigma}_{\mathbf{X}_{i}}^{2}(t) \widetilde{\sigma}_{\mathbf{X}_{j}}^{2}}}, \text{ where}$$
(4)

$$\widetilde{\mathbf{X}}_{k}(t) = \sum_{i=1}^{T} w(t, i) \mathbf{X}_{k}(i), \tag{5}$$

$$\widetilde{\sigma}_{\mathbf{X}_k}^2(t) = \sum_{i=1}^T \left(\mathbf{X}_k(i) - \widetilde{\mathbf{X}}_k(t) \right)^2, \tag{6}$$

- and w(t, i) is shorthand for w(t) evaluated at timepoint i. Equation 5 may be used to estimate the instanta-
- neous correlations between every pair of observations, at each timepoint (i.e., Y).

64 Inter-subject dynamic correlations

Equation 5 provides a means of taking a single observation matrix, X and estimating the dynamic correlations from moment to moment, Y. Suppose that one has access to a set of multiple observation matrices that reflect the same phenomenon. For example, one might collect neuroimaging data from several experimental participants, as each participant performs the same task (or sequence of tasks). Let $\{mathbfX_1, mathbfX_2, ..., mathbfX_P\}$ reflect the T by F observation matrices for each of P participants in an experiment. We can use inter-subject functional connectivity (ISFC; Simony et al., 2016) to compute the degree of stimulus-driven correlations reflected in the multi-participant dataset at a given timepoint t using:

$$\bar{\mathbf{C}}(t) = M \left(R \left(\frac{1}{2P} \sum_{i=1}^{P} Z\left(Y_i(t) \right)^{\mathrm{T}} + Z\left(Y_i, (t) \right) \right) \right), \tag{7}$$

where M extracts and vectorizes the diagonal and upper triangle of a symmetric matrix, Z is the Fisher z-transformation (Zar, 2010):

$$Z(r) = \frac{\log(1+r) - \log(1-r)}{2} \tag{8}$$

R is the inverse of *Z*:

$$R(z) = \frac{\exp(2z - 1)}{\exp(2z + 1)},\tag{9}$$

and $\mathbf{Y}_i(t)$ denotes the correlation matrix (Eqn. 2) between each column of \mathbf{X}_i and each column of the average observations from all *other* participants, $\bar{\mathbf{X}}_{\setminus i}$:

$$\bar{\mathbf{X}}_{\backslash i} = R\left(\frac{1}{P-1}\sum_{i\in\backslash i}Z\left(\mathbf{X}_{i}\right)\right),\tag{10}$$

where \i denotes the set of all participants other than participant *i*. In this way, the *T* by $\left(\frac{F^2-F}{2}+F\right)$ matrix $\bar{\mathbf{C}}$ is the time-varying extension of the ISFC approach developed by Simony et al. (2016).

67 Higher-order correlations

Given a timeseries of dynamic correlations (e.g., obtained using Eqn. 5), higher-order correlations reflect the dynamic correlations between columns of **Y**. Given unlimited computing resources, one could use repeated applications of Equation 5 to estimate these higher-order correlations (i.e., substituting in the previous output, **Y**, for the input, **X** in the equation). However, because each output **Y** has $O(F^2)$ columns relative to F columns in the input **X**, the output of Equation 5 grows with the square of the number of repeated applications (total cost of computing n^{th} order correlations is $O(F^{2n})$ for $n \in \mathcal{J}, n > 0$). When F or n is large, this approach quickly becomes intractable.

To make progress in computing \mathbf{Y}_{n+1} , we can approximate \mathbf{Y}_n by computing an O(F)-dimensional embedding of \mathbf{Y}_n , termed $\hat{\mathbf{Y}}_n$, and then we can apply Equation 5 to $\hat{\mathbf{Y}}_n$ rather than directly to \mathbf{Y}_n . This enables us to maintain O(n) scaling with respect to n, rather than exponential scaling via the direct approach.

There are many possible methods for computing $\hat{\mathbf{Y}}_n$ from \mathbf{Y}_n , including traditional dimensionality reduction approaches and graph theory based approaches as described next. In the *Discussion* section we elaborate on other potential approaches.

