

1 **High-level cognition during story listening is reflected in
2 high-order dynamic correlations in neural activity patterns**

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5 **Abstract**

6 Our thoughts arise from coordinated patterns of interactions between brain structures that change
7 with our ongoing experiences. High-order dynamic correlations in neural activity patterns reflect different
8 subgraphs of the brain's functional connectome that display homologous lower-level dynamic correlations.
9 We tested the hypothesis that high-level cognition is reflected in high-order dynamic correlations in brain
10 activity patterns. We developed an approach to estimating high-order dynamic correlations in timeseries
11 data, and we applied the approach to neuroimaging data collected as human participants either listened to
12 a ten-minute story or listened to a temporally scrambled version of the story. We trained across-participant
13 pattern classifiers to decode (in held-out data) when in the session each neural activity snapshot was
14 collected. We found that classifiers trained to decode from high-order dynamic correlations yielded the best
15 performance on data collected as participants listened to the (unscrambled) story. By contrast, classifiers
16 trained to decode data from scrambled versions of the story yielded the best performance when they
17 were trained using first-order dynamic correlations or non-correlational activity patterns. We suggest that
18 as our thoughts become more complex, they are reflected in higher-order patterns of dynamic network
19 interactions throughout the brain.

20 **Introduction**

21 A central goal in cognitive neuroscience is to elucidate the *neural code*: the mapping between (a) mental
22 states or cognitive representations and (b) neural activity patterns. One means of testing models of the
23 neural code is to ask how accurately that model is able to "translate" neural activity patterns into known
24 (or hypothesized) mental states or cognitive representations (e.g., Haxby et al., 2001; Huth et al., 2016, 2012;
25 Kamitani & Tong, 2005; Mitchell et al., 2008; Nishimoto et al., 2011; Norman et al., 2006; Pereira et al., 2018;
26 Tong & Pratte, 2012). Training decoding models on different types of neural features (Fig. 1a) can also help to
27 elucidate which specific aspects of neural activity patterns are informative about cognition and, by extension,
28 which types of neural activity patterns might compose the neural code. For example, prior work has used
29 region of interest analyses to estimate the anatomical locations of specific neural representations (e.g., Etzel
30 et al., 2009), or to compare the relative contributions to the neural code of multivariate activity patterns

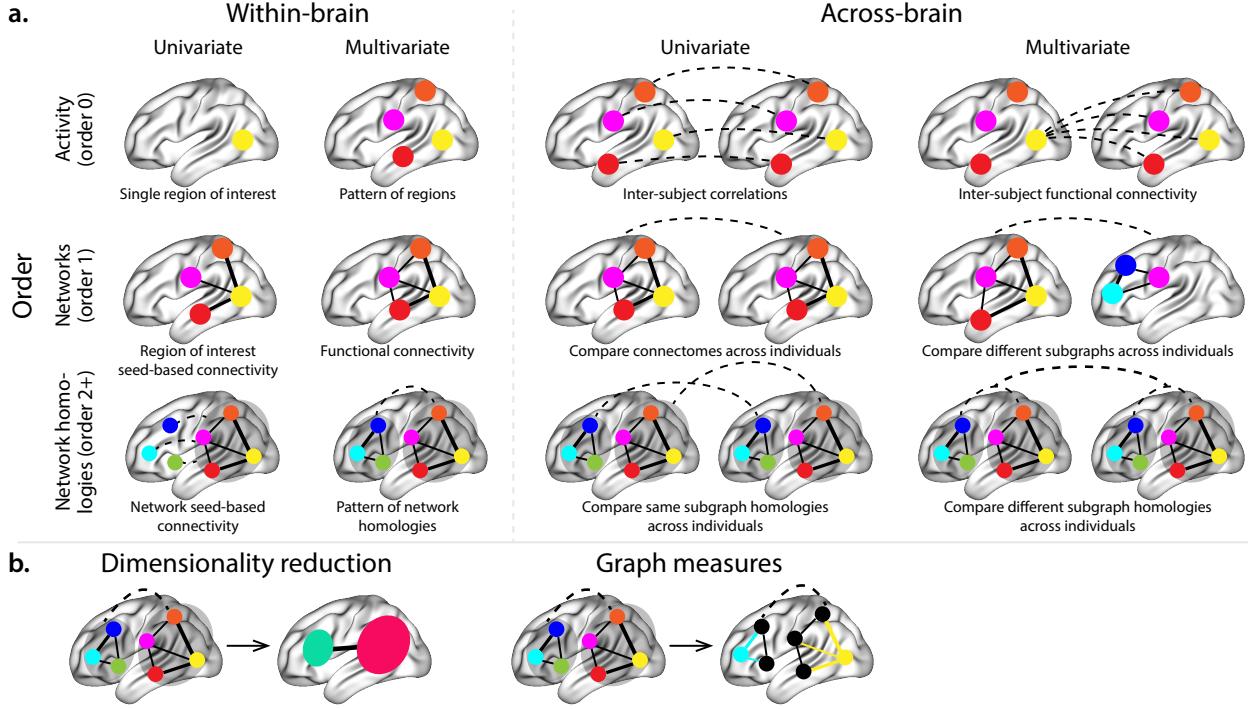


Figure 1: Neural patterns. a. A space of neural features. Within-brain analyses are carried out within a single brain, whereas across-brain analyses compare neural patterns across two or more individuals' brains. Univariate analyses characterize the activities of individual units (e.g., nodes, small networks, hierarchies of networks, etc.), whereas multivariate analyses characterize the patterns of activity across units. Order 0 patterns involve individual nodes; order 1 patterns involve node-node interactions; order 2 (and higher) patterns relate to interactions between homologous networks. Each of these patterns may be static (e.g., averaging over time) or dynamic. **b. Summarizing neural patterns.** To efficiently compute with complex neural patterns, it can be useful to characterize the patterns using summary measures. Dimensionality reduction algorithms project the patterns onto lower-dimensional spaces whose dimensions reflect weighted combinations or non-linear transformations of the dimensions in the original space. Graph measures characterize each unit's participation in its associated network.

31 versus dynamic correlations between neural activity patterns (e.g., Fong et al., 2019; Manning et al., 2018).

32 An emerging theme in this literature is that cognition is mediated by dynamic interactions between brain

33 structures (Bassett et al., 2006; Bressler & Kelso, 2001; Demertzi et al., 2019; Friston, 2000; Grossberg, 1988;

34 Lurie et al., 2018; Mack et al., 2017; McIntosh, 2000; Preti et al., 2017; Solomon et al., 2019; Sporns & Honey,

35 2006; Turk-Browne, 2013; Zou et al., 2019).

36 Studies of the neural code to date have primarily focused on univariate or multivariate neural pat-
 37 terns (for review see Norman et al., 2006), or (more recently) on patterns of dynamic first-order corre-
 38 lations (i.e., interactions between pairs of brain structures; Demertzi et al., 2019; Fong et al., 2019; Lurie et al.,
 39 2018; Manning et al., 2018; Preti et al., 2017; Zou et al., 2019). What might the future of this line of work
 40 hold? For example, is the neural code implemented through higher-order interactions between brain struc-

41 tures (e.g., see Reimann et al., 2017)? Second-order correlations reflect *homologous* patterns of correlation.
42 In other words, if the dynamic patterns of correlations between two regions, *A* and *B*, are similar to those
43 between two other regions, *C* and *D*, this would be reflected in the second-order correlations between (*A*–*B*)
44 and (*C*–*D*). In this way, second-order correlations identify similarities and differences between subgraphs
45 of the brain’s connectome. Analogously, third-order correlations reflect homologies between second-order
46 correlations—i.e., homologous patterns of homologous interactions between brain regions. More generally,
47 higher-order correlations reflect homologies between patterns of lower-order correlations. We can then ask:
48 which “orders” of interaction are most reflective of high-level cognitive processes?

49 One reason one might expect to see homologous networks in a dataset is related to the notion that
50 network dynamics reflect ongoing neural computations or cognitive processing (e.g., Beaty et al., 2016). If
51 the nodes in two brain networks are interacting (within each network) in similar ways then, according to
52 our characterization of network dynamics, we refer to the similarities between those patterns of interaction
53 as higher-order correlations. When higher-order correlations are themselves changing over time, we can
54 also attempt to capture and characterize those high-order dynamics.

55 Another central question pertains to the extent to which the neural code is carried by activity patterns
56 that directly reflect ongoing cognition (e.g., following Haxby et al., 2001; Norman et al., 2006), versus the
57 dynamic properties of the network structure itself, independent of specific activity patterns in any given
58 set of regions (e.g., following Bassett et al., 2006). For example, graph measures such as centrality and
59 degree (Bullmore & Sporns, 2009) may be used to estimate how a given brain structure is “communicating”
60 with other structures, independently of the specific neural representations carried by those structures.
61 If one considers a brain region’s position in the network (e.g., its eigenvector centrality) as a dynamic
62 property, one can compare how the positions of different regions are correlated, and/or how those patterns
63 of correlations change over time. We can also compute higher-order patterns in these correlations to
64 characterize homologous subgraphs in the connectome that display similar changes in their constituent
65 brain structures’ interactions with the rest of the brain.

66 To gain insights into the above aspects of the neural code, we developed a computational framework
67 for estimating dynamic high-order correlations in timeseries data. This framework provides an important
68 advance, in that it enables us to examine patterns of higher-order correlations that are computationally
69 intractable to estimate via conventional methods. Given a multivariate timeseries, our framework pro-
70 vides timepoint-by-timepoint estimates of the first-order correlations, second-order correlations, and so
71 on. Our approach combines a kernel-based method for computing dynamic correlations in timeseries
72 data with a dimensionality reduction step (Fig. 1b) that projects the resulting dynamic correlations into
73 a low-dimensional space. We explored two dimensionality reduction approaches: principle components

74 analysis (PCA; Pearson, 1901), which preserves an approximately invertible transformation back to the
75 original data (e.g., this follows related approaches taken by Gonzalez-Castillo et al., 2019; McIntosh & Jirsa,
76 2019; Toker & Sommer, 2019); and a second non-invertible algorithm for computing dynamic patterns in
77 eigenvector centrality (Landau, 1895). This latter approach characterizes correlations between each feature
78 dimension's relative *position* in the network (at each moment in time) in favor of the specific activity histories
79 of different features (also see Betzel et al., 2019; Reimann et al., 2017; Sizemore et al., 2018).

80 We validated our approach using synthetic data where the underlying correlations were known. We
81 then applied our framework to a neuroimaging dataset collected as participants listened to either an audio
82 recording of a ten-minute story, listened to a temporally scrambled version of the story, or underwent a
83 resting state scan (Simony et al., 2016). Temporal scrambling has been used in a growing number of studies,
84 largely by Uri Hasson's group, to identify brain regions that are sensitive to higher-order and longer-
85 timescale information (e.g., cross-sensory integration, rich narrative meaning, complex situations, etc.)
86 versus regions that are primarily sensitive to low-order (e.g., sensory) information. For example, Hasson et
87 al. (2008) argues that when brain areas are sensitive to fine versus coarse temporal scrambling, this indicates
88 that they are "higher order" in the sense that they process contextual information pertaining to further-
89 away timepoints. By contrast, low-level regions, such as primary sensory cortices, do not meaningfully
90 change their responses (after correcting for presentation order) even when the stimulus is scrambled at fine
91 timescales.

