

1998 Mech MC

1) b ✓ 2) e ✓ 3) d ✓

4)  $\Sigma F = 0$  when  $a = 0$

$$\frac{dx}{dt} = 3t^2 - 12t + 9$$

$$\frac{d^2x}{dt^2} = 6t - 12$$

$$t = 2 \text{ (b) } \checkmark$$

5)  $\Sigma F = 0$   $2F_{3R} - F_{3R} - F_{2R} - F_{3R}$   
 $6F_R - 6F_R - 2F_R \text{ (c) } \checkmark$

6)  $v = R\omega \text{ (a) } \checkmark$

7) (a) ✓ 8)  $F = \frac{GMm}{R^2}$   $F_a = \frac{GMm}{4R^2} \text{ (d) } \checkmark$

9)  $\frac{dx}{dt} = -\frac{a}{2} x^2$   $x(t) = -\frac{3}{2} x^3 \text{ (c) } \checkmark$   
guess

10)  $T = 2\pi\sqrt{\frac{l}{g}} \text{ (c) } \checkmark$

11) e ✓ 12)  $F_{BC} = DP = 40 \text{ W} \text{ (a) } \checkmark$

13)  $mv = (3m) v_f$

$v_f = \frac{1}{3} v \text{ (a) } \checkmark$

14)  $\frac{mv^2}{r} = F_c = kx$   
 $= F_s = kx = (100 \text{ N/m})(0.03 \text{ m})$   
 $= 3 \text{ N (b) } \checkmark$

15) (a) ✓

16)  $3U_0 - U_0 = \frac{1}{2}mv^2$

$4U_0 = mv^2$

$v_f = \sqrt{\frac{4U_0}{m}} \text{ (c) } \checkmark$

17)  $U(r) = br^{-3/2} + C$

$W = \int F \cdot dr$

$\frac{dW}{dr} = F$

$F = -\frac{3}{2} br^{-5/2} \text{ (a) } \checkmark$

18) (b) ✓

19)  $\uparrow 11,000 \text{ N}$



$\Sigma F = ma$

$a = 1 \text{ m/s}^2$

~~MC =  $\frac{30}{35}$~~

~~$v_f = v_0^2 + 2a\Delta x$~~

~~$v_0^2 = -2a\Delta x$~~

$v_f^2 = v_0^2 + 2a\Delta x$

$v_0^2 = -2a\Delta x$

$v_0 = \sqrt{2(1)(8)}$

$= \sqrt{16} = 4 \text{ (a) } \checkmark$

20)  $F = \frac{GMm}{r^2} = \frac{Mv^2}{r}$

$\frac{GM^2}{D^2} = \frac{2Mv^2}{D}$

$v^2 = \frac{GM}{2D} \text{ (b) } \checkmark$

21)  $F \cos \theta - f = ma \text{ (d) } \checkmark$

22)  $F \sin \theta + N - mg = 0$

$N = mg - F \sin \theta$

$f = \mu N$

$\mu = \frac{f}{N} = \frac{f}{mg - F \sin \theta} \text{ (e) } \checkmark$

23) X N/A

24) (a) ✓ 25) (b) ✓

26)  $\bar{v} = \frac{\Delta x}{t}$   ~~$v_f = v_0 + at$~~

$\Delta y = v_{0y}t + \frac{1}{2}gt^2$

$t = \sqrt{\frac{2\Delta y}{g}}$

$v = \frac{3 \text{ m}}{\sqrt{\frac{2(10 \text{ m})}{10}}} = \frac{3}{\sqrt{2}} \text{ (c) } \checkmark$