Dimensionality reduction-based approaches to computing $\hat{\mathbf{Y}}_n$

Commonly used dimensionality reduction algorithms include Principal Components Analysis (PCA; Pearson, 1901), Probabilistic PCA (PPCA; Tipping & Bishop, 1999), Exploratory Factor Analysis (EFA; Spearman, 1904), Independent Components Analysis (ICA; Jutten & Herault, 1991; Comon et al., 1991), *t*-Stochastic Neighbor Embedding (*t*-SNE; van der Maaten & Hinton, 2008), Uniform Manifold Approximation and Projection (UMAP; McInnes & Healy, 2018), non-negative matrix factorization (NMF; Lee & Seung, 1999), Topographic Factor Analysis (TFA) Manning et al. (2014), Hierarchical Topographic Factor analysis (HTFA) Manning et al. (2018), Topographic Latent Source Analysis (TLSA) Gershman et al. (2011), Dictionary learning (J. B. Mairal et al., 2009; J. Mairal et al., 2009), deep autoencoders (Hinton & Salakhutdinov,

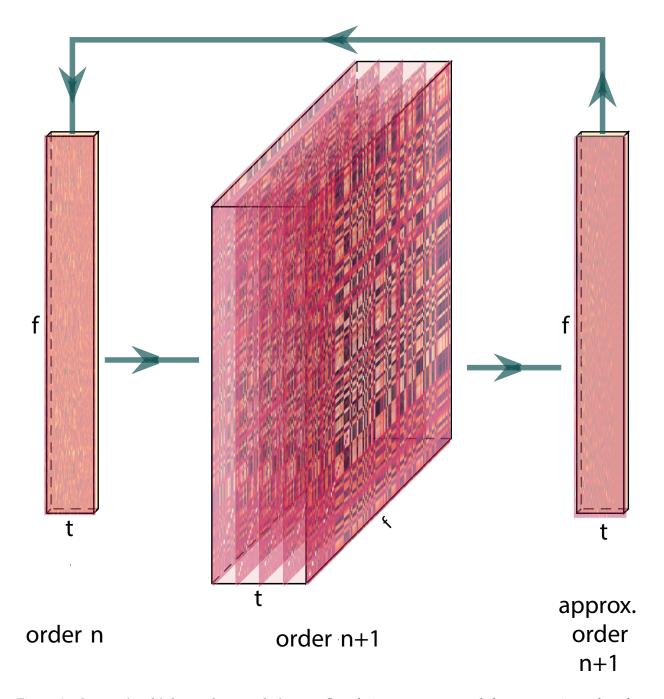


Figure 2: **Computing higher order correlations.** Correlations are computed then approximated to the same size as original data. This process is repeated to computer

2006), among others. While complete characterizations of each of these algorithms is beyond the scope of the present manuscript, the general intuition driving these approaches is to compute the $\hat{\mathbf{Y}}$ with i columns that is closest to the original \mathbf{Y} with j columns, and where (typically) $i \ll j$. The different approaches place different constraints on what properties $\hat{\mathbf{Y}}$ must satisfy and which aspects of the data are compared (and how) to characterize the match between $\hat{\mathbf{Y}}$ and \mathbf{Y} .

Applying dimensionality reduction algorithms to \mathbf{Y} yields a $\hat{\mathbf{Y}}$ whose columns reflect weighted combinations (or nonlinear transformations) of the original columns of \mathbf{Y} . This has two main consequences. First, with each repeated dimensionality reduction, the resulting $\hat{\mathbf{Y}}_n$ has lower and lower fidelity (with respect to what the "true" \mathbf{Y}_n might have looked like without using dimensionality reduction to maintain scalability). In other words, computing $\hat{\mathbf{Y}}_n$ is a lossy operation. Second, whereas the columns of \mathbf{Y}_n may be mapped directly onto pairs of columns of \mathbf{Y}_{n-1} , that mapping either becomes less cleanly defined in $\hat{\mathbf{Y}}_n$ due to the reweightings and/or nonlinear transformations.

Graph theory-based approaches to computing $\hat{\mathbf{Y}}_n$

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Graph theoretic measures take as input a matrix of interactions (e.g., using the above notation, an $F \times F$ correlation matrix or binarized correlation matrix reconstituded from a single timepoint's row of Y) and 104 return as output a set of F measures describing how each node (feature) sits within that interactions matrix with respect to the rest of the population. Common measures include betweeness centrality (the proportion 106 of shortest paths between each pair of nodes in the population that involves the given node in question; e.g., Newman, 2005; Opsahl et al., 2010; Barthélemy, 2004; Geisberger et al., 2008; Freeman, 1977); diversity and 108 dissimilarity (characterizations of how differently connected a given node is from others in the population; 109 e.g., Rao, 1982; Lin, 2009; Ricotta & Szeidl, 2006); Eigenvector centrality and pagerank centrality (measures of how influential a given node is within the broader network; e.g., Newman, 2008; Bonacich, 2007; Lohmann 111 et al., 2010; Halu et al., 2013); transfer entropy and flow coefficients (a measure of how much information is flowing from a given node to other nodes in the network; e.g., Honey et al., 2007; Schreiber, 2000); k-coreness 113 centrality (a measure of the connectivity of a node within its local sub-graph; e.g., Alvarez-Hamelin et al., 2005; Christakis & Fowler, 2010); within-module degree (a measure of how many connections a node has to 115 its close neighbors in the network; e.g., Rubinov & Sporns, 2010); participation coefficient (a measure of the 116 diversity of a node's connections to different sub-graphs in the network; e.g., Rubinov & Sporns, 2010); and 117 sub-graph centrality (a measure of a node's participation in all of the network's sub-graphs; e.g., Estrada & Rodríguez-Velázquez, 2005). 119