92 We used a subset of the story listening and rest data to train across-participant classifiers to decode
93 listening times (of groups of participants) using a blend of neural features (comprising neural activity
94 patterns, as well as different orders of dynamic correlations between those patterns that were inferred
95 using our computational framework). We found that both the PCA-based and eigenvector centrality-based
96 approaches yielded neural patterns that could be used to decode accurately (i.e., well above chance). Both
97 approaches also yielded the best decoding accuracy for data collected during (intact) story listening when
98 high-order (PCA: second-order; eigenvector centrality: fourth-order) dynamic correlation patterns were
99 included as features. When we trained classifiers on the scrambled stories or resting state data, only
100 (relatively) lower-order dynamic patterns were informative to the decoders. Taken together, our results
101 indicate that high-level cognition is supported by high-order dynamic patterns of communication between
102 brain structures.

103 **Results**

104 We sought to understand whether high-level cognition is reflected in dynamic patterns of high-order
105 correlations. To that end, we developed a computational framework for estimating the dynamics of stimulus-
106 driven high-order correlations in multivariate timeseries data (see *Dynamic inter-subject functional connectivity*
107 (*DISFC*) and *Dynamic higher-order correlations*). We evaluated the efficacy of this framework at recovering
108 known patterns in several synthetic datasets (see *Synthetic data: simulating dynamic first-order correlations* and
109 *Synthetic data: simulating dynamic higher-order correlations*). We then applied the framework to a public fMRI
110 dataset collected as participants listened to an auditorily presented story, listened to a temporally scrambled
111 version of the story, or underwent a resting state scan (see *Functional neuroimaging data collected during story*
112 *listening*). We used the relative decoding accuracies of classifiers trained on different sets of neural features
113 to estimate which types of features reflected ongoing cognitive processing.

114 **Recovering known dynamic correlations from synthetic data**

115 **Recovering dynamic first-order correlations**

116 We generated synthetic datasets that differed in how the underlying first-order correlations changed over
117 time. For each dataset, we applied Equation 4 with a variety of kernel shapes and widths. We assessed how
118 well the true underlying correlations at each timepoint matched the recovered correlations (Fig. 2). For every
119 kernel and dataset we tested, our approach recovered the correlation dynamics we embedded into the data.
120 However, the quality of these recoveries varied across different synthetic datasets in a kernel-dependent
121 way.

122 In general, wide monotonic kernel shapes (Laplace, Gaussian), and wider kernels (within a shape),
123 performed best when the correlations varied gradually from moment-to-moment (Figs. 2a, c, and d). In the
124 extreme, as the rate of change in correlations approaches 0 (Fig. 2a), an infinitely wide kernel would exactly
125 recover the Pearson's correlation (e.g., compare Eqns. 1 and 4).

126 When the correlation dynamics were unstructured in time (Fig. 2b), a Dirac δ kernel (infinitely nar-
127 row) performed best. This is because, when every timepoint's correlations are independent ~~of~~ from the
128 correlations at every other timepoint, averaging data over time dilutes the available signal. Following a
129 similar pattern, holding kernel shape fixed, narrower kernel parameters better recovered randomly varying
130 correlations.

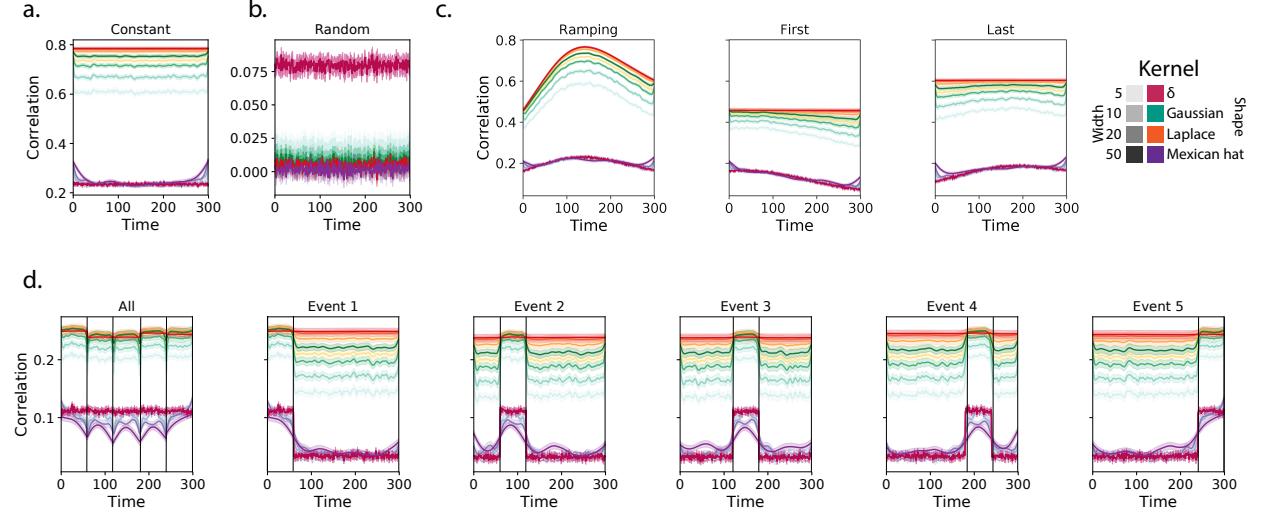


Figure 2: Recovering known dynamic first-order correlations from synthetic data. Each panel displays the average correlations between the vectorized upper triangles of the recovered correlation matrix at each timepoint and either the true underlying correlation at each timepoint or a reference correlation matrix. (The averages are taken across 10–100 different randomly generated synthetic datasets of [the each](#) given category, [each with \$K = 50\$ features and \$T = 300\$ timepoints](#).) Error ribbons denote 95% confidence intervals (taken across datasets). Different colors denote different kernel shapes, and the shading within each color family denotes the kernel width parameter. For a complete description of each synthetic dataset, see *Synthetic data: simulating dynamic first-order correlations*. **a. Constant correlations.** These datasets have a stable (unchanging) underlying correlation matrix. **b. Random correlations.** These datasets are generated using a new independently drawn correlation matrix at each new timepoint. **c. Ramping correlations.** These datasets are generated by smoothly varying the underlying correlations between the randomly drawn correlation matrices at the first and last timepoints. The left panel displays the correlations between the recovered dynamic correlations and the underlying ground truth correlations. The middle panel compares the recovered correlations with the *first* timepoint’s correlation matrix. The right panel compares the recovered correlations with the *last* timepoint’s correlation matrix. **d. Event-based correlations.** These datasets are each generated using five randomly drawn correlation matrices that each remain stable for a fifth of the total timecourse. The left panel displays the correlations between the recovered dynamic correlations and the underlying ground truth correlations. The right panels compare the recovered correlations with the correlation matrices unique to each event. The vertical lines denote event boundaries.

131 **Recovering dynamic higher-order correlations**

132 Following our approach to evaluating our ability to recover known dynamic first-order correlations from
133 synthetic data, we generated an analogous second set of synthetic datasets that we designed to exhibit
134 known dynamic first-order *and* second-order correlations (see *Synthetic data: simulating dynamic higher-order*
135 *correlations*). We generated a total of ~~40–400~~ datasets that varied in how the first-order and second-order
136 correlations changed over time. We then repeatedly applied Equation 4 using the overall best-performing
137 kernel from our first-order tests (a Laplace kernel with a width of 20; Fig. 2) to assess how closely the
138 recovered dynamic correlations matched the dynamic correlations we had embedded into the datasets.

139 Overall, we found that we could reliably recover both first-order and second-order correlations from
140 the synthetic data (Fig. 3). When the correlations were stable for longer intervals, or changed gradually
141 (constant, ramping, and event datasets), recovery performance was relatively high, and we were better
142 able to recover dynamic first-order correlations than second-order correlations. ~~We expected that this~~
143 ~~would happen, given that~~ This is because errors in our ~~estimation~~ estimation procedure at lower orders
144 necessarily propagate to higher orders (since lower-order correlations are used to estimate higher-order
145 correlations). ~~Interestingly, we also found that~~ Conversely, when the correlations were particularly *unstable*
146 (random datasets), we better recovered second-order correlations. This is because noise in our *data generation*
147 procedure propagates from higher orders to lower orders (see *Synthetic data: simulating dynamic high-order*
148 *correlations*).

149 We also examined the impact of the data duration (Fig. S3) and complexity (number of zero-order features;
150 Fig. S4) on our ability to accurately recover ground truth first-order and second-order dynamic correlations.
151 In general, we found that our approach better recovers ground truth dynamic correlations from longer
152 duration timeseries data. We also found that our approach tends to best recover data generated using fewer
153 zero-order features (i.e., lower complexity), although this tendency was not strictly monotonic. Further,
154 because our data generation procedure requires $O(K^4)$ memory to generate a second-order timeseries with K
155 zero-order features, we were not able to fully explore how the number of zero-order features affects recovery
156 accuracy as the number of features gets larger (e.g., as it approaches the number of features present in the
157 fMRI data we examine below). Although we were not able to formally test this to our satisfaction, we expect
158 that accurately estimating dynamic high-order correlations would require data with many more zero-order
159 features than we were able to simulate. Our reasoning is that high-order correlations necessarily involve
160 larger numbers of lower-order features, so achieving adequate “resolution” high-order timeseries might
161 require many low-order features.

162 Taken together, our explorations using synthetic data indicated that we are able to partially, but not

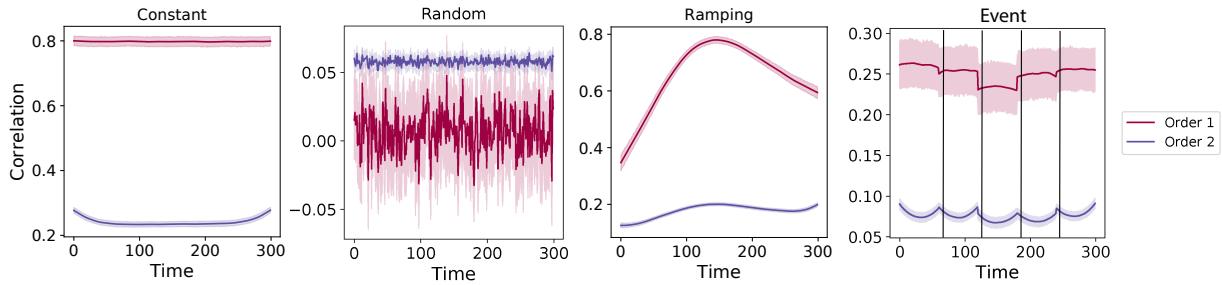


Figure 3: **Recovery of simulated first-order and second-order dynamic correlations.** Each panel displays the average correlations between the vectorized upper triangles of the recovered first-order and second-order correlation matrices and the true (simulated) first-order and second order correlation matrices at each timepoint and for each synthetic dataset. (The averages are taken across 10–100 different randomly generated synthetic datasets of the each given category, each with $K = 10$ features and $T = 300$ timepoints.) Error ribbons denote 95% confidence intervals (taken across datasets). For a complete description of each synthetic dataset, see *Synthetic data: simulating dynamic higher-order correlations*. All estimates represented in this figure were computed using a Laplace kernel (width = 20). **a. Constant correlations.** **Constant.** These datasets have stable (unchanging) underlying second-order correlation matrices. **b. Random correlations.** **Random.** These datasets are generated using a new independently drawn second-order correlation matrix at each timepoint. **c. Ramping correlations.** **Ramping.** These datasets are generated by smoothly varying the underlying second-order correlations between the randomly drawn correlation matrices at the first and last timepoints. **d. Event-based correlations.** **Event.** These datasets are each generated using five randomly drawn second-order correlation matrices that each remain stable for a fifth of the total timecourse. The vertical lines denote event boundaries. Note that the “dips” and “ramps” at the boundaries of sharp transitions (e.g., the beginning and ends of the “constant” and “ramping” datasets, and at the event boundaries of the “event” datasets) are finite-sample effects that reflect the reduced numbers of samples that may be used to accurately estimate correlations at sharp boundaries.

