

CONTROL AUTOMATICO

Compensador de error

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$$k_p = \lim_{s \rightarrow 0} G(s)$$

$$\lim_{s \rightarrow 0} \frac{1}{(s+2)(s+3)} = \frac{1}{6}$$

$$E = \frac{1}{1+k_p} = \frac{1}{1+\frac{1}{6}} = \frac{6}{7}$$

$$E = \frac{6}{7}$$

$$E_{10\%} = E \cdot 0.9 = \frac{6}{7} \cdot 0.9 = 0.771429$$

$$\frac{1}{1+k_{10\%}} = 0.771429$$

$$k_{10\%} = 0.296296$$

$$k_{10\%} = \frac{Z}{P} \cdot k_p$$

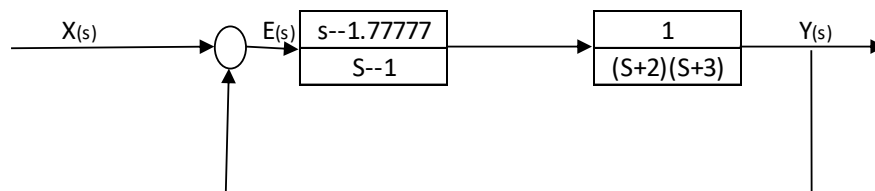
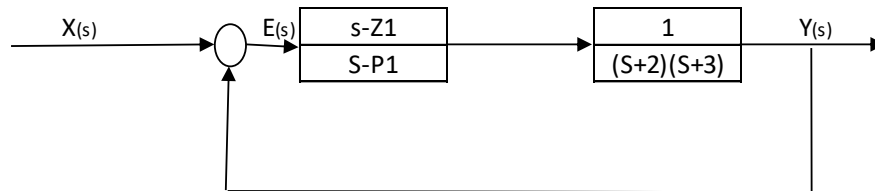
$$P = 1$$

$$0.296296 = \frac{Z}{-1} \cdot \frac{1}{6} = -1.77777$$

$$P = -1 \quad Z = -1.77777$$

$$\lim_{s \rightarrow 0} \frac{s-Z_0}{s-P_0} \cdot \frac{1}{(s+2)(s+3)}$$

$$\lim_{s \rightarrow 0} \frac{s-1.77777}{s-1} \cdot \frac{1}{(s+2)(s+3)} = 0.296296$$



```
octave:1> num=[1 1.77777]
num =
```

```
1.0000 1.7778
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octave:2> den=[1 6 11 6]
den =
```

```
1 6 11 6
```

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octave:3> G0=tf(num,den)
```

Transfer function 'G0' from input 'u1' to output ...

```

          s + 1.778
y1:  -----
      s^3 + 6 s^2 + 11 s + 6
```

Transfer function 'G1' from input 'u1' to output ...

$$y1: \frac{s + 1.778}{s^3 + 6s^2 + 12s + 7.778}$$

