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An examination of the high-order dynamic interactions 2 underlying multi-dimensional timeseries data

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5 **Abstract**

6 Most complex systems reflect dynamic interactions between myriad evolving components (e.g., interacting
7 molecules, interacting brain systems, interacting individuals within a social network or ecological
8 system, coordinated components within a mechanical or digital device, etc.). Despite that these interactions
9 are central to the full system’s behavior (e.g., removing a component from the full system can change the
10 entire system’s behavior), dynamic interactions cannot typically be directly measured. Rather, the interactions
11 must be inferred through their hypothesized role in guiding the dynamics of system components.
12 Here we use a model-based approach to inferring dynamic interactions from timeseries data. In addition
13 to examining first-order interactions (e.g., between pairs of components) we also examine higher-order
14 interactions (e.g., that characterize mirrored structure in the patterns of interaction dynamics displayed
15 by different subsets of components). We apply our approach to two datasets. First, we use a synthetic
16 dataset, for which the underlying dynamic interactions are known, to show that our model recovers those
17 ground-truth dynamic interactions. We also apply our model to a neuroimaging dataset and show that the
18 high-order dynamic interactions exhibited by brain data vary meaningfully as a function of the cognitive
19 “richness” of the stimulus people are experiencing.

20 **Introduction**

21 The dynamics of the observable universe are meaningful in three respects. First, the behaviors of the *atomic*
22 *units* that exhibit those dynamics are highly interrelated. The actions of one unit typically have implications
23 for one or more other units. In other words, there is non-trivial *correlational structure* defining how different
24 units interact with and relate to each other. Second, that correlational structure is *hierarchical* in the sense
25 that it exists on many spatiotemporal scales. The way one group of units interacts may relate to how another
26 group of units interact, and the interactions between those groups may exhibit some rich structure. Third,
27 the structure at each level of this correlational hierarchy changes from moment to moment, reflecting the
28 “behavior” of the full system.

29 These three properties (rich correlations, hierarchical organization, and dynamics) are major hallmarks
30 of many complex systems. For example, within a single cell, the cellular components interact at many

31 spatiotemporal scales, and those interactions change according to what that single cell is doing. Within a
32 single human brain, the individual neurons interact within each brain structure, and the structures interact
33 to form complex networks. The interactions at each scale vary according to the functions our brains are
34 carrying out. And within social groups, interactions at different scales (e.g., between individuals, family
35 units, communities, etc.) vary over time according to changing goals and external constraints.

36 Although many systems exhibit rich dynamic correlations at many scales, a major challenge to studying
37 such patterns is that typically neither the correlations nor the hierarchical organizations of those correlations
38 may be directly observed. Rather, these fundamental properties must be inferred indirectly by examining
39 the observable parts of the system— e.g., the behaviors of the individual atomic units of that system. In
40 the *Methods* section, we propose a series of mathematical operations that may be used to recover dynamic
41 correlations at a range of scales (i.e., orders of interaction). In the *Results* section, we demonstrate how our
42 approach may be applied to multi-dimensional timeseries data: a synthetic dataset where the underlying
43 dynamic correlations are known (we use this dataset to validate our approach), and a neuroimaging dataset
44 comprising data collected as participants listened to a story (Simony et al., 2016). In different experimental
45 conditions in the neuroimaging study, participants listened to altered versions of the story that varied in
46 cognitive richness: the intact story (fully engaging), a scrambled version of the story where the paragraphs
47 were presented in a randomized order (moderately engaging), a second scrambled condition where the
48 words were presented in a random order (minimally engaging), and a “rest” condition where the participants
49 did not listen to any version of the story (control condition). We use the neuroimaging dataset to examine
50 how higher-order structure in brain data varies as a function of the cognitive richness of the stimulus.

51 Methods

52 There are two basic steps to our approach (Fig. 2). In the first step, we take a number-of-timepoints (T) by
53 number-of-features (F) *matrix of observations* (\mathbf{X}) and we return a T by $\frac{F^2-F}{2}$ *matrix of dynamic correlations* (\mathbf{Y}).
54 Here \mathbf{Y}_0 describes, at each moment, how all of the features (columns of \mathbf{X}) are inferred to be interacting.
55 (Since the interactions are assumed to be non-recurrent and symmetric, only the upper triangle of the full
56 correlation matrix is computed.) In the second step, we project \mathbf{Y}_0 onto an F -dimensional space, resulting in
57 a new T by F matrix \mathbf{Y}_1 . Note that \mathbf{Y}_1 contains information about the correlation dynamics present in \mathbf{X} , but
58 represented in a compressed number of dimensions. By repeatedly applying these two steps in sequence,
59 we can examine and explore higher order dynamic correlations in \mathbf{X} .

