

Chapter 1 Notes - LA

John Yang

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1 Vectors

1.1 The Geometry and Algebra of Vectors

- A vector is a directed line segment that corresponds to a displacement from one point A to another point B.
- Column vectors and row vectors are different ways to express the same thing:

$$[3, 2] = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

- The point is that components of vectors are ordered.
- Two vectors are equal if they have the same magnitude and direction. Two vectors can still be equal if they have different initial and terminal points.
- Standard position of a vector - when the initial point is at the origin.
- Sum $\mathbf{u} + \mathbf{v} = [u_1 + v_1, u_2 + v_2]$
- Place vectors from head to tail.
- Scalar multiples: $c\mathbf{v} = [cv_1, cv_2]$ aka scaling a vector
- Subtraction is just adding the negative.
- Properties of vectors in \mathbb{R}^n : let \mathbf{u} , \mathbf{v} , and \mathbf{w} be vectors in \mathbb{R}^n and let c and d be scalars. Then:

- $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$
- $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$
- $\mathbf{u} + \mathbf{0} = \mathbf{u}$
- $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$
- $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$
- $(c + d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$

- $c(d\mathbf{u}) = (cd)\mathbf{u}$
- $1\mathbf{u} = \mathbf{u}$
- A vector \mathbf{v} is a linear combination of vectors $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k$ if there are scalars c_1, c_2, \dots, c_k such that $\mathbf{v} = c_1\mathbf{v}_1 + c_2\mathbf{v}_2 + \dots + c_k\mathbf{v}_k$. Those scalars are called the coefficients of the linear combination.
- Binary vectors - the components are either 0 or 1.
- Modulus function - divide by a given number and you're left with the remainder.

1.2 Length and Angle: the Dot Product

- dot product: If

$$\mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} \quad \text{and} \quad \mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

then the dot product of $\mathbf{u} \cdot \mathbf{v}$ of \mathbf{u} and \mathbf{v} is defined by

$$\mathbf{u} \cdot \mathbf{v} = u_1v_1 + u_2v_2 + \dots + u_nv_n$$

- properties of dot product: let \mathbf{u} , \mathbf{v} , and \mathbf{w} be vectors in \mathbb{R}^n and let c be a scalar. Then:

$$- \mathbf{u} \cdot \mathbf{v} = \mathbf{v} \cdot \mathbf{u}$$

$$- \mathbf{u} \cdot (\mathbf{v} + \mathbf{w}) = \mathbf{u} \cdot \mathbf{v} + \mathbf{u} \cdot \mathbf{w}$$

$$- (c\mathbf{u}) \cdot \mathbf{v} = c(\mathbf{u} \cdot \mathbf{v})$$

$$- \mathbf{u} \cdot \mathbf{u} \geq 0 \text{ and } \mathbf{u} \cdot \mathbf{u} = 0 \text{ IFF } \mathbf{u} = \mathbf{0}$$

$$- \text{Length or norm of a vector } \mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} \text{ in } \mathbb{R}^n \text{ is the nonnegative scalar } \|\mathbf{v}\| \text{ defined by}$$

$$\|\mathbf{v}\| = \sqrt{\mathbf{v} \cdot \mathbf{v}} = \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}$$

- Normalizing a vector means finding the unit vector.
- Cauchy-Schwarz Inequality: For all vectors \mathbf{u} and \mathbf{v} in \mathbb{R}^n ,

$$|\mathbf{u} \cdot \mathbf{v}| \leq \|\mathbf{u}\| \|\mathbf{v}\|$$

- Triangle inequality: for all vectors \mathbf{u} and \mathbf{v} and \mathbb{R}^n ,

$$\|\mathbf{u} + \mathbf{v}\| \leq \|\mathbf{u}\| + \|\mathbf{v}\|$$

- Distance between two vectors is defined by

$$d(\mathbf{u}, \mathbf{v}) = \|\mathbf{u} - \mathbf{v}\|$$

1.3 Lines and Planes

1.4 Applications