163 perfectly, recover ground truth dynamic first-order and second-order correlations. This suggests that our
164 modeling approach provides a meaningful (if noisy) estimate of high-order correlations. We next turned
165 to analyses of human fMRI data to examine whether the recovered dynamics might reflect the dynamics of
166 human cognition during a naturalistic story-listening task.

167 Cognitively relevant dynamic high-order correlations in fMRI data

168 We used across-participant temporal decoders to identify cognitively relevant neural patterns in fMRI data
169 (see *Forward inference and decoding accuracy*). The dataset we examined (collected by Simony et al., 2016)
170 comprised four experimental conditions that exposed participants to stimuli that varied systematically in
171 how cognitively engaging they were. The *intact* experimental condition had participants listen to an audio
172 recording of a 10-minute story. The *paragraph*-scrambled experimental condition had participants listen to a
173 temporally scrambled version of the story, where the paragraphs occurred out of order (but where the same
174 total set of paragraphs were presented over the full listening interval). All participants in this condition
175 experienced the scrambled paragraphs in the same order. The *word*-scrambled experimental condition had
176 participants listen to a temporally scrambled version of the story where the words in the story occurred in a
177 random order. All participants in the word condition experienced the scrambled words in the same order.
178 Finally, in a *rest* experimental condition, participants lay in the scanner with no overt stimulus, with their
179 eyes open (blinking as needed). This public dataset provided a convenient means of testing our hypothesis
180 that different levels of cognitive processing and engagement are reflected in different orders of brain activity
181 dynamics.

182 In brief, we computed timeseries of dynamic high-order correlations that were similar across participants
183 in each of two randomly assigned groups: a training group and a test group. We then trained classifiers
184 on the training group's data to match each sample from the test group with a stimulus timepoint. Each
185 classifier comprised a weighted blend of neural patterns that reflected up to n^{th} -order dynamic correlations
186 (see *Feature weighting and testing*, Fig. 10). We repeated this process for $n \in \{0, 1, 2, \dots, 10\}$. Our examinations
187 of synthetic data suggested that none of the kernels we examined were “universal” in the sense of optimally
188 recovering underlying correlations regardless of the temporal structure of those correlations. We found a
189 similar pattern in the (real) fMRI data, whereby different kernels yielded different decoding accuracies, but
190 no single kernel emerged as the clear “best.” In our analyses of neural data, we therefore averaged our
191 decoding results over a variety of kernel shapes and widths in order to identify results that were robust to
192 specific kernel parameters (see *Identifying robust decoding results*).

193 Our approach to estimating dynamic high-order correlations entails mapping the high-dimensional

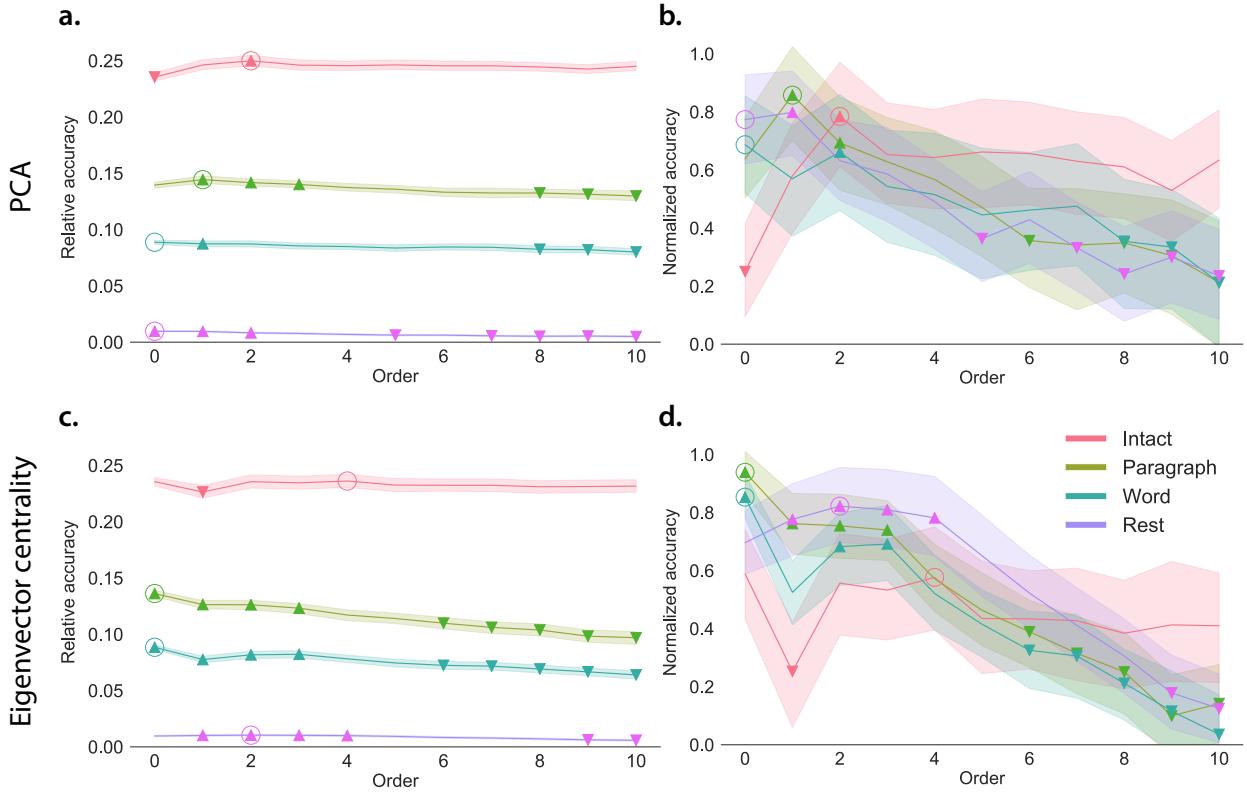


Figure 4: Across-participant timepoint decoding accuracy varies with correlation order and cognitive engagement. **a. Decoding accuracy as a function of order: PCA.** Order (x-axis) refers to the maximum order of dynamic correlations that were available to the classifiers (see *Feature weighting and testing*). The reported across-participant decoding accuracies are averaged over all kernel shapes and widths (see *Identifying robust decoding results*). The y-values are displayed relative to chance accuracy (intact: $\frac{1}{300}$; paragraph: $\frac{1}{272}$; word: $\frac{1}{300}$; rest: $\frac{1}{400}$; these chance accuracies were subtracted from the observed accuracies to obtain the relative accuracies reported on the y-axis). The error ribbons denote 95% confidence intervals across cross-validation folds (i.e., random assignments of participants to the training and test sets). The colors denote the experimental condition. Arrows denote sets of features that yielded reliably higher (upward facing) or lower (downward facing) decoding accuracy than the mean of all other features (via a two-tailed *t*-test, thresholded at $p < 0.05$). Figure 5 displays additional comparisons between the decoding accuracies achieved using different sets of neural features. The circled values represent the maximum decoding accuracy within each experimental condition. **b. Normalized timepoint decoding accuracy as a function of order: PCA.** This panel displays the same results as Panel a, but here each curve has been normalized to have a maximum value of 1 and a minimum value of 0 (including the upper and lower bounds of the respective 95% confidence intervals). Panels a and b used PCA to project each high-dimensional pattern of dynamic correlations onto a lower-dimensional space. **c. Timepoint decoding accuracy as a function of order: eigenvector centrality.** This panel is in the same format as Panel a, but here eigenvector centrality has been used to project the high-dimensional patterns of dynamic correlations onto a lower-dimensional space. **d. Normalized timepoint decoding accuracy as a function of order: eigenvector centrality.** This panel is in the same format as Panel b, but here eigenvector centrality has been used to project the high-dimensional patterns of dynamic correlations onto a lower-dimensional space. See Figures S1 and S2 for decoding results broken down by kernel shape and width, respectively.

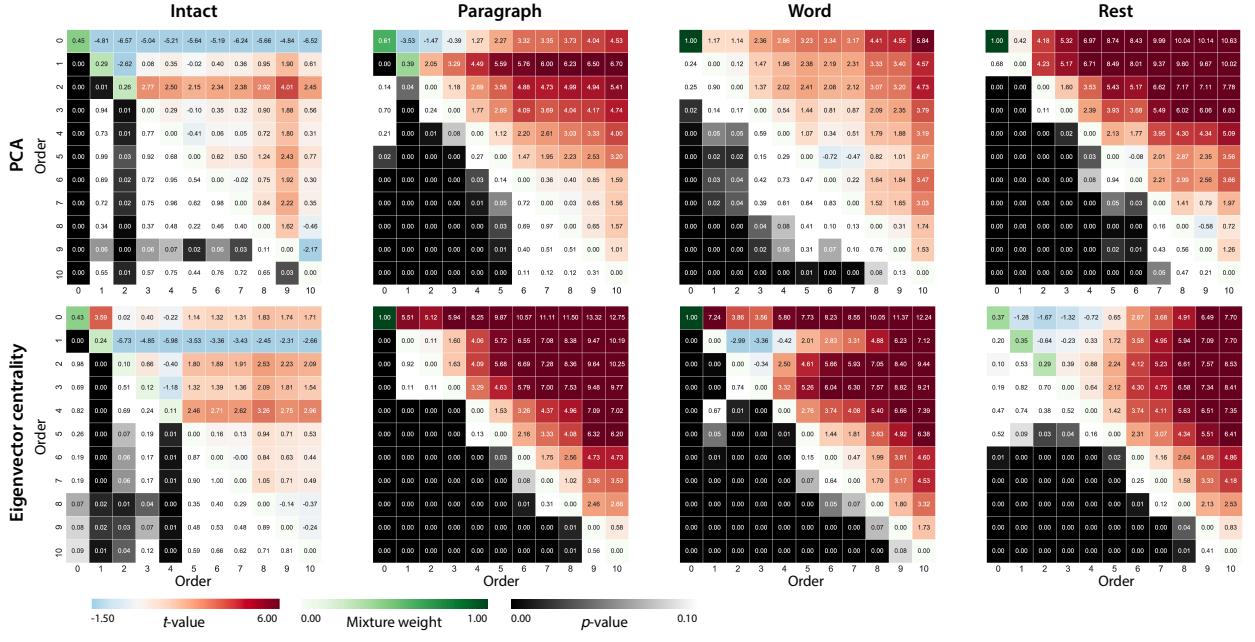


Figure 5: Statistical summary of decoding accuracies for different neural features. Each column of matrices displays decoding results for one experimental condition (intact, paragraph, word, and rest). We considered dynamic activity patterns (order 0) and dynamic correlations at different orders (order > 0). We used two-tailed t -tests to compare the distributions of decoding accuracies obtained using each pair of features. The distributions for each feature reflect the set of average decoding accuracies (across all kernel parameters), obtained for each random assignment of training and test groups. In the upper triangles of each matrix, warmer colors (positive t -values) indicate that the neural feature indicated in the given row yielded higher accuracy than the feature indicated in the given column. Cooler colors (negative t -values) indicate that the feature in the given row yielded lower decoding accuracy than the feature in the given column. The lower triangles of each map denote the corresponding p -values for the t -tests. The diagonal entries display the relative average optimized weight given to each type of feature in a decoder that included all feature types (see *Feature weighting and testing*).

feature space of correlations (represented by a T by $O(K^2)$ matrix) onto a lower-dimensional feature space (represented by a T by K matrix). We carried out two sets of analyses that differed in how this mapping was computed. The first set of analyses used PCA to find a low-dimensional embedding of the original dynamic correlation matrices (Fig. 4a,b). The second set of analyses characterized correlations in dynamics of each feature's eigenvector centrality, but did not preserve the underlying activity dynamics (Fig. 4c,d).