As an alternative to the above dimensionality reduction approach to embedding \mathbf{Y}_n in a lower-dimensional

space, but still allowing for scalable explorations of higher-order structure in the data, we also explore using the above graph theoretic measures as a means of obtaining $\hat{\mathbf{Y}}_n$. In particular: for a given graph theoretic measure, $\eta: \mathcal{R}^{F\times F} \to \mathcal{R}^F$, we can use η to tranform each row of \mathbf{Y}_n in a way that characterizes the corresponding graph-theoretic properties of each column. Whereas the dimensionality reduction approach to computing $\hat{\mathbf{Y}}_n$ is lossy, the graph-theory approach is lossless. However, whereas the dimensionality reduction approach maintains ties (direct or indirect) to the original activity patterns reflected in \mathbf{Y}_{n-1} , the graph-theory approach does not. Instead, the graph-theory characterizes the nature and timecourse of each feature's *participation* in the network.

129 Evaluation metrics

We evaluate our approach to extracting dynamic correlations and higher-order correlations using several metrics detailed next. First, we generated synthetic data using known time-varying correlations, and then we evaluated the fidelity with which Equation 5 could recover those correlations (for synthetic datasets with different properties, and using different kernels to define the weights; Fig. 1). We then turned to a series of analyses on a (real) neuroimaging dataset where the ground truth correlations were *not* known. We evaluated whether the recovered correlations could be used to accurately label held-out neuroimaging data with the time at which it was collected. We used this latter evaluations (using timepoint decoding) as a proxy for gauging how much explanatory power the recovered correlations held with respect to the observed data.

139 Generating synthetic data

To explore recovery of a constant covariance (Fig. 3, A.), we generated synthetic data sampled from a constant covariance matrix. To do this, we created one random covariance matrix, K, with 50 features, and for each of the 300 timepoints we sampled from a Gaussian distribution centered on K. Similarly, we generated synthetic data sampled from a random covariance matrix (Fig. 3, B.) by creating a new random covariance matrix K(t), for each of the 300 timepoints and sampled from a Gaussian distribution centered on K(t).

To generate synthetic data from a dynamically changing covariance matrix (ramping covariance matrix Fig. 3, C.), we generated two random covariance matrices, K_1 and K_2 . We then computed a covariance matrix for each of the 300 timepoint, K(t) by taking the linearly spaced weights (w) of the two random matrices,

$$K(t) = w(t) * K_1 + 1 - w(t) * K_2$$
(11)

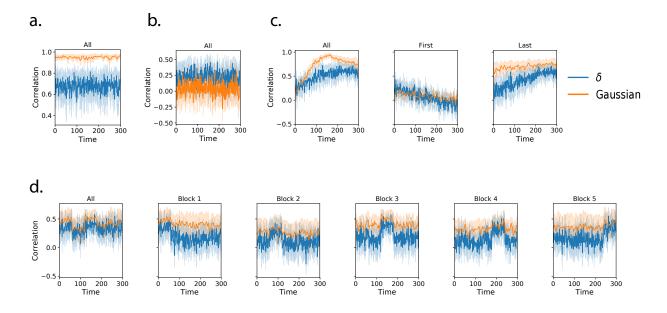


Figure 3: Dynamic correlation recovery with synthetic data. a.Recovery using a constant dataset. Using constant dataset, how well can we recover using different kernels. b. Recovery using random dataset. c. Ramping recovery. d. Block recovery blah

(Fig. 3)

146 Recovery of ground truth parameters from synthetic data

We applied timecorr, using delta and gaussian kernels Fig. 1) to each of these synthetic datasets, then correlate each recovered correlation matrix with the ground truth. Explore how recovery varies with the kernel and the specific structure of the data (e.g. slow changes as in the ramping dataset, versus rapid changes as in the block dataset).