27)  $W = \int_0^2 F \cdot dx = \int_0^2 (40x - 6x^2) dx$

$= 20x^2 - 2x^3 \Big|_0^2 = 80 - 16 \text{ J} = 64 \text{ J (d) } \checkmark$

28) (c) ✓ 29)  $\frac{dx}{dt} = -A\omega \sin \omega t$

$\frac{dy}{dt} = A\omega \cos \omega t$

$\frac{d^2y}{dt^2} = \frac{d}{dt} \left( \frac{dy}{dt} \right)$

$\frac{d^2y}{dt^2} = -A\omega^2 \sin \omega t$   
 $= -\sin^2 \omega t (-A\omega^2 \sin \omega t)$

$$\frac{d^2x}{dt^2} = -A\omega^2 \cos \omega t \hat{i}$$

$$\frac{d^2y}{dt^2} = -A\omega^2 \sin \omega t \hat{j}$$

Assuming  $t=0$ ?

$$u = -A\omega^2 (\cos \omega t \hat{i} + \sin \omega t \hat{j})$$

$$= -1.5(u)(1\hat{i})$$

$$= 6 \text{ N} \quad (e) \checkmark$$

$$30) m_1 = 2 \text{ kg}$$

$$m_1 g a = m_2 g b \quad (b) \checkmark$$

$$31)(e) \quad 32) \quad \tau = I \alpha \quad \omega_f = \omega_i + \alpha t$$

$$\tau = \frac{I \omega_f}{T} \quad \alpha = \frac{\omega_f}{T} \quad (e) \checkmark$$

$$33) W = \int \tau \cdot d\theta$$

Skip 32)

$$KE_f = \frac{1}{2} I \omega_f^2$$

$$\frac{W}{T} = \int \tau \cdot \frac{d\theta}{T}$$

$$\frac{W}{T} = \frac{I \omega_f^2}{2T} \quad (b) \checkmark$$

$$34) \frac{dv}{dt} = g - bv$$

$$\frac{dv}{g-bv} = dt$$

$$u = g - bv \quad \frac{du}{dv} = -b$$

$$t = -\frac{1}{b} \ln |g - bv|$$

$$dv = \frac{du}{-b}$$

$$-bt = \ln |g - bv|$$

$$g - bv = e^{-bt}$$

$$bv = g - e^{-bt}$$

$$v = \frac{1}{b} (g - e^{-bt}) \quad (a) \checkmark$$

$$35) \frac{1}{2} m v_m^2 = \frac{1}{2} k A^2$$

$$k = \frac{m v_m^2}{A^2} \quad (d) \checkmark$$



1998 Mech FR

$$\frac{42.5}{45} \rightarrow \frac{42}{45} \text{ (approx.)}$$

1) a) (i)  $\bar{v} = \frac{x}{t} = \frac{0.5m}{0.5s} = 1m/s$   
 (ii)  $\bar{v} = \frac{x}{t} = \frac{0.4m}{0.8s} = 0.5m/s$   
 (iii)  $\bar{v} = \frac{x}{t} =$

2) a) (i)  $m v_0 = 3m(v_f) + 1$

$$v_f = \frac{v_0}{3} + \frac{1}{3}$$

$$KE = \frac{1}{2} (3m) v_f^2 = \frac{1}{2} (3m) \left( \frac{v_0}{3} + \frac{1}{3} \right)^2 = \frac{1}{6} m v_0^2 + \frac{1}{3} m v_0 + \frac{1}{6} m$$

(i)  $\bar{v} = \frac{\Delta x}{t} = \frac{0.2m}{0.2s} = 1m/s$  ✓ +1

(ii)  $\bar{v} = \frac{\Delta x}{t} = \frac{0.12m}{0.2s} = 0.6m/s$  ✓ +1

(iii)  $\bar{v} = \frac{\Delta x}{t} = \frac{0.04m}{0.2s} = 0.2m/s$  ✓ +1

(ii)  $KE_0 = \frac{1}{2} m v_0^2$

$$\Delta KE = KE_f - KE_0 = \left[ \frac{1}{3} m v_0^2 \right] + \frac{1}{3} m v_0 + \frac{1}{6} m$$

