Modal Abstractions for OS Kernels

Ph.D. Defense

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Part I

Modal Understanding of Location Virtualization

The Essentials in Systems Programming

a supposedly allocated physical resource

pointer va := malloc (size)

a virtual reference

Memory Location Virtualization

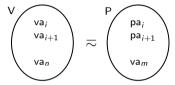


Figure: Virtualization: The Deception of Abundance

Memory Location Virtualization: Abstraction

An Address Space with Logical Name γ

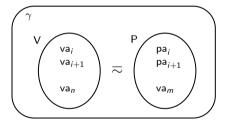


Figure: Address-Spaces: Named Containers for Virtual Memory Mappings

A Program Named A Program Named

 γ_n γ_m pointer va := malloc(size) malloc(size)

- A program is abstracted as a named address-space
- A container of virtual-to-physical memory resource mappings

Memory Location Virtualization: Mechanism

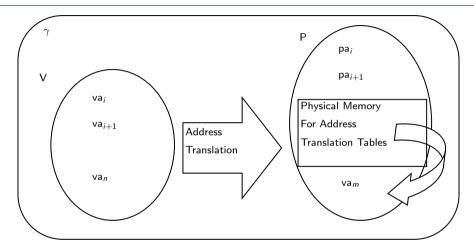


Figure: Address-Translation: A Mechanism for Realizing Address Virtualization

Page Tables

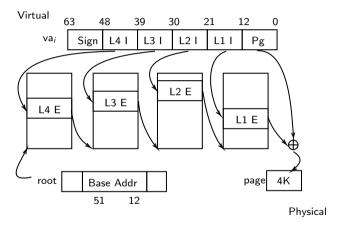


Figure: Page-Tables (PT): Data Structures for Address-Translation

A Complete Picture of Address-Space Abstraction

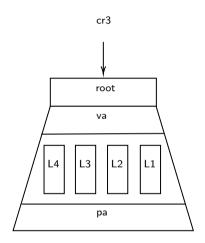


Figure: Depicting an Address-Space with its Essential Aspects

The Current View of Memory

The register cr₃ points to the current view of the memory, i.e., the loaded address space in the memory

Virtual Memory Management (VMM)

VMM as a General Resource Provider

"the virtual memory sub-system can be considered the core of a Solaris instance, and the implementation of Solaris virtual memory affects just about every other subsystem in the operating system" [McDougall and Mauro(2006)]

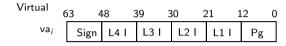
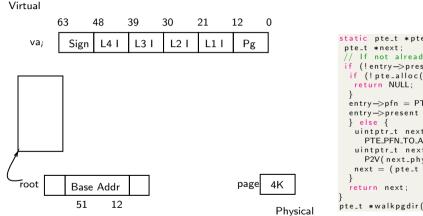


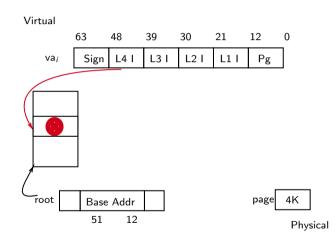


Figure: Physical and Virtual Resources



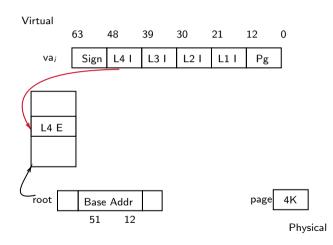
```
static pte_t *pte_nxt_table (pte_t *entry){
    If not already present, try to allocate
   (!entry->present){
 if (!pte_alloc(&next)) {
 entry->pfn = PTE_PFN((uintptr_t) next);
 entry\rightarrowpresent = 1;
   uintptr_t next_phys_addr =
     PTE_PFN_TO_ADDR(entry->pfn);
   uintptr_t next_virt_addr = (uintptr_t)
     P2V(next_phys_addr);
   next = (pte_t *) next_virt_addr:
pte_t *walkpgdir(pte_t *I4, void *va){
```

Figure: Traversal Starts from the root



```
static pte_t *pte_nxt_table (pte_t *entry){
 pte_t *next:
    If not already present, try to allocate
 if (!entry->present){
  if (!pte_alloc(&next)) {
   return NULL:
  entry->pfn = PTE_PFN((uintptr_t) next);
  entry \rightarrow present = 1:
  } else {
   uintptr_t next_phys_addr =
     PTE_PFN_TO_ADDR(entry -> pfn);
   uintptr_t next_virt_addr = (uintptr_t)
     P2V(next_phys_addr):
   next = (pte_t *) next_virt_addr:
  return next:
pte_t *walkpgdir(pte_t *I4, void *va){
 pte_t *|4_entry = &|4[L4I(va)];
```

Figure: Missing L4 Entry



```
static pte_t *pte_nxt_table (pte_t *entry){
 pte t *next:
    If not already present, try to allocate
    (!entry->present){
 if (!pte_alloc(&next)) {
   return NULL:
 entry->pfn = PTE_PFN((uintptr_t) next);
 entry \rightarrow present = 1:
  } else {
   uintptr_t next_phys_addr =
     PTE_PFN_TO_ADDR(entry->pfn):
   uintptr_t next_virt_addr = (uintptr_t)
     P2V(next_phys_addr):
   next = (pte_t *) next_virt_addr;
 return next:
pte_t *walkpgdir(pte_t *I4, void *va){
 pte_t * | 4_entry = & | 4[L4](va) |:
```

Figure: A New L4 Entry

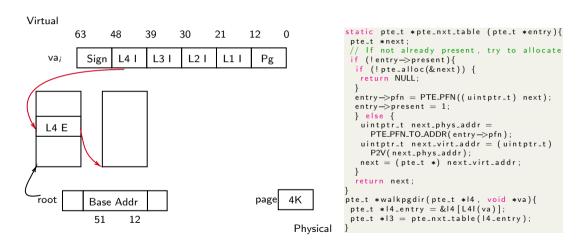
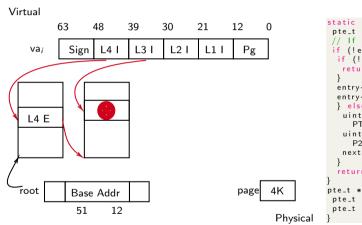


Figure: Accessing to Table L3



```
static pte_t *pte_nxt_table (pte_t *entry){
    If not already present, try to allocate
   (!entry->present){
 if (!pte_alloc(&next)) {
   return NULL:
 entry->pfn = PTE_PFN((uintptr_t) next);
 entry \rightarrow present = 1:
  } else {
   uintptr_t next_phys_addr =
     PTE_PFN_TO_ADDR(entry -> pfn):
   uintptr_t next_virt_addr = (uintptr_t)
     P2V(next_phys_addr);
   next = (pte_t *) next_virt_addr;
 return next:
pte_t *walkpgdir(pte_t *I4, void *va){
 pte_t *|4_{entry}| = &|4[L4I(va)]:
 pte_t *I3 = pte_nxt_table(I4_entry);
```