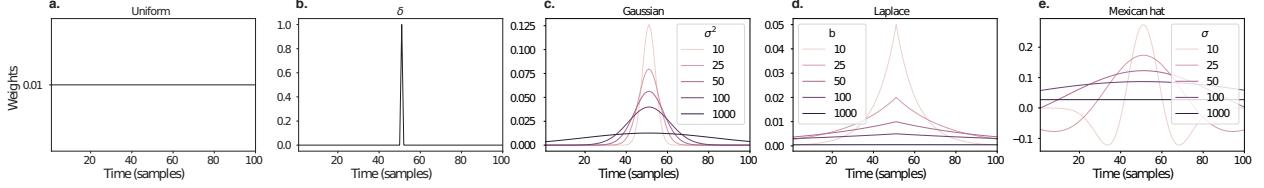


Figure 1: **Examples of time-varying weights.** Each panel displays per-timepoint weights at $t = 50$, evaluated for 100 timepoints (1, ..., 100). **a. Uniform weights.** The weights are timepoint-invariant; observations at all timepoints are weighted equally, and do not change as a function of t . This is a special case of weight function that reduces dynamic correlations to static correlations. **b. Dirac delta function.** Only the observation at timepoint t is given weight (of 1), and weights for observations at all other timepoints are set to 0. **c. Gaussian weights.** Each observation's weights fall off in time according to a Gaussian probability density function centered on $\mu = t$. Weights derived using several different example variance parameters (σ^2) are displayed. **d. Laplace weights.** Each observation's weights fall off in time according to a Laplace probability density function centered on $\mu = t$. Weights derived using several different example scale parameters (b) are displayed. **e. Mexican hat (Ricker wavelet) weights.** Each observation's weights fall off in time according to a Ricker wavelet centered on t . This function highlights the *contrasts* between local versus surrounding activity patterns in estimating dynamic correlations. Weights derived using several different example width parameters (σ) are displayed.

60 Dynamic correlations

Given a matrix of observations, we can compute the (static) correlations between any pair of observations, \mathbf{X}_i and \mathbf{X}_j using:

$$\text{corr}(\mathbf{X}_i, \mathbf{X}_j) = \frac{\sum_{t=1}^T (\mathbf{X}_i(t) - \bar{\mathbf{X}}_i)(\mathbf{X}_j(t) - \bar{\mathbf{X}}_j)}{\sqrt{\sum_{t=1}^T \sigma_{\mathbf{X}_i}^2 \sigma_{\mathbf{X}_j}^2}}, \text{ where} \quad (1)$$

$$\bar{\mathbf{X}}_k = \sum_{t=1}^T \mathbf{X}_k(t), \text{ and} \quad (2)$$

$$\sigma_{\mathbf{X}_k}^2 = \sum_{t=1}^T (\mathbf{X}_k(t) - \bar{\mathbf{X}}_k)^2 \quad (3)$$

61 We can generalize this formula to compute time-varying correlations by incorporating a *weight function*
62 that takes a time t as input, and returns how much the observed data every timepoint (including t) contribute
63 to the correlations at time t (Fig. 1).

Given a weight function $w(t)$ for timepoint t , evaluated at timepoints in the interval $[1, \dots, T]$, we can

extend the static correlation formula in Equation 2 to reflect an *instantaneous correlation* at timepoint t :

$$\text{timecorr}(\mathbf{X}_i, \mathbf{X}_j, t) = \frac{\sum_{t=1}^T (\mathbf{X}_i(t) - \tilde{\mathbf{X}}_i(t))(\mathbf{X}_j(t) - \tilde{\mathbf{X}}_j(t))}{\sqrt{\sum_{t=1}^T \tilde{\sigma}_{\mathbf{X}_i}^2(t) \tilde{\sigma}_{\mathbf{X}_j}^2(t)}}, \text{ where} \quad (4)$$

$$\tilde{\mathbf{X}}_k(t) = \sum_{i=1}^T w(t, i) \mathbf{X}_k(i), \quad (5)$$

$$\tilde{\sigma}_{\mathbf{X}_k}^2(t) = \sum_{i=1}^T (\mathbf{X}_k(i) - \tilde{\mathbf{X}}_k(t))^2, \quad (6)$$

- and $w(t, i)$ is shorthand for $w(t)$ evaluated at timepoint i . Equation 5 may be used to estimate the instantaneous correlations between every pair of observations, at each timepoint (i.e., \mathbf{Y}).