Both sets of temporal decoding analyses yielded qualitatively similar results for the auditory (non-rest) conditions of the experiment (Fig. 4: pink, green, and teal lines; Fig. 5: three leftmost columns). The highest decoding accuracy for participants who listened to the intact (unscrambled) story was achieved using high-order dynamic correlations (PCA: second-order; eigenvector-centrality: fourth-order). Scrambled versions of the story were best decoded by lower-order correlations (PCA/paragraph: first-order; PCA/word: order zero; eigenvector centrality/paragraph: order zero; eigenvector centrality/word: order zero). The two sets of analyses yielded different decoding results on resting state data (Fig. 4: purple lines; Fig. 5: rightmost

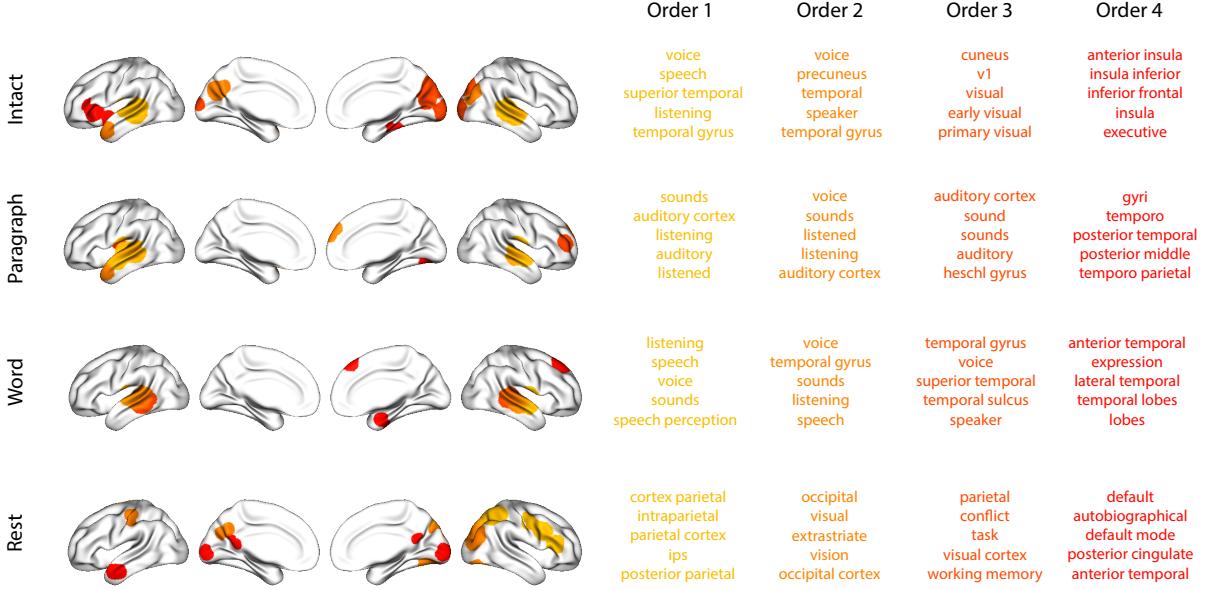


Figure 6: Top terms associated with the most strongly correlated nodes at each order. Each color corresponds to one order of inter-subject functional correlations. To calculate the dynamic correlations, eigenvector centrality has been used to project the high-dimensional patterns of dynamic correlations onto a lower-dimensional space at each previous order, which allows us to map the brain regions at each order by retaining the features of the original space. The inflated brain plots display the locations of the endpoints of the 10 strongest (absolute value) correlations at each order, thresholded at 0.999, and projected onto the cortical surface (Combrisson et al., 2019). The lists of terms on the right display the top five Neurosynth terms (Rubin et al., 2017) decoded from the corresponding brain maps for each order. Each row displays data from a different experimental condition. Additional maps and their corresponding Neurosynth terms may be found in the *Supplementary materials* (intact: Fig. S5; paragraph: Fig. S6; word: Fig. S7; rest: Fig. S8).

206 column). We note that, while the resting state times could be decoded reliably, the accuracies were only very
 207 slightly above chance. We speculate that the decoders might have picked up on attentional drift, boredom,
 208 or tiredness; we hypothesize that these all increased throughout the resting state scan. The decoders might
 209 be picking up on aspects of these loosely defined cognitive states that are common across individuals. The
 210 PCA-based approach achieved the highest resting state decoding accuracy using order zero features (non-
 211 correlational, activation-based), whereas the eigenvector centrality-based approach achieved the highest
 212 resting state decoding accuracy using second-order correlations. Taken together, these analyses indicate
 213 that high-level cognitive processing (while listening to the intact story) is reflected in the dynamics of high-
 214 order correlations in brain activity, whereas lower-level cognitive processing (while listening to scrambled
 215 versions of the story that lack rich meaning) is reflected in the dynamics of lower-order correlations and
 216 non-correlational activity dynamics. Further, these patterns are associated both with the underlying activity
 217 patterns (characterized using PCA) and also with the changing relative positions that different brain areas
 218 occupy in their associated networks (characterized using eigenvector centrality).

Having established that patterns of high-order correlations are informative to decoders, we next wondered which specific networks of brain regions contributed most to these patterns. As a representative example, we selected the kernel parameters that yielded decoding accuracies that were the most strongly correlated (across conditions and orders) with the average accuracies across all of the kernel parameters we examined. Using Figure 4c as a template, the best-matching kernel was a Laplace kernel with a width of 50 (Fig. 9d; also see Fig. S9). We used this kernel to compute a single K by K n^{th} -order DISFC matrix for each experimental condition. We then used Neurosynth (Rubin et al., 2017) to compute the terms most highly associated with the most strongly correlated pairs of regions in each of these matrices (Fig. 6; see *Reverse inference*).

For all of the story listening conditions (intact, paragraph, and word; top three rows of Fig. 6), we found that first- and second-order correlations were most strongly associated with auditory and speech processing areas. During intact story listening, third-order correlations reflected integration with visual areas, and fourth-order correlations reflected integration with areas associated with high-level cognition and cognitive control, such as the ventrolateral prefrontal cortex. However, when participants listened to temporally scrambled stories, these higher-order correlations instead involved interactions with additional regions associated with speech and semantic processing (second and third rows of Fig. 6). By contrast, we found a much different set of patterns in the resting state data (Fig. 6, bottom row). First-order resting state correlations were most strongly associated with regions involved in counting and numerical understanding. Second-order resting state correlations were strongest in visual areas; third-order correlations were strongest in task-positive areas; and fourth-order correlations were strongest in regions associated with autobiographical and episodic memory. We carried out analogous analyses to create maps (and decode the top associated Neurosynth terms) for up to fifteenth-order correlations (Figs. S5, S6, S7, and S8). Of note, examining fifteenth-order correlations between 700 nodes using conventional methods would have required storing roughly $\frac{700^{2 \times 15}}{2} \approx 1.13 \times 10^{85}$ floating point numbers—assuming single-precision (32 bits each), this would require roughly 32 times as many bits as there are molecules in the known universe! Although these fifteenth-order correlations do appear (visually) to have some well-formed structure, we provide this latter example primarily as a demonstration of the efficiency and scalability of our approach.

Discussion

We tested the hypothesis that high-level cognition is reflected in high-order brain network dynamics (e.g., see Reimann et al., 2017; Solomon et al., 2019). We examined high-order network dynamics in functional neuroimaging data collected during a story listening experiment. When participants listened to an auditory

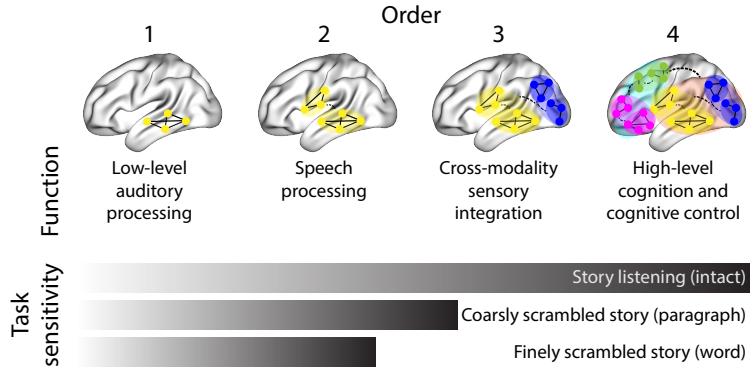


Figure 7: Proposed high-order network dynamics underlying high-level cognition during story listening. Schematic depicts higher orders of network interactions supporting higher-level aspects of cognitive processing. When tasks evoke richer, deeper, and/or higher-level processing, this is reflected in higher-order network interactions.

recording of the story, participants exhibited similar high-order brain network dynamics. By contrast, when participants instead listened to temporally scrambled recordings of the story, only lower-order brain network dynamics were similar across participants. Our results indicate that higher orders of network interactions support higher-level aspects of cognitive processing (Fig. 7).

The notion that cognition is reflected in (and possibly mediated by) patterns of first-order network dynamics has been suggested by or proposed in myriad empirical studies and reviews (e.g., Bressler & Kelso, 2001; Chang & Glover, 2010; Demertzi et al., 2019; Fong et al., 2019; Gonzalez-Castillo et al., 2019; Liégeois et al., 2019; Lurie et al., 2018; Manning et al., 2018; McIntosh, 2000; Park et al., 2018; Preti et al., 2017; Roy et al., 2019; Turk-Browne, 2013; Zou et al., 2019). Our study extends this line of work by finding cognitively relevant *higher-order* network dynamics that reflect ongoing cognition. Our findings also complement other work that uses graph theory and topology to characterize how brain networks reconfigure during cognition (e.g., Bassett et al., 2006; Betzel et al., 2019; McIntosh & Jirsa, 2019; Reimann et al., 2017; Sizemore et al., 2018; Toker & Sommer, 2019; Zheng et al., 2019).