Figure: Missing L3 Entry

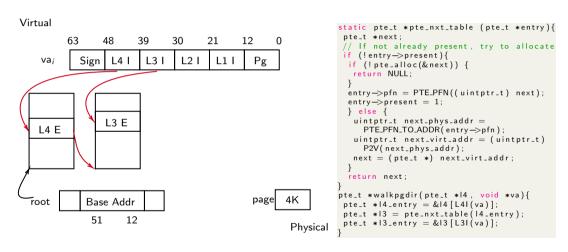


Figure: A New L3 Entry

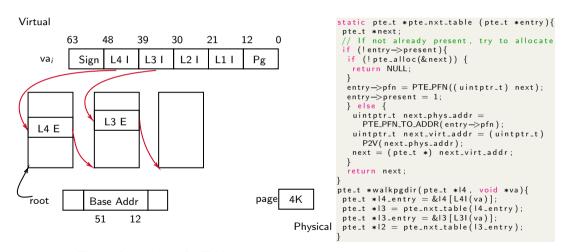
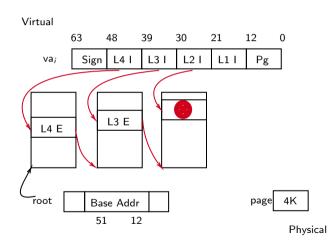
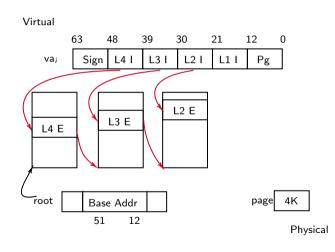


Figure: Accessing to L2 Table



```
static pte_t *pte_nxt_table (pte_t *entry){
      pte t *next:
                       If not already present, try to allocate
                       (!entry->present){
            if (!pte_alloc(&next)) {
                  return NULL:
           entry->pfn = PTE_PFN((uintptr_t) next);
           entry \rightarrow present = 1:
            } else {
                  uintptr_t next_phys_addr =
                               PTE_PFN_TO_ADDR(entry -> pfn);
                  uintptr_t next_virt_addr = (uintptr_t)
                               P2V(next_phys_addr):
                  next = (pte_t *) next_virt_addr:
           return next:
pte_t *walkpgdir(pte_t *I4, void *va){
      pte_t * 14_entry = &14[L41(va)];
      pte_t * 13 = pte_n \times t_t = 0.01 \times 13 = 0
    pte_t *I3_entry = &I3[L3I(va)];
      pte_t *|2 = pte_nxt_table(|3_entry):
```

Figure: Missing L2 Entry



```
static pte_t *pte_nxt_table (pte_t *entry){
 pte_t *next:
   If not already present, try to allocate
   (!entry->present){
  if (!pte_alloc(&next)) {
   return NULL:
  entry->pfn = PTE-PFN((uintptr_t) next):
  entry \rightarrow present = 1:
  } else {
   uintptr_t next_phys_addr =
     PTE_PFN_TO_ADDR(entry->pfn):
   uintptr_t next_virt_addr = (uintptr_t)
     P2V(next_phys_addr):
   next = (pte_t *) next_virt_addr:
  return next:
pte_t *walkpgdir(pte_t *I4, void *va){
 pte_t *I4_entry = &I4[L4I(va)];
 pte_t *|3 = pte_nxt_table(|4_entry):
 pte_t *I3_entry = &I3[L3I(va)];
 pte_t *|2 = pte_nxt_table(|3_entry):
 pte_t * |2_entry = &|3[L2](va)]:
```

Figure: A New L2 Entry

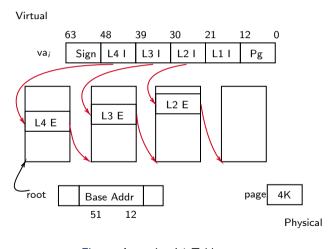


Figure: Accessing L1 Table

```
static pte_t *pte_nxt_table (pte_t *entry){
 pte_t *next;
    If not already present, try to allocate
   (!entry->present){
 if (!pte_alloc(&next)) {
   return NULL:
 entry->pfn = PTE_PFN((uintptr_t) next);
 entry \rightarrow present = 1:
  } else {
   uintptr_t next_phys_addr =
     PTE_PFN_TO_ADDR(entry->pfn):
   uintptr_t next_virt_addr = (uintptr_t)
     P2V(next_phys_addr):
   next = (pte_t *) next_virt_addr:
 return next:
pte_t *walkpgdir(pte_t *I4, void *va){
 pte_t *|4_entry = &|4[L4I(va)]:
 pte_t *|3 = pte_nxt_table(|4_entry);
 pte_t *|3_entry = &|3[L31(va)];
 pte_t * 12 = pte_n \times t_t = 0:
 pte_t *|2_entry = &|3[L2|(va)];
 pte_t *|1 = pte_nxt_table(|2_entry):
```

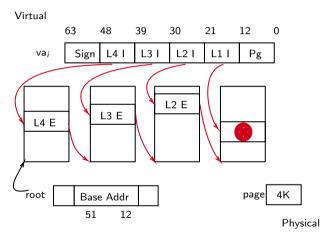
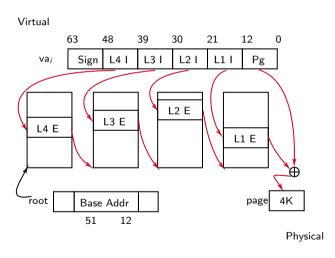


Figure: Missing L1 Entry

```
static pte_t *pte_nxt_table (pte_t *entry){
 pte_t *next;
    If not already present, try to allocate
    (!entry->present){
 if (!pte_alloc(&next)) {
   return NULL:
 entry->pfn = PTE_PFN((uintptr_t) next);
 entry \rightarrow present = 1:
  } else {
   uintptr_t next_phys_addr =
     PTE_PFN_TO_ADDR(entry->pfn);
   uintptr_t next_virt_addr = (uintptr_t)
     P2V(next_phys_addr):
   next = (pte_t *) next_virt_addr:
 return next:
pte_t *walkpgdir(pte_t *I4, void *va){
 pte_t *|4_{entry}| = &|4[L4I(va)]:
 pte_t *|3 = pte_nxt_table(|4_entry):
 pte_t *|3_entry = &|3[L3|(va)];
 pte_t * 12 = pte_n \times t_t = 0  (13_entry):
pte_t *12_entry = &13[L2I(va)];
 pte_t *|1 = pte_nxt_table(|2_entry);
```



static pte_t *pte_nxt_table (pte_t *entry){ pte_t *next: If not already present, try to allocate (!entry->present){ if (!pte_alloc(&next)) { return NULL: entry->pfn = PTE_PFN((uintptr_t) next); entry \rightarrow present = 1; } else { uintptr_t next_phys_addr = PTE_PFN_TO_ADDR(entry->pfn); uintptr_t next_virt_addr = (uintptr_t) P2V(next_phys_addr): next = (pte_t *) next_virt_addr: return next: pte_t *walkpgdir(pte_t *I4, void *va){ pte_t * $|4_{entry} = &|4[L4](va)$]: pte_t *|3| = pte_nxt_table(|4|entrv): $pte_t * 13_entry = &13[L3I(va)];$ pte_t *|2 = pte_nxt_table(|3_entry); pte_t *|2_entry = &|2[L2|(va)]; pte_t *|1 = pte_nxt_table(|2_entry); pte_t *|1_entry = &|1[L1|(va)]; return | 11_entry

Figure: Accessing to the Page Referenced by L1 Entry

Breaking Soundness in Sharing

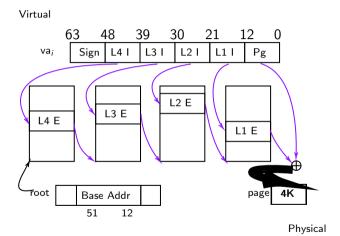
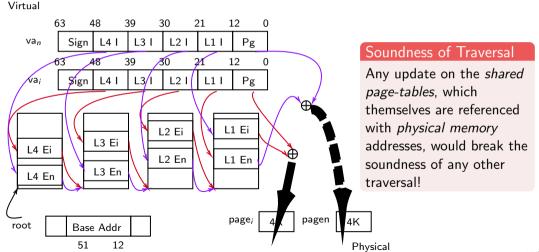


