

## **CONTROL AUTOMATICO**

## **Compensador de error**

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$$kp = \lim_{s \to 0} s \frac{1}{s} G(s)$$

$$\lim_{s \to 0} s \frac{1}{s} \frac{1}{s} = \frac{1}{24}$$

$$E = \frac{1}{1+kp} = \frac{1}{1+\frac{1}{24}} = 0,96$$

E nuevo = 1,152

$$\frac{1}{1+x} = 1,2$$

$$x = -0,1$$

$$\frac{Z1}{24P1} = -0,1$$

$$Z1 = -3,2 P1$$

$$-0,131 = 1$$