An open question not addressed by our study pertains to how different structures integrate incoming information with different time constants. For example, one line of work suggests that the cortical surface comprises a structured map such that nearby brain structures process incoming information at similar timescales. Low-level sensory areas integrate information relatively quickly, whereas higher-level regions integrate information relatively slowly (Baldassano et al., 2017; Chien & Honey, 2019; Hasson et al., 2015, 2008; Honey et al., 2012; Lerner et al., 2014, 2011). A similar hierarchy appears to play a role in predicting future events (C. S. Lee et al., 2020). Other related work in human and mouse brains indicates that the temporal response profile of a given brain structure may relate to how strongly connected that structure is with other brain areas (Fallon et al., 2020). Further study is needed to understand the role of

272 temporal integration at different scales of network interaction, and across different anatomical structures.
273 Importantly, our analyses do not speak to the physiological basis of higher-order dynamics, and could
274 reflect nonlinearities, chaotic patterns, non-stationarities, and/or multistability, etc. However, our decoding
275 analyses do indicate that higher-order dynamics are consistent across individuals, and therefore unlikely to
276 reflect non-stimulus-driven dynamics that are unlikely to be similar across individuals.

277 One limitation of our approach relates to how noise propagates in our estimation procedure. Specifically,
278 our procedure for estimating high-order dynamic correlations depends on estimates of lower-order dynamic
279 correlations. This means that our measures of which higher-order patterns are reliable and stable across
280 experimental conditions are partially confounded with the stability of lower-order patterns. Prior work
281 suggests that the stability of what we refer to here as first-order dynamics likely varies across the experimental
282 conditions we examined (Simony et al., 2016). Therefore a caveat to our claim that richer stimuli evoke more
283 stable higher-order dynamics is that our approach assumes that those high-order dynamics reflect relations
284 or interactions between lower-order features.

285 Another potential limitation of our approach relates to recent work suggesting that the brain undergoes
286 rapid state changes, for example across event boundaries (e.g., Baldassano et al., 2017). Shappell et al.
287 (2019) used hidden semi-Markov models to estimate state-specific network dynamics (also see Vidaurre et
288 al., 2018). Our general approach might be extended by considering putative state transitions. For example,
289 rather than weighting all timepoints using a similar kernel (Eqn. 4), the kernel function could adapt on a
290 timepoint-by-timepoint basis such that only timepoints determined to be in the same “state” were given
291 non-zero weight.

292 Identifying high-order network dynamics associated with high-level cognition required several impor-
293 tant methods advances. First, we used kernel-based dynamic correlations to extended the notion of (static)
294 inter-subject functional connectivity (Simony et al., 2016) to a dynamic measure of inter-subject functional
295 connectivity (DISFC) that does not rely on sliding windows (e.g., as in Manning et al., 2018), and that may
296 be computed at individual timepoints. This allowed us to precisely characterize stimulus-evoked network
297 dynamics that were similar across individuals. Second, we developed a computational framework for
298 efficiently and scalably estimating high-order dynamic correlations. Our approach uses dimensionality
299 reduction algorithms and graph measures to obtain low-dimensional embeddings of patterns of network
300 dynamics. Third, we developed an analysis framework for identifying robust decoding results by carrying
301 out our analyses using a range of parameter values and identifying which results were robust to specific
302 parameter choices. By showing that high-level cognition is reflected in high-order network dynamics, we
303 have elucidated the next step on the path towards understanding the neural basis of cognition.

304 **Methods**

305 Our general approach to efficiently estimating high-order dynamic correlations comprises four general
306 steps (Fig. 8). First, we derive a kernel-based approach to computing dynamic pairwise correlations in
307 a T (timepoints) by K (features) multivariate timeseries, \mathbf{X}_0 . This yields a T by $O(K^2)$ matrix of dynamic
308 correlations, \mathbf{Y}_1 , where each row comprises the upper triangle and diagonal of the correlation matrix at
309 a single timepoint, reshaped into a row vector (this reshaped vector is $(\frac{K^2-K}{2} + K)$ -dimensional). Second,
310 we apply a dimensionality reduction step to project the matrix of dynamic correlations back onto a K -
311 dimensional space. This yields a T by K matrix, \mathbf{X}_1 , that reflects an approximation of the dynamic correlations
312 reflected in the original data. Third, we use repeated applications of the kernel-based dynamic correlation
313 step to \mathbf{X}_n and the dimensionality reduction step to the resulting \mathbf{Y}_{n+1} to estimate high-order dynamic
314 correlations. Each application of these steps to a T by K time series \mathbf{X}_n yields a T by K matrix, \mathbf{X}_{n+1} , that
315 reflects the dynamic correlations between the columns of \mathbf{X}_n . In this way, we refer to n as the *order* of the
316 timeseries, where \mathbf{X}_0 (order 0) denotes the original data and \mathbf{X}_n denotes (approximated) n^{th} -order dynamic
317 correlations between the columns of \mathbf{X}_0 . Finally, we use a cross-validation-based decoding approach to
318 evaluate how well information contained in a given order (or weighted mixture of orders) may be used
319 to decode relevant cognitive states. If including a given \mathbf{X}_n in the feature set yields higher classification
320 accuracy on held-out data, we interpret this as evidence that the given cognitive states are reflected in
321 patterns of n^{th} -order correlations.

322 All of the code used to produce the figures and results in this manuscript, along with links to the
323 corresponding datasets, may be found at github.com/ContextLab/timecorr-paper. In addition, we have
324 released a Python toolbox for computing dynamic high-order correlations in timeseries data; our toolbox
325 may be found at timecorr.readthedocs.io.

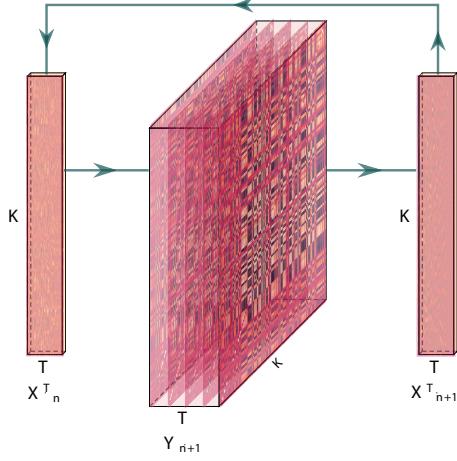


Figure 8: **Estimating dynamic high-order correlations.** Given a T by K matrix of multivariate timeseries data, \mathbf{X}_n (where $n \in \mathbb{N}, n \geq 0$), we use Equation 4 to compute a timeseries of K by K correlation matrices, \mathbf{Y}_{n+1} . We then approximate \mathbf{Y}_{n+1} with the T by K matrix \mathbf{X}_{n+1} . This process may be repeated to scalably estimate iteratively higher-order correlations in the data. Note that the transposes of \mathbf{X}_n and \mathbf{X}_{n+1} are displayed in the figure for compactness.

326 Kernel-based approach for computing dynamic correlations

Given a T by K matrix of observations, \mathbf{X} , we can compute the (static) Pearson's correlation between any pair of columns, $\mathbf{X}(\cdot, i)$ and $\mathbf{X}(\cdot, j)$ using (Pearson, 1901):

$$\text{corr}(\mathbf{X}(\cdot, i), \mathbf{X}(\cdot, j)) = \frac{\sum_{t=1}^T (\mathbf{X}(t, i) - \bar{\mathbf{X}}(\cdot, i))(\mathbf{X}(t, j) - \bar{\mathbf{X}}(\cdot, j))}{\sqrt{\sum_{t=1}^T \sigma_{\mathbf{X}(\cdot, i)}^2 \sigma_{\mathbf{X}(\cdot, j)}^2}}, \text{ where} \quad (1)$$

$$\bar{\mathbf{X}}(\cdot, k) = \frac{1}{T} \sum_{t=1}^T \mathbf{X}(t, k), \text{ and} \quad (2)$$

$$\sigma_{\mathbf{X}(\cdot, k)}^2 = \frac{1}{T} \sum_{t=1}^T (\mathbf{X}(t, k) - \bar{\mathbf{X}}(\cdot, k))^2 \quad (3)$$

327 We can generalize this formula to compute time-varying correlations by incorporating a *kernel function* that
 328 takes a time t as input, and returns how much the observed data at each timepoint $\tau \in [-\infty, \infty]$ contributes
 329 to the estimated instantaneous correlation at time t (Fig. 9; also see Allen et al., 2012, for a similar approach).

330

Given a kernel function $\kappa_t(\cdot)$ for timepoint t , evaluated at timepoints $\tau \in [1, \dots, T]$, we can update the

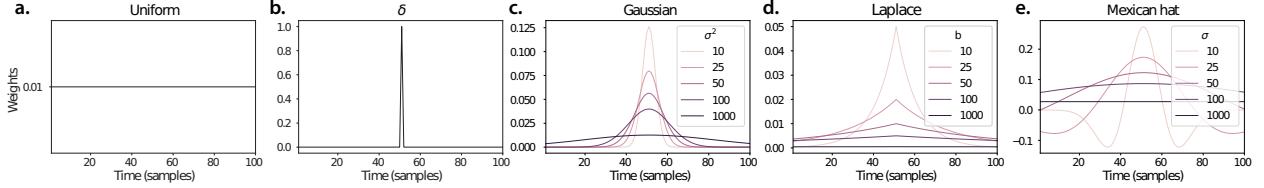


Figure 9: Examples of kernel functions. Each panel displays per-timepoint weights for a kernel centered at $t = 50$, evaluated at 100 timepoints ($\tau \in [1, \dots, 100]$). **a. Uniform kernel.** The weights are timepoint-invariant; observations at all timepoints are weighted equally, and do not change as a function of τ . This is a special case kernel function that reduces dynamic correlations to static correlations. **b. Dirac δ kernel.** Only the observation at timepoint t is given a non-zero weight (of 1). **c. Gaussian kernels.** Each kernel's weights fall off in time according to a Gaussian probability density function centered on time t . Weights derived using several different example width parameters (σ^2) are displayed. **d. Laplace kernels.** Each kernel's weights fall off in time according to a Laplace probability density function centered on time t . Weights derived using several different example width parameters (b) are displayed. **e. Mexican hat (Ricker wavelet) kernels.** Each kernel's weights fall off in time according to a Ricker wavelet centered on time t . This function highlights the *contrasts* between local versus surrounding activity patterns in estimating dynamic correlations. Weights derived using several different example width parameters (σ) are displayed.

static correlation formula in Equation 1 to estimate the *instantaneous correlation* at timepoint t :

$$\text{timecorr}_{\kappa_t}(\mathbf{X}(\cdot, i), \mathbf{X}(\cdot, j)) = \frac{\sum_{\tau=1}^T (\mathbf{X}(\tau, i) - \tilde{\mathbf{X}}_{\kappa_t}(\cdot, i))(\mathbf{X}(\tau, j) - \tilde{\mathbf{X}}_{\kappa_t}(\cdot, j))}{\sqrt{\sum_{\tau=1}^T \tilde{\sigma}_{\kappa_t}^2(\mathbf{X}(\cdot, i))\tilde{\sigma}_{\kappa_t}^2(\mathbf{X}(\cdot, j))}}, \text{ where} \quad (4)$$

$$\tilde{\mathbf{X}}_{\kappa_t}(\cdot, k) = \sum_{\tau=1}^T \kappa_t(\tau) \mathbf{X}(\tau, k), \quad (5)$$

$$\tilde{\sigma}_{\kappa_t}^2(\mathbf{X}(\cdot, k)) = \sum_{\tau=1}^T (\mathbf{X}(\tau, k) - \tilde{\mathbf{X}}_{\kappa_t}(\cdot, k))^2. \quad (6)$$

331 Here $\text{timecorr}_{\kappa_t}(\mathbf{X}(\cdot, i), \mathbf{X}(\cdot, j))$ reflects the correlation at time t between columns i and j of \mathbf{X} , estimated using
 332 the kernel κ_t . We evaluate Equation 4 in turn for each pair of columns in \mathbf{X} and for kernels centered on each
 333 timepoint in the timeseries, respectively, to obtain a T by K by K timeseries of dynamic correlations, \mathbf{Y} . For
 334 convenience, we then reshape the upper triangles and diagonals of each timepoint's symmetric correlation
 335 matrix into a row vector to obtain an equivalent T by $\left(\frac{K^2-K}{2} + K\right)$ matrix.