Figure: Sharing Page-Tables under Updates to Page-Tables

Breaking Soundness in Sharing



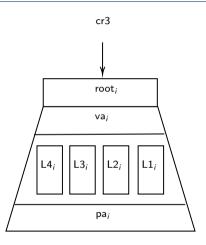


Figure: An Address Space with Unique Root Address root;

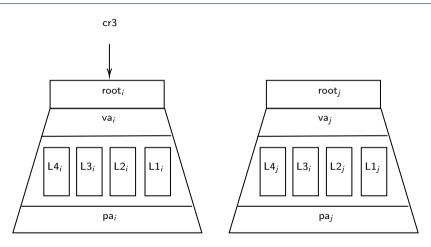


Figure: Two Address-Spaces with the Unique Root Addresses $root_i$ and $root_j$

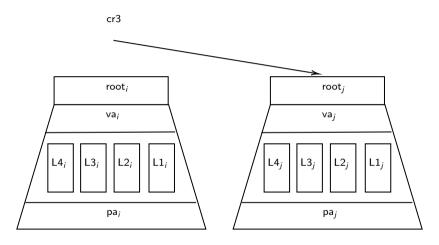


Figure: Switching Address-Spaces

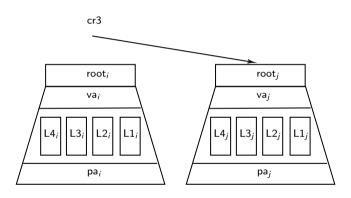


Figure: Switching Address-Spaces

Referring to Agnostic Resources

Unless we bookkeep to which address-space each of these virtual-to-physical mappings belongs, which we never see in the practice of using virtual memory references, we need to figure out a way of referring to these mappings as they are only valid in their own address-spaces.

Specifying Programs

 $\{P\} \subset \{Q\}$

Separation Logic: Separating Conjuction

$$\frac{\{P\} \ e \ \{Q\}}{\{P*R\} \ e \ \{Q*R\}}$$

Separation Logic: Ownership

- ullet Well-known points-to assertion, e.g., memory_ref \mapsto_q val
- Regarding the logical machinery, Iris SL enables encoding a generalized form ownership of logical resources
- A fragmental $[P]^{\gamma}$ ownership
 - Enabling coordinated access to logical resources
- Full P^{γ} ownership
 - Enabling access to *update* logical resources, presented as *invariants*

Separation Logic: Invariants

$$\frac{\text{Inv}}{\left\{P*R\right\}\;\alpha\;\left\{P*Q\right\}_{\epsilon}\qquad\alpha\;\text{physically atomic}}{\left[P\right]^{n}\vdash\left\{R\right\}\;\alpha\;\left\{Q\right\}_{\epsilon\uplus\left\{n\right\}}}$$

Defining Some Ownersip Assertions

- Expected to have register ownership to be defined : reg \mapsto_r reg_val
- ullet Expected to have *physical memory* ownership defined: pa \mapsto_p val
- How about virtual memory references?

A Naive Attempt on Virtual-Pointsto

- Page and page table addresses are physical
- Purple (or red) path + bold black page references are *physical*
- Why don't we define *virtual* memory references in terms of the physical page-table and the final page references?

 L_{4} _ L_{1} _PointsTo(va, I4e, I3e, I2e, I1e, paddr) + $paddr \mapsto_{p} page_{val}$

Tokens for Traversals

$$\underbrace{\mathsf{va} \hookrightarrow_\mathsf{q}^\delta \mathsf{pa}}_{\mathsf{Ghost translation}} * \underbrace{\mathsf{pa} \mapsto_\mathsf{p} \{\mathsf{qfrac}\} \mathsf{val}}_{\mathsf{Physical location}}$$

- Abstract the purple and red segment of page-table traversal into logical summarization of the walk
- Distribute the fragmental ownersip of the logical page-table summarization to virtual memory ownership

A Candidate for Kernel Invariant

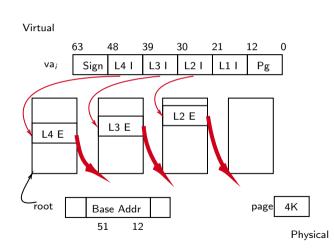
```
\mathcal{I}\mathsf{ASpace}(\theta,m) \stackrel{\triangle}{=} \mathsf{ASpace\_Lookup}(\theta,m) * \\ \qquad \qquad \qquad \exists \ (\mathsf{I4e} \ \mathsf{I3e} \ \mathsf{I2e}, \ \mathsf{I1e}, \ \mathsf{paddr}). \ \mathsf{L}_{\mathsf{4}\mathsf{L}\mathsf{L}_{\mathsf{1}}\mathsf{-}}\mathsf{PointsTo}(\mathsf{va}, \ \mathsf{I4e}, \ \mathsf{I3e}, \ \mathsf{I2e}, \ \mathsf{I1e}, \ \mathsf{paddr}) \\ \text{where} \\ \mathsf{ASpace\_Lookup}(\theta,m) \stackrel{\triangle}{=} \lambda \ \mathsf{cr3val}. \ \exists \delta \ . \ulcorner m \ !! \ \mathsf{cr3val} = \mathsf{Some} \ \delta \urcorner * \mathcal{A} \mathsf{bsPTableWalk}(\delta,\theta) \\ \mathsf{Figure:} \ \mathsf{Global} \ \mathsf{Address-Space} \ \mathsf{Invariant} \ \mathsf{with} \ \mathsf{a} \ \mathsf{fixed} \ \mathsf{global} \ \mathsf{map} \ \mathsf{of} \ \mathsf{address-space} \ \mathsf{names} \ m
```

A Candidate for Kernel Invariant

The Kernel Invariant in Action

How useful (complete) is this invariant?

Kernels Locating L1 Entries



```
static pte_t *pte_nxt_table (pte_t *entry){
 pte_t *next:
    If not already present, try to allocate
   (!entry->present){
 if (!pte_alloc(&next)) {
   return NULL:
 entry->pfn = PTE_PFN((uintptr_t) next);
 entry\rightarrowpresent = 1;
  } else {
   \uintptr_t next_phys_addr =
     PTE_PFN_TO_ADDR(entry->pfn);
   uintptr_t next_virt_addr = (uintptr_t)
     P2V(next_phys_addr):
   next = (pte_t *) next_virt_addr;
 return next:
pte_t *walkpgdir(pte_t *I4. void *va){
 pte_t *|4_{entry}| = &|4[L4I(va)]:
 pte_t *|3 = pte_nxt_table(|4_entry):
 pte_t *I3_entry = &I3[L3I(va)];
 pte_t *|2 = pte_nxt_table(|3_entry):
pte_t *|2_entry = &|2[L2|(va)]:
 pte_t *|1 = pte_nxt_table(|2_entry):
 pte_t *|1_entry = &|1[L1|(va)]:
```