66 Inter-subject dynamic correlations

Equation 5 provides a means of taking a single observation matrix, \mathbf{X} and estimating the dynamic correlations from moment to moment, \mathbf{Y} . Suppose that one has access to a set of multiple observation matrices that reflect the same phenomenon. For example, one might collect neuroimaging data from several experimental participants, as each participant performs the same task (or sequence of tasks). Let $\{\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_P\}$ reflect the T by F observation matrices for each of P participants in an experiment. We can use *inter-subject functional connectivity* (ISFC; Simony et al., 2016) to compute the degree of stimulus-driven correlations reflected in the multi-participant dataset at a given timepoint t using:

$$\bar{\mathbf{C}}(t) = M \left(R \left(\frac{1}{2P} \sum_{i=1}^P Z(Y_i(t))^T + Z(Y_i(t)) \right) \right), \quad (7)$$

where M extracts and vectorizes the diagonal and upper triangle of a symmetric matrix, Z is the Fisher z -transformation (Zar, 2010):

$$Z(r) = \frac{\log(1+r) - \log(1-r)}{2} \quad (8)$$

R is the inverse of Z :

$$R(z) = \frac{\exp(2z-1)}{\exp(2z+1)}, \quad (9)$$

and $\mathbf{Y}_i(t)$ denotes the correlation matrix (Eqn. 2) between each column of \mathbf{X}_i and each column of the average observations from all *other* participants, $\bar{\mathbf{X}}_{\setminus i}$:

$$\bar{\mathbf{X}}_{\setminus i} = R \left(\frac{1}{P-1} \sum_{i \in \setminus i} Z(\mathbf{X}_i) \right), \quad (10)$$

where $\setminus i$ denotes the set of all participants other than participant i . In this way, the T by $\left(\frac{F^2-F}{2} + F\right)$ matrix $\bar{\mathbf{C}}$ is the time-varying extension of the ISFC approach developed by Simony et al. (2016).

69 Higher-order correlations

Given a timeseries of dynamic correlations (e.g., obtained using Eqn. 5), higher-order correlations reflect the dynamic correlations between columns of \mathbf{Y} . Given unlimited computing resources, one could use repeated applications of Equation 5 to estimate these higher-order correlations (i.e., substituting in the previous output, \mathbf{Y} , for the input, \mathbf{X} in the equation). However, because each output \mathbf{Y} has $O(F^2)$ columns relative to F columns in the input \mathbf{X} , the output of Equation 5 grows with the square of the number of repeated applications (total cost of computing n^{th} order correlations is $O(F^{2n})$ for $n \in \mathcal{J}, n > 0$). When F or n is large, this approach quickly becomes intractable.

To make progress in computing \mathbf{Y}_{n+1} , we can approximate \mathbf{Y}_n by computing an $O(F)$ -dimensional embedding of \mathbf{Y}_n , termed $\hat{\mathbf{Y}}_n$, and then we can apply Equation 5 to $\hat{\mathbf{Y}}_n$ rather than directly to \mathbf{Y}_n . This enables us to maintain $O(n)$ scaling with respect to n , rather than exponential scaling via the direct approach.

There are many possible methods for computing $\hat{\mathbf{Y}}_n$ from \mathbf{Y}_n , including traditional dimensionality reduction approaches and graph theory based approaches as described next. In the *Discussion* section we elaborate on other potential approaches.

83 Dimensionality reduction-based approaches to computing $\hat{\mathbf{Y}}_n$

Commonly used dimensionality reduction algorithms include Principal Components Analysis (PCA; Pearson, 1901), Probabilistic PCA (PPCA; Tipping & Bishop, 1999), Exploratory Factor Analysis (EFA; Spearman, 1904), Independent Components Analysis (ICA; Jutten & Herault, 1991; Comon et al., 1991), t -Stochastic Neighbor Embedding (t -SNE; van der Maaten & Hinton, 2008), Uniform Manifold Approximation and Projection (UMAP; McInnes & Healy, 2018), non-negative matrix factorization (NMF; Lee & Seung, 1999), Topographic Factor Analysis (TFA) Manning et al. (2014), Hierarchical Topographic Factor analysis (HTFA) Manning et al. (2018), Topographic Latent Source Analysis (TLSA) Gershman et al. (2011), Dictionary learning (J. B. Mairal et al., 2009; J. Mairal et al., 2009), deep autoencoders (Hinton & Salakhutdinov,