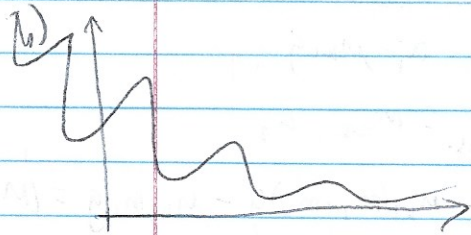
b)  $\frac{m}{2} \quad \frac{l}{2} \quad \frac{2m}{2}$

(i)

$$x_{cm} = \frac{m_1 x_1 + m_2 x_2}{m_{total}} + 1$$

$$= \frac{(m)(0m) + 2m(l)}{3m}$$

$$= \frac{2}{3} l \text{ from the left end}$$



c) (i)  $m_a v_{a0} + m_b v_{b0} = m_a v_{af} + m_b v_{bf}$  +1

$$(0.40kg)(1m/s) = 0.40kg v_{af} + 0.60kg v_{bf}$$

$$0.40kg(0.2m/s) + 0.60kg(v_{bf})$$

$$v_{bf} = \frac{0.40kg(1m/s - 0.2m/s)}{0.60kg} = 0.53m/s$$

(ii)

$$v_{cm} = \frac{m v_0}{3m} + \frac{1}{3}$$

(iii)  $m v_0 = 3m(v_f)$

$$v_f = \frac{v_0}{3} + \frac{1}{3}$$

(iv)  $l_0 = L_f$

$$I = m \left( \frac{2l}{3} \right)^2 + 2m \left( \frac{l}{3} \right)^2 = \frac{4}{9} m l^2 + \frac{2}{9} m l^2 = \frac{2}{3} m l^2 + 1$$

d) (i) Yes, KE is conserved. +1

(ii) the kinetic energy is stored in spring potential energy. +1

$$r_p = I \omega_f$$

$$\omega_f = \frac{\frac{1}{3} k \cdot m v_0}{\frac{2}{3} m l^2} = \frac{v_0}{2l} + 1$$

(U)  $KE_0 = \frac{1}{2} m v_0^2$

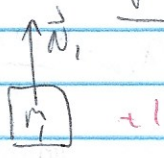
$KE_f = \frac{1}{6} m v_0^2 + \frac{1}{2} \left( \frac{2}{3} m l^2 \right) \left( \frac{v_0}{2l} \right)^2$

$$= \underbrace{\frac{1}{6} m v_0^2}_{\text{linear (translational) KE}} + \underbrace{\frac{1}{2} \left( \frac{2}{3} m l^2 \right) \left( \frac{v_0}{2l} \right)^2}_{\text{rotational KE}}$$

$= \frac{3}{12} m v_0^2 = \frac{1}{4} m v_0^2$

$\Delta KE = KE_f - KE_0 = -\frac{1}{2} m v_0^2$

3) a) (i)



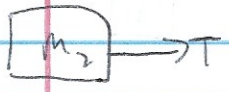
$N_1 = m_1 g$

(ii)



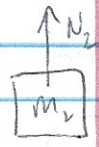
$F_f = \mu_{s1} N = \mu_{s1} m_1 g$

(iii)



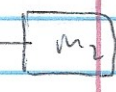
$T = M g$

(iv)



$N_2 = (m_1 + m_2) g$

(v)