Incorporating P2V into the Kernel Invariant

Definition (The Kernel Invariant for Page-Table Traversal with Virtual Page-Table Pointers)

$$\begin{split} \mathcal{I} \mathsf{ASpace}_{\mathsf{id}}(\theta,\Xi,m) & \stackrel{\triangle}{=} \mathsf{ASpace_Lookup}_{\mathsf{id}}(\theta,\Xi,m) * \mathsf{GhostMap}(\mathsf{id},\Xi) * \\ & \left(\begin{matrix} \bigstar & \exists \ (\mathsf{I4e},\ \mathsf{I3e},\ \mathsf{I2e},\ \mathsf{I1e},\ \mathsf{paddr}). \ \mathsf{L}_{\mathsf{4}_\mathsf{L}_1_\mathsf{PointsTo}}(\mathsf{va},\ \mathsf{I4e},\ \mathsf{I3e},\ \mathsf{I2e},\ \mathsf{I1e},\ \mathsf{paddr}) \right) * \\ & \bigstar & \exists \ (\mathsf{qfrac},\ \mathsf{q},\ \mathsf{val},\mathsf{va}). \ \lceil \mathsf{va} = \mathsf{pa} + \mathsf{KERNBASE}\ \mathsf{level} > 1 \rceil * \underbrace{\mathsf{va} \hookrightarrow_{\mathsf{q}}^{\delta} \mathsf{pa}}_{\mathsf{Ghost\ translation}} * \underbrace{\mathsf{pa} \mapsto_{\mathsf{p}} \{\mathsf{qfrac}\}\ \mathsf{val} * \\ \mathsf{physical\ location}}_{\mathsf{Physical\ location}} * \\ & \underbrace{\lceil \mathsf{qfrac} = 1 \leftrightarrow \neg \mathsf{entry_present}\ (\mathsf{val}) \rceil}_{\mathsf{Entry\ validity}} * \\ & \underbrace{\lceil \mathsf{qfrac} = 1 \leftrightarrow \neg \mathsf{entry_present}\ (\mathsf{val}) \rceil}_{\mathsf{Indexing\ into\ next\ level\ of\ tables}} * \\ & \mathsf{vhere} \\ & \mathsf{present_L}(\mathsf{val},\ \mathsf{level}) \stackrel{\triangle}{=} \mathsf{entry_present}(\mathsf{val}) \land \mathsf{level} > 0 \end{split}$$

Specifying P2V

```
 \begin{cases} \text{$P*$ $\mathcal{I}$ ASpace}_{id}(\theta,\Xi\setminus\{\text{entry}\}), m)* \text{$r$ bp-8$} \mapsto_{v} \text{entry}* \text{$r$ cx} \mapsto_{r-}* \text{entry} \mapsto_{id} \_* \text{$r$ tv} \hookrightarrow^{\delta s} \delta \rbrace_{\text{rtv}} \\ \left\{ \text{entry+KERNBASE} \mapsto_{\text{vpte,qfrac}} (\text{pte\_initialized (entry\_val.pfn)})^{\gamma}_{\text{rtv}} \right. \\ \left\{ \text{$r$ bp-16$} \mapsto_{v} (\text{pte\_initialized (entry\_val.pfn)})) * \text{$r$ ax} \mapsto_{r} \text{ table\_root (pte\_initialize(entry\_val.pfn))} \rbrace_{\text{rtv}} \\ \left\{ \forall_{i \in 0 \dots 511} . ((\text{table\_root (pte\_initialized (entry\_val.pfn))}) + i*8 ) \hookrightarrow^{\text{id}} v-1 \right\} \\ \text{$;$ is uintptr\_t next\_virt\_addr} = (uintptr\_t) P2V(entry.pfn <<12); \\ \text{movabs KERNBASE, $r$ cx } \left\{ \dots * r \text{$cx} \mapsto_{r} \text{KERNBASE} * \dots \right\}_{\text{rtv}} \\ \text{add} \qquad \text{$r$ cx, $r$ ax} \\ \left\{ \dots * r \text{$ax} \mapsto_{r} \text{ table\_root (pte\_initialize(entry\_val.pfn))} + \text{KERNBASE} * \dots \right\}_{\text{rtv}} \\ \dots \; \text{$;$ clean up the stack and return the rax value} \end{cases}
```

Figure: Converting a physical address of a PTE to a virtual address (w/o instruction pointer or flag updates).

The Current Status of Machinery

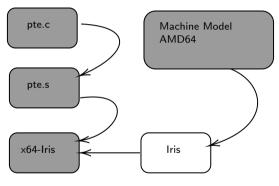


Figure: x64-Iris

- Dumping .o files
- Manuel treatment on Xabs instructions and field access

A Rough Quantification on the Current Status

Table: Line-of-Code Numbers for pte Verification

	C LoC A	Assembly LoC	Roqc Proof LoC
pte_get_next_table	12	45	3200
pte_walkpgdir	8	44	3200
pte_p2v	_	1	75
pte_switch_addrspace	_	18	350
pte_map_page	7	28	1750
pte_initialize	4	20	700

Table: Line-of-Code Numbers for x64-Iris Logic

	Roqc LoC
Soundness of Instructions Mentioned in the Thesis	50176
VMM Related Logical Constructions	5554
Machine Model	6172

Modal Abstractions as Verification Patterns in Practice

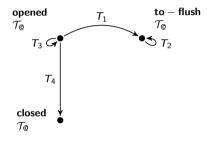
	Resource Context	Resource Elements	Nominalization	Resource Context Steps
Post-Crash Modality [Chajed(2022), Tej Chajed and contributors(2023), Chajed et al.(2019)]	◊ P	$\ell \mapsto_{n}^{\overline{\gamma}} v$	Strong	Crash Recovery
NextGen Modality [Vindum et al.(2025)]	$\stackrel{t}{\hookrightarrow}$ P	Own (t(a))	Strong	Determined Based on the Model*
StackRegion Modality* [Vindum et al.(2025)] Memory-Fence Modality [Doko and Vafeiadis(2016), Doko and Vafeiadis(2017), Dang et al.(2019)] Address-Space Modality [Kuru and Gordon(2024)] Ref-Count Modality [Wagner et al.(2024)]	$egin{array}{c} \stackrel{I \subset ut^n}{\hookrightarrow} P \ riangle_{\pi} \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$	$ \begin{array}{c} \boxed{\textbf{n}} \; \ell \mapsto \textbf{v} \\ \ell \mapsto \textbf{v} \\ \ell \mapsto \textbf{v} \\ \ell_1 \mapsto \textbf{v} \end{array} $	Strong Weak Weak Weak	Alloc and Return to/from stack Fence Acquire and Release Address-Space Switch Allocating, Dropping and Shar- ing a Reference

 The StackRegion Modality is an instance of NextGen (called the Independence Modality in [Vindum et al.(2025)]).

Part II

Modal Understanding of Specification Evolution

Specifying Protocols for Systems with STSes



opened $\mathcal{T}_{@}$ \mathcal{T}_{6} closed $\mathcal{T}_{@}$

Figure: STS for Distributed File Protocol

Figure: STS for Traditional File Protocol

Interacting with STSes

Modelling interactions of a client with a state machine via token exchange

Defining STSes

Definition (STS Definition following CaReSL's presentation [Turon et al.(2013)])

An STS π is given by:

- 1. a set of states S,
- 2. a map from a state set of tokens $\mathcal{T}: \mathcal{S} \to \mathsf{TokSet}$,
- 3. a transition relation → on states, which is then lifted to pairs of a state and token set:

$$(s;T) \rightsquigarrow (s';T') \triangleq s \rightsquigarrow s' \land \mathcal{T}(s) \uplus T = \mathcal{T}(s') \uplus T'$$

4. an interpretation mapping states to state assertions $\varphi: \mathcal{S} \to \mathsf{Prop}$.