151 Timepoint decoding

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To explore how higher-order structure varies with stimulus structure and complexity, we used a previous neuroimaging dataset Simony et al. (2016) in which participants listened to an audio recording of a story;
36 participants listen to an intact version of the story, 17 participants listen to time-scrambled recordings of the same story where paragraphs were scrambled, 36 participants listen to word-scrambled version and 36 participants lay in rest condition.

Prior work has shown participants share similar neural responses to richly structured stimuli when compared to stimuli with less structure. To assess whether the moment-by-moment higher order correlations were reliably preserved across participants, we used inter-subject functional connectivity (ISFC) to isolate the time-varying correlational structure (functional connectivity patterns that were specifically driven by

the story participants listened to. Following the analyses conducted by (HTFA) Manning et al. (2018), we first applied *hierarchical topographic factor analysis* (HTFA) to the fMRI datasets to obtain a time series of 700 node activities for every participant. We then computed the dynamic weighted ISFC using a gaussian kernel with a width of 5. We then approximated these dynamic correlation using PCA and computed the dynamic weighted ISFC on the approximations. We repeated this process up to 10th order approximated correlations.

To assess decoding accuracy, we randomly divided participants for each stimulus into training and 167 testing groups. For the zeroth order, we computed the mean factor activity for each group. For all subsequent 168 orders up to the tenth order, we computed the mean approximated dynamic ISFC of factor activity for each group. To assess how additional higher-order correlations contribute to decoding accuracy, for each order 170 we included a weighted-mixutre (described below) of the activity patterns of all previous orders. For each group of participants in turn, we compared these activity patterns (using Pearson correlations) to estimate 172 the story times each pattern corresponded to. Specifically, we asked, for each timepoint: what are the correlations between the first group's and second group's activity patterns at each order. We note that the 174 decoding test we used is a conservative in which we count a timepoint label as incorrect if it is not an exact match. 176

For each order we obtained the weighted-mixture of the correlation matrices for the current order and all previous orders using mixing parameter , ϕ , where $0 < \phi < 1$ reflects a weighted mixture of order based decoding Fig. ?? Panel C.). We calculated ϕ , by subdividing the training group and using the quasiNewton method of Broyden, Fletcher, Goldfarb, and Shanno (BFGS) for optimization. We repeated this cross-validation process 100 times.

182 Results

83 Synthetic data

Figure: overall timecourse of recovery, also recovery near event boundaries.

Neuroimaging dataset (Simony et al., 2016)

For our decoding analysis, we used HTFA-derived node activities Manning et al. (2018) from fMRI data collected as participants listened to an audio recording of a story (intact condition; 36 participants), listened to time scrambled recordings of the same story (17 participants in the paragraph-scrambled condition listened to the paragraphs in a randomized order and 36 in the word-scrambled condition listened to

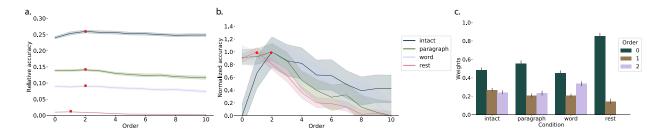


Figure 4: **Decoding by order. a. Relative decoding accuracy by order.** Ribbons of each color display cross-validated decoding performance for each condition (intact, paragraph, word, and rest. Decoders were trained using increasingly more higher-order information and this ribbons are displayed relative to chance at 0. The red dots indicates maximum decoding accuracy for each condition. **b. Normalized decoding accuracy by order.** We normalized the decoding accuracy by order to better visualize the order with the maximum decoding accuracy for each condition. **c. Optimized weights.** Bar heights indicate the optimized mixing paramete ϕ of each contributing order up to and including the order with the maximum decoding accuracy for each contributing order For the order with maximum decoding accuracy by condition, we show barplots of the optimized weights ϕ for each contributing order.

the words in a randomized order), or lay resting with their eyes open in the scanner (rest condition; 36 participants). We sought to demonstrate how higher-order correlations may be used to examine dynamic interactions of brain patterns in (real) multi-subject fMRI datasets. This story listening dataset was collected as part of a separate study, where the full imaging parameters, image preprocessing methods, and experimental details may be found (Simony et al., 2016). The dataset is available at http://arks. princeton.edu/ark:/88435/dsp015d86p269k. Bars of each color display cross-validated decoding performance for decoders trained using different sets of neural features: whole-brain patterns of voxel activities

We next evaluated if our model of high-order correlations in brain activity can capture cognitively relevant brain patterns. We performed a decoding analysis, using cross validation to estimate (using other participants' data) which parts of the story each weighted-mixture of higher-order brain activity pattern corresponded to (see *Materials and methods*). We note that our primary goal was not to achieve perfect decoding accuracy, but rather to use decoding accuracy as a benchmark for assessing whether different neural features specifically capture cognitively relevant brain patterns.