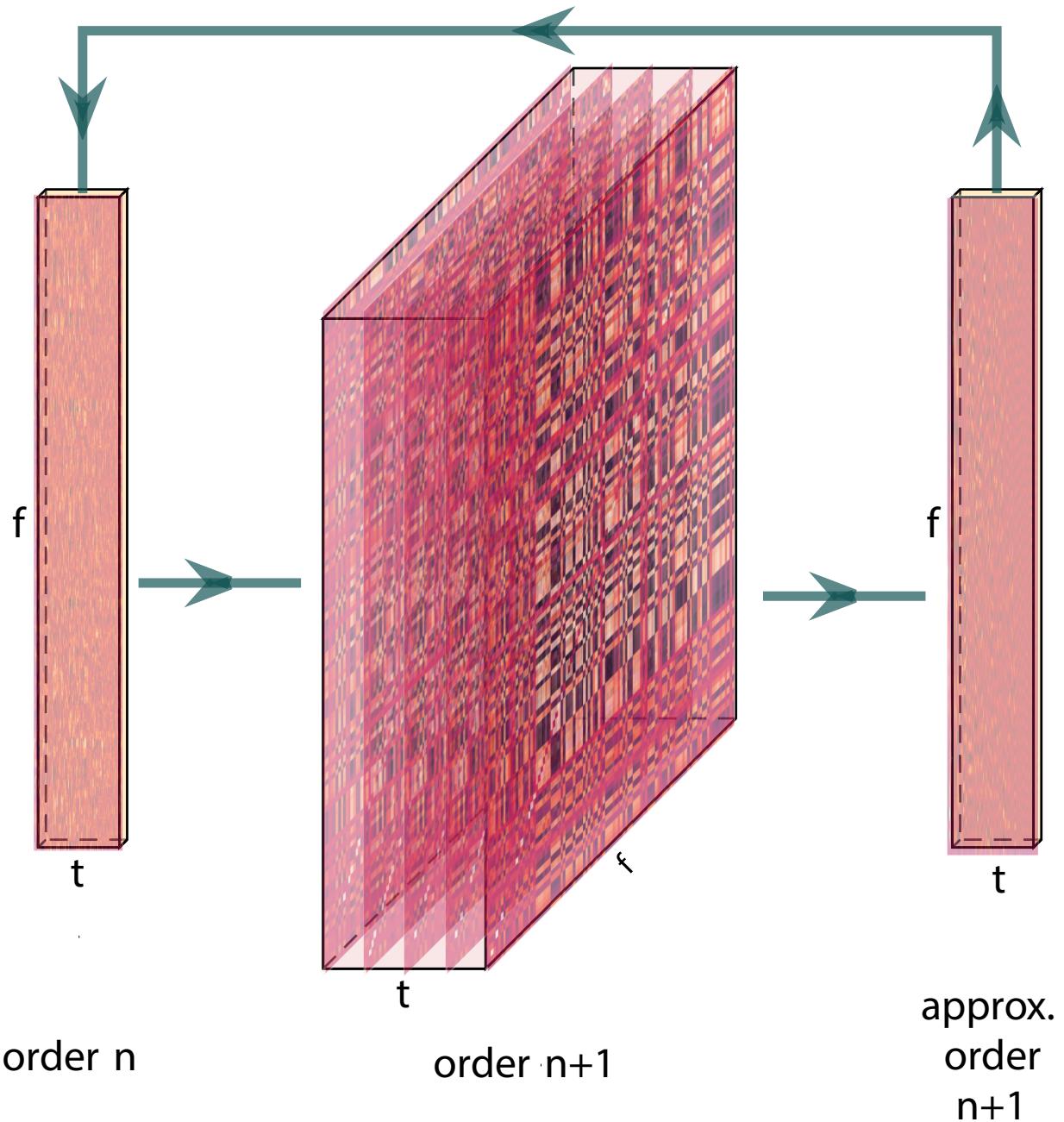


Figure 2: **Computing higher order correlations.** Correlations are computed then approximated to the same size as original data. This process is repeated to computer

92 among others. While complete characterizations of each of these algorithms is beyond the scope of
93 the present manuscript, the general intuition driving these approaches is to compute the $\hat{\mathbf{Y}}$ with i columns
94 that is closest to the original \mathbf{Y} with j columns, and where (typically) $i \ll j$. The different approaches place
95 different constraints on what properties $\hat{\mathbf{Y}}$ must satisfy and which aspects of the data are compared (and
96 how) to characterize the match between $\hat{\mathbf{Y}}$ and \mathbf{Y} .

97 Applying dimensionality reduction algorithms to \mathbf{Y} yields a $\hat{\mathbf{Y}}$ whose columns reflect weighted combi-
98 nations (or nonlinear transformations) of the original columns of \mathbf{Y} . This has two main consequences. First,
99 with each repeated dimensionality reduction, the resulting $\hat{\mathbf{Y}}_n$ has lower and lower fidelity (with respect to
100 what the “true” \mathbf{Y}_n might have looked like without using dimensionality reduction to maintain scalability).
101 In other words, computing $\hat{\mathbf{Y}}_n$ is a lossy operation. Second, whereas the columns of \mathbf{Y}_n may be mapped
102 directly onto pairs of columns of \mathbf{Y}_{n-1} , that mapping either becomes less cleanly defined in $\hat{\mathbf{Y}}_n$ due to the
103 reweightings and/or nonlinear transformations.

