

docs

ATOM / Fieldbus / EtherNet/IP / Codesys

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Date: 2025-10-30

Contents

| | |
|---|----|
| • ATOM / Fieldbus / EtherNet/IP / Codesys | 1 |
| ○ Prerequisites | 1 |
| ○ Hardware setup | 1 |
| ○ Configuring Atom network settings | 2 |
| ○ Create a Codesys project | 3 |
| ○ Adding an EtherNet/IP Scanner | 5 |
| ○ Adding ATOM to the scanner | 10 |
| ○ Create a program | 15 |
| ○ Example: Ladder logic | 15 |
| ■ Creating the program | 15 |
| ■ Setting up visualization | 23 |
| ■ Wiring up the controls | 28 |
| ■ Mapping variables | 30 |
| ○ Example: Structured text | 33 |
| ■ Creating the program | 33 |
| ■ Mapping variables | 39 |
| ○ Running the program with SoftPLC | 42 |

ATOM / Fieldbus / EtherNet/IP / Codesys

In this tutorial, you'll learn how to use Codesys with the SoftPLC emulator to connect to ATOM using EtherNet/IP and perform some basic operations and monitor data. You can follow along using the SoftPLC emulator or your own PLC.

We provide examples for both ladder logic and structured text.

If you haven't yet, please review ATOM's [EtherNet/IP Profile](#).

If you'd like to skip the tutorial, you can download a completed example project:

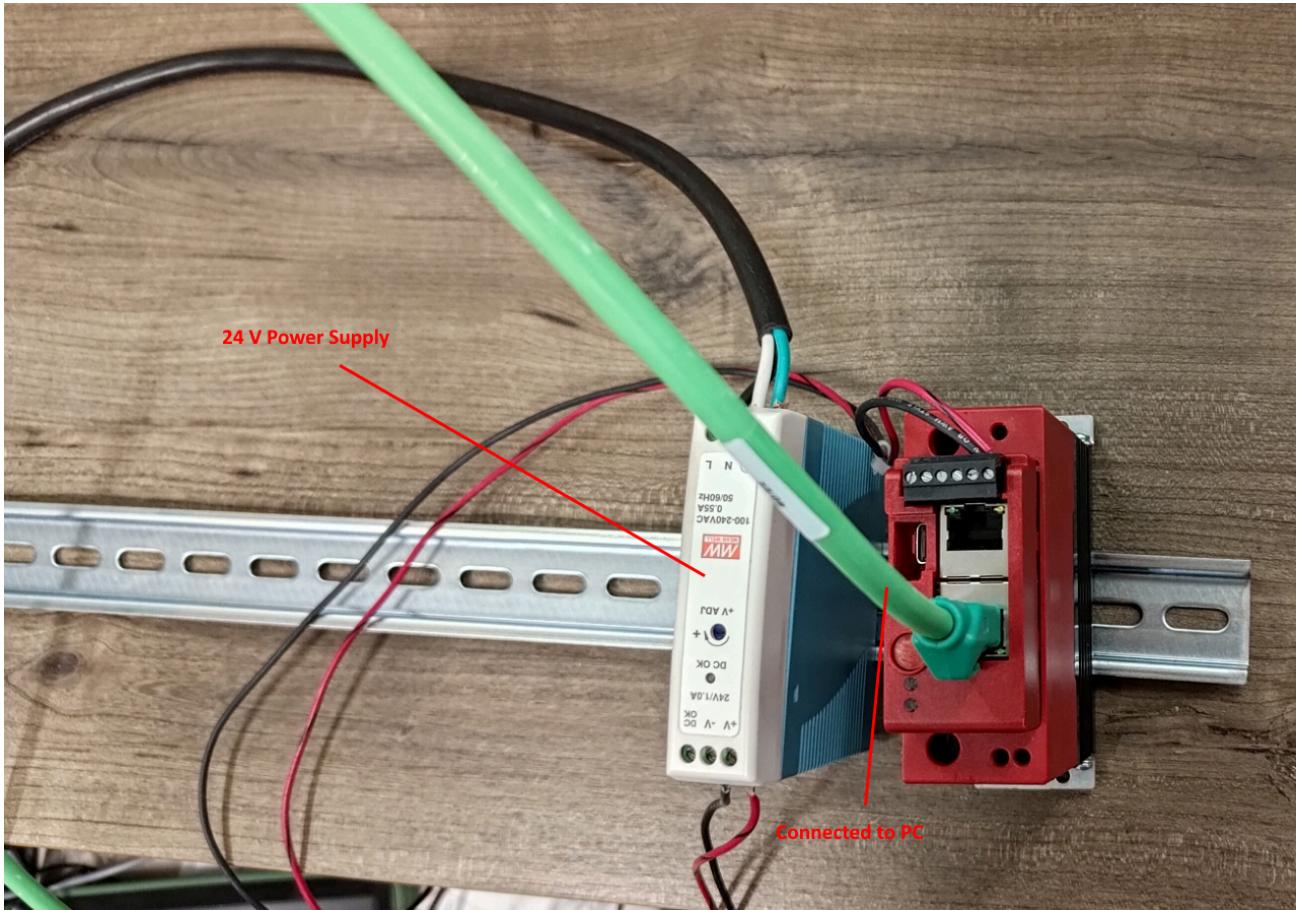
- Download [ATOM_Codesys_LadderLogic_Example.zip](#)
- Download [ATOM_Codesys_StructuredText_Example.zip](#)

Prerequisites

1. Install [Codesys](#)
2. Download ATOM's [EDS file](#)

Hardware setup

Connect 24V to your PLC and Atom unit with the provided power cable. Connect Atom to your PC with an Ethernet cable.



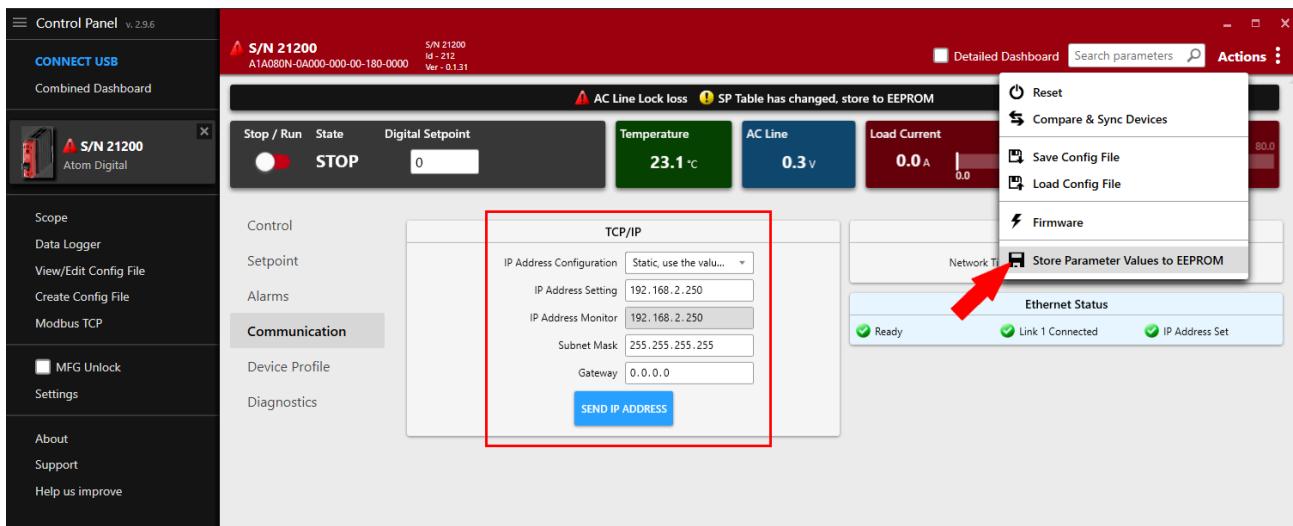
ⓘ INFO

To simplify this diagram, we have not connected a load to Atom. You may connect a load or leave it disconnected, either way is fine for the purposes of this tutorial.

If you do not connect a load, you can still verify your PLC is working by connecting a USB cable to Atom and using Control Panel to watch the parameters change/verify the PLC is receiving the correct monitor data.

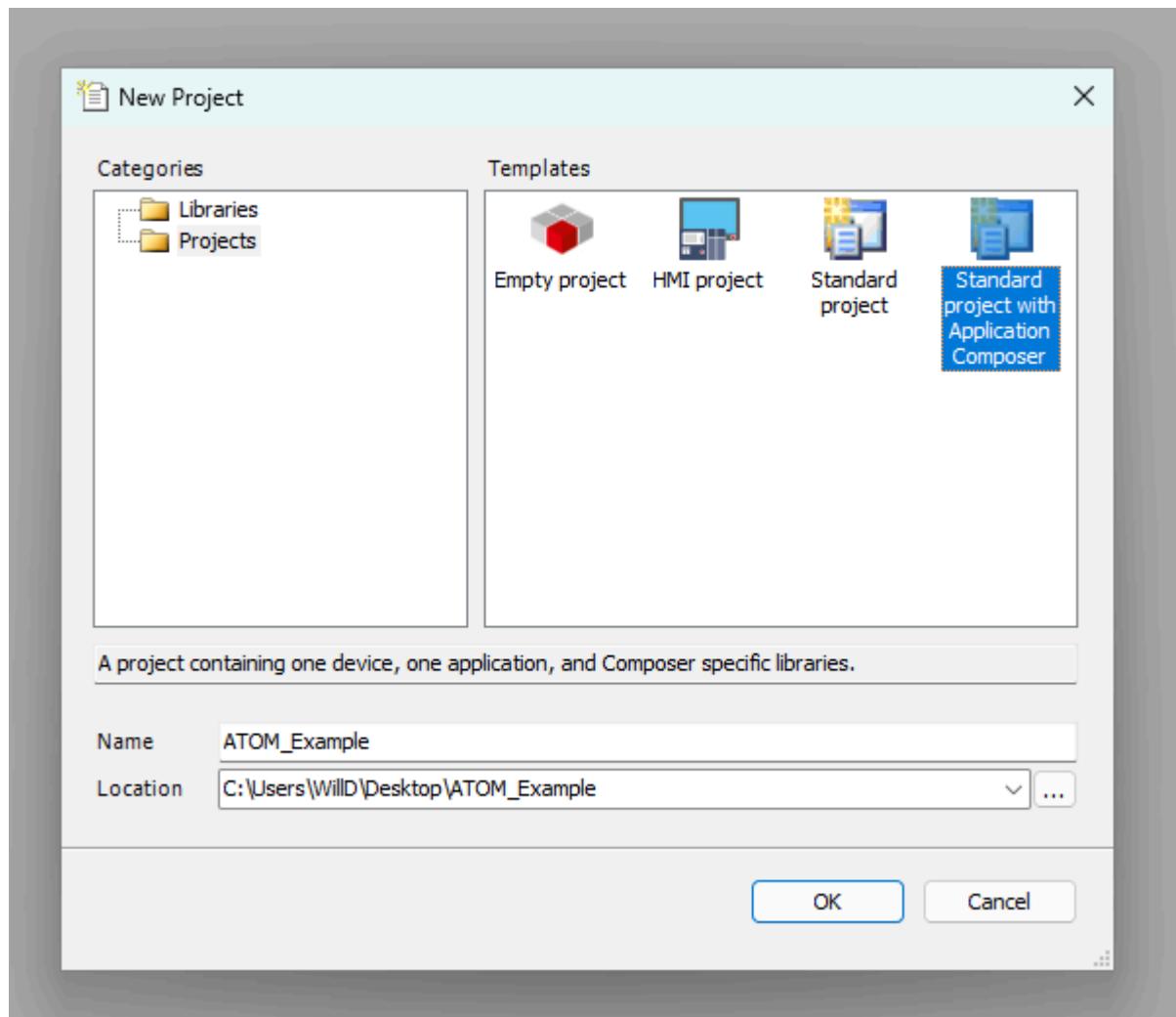
Configuring Atom network settings

Connect your Atom unit to your PC using a USB cable. Open Control Panel and update your Atom's communication parameters. When you're finished, click **Send IP Address**, then go to **Actions** in the upper right and select **Store Parameter Values to EEPROM**:

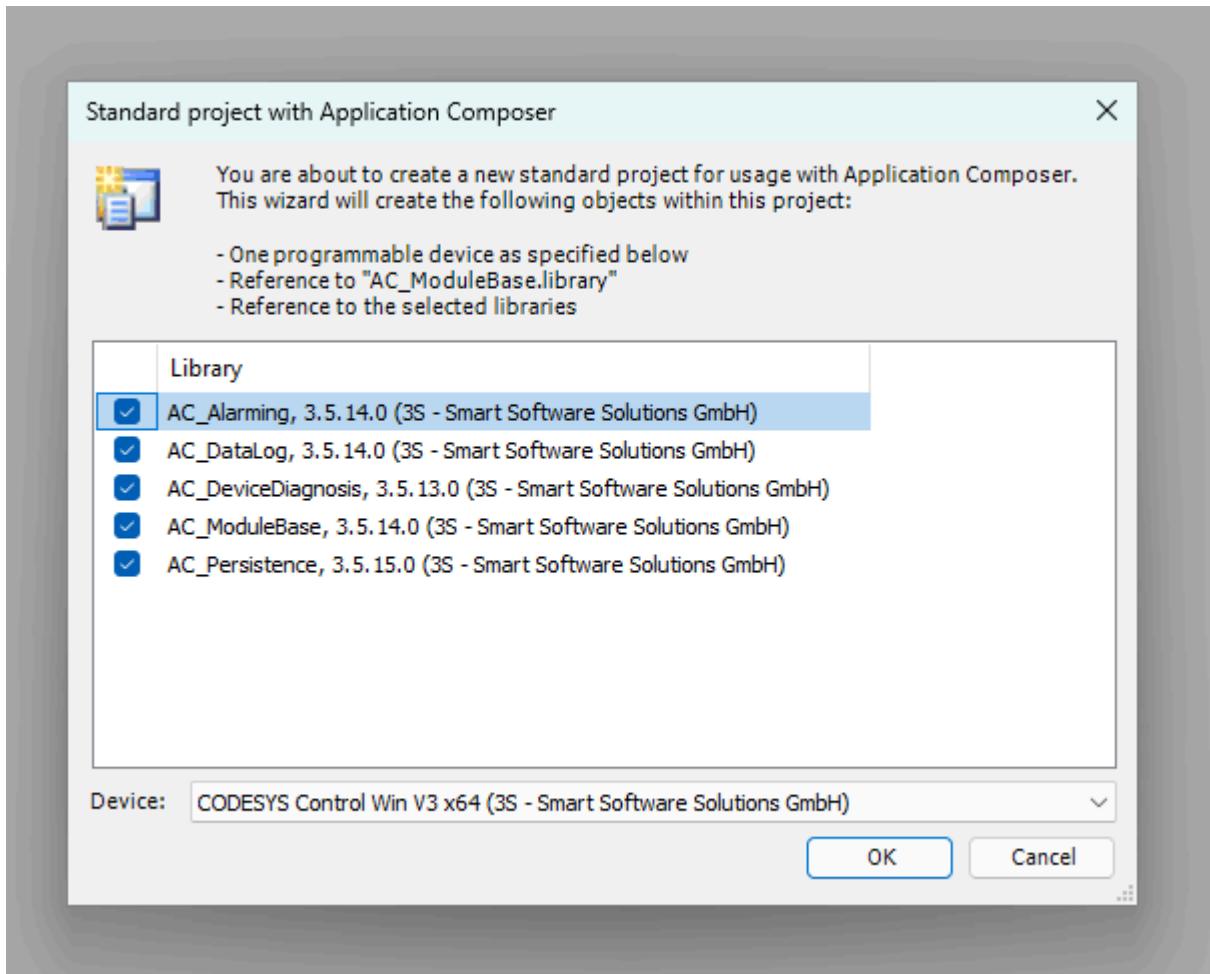


Create a Codesys project

Create a new Codesys project using the **Standard project with Application Composer** template:



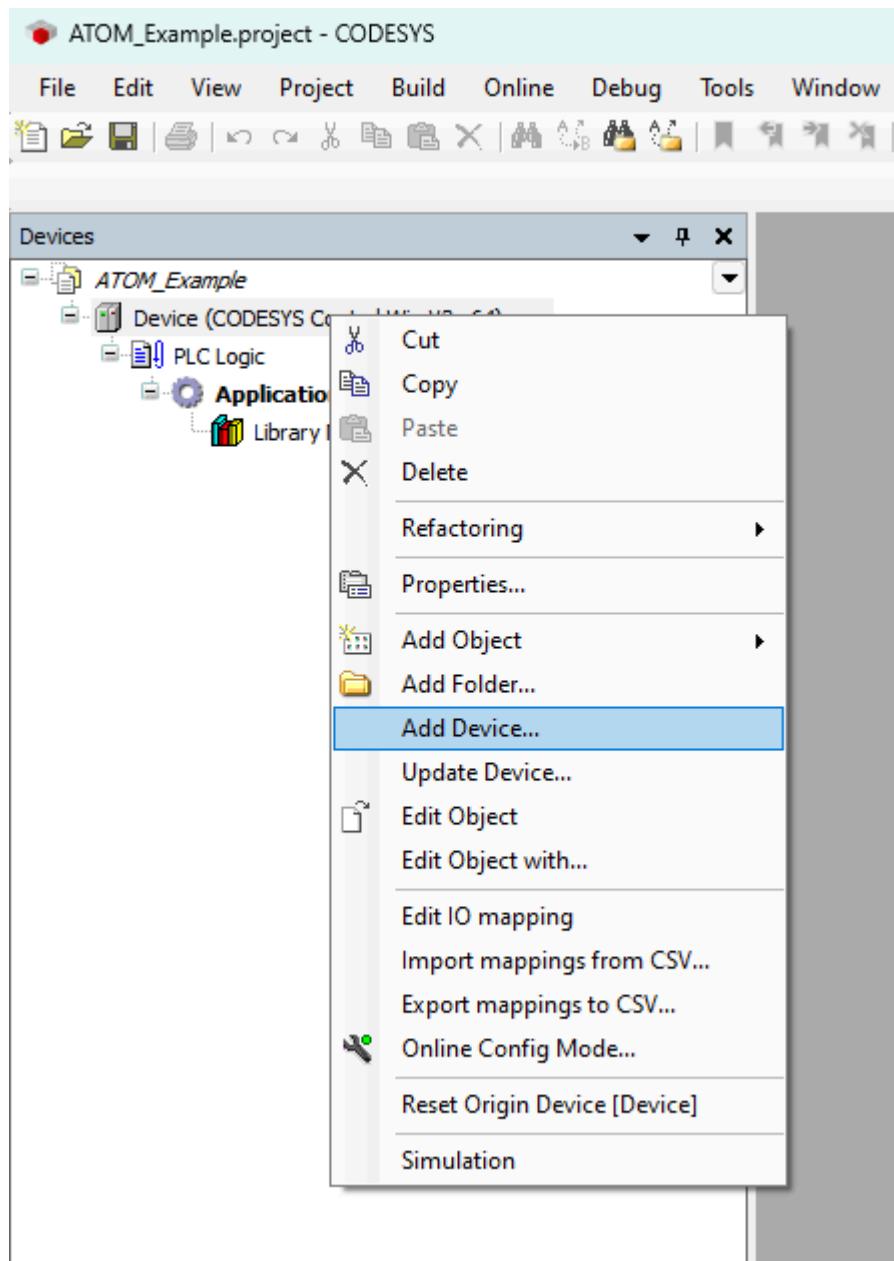
Check each library to include it in the project and select **CODESYS Control WIN V3 x64** as the device:



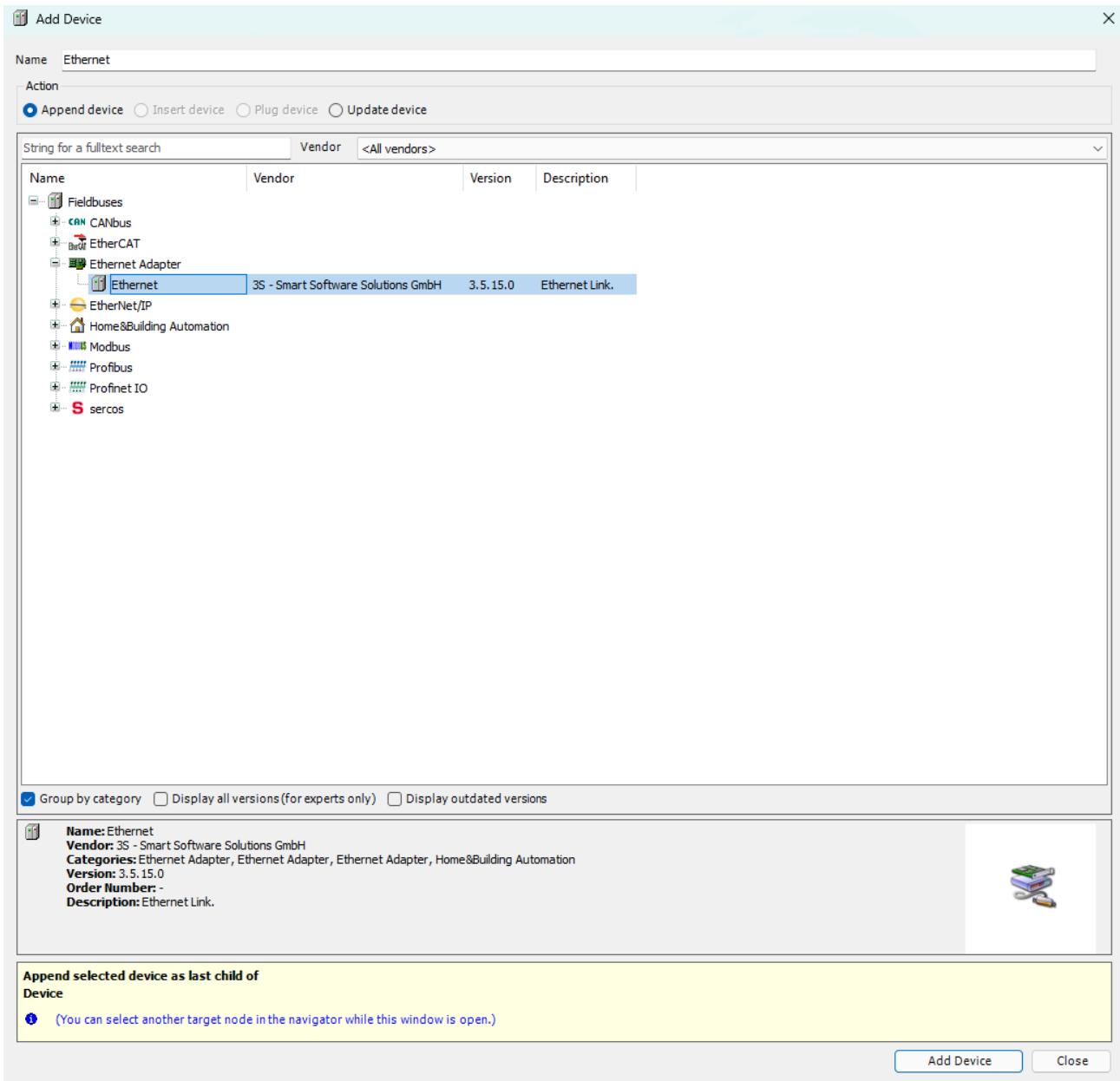
Adding an EtherNet/IP Scanner

Next we'll add an EtherNet/IP Scanner module. This allows the PLC to discover EtherNet/IP devices on the network (in our case, ATOM) and establish a connection with them.

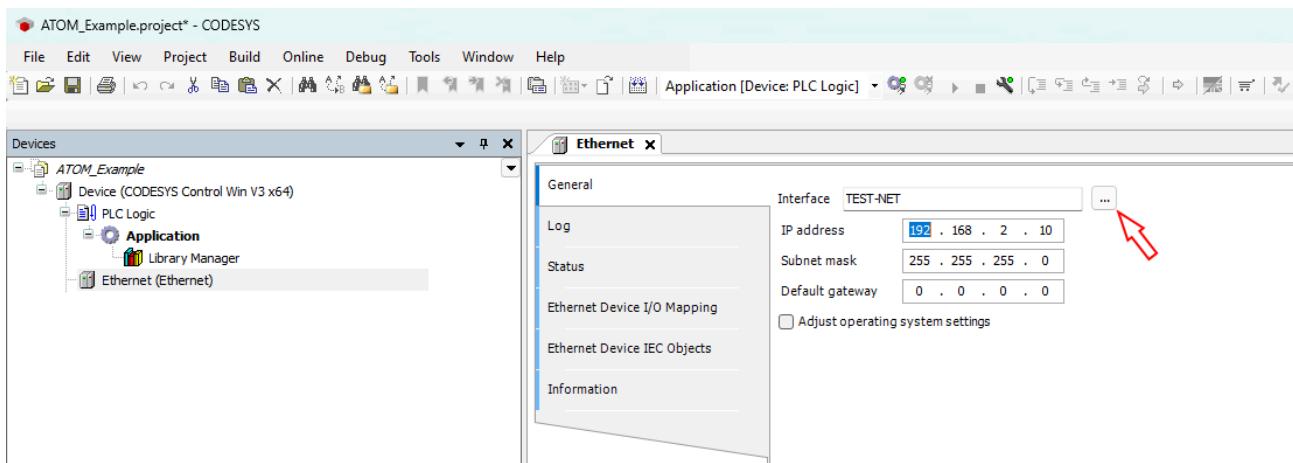
First, right click **Device** and select **Add Device**:



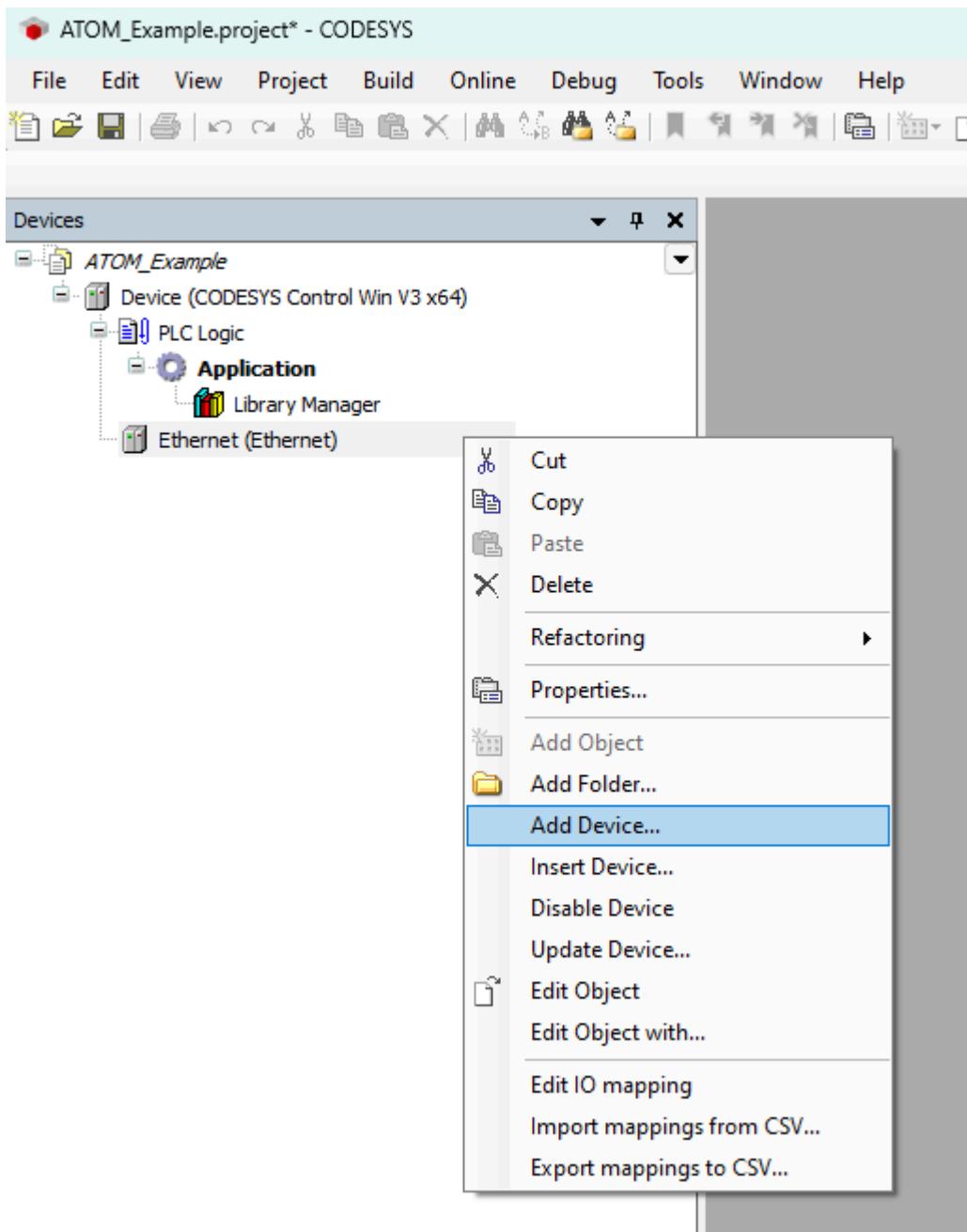
Next, expand **Ethernet Adapter** and select **Ethernet**, then click **Add Device**:



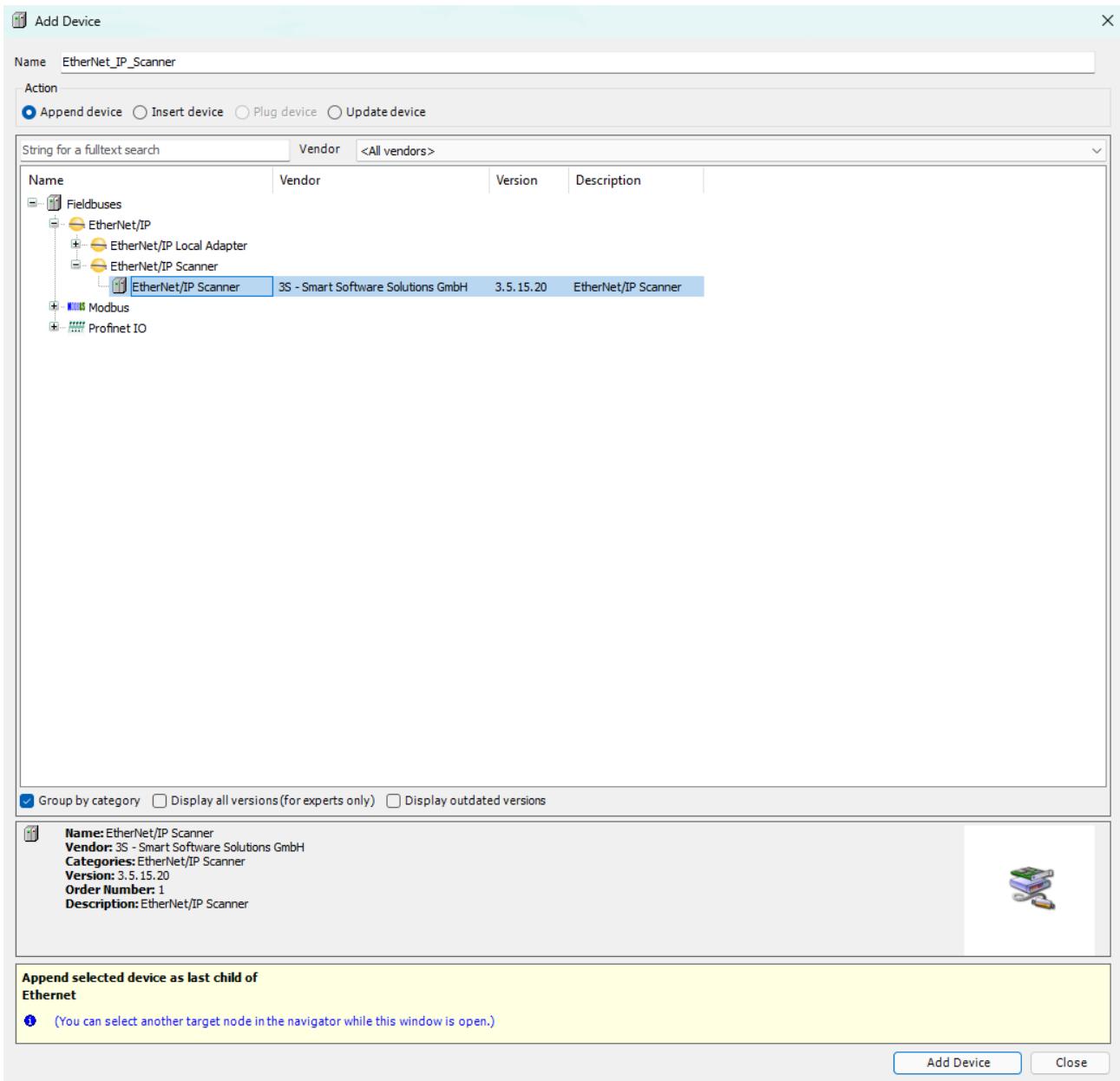
The newly added **Ethernet** device will now appear in the device tree. Double click **Ethernet (Ethernet)** to open its configuration tab. Within the **General** configuration tab, use the button indicated by the red arrow to select the network interface of the host machine that will be used to communicate with ATOM. In our case, we have a **TEST-NET** interface but this will be different for you.



Next, right click **Ethernet (Ethernet)** and select **Add Device**:



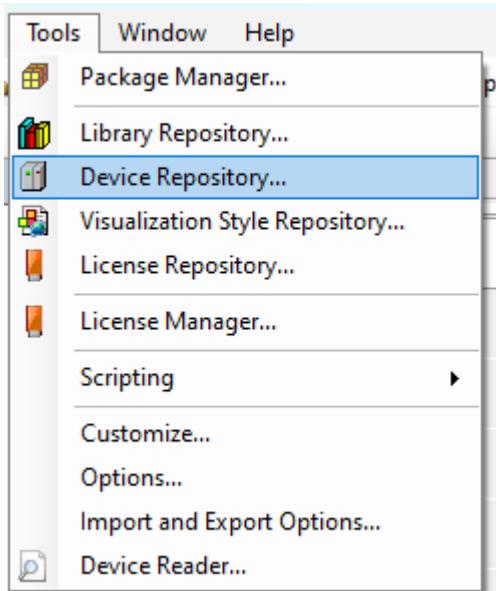
Expand **EtherNet/IP Scanner**, select **EtherNet/IP Scanner**, then click **Add Device**:



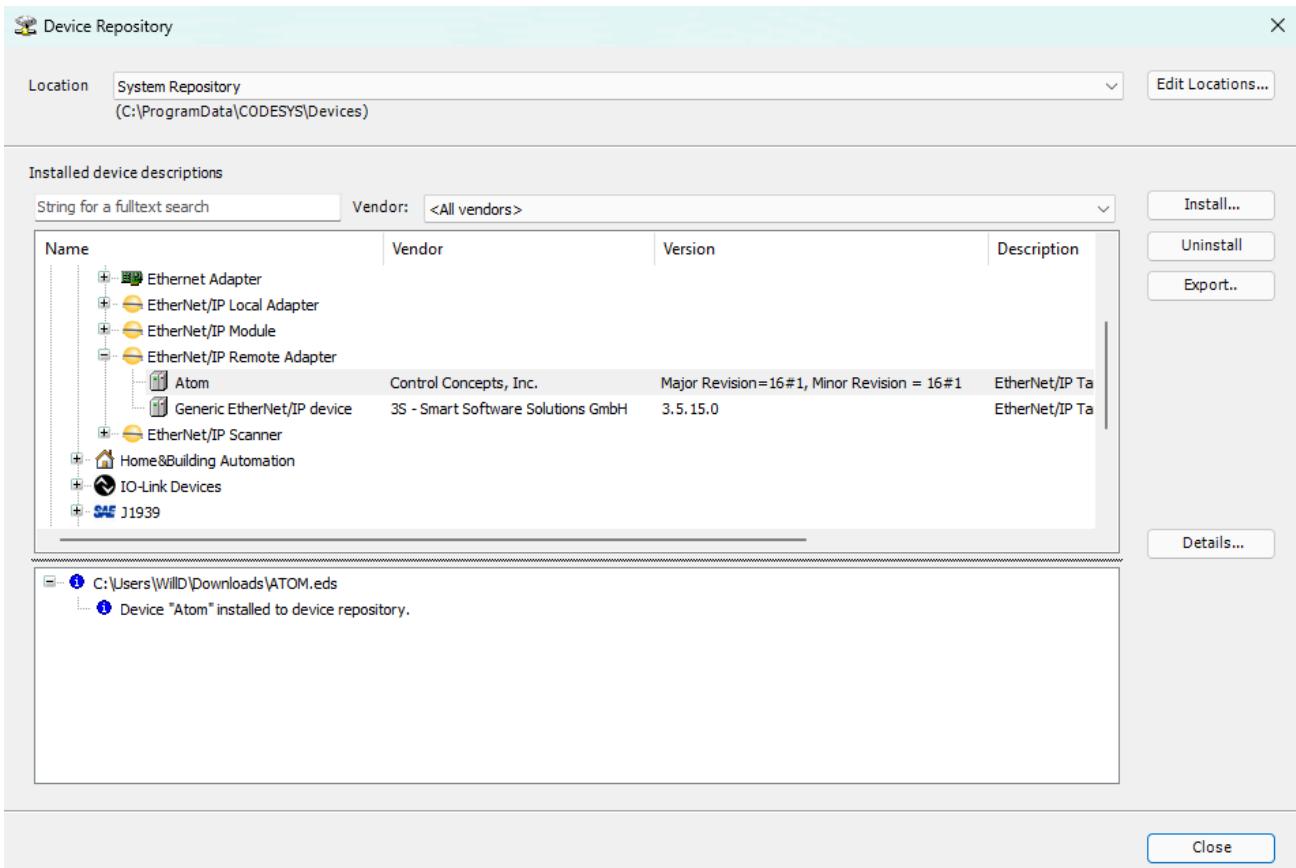
Your device tree should update to include the **EtherNet/IP Scanner** device.