336 Dynamic inter-subject functional connectivity (DISFC)

Equation 4 provides a means of taking a single observation matrix, \mathbf{X}_n and estimating the dynamic correlations from moment to moment, \mathbf{Y}_{n+1} . Suppose that one has access to a set of multiple observation matrices that reflect the same phenomenon. For example, one might collect neuroimaging data from several experimental participants, as each participant performs the same task (or sequence of tasks). Let $\mathbf{X}_n^1, \mathbf{X}_n^2, \dots, \mathbf{X}_n^P$ reflect the T by K observation matrices ($n = 0$) or reduced correlation matrices ($n > 0$) for each of P

participants in an experiment. We can use *inter-subject functional connectivity* (ISFC; Simony & Chang, 2020; Simony et al., 2016) to compute the stimulus-driven correlations reflected in the multi-participant dataset at a given timepoint t using:

$$\bar{\mathbf{C}}(t) = M \left(R \left(\frac{1}{2P} \sum_{p=1}^P Z(\mathbf{Y}_{n+1}^p(t))^\top + Z(\mathbf{Y}_{n+1}^p(t)) \right) \right), \quad (7)$$

where M extracts and vectorizes the upper triangle and diagonal of a symmetric matrix, Z is the Fisher z -transformation (Zar, 2010):

$$Z(r) = \frac{\log(1+r) - \log(1-r)}{2}, \quad (8)$$

R is the inverse of Z :

$$R(z) = \frac{\exp(2z-1)}{\exp(2z+1)}, \quad (9)$$

and $\mathbf{Y}_{n+1}^p(t)$ denotes the correlation matrix at timepoint t (Eqn. 4) between each column of \mathbf{X}_n^p and each column of the average \mathbf{X}_n from all *other* participants, $\bar{\mathbf{X}}_n^p$:

$$\bar{\mathbf{X}}_n^p = \frac{1}{P-1} \sum_{q \in \setminus p} \mathbf{X}_n^q, \quad (10)$$

337 where $\setminus p$ denotes the set of all participants other than participant p . In this way, the T by $(\frac{K^2-K}{2} + K)$ DISFC
338 matrix $\bar{\mathbf{C}}$ provides a time-varying extension of the ISFC approach developed by Simony et al. (2016).

339 Low-dimensional representations of dynamic correlations

340 Given a T by $(\frac{K^2-K}{2} + K)$ matrix of n^{th} -order dynamic correlations, \mathbf{Y}_n , we propose two general approaches
341 to computing a T by K low-dimensional representation of those correlations, \mathbf{X}_n . The first approach uses
342 dimensionality reduction algorithms to project \mathbf{Y}_n onto a K -dimensional space. The second approach uses
343 graph measures to characterize the relative positions of each feature ($k \in [1, \dots, K]$) in the network defined
344 by the correlation matrix at each timepoint.

345 Dimensionality reduction-based approaches to computing \mathbf{X}_n

346 The modern toolkit of dimensionality reduction algorithms include Principal Components Analysis (PCA;
347 Pearson, 1901), Probabilistic PCA (PPCA; Tipping & Bishop, 1999), Exploratory Factor Analysis (EFA;

348 Spearman, 1904), Independent Components Analysis (ICA; Comon et al., 1991; Jutten & Herault, 1991),
349 *t*-Stochastic Neighbor Embedding (*t*-SNE; van der Maaten & Hinton, 2008), Uniform Manifold Approximation
350 and Projection (UMAP; McInnes et al., 2018), non-negative matrix factorization (NMF; D. D. Lee
351 & Seung, 1999), Topographic Factor Analysis (TFA; Manning et al., 2014), Hierarchical Topographic Factor
352 analysis (HTFA; Manning et al., 2018), Topographic Latent Source Analysis (TLSA; Gershman et al.,
353 2011), dictionary learning (J. Mairal et al., 2009; J. B. Mairal et al., 2009), and deep auto-encoders (Hinton
354 & Salakhutdinov, 2006), among others. While complete characterizations of each of these algorithms is
355 beyond the scope of the present manuscript, the general intuition driving these approaches is to compute
356 the T by K matrix, \mathbf{X} , that is closest to the original T by J matrix, \mathbf{Y} , where (typically) $K \ll J$. The different
357 approaches place different constraints on what properties \mathbf{X} must satisfy and which aspects of the data are
358 compared (and how) in order to optimize how well \mathbf{X} approximates \mathbf{Y} .

359 Applying dimensionality reduction algorithms to \mathbf{Y} yields an \mathbf{X} whose columns reflect weighted combi-
360 nations (or nonlinear transformations) of the original columns of \mathbf{Y} . This has two main consequences. First,
361 with each repeated dimensionality reduction, the resulting \mathbf{X}_n has lower and lower fidelity (with respect to
362 what the “true” \mathbf{Y}_n might have looked like without using dimensionality reduction to maintain tractability).
363 In other words, computing \mathbf{X}_n is a lossy operation. Second, whereas each column of \mathbf{Y}_n may be mapped
364 directly onto specific pairs of columns of \mathbf{X}_{n-1} , the columns of \mathbf{X}_n reflect weighted combinations and/or
365 nonlinear transformations of the columns of \mathbf{Y}_n . Many dimensionality reduction algorithms are invertible
366 (or approximately invertible). However, attempting to map a given \mathbf{X}_n back onto the original feature space
367 of \mathbf{X}_0 will usually require $O(TK^2)$ space and therefore becomes intractable as n or K grow large.

368 **Graph measure approaches to computing \mathbf{X}_n**

369 The above dimensionality reduction approaches to approximating a given \mathbf{Y}_n with a lower-dimensional
370 \mathbf{X}_n preserve a (potentially recombined and transformed) mapping back to the original data in \mathbf{X}_0 . We also
371 explore graph measures that instead characterize each feature’s relative *position* in the broader network of
372 interactions and connections. To illustrate the distinction between the two general approaches we explore,
373 suppose a network comprises nodes A and B , along with several other nodes. If A and B exhibit uncorrelated
374 activity patterns, then by definition the functional connection (correlation) between them will be close to
375 0. However, if A and B each interact with *other* nodes in similar ways, we might attempt to capture those
376 similarities between A ’s and B ’s interactions with those other members of the network.

377 In general, graph measures take as input a matrix of interactions (e.g., using the above notation, a K
378 by K correlation matrix or binarized correlation matrix reconstituted from a single timepoint’s row of \mathbf{Y}),

379 and return as output a set of K measures describing how each node (feature) sits within that correlation
380 matrix with respect to the rest of the population. Widely used measures include betweenness centrality (the
381 proportion of shortest paths between each pair of nodes in the population that involves the given node
382 in question; e.g., Barthélemy, 2004; Freeman, 1977; Geisberger et al., 2008; Newman, 2005; Opsahl et al.,
383 2010); diversity and dissimilarity (characterizations of how differently connected a given node is from others
384 in the population; e.g., Lin, 2009; Rao, 1982; Ricotta & Szeidl, 2006); eigenvector centrality and pagerank
385 centrality (measures of how influential a given node is within the broader network; e.g., Bonacich, 2007;
386 Halu et al., 2013; Lohmann et al., 2010; Newman, 2008); transfer entropy and flow coefficients (a measure of
387 how much information is flowing from a given node to other nodes in the network; e.g., Honey et al., 2007;
388 Schreiber, 2000); k -coreness centrality (a measure of the connectivity of a node within its local subgraph; e.g.,
389 Alvarez-Hamelin et al., 2005; Christakis & Fowler, 2010); within-module degree (a measure of how many
390 connections a node has to its close neighbors in the network; e.g., Rubinov & Sporns, 2010); participation
391 coefficient (a measure of the diversity of a node's connections to different subgraphs in the network; e.g.,
392 Rubinov & Sporns, 2010); and subgraph centrality (a measure of a node's participation in all of the network's
393 subgraphs; e.g., Estrada & Rodríguez-Velázquez, 2005); among others.

394 For a given graph measure, $\eta : \mathbb{R}^{K \times K} \rightarrow \mathbb{R}^K$, we can use η to transform each row of \mathbf{Y}_n in a way that
395 characterizes the corresponding graph properties of each column. This results in a new T by K matrix,
396 \mathbf{X}_n , that reflects how the features reflected in the columns of \mathbf{X}_{n-1} participate in the network during each
397 timepoint (row).

398 **Dynamic higher-order correlations**

399 Because \mathbf{X}_n has the same shape as the original data \mathbf{X}_0 , approximating \mathbf{Y}_n with a lower-dimensional \mathbf{X}_n
400 enables us to estimate high-order dynamic correlations in a scalable way. Given a T by K input matrix, the
401 output of Equation 4 requires $O(TK^2)$ space to store. Repeated applications of Equation 4 (i.e., computing
402 dynamic correlations between the columns of the outputted dynamic correlation matrix) each require
403 exponentially more space; in general the n^{th} -order dynamic correlations of a T by K timeseries occupies
404 $O(TK^{2^n})$ space. However, when we approximate or summarize the output of Equation 4 with a T by K matrix
405 (as described above), it becomes feasible to compute even very high-order correlations in high-dimensional
406 data. Specifically, approximating the n^{th} -order dynamic correlations of a T by K timeseries requires only
407 $O(TK^2)$ additional space— the same as would be required to compute first-order dynamic correlations. In
408 other words, the space required to store $n + 1$ multivariate timeseries reflecting up to n^{th} order correlations
409 in the original data scales linearly with n using our approach (Fig. 8).

410 **Data**

411 We examined two types of data: synthetic data and human functional neuroimaging data. We constructed
412 and leveraged the synthetic data to evaluate our general approach (for a related validation approach see
413 Thompson et al., 2018). Specifically, we tested how well Equation 4 could be used to recover known dynamic
414 correlations using different choices of kernel (κ ; Fig. 9), for each of several synthetic datasets that exhibited
415 different temporal properties. We also simulated higher-order correlations and tested how well Equation 4
416 could recover these correlations using the best kernel from the previous synthetic data analyses. We then
417 applied our approach to a functional neuroimaging dataset to test the hypothesis that ongoing cognitive
418 processing is reflected in high-order dynamic correlations. We used an across-participant classification test
419 to estimate whether dynamic correlations of different orders contain information about which timepoint in
420 a story participants were listening to.

421 **Synthetic data: simulating dynamic first-order correlations**

422 We constructed a total of 40–400 different multivariate timeseries, collectively reflecting a total of 4 qual-
423 itatively different patterns of dynamic first-order correlations (i.e., 10–100 datasets reflecting each type of
424 dynamic pattern). Each timeseries comprised 50 features (dimensions) that varied over 300 timepoints. The
425 observations at each timepoint were drawn from a zero-mean multivariate Gaussian distribution with a co-
426 variance matrix defined for each timepoint as described below. We drew the observations at each timepoint
427 independently from the draws at all other timepoints; in other words, for each observation $s_t \sim \mathcal{N}(\mathbf{0}, \Sigma_t)$ at
428 timepoint t , $p(s_t) = p(s_t | s_{\setminus t})$.