Separately for each experimental condition, we divided participants into two groups. For the zeroth order, we computed the mean factor activity for each group. For all subsequent orders up to the tenth order, we computed the mean approximated dynamic ISFC of factor activity for each group (see *Materials and methods*), and combined in a weighted mixutre with all previous orders (i.e. cross-validation for the second order contained a weighted-mixture of zeroth, first, and second order c. **Optimized weights.**.) For each order, we correlated the group 1 activity patterns with group 2 activity patterns. We then subdivided the group 1 to obtain an optimal weighting parameter for each order's correlation matrix using the same cross validation method. We used the optimal weighting parameters to obtain a weighted-mixture (see

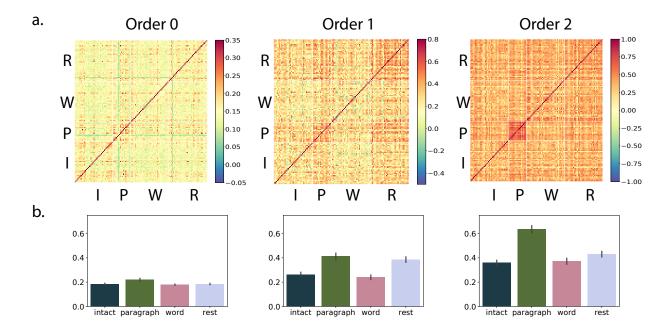


Figure 5: Inter-subject correlations by order. a. Inter-subject correlation heatmaps by order. Heatmaps for each order of how correlated each subject is with every other subject grouped by condition (intact (I), paragraph (P), word (W), and rest (R)). b. Mean correlation for each condition by order. Bar heights indicate inter-subject correlations by condition for each order.

Materials and methods) of each order's correlation matrix. Using these correlations, we labeled the group 1 timepoints using the group 2 timepoints with which they were most highly correlated; we then computed the proportion of correctly labeled group 1 timepoints. (We also performed the symmetric analysis whereby we labeled the group 2 timepoints using the group 1 timepoints as a template.) We repeated this procedure 100 times (randomly re-assigning participants to the two groups each time) to obtain a distribution of decoding accuracies for each experimental condition. (There were 272 timepoints for paragraph condition, 300 timepoints for intact and word conditions, and 400 timepoints for rest condition, so chance performance on this decoding test is was $\frac{1}{272}$, $\frac{1}{300}$, and $\frac{1}{400}$ respectively.

Discussion

- Decoding accuracy best for level 2 data for all but rest condition. Could be that the brain is 2nd order
 or that fMRI can only reliable give 2nd order.
- multiple timescale representations (a la Hasson group) implies first-order network interactions.
 higher-order interactions imply generalizations between interacting representations (e.g. mirrored schema, a la Norman/Baldassano/Hasson). possibly cite NTB 2013 science review, using as evidence

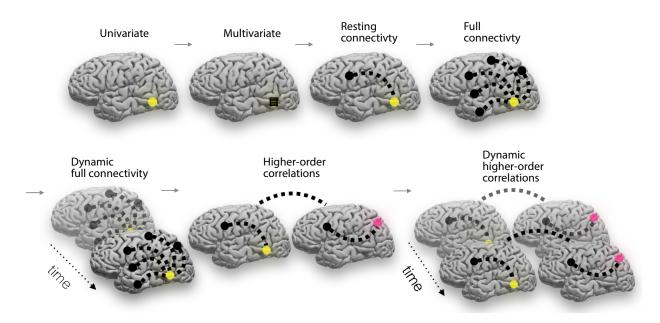


Figure 6: Direction of the field.

- that this is where the field is going (voxels \rightarrow patterns (L0) \rightarrow interactions (L1) \rightarrow higher order patterns (L2+).
- related approaches: sliding window, phase-based correlations, within-ROI spatial correlations at each timepoint, granger causality, other explit models (e.g. virtual brain).
 - other applications: molecular interactions (protein folding?), diagnosis (e.g. psychiatric disorders as network flow problems– gratton work?), social network dynamics (e.g. financial markets, social media interactions)

232 Concluding remarks

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the universe is complicated and we need scalable approaches to studying how the pieces are interacting to make sense of it. one small step for mankind, and so on.

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Author contributions

Concept: J.R.M. Implementation: T.H.C., L.L.W.O., and J.R.M. Analyses: L.L.W.O and J.R.M.

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