Adding ATOM to the scanner

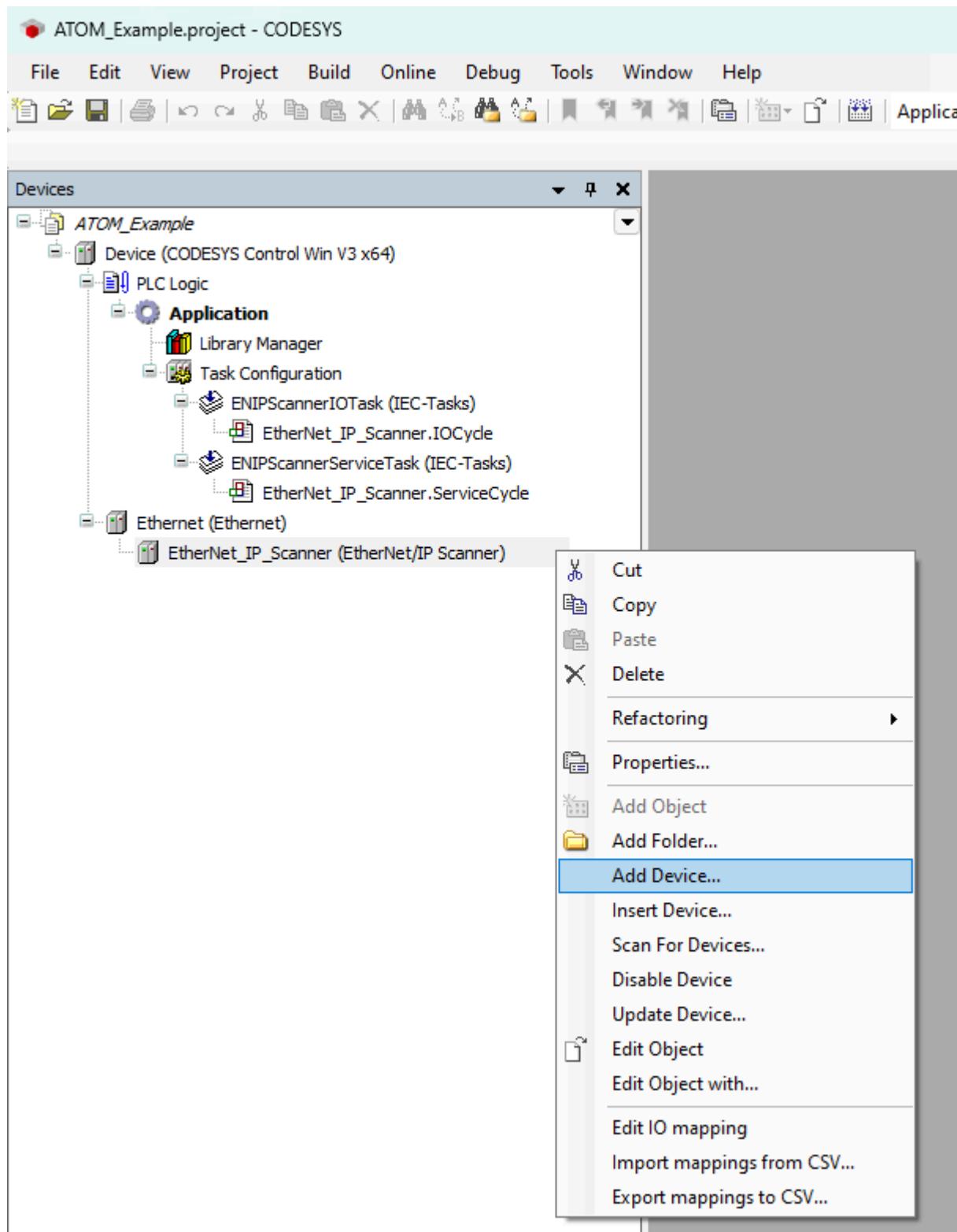
First, we'll import ATOM's EDS file you downloaded [earlier](#) into our Codesys device library. Open the tools menu and select **Device repository**:



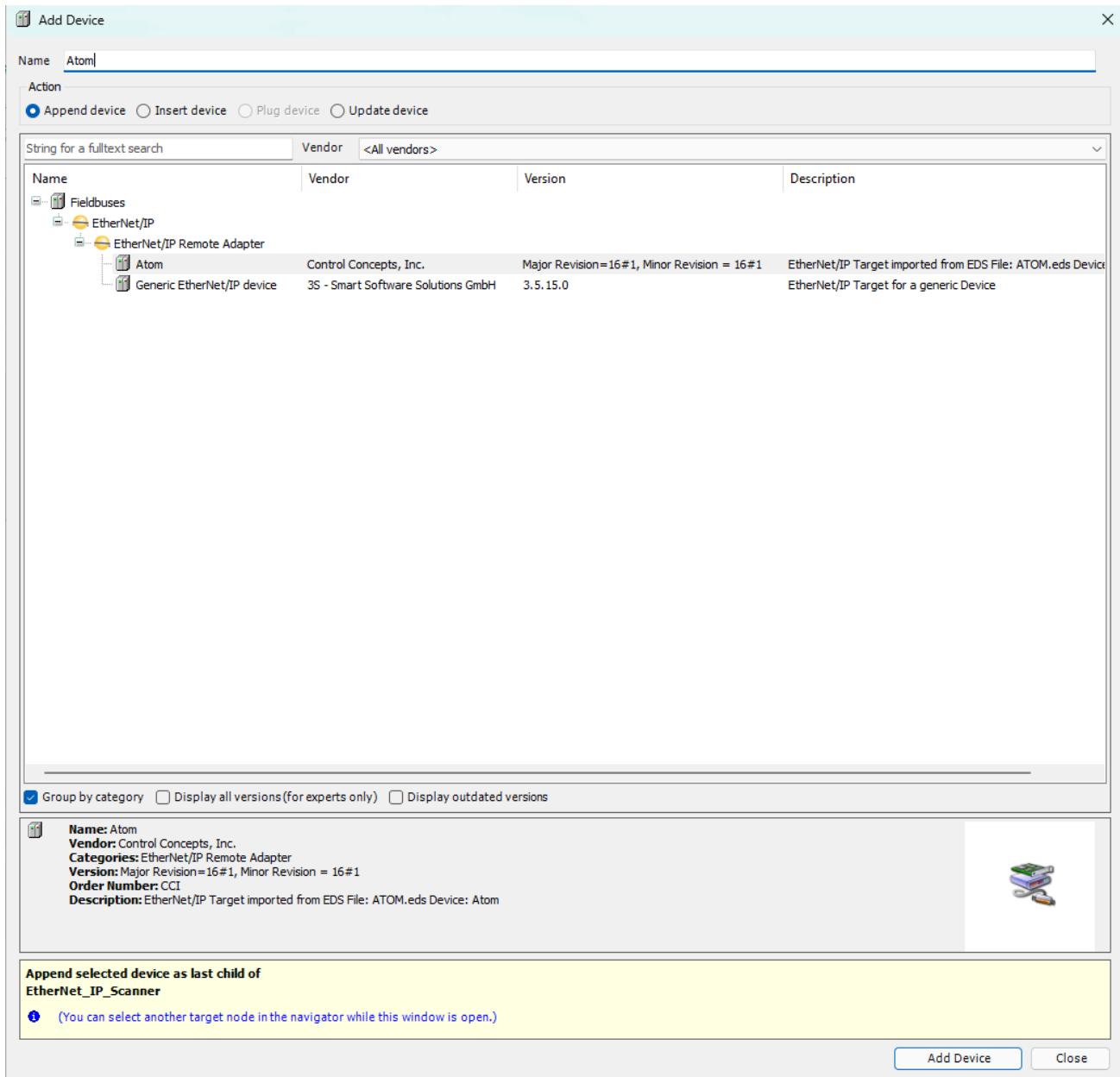
Next, click **Install** and select the `ATOM.eds` file. After you click install, **Atom** will appear under the **EtherNet/IP Remote Adapter** category. Click **Close** to dismiss the dialog:



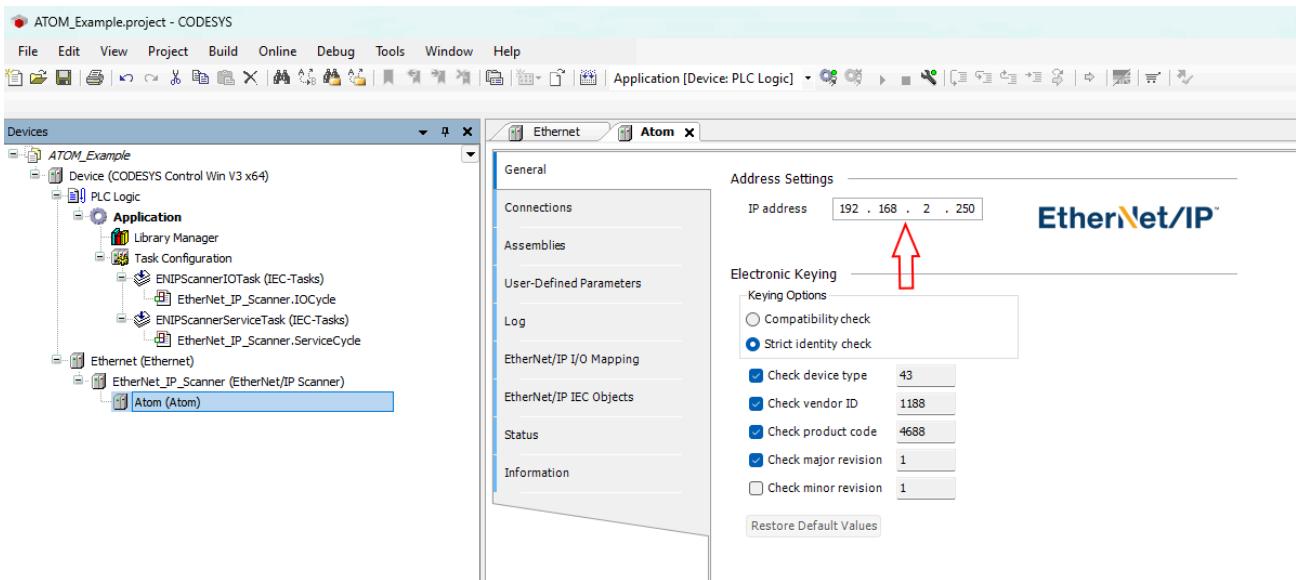
Now, we'll add ATOM to the scanner. Right click **EtherNet/IP Scanner (EtherNet/IP Scanner)** and select **Add Device**:



Expand **EtherNet/IP Remote Adapter** and select **Atom**, then click **Add Device**:



Finally, double click **Atom (Atom)** to open its configuration tab. In the **General** tab, set the **IP Address** to the IP address of your ATOM device:



Create a program

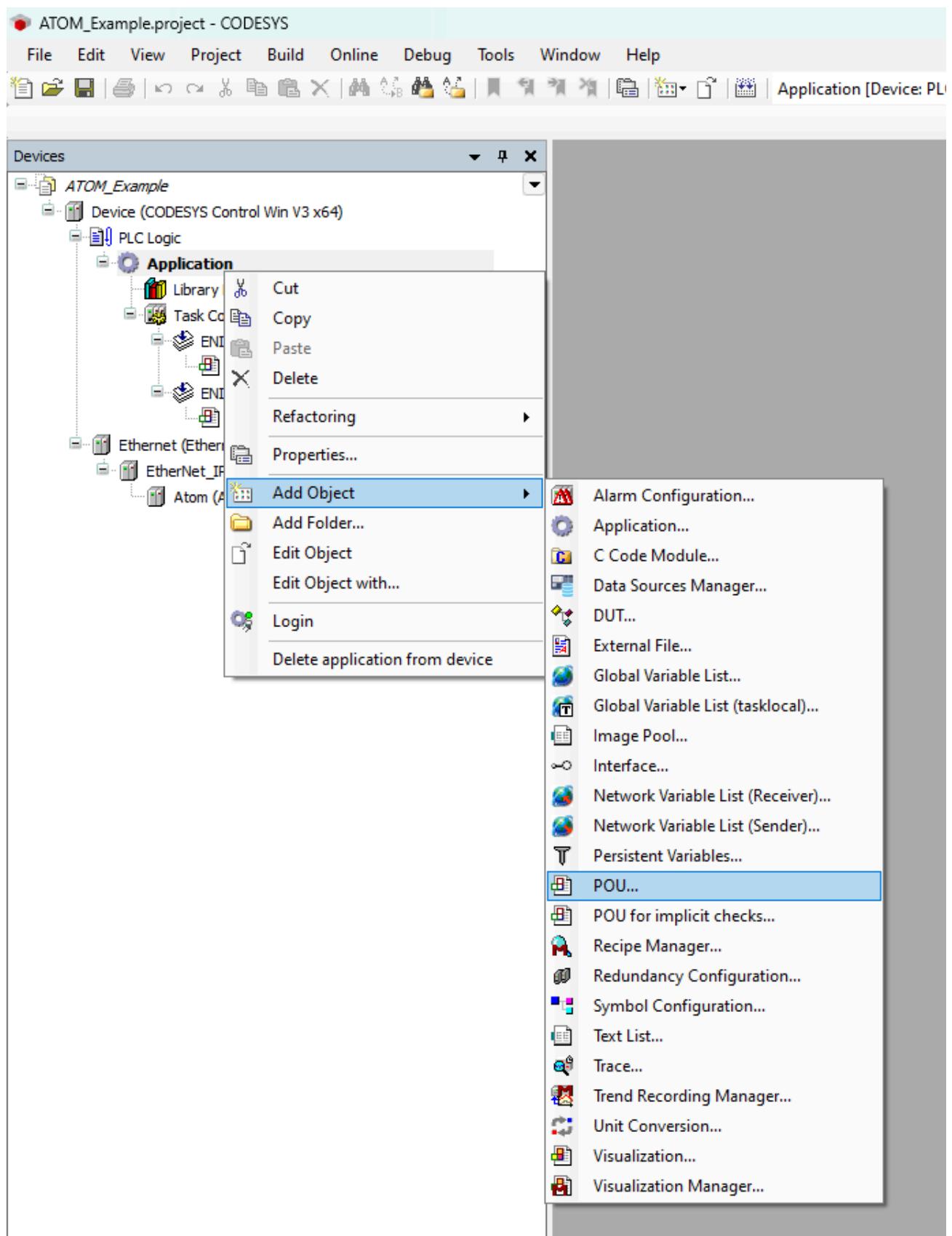
Next, we'll create a PLC program. We provide examples for both ladder logic and structured text:

- Program with ladder logic
- Program with structured text

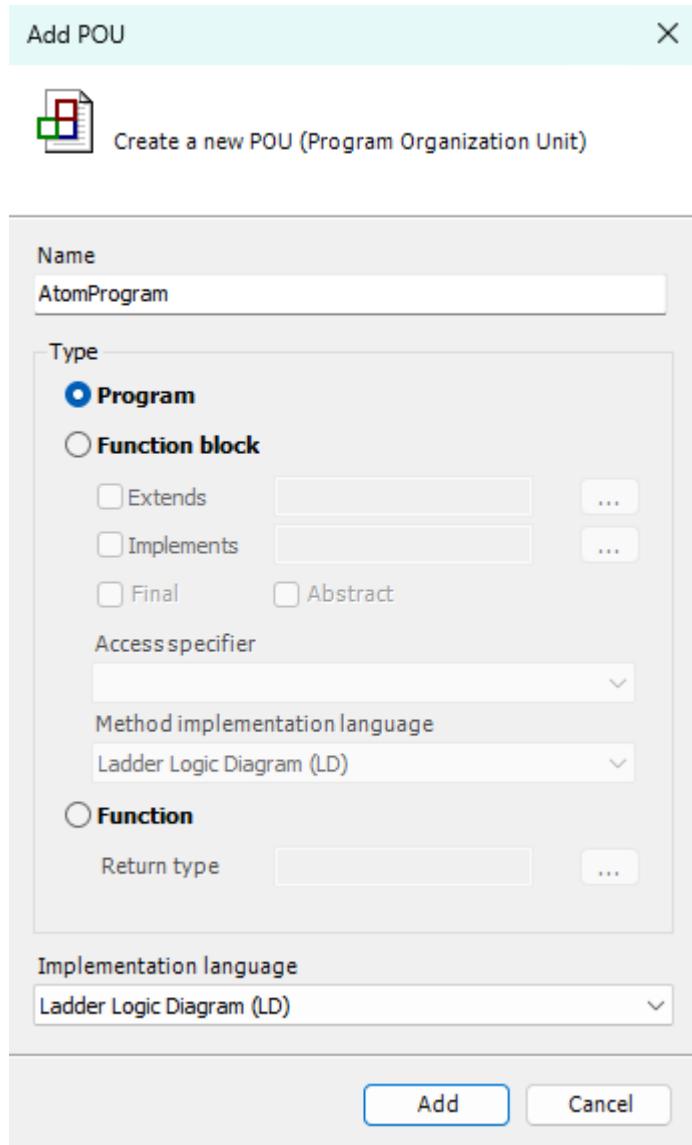
Example: Ladder logic

Creating the program

Right click **Application** and select **Add Object > POU**:



Set the name to **AtomProgram** and select **Ladder Diagram (LD)** as the Implementation language:



Copy the following code into the top panel of the **AtomProgram** editor:

```
PROGRAM AtomProgram
```

```
VAR
```

```
RUN_SWITCH: BOOL;
```

```
SETPOINT: DINT;
```

```
TEMP: REAL;
```

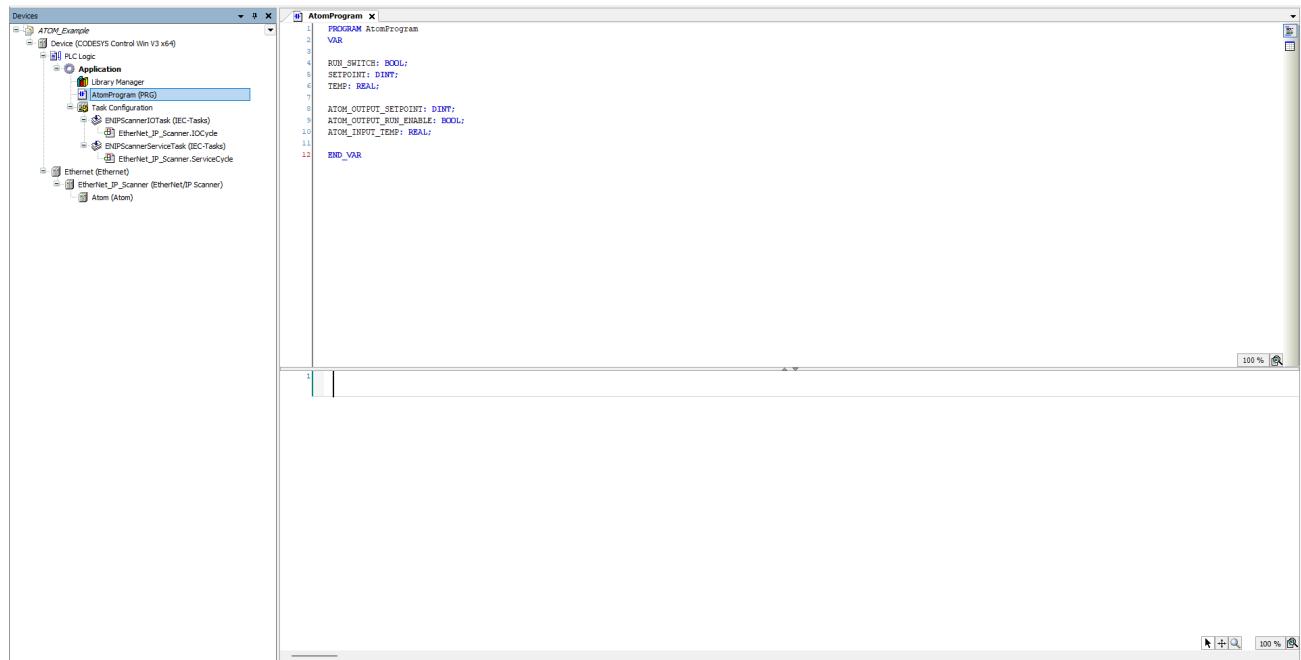
```
ATOM_OUTPUT_SETPOINT: DINT;
```

```
ATOM_OUTPUT_RUN_ENABLE: BOOL;
```

```
ATOM_INPUT_TEMP: REAL;
```

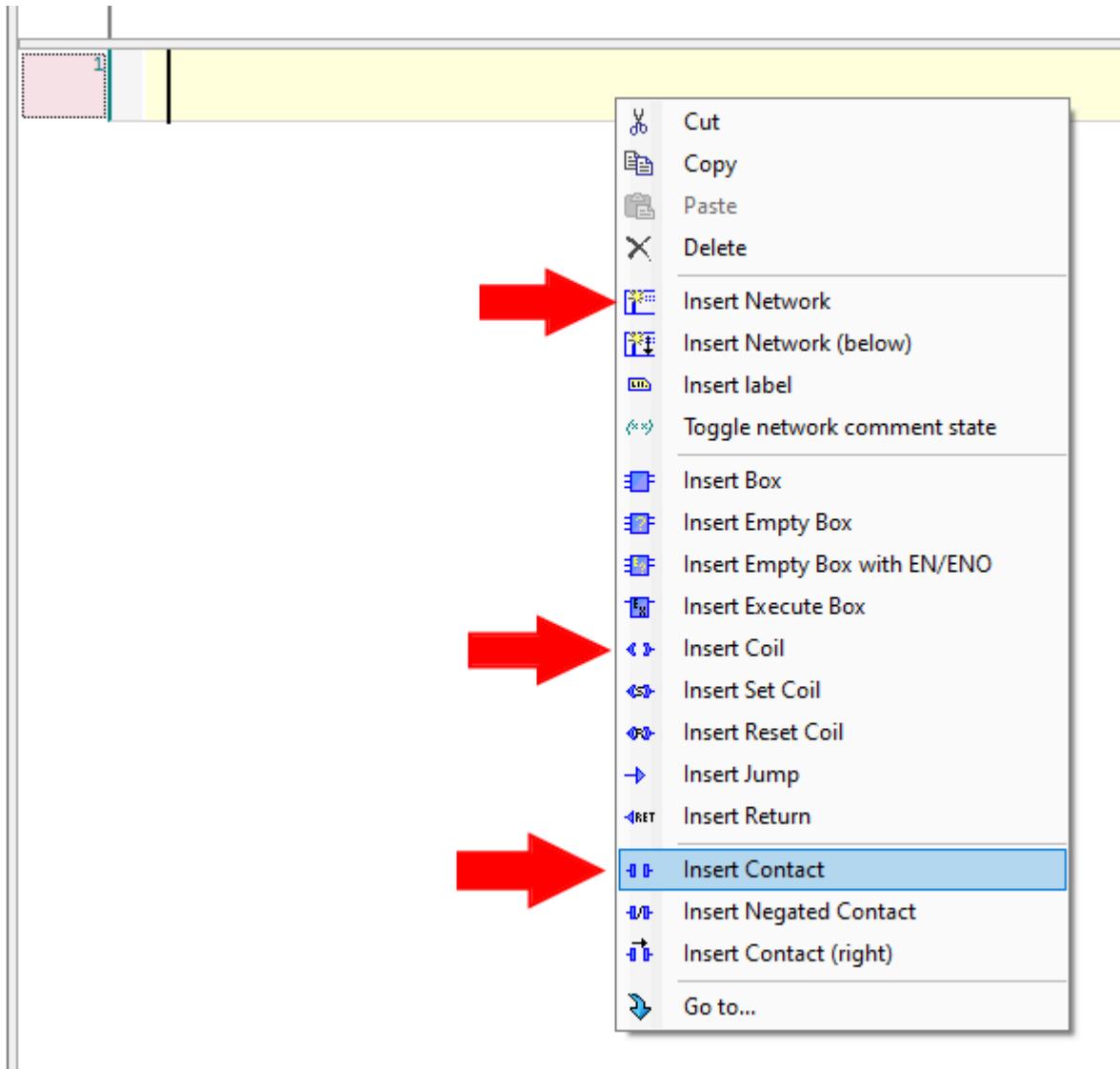
```
END_VAR
```

After you've copied the code over, the editor for **AtomProgram** should look like this:



In the bottom panel of the editor, we'll create a simple ladder logic program using the variables we just added above.