Propositional Kripke Model

Definition ((Propositional) Kripke Model [Hughes and Cresswell(1996)])

A Kripke model \mathfrak{M} is a triple (W, R, V) where

- W is a set of "worlds"
- $R \subseteq W \times W$ is a relation called the *accessibility* relation between worlds
- $V: \mathsf{PropVar} \to \mathcal{P}(W)$ gives for each propositional variable p a set of worlds V(p) where p is considered true

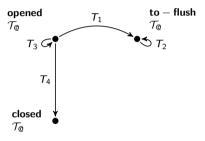
Bisimulations over Kripke Models

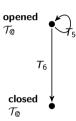
Definition ((Propositional) Bisimulation of Kripke Structures: $\mathfrak{M} \sim \mathfrak{M}'$.)

A bisimulation between (multimodal) Kripke structures $(W, R_{i \in I}, V)$ and $(W', R'_{i \in I}, V')$ is a relation $E \subseteq W \times W'$ satisfying:

- If w E w', then w and w' satisfy the same propositional variables.
- If w E w' and w R v, then there exists $v' \in W'$ such that v E v' and w' R' v'
- If w E w' and w' R' v', then there exists $v \in W$ such that v R v' and w R v

Intuition on Bisimulations over STSes





- More than just relating **STS**es in representation invariants per state.
- Bisimilar states can have different representation invariants.

Proof Indistinguishability

Knowing the proof of a client against the right (target STS conventionally π') enables deducing the proof against the bisimilar on the left (source STS conventionally π).

A Quick Tour on STS Assertions

• Invariants φ_{π}^{γ} , client capability $[s, T]^{\gamma}$

STSALLOC

$$\varphi(s) \Rightarrow \exists \gamma. \boxed{\varphi}_{\pi}^{\gamma} * \boxed{s; AllTokens} \backslash \overline{\mathcal{T}(s)}_{\gamma}^{\gamma}$$
STSOPEN

$$\frac{STSOPEN}{\left[\varphi\right]_{\pi}^{\gamma}*\left[\bar{s};\bar{T}\right]^{\gamma}} \Rightarrow \left(\exists \ s'. \lceil (s0,T) \stackrel{\mathsf{rely}^{*}}{\sqsubseteq}_{\pi} (s',T) \rceil * \varphi(s) * \forall sl', \ T'. \lceil (s',T) \stackrel{\mathsf{guar.}^{*}}{\sqsubseteq}_{\pi} (sl',T') \rceil * \varphi(sl') \Rightarrow \left[\bar{sl};\bar{T'}\right]^{\gamma}\right)}{\text{UPDISL}}$$

 α physically atomic

$$\frac{\forall s_0 . \ ((s;T) \overset{\mathsf{rely}^*}{\sqsubseteq}_{\pi} (s_0;T)) \vdash \{\varphi(s_0) * P\} \ \alpha \ \{\exists s', \mathsf{T}' . \ (s_0;\mathsf{T}) \overset{\mathsf{guar}^*}{\sqsubseteq}_{\pi} (s';\mathsf{T}') * \varphi(s') * Q\}}{[\varphi]_{\pi}^{\gamma} \vdash \{[\underline{s};\overline{\mathsf{T}}]^{\gamma} * P\} \ \alpha \ \{\exists s',\mathsf{T}' . [\underline{s'};\overline{\mathsf{T}'}]^{\gamma} * Q\}}$$

Figure: Iris STS Library [Jung et al.(2015)] simplified with later modality and invariant masks omitted

Decomposing Bisimilarity in STSes

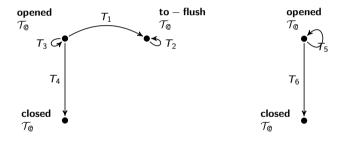
The bisimulation $(\mathcal{M}(\pi, \pi', \varphi, \varphi', s, \mathsf{T}, \mathsf{U}))$ between two state machines, π and π' is composed of

- The source STS π
- The target STS π'
- The source STS's state interpretation function $-\varphi$
- The target STS's state interpretation function $-\varphi'$
- Token Embedding $\epsilon_{\mathcal{S}}: \mathcal{S}(\pi) \mapsto \mathcal{S}(\pi')$
- State Embedding ϵ_T : $\mathcal{T}(\pi) \mapsto \mathcal{T}(\pi')$
- The Law of Rely
- The Law of Guarantee
- The Law of Tolerance
- The state of source STS from which bisimulation is considered against any client interference with the token set T

Proof Translation

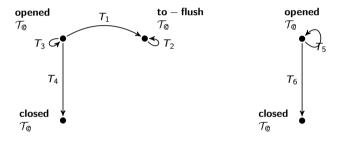
Obtain a proof rule utilizing the bisimulation to translate proofs between bisimilar state machines!

Embeddings for Tokens and States



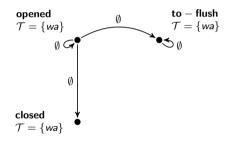
- How to impose indistinguishability of behavior observed on bisimilar states
- How to impose indistinguishability over the steps taken between bisimilar states

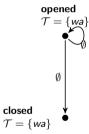
Embeddings for Tokens



• Make token exchange align with indistinguishability: Embedding tokens (lifted $\epsilon_{\overline{T}}$) T_1 , T_3 , and T_2 to T_5 , and T_4 to T_6

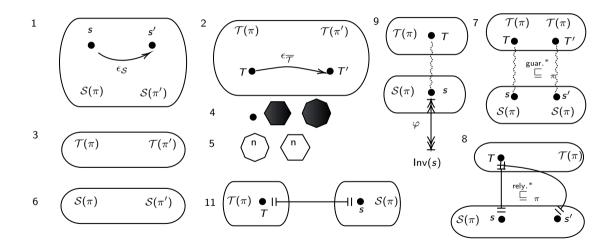
Embeddings for State



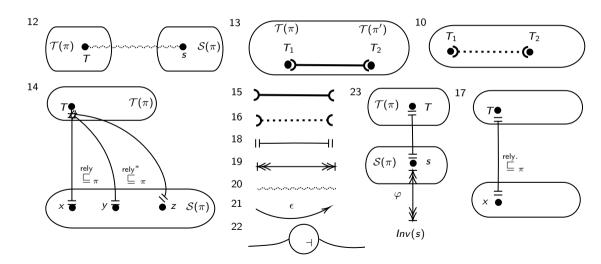


 Setting client interference aside, we would consider opened and flushed of the left state machine to be bisimilar to opened of the right state machine

A Quick Tour on the Represention of Laws - 1



A Quick Tour on the Represention of Laws - 2



We Need This

$$\frac{\text{BISIM}}{\pi \sim \pi'} \frac{q \, \epsilon_{\mathcal{S}} \, s}{q' \, \epsilon_{\mathcal{S}} \, s'} \frac{\{[s; \epsilon_{\overline{\mathcal{T}}}(\overline{\mathcal{T}})]_{\pi'}^{\gamma} * P\} \, C \, \{[s'; \overline{\mathcal{T}}]_{\pi'}^{\gamma} * Q\}}{[\varphi]_{\pi}^{\gamma} \vdash \{[q; \overline{\mathcal{T}}]_{\pi}^{\gamma} * P\} \, C \, \{[q'; \overline{\mathcal{T}}]_{\pi}^{\gamma} * Q\}}$$

