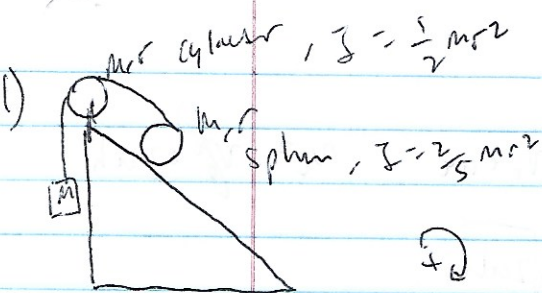


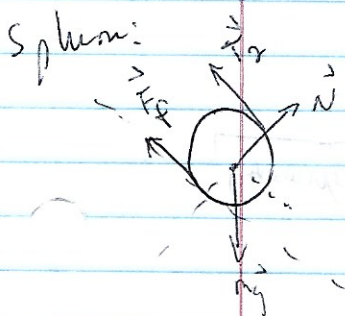
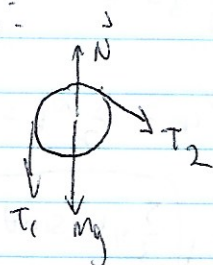
Review Cumulative 2



a) mass:



pulley:



b) $\Sigma F = m a_b$

mass: $\vec{T}_1 + m\vec{g} = m\vec{a}_b$

$T_1 - mg = m a_b$

cylinder:

$\Sigma F = m a_{cm} = 0$

$N - mg = 0$

$\Sigma \tau = I \alpha$

$r T_2 - r T_1 = I \alpha$

$r T_2 - r T_1 = \frac{1}{2} m r^2 \cdot \frac{a_b}{r}$

$T_2 - T_1 = \frac{1}{2} m a_b$

sphere: $\Sigma F = m a$

$\Sigma F_{||} = m a_{cm}$ $\Sigma F_{\perp} = 0$

$mg \sin \theta - F_f - T_2 = m a_{cm}$

$N - mg \cos \theta = 0$

$F_f = \mu N$

$= \mu mg \cos \theta$

$\Sigma \tau = I \alpha$

$r F_f - r T_2 = I \alpha$

$v_{block} = v_{cyl} = 2 v_{cm}$ $a_b = 2 a_{cm}$

$r F_f - r T_2 = \frac{2}{5} m r^2 \cdot \frac{a_{cm}}{r}$

$F_f - T_2 = \frac{2}{5} m a_{cm}$

c) $T_1 = mg + m a_b$ (1)

$T_2 = \frac{1}{2} m a_b + T_1$ (2)

$T_2 = mg \sin \theta + \mu mg \cos \theta - m a_{cm}$ (3)

$T_2 = \mu mg \cos \theta - \frac{2}{5} m a_{cm}$ (4)

$a_b = 2 a_{cm}$ (5)

$mg \sin \theta - \mu mg \cos \theta - m a_{cm} = \mu mg \cos \theta - \frac{2}{5} m a_{cm}$

$\frac{3}{5} m a_{cm} = \mu mg \cos \theta - 2 \mu mg \cos \theta$

$\frac{3}{5} a_{cm} = g (\sin \theta - 2 \mu \cos \theta)$

$a_{cm} = \frac{5}{3} g (\sin \theta - 2 \mu \cos \theta)$

$a_b = 2 a_{cm} = \frac{10}{3} g (\sin \theta - 2 \mu \cos \theta)$

[Signature]

$$d) \alpha = \frac{a}{r}$$

$$1) \text{ sphere: } a = \frac{5g}{3r} (\sin \theta - 2\mu \cos \theta)$$

$$= \frac{5g}{3r} (\sin \theta - 2\mu \cos \theta)$$

$$2) \text{ cylinder: } a = \frac{10g}{3r} (\sin \theta - 2\mu \cos \theta)$$

$$\alpha = \frac{a}{r} = \frac{a_{cm}}{r} = \frac{5g}{3r} (\sin \theta - 2\mu \cos \theta)$$

$$+ \frac{10g}{3r} (\sin \theta - 2\mu \cos \theta)$$

$$2) \text{ cylinder: } \alpha = \frac{a_b}{r} = \frac{10g}{3r} (\sin \theta - 2\mu \cos \theta)$$