1. Create **3** networks total by right-clicking and selecting **Insert Network**
2. For each network, right click and insert **one** contact and **one** coil



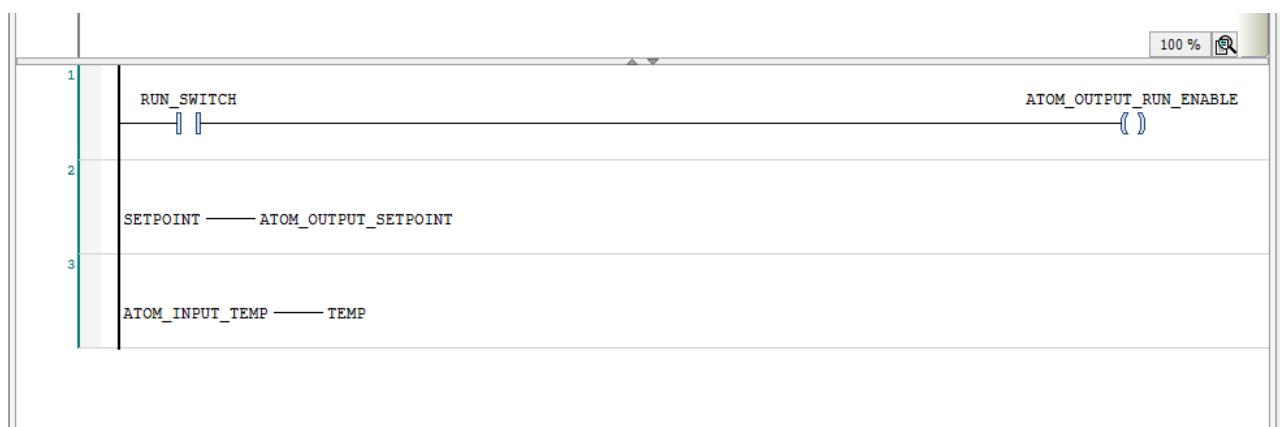
After you're finished, your ladder logic program should look like:



For each rung, replace the **???** with the corresponding variables:

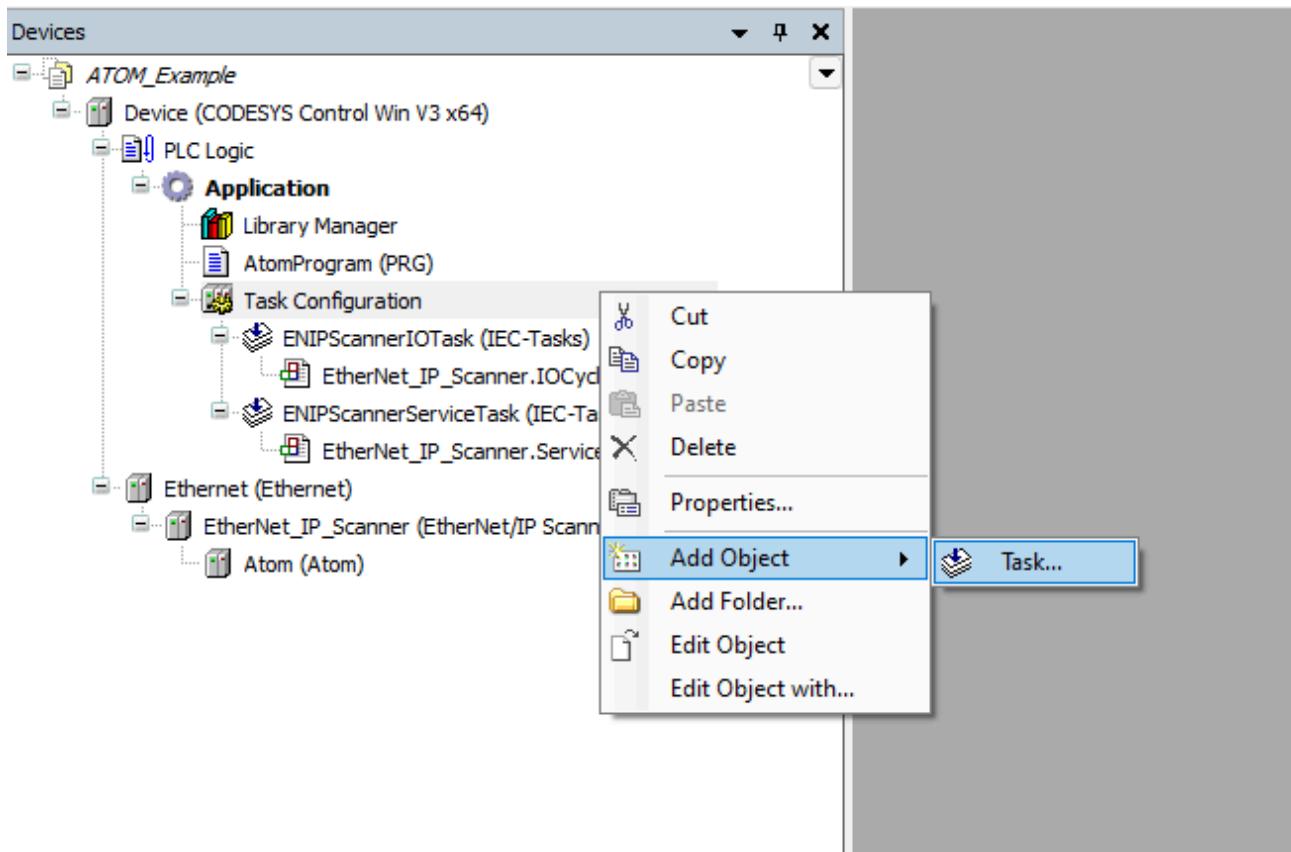
1. **Rung #1** - **RUN_SWITCH** and **ATOM_OUTPUT_RUN_ENABLE**
2. **Rung #2** - **SETPOINT** and **ATOM_OUTPUT_SETPOINT**
3. **Rung #3** - **ATOM_INPUT_TEMP** and **TEMP**

After you're finished, your ladder logic program should look like:

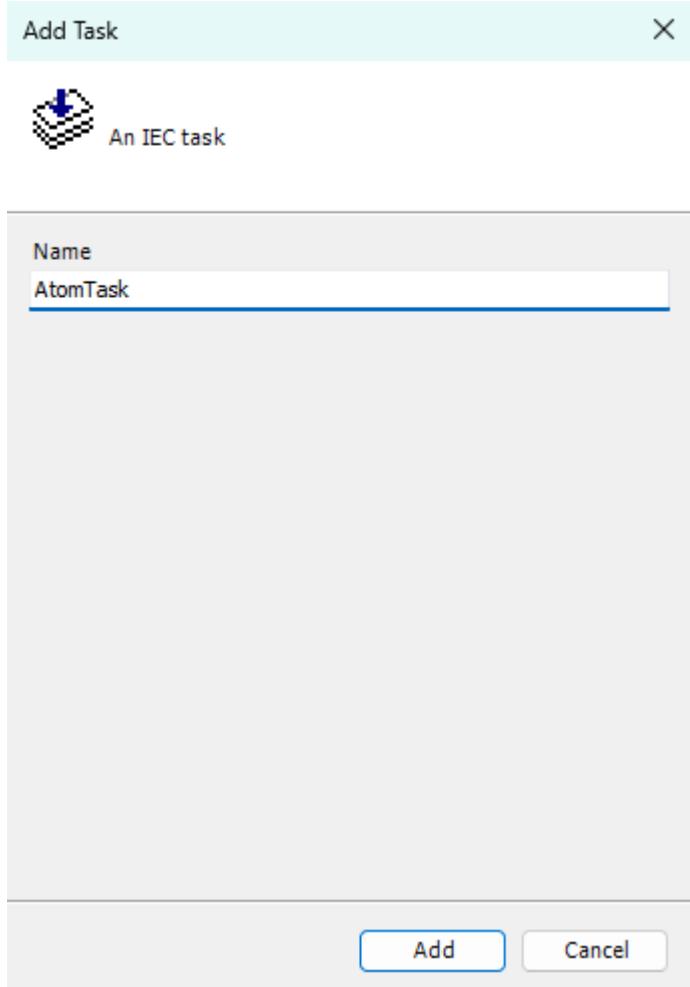


Finally, we'll add a task to call **AtomProgram** from the PLC's control loop:

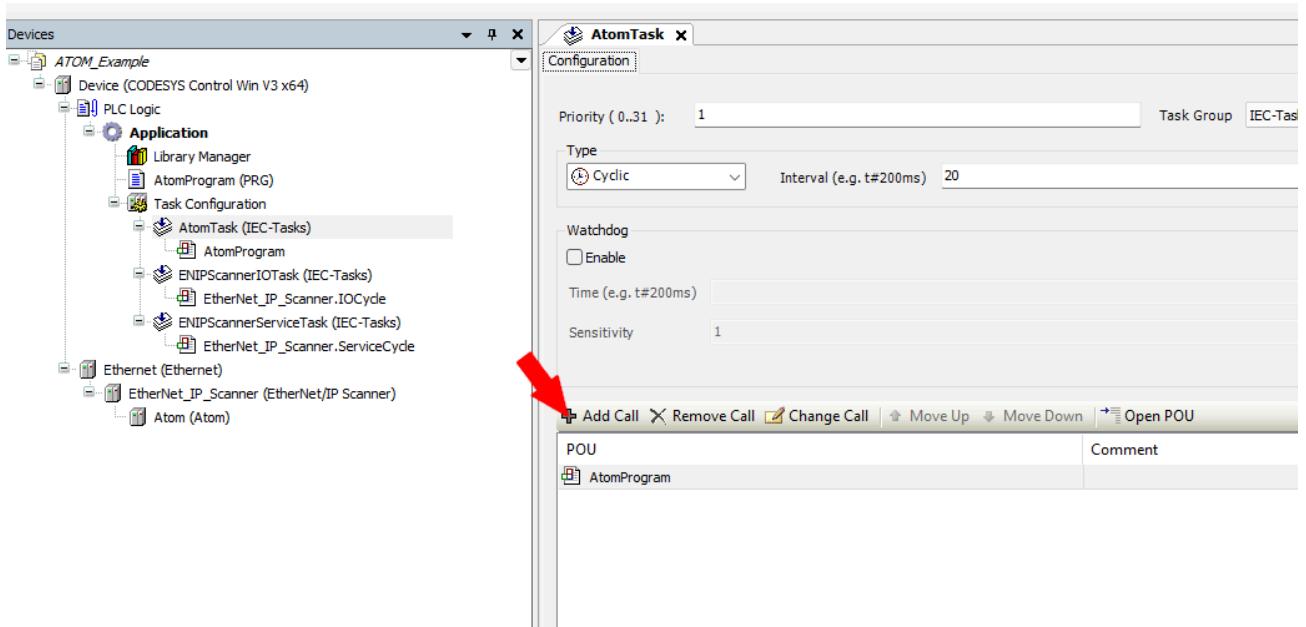
Right click **Task Configuration** and select **Add Object > Task**:



Name your task **AtomTask** and click **OK**:



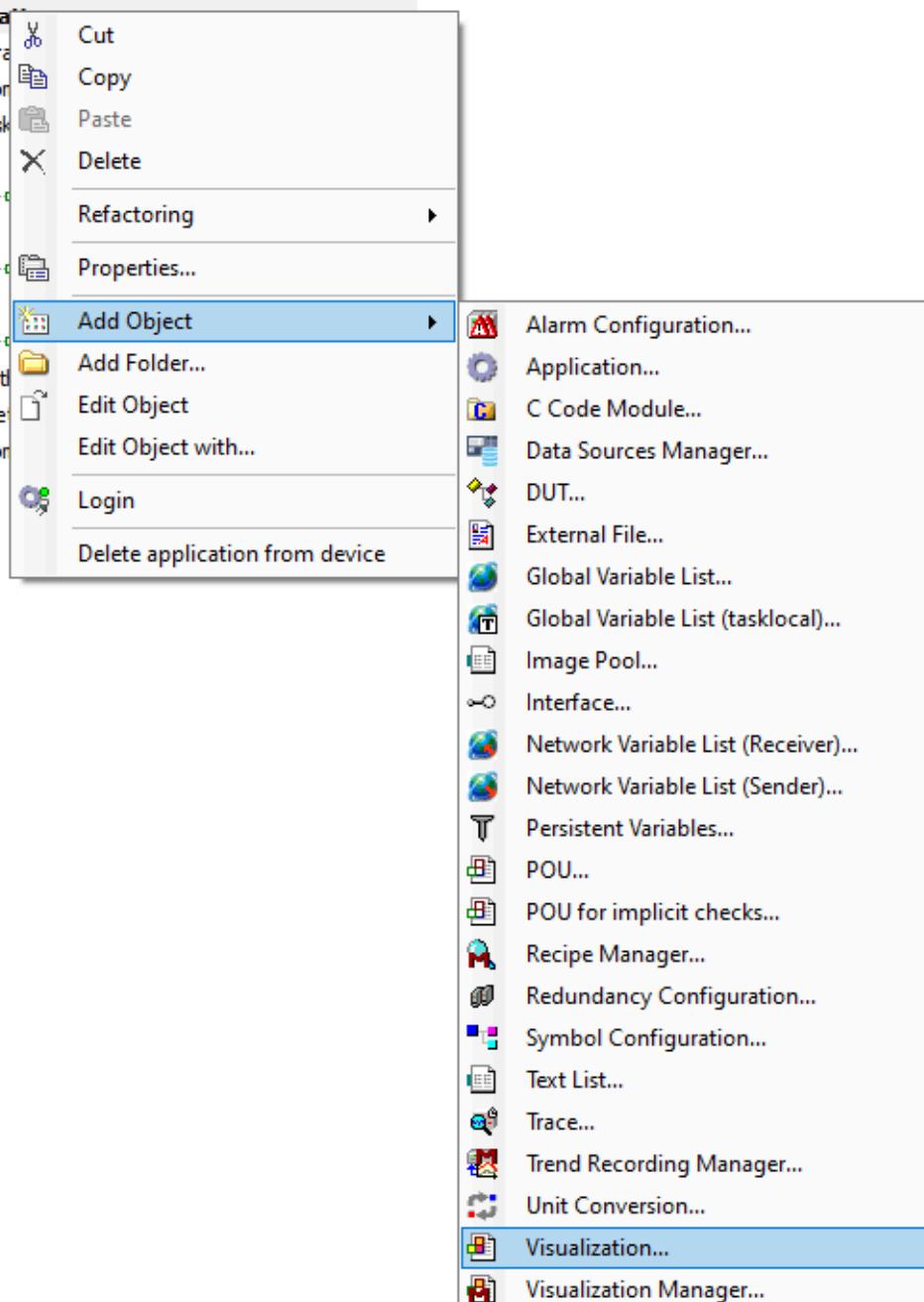
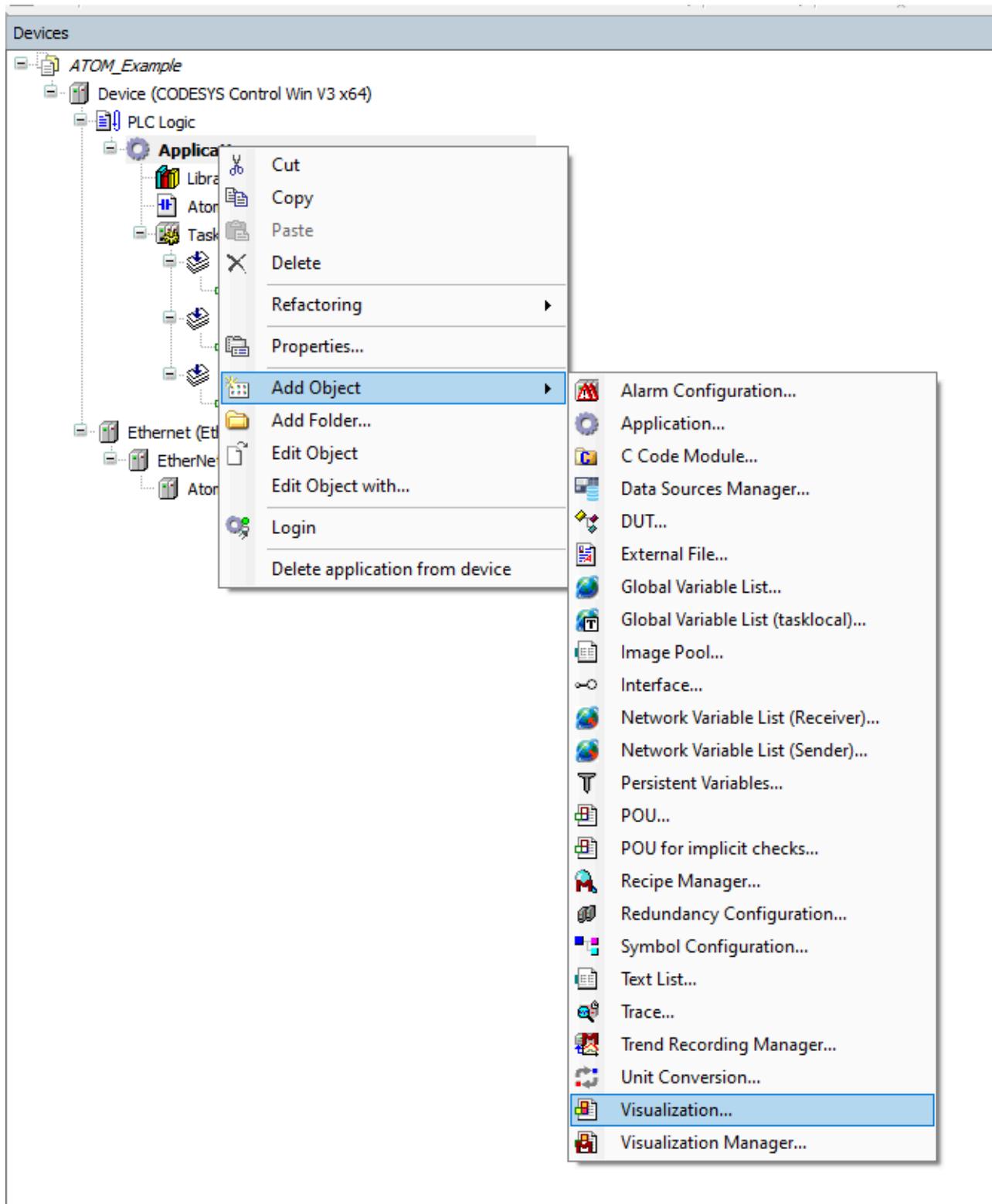
Next, double click **AtomTask (IEC-Tasks)** to open its configuration tab. Click **Add Call** and select **Application > AtomProgram**. After doing so, AtomTask's configuration should look like:



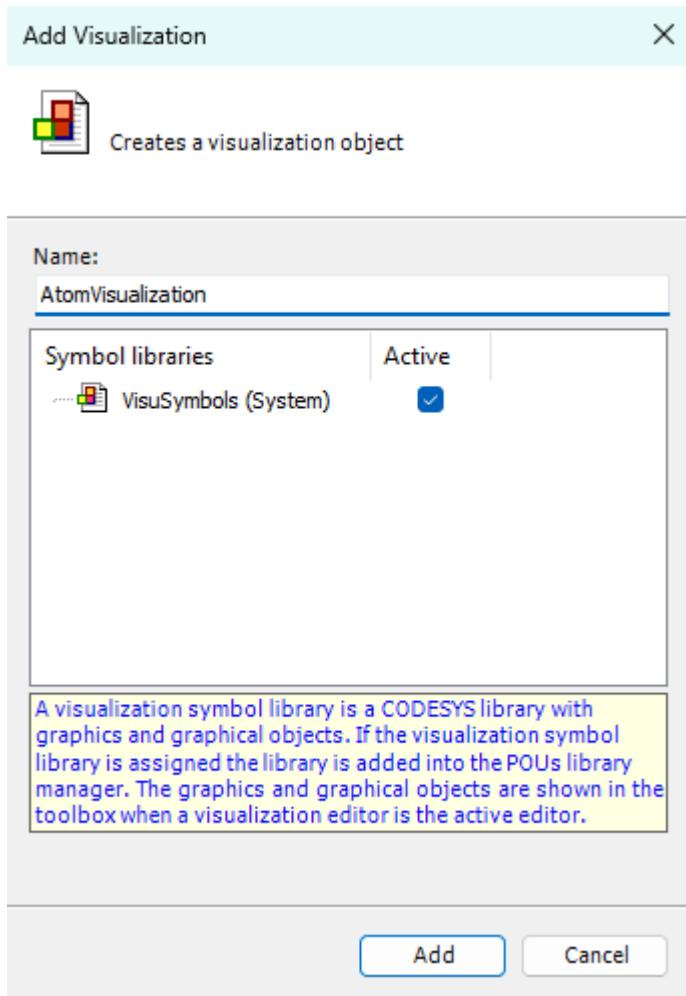
Setting up visualization

Next, we'll set up a simple visualization display to control and monitor ATOM.

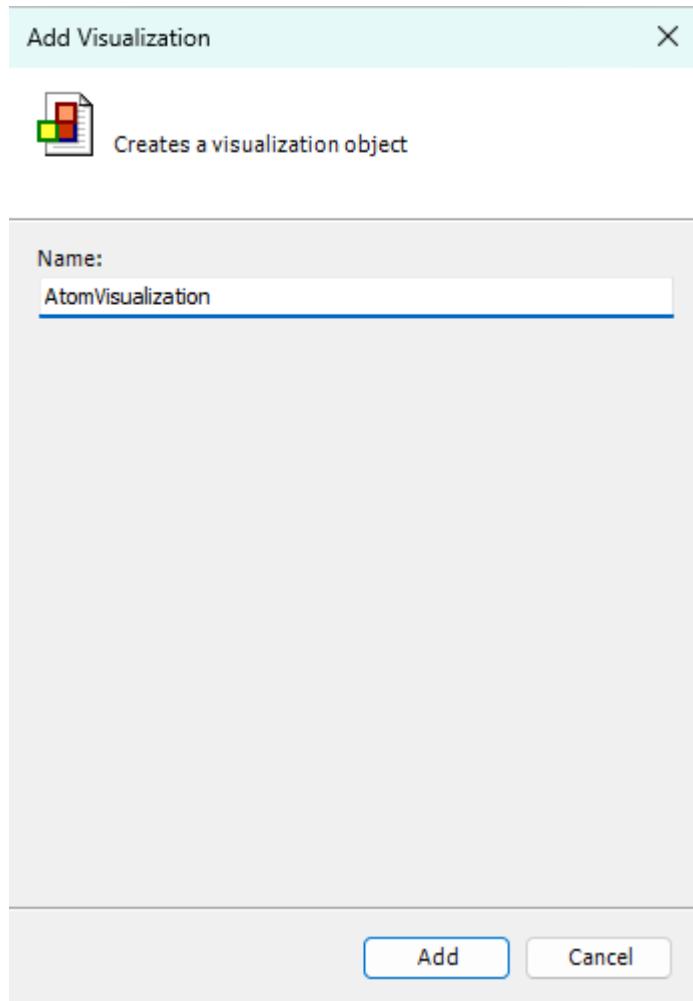
Right click **Application** and select **Add Object > Visualization**:



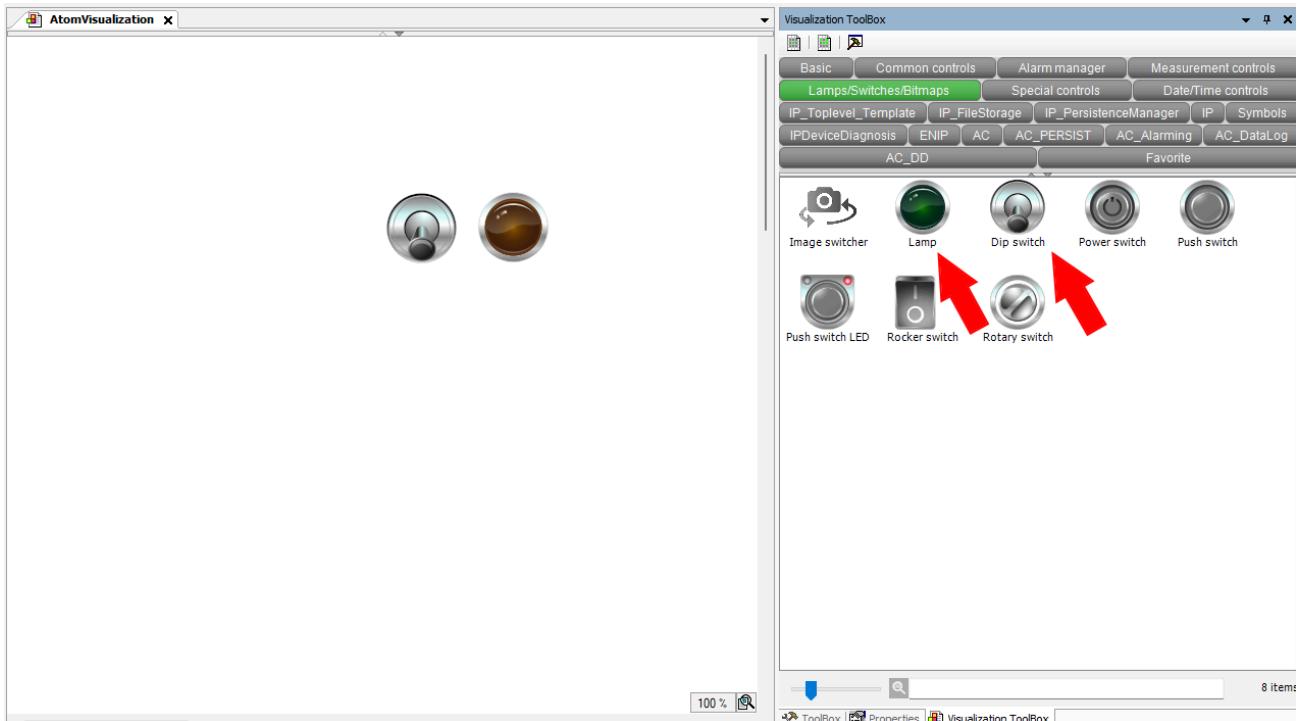
Make sure to check **Active** for **VisuSymbols (System)**, then click **Add**:



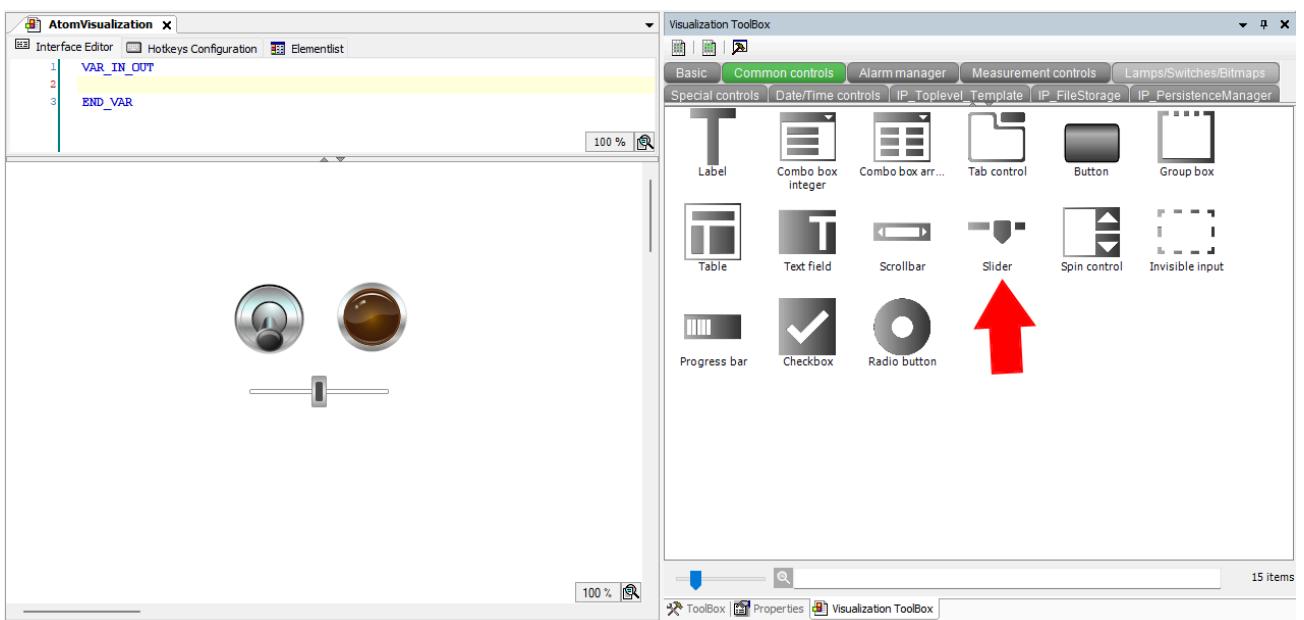
Name your visualization **AtomVisualization** and click **Add**:



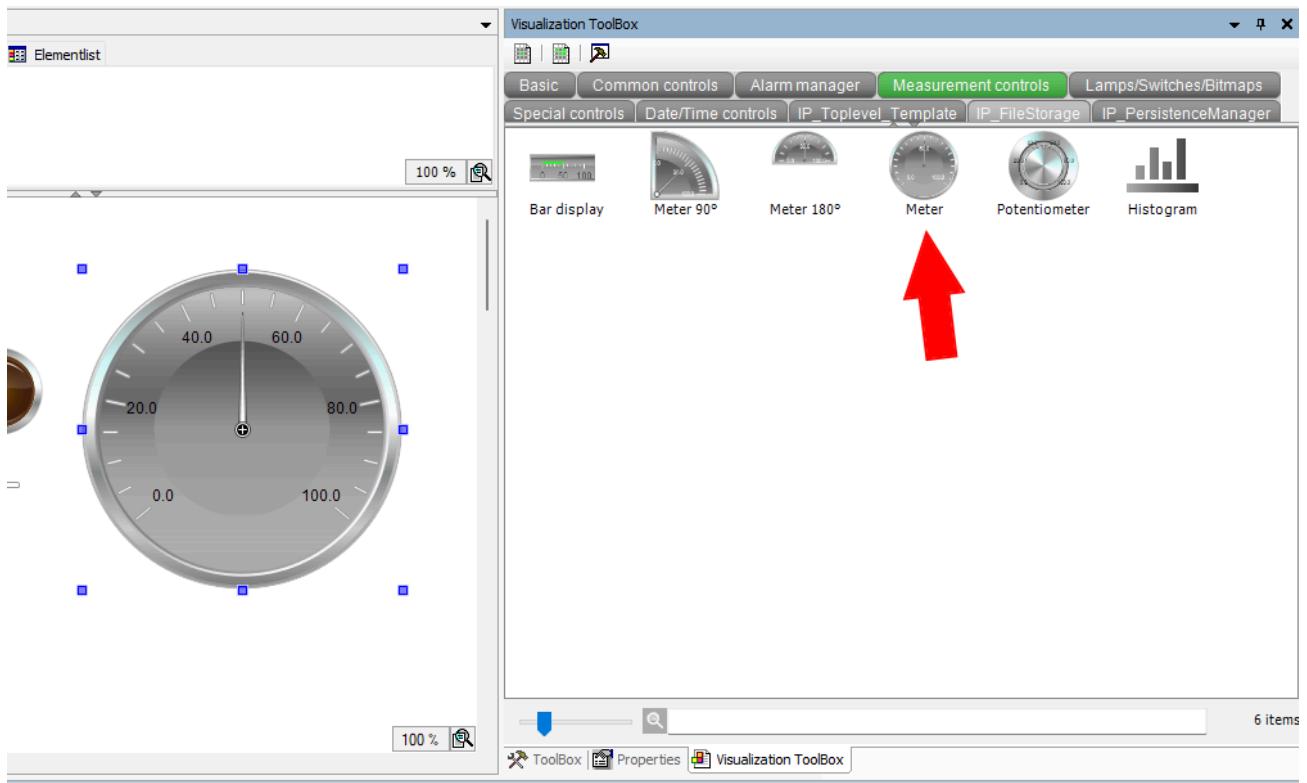
Double click **AtomVisualization** to open its configuration editor. From the **Visualization ToolBox** panel on the right, select the **Lamps/Switches/Bitmaps** category and add a lamp and a dip switch:



Next, in the **Common controls** category, add a slider:

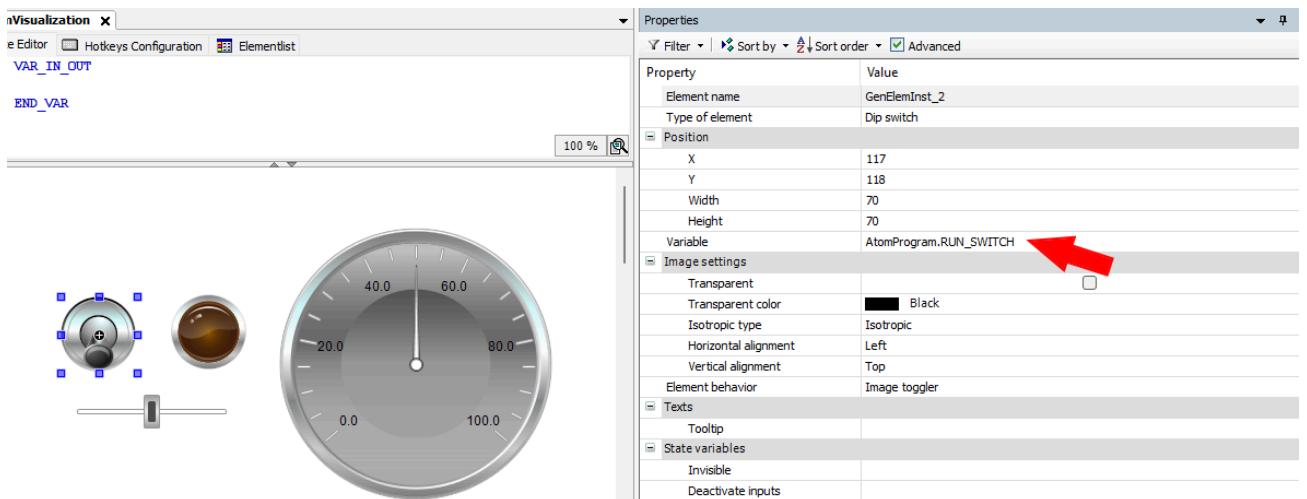


Finally, in the **Measurement controls** category, add a meter:

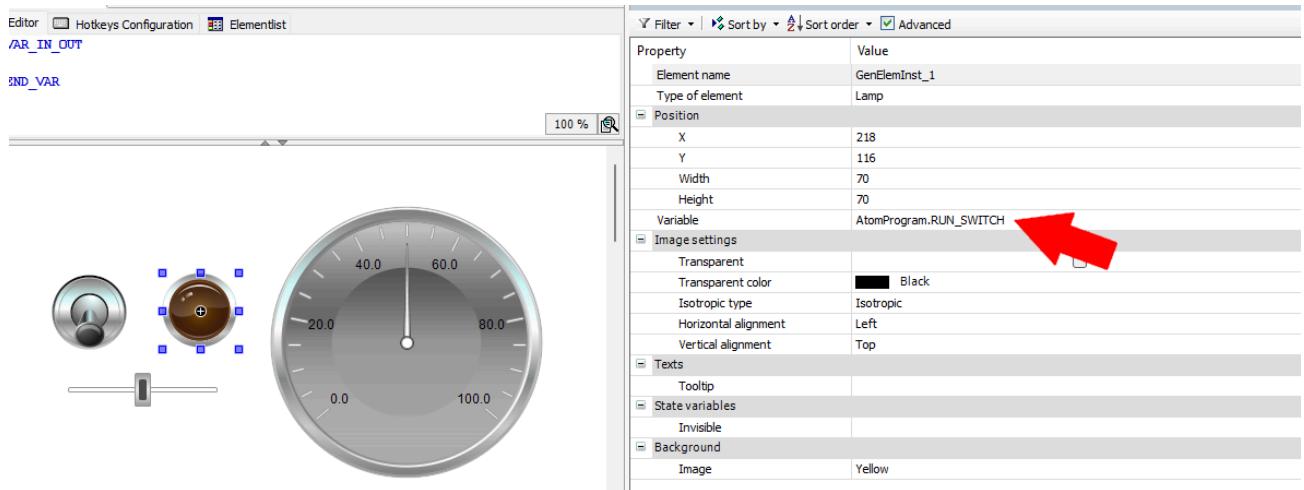


Wiring up the controls

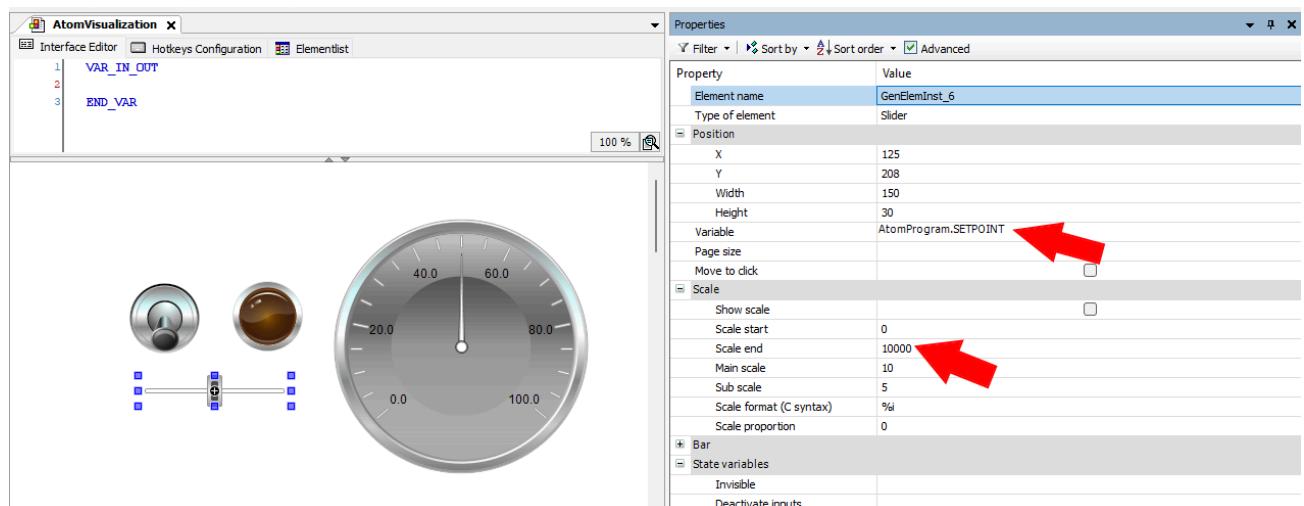
Next, we'll connect the controls to our PLC program. Select the dip switch and set the **Variable** field to `AtomProgram.RUN_SWITCH` as indicated by the red arrow:



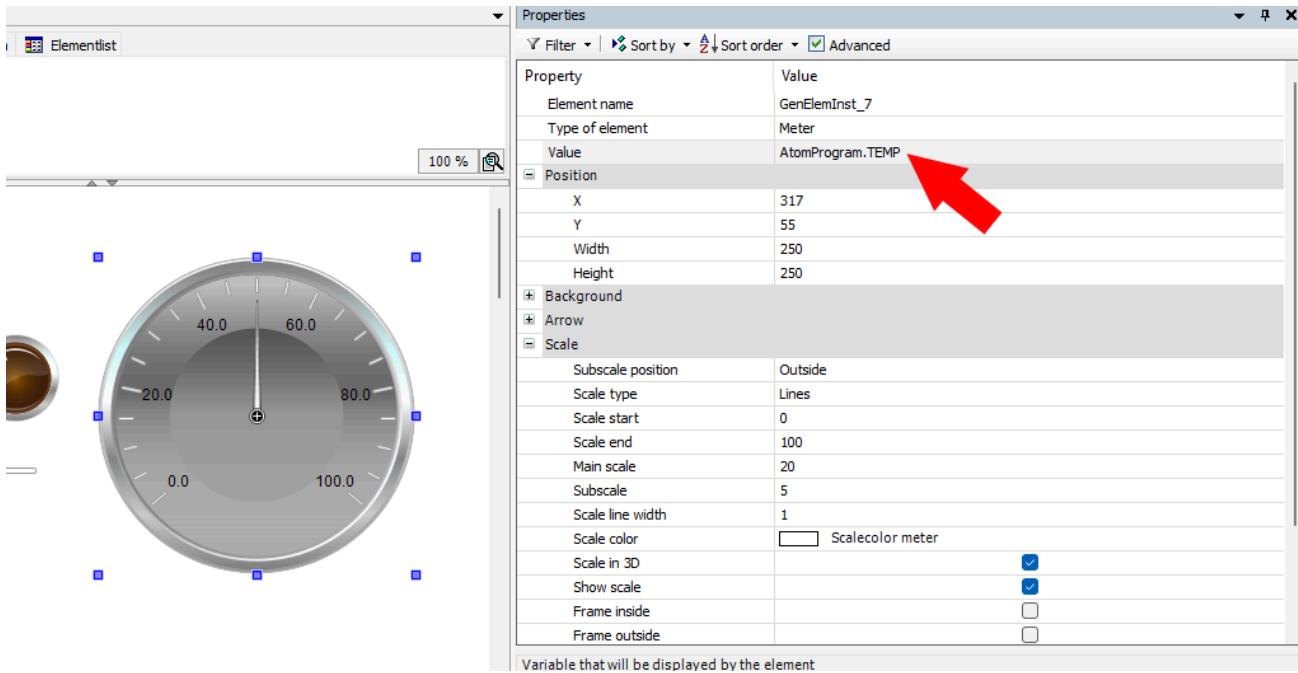
Select the lamp and set the **Variable** field to `AtomProgram.RUN_SWITCH` as indicated by the red arrow:



Select the slider and set the **Variable** field to `AtomProgram.SETPOINT` and set **Scale end** to `10000`:

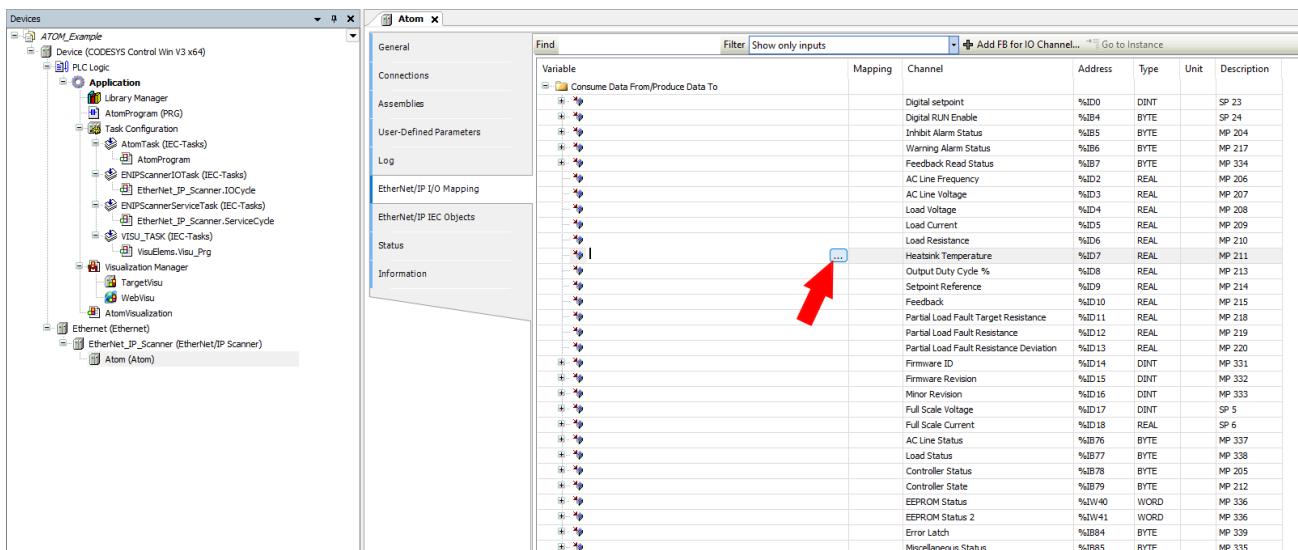


Select the meter and set the **Variable** field to `AtomProgram.TEMP`:

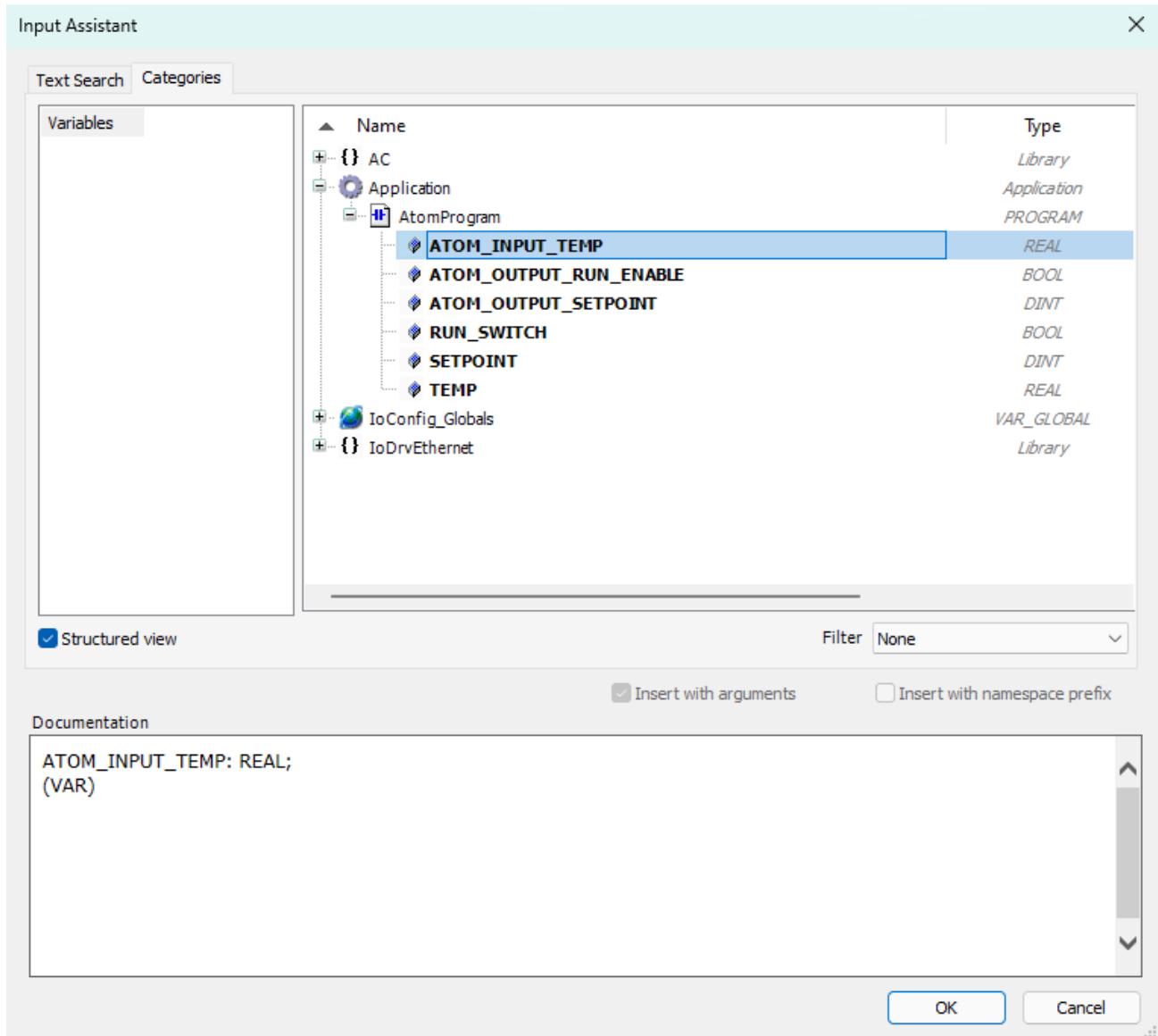


Mapping variables

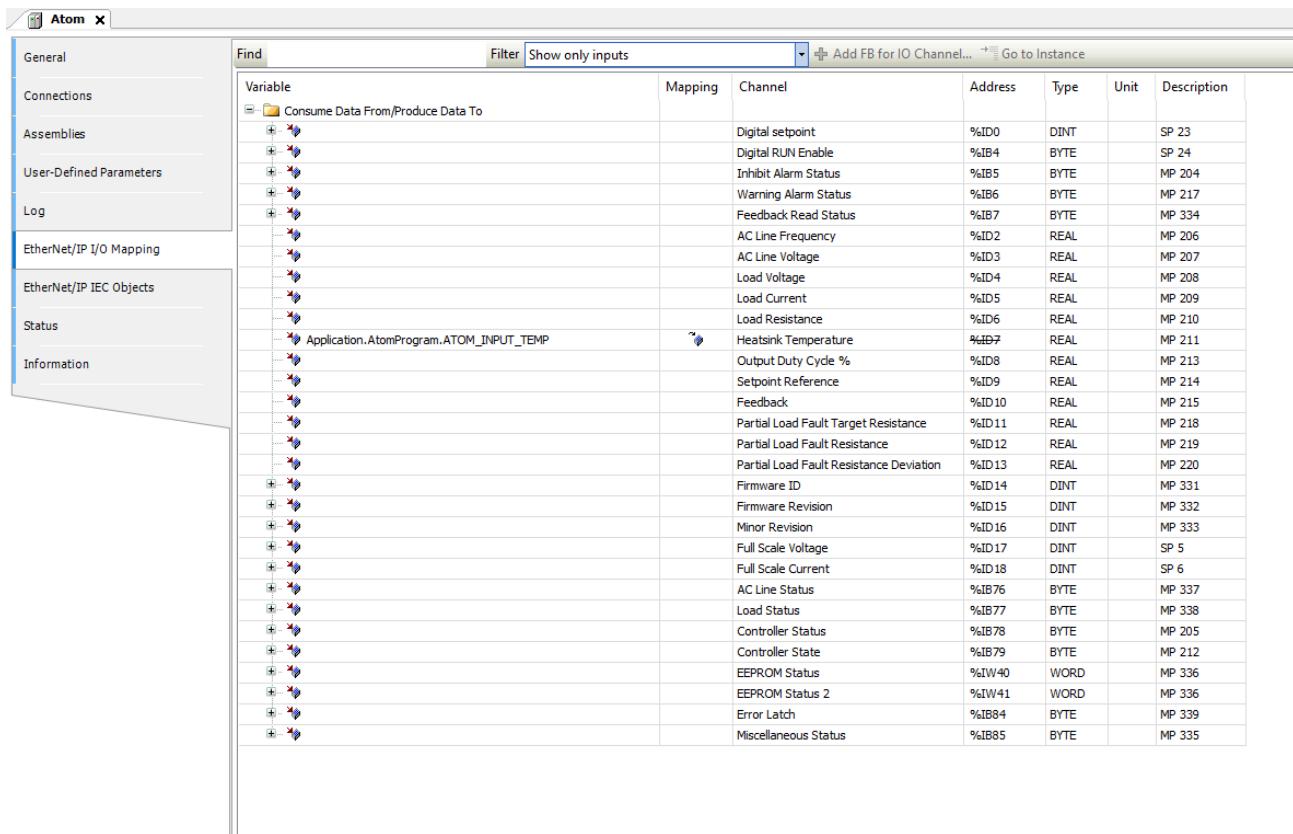
Finally, we'll map our PLC variables to ATOM. Double click **Atom** in the device tree to open its configuration window. Select the **EtherNet/IP I/O Mapping** tab and set **Filter** to **Show only inputs**:



Above, select the button indicated by the red arrow. This will open the **Input Assistant** dialog. Select **Application > AtomProgram > ATOM_INPUT_TEMP** and click **Add**:



After doing so, your input I/O mappings should look like:

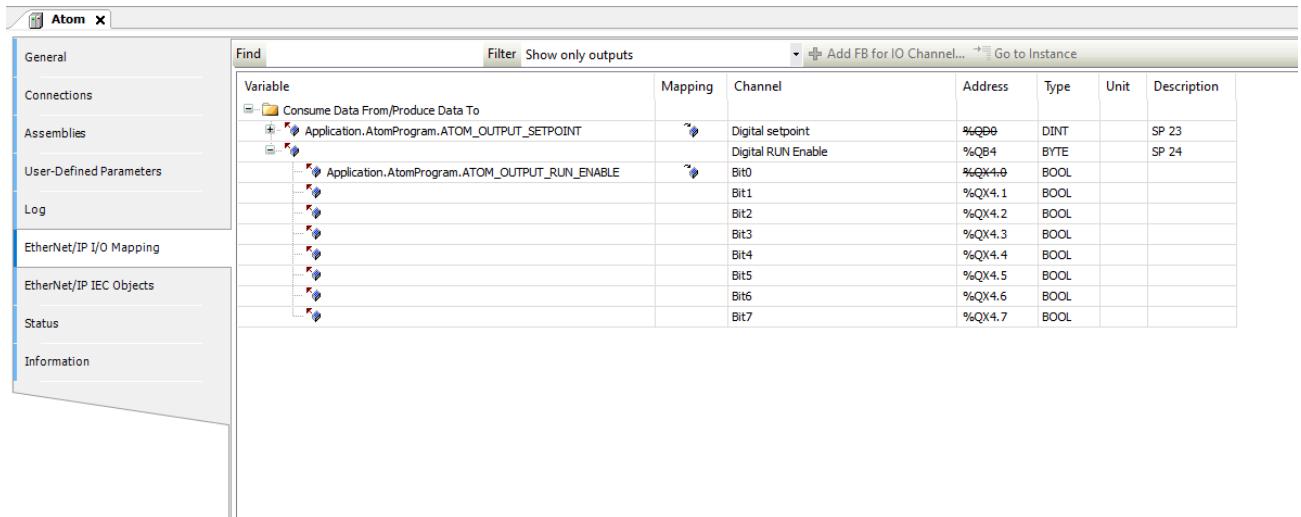


The screenshot shows the Atom software interface with the title bar "Atom X". On the left, there is a navigation pane with the following items: General, Connections, Assemblies, User-Defined Parameters, Log, EtherNet/IP I/O Mapping (which is selected), EtherNet/IP IEC Objects, Status, and Information. The main area is a table titled "Find" with columns: Variable, Mapping, Channel, Address, Type, Unit, and Description. The table lists various I/O points, many of which are grouped under a folder named "Consume Data From/Produce Data To". The table includes rows for Digital setpoint, Digital RUN Enable, Inhibit Alarm Status, Warning Alarm Status, Feedback Read Status, AC Line Frequency, AC Line Voltage, Load Voltage, Load Current, Load Resistance, Heatsink Temperature, Output Duty Cycle %, Setpoint Reference, Feedback, Partial Load Fault Target Resistance, Partial Load Fault Resistance, Partial Load Fault Resistance Deviation, Firmware ID, Firmware Revision, Minor Revision, Full Scale Voltage, Full Scale Current, AC Line Status, Load Status, Controller Status, Controller State, EEPROM Status, EEPROM Status 2, Error Latch, and Miscellaneous Status. The "Address" column contains addresses like %ID0, %IB4, %IB5, %IB6, %IB7, %ID2, %ID3, %ID4, %ID5, %ID6, %ID7, %ID8, %ID9, %ID10, %ID11, %ID12, %ID13, %ID14, %ID15, %ID16, %ID17, %ID18, %IB76, %IB77, %IB78, %IB79, %IW40, %IW41, %IB84, and %IB85. The "Type" column includes DINT, BYTE, MP, REAL, WORD, and SP types. The "Unit" column shows values like 23, 24, 204, 217, 334, 206, 207, 208, 209, 210, 211, 213, 214, 215, 218, 219, 220, 331, 332, 333, 5, 6, 337, 338, 205, 212, 336, 336, 339, and 335.

Change the **Filter** to **Show only outputs** and repeat the process for the outputs. Map **Digital setpoint** to `Application.AtomProgram.ATOM_OUTPUT_SETPOINT` and **Digital RUN Enable** to `Application.AtomProgram.ATOM_OUTPUT_RUN_ENABLE`.