104 **Graph theory-based approaches to computing $\hat{\mathbf{Y}}_n$**

105 Graph theoretic measures take as input a matrix of interactions (e.g., using the above notation, an $F \times F$
106 correlation matrix or binarized correlation matrix reconstituted from a single timepoint’s row of \mathbf{Y}) and
107 return as output a set of F measures describing how each node (feature) sits within that interactions matrix
108 with respect to the rest of the population. Common measures include betweenness centrality (the proportion
109 of shortest paths between each pair of nodes in the population that involves the given node in question; e.g.,
110 Newman, 2005; Opsahl et al., 2010; Barthélemy, 2004; Geisberger et al., 2008; Freeman, 1977); diversity and
111 dissimilarity (characterizations of how differently connected a given node is from others in the population;
112 e.g., Rao, 1982; Lin, 2009; Ricotta & Szeidl, 2006); Eigenvector centrality and pagerank centrality (measures of
113 how influential a given node is within the broader network; e.g., Newman, 2008; Bonacich, 2007; Lohmann
114 et al., 2010; Halu et al., 2013); transfer entropy and flow coefficients (a measure of how much information is
115 flowing from a given node to other nodes in the network; e.g., Honey et al., 2007; Schreiber, 2000); k -coreness
116 centrality (a measure of the connectivity of a node within its local sub-graph; e.g., Alvarez-Hamelin et al.,
117 2005; Christakis & Fowler, 2010); within-module degree (a measure of how many connections a node has to
118 its close neighbors in the network; e.g., Rubinov & Sporns, 2010); participation coefficient (a measure of the
119 diversity of a node’s connections to different sub-graphs in the network; e.g., Rubinov & Sporns, 2010); and
120 sub-graph centrality (a measure of a node’s participation in all of the network’s sub-graphs; e.g., Estrada &
121 Rodríguez-Velázquez, 2005).

122 As an alternative to the above dimensionality reduction approach to embedding \mathbf{Y}_n in a lower-dimensional

space, but still allowing for scalable explorations of higher-order structure in the data, we also explore using the above graph theoretic measures as a means of obtaining $\hat{\mathbf{Y}}_n$. In particular: for a given graph theoretic measure, $\eta : \mathcal{R}^{F \times F} \rightarrow \mathcal{R}^F$, we can use η to transform each row of \mathbf{Y}_n in a way that characterizes the corresponding graph-theoretic properties of each column. Whereas the dimensionality reduction approach to computing $\hat{\mathbf{Y}}_n$ is lossy, the graph-theory approach is lossless. However, whereas the dimensionality reduction approach maintains ties (direct or indirect) to the original activity patterns reflected in \mathbf{Y}_{n-1} , the graph-theory approach does not. Instead, the graph-theory characterizes the nature and timecourse of each feature's *participation* in the network.

131 Evaluation metrics

132 We evaluate our approach to extracting dynamic correlations and higher-order correlations using several
133 metrics detailed next. First, we generated synthetic data using known time-varying correlations, and then
134 we evaluated the fidelity with which Equation 5 could recover those correlations (for synthetic datasets
135 with different properties, and using different kernels to define the weights; Fig. 1). We then turned to a
136 series of analyses on a (real) neuroimaging dataset where the ground truth correlations were *not* known.
137 We evaluated whether the recovered correlations could be used to accurately label held-out neuroimaging
138 data with the time at which it was collected. We used this latter evaluations (using timepoint decoding)
139 as a proxy for gauging how much explanatory power the recovered correlations held with respect to the
140 observed data.

141 Generating synthetic data

142 Ramping dataset and block dataset. Add details (Fig. 3)

143 Recovery of ground truth parameters from synthetic data

To explore recovery of a constant correlation, we generated synthetic data sampled from a constant covariance matrix. To do this, we created a random correlation matrix K of size s , and added a small amount of Gaussian noise to create a timeseries of for s subjects. $\sim N(\mu, \sigma^2)$

144 We applied timecorr with a given kernel (Fig. 1) to synthetic data, then correlate each recovered correlation
145 matrix with the ground truth. Explore how recovery varies with the kernel, kernel parameters, and specific
146 structure of the data (e.g. slow changes as in the ramping dataset, versus rapid changes as in the block
147 dataset).