We Use This

UPDISL

$$\frac{\alpha \text{ physically atomic}}{\forall s_0 \; . \; ((s;\mathsf{T}) \overset{\mathsf{rely}^*}{\sqsubseteq}_{\pi} \; (s_0;\mathsf{T})) \; \vdash \; \{\varphi(s_0) * P\} \; \alpha \; \{\exists s' \; , \; \mathsf{T'} \; . \; (s_0;\mathsf{T}) \overset{\mathsf{guar}^*}{\sqsubseteq}_{\pi} \; (s';\mathsf{T'}) * \varphi(s') * Q\} }{ \underbrace{\varphi}_{\pi}^{\gamma} \vdash \; \{ \underbrace{[s;\mathsf{T}]^{\gamma} * P\} \; \alpha \; \{\exists s' \; , \; \mathsf{T'} . \underbrace{[s';\mathsf{T'}]^{\gamma} * Q\} } }$$
 BISIM
$$\frac{\pi \sim \pi' \qquad q \; \epsilon_{\mathcal{S}} \; s \qquad q' \; \epsilon_{\mathcal{S}} \; s' \qquad \{ \underbrace{[s;\epsilon_{\overline{T}}(\mathcal{T})]_{\pi'}^{\gamma} * P\} \; C \; \{ \underbrace{[s';\mathsf{T'}]_{\pi'}^{\gamma} * Q\} } }$$

$$\underbrace{\varphi}_{\gamma}^{\gamma} \vdash \; \{ \underbrace{[q;\mathsf{T}]_{\pi}^{\gamma} * P\} \; C \; \{ \underbrace{[q';\mathsf{T'}]_{\pi}^{\gamma} * Q\} } }$$

How? Obligation - 1

UPDISL

 α physically atomic

$$\forall s_{0} . \qquad ((s; \mathsf{T}) \stackrel{\mathsf{rely}^{*}}{\sqsubseteq}_{\pi} (s_{0}; \mathsf{T})) \qquad \vdash \{\varphi(s_{0}) * P\} \alpha \{\exists s', \mathsf{T}' . (s_{0}; \mathsf{T}) \stackrel{\mathsf{guar}^{*}}{\sqsubseteq}_{\pi} (s'; \mathsf{T}') * \varphi(s') * Q\}$$

$$\qquad \qquad \varphi \uparrow_{\pi} \vdash \{ [s; \mathsf{T}]_{\pi}^{\gamma} * P\} \alpha \{\exists s', \mathsf{T}' . [s'; \mathsf{T}']_{\pi}^{\gamma} * Q\}$$

$$\qquad \qquad \exists \mathsf{BISIM} \\ \frac{\pi \sim \pi'}{\pi} q \, \epsilon_{\mathcal{S}} s \qquad q' \, \epsilon_{\mathcal{S}} s' \qquad \{ [s; \epsilon_{\overline{\mathcal{T}}}(\mathsf{T})]_{\pi'}^{\gamma} * P\} \, C \, \{ [s'; \mathsf{T}']_{\pi'}^{\gamma} * Q\}$$

$$\qquad \qquad \qquad \varphi \uparrow_{\pi} \vdash \{ [q; \mathsf{T}]_{\pi}^{\gamma} * P\} \, C \, \{ [q'; \mathsf{T}']_{\pi}^{\gamma} * Q\}$$

The Law of Rely

Theorem (The Law of Rely)

$$\forall s'.(s;T) \stackrel{\mathsf{rely}^*}{\sqsubseteq}_{\pi} (s';T) \leftrightarrow \\ (\forall_{s_1,s'_1,T_1}.\,\epsilon_{\mathcal{S}}(s,s_1) \to \epsilon_{\mathcal{S}}(s',s'_1) \to \epsilon_{\overline{\mathcal{T}}}(T,T_1) \to (s_1;T_1) \stackrel{\mathsf{rely}^*}{\sqsubseteq}_{\pi'} (s'_1;T_1)$$

- We do not drop any client interference with capabilities T
- Indetification of the states that are tolerant to the client interference from which the STS can take steps (Guarantee)
- Bookkeeping of the client interference needed!
- Identifying the valid pre state

The Law of Rely

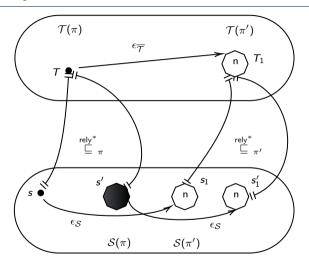
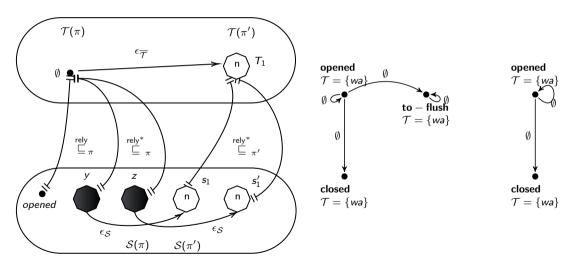


Figure: Embedding The Client Interface

The Law of Rely for a Bisimulation Instance



We Need This

UPDISL

$$\frac{\alpha \text{ physically atomic}}{\forall s_0 \; . \; ((s;\mathsf{T}) \overset{\mathsf{rely}^*}{\sqsubseteq}_{\pi} \; (s_0;\mathsf{T})) \; \vdash \{\varphi(s_0) * P\} \; \alpha \; \{\exists s' \; , \; \mathsf{T'} \; . \; (s_0;\mathsf{T}) \overset{\mathsf{guar}^*}{\sqsubseteq}_{\pi} \; (s';\mathsf{T'}) * \varphi(s') * Q\}}{ \underbrace{\varphi}_{\pi}^{\gamma} \vdash \{ \underbrace{[s;\mathsf{T}]_{\pi}^{\gamma} * P\} \; \alpha \; \{\exists s' \; , \; \mathsf{T'} . \underbrace{[s';\mathsf{T'}]_{\pi}^{\gamma} * Q\}}}_{\mathsf{S}} \; \mathsf{BISIM} \\ \underbrace{\frac{\pi \sim \pi'}{\pi} \; q \; \epsilon_{\mathcal{S}} \; s \; q' \; \epsilon_{\mathcal{S}} \; s' \quad \{ \underbrace{[s;\epsilon_{\overline{T}}(\mathcal{T})]_{\pi'}^{\gamma} * P\} \; C \; \{ \underbrace{[s';\mathsf{T'}]_{\pi'}^{\gamma} * Q\}}_{\mathsf{T'}} \; \underbrace{\varphi}_{\mathsf{T'}} \; \underbrace{[s;\mathsf{T'}]_{\pi'}^{\gamma} * Q\}}_{\mathsf{T'}} \; \underbrace{\varphi}_{\mathsf{T'}} \; \underbrace{$$

How? Obligation - 2

UPDISL

 α physically atomic

$$\forall s_{0} . \ ((s;T) \overset{\text{rely}^{*}}{\sqsubseteq}_{\pi} (s_{0};T)) \vdash \{\varphi(s_{0}) * P\} \alpha \ \{\exists s' \ , \ T' \ . \qquad (s_{0};T) \overset{\text{guar}^{*}}{\sqsubseteq}_{\pi} (s';T') \qquad * \varphi(s') * Q\}$$

$$= \underbrace{ \begin{cases} \varphi _{\pi} \end{cases} \vdash \{ \underbrace{[s;T]_{\pi}^{\gamma} * P\} \alpha \ \{\exists s', T' . \underbrace{[s';T']_{\pi}^{\gamma} * Q\}}_{\pi} * Q\} }$$

$$= \underbrace{ \begin{cases} BISIM _{\pi} \sim \pi' \end{cases} \quad q \epsilon_{S} s \quad q' \epsilon_{S} s' \quad \{ \underbrace{[s;\epsilon_{\overline{T}}(T)]_{\pi}^{\gamma} * P\} C \{ \underbrace{[s';T']_{\pi}^{\gamma} * Q\}}_{\pi} * Q\} }$$

$$= \underbrace{ \begin{cases} \varphi _{\pi} \end{cases} \vdash \{ \underbrace{[q;T]_{\pi}^{\gamma} * P\} C \{ \underbrace{[s';T']_{\pi}^{\gamma} * Q\}}_{\pi} * Q\} }$$