$$e) T_1 = mg + ma_b \quad (\text{pulley \& mass})$$

$$= m \left(\frac{10}{3} g (\sin \theta - 2\mu \cos \theta) + g \right)$$

$$= mg \left(\frac{10}{3} (\sin \theta - 2\mu \cos \theta) + 1 \right)$$

$$T_2 = \frac{1}{2} ma_b + T_1 \quad (\text{sphere \& pulley})$$

$$= m \left(\frac{5}{3} g (\sin \theta - 2\mu \cos \theta) + g \cdot \frac{10}{3} (\sin \theta - 2\mu \cos \theta) \right)$$

$$= 5mg (\sin \theta - 2\mu \cos \theta)$$

$$f) \tau_{\text{string}} = 5mgr (\sin \theta - 2\mu \cos \theta)$$

$$g) f_f = \mu a = \mu mg \cos \theta$$

$$h) mg \sin \theta - \mu mg \cos \theta = 0$$

$$\mu = \tan \theta$$

$$(i) \Delta y = h$$

$$1) v_f = v_0 + at$$

$$v_f^2 = v_0^2 + 2ah$$

$$v_f = \sqrt{2ah}$$

$$= \sqrt{\frac{20}{3} gh (\sin \theta - 2\mu \cos \theta)}$$

$$2) v_{cm} = \frac{1}{2} v_b = \frac{1}{2} \sqrt{\frac{20}{3} gh (\sin \theta - 2\mu \cos \theta)}$$

$$= \sqrt{\frac{5}{3} gh (\sin \theta - 2\mu \cos \theta)}$$

$$3) \text{ sphere: } \omega = \frac{v_{cm}}{r}$$

$$= \frac{1}{r} \sqrt{\frac{5}{3} gh (\sin \theta - 2\mu \cos \theta)}$$

$$\text{pulley: } \omega = \frac{v_b}{r}$$

$$= \frac{1}{r} \sqrt{\frac{20}{3} gh (\sin \theta - 2\mu \cos \theta)}$$

$$4) p = mv = m \sqrt{\frac{20}{3} gh (\sin \theta - 2\mu \cos \theta)}$$

$$5) p = mv = m \sqrt{\frac{5}{3} gh (\sin \theta - 2\mu \cos \theta)}$$

$$6) \text{ sphere: } L = I\omega = \frac{2}{5} mr^2 \omega$$

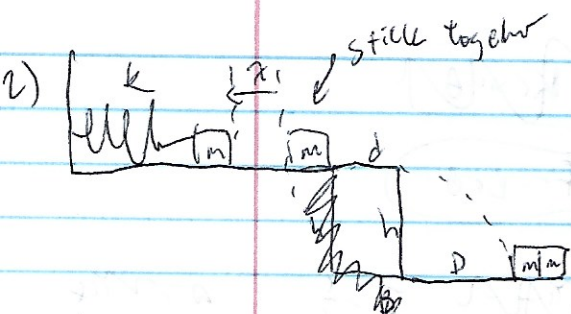
$$= \frac{2}{5} mr \sqrt{\frac{5}{3} gh (\sin \theta - 2\mu \cos \theta)}$$

$$\text{pulley: } L = I\omega = \frac{1}{2} mr^2 \omega$$

$$= \frac{1}{2} mr \sqrt{\frac{20}{3} gh (\sin \theta - 2\mu \cos \theta)}$$

$$= mr \sqrt{\frac{5}{3} gh (\sin \theta - 2\mu \cos \theta)}$$

mu



$$A) \frac{1}{2} k x^2 = \frac{1}{2} m v_b^2 \quad (1)$$

$$m v_b = 2 m v_a \quad (2)$$

$$v_a = v_x \quad D = v_x t$$

$$v_{fy} = v_{fy} + g t$$

$$h = v_{fy} t + \frac{1}{2} g t^2$$

$$t = \sqrt{\frac{2h}{g}}$$

$$D = v_x \sqrt{\frac{2h}{g}} \quad (3)$$

$$v_a = \frac{1}{2} v_b \quad v_b^2 = \frac{k}{m} x^2$$

$$v_b = x \sqrt{\frac{k}{m}}$$

$$v_x = v_a = \frac{1}{2} x \sqrt{\frac{k}{m}}$$

$$D = \frac{1}{2} x \sqrt{\frac{k}{m}} \sqrt{\frac{2h}{g}}$$

$$D = \frac{1}{2} x \sqrt{\frac{2hk}{mg}}$$

$$b) D^2 = \frac{1}{4} x^2 \left(\frac{2hk}{mg} \right)$$

$$4 D^2 mg = x^2 h k$$

$$2 D^2 mg = x^2 h k$$

$$k = \frac{2 D^2 mg}{x^2 h}$$

c) Set m in a SHM on the table with the spring k.

$$T_s = 2\pi \sqrt{\frac{m}{k}}$$

measure the period of oscillation for a variety of masses.

$$\frac{1}{T^2} = \frac{m}{k}$$

$$y = m x$$

plot

$$\frac{4\pi^2}{T^2} = \frac{k}{m}$$

plot $\frac{4\pi^2}{T^2}$ vs. $\frac{1}{m}$; find the slope to get k.

$$d) \frac{1}{2} k x^2 = \frac{1}{2} m v_b^2$$

$$m v_b = 2 m v_a$$

$$v_a = \frac{1}{2} v_b = \frac{1}{2} x \sqrt{\frac{k}{m}}$$

$$\frac{1}{2} m v_a^2 = \frac{1}{2} m v_f^2 + \mu 2mgd$$

$$\frac{1}{2} m v_f^2 = \frac{1}{2} m \cdot \frac{1}{4} x^2 \cdot \frac{k}{m} - 2\mu mgd$$

$$D = v_f \sqrt{\frac{2h}{g}}$$

$$v_f = D \sqrt{\frac{g}{2h}}$$

$$\frac{1}{2} m D^2 \cdot \frac{g}{2h} = \frac{1}{8} m x^2 \frac{k}{m} - 2\mu mgd$$

$$\mu mgd = \frac{1}{16} m x^2 \frac{k}{m} - \frac{1}{4} m D^2 \cdot \frac{g}{2h}$$

$$\mu g d = \frac{x^2 k}{16m} - \frac{g D^2}{8} = \frac{1}{16} \left(\frac{k x^2}{m} - \frac{g D^2}{2h} \right)$$

$$\mu = \frac{1}{16gd} \left(\frac{k x^2}{m} - \frac{g D^2}{2h} \right)$$

Jim

e) perform the experiment with known x, k, m, d , and D .

~~$$F = kx = krsin\theta$$~~

~~$$F = -kr\theta$$~~

or,
from the experiment setup that the two blocks don't leave the table. measure with d to calculate the coefficient of friction.

~~$$T = \frac{1}{f}$$~~

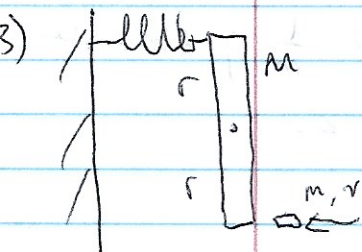
$$\omega = 2\pi f$$

$$f = \frac{\omega}{2\pi}$$

~~$$T = \frac{2\pi}{\omega}$$~~

~~$$T = \frac{2\pi I (2M + 3m)}{3m\omega}$$~~

~~$$\frac{1}{2} I \omega^2 = \frac{1}{2} k r^2 \sin^2 \theta$$~~



$$I_{bar} = 2 \cdot \frac{1}{3} M r^2 = \frac{2}{3} M r^2$$

$$L = r p = I \omega$$

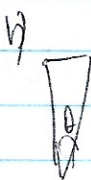
$$3m v = \left(\frac{2}{3} M r^2 + m r^2 \right) \omega_f$$

$$\omega_f = \frac{r m v}{r^2 \left(\frac{2}{3} M + m \right)} = \left(\frac{m v}{r \left(\frac{2}{3} M + m \right)} \right)$$

$$\frac{2}{3} M + m = \frac{2M + 3m}{3}$$

$$\omega_f = \frac{m v}{r} \cdot \frac{3}{2M + 3m}$$

$$= \left(\frac{3m v}{r (2M + 3m)} \right)$$



for small θ , $\sin \theta \approx \theta$

$$x = r \theta \approx r \sin \theta$$

$$I \alpha = I \ddot{\theta}$$

$$-r(k\theta) = I \ddot{\theta} = I \frac{d^2 \theta}{dt^2}$$

$$-kr^2 \theta = \left(\frac{2}{3} M r^2 + m r^2 \right) \frac{d^2 \theta}{dt^2}$$

$$-k\theta = \left(\frac{2}{3} M + m \right) \frac{d^2 \theta}{dt^2}$$

$$\frac{d^2 \theta}{dt^2} + \left(\frac{k}{\frac{2}{3} M + m} \right) \theta = 0$$

$$\omega^2 = \frac{k}{M + 3m}$$

$$\omega = \sqrt{\frac{3k}{M + 3m}}$$

$$T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{M + 3m}{3k}}$$

$$\left[\frac{d^2 x}{dt^2} + \omega^2 x = 0 \right]$$

from