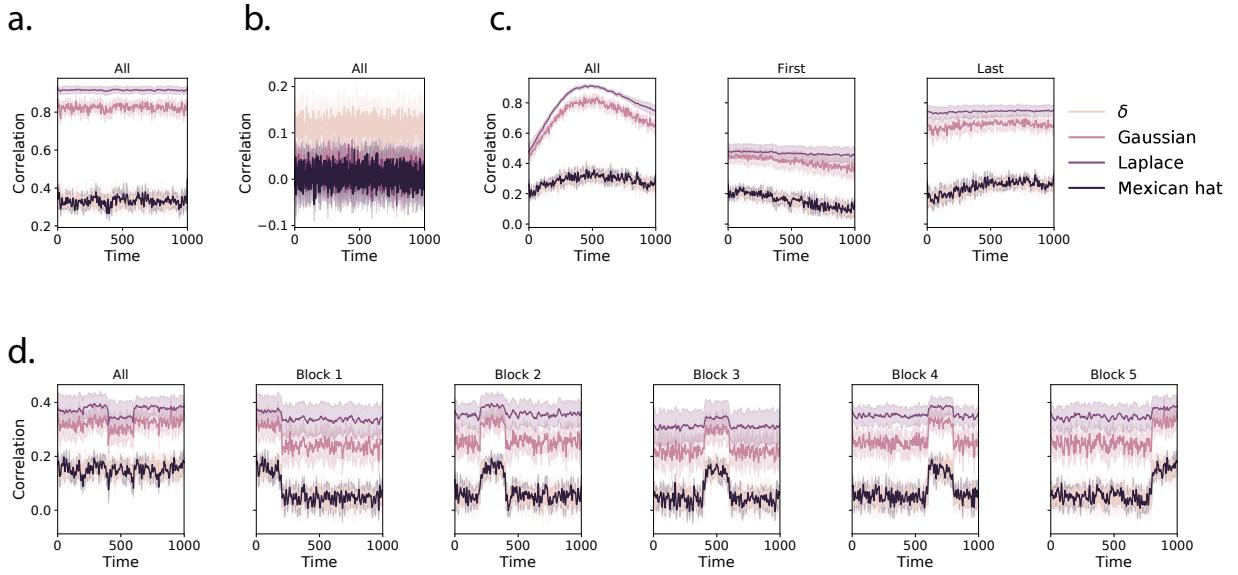


Figure 3: Dynamic correlation recovery with synthetic data. **a.** Recovery using a constant dataset. Using constant dataset, how well can we recover using different kernels. **b.** Recovery using random dataset. **c.** Ramping recovery. **d.** Block recovery

148 Timepoint decoding

149 To explore how higher-order structure varies with stimulus structure and complexity, we used a previous
 150 neuroimaging dataset Simony et al. (2016) in which participants listened to an audio recording of a story;
 151 36 participants listen to an intact version of the story, 17 participants listen to time-scrambled recordings of
 152 the same story where paragraphs were scrambled, 36 participants listen to word-scrambled version and 36
 153 participants lay in rest condition.

154 Prior work has shown participants share similar neural responses to richly structured stimuli when
 155 compared to stimuli with less structure. To assess whether the moment-by-moment higher order correlations
 156 were reliably preserved across participants, we used inter-subject functional connectivity (ISFC) to isolate
 157 the time-varying correlational structure (functional connectivity patterns that were specifically driven by
 158 the story participants listened to. Following the analyses conducted by (HTFA) Manning et al. (2018), we
 159 first applied *hierarchical topographic factor analysis* (HTFA) to the fMRI datasets to obtain a time series of
 160 700 node activities for every participant. We then computed the dynamic weighted ISFC using a gaussian
 161 kernel with a width of 5. We then approximated these dynamic correlation using PCA and computed the
 162 dynamic weighted ISFC on the approximations. We repeated this process up to 10th order approximated
 163 correlations.

164 To assess decoding accuracy, we randomly divided participants for each stimulus into training and

165 testing groups. For the zeroth order, we computed the mean factor activity for each group. For all subsequent
166 orders up to the tenth order, we computed the mean approximated dynamic ISFC of factor activity for each
167 group. To assess how additional higher-order correlations contribute to decoding accuracy, for each order
168 we included a weighted-mixture (described below) of the activity patterns of all previous orders. For each
169 group of participants in turn, we compared these activity patterns (using Pearson correlations) to estimate
170 the story times each pattern corresponded to. Specifically, we asked, for each timepoint: what are the
171 correlations between the first group's and second group's activity patterns at each order. We note that the
172 decoding test we used is a conservative in which we count a timepoint label as incorrect if it is not an exact
173 match.

174 For each order we obtained the weighted-mixture of the correlation matrices for the current order and
175 all previous orders using mixing parameter ϕ , where $0 < \phi < 1$ reflects a weighted mixture of order
176 based decoding Fig. ?? Panel C.). We calculated ϕ , by subdividing the training group and using the quasi-
177 Newton method of Broyden, Fletcher, Goldfarb, and Shanno (BFGS) for optimization. We repeated this
178 cross-validation process 100 times.

179 Results

180 Synthetic data

181 Figure: overall timecourse of recovery, also recovery near event boundaries.

182 Neuroimaging dataset (Simony et al., 2016)

183 For our decoding analysis, we used HTFA-derived node activities Manning et al. (2018) from fMRI data
184 collected as participants listened to an audio recording of a story (intact condition; 36 participants), lis-
185 tened to time scrambled recordings of the same story (17 participants in the paragraph-scrambled condition
186 listened to the paragraphs in a randomized order and 36 in the word-scrambled condition listened to
187 the words in a randomized order), or lay resting with their eyes open in the scanner (rest condition; 36
188 participants). We sought to demonstrate how higher-order correlations may be used to examine dynamic
189 interactions of brain patterns in (real) multi-subject fMRI datasets. This story listening dataset was col-
190 lected as part of a separate study, where the full imaging parameters, image preprocessing methods, and
191 experimental details may be found (Simony et al., 2016). The dataset is available at <http://arks.princeton.edu/ark:/88435/dsp015d86p269k>. Bars of each color display cross-validated decoding performance for
193 decoders trained using different sets of neural features: whole-brain patterns of voxel activities

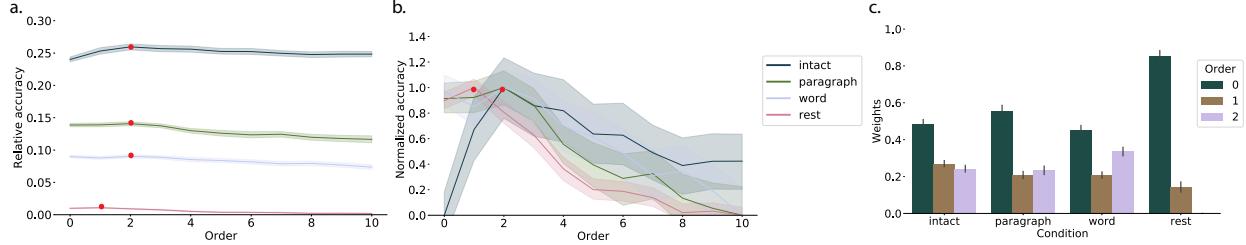


Figure 4: Decoding by order. **a. Relative decoding accuracy by order.** Ribbons of each color display cross-validated decoding performance for each condition (intact, paragraph, word, and rest). Decoders were trained using increasingly more higher-order information and this ribbons are displayed relative to chance at 0. The red dots indicates maximum decoding accuracy for each condition. **b. Normalized decoding accuracy by order.** We normalized the decoding accuracy by order to better visualize the order with the maximum decoding accuracy for each condition. **c. Optimized weights.** Bar heights indicate the optimized mixing paramete ϕ of each contributing order up to and including the order with the maximum decoding accuracy for each contributing order For the order with maximum decoding accuracy by condition, we show barplots of the optimized weights ϕ for each contributing order.

194 We next evaluated if our model of high-order correlations in brain activity can capture cognitively
 195 relevant brain patterns. We performed a decoding analysis, using cross validation to estimate (using other
 196 participants' data) which parts of the story each weighted-mixture of higher-order brain activity pattern
 197 corresponded to (see *Materials and methods*). We note that our primary goal was not to achieve perfect
 198 decoding accuracy, but rather to use decoding accuracy as a benchmark for assessing whether different
 199 neural features specifically capture cognitively relevant brain patterns.

200 Separately for each experimental condition, we divided participants into two groups. For the zeroth
 201 order, we computed the mean factor activity for each group. For all subsequent orders up to the tenth
 202 order, we computed the mean approximated dynamic ISFC of factor activity for each group (see *Materials*
 203 and *methods*), and combined in a weighted mixutre with all previous orders (i.e. cross-validation for the
 204 second order contained a weighted-mixture of zeroth, first, and second order c. Optimized weights..) For
 205 each order, we correlated the group 1 activity patterns with group 2 activity patterns. We then subdivided
 206 the group 1 to obtain an optimal weighting parameter for each order's correlation matrix using the same
 207 cross validation method. We used the optimal weighting parameters to obtain a weighted-mixture (see
 208 *Materials and methods*) of each order's correlation matrix. Using these correlations, we labeled the group 1
 209 timepoints using the group 2 timepoints with which they were most highly correlated; we then computed
 210 the proportion of correctly labeled group 1 timepoints. (We also performed the symmetric analysis whereby
 211 we labeled the group 2 timepoints using the group 1 timepoints as a template.) We repeated this procedure
 212 100 times (randomly re-assigning participants to the two groups each time) to obtain a distribution of
 213 decoding accuracies for each experimental condition. (There were 272 timepoints for paragraph condition,
 214 300 timepoints for intact and word conditions, and 400 timepoints for rest condition, so chance performance