The Law of Guarantee

Theorem (Guarantee Bisim without Invariants)

$$\forall_{q',q,T'}.\epsilon_{\overline{T}}(T) \equiv T' \to \epsilon_{\mathcal{S}}(s,q) \to (q;T') \stackrel{\mathsf{rely}^*}{\sqsubseteq}_{\pi'} (q';T') \to \\ \forall_{q'',T''}.(q';T') \stackrel{\mathsf{guar}}{\sqsubseteq}_{\pi'} (q'';T'') \to \\ \exists_{s',s'',T'_0,T''_0}.(s';T'_0) \stackrel{\mathsf{guar}}{\sqsubseteq}_{\pi} (s'';T''_0) \land \\ \epsilon_{\mathcal{S}}(s') = q' \land \epsilon_{\mathcal{S}}(s'') = q'' \land \epsilon_{\overline{T}}(T''_0) \equiv T' \land \epsilon_{\overline{T}}(T''_0) \equiv T''$$

- Under the embedded client interference, the steps taken by the target STS must be countered by a one in the source STS
- From target STS to source STS
- Identifying the valid post state

The Law of Guarantee

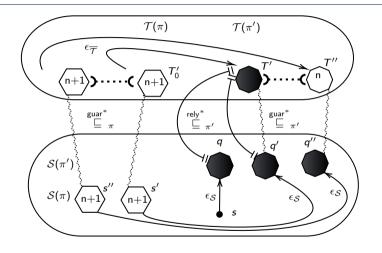
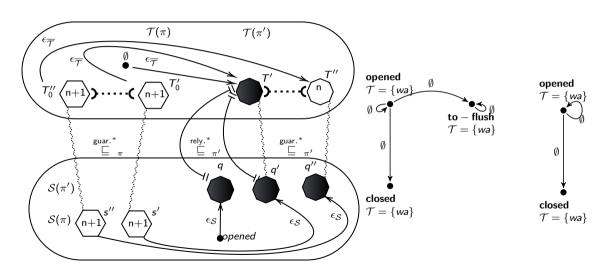
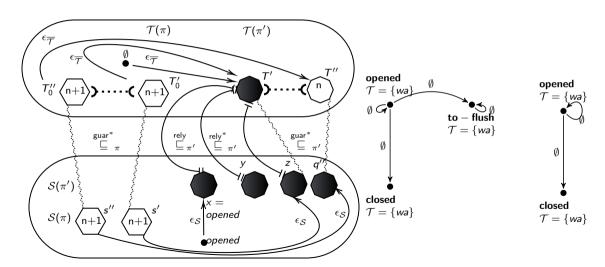


Figure: Embedding the Guarantee Steps of Target STS

The Law of Guarantee for the Bisimulation Instance



The Law of Guarantee for the Bisimulation Instance



We Need This

UPDISL

$$\frac{\alpha \text{ physically atomic}}{\forall s_0 \; . \; ((s;\mathsf{T}) \overset{\mathsf{rely}^*}{\sqsubseteq}_{\pi} \; (s_0;\mathsf{T})) \; \vdash \; \{\varphi(s_0) * P\} \; \alpha \; \{\exists s' \; , \; \mathsf{T'} \; . \; (s_0;\mathsf{T}) \overset{\mathsf{guar}^*}{\sqsubseteq}_{\pi} \; (s';\mathsf{T'}) * \varphi(s') * Q\} }{ \underbrace{\varphi}_{\pi}^{\gamma} \vdash \; \{ \underbrace{[s;\mathsf{T}]_{\pi}^{\gamma} * P\} \; \alpha \; \{\exists s' \; , \; \mathsf{T'} . \underbrace{[s';\mathsf{T'}]_{\pi}^{\gamma} * Q\} } }_{\mathsf{G}} \; \mathcal{A} }$$

$$\frac{\mathsf{BISIM}}{\underbrace{\pi \sim \pi'} \; q \; \epsilon_{\mathcal{S}} \; s \; q' \; \epsilon_{\mathcal{S}} \; s' \; \{ \underbrace{[s;\epsilon_{\overline{T}}(\mathcal{T})]_{\pi'}^{\gamma} * P\} \; C \; \{ \underbrace{[s';\mathsf{T'}]_{\pi'}^{\gamma} * Q\} }_{\mathsf{G}} \; \mathcal{A} \; \mathcal{A$$

How? Obligation - 3

$$\begin{array}{c} \text{UPDISL} \\ \forall s_0 \; . \; ((s;\mathsf{T}) \overset{\text{rely}^*}{\sqsubseteq}_{\pi} \; (s_0;\mathsf{T})) \; \vdash \; \left\{ \begin{array}{c} \varphi(s_0) \\ \end{array} \right. * P \} \; \alpha \; \{\exists s' \; , \; \mathsf{T}' \; . \; (s_0;\mathsf{T}) \overset{\text{guar}^*}{\sqsubseteq}_{\pi} \; (s';\mathsf{T}') * \varphi(s') * Q \} \\ \\ & \underbrace{ \begin{array}{c} \varphi \\ \pi \end{array}}_{\pi} \vdash \{ \underbrace{ \left[\; s; \mathsf{T} \right]_{\pi}^{\gamma} * P \right\} } \; \alpha \; \{\exists \; s', \mathsf{T}' \; . \; \underbrace{ \left[\; s; \mathsf{T} \right]_{\pi}^{\gamma} * Q \right\} } \\ \\ & \underbrace{ \begin{array}{c} \mathsf{BISIM} \\ \pi \sim \pi' \; & q \; \epsilon_{\mathcal{S}} \; s \; & q' \; \epsilon_{\mathcal{S}} \; s' \; & \{ \underbrace{ \left[\; s; \epsilon_{\overline{\mathcal{T}}}(\overline{\mathcal{T}})\right]_{\pi}^{\gamma} * P \right\} } \; C \; \{ \underbrace{ \left[\; s'; \overline{\mathsf{T}'} \right]_{\pi}^{\gamma} * Q \} } \\ \\ & \underbrace{ \begin{array}{c} \varphi \\ \pi \end{array}}_{\pi} \vdash \{ \underbrace{ \left[\; q; \overline{\mathsf{T}} \right]_{\pi}^{\gamma} * P \right\} } \; C \; \{ \underbrace{ \left[\; s'; \overline{\mathsf{T}'} \right]_{\pi}^{\gamma} * Q \} } \\ \end{array}$$

How? Obligation - 4

How? Intuition on Invariants in Bisimulation

UPDISL

- The post condition of the target state machine π' implies the post condition of the source state machine π , e.g., opened
- Applying UPDISL would give
 - $\varphi'(\epsilon_{\mathcal{S}}(s0)) \vdash \exists s' . \varphi'(s')$
 - and precondition in the source STS $\varphi(s0)$
- To obtain $\exists s' . \varphi(s')$

