Chapter 1 Assignment - LA

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1 Vectors

1.1 Questions

- 1. What is a vector? What are its properties?
 - (a) A directed line segment that corresponds to a displacement from one point A to another point B
 - (b) That is, a quantity with both magnitude and direction
- 2. How many components can a vector have? In how many distinct ways can we write a vector in LA?
 - (a) It can have infinitely many components. Can be expressed in row form or column form.
- 3. When we change the coordinate frame, what about a vector changes, what about a vector remains the same (invariance)?
 - (a) The magnitude stays the same, the true direction stays the same, but the components change.
- 4. What are the algebraic properties of vectors? What is vector algebra? Give analytic and geometric methods of applying vector algebra operations to vectors.
 - (a) $\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$
 - (b) (u + v) + w = u + (v + w)
 - (c) u + 0 = u
 - (d) $\mathbf{u} + (-\mathbf{u}) = 0$
 - (e) $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$
 - (f) $(c+d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$
 - (g) $c(d\mathbf{u}) = (cd)\mathbf{u}$
 - (h) $1\mathbf{u} = \mathbf{u}$
 - (i) Vector algebra manipulating vectors to find new ones or solve equations. Take addition, subtraction and multiplication of components analytically, or draw them out geometrically.
- 5. What is a linear combination? What is a coordinate, a coordinate system?
 - (a) A vector \mathbf{v} is a linear combination of vectors $\mathbf{v}_1, \mathbf{v}_2, \cdots, \mathbf{v}_k$ if there are scalars c_1, c_2, \cdots, c_k such that $\mathbf{v} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \cdots + c_k \mathbf{v}_k$. Those scalars are called the coefficients of the linear combination.

- 6. What is the dot product of vectors? What are its properties?
 - (a) dot product: If

$$\mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} \quad \text{and} \quad \mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

then the dot product of $\mathbf{u} \cdot \mathbf{v}$ of \mathbf{u} and \mathbf{v} is defined by

$$\mathbf{u} \cdot \mathbf{v} = u_1 v_1 + u_2 v_2 + \dots + u_n v_n$$

- (b) $\mathbf{u} \cdot \mathbf{v} = \mathbf{v} \cdot \mathbf{u}$
- (c) $\mathbf{u} \cdot (\mathbf{v} + \mathbf{w}) = \mathbf{u} \cdot \mathbf{v} + \mathbf{u} \cdot \mathbf{w}$
- (d) $(c\mathbf{u})\cdot\mathbf{v} = c(\mathbf{u}\cdot\mathbf{v})$
- (e) $\mathbf{u} \cdot \mathbf{u} \geq \mathbf{0}$ and $\mathbf{u} \cdot \mathbf{u} = 0$ IFF $\mathbf{u} = \mathbf{0}$
- 7. What is the length (norm) of a vector? What are its properties? Does the norm of a vector depend on the coordinate system in use? That is, is it or is it not an invariant under coordinate transformations?
 - (a) Length or norm of a vector $\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$ in \mathbb{R}^n is the nonnegative scalar $||\mathbf{v}||$ defined by

$$||\mathbf{v}|| = \sqrt{\mathbf{v} \cdot \mathbf{v}} = \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}$$

- 8. What is the Cauchy-Schwartz inequality?
 - (a) For all vectors \mathbf{u} and \mathbf{v} in \mathbb{R}^n ,

$$|\mathbf{u} \cdot \mathbf{v}| \le ||\mathbf{u}||||\mathbf{v}||$$

- 9. What is the Triangle inequality?
 - (a) for all vectors **u** and **v** and \mathbb{R}^n ,

$$||\mathbf{u} + \mathbf{v}|| \le ||\mathbf{u}|| + ||\mathbf{v}||$$

- 10. What is the vector orthogonality?
 - (a) Two vectors are orthogonal if $\mathbf{u} \cdot \mathbf{v} = 0$
- 11. What is Pythagoras' Theorem in LA?
 - (a) For all vectors \mathbf{u} and \mathbf{v} in \mathbb{R}^n , $||\mathbf{u} + \mathbf{v}||^2 = ||\mathbf{u}||^2 + ||\mathbf{v}||^2$ IFF \mathbf{u} and \mathbf{v} are orthogonal.
- 12. What is a line? What vectors describe a given line? What are the unit tangent vector \vec{T} , the unit normal vector \vec{N} , the unit binormal vector \vec{B} to a line, and the curvature κ of the line?
 - (a) A line is a set of points in space. See paper worksheet.
- 13. Given a line ℓ what are its normal form, general form, vector form, and parametric equations?
 - (a) normal: $\mathbf{n} \cdot (\mathbf{x} \mathbf{p}) = 0$
 - (b) general: ax + by = c
 - (c) vector: $\mathbf{x} = \mathbf{p} + t\mathbf{d}$
 - (d) Parametric equations: x = f(t), y = f(t)

- 14. What is a plane? What vector describes a given plane?
 - (a) Normal vector describes the plane. The plane is the set of all points that satisfy the general equation of the plane (?).
- 15. Given a plane \mathcal{P} what are its normal form, general form, vector form, and parametric equations?

(a)
$$\mathbf{n} \cdot \mathbf{x} = \mathbf{n} \cdot \mathbf{p}$$
, $ax + by + cz = d$, $\mathbf{x} = \mathbf{p} + s\mathbf{u} + t\mathbf{v}$,
$$\begin{cases} x = p_1 + su_1 + tv_1 \\ y = p_2 + su_2 + tv_2 \\ z = p_3 + su_3 + tv_3 \end{cases}$$

- 16. Derive an equation for the shortest distance $d(B, \ell)$ from a point (x_0, y_0) to a line ax + by = c(a)
- 17. Derive an equaiton for the shortest distance $d(B, \mathcal{P})$ from a point (x_0, y_0, z_0) to a plane ax + by + cz = d(a)
- 18. What is the binary code?
 - (a) Only two values, 0 and 1. Consists of a set of binary code vectors that contain some message.
- 19. What is an error detecting code? How does it work?
 - (a)
- 20. What is modular arithmetic?
 - (a) When you divide by a given number and only keep the remainder