Constant. We generated data with stable underlying correlations to evaluate how Equation 4 characterized correlation “dynamics” when the ground truth correlations were static. We constructed 10–100 multivariate timeseries whose observations were each drawn from a single (stable) Gaussian distribution. For each dataset (indexed by m), we constructed a random covariance matrix, Σ_m :

$$\Sigma_m = \mathbf{C}\mathbf{C}^\top, \text{ where} \quad (11)$$

$$\mathbf{C}(i, j) \sim \mathcal{N}(0, 1), \text{ and where} \quad (12)$$

429 $i, j \in [1, 2, \dots, 50]$. In other words, all of the observations (for each of the 300 timepoints) within each dataset
430 were drawn from a multivariate Gaussian distribution with the same covariance matrix, and the 10–100
431 datasets each used a different covariance matrix.

432 **Random.** We generated a second set of 10–100 synthetic datasets whose observations at each timepoint were
 433 drawn from a Gaussian distribution with a new randomly constructed (using Eqn. 11) covariance matrix.
 434 Because each timepoint’s covariance matrix was drawn independently from the covariance matrices for all
 435 other timepoints, these datasets provided a test of reconstruction accuracy in the absence of any meaningful
 436 underlying temporal structure in the dynamic correlations underlying the data.

Ramping. We generated a third set of 10–100 synthetic datasets whose underlying correlations changed gradually over time. For each dataset, we constructed two *anchor* covariance matrices using Equation 11, Σ_{start} and Σ_{end} . For each of the 300 timepoints in each dataset, we drew the observations from a multivariate Gaussian distribution whose covariance matrix at each timepoint $t \in [0, \dots, 299]$ was given by

$$\Sigma_t = \left(1 - \frac{t}{299}\right)\Sigma_{\text{start}} + \frac{t}{299}\Sigma_{\text{end}}. \quad (13)$$

437 The gradually changing correlations underlying these datasets allow us to evaluate the recovery of dynamic
 438 correlations when each timepoint’s correlation matrix is unique (as in the random datasets), but where the
 439 correlation dynamics are structured and exhibit first-order autocorrelations (as in the constant datasets).

440 **Event.** We generated a fourth set of 10–100 synthetic datasets whose underlying correlation matrices
 441 exhibited prolonged intervals of stability, interspersed with abrupt changes. For each dataset, we used
 442 Equation 11 to generate 5 random covariance matrices. We constructed a timeseries where each set of
 443 60 consecutive samples was drawn from a Gaussian with the same covariance matrix. These datasets
 444 were intended to simulate a system that exhibits periods of stability punctuated by occasional abrupt state
 445 changes.

446 Synthetic data: simulating dynamic high-order correlations

447 We developed an iterative procedure for constructing timeseries data that exhibits known dynamic high-
 448 order correlations. The procedure builds on our approach to generating dynamic first-order correlations.
 449 Essentially, once we generate a timeseries with known first-order correlations, we can use the known first-
 450 order correlations as a template to generate a new timeseries of second-order correlations. In turn, we can
 451 generate a timeseries of third-order correlations from the second-order correlations, and so on. In general,
 452 we can generate order n correlations given a timeseries of order $n - 1$ correlations, for any $n > 1$. Finally,
 453 given the order n timeseries, we can reverse the preceding process to generate an order $n - 1$ timeseries, an
 454 order $n - 2$ order timeseries, and so on, until we obtain an order 0 timeseries of simulated data that reflects

455 the chosen high-order dynamics.

The central mathematical ~~operations~~ operation in our procedure ~~are two bookkeeping functions, `vec()` and `mat()`. The `vec()` function takes as input~~ is the Kronecker product (\otimes). The Kronecker product of a $K \times K$ symmetric matrix and returns as output a $(\frac{K^2-K}{2} + K)$ -dimensional column vector containing matrix, m_1 , with itself (i.e., $m_1 \otimes m_1$) produces a new $K^2 \times K^2$ matrix, m_2 whose entries reflect a scaled tiling of the entries in the upper triangle and diagonal. The `mat()` function inverts `vec()` by taking as input a $(\frac{K^2-K}{2} + K)$ -dimensional column vector and returning a $K \times K$ symmetric matrix as output. We can then generate an order m_1 . If these tilings (scaled copies of m_1) are indexed by row and column, then the tile in the i^{th} row and j^{th} column contains the entries of m_1 , multiplied by $m_1(i, j)$. Following this pattern, the Kronecker product $m_2 \otimes m_2$ yields the $K^4 \times K^4$ matrix m_3 whose tiles are scaled copies of m_2 . In general, repeated applications of the Kronecker self-product may be used to generate $m_{n+1} = m_n \otimes m_n$ for $n > 1$, where m_{n+1} is a $K^{2^n} \times K^{2^n}$ matrix. After generating a first-order timeseries of dynamic correlations (see *Synthetic data: simulating dynamic first-order correlations*), we use this procedure (applied independently at each timepoint) to transform it into a timeseries of n correlation matrices (for one timepoint, t) from an order $n - 1$ template (from the same timepoint) as follows:

$$\Sigma_n(t) = \text{mat}(\text{vec}(\Sigma_{n-1}(t)) \otimes \text{vec}(\Sigma_{n-1}(t))^\top).$$

456 n^{th} -order correlations. When m_{n+1} is generated in this way, the temporal structure of the full timeseries (i.e.,
457 constant, random, ramping, event) is preserved, since changes in the original first-order timeseries are also
458 reflected in the scaled tilings of itself that comprise the higher-order matrices.

Given a timeseries of ~~order- n correlation matrices, we can draw~~ n^{th} -order correlations, we then need to work “backwards” in order to generate the order-zero timeseries. If the n^{th} -order correlation matrix at a given timepoint is m_n , then we can generate an order $n - 1$ correlation matrix ~~for each timepoint t using~~

$$\sigma_{n-1}(t) \sim \mathcal{N}(0, \Sigma_n(t))$$

$$\Sigma_{n-1}(t) = \text{mat}(\sigma_{n-1}(t)).$$

459 We can then use repeated applications of Equations ?? and ?? in order to obtain a synthetic dataset.

460 When the template first-order correlations are constructed to exhibit different temporal profiles (e.g.,
461 using the constant, random, ramping, and event procedures described above), (for $n > 1$) by taking a draw
462 from $\mathcal{N}(0, m_n)$ and reshaping the resulting vector to have square dimensions. Intuitively, the resulting
463 re-shaped matrix will look like a noisy version of the template matrix, m_{n-1} . (When $n = 1$, no re-shaping

464 is needed; the resulting K -dimensional vector may be used as the observation at the given timepoint.)
465 After independently drawing each timepoint's order $n - 1$ correlation matrix from that timepoint's order
466 n correlation matrix, this process can be applied repeatedly until $n = 0$. This results in a K -dimensional
467 timeseries of T observations containing the specified high-order correlations and synthetic data will exhibit
468 the same category of temporal profile at orders 1 through n . Following our approach to generating synthetic
469 data exhibiting known first-order correlations, we constructed a total of 40–400 additional multivariate
470 timeseries, collectively reflecting a total of 4 qualitatively different patterns of dynamic correlations (i.e.,
471 10–100 datasets reflecting each type of dynamic pattern: constant, random, ramping, and event). Each
472 timeseries comprised 10 zero-order features (dimensions) that varied over 300 timepoints. After applying
473 our dynamic correlation estimation procedure, this yielded a 100-dimensional timeseries of first-order
474 features that could then be used to estimate dynamic second-order correlations. (We chose to use $K = 10$
475 zero-order features for our higher order simulations in order to put the accuracy computations displayed
476 in Figs. 2 and 3 on a roughly even footing.)

477 Functional neuroimaging data collected during story listening

478 We examined an fMRI dataset collected by Simony et al. (2016) that the authors have made publicly available
479 at arks.princeton.edu/ark:/88435/dsp015d86p269k. The dataset comprises neuroimaging data collected as
480 participants listened to an audio recording of a story (intact condition; 36 participants), listened to temporally
481 scrambled recordings of the same story (17 participants in the paragraph-scrambled condition listened to
482 the paragraphs in a randomized order and 36 in the word-scrambled condition listened to the words in a
483 randomized order), or lay resting with their eyes open in the scanner (rest condition; 36 participants). Full
484 neuroimaging details may be found in the original paper for which the data were collected (Simony et al.,
485 2016).

486 **Hierarchical topographic factor analysis (HTFA).** Following our prior related work, we used HTFA (Manning et al., 2018) to derive a compact representation of the neuroimaging data. In brief, this approach approximates the timeseries of voxel activations (44,415 voxels) using a much smaller number of radial basis function (RBF) nodes (in this case, 700 nodes, as determined by an optimization procedure described by Manning et al., 2018). This provides a convenient representation for examining full-brain network dynamics.
487 All of the analyses we carried out on the neuroimaging dataset were performed in this lower-dimensional
488 space. In other words, each participant's data matrix, X_0 , was a number-of-timepoints by 700 matrix of
489 HTFA-derived factor weights (where the row and column labels were matched across participants). Code
490 for carrying out HTFA on fMRI data may be found as part of the BrainIAK toolbox (Capota et al., 2017),
491

495 which may be downloaded at brainiak.org.

496 **Temporal decoding**

497 We sought to identify neural patterns that reflected participants' ongoing cognitive processing of incoming
498 stimulus information. As reviewed by Simony et al. (2016), one way of homing in on these stimulus-driven
499 neural patterns is to compare activity patterns across individuals (e.g., using ISFC analyses). In particular,
500 neural patterns will be similar across individuals to the extent that the neural patterns under consideration
501 are stimulus-driven, and to the extent that the corresponding cognitive representations are reflected in
502 similar spatial patterns across people (also see Simony & Chang, 2020). Following this logic, we used an
503 across-participant temporal decoding test developed by Manning et al. (2018) to assess the degree to which
504 different neural patterns reflected ongoing stimulus-driven cognitive processing across people (Fig. 10). The
505 approach entails using a subset of the data to train a classifier to decode stimulus timepoints (i.e., moments
506 in the story participants listened to) from neural patterns. We use decoding (forward inference) accuracy
507 on held-out data, from held-out participants, as a proxy for the extent to which the inputted neural patterns
508 reflected stimulus-driven cognitive processing in a similar way across individuals.

509 **Forward inference and decoding accuracy**

510 We used an across-participant correlation-based classifier to decode which stimulus timepoint matched
511 each timepoint's neural pattern (Fig. 10). We first divided the participants into two groups: a template group,
512 $\mathcal{G}_{\text{template}}$ (i.e., training data), and a to-be-decoded group, $\mathcal{G}_{\text{decode}}$ (i.e., test data). We used Equation 7 to
513 compute a DISFC matrix for each group ($\bar{\mathbf{C}}_{\text{template}}$ and $\bar{\mathbf{C}}_{\text{decode}}$, respectively). We then correlated the rows of
514 $\bar{\mathbf{C}}_{\text{template}}$ and $\bar{\mathbf{C}}_{\text{decode}}$ to form a number-of-timepoints by number-of-timepoints decoding matrix, Λ . In this
515 way, the rows of Λ reflected timepoints from the template group, while the columns reflected timepoints
516 from the to-be-decoded group. We used Λ to assign temporal labels to each row $\bar{\mathbf{C}}_{\text{decode}}$ using the row of
517 $\bar{\mathbf{C}}_{\text{template}}$ with which it was most highly correlated. We then repeated this decoding procedure, but using
518 $\mathcal{G}_{\text{decode}}$ as the template group and $\mathcal{G}_{\text{template}}$ as the to-be-decoded group. Given the true timepoint labels (for
519 each group), we defined the *decoding accuracy* as the average proportion of correctly decoded timepoints,
520 across both groups. We defined the *relative decoding accuracy* as the difference between the decoding accuracy
521 and chance accuracy (i.e., $\frac{1}{T}$).