Invariants of File Protocols

Definition (File Protocol Invariants)

$$\varphi_{\mathsf{distributedfile}}\left(\ \ell \ , \ \mathsf{R} \) \left(\ \mathsf{s} \ \right) \ \triangleq \left\{ \begin{array}{l} \mathsf{match} \ \mathsf{s} \ \mathsf{with} \\ \mathsf{to} - \mathsf{flush} \Rightarrow & \mathsf{R} \ast \exists \ \mathsf{fs.} \ \mathsf{isValidDirty}(\mathsf{fs}) \ast \\ & \ell \mapsto (\mathsf{fs.} \mathit{id.} \ \mathsf{fs.status} = \mathsf{dirty}) \\ \mathsf{opened} \Rightarrow & \mathsf{R} \ast \exists \ \mathsf{fs.} \ \mathsf{isValid}(\mathsf{fs}) \ast \\ & \ell \mapsto (\mathsf{fs.} \mathit{id.} \ \mathsf{fs.status} = \mathsf{clean}) \\ \mathsf{closed} \Rightarrow & \exists \ \mathsf{fs.} \ \mathsf{isValidClosed}(\mathsf{fs}) \ast \\ & \ell \mapsto (\mathsf{fs.} \mathit{id.} \ \mathsf{fs.status} = \mathsf{closed}) \\ \end{array} \right)$$

$$\varphi_{\mathsf{file}}\left(\ \ell \ \mathsf{R} \) \left(\ \mathsf{s} \ \right) \ \triangleq \left\{ \begin{array}{l} \mathsf{match} \ \mathsf{s} \ \mathsf{with} \\ \mathsf{opened} \Rightarrow & \mathsf{R} \ast \exists \ \mathsf{fs.} \ \mathsf{isValid}(\mathsf{fs}) \ast \ell \mapsto (\mathsf{fs.} \mathit{id.} \ \mathsf{fs.status} = \mathsf{clean} \lor \mathsf{dirty}) \\ \mathsf{closed} \Rightarrow & \exists \ \mathsf{fs.} \ \mathsf{isValidClosed}(\mathsf{fs}) \ast \ell \mapsto (\mathsf{fs.} \mathit{id.} \ \mathsf{fs.status} = \mathsf{closed}) \\ \end{array} \right\}$$

The Law of Tolerance

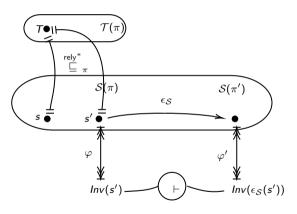


Figure: The Law of Tolerance for a Valid Pre-Condition

Theorem (The Law of Tolerance)

$$\forall \ s' \ . \ (s \ \mathsf{T}) \stackrel{\mathsf{rely}^*}{\sqsubseteq}_{\pi} \ (s'; \mathsf{T}) \leftrightarrow \qquad \varphi(s') \ \vdash \ \varphi'(\epsilon_{\mathcal{S}}(s'))$$

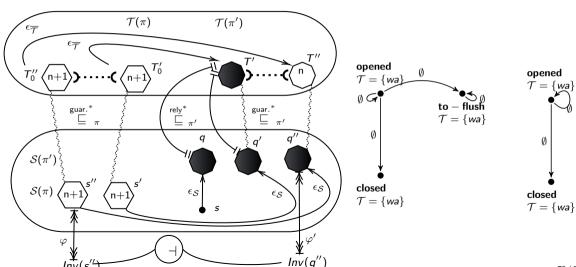
- The source STS's precondition for the embedded states is stronger
- $\varphi(\text{flushed})$ of π or $\varphi(\text{opened})$ of π implies $\varphi'(\text{opened})$ of π'

Revisiting the Law of Guarantee for Invariants

Theorem (The Law of Guarantee with Invariants)

$$\forall \ q' \ . \ (\epsilon_{\mathcal{S}}(s); \epsilon_{\overline{\mathcal{T}}}(\mathsf{T})) \stackrel{\mathsf{rely}^*}{\sqsubseteq}_{\pi'} (\epsilon_{\mathcal{S}}(q'); \epsilon_{\overline{\mathcal{T}}}(\mathsf{T})) \rightarrow \\ \forall \ q'', \ \mathsf{T}'' \ . \ (q'; \epsilon_{\overline{\mathcal{T}}}(\mathsf{T})) \stackrel{\mathsf{guar}^*}{\sqsubseteq}_{\pi'} (q''; \mathsf{T}'') \rightarrow \\ \exists \ s' \ s'' \ \mathsf{T0}' \ \mathsf{T0}'' \ . \ (s'; \mathsf{T0}') \stackrel{\mathsf{guar}^*}{\sqsubseteq}_{\pi} (s''; \mathsf{T0}'') \land \\ \epsilon_{\mathcal{S}}(s') = q' \land \epsilon_{\mathcal{S}}(s'') = q'' \land \\ (\epsilon_{\overline{\mathcal{T}}}(\mathsf{T0}')) = (\epsilon_{\overline{\mathcal{T}}}(\mathsf{T})) \land (\epsilon_{\mathcal{T}}(\mathsf{T0}')) = \mathsf{T}'' \land \\ \varphi'(q'') \vdash \varphi(s'')$$

Revisiting the Law of Guarantee for Invariants

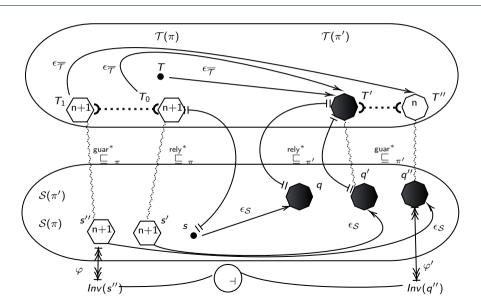


Soundness

Theorem (Soundness)

The updated state from UPDISL is preserved by the bisimulation.

Soundness



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Keeping Promises

TRANSFER FILE WRITE
$$\pi \sim \pi' \quad \text{opened } \epsilon_{\mathcal{S}} \ s \quad q' \ \epsilon_{\mathcal{S}} \ s' \\ \{ \ [s; \epsilon_{\overline{T}}(\overline{T})]_{\pi'}^{\gamma} * P \} \text{ write } \ell \text{ new_val } \{ \ [s'; \overline{T'}]_{\pi'}^{\gamma} * Q \} \\ \hline \\ \varphi_{\text{distributedfile}} \ \ _{\pi}^{\gamma} \vdash \{ \ [\text{opened}; \overline{T}]_{\pi}^{\gamma} * P \} \ C \ \{ \ [q'; \overline{T'}]_{\pi}^{\gamma} * Q \}$$

Ongoing Work

- Bisimulation over Restricted Submodels
 - We need to strengthen the bisimulation
 - What is this strength?
 - Guarantee steps taken at the target machine with $T\setminus U$ has to be indistinguishable (entail) the ones taken with T
 - The Law of Abduction: Knowing more about U and capabilities dropped with the absence of it.
- Extending Rules for the Complete Iris HEAPLANG
- An abstract framework with relational *embeddings* is finished and written.
 - Subjectively more promising!
 - We need to justify concretely via an example, that is, an example exposes incapability
 of current non-relational embeddings of states and tokens

The Future Directions

- Exploit obvious application fields, e.g., device drivers
- Only Iris pluggable?



Verifying a concurrent, crash-safe file system with sequential reasoning.

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