



4.2 Lecture Summary

4 Dataflow Synchronization and Pipelining

4.2 Point-to-Point Synchronization with Phasers

Lecture Summary: In this lecture, we looked at a parallel program example in which the span (critical path length) would be 6 units of time if we used a barrier, but is reduced to 5 units of time if we use individual phasers as shown in the following table:

Task 0	Task 1	Task 2
1a : $X = A()$; $//cost = 1$	1b : $Y = B()$; $//cost = 2$	1c : $Z = C()$; $//cost = 3$
2a : $ph0.arrive()$;	2b : $ph1.arrive()$;	2c : $ph2.arrive()$;
3a : $ph1.awaitAdvance(0)$;	3b : $ph0.awaitAdvance(0)$;	3c : $ph1.awaitAdvance(0)$;
4a : $D(X, Y)$; $//cost = 3$	4b : $ph2.awaitAdvance(0)$;	4c : $F(Y, Z)$; $//cost = 1$
	5b : $E(X, Y, Z)$; $//cost = 2$	

Each column in the table represents execution of a separate task, and the calls to **arrive()** and **awaitAdvance(0)** represent synchronization across different tasks via phaser objects, **ph0**, **ph1**, and **ph2**, each of which is initialized with a party count of 1 (only one signalling task). (The parameter 0 in **awaitAdvance(0)** represents a transition from phase 0 to phase 1.)

Optional Reading:

1. Documentation on Java [Phaser](#) class.

Mark as completed