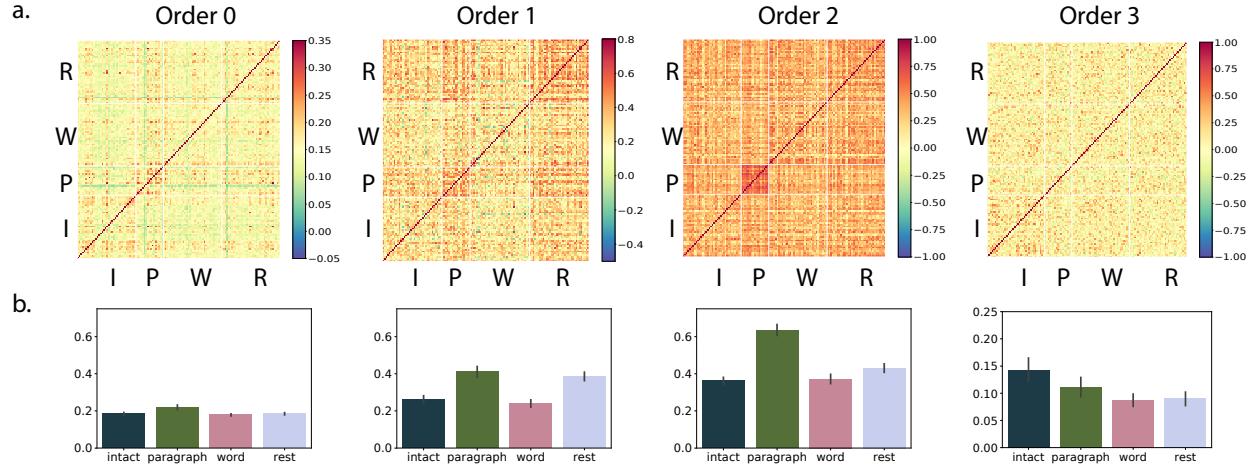


Figure 5: Inter-subject correlations by order. **a. Inter-subject correlation heatmaps by order.** Heatmaps for each order of how correlated each subject is with every other subject grouped by condition (intact (I), paragraph (P), word (W), and rest (R)). **b. Mean correlation for each condition by order.** Bar heights indicate inter-subject correlations by condition for each order.

215 on this decoding test is was $\frac{1}{272}$, $\frac{1}{300}$, and $\frac{1}{400}$ respectively.

216 Discussion

- 217 • Decoding accuracy best for level 2 data for all but rest condition. Could be that the brain is 2nd order
218 or that fMRI can only reliably give 2nd order.
- 219 • multiple timescale representations (a la Hasson group) implies first-order network interactions.
220 higher-order interactions imply generalizations between interacting representations (e.g. mirrored
221 schema, a la Norman/Baldassano/Hasson). possibly cite NTB 2013 science review, using as evidence
222 that this is where the field is going (voxels → patterns (L0) → interactions (L1) → higher order patterns
223 (L2+)).
- 224 • related approaches: sliding window, phase-based correlations, within-ROI spatial correlations at each
225 timepoint, granger causality, other explicit models (e.g. virtual brain).
- 226 • other applications: molecular interactions (protein folding?), diagnosis (e.g. psychiatric disorders
227 as network flow problems- grattan work?), social network dynamics (e.g. financial markets, social
228 media interactions)

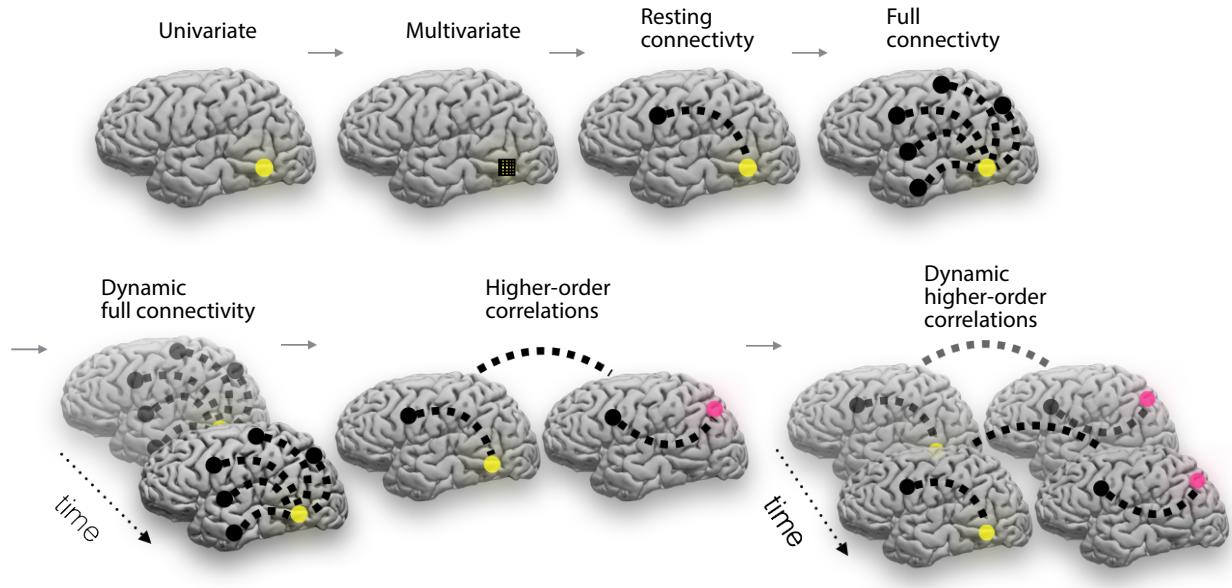


Figure 6: **Direction of the field.**

²²⁹ **Concluding remarks**

²³⁰ the universe is complicated and we need scalable approaches to studying how the pieces are interacting to
²³¹ make sense of it. one small step for mankind, and so on.

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²³⁷ content is solely the responsibility of the authors and does not necessarily represent the official views of our
²³⁸ supporting organizations.

²³⁹ **Author contributions**

²⁴⁰ Concept: J.R.M. Implementation: T.H.C., L.L.W.O., and J.R.M. Analyses: L.L.W.O and J.R.M.

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