$F_f = \mu_{s2} (m_1 + m_2) g$

b)  $M g - \mu_{s2} (m_1 + m_2) g = 0$

$M = \mu_{s2} (m_1 + m_2)$

c)  $\sum F = m a$

$M g - \mu_{s2} (m_1 + m_2) g = (M + m_1 + m_2) a$

$a = \frac{M g - \mu_{s2} (m_1 + m_2) g}{M + m_1 + m_2}$

d)  $\sum F = m a$

(i)  $F_f = m_1 a$

$\mu_{k1} m_1 g = m_1 a$

$a = \mu_{k1} g$

(ii)  $\sum F_{sys} = m_{sys} a_2$

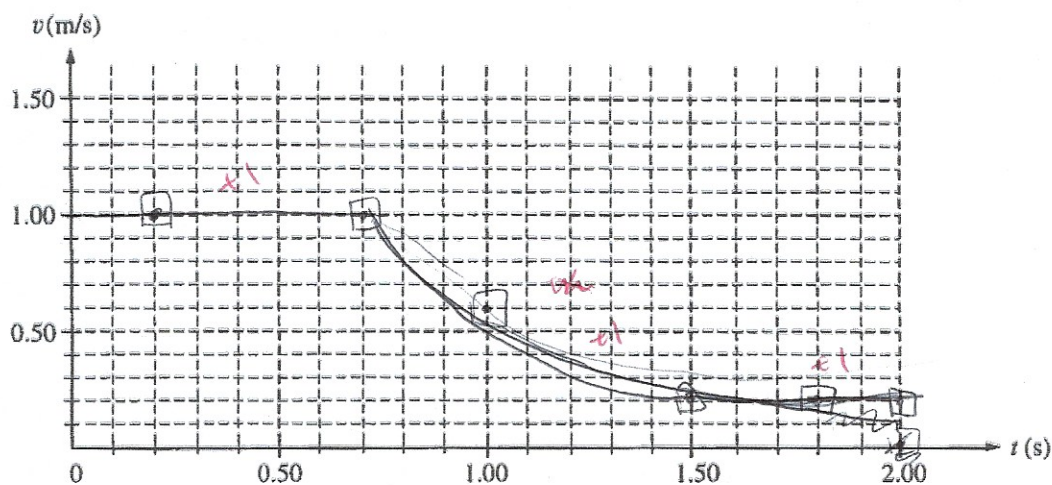
$M g - \mu_{k2} (m_1 + m_2) g - \mu_{k1} m_1 g = (M + m_2) a_2$

$a_2 = \frac{M g - \mu_{k2} (m_1 + m_2) g - \mu_{k1} m_1 g}{M + m_2}$



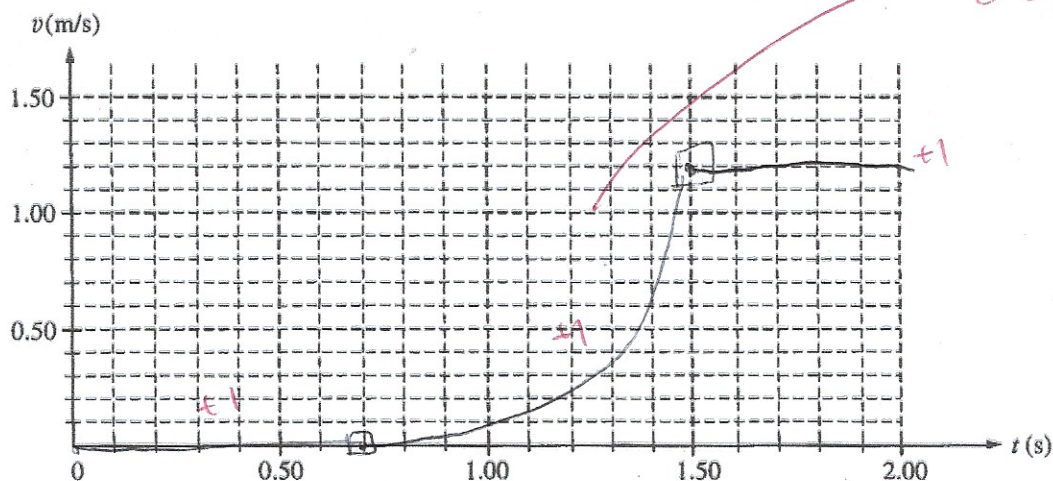
# 1998 PHYSICS C—MECHANICS

- (b) On the axes below, sketch a graph, consistent with the data above, of the speed of glider A as a function of time  $t$  for the 2.00 s interval.



- (c) i. Use the data to calculate the speed of glider B immediately after it separates from the spring.

- ii. On the axes below, sketch a graph of the speed of glider B as a function of time  $t$ .



GO ON TO THE NEXT PAGE