522 **Feature weighting and testing**

523 We sought to examine which types of neural features (i.e., activations, first-order dynamic correlations, and
524 higher-order dynamic correlations) were informative to the temporal decoders. Using the notation above,
525 these features correspond to $\mathbf{X}_0, \mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3$, and so on.

526 One challenge to fairly evaluating high-order correlations is that if the kernel used in Equation 4 is
527 wider than a single timepoint, each repeated application of the equation will result in further temporal
528 blur. Because our primary assessment metric is temporal decoding accuracy, this unfairly biases against
529 detecting meaningful signal in higher-order correlations (relative to lower-order correlations). We attempted
530 to mitigate temporal blur in estimating each \mathbf{X}_n by using a Dirac δ function kernel (which places all of its
531 mass over a single timepoint; Fig. 9b, 10a) to compute each lower-order correlation ($\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_{n-1}$). We
532 then used a new (potentially wider, as described below) kernel to compute \mathbf{X}_n from \mathbf{X}_{n-1} . In this way,
533 temporal blurring was applied only in the last step of computing \mathbf{X}_n . We note that, because each \mathbf{X}_n is a
534 low-dimensional representation of the corresponding \mathbf{Y}_n , the higher-order correlations we estimated reflect
535 true correlations in the data with lower-fidelity than estimates of lower-order correlations. Therefore, even
536 after correcting for temporal blurring, our approach is still biased against finding meaningful signal in
537 higher-order correlations.

538 After computing each $\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_{n-1}$ for each participant, we divided participants into two equally sized
539 groups (± 1 for odd numbers of participants): $\mathcal{G}_{\text{train}}$ and $\mathcal{G}_{\text{test}}$. We then further subdivided $\mathcal{G}_{\text{train}}$ into $\mathcal{G}_{\text{train}_1}$
540 and $\mathcal{G}_{\text{train}_2}$. We then computed Λ (temporal correlation) matrices for each type of neural feature, using $\mathcal{G}_{\text{train}_1}$
541 and $\mathcal{G}_{\text{train}_2}$. This resulted in $n + 1$ Λ matrices (one for the original timeseries of neural activations, and one
542 for each of n orders of dynamic correlations). Our objective was to find a set of weights for each of these
543 Λ matrices such that the weighted average of the $n + 1$ matrices yielded the highest decoding accuracy.
544 We used quasi-Newton gradient ascent (Nocedal & Wright, 2006), using decoding accuracy (for $\mathcal{G}_{\text{train}_1}$ and
545 $\mathcal{G}_{\text{train}_2}$) as the objective function to be maximized, to find an optimal set of training data-derived weights,
546 $\phi_{0,1,\dots,n}$, where $\sum_{i=0}^n \phi_i = 1$ and where $\phi_i \geq 0 \forall i \in [0, 1, \dots, n]$.

547 After estimating an optimal set of weights, we computed a new set of $n + 1$ Λ matrices correlating the
548 DISFC patterns from $\mathcal{G}_{\text{train}}$ and $\mathcal{G}_{\text{test}}$ at each timepoint. We use the resulting decoding accuracy of $\mathcal{G}_{\text{test}}$
549 timepoints (using the weights in $\phi_{0,1,\dots,n}$ to average the Λ matrices) to estimate how informative the set of
550 neural features containing up to n^{th} order correlations were.

551 We used a permutation-based procedure to form stable estimates of decoding accuracy for each set of
552 neural features. In particular, we computed the decoding accuracy for each of 10 random group assignments
553 of $\mathcal{G}_{\text{train}}$ and $\mathcal{G}_{\text{test}}$. We report the mean accuracy (along with 95% confidence intervals) for each set of neural

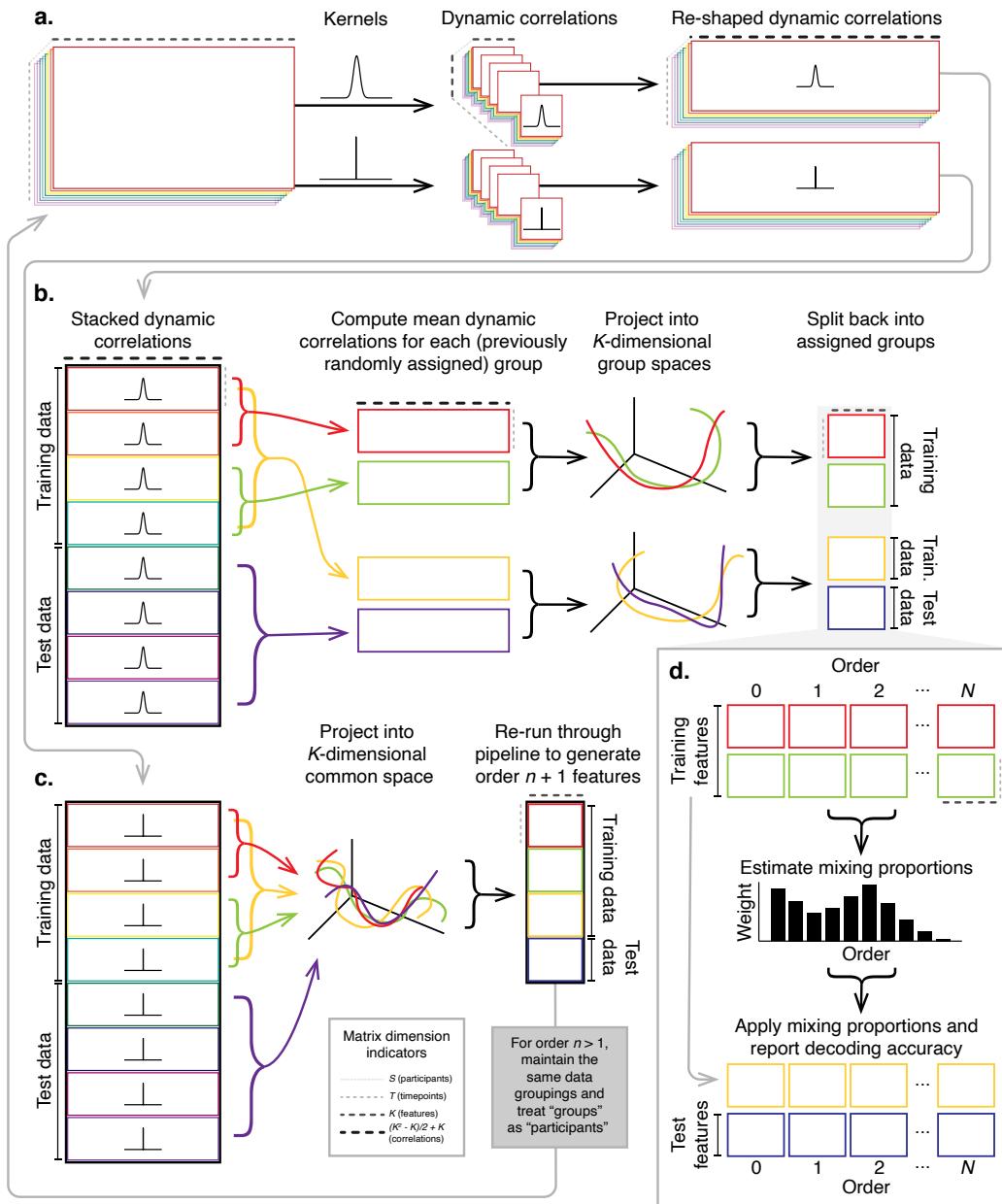


Figure 10: Decoding analysis pipeline. **a. Computing dynamic correlations from timeseries data.** Given a timeseries of observations as a $T \times K$ matrix (or a set of S such matrices), we use Equation 4 to compute each participant's DISFC (relative to other participants in the training or test sub-group, as appropriate). We repeat this process twice—once using the analysis kernel (shown here as a Gaussian in the upper row of the panel), and once using a δ function kernel (lower row of the panel). **b. Projecting dynamic correlations into a lower-dimensional space.** We project the training and test data into K -dimensional spaces to create compact representations of dynamic correlations at the given order (estimated using the analysis kernel). **c. Kernel trick.** We project the dynamic correlations computed using a δ function kernel into a common K -dimensional space. These low-dimensional embeddings are fed back through the analysis pipeline in order to compute features at the next-highest order. **d. Decoding analysis.** We split the training data into two equal groups, and optimize the feature weights (i.e., dynamic correlations at each order) to maximize decoding accuracy. We then apply the trained classifier to the (held-out) test data.

554 features.

555 **Identifying robust decoding results**

556 The temporal decoding procedure we use to estimate which neural features support ongoing cognitive
557 processing is governed by several parameters. In particular, Equation 4 requires defining a kernel function,
558 which can take on different shapes and widths. For a fixed set of neural features, each of these parameters
559 can yield different decoding accuracies. Further, the best decoding accuracy for a given timepoint may be
560 reliably achieved by one set of parameters, whereas the best decoding accuracy for another timepoint might
561 be reliably achieved by a different set of parameters, and the best decoding accuracy across *all* timepoints
562 might be reliably achieved by still another different set of parameters. Rather than attempting to maximize
563 decoding accuracy, we sought to discover the trends in the data that were robust to classifier parameters
564 choices. Specifically, we sought to characterize how decoding accuracy varied (under different experimental
565 conditions) as a function of which neural features were considered.

566 To identify decoding results that were robust to specific classifier parameter choices, we repeated our
567 decoding analyses after substituting into Equation 4 each of a variety of kernel shapes and widths. We
568 examined Gaussian (Fig. 9c), Laplace (Fig. 9d), and Mexican Hat (Fig. 9e) kernels, each with widths of 5, 10,
569 20, and 50 samples. We then report the average decoding accuracies across all of these parameter choices.
570 This enabled us to (partially) factor out performance characteristics that were parameter-dependent, within
571 the set of parameters we examined.

572 **Reverse inference**

573 The dynamic patterns we examined comprise high-dimensional correlation patterns at each timepoint. To
574 help interpret the resulting patterns in the context of other studies, we created summary maps by computing
575 the across-timepoint average pairwise correlations at each order of analysis (first order, second order, etc.).
576 We selected the 10 strongest (absolute value) correlations at each order. Each correlation is between the
577 dynamic activity patterns (or patterns of dynamic high-order correlations) measured at two RBF nodes
578 (see *Hierarchical Topographic Factor Analysis*). Therefore, the 10 strongest correlations involved up to 20 RBF
579 nodes. Each RBF defines a spatial function whose activations range from 0 to 1. We constructed a map
580 of RBF components that denoted the endpoints of the 10 strongest correlations (we set each RBF to have a
581 maximum value of 1). We then carried out a meta analysis using Neurosynth (Rubin et al., 2017) to identify
582 the 10 terms most commonly associated with the given map. This resulted in a set of 10 terms associated
583 with the average dynamic correlation patterns at each order.

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