⚠ TAKE CARE

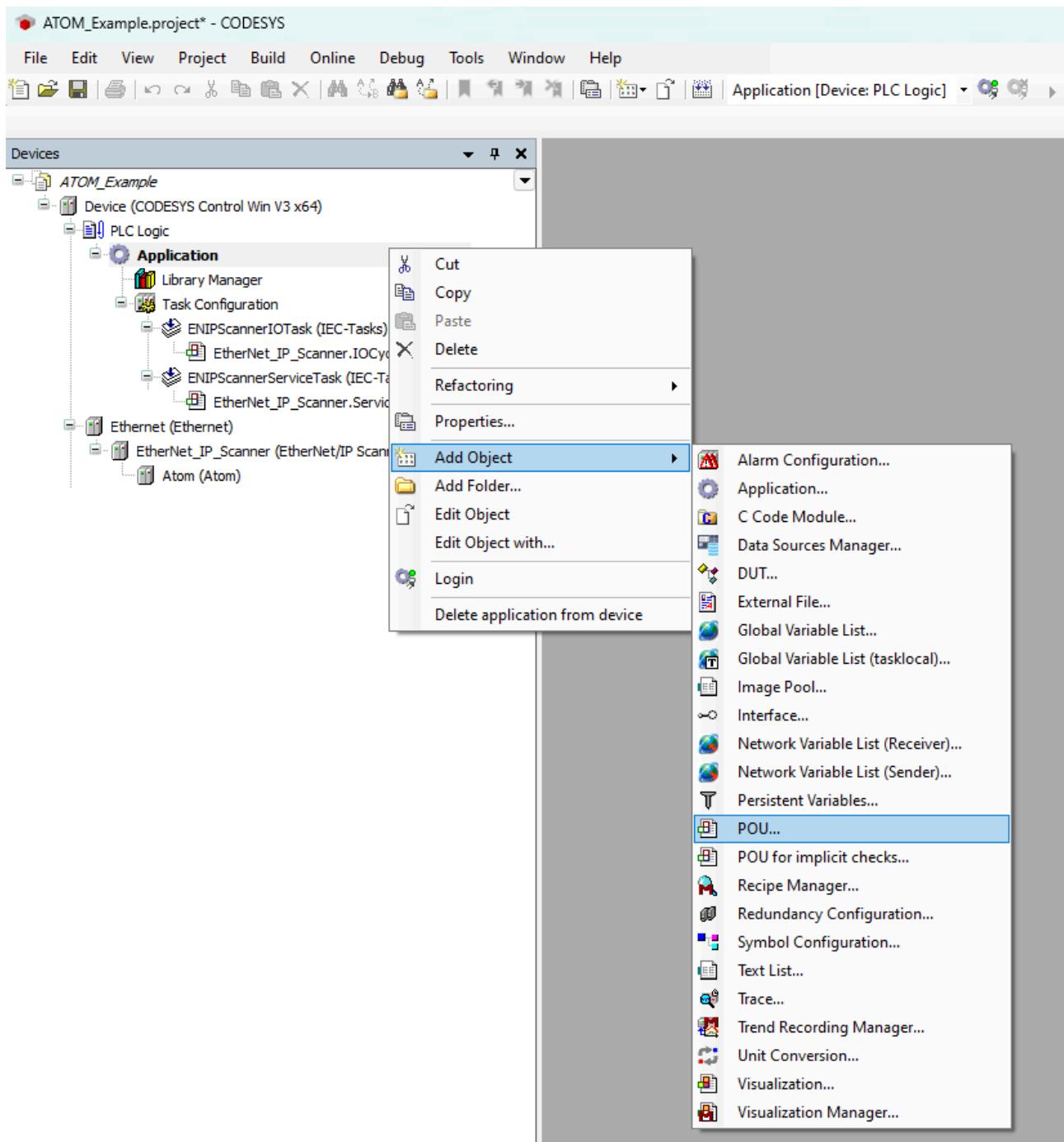
Make sure you map **Bit0** of **Digital RUN Enable** to **ATOM_OUTPUT_RUN_ENABLE**, NOT **Digital RUN Enable** itself.



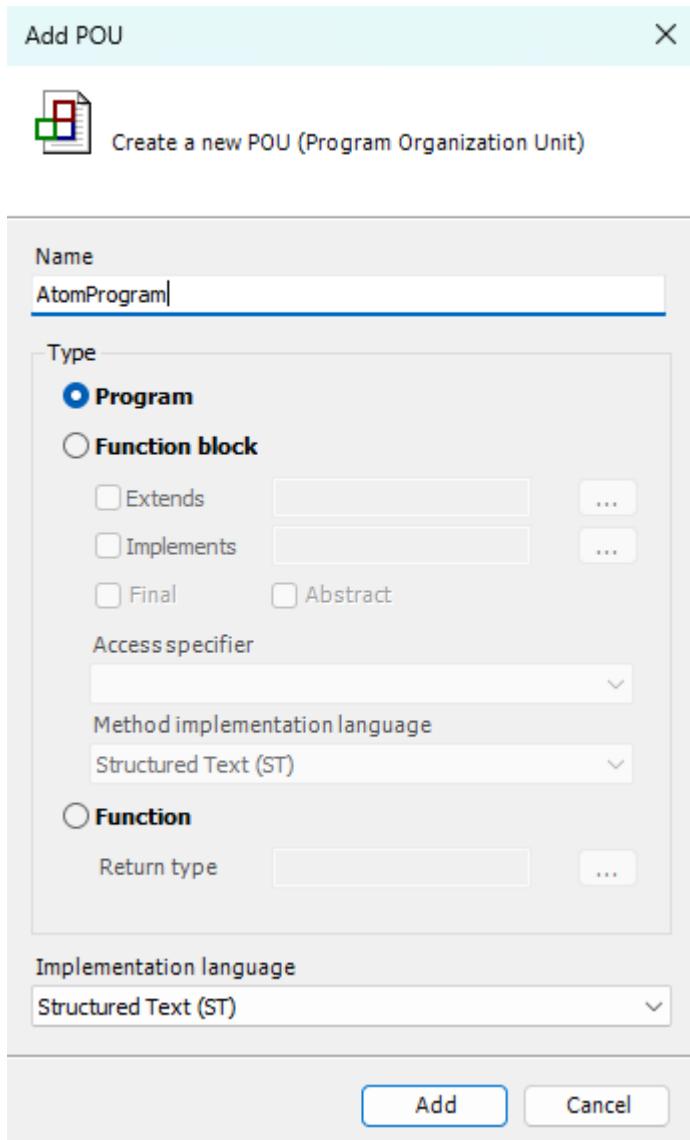
Example: Structured text

Creating the program

Right click **Application** and select **Add Object > POU**:



Name your **POU** AtomProgram and select **Structured Text (ST)** as the language:



Next, let's create a basic program. We'll check to make sure no alarms are active and then write a setpoint value of `8000` and set run enable to `true`.

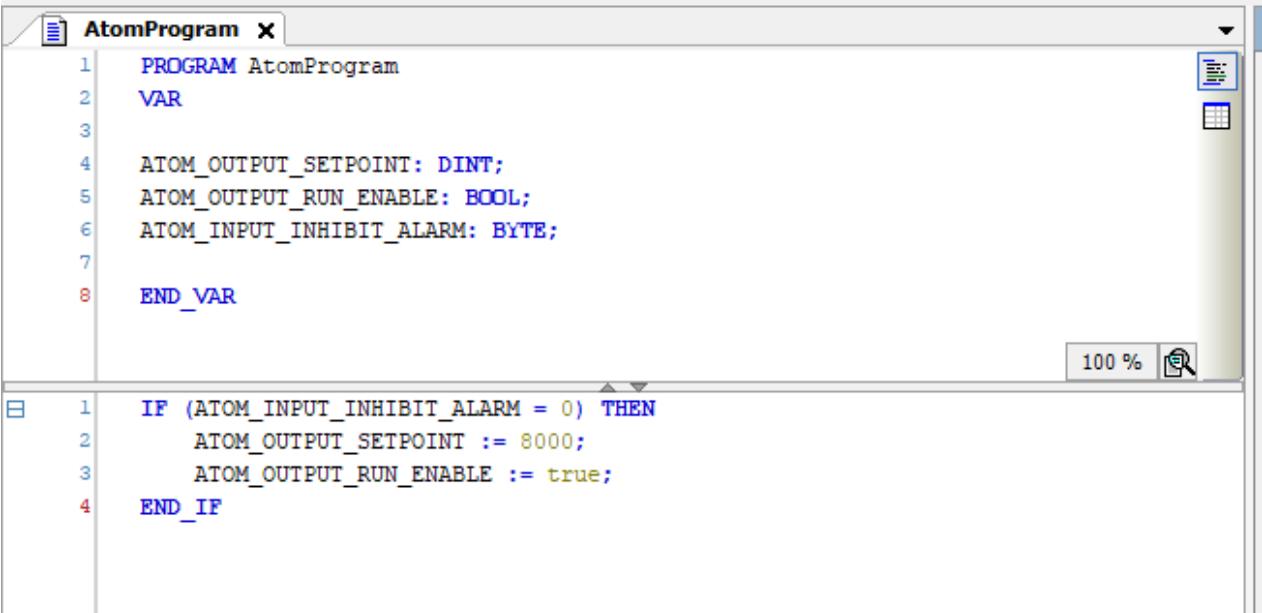
Copy the following code into the top panel of the **AtomProgram** editor:

```
PROGRAM AtomProgram
VAR
    ATOM_OUTPUT_SETPOINT: BOOL;
    ATOM_OUTPUT_RUN_ENABLE: BYTE;
    ATOM_INPUT_INHIBIT_ALARM: BYTE;
END_VAR
```

Copy the following code into the main program section:

```
IF (ATOM_INPUT_INHIBIT_ALARM = 0) THEN
    ATOM_OUTPUT_SETPOINT := 8000;
    ATOM_OUTPUT_RUN_ENABLE := true;
END_IF
```

Your editor should look like:



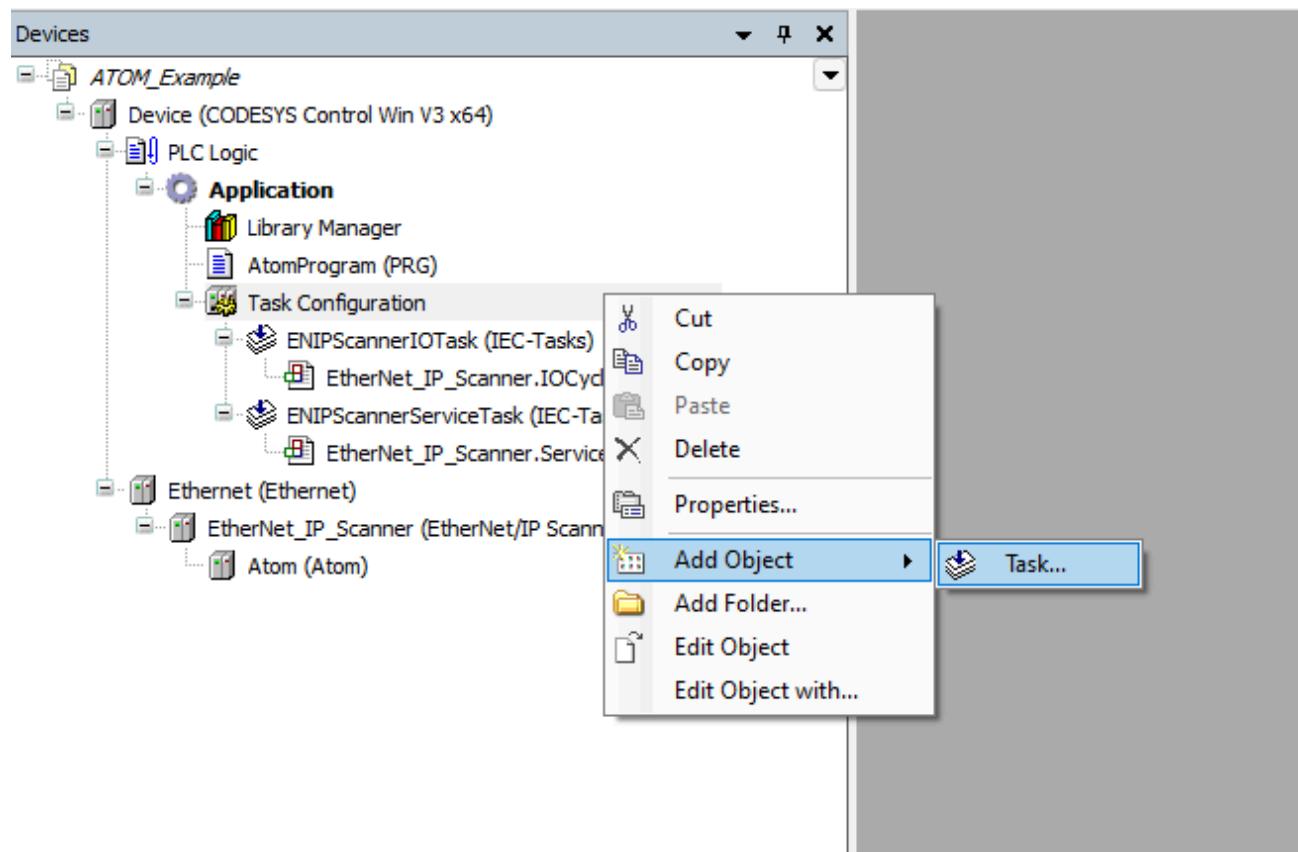
The screenshot shows a software interface for editing PLC programs. The title bar says "AtomProgram". The code area contains the following:

```
PROGRAM AtomProgram
VAR
    ATOM_OUTPUT_SETPOINT: DINT;
    ATOM_OUTPUT_RUN_ENABLE: BOOL;
    ATOM_INPUT_INHIBIT_ALARM: BYTE;
END_VAR

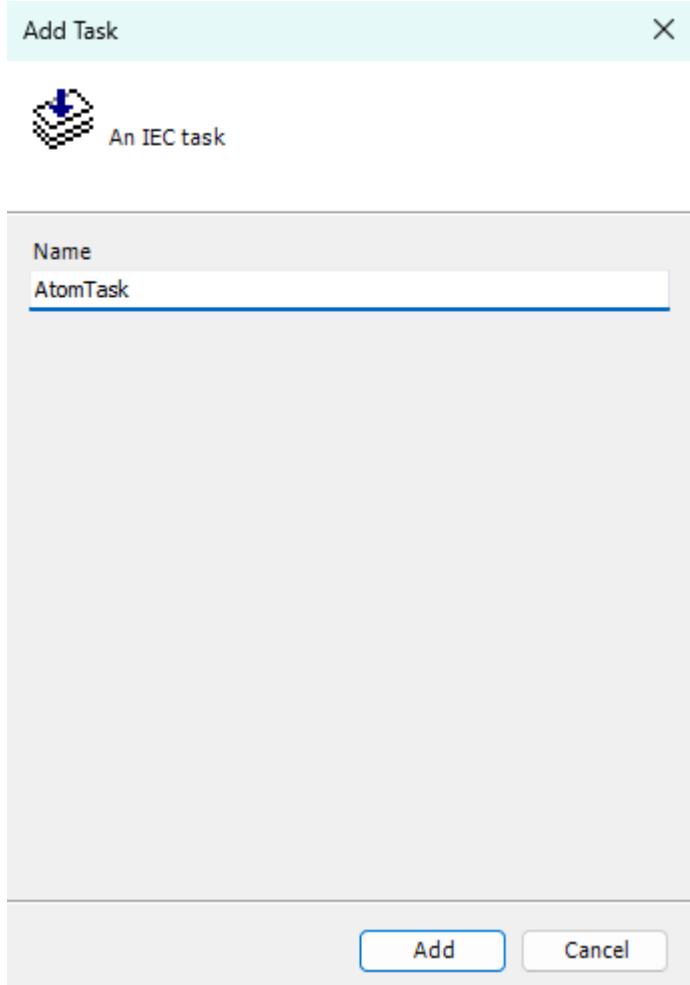
IF (ATOM_INPUT_INHIBIT_ALARM = 0) THEN
    ATOM_OUTPUT_SETPOINT := 8000;
    ATOM_OUTPUT_RUN_ENABLE := true;
END_IF
```

The code is color-coded: blue for keywords like PROGRAM, VAR, IF, THEN, END_VAR, END_IF, and assignments; black for variable names; and yellow for the condition in the IF statement. The editor has a toolbar on the right and a status bar at the bottom showing "100 %".

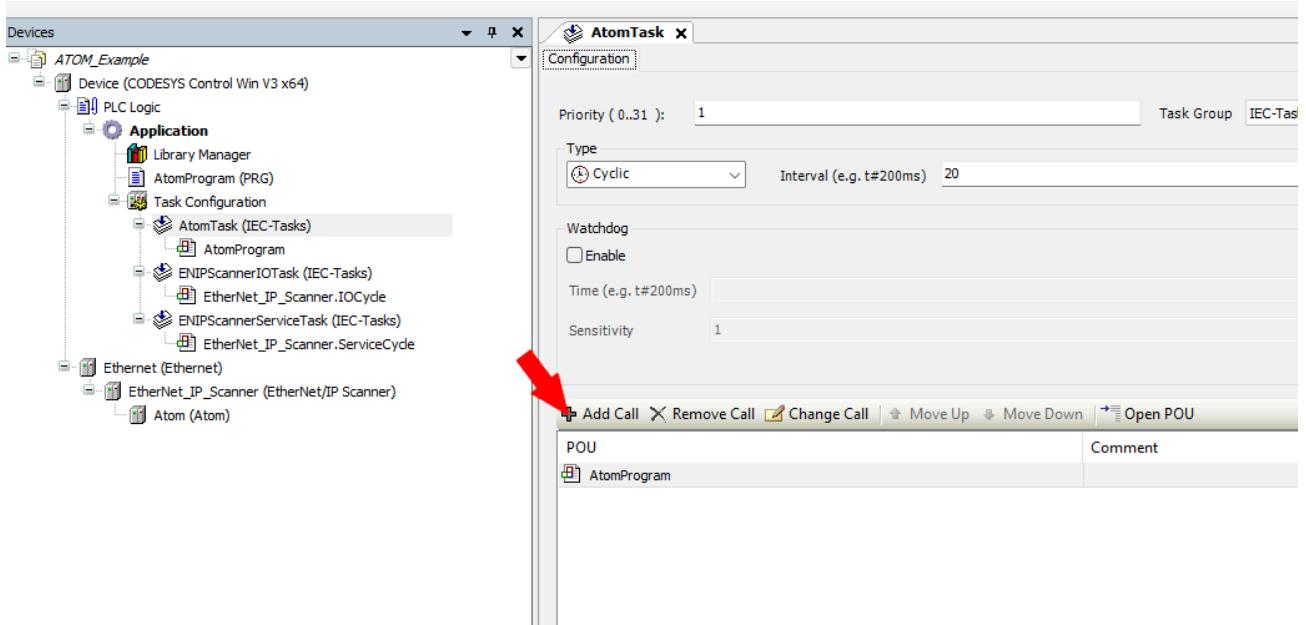
Next, we'll add a new task to call our program. Right click **Task Configuration** and Select **Add Object > Task:**



Name your task `AtomTask` and click **Add**:

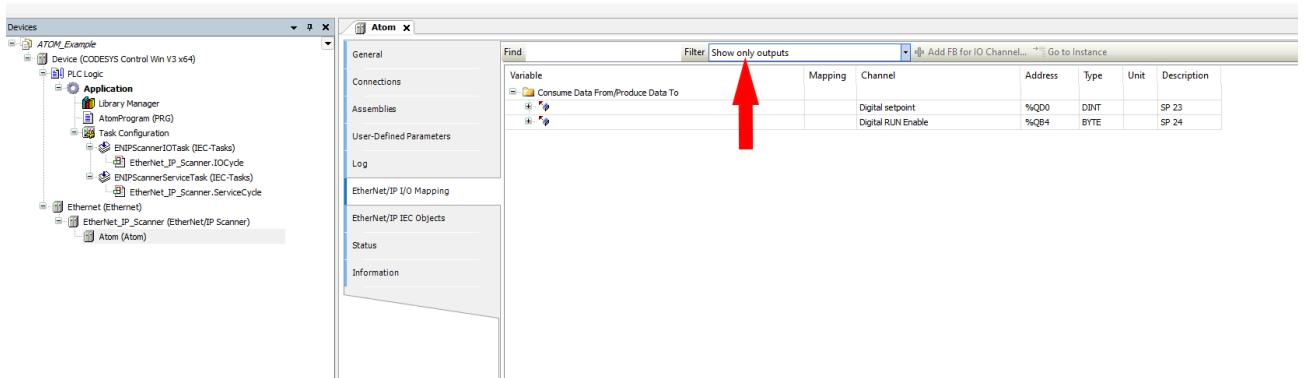


Next, double click **AtomTask (IEC-Tasks)** to open its configuration tab. Click **Add Call** and select **Application > AtomProgram**. After doing so, **AtomTask**'s configuration should look like:

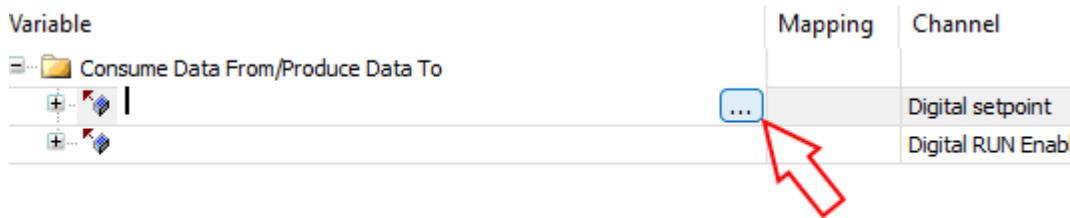


Mapping variables

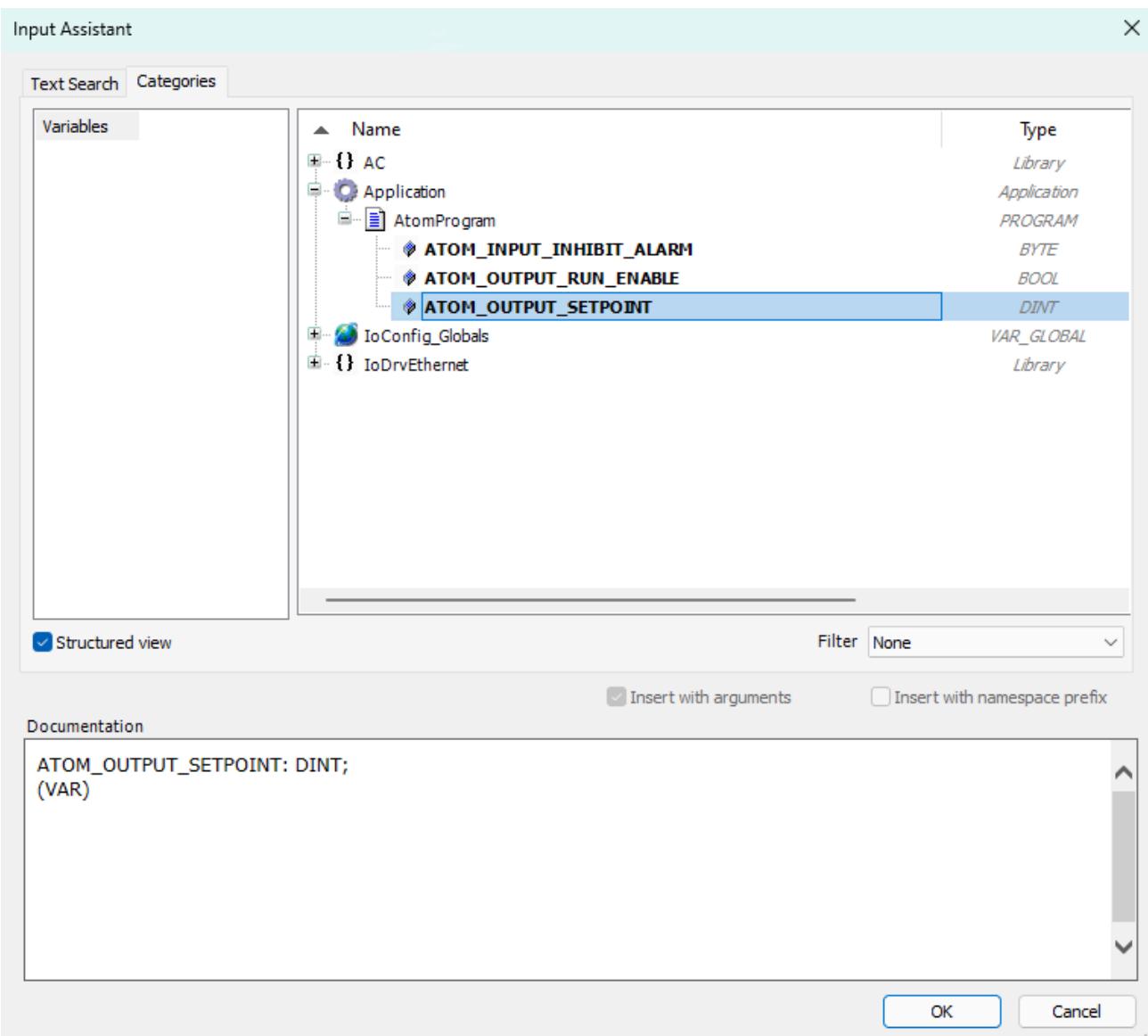
Next, we'll map our ATOM's I/O configuration to our program variables. Double click **Atom (Atom)** to open its configuration window, then select the **EtherNet/IP I/O Configuration** tab. On the **Filter** dropdown indicated by the red arrow, select **Show only outputs**:



Click the button indicated by the red arrow to map the **Digital setpoint** value:



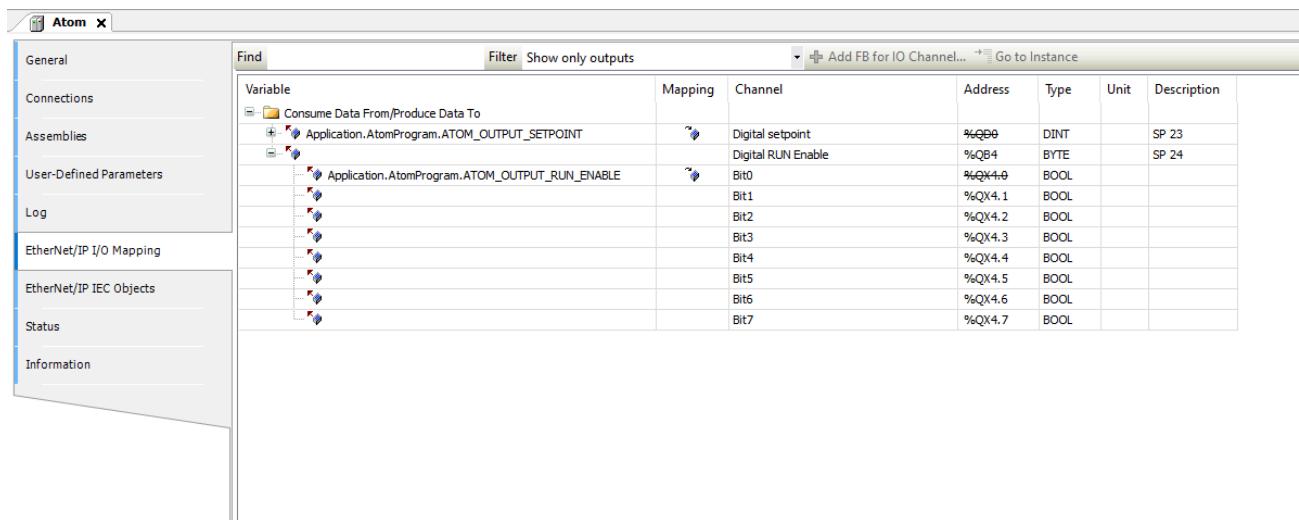
This button will open the **Input Assistant** dialog. Select the corresponding variable from your program and click **Ok**:



Repeat this process so that your output variables are mapped like so:

⚠ TAKE CARE

Make sure you map **Bit0** of **Digital RUN Enable** to **ATOM_OUTPUT_RUN_ENABLE**,
NOT **Digital RUN Enable** itself.



The screenshot shows the Atom software interface with the 'Atom' window open. On the left, there's a sidebar with tabs: General, Connections, Assemblies, User-Defined Parameters, Log, EtherNet/IP I/O Mapping (which is selected), EtherNet/IP IEC Objects, Status, and Information. The main area is a table titled 'Find' with columns: Variable, Mapping, Channel, Address, Type, Unit, and Description. The table lists variables under 'Consume Data From/Produce Data To' for 'Application.AtomProgram.ATOM_OUTPUT_SETPOINT' and 'Application.AtomProgram.ATOM_OUTPUT_RUN_ENABLE'. The 'ATOM_OUTPUT_RUN_ENABLE' row has 'Digital RUN Enable' mapped to 'Bit0' on channel '%QX4.0'. Other bits from Bit1 to Bit7 are listed but have no mappings assigned.

| Variable | Mapping | Channel | Address | Type | Unit | Description |
|--|---------|--------------------|---------|------|------|-------------|
| Consume Data From/Produce Data To | | | | | | |
| + Application.AtomProgram.ATOM_OUTPUT_SETPOINT | | Digital setpoint | %Q00 | DINT | | SP 23 |
| + Application.AtomProgram.ATOM_OUTPUT_RUN_ENABLE | | Digital RUN Enable | %QB4 | BYTE | | SP 24 |
| | Bit0 | %QX4.0 | BOOL | | | |
| | Bit1 | %QX4.1 | BOOL | | | |
| | Bit2 | %QX4.2 | BOOL | | | |
| | Bit3 | %QX4.3 | BOOL | | | |
| | Bit4 | %QX4.4 | BOOL | | | |
| | Bit5 | %QX4.5 | BOOL | | | |
| | Bit6 | %QX4.6 | BOOL | | | |
| | Bit7 | %QX4.7 | BOOL | | | |

Switch the filter to **Show only inputs** and then map the **Inhibit alarm status** variable:

| Variable | Mapping | Channel | Address | Type | Unit | Description |
|--|---------|---|---------|------|------|-------------|
| Consume Data From/Produce Data To | | Digital setpoint | %ID0 | DINT | | SP 23 |
| | | Digital RUN Enable | %IB4 | BYTE | | SP 24 |
| Application.AtomProgram.ATOM_INPUT_INHIBIT_ALARM | | Inhibit Alarm Status | %IB5 | BYTE | | MP 204 |
| | | Warning Alarm Status | %IB6 | BYTE | | MP 217 |
| | | Feedback Read Status | %IB7 | BYTE | | MP 334 |
| | | AC Line Frequency | %ID2 | REAL | | MP 206 |
| | | AC Line Voltage | %ID3 | REAL | | MP 207 |
| | | Load Voltage | %ID4 | REAL | | MP 208 |
| | | Load Current | %ID5 | REAL | | MP 209 |
| | | Load Resistance | %ID6 | REAL | | MP 210 |
| | | Heatsink Temperature | %ID7 | REAL | | MP 211 |
| | | Output Duty Cycle % | %ID8 | REAL | | MP 213 |
| | | Setpoint Reference | %ID9 | REAL | | MP 214 |
| | | Feedback | %ID10 | REAL | | MP 215 |
| | | Partial Load Fault Target Resistance | %ID11 | REAL | | MP 218 |
| | | Partial Load Fault Resistance | %ID12 | REAL | | MP 219 |
| | | Partial Load Fault Resistance Deviation | %ID13 | REAL | | MP 220 |
| | | Firmware ID | %ID14 | DINT | | MP 331 |
| | | Firmware Revision | %ID15 | DINT | | MP 332 |
| | | Minor Revision | %ID16 | DINT | | MP 333 |
| | | Full Scale Voltage | %ID17 | DINT | | SP 5 |
| | | Full Scale Current | %ID18 | REAL | | SP 6 |
| | | AC Line Status | %IB76 | BYTE | | MP 337 |
| | | Load Status | %IB77 | BYTE | | MP 338 |
| | | Controller Status | %IB78 | BYTE | | MP 205 |
| | | Controller State | %IB79 | BYTE | | MP 212 |
| | | EEPROM Status | %IW40 | WORD | | MP 336 |
| | | EEPROM Status 2 | %IW41 | WORD | | MP 336 |
| | | Error Latch | %IB84 | BYTE | | MP 339 |
| | | Miscellaneous Status | %IB85 | BYTE | | MP 335 |

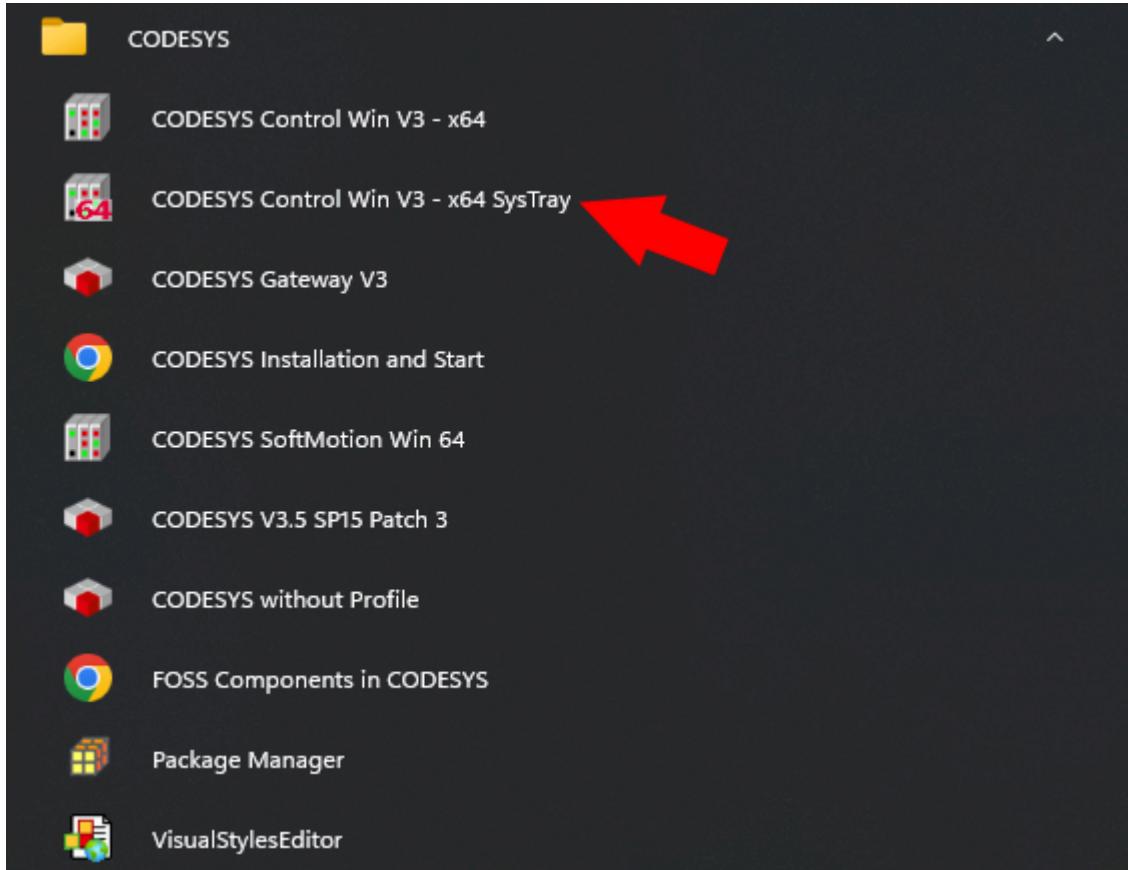
Running the program with SoftPLC

INFO

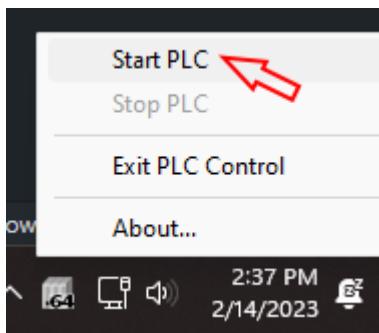
The instructions to run your program are the same regardless of whether you are using ladder logic or structured text.

The only difference is that in the ladder logic example, a visualization window will open that allows you to control ATOM.

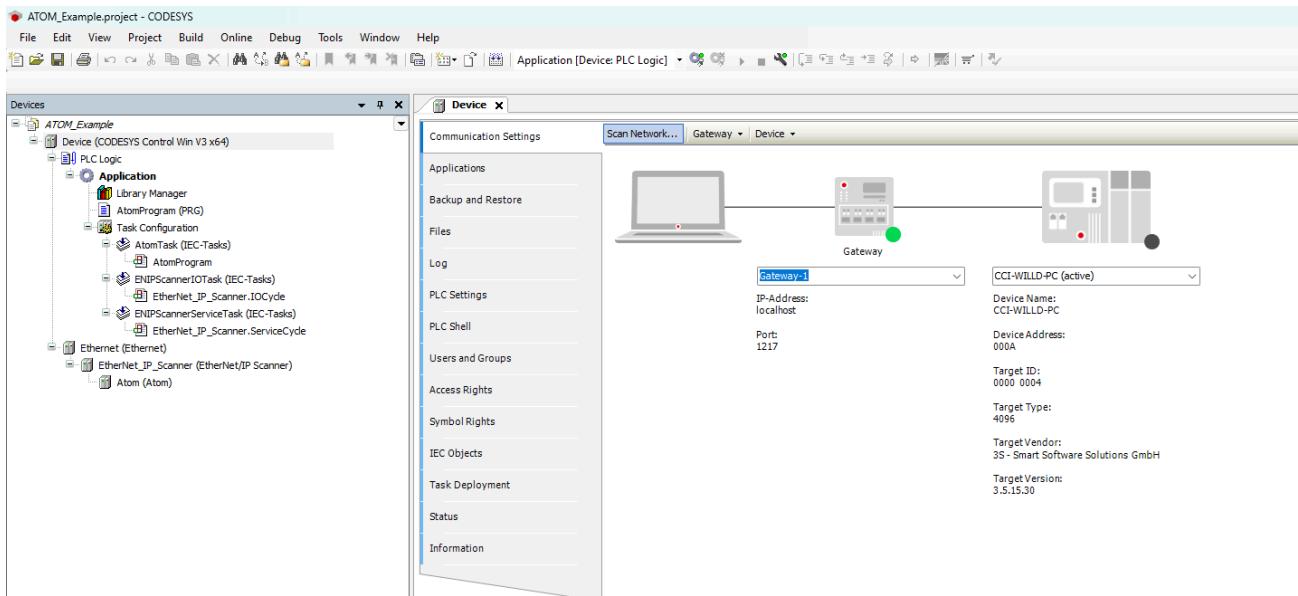
To debug the program, first make sure you start **Codesys WIN Control V3 - x64 SysTray**



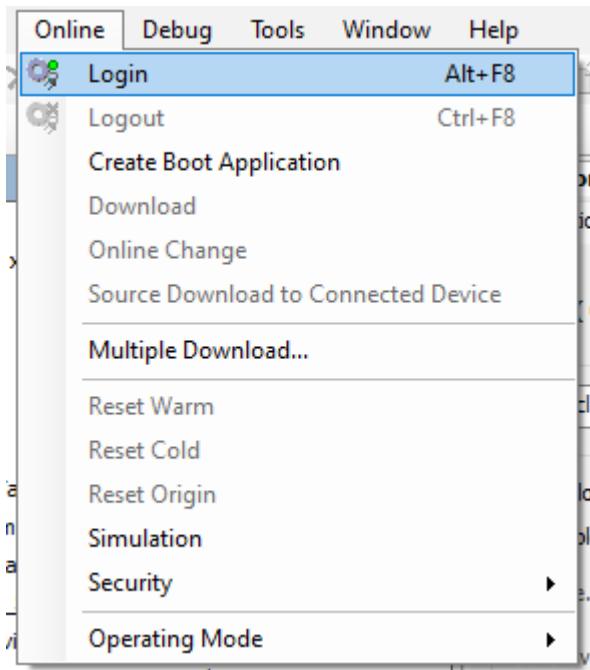
This will launch the Codesys SoftPLC. You should see an icon appear in your systray and you can right click it and select **Start PLC** to start the SoftPLC:



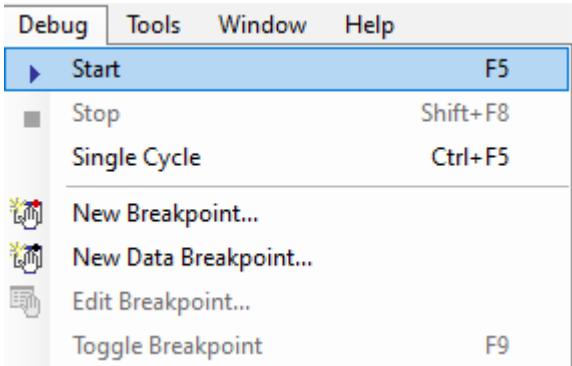
Next, in Codesys double click **Application** to open its configuration window. Here you can select **Scan Network** to discover your SoftPLC:



Finally, **Login** to your SoftPLC:



Then you can start debugging the program:



If you use Control Panel to monitor ATOM, you should see the **Stop / Run** state and the **Digital Setpoint** values change to reflect the PLC program's instructions. If you followed the structured text example, the values will change once and remain fixed. If you followed the ladder logic example, a visualization control panel will appear. Flipping the dip switch or adjusting the slider will immediately update ATOM and the changes should reflect in real-time:

