

MA1521 CALCULUS FOR COMPUTING

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What will we learn in MA1521?

- Chapter 0: Pre-calculus
- Chapter 1: Limits and Continuity
- Chapter 2: Derivatives with Applications
- Chapter 3: Sequences and Series
- Chapter 4: Partial Derivatives
- Chapter 5: Optimization
- Chapter 6: Integrals with Applications
- Chapter 7: Ordinary Differential Equations

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Workload and Assessment

- Workload:
 - Lecture: 1.5×2 hours per week (week 1 to 13);
(Chinese New Year: 11 February);
Monday, Thursday 12:00 – 1:35pm, LT33.
 - Tutorial: 1 hour per week (week 3 to 13);
- Notes and References:
 - Lecture materials: Available in [IVLE](#),
 - Textbook: Thomas' Calculus 12th ed.
- Assessment:
 - Homework Assignments: $5\% \times 3 = 15\%$
 - Tutorial Participation: 5%
 - Mid-Term Test: 20%
(11 March, 12:00 – 1:30pm, LT33)
 - Final Exam: 60% (02 May, afternoon)

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Sets

- A **set** is a collection of **objects**.
- A set is usually denoted by capital letters A, B, C, \dots .
 - The objects a, b, c, \dots contained in set A are called the **elements** of A . We write

$$A = \{a, b, c, \dots\}.$$

- For example, $\{-1, 1\}, \{2, 3, 5, 7, 11, 13, 17, 19, \dots\}$.
- We can also write a set using **description**:

$$A = \{x \mid \text{properties of } x\}.$$

- For example, $\{x \mid x^2 = 1\}, \{x \mid x \text{ is a prime number}\}$.

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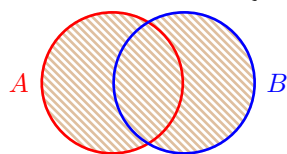
Sets

- If a **is** an element of A , we write $a \in A$;
If a **is not** an element of A , we write $a \notin A$.
 - Example: $1 \in \{1, 2\}, 0 \notin \{1, 2\}$.
- If **every** element of set A is also an element of set B , we say A is a **subset** of B , denoted by $A \subseteq B$.
If A **is not** a subset of B , we write $A \not\subseteq B$.
 - Example: $\{1, 2\} \subseteq \{1, 2, 3\}, \{0, 1\} \not\subseteq \{1, 2, 3\}$.
- Two sets are **equal** if they have the same collection of elements, regardless of order.
In other words, " $A = B$ " \Leftrightarrow " $A \subseteq B$ & $B \subseteq A$ ".
 - Examples:
 - $\{1, 2, 3\} = \{3, 2, 1\}$.
 - $\{x \mid x^2 = 1\} = \{1, -1\}$.

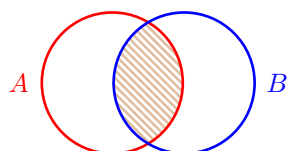
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Operations on Sets

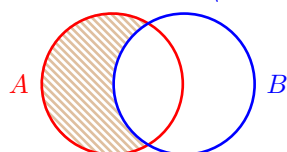
- **Union:** $A \cup B = \{x \mid x \in A \text{ or } x \in B\};$



- **Intersection:** $A \cap B = \{x \mid x \in A \text{ and } x \in B\};$



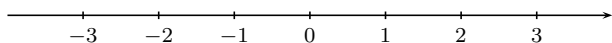
- **Difference:** $A \setminus B = \{x \mid x \in A \text{ and } x \notin B\}.$



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Number System

- $\mathbb{N} = \{1, 2, 3, \dots\}$: the set of **natural numbers**.
- $\mathbb{Z} = \{0, \pm 1, \pm 2, \pm 3, \dots\}$: the set of **integers**.
 - $\mathbb{Z}^+ = \{1, 2, 3, \dots\}$: **positive integers**;
 - $\mathbb{Z}^- = \{-1, -2, -3, \dots\}$: **negative integers**.
- $\mathbb{Q} = \{m/n \mid m, n \in \mathbb{Z}, n \neq 0\}$: **rational numbers**.
- \mathbb{R} : the set of **real numbers**.
 - There is a one-to-one correspondence between \mathbb{R} and the points on the number line.



- $a < b \Leftrightarrow a$ lies to the left of b on the number line.
- \emptyset : the **empty set**, the set containing no element.
- Similarly as \mathbb{Z}^+ and \mathbb{Z}^- , we use \mathbb{Q}^+ , \mathbb{Q}^- , \mathbb{R}^+ , \mathbb{R}^- .

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Intervals

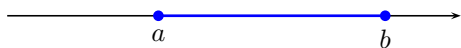
- Certain subsets of \mathbb{R} can be expressed as **intervals**.

- **Finite intervals:** (Suppose $a < b$.)

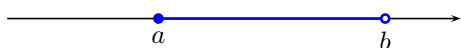
- $(a, b) = \{x \in \mathbb{R} \mid a < x < b\}$.



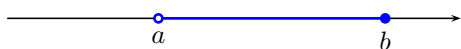
- $[a, b] = \{x \in \mathbb{R} \mid a \leq x \leq b\}$.



- $[a, b) = \{x \in \mathbb{R} \mid a \leq x < b\}$.



- $(a, b] = \{x \in \mathbb{R} \mid a < x \leq b\}$.



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Intervals

- Certain subsets of \mathbb{R} can be expressed as **intervals**.

- **Infinite intervals:**

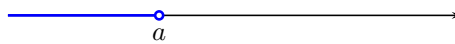
- $(a, \infty) = \{x \in \mathbb{R} \mid x > a\}$.



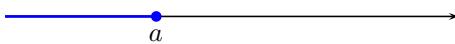
- $[a, \infty) = \{x \in \mathbb{R} \mid x \geq a\}$.



- $(-\infty, a) = \{x \in \mathbb{R} \mid x < a\}$.



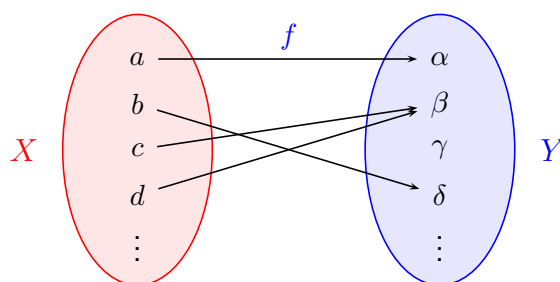
- $(-\infty, a] = \{x \in \mathbb{R} \mid x \leq a\}$.



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Functions

- Let X and Y be two sets.



- A **function** $f : X \rightarrow Y$ is a **rule** which assigns **each** element in X to a **unique** element in Y .
- If the function f assigns $x \in X$ to $y \in Y$, we say y is the **image** of x under f , denoted by $y = f(x)$.

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Functions

- Let $f : X \rightarrow Y$ be a function.

- X is the **domain** of f ;
- Y is the **codomain** of f .

Unless otherwise stated, X and Y are always taken to be subsets of the set of real numbers \mathbb{R} .

- We make the following convention:

- If X is not stated, the domain of f is taken to be the **largest** possible set ($\subseteq \mathbb{R}$) on which f is defined.
- If Y is not stated, take $Y = \mathbb{R}$.

- The **range** is the set of images:

- range of " $f : X \rightarrow Y$ " = $\{f(x) \mid x \in X\}$.

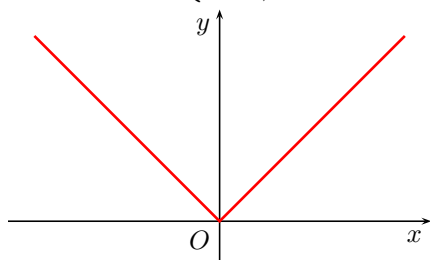
By definition, the range is a subset of the codomain.

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Absolute Value Function

- The **absolute value function**:

$$f(x) = |x| = \begin{cases} x, & \text{if } x \geq 0, \\ -x, & \text{if } x < 0. \end{cases}$$



- Domain: \mathbb{R} ; Range: $\{x \in \mathbb{R} \mid x \geq 0\}$.
- $|x|$ represents the **distance** between x and O .
 - $|x| \leq c \Leftrightarrow -c \leq x \leq c$;
 - $|x| < c \Leftrightarrow -c < x < c$.

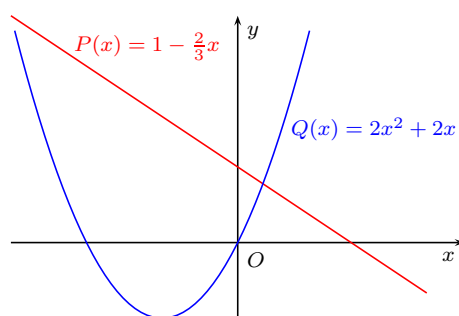
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Polynomials

- A **polynomial** is a function of the form

$$P(x) = a_n x^n + a_{n-1} x^{n-1} + \cdots + a_1 x + a_0.$$

- a_0, a_1, \dots, a_n are the **coefficients** of $P(x)$;
- If $a_n \neq 0$, then $n = \deg P(x)$ is the **degree** of $P(x)$.
 - A polynomial of **degree 1** is a **linear function**.
 - A polynomial of **degree 2** is a **quadratic function**.



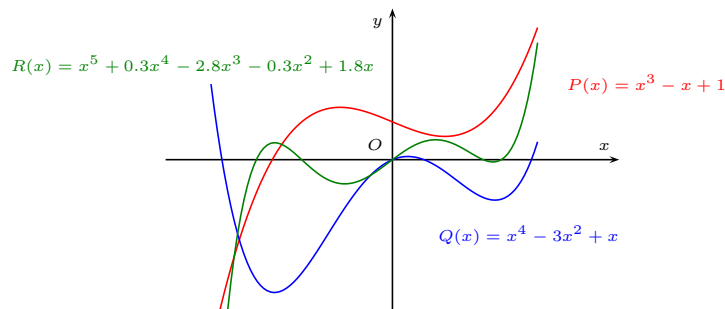
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Polynomials

- A **polynomial** is a function of the form

$$P(x) = a_n x^n + a_{n-1} x^{n-1} + \cdots + a_1 x + a_0.$$

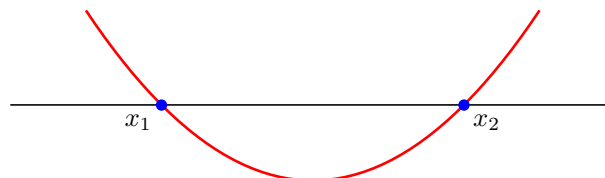
- A polynomial of **degree 3** is a **cubic function**.
- A polynomial of **degree 4** is a **quartic function**.
- A polynomial of **degree 5** is a **quintic function**.



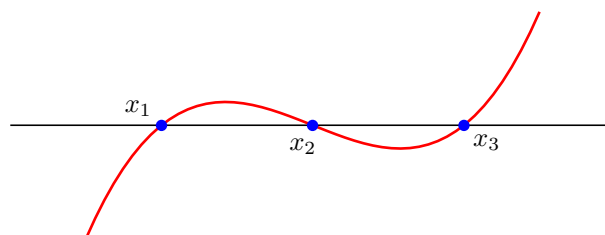
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Graphs of Polynomials

- Let $f(x) = (x - x_1)(x - x_2)$, where $x_1 < x_2$.



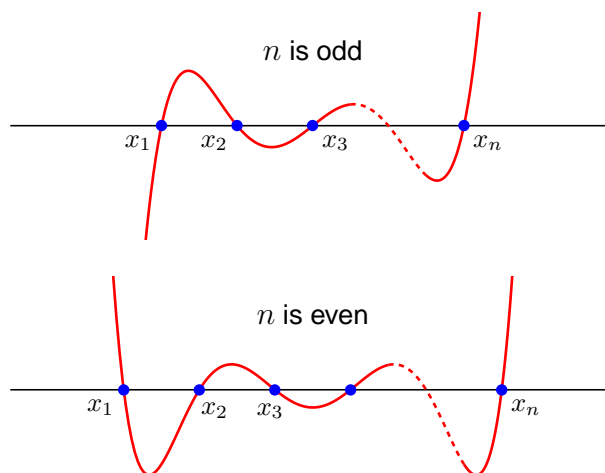
- Let $f(x) = (x - x_1)(x - x_2)(x - x_3)$, $x_1 < x_2 < x_3$.



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Graphs of Polynomials

- $f(x) = (x - x_1) \cdots (x - x_n)$, where $x_1 < \cdots < x_n$.



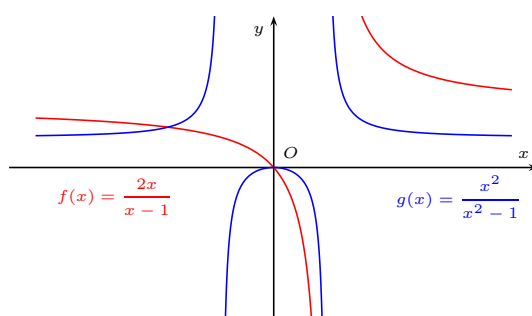
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Rational Functions

- A **rational function** $R(x)$ is a function of the form

$$R(x) = \frac{P(x)}{Q(x)},$$

where P, Q are polynomials, $Q(x)$ is not identically zero.



- Every polynomial is a rational function by letting $Q(x) = 1$.

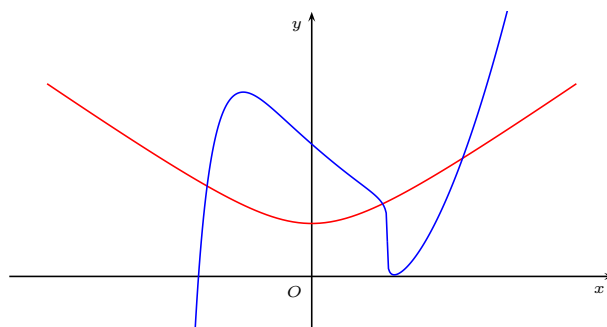
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Algebraic Functions

- An **algebraic function** is a function constructed from **polynomials** using **algebraic operations**:

- addition, subtraction, multiplication, division, taking roots, composite

- $f(x) = \sqrt{x^2 + 1}$, $g(x) = \frac{x^3 + 1}{x + 2} + (x - 2)\sqrt[5]{x^3 - 1}$



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Examples

- Find the domain of $f(x) = \frac{1}{x^4 - 16} + \frac{2}{x^4 + 16}$.

- For fraction, $\frac{P(x)}{Q(x)}$ is defined $\Leftrightarrow Q(x) \neq 0$.

- $\frac{1}{x^4 - 16}$:

- $x^4 - 16 = (x^2 + 4)(x - 2)(x + 2)$.
- $x^4 - 16 \neq 0 \Leftrightarrow x \neq \pm 2$.

- $\frac{1}{x^4 + 16}$:

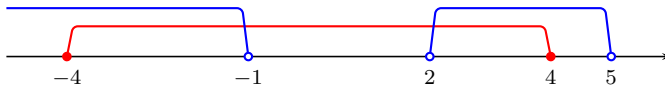
- $x^4 + 16 \geq 0 + 16 = 16 > 0$.
- $x^4 + 16 \neq 0$ for all $x \in \mathbb{R}$.

- Therefore, the domain of f is $\{x \in \mathbb{R} \mid x \neq \pm 2\}$.

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Examples

- $f(x) = \sqrt{16 - x^2} + \frac{6}{\sqrt{(x+1)(x-2)(5-x)}}$.
- For square root function, $\sqrt{g(x)}$ is defined $\Leftrightarrow g(x) \geq 0$.
 - $\sqrt{16 - x^2}$:
 - $16 - x^2 = (4 - x)(4 + x) = -(x - 4)(x + 4)$.
 - $16 - x^2 \geq 0 \Leftrightarrow (x - 4)(x + 4) \leq 0 \Leftrightarrow -4 \leq x \leq 4$.
 - $\frac{6}{\sqrt{(x+1)(x-2)(5-x)}}$:
 - $(x+1)(x-2)(5-x) \geq 0$ and $\neq 0$ (i.e., > 0)
 - $x < -1$ or $2 < x < 5$.



- Domain: $\{x \in \mathbb{R} \mid -4 \leq x < -1 \text{ or } 2 < x \leq 4\}$.

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Examples

- Solve the inequalities $-1 > -x^3 > -8$.
 - $-1 > -x^3 \Leftrightarrow 1 < x^3 \Leftrightarrow \sqrt[3]{1} < \sqrt[3]{x^3} \Leftrightarrow 1 < x$.
 - $-x^3 > -8 \Leftrightarrow x^3 < 8 \Leftrightarrow \sqrt[3]{x^3} < \sqrt[3]{8} \Leftrightarrow x < 2$.

In general, we need to use polynomial factorization:

- $-1 > -x^3 \Leftrightarrow x^3 - 1 > 0$.
 - $x^3 - 1 = (x - 1)(x^2 + x + 1) > 0$.
 $x^2 + x + 1 = \left(x + \frac{1}{2}\right)^2 + \frac{3}{4} > 0$.
 $\therefore x^3 - 1 > 0 \Leftrightarrow x > 1$.
- $-x^3 > -8 \Leftrightarrow x^3 - 8 < 0$.
 - $x^3 - 8 = (x - 2)(x^2 + 2x + 4) < 0$.
 $x^2 + 2x + 4 = (x + 1)^2 + 3 > 0$.
 $\therefore x^3 - 8 < 0 \Leftrightarrow x < 2$.

Therefore, $1 < x < 2$.

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Examples

- Solve $|x + 2| \geq |2x - 3|$.

$$\begin{aligned}|a| \geq |b| &\Leftrightarrow a^2 \geq b^2 \Leftrightarrow a^2 - b^2 \geq 0 \\ &\Leftrightarrow (a - b)(a + b) \geq 0\end{aligned}$$

$$\begin{aligned}|x + 2| &\geq |2x - 3| \\ \Leftrightarrow [(x + 2) - (2x - 3)][(x + 2) + (2x - 3)] &\geq 0 \\ \Leftrightarrow (-x + 5)(3x - 1) &\geq 0 \\ \Leftrightarrow (x - 5)(3x - 1) &\leq 0 \\ \Leftrightarrow \frac{1}{3} \leq x &\leq 5.\end{aligned}$$

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Examples

- Solve the inequality $x \leq \frac{3x}{x + 2}$.

$$\begin{aligned}x \leq \frac{3x}{x + 2} &\Leftrightarrow x - \frac{3x}{x + 2} \leq 0 \\ &\Leftrightarrow \frac{x(x + 2) - 3x}{x + 2} \leq 0 \\ &\Leftrightarrow \frac{x(x - 1)}{x + 2} \leq 0 \\ &\Leftrightarrow x(x - 1)(x + 2) \leq 0 \text{ and } x + 2 \neq 0.\end{aligned}$$

$$\circ \quad x(x - 1)(x + 2) \leq 0 \Leftrightarrow x \leq -2 \text{ or } 0 \leq x \leq 1.$$

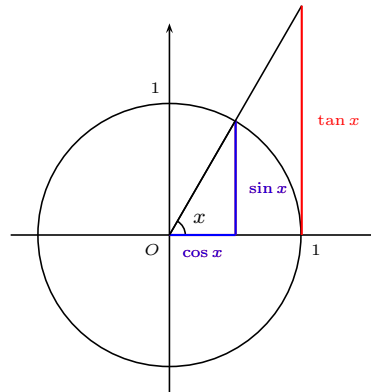
Hence, the answer is " $x < -2$ or $0 \leq x \leq 1$ ".

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Trigonometric Functions

- The **trigonometric functions**
 - $\sin x$, $\cos x$, $\tan x$, $\cot x$, $\sec x$, $\csc x$.

are the ratios of the sides of a right angle triangle.

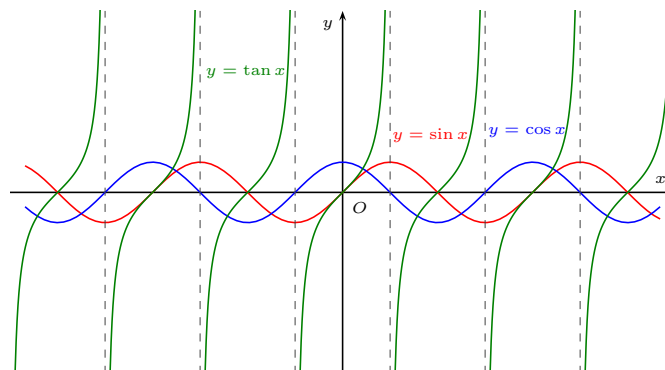


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Trigonometric Functions

- The **trigonometric functions**
 - $\sin x$, $\cos x$, $\tan x$, $\cot x$, $\sec x$, $\csc x$.

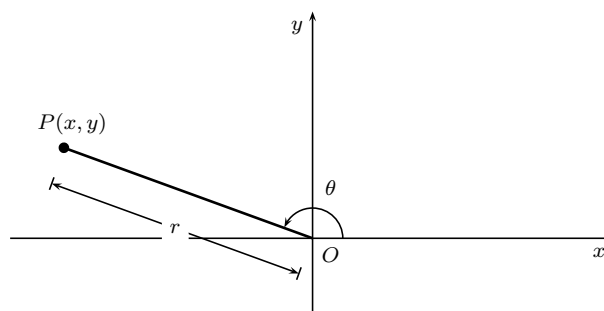
are the ratios of the sides of a right angle triangle.



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Trigonometric Functions

- Let $P(x, y)$ be a point and let $|OP| = r = \sqrt{x^2 + y^2}$.



- $\sin \theta = \frac{y}{r}; \quad \cos \theta = \frac{x}{r}; \quad \tan \theta = \frac{y}{x};$
- $\csc \theta = \frac{r}{y}; \quad \sec \theta = \frac{r}{x}; \quad \cot \theta = \frac{x}{y}.$

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Trigonometric Identities

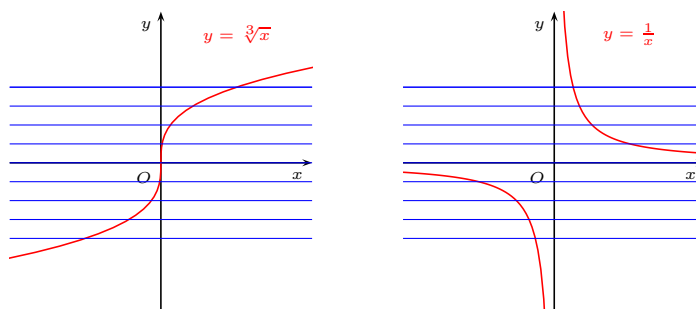
- Identities on trigonometric functions:
 - $\sin^2 \theta + \cos^2 \theta = 1; \quad \tan \theta = \frac{\sin \theta}{\cos \theta};$
 - $\sec^2 \theta - \tan^2 \theta = 1; \quad \csc^2 \theta - \cot^2 \theta = 1.$
- Trigonometric functions of compounded angles:
 - $\sin(\alpha \pm \beta) = \sin \alpha \cos \beta \pm \cos \alpha \sin \beta;$
 - $\cos(\alpha \pm \beta) = \cos \alpha \cos \beta \mp \sin \alpha \sin \beta.$
- Double-angled formulas:
 - $\sin 2\alpha = 2 \sin \alpha \cos \alpha;$
 - $\cos 2\alpha = \cos^2 \alpha - \sin^2 \alpha.$
- Periodicity:
 - $\sin(\alpha + 2\pi) = \sin \alpha; \quad \cos(\alpha + 2\pi) = \cos \alpha;$
 - $\tan(\alpha + \pi) = \tan \alpha.$

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One to One Functions

- Consider the two functions $f(x) = \sqrt[3]{x}$ and $g(x) = 1/x$.

- Do they have any common property?



- Every horizontal line cuts each graph **at most once**.
- In other words, f and g *never take on the same value twice (or more)*.
- This lends to the definition of **one to one function**.

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One to One Functions

- Definition.** Let f be a function with domain D .

- f is said to be **one to one** if

- for any $a, b \in D$, $a \neq b \Rightarrow f(a) \neq f(b)$.

Or equivalently, ($P \Rightarrow Q \Leftrightarrow \text{"not } Q \Rightarrow \text{not } P$),

- for any $a, b \in D$, $f(a) = f(b) \Rightarrow a = b$.

In short, **one to one** means **not many to one**.

- Examples.** $f(x) = \sqrt[3]{x}$ and $g(x) = 1/x$.

- Suppose $f(a) = f(b)$, i.e., $\sqrt[3]{a} = \sqrt[3]{b}$.

- Then $(\sqrt[3]{a})^3 = (\sqrt[3]{b})^3$. That is, $a = b$.

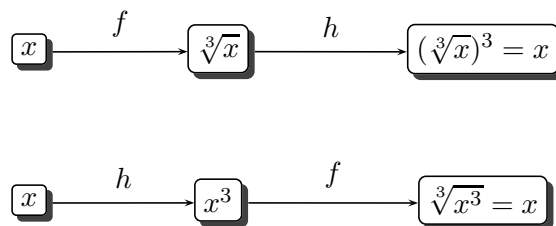
- Suppose $g(a) = g(b)$, i.e., $1/a = 1/b$.

- Then $(1/a)^{-1} = (1/b)^{-1}$. That is, $a = b$.

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Inverse Functions

- $f(x) = \sqrt[3]{x}$ and $h(x) = x^3$ are the **inverse operations** of each other.



Definition. Let f be a **one to one function** with

- domain A and range B .

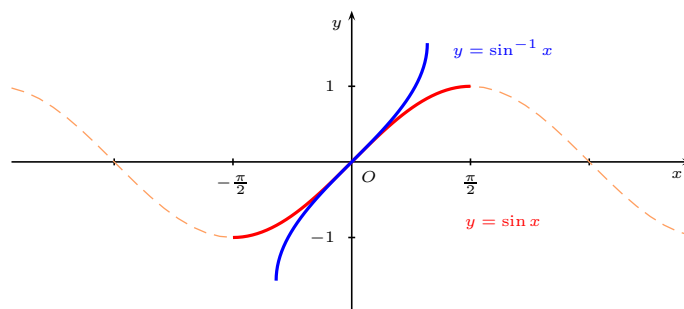
Its **inverse function** f^{-1} is the function with

- domain B and range A , and
- $f^{-1}(y) = x \Leftrightarrow y = f(x)$ for any $x \in A, y \in B$.

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Inverse Sine Function

- Let $y = \sin x$. It is not one to one on \mathbb{R} .

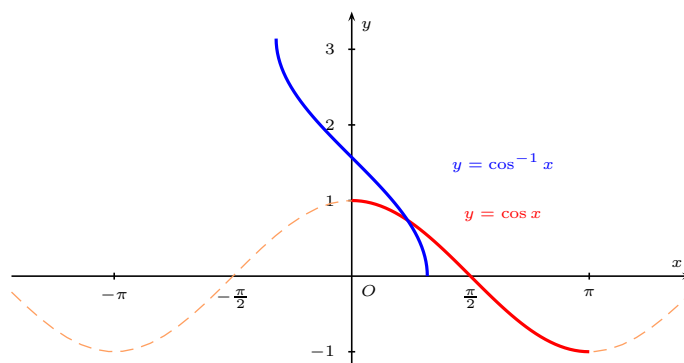


- But we can restrict the domain on $[-\frac{\pi}{2}, \frac{\pi}{2}]$.
Then $\sin x$ is one to one on $[-\frac{\pi}{2}, \frac{\pi}{2}]$, range = $[-1, 1]$.
- The **inverse sine function** is
 - \sin^{-1} with domain $[-1, 1]$ and range $[-\frac{\pi}{2}, \frac{\pi}{2}]$.
 - $\sin^{-1} x = y \Leftrightarrow x = \sin y$.

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Inverse Cosine Function

- Let $y = \cos x$. It is not one to one on \mathbb{R} .



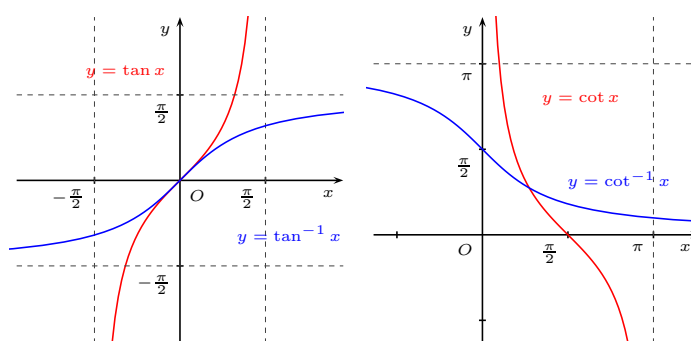
But $\cos x$ is one to one on $[0, \pi]$, range $= [-1, 1]$.

- The **inverse cosine function** is
 - \cos^{-1} with domain $[-1, 1]$ and range $[0, \pi]$.
 - $\cos^{-1} x = y \Leftrightarrow x = \cos y$.

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Inverse Trigonometric Functions

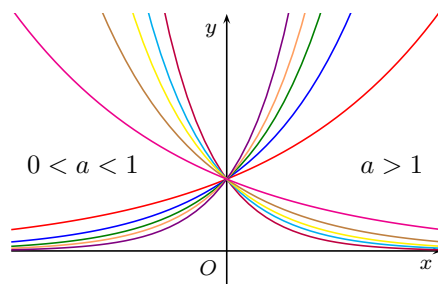
- We have the following **inverse trigonometric functions** from the given domain to its range:
 - $\tan^{-1} x : \mathbb{R} \rightarrow (-\frac{\pi}{2}, \frac{\pi}{2})$.
 - $\cot^{-1} x : \mathbb{R} \rightarrow (0, \pi)$.



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Exponential Functions

- Let $a > 0$ and $a \neq 1$. Consider the **exponential function** $f(x) = a^x$, $x \in \mathbb{R}$.



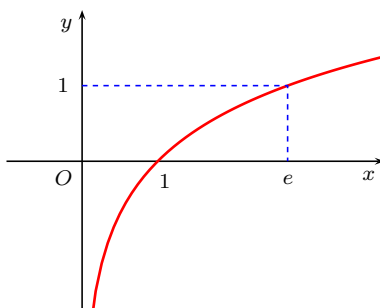
- a^x is **one to one** on \mathbb{R} , and its range is \mathbb{R}^+ .
- It admits an inverse function $\log_a : \mathbb{R}^+ \rightarrow \mathbb{R}$:
 - $y = \log_a x \Leftrightarrow x = a^y$.

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Logarithmic Functions

- Let e denote the **Euler number**:
 - $e = 1 + \frac{1}{1!} + \frac{1}{2!} + \frac{1}{3!} + \cdots + \frac{1}{n!} + \cdots = 2.71828 \dots$

We call $\log_e x = \ln x$ the **natural logarithm function**.



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Properties

- Exponential Functions: Let $a > 0$.
 - $a^0 = 1$; $a^{-x} = 1/a^x$;
 - $a^x a^y = a^{x+y}$; $(a^x)^y = a^{xy}$.
- Logarithmic Functions: Let $a, x, y > 0$ with $a \neq 1$.
 - $\log_a x + \log_a y = \log_a xy$;
 - $\log_a x - \log_a y = \log_a (x/y)$;
 - $\log_a (x^b) = b \log_a x$;
 - $\log_b x = \frac{\log_a x}{\log_a b}$, where $b > 0$ and $b \neq 1$.
- Relations:
 - $a^{\log_a x} = x$ for all $x > 0$ and $a > 0, a \neq 1$.
 - $\log_a (a^x) = x$ for all $a > 0, a \neq 1$.

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Examples

- Prove that $a^{\ln b} = b^{\ln a}$ for all $a > 0$ and $b > 0$.
 - Let $X = a^{\ln b}$. Then
 - $\ln X = \ln(a^{\ln b}) = \ln b \cdot \ln a$.
 - Let $Y = b^{\ln a}$. Then
 - $\ln Y = \ln(b^{\ln a}) = \ln a \cdot \ln b$.

So $\ln X = \ln Y$. It follows that

 - $X = e^{\ln X} = e^{\ln Y} = Y$.- That is, $a^{\ln b} = b^{\ln a}$.

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Examples

- Find the domain of $f(x) = \cos \ln(5 - x) + \tan \sqrt{x - 3}$.
 - $\ln x$ is defined on positive numbers.
 - $\ln(5 - x)$: $5 - x > 0 \Leftrightarrow x < 5$.
 - \sqrt{x} is defined on nonnegative numbers.
 - $\sqrt{x - 3}$: $x - 3 \geq 0 \Leftrightarrow x \geq 3$.
 - $\tan x = \frac{\sin x}{\cos x}$ is defined when $\cos x \neq 0$.
 - So $\sqrt{x - 3} \neq \pm \frac{\pi}{2}, \pm \frac{3\pi}{2}, \pm \frac{5\pi}{2}, \pm \frac{7\pi}{2}, \dots$
 - $\sqrt{x - 3} < \sqrt{5 - 3} = \sqrt{2} \approx 1.414 < 1.57 \approx \frac{\pi}{2} < \frac{3\pi}{2} < \dots$
- Hence, the domain is $[3, 5)$.

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Examples

- Find the domain of $f(x) = \frac{x^2 + x + 2}{\sqrt{x^2 - 5x + 6}} + \sqrt{2 - \ln x}$.
 - $\frac{x^2 + x + 2}{\sqrt{x^2 - 5x + 6}}$:
 - $x^2 - 5x + 6 \geq 0$ and $\neq 0$ (i.e., > 0).
 - $x^2 - 5x + 6 = (x - 2)(x - 3) > 0 \Leftrightarrow x < 2$ or $x > 3$.
 - $\sqrt{2 - \ln x}$:
 - $\ln x$ is defined: $x > 0$.
 - $2 - \ln x \geq 0 \Leftrightarrow \ln x \leq 2 \Leftrightarrow x \leq e^2$.



Hence, the domain is $(0, 2) \cup (3, e^2]$.

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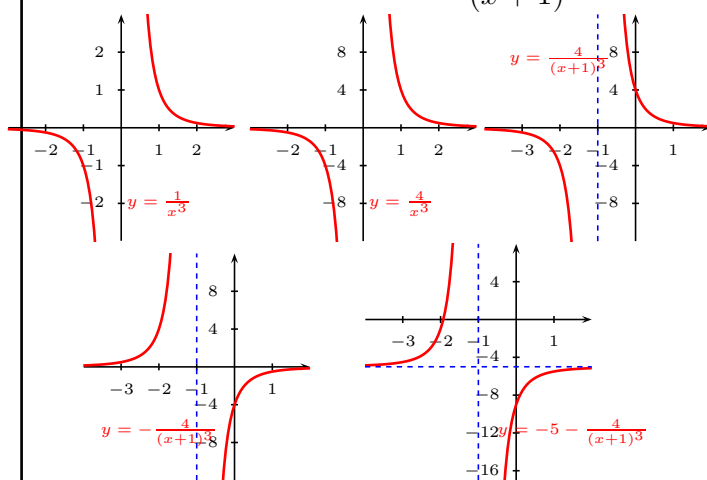
Graph Sketching

- Given a function $f(x)$.
 - Basic Transformation of Graphs:
 - $f(x - k)$: k units to the right;
 - $f(x + k)$: k units to the left;
 - $f(x) + k$: k units up;
 - $f(x) - k$: k units down;
 - $f(-x)$: reflection about y -axis;
 - $-f(x)$: reflection about x -axis;
 - $kf(x)$: scale along y -axis by k ;
 - $f(kx)$: scale along x -axis by $1/k$.

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Examples

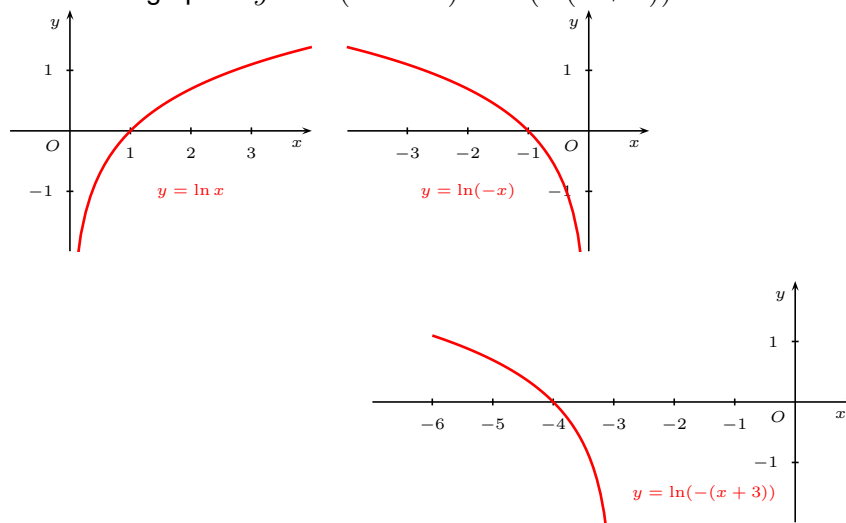
- Sketch the graph of $y = -5 - \frac{4}{(x+1)^3}$.



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Examples

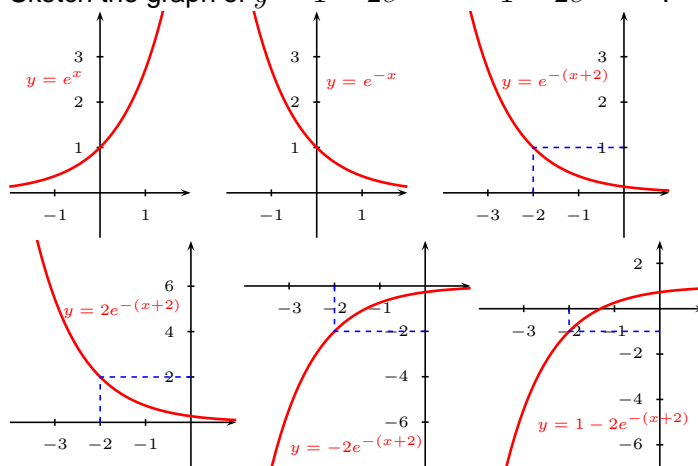
- Sketch the graph of $y = \ln(-x - 3) = \ln(-(x + 3))$.



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Examples

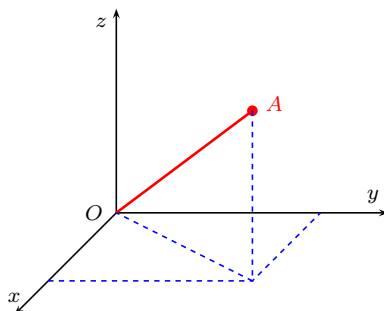
- Sketch the graph of $y = 1 - 2e^{-x-2} = 1 - 2e^{-(x+2)}$.



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Three-Dimensional Space

- The **three-dimensional space** is the set of points:
 - $\mathbb{R}^3 = \{(x, y, z) \mid x, y, z \in \mathbb{R}\}$.
- Let $A(x_1, y_1, z_1)$ be a point and $O(0, 0, 0)$ be the origin.
 - The vector \overrightarrow{OA} is called the **position vector** of A .
 - Its **length** is denoted by $|\overrightarrow{OA}| = \sqrt{x_1^2 + y_1^2 + z_1^2}$.



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Three-Dimensional Space

- If $\mathbf{v} \neq \mathbf{0} (= (0, 0, 0))$, then $\mathbf{v} = |\mathbf{v}| \left(\frac{\mathbf{v}}{|\mathbf{v}|} \right)$.
 - $\left| \frac{\mathbf{v}}{|\mathbf{v}|} \right| = \frac{1}{|\mathbf{v}|} |\mathbf{v}| = 1 \Rightarrow \frac{\mathbf{v}}{|\mathbf{v}|}$ is a **unit vector**.
- Two vectors \mathbf{u} and \mathbf{v} are **parallel** if and only if
 - $\mathbf{u} = \lambda \mathbf{v}$ for some $\lambda \in \mathbb{R}$, denoted by $\mathbf{u} \parallel \mathbf{v}$.
- Let $A(x_1, y_1, z_1)$ and $B(x_2, y_2, z_2)$ be points in \mathbb{R}^3 . Then
 - $\overrightarrow{AB} = (x_2 - x_1)\mathbf{i} + (y_2 - y_1)\mathbf{j} + (z_2 - z_1)\mathbf{k}$.

Without ambiguity, sometimes we may also write

 - $\overrightarrow{AB} = (x_2 - x_1, y_2 - y_1, z_2 - z_1)$.

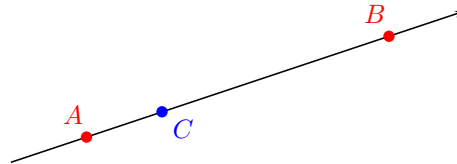
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Lines in Three-Dimensional Space

- Consider the straight line L passing through points A, B .
 - $\mathbf{u} = \overrightarrow{AB}$ is a **direction vector**.

Let \mathbf{a}, \mathbf{b} be the position vectors of A, B , respectively.

Let \mathbf{r} be the position vector of $C \in L$.



- $(\mathbf{r} - \mathbf{a}) \parallel (\mathbf{b} - \mathbf{a}) \Rightarrow (\mathbf{r} - \mathbf{a}) = \lambda(\mathbf{b} - \mathbf{a}), \lambda \in \mathbb{R}.$

Therefore, L can be represented by

- $\mathbf{r} = \mathbf{a} + \lambda(\mathbf{b} - \mathbf{a}), \lambda \in \mathbb{R}.$

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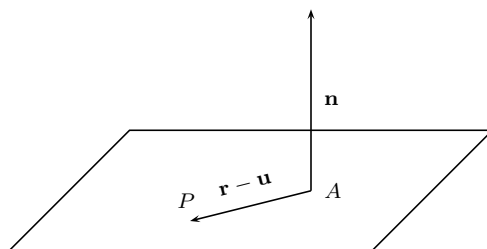
Scalar Products

- Let $\mathbf{u} = x_1\mathbf{i} + y_1\mathbf{j} + z_1\mathbf{k}$ and $\mathbf{v} = x_2\mathbf{i} + y_2\mathbf{j} + z_2\mathbf{k}$.
 - Their **scalar product** is defined by
 - $\mathbf{u} \bullet \mathbf{v} = x_1x_2 + y_1y_2 + z_1z_2.$
 - Geometric meaning:
 - $\mathbf{u} \bullet \mathbf{v} = |\mathbf{u}| |\mathbf{v}| \cos \theta, \theta$ is the angle between \mathbf{u}, \mathbf{v} .
- Properties:
 - $\mathbf{u} \bullet \mathbf{v} = \mathbf{v} \bullet \mathbf{u};$
 - $\mathbf{u} \bullet (\mathbf{v} + \mathbf{w}) = \mathbf{u} \bullet \mathbf{v} + \mathbf{u} \bullet \mathbf{w};$
 - $\lambda(\mathbf{u} \bullet \mathbf{v}) = (\lambda\mathbf{u}) \bullet \mathbf{v} = (\mathbf{u}) \bullet (\lambda\mathbf{v});$
 - $\mathbf{u} \bullet \mathbf{u} = |\mathbf{u}|^2;$
 - $\mathbf{u} \bullet \mathbf{v} = 0 \Leftrightarrow \mathbf{u} \perp \mathbf{v}$ (\mathbf{u} and \mathbf{v} are perpendicular).

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Planes in Three-Dimensional Space

- Let Π be a plane containing point A with position vector \mathbf{u} , and let \mathbf{n} be a **normal vector** of Π (i.e., $\mathbf{n} \perp \Pi$).
 - Let \mathbf{r} be the position vector of any point P .



$$\begin{aligned}
 P \in \Pi &\Leftrightarrow \overrightarrow{AP} \perp \mathbf{n} \\
 &\Leftrightarrow (\mathbf{r} - \mathbf{u}) \bullet \mathbf{n} = 0 \\
 &\Leftrightarrow \mathbf{r} \bullet \mathbf{n} = \mathbf{u} \bullet \mathbf{n}.
 \end{aligned}$$

- Therefore, the equation of Π is given by $\mathbf{r} \bullet \mathbf{n} = \mathbf{u} \bullet \mathbf{n}$.

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Vector Products

- Let $\mathbf{u} = x_1\mathbf{i} + y_1\mathbf{j} + z_1\mathbf{k}$ and $\mathbf{v} = x_2\mathbf{i} + y_2\mathbf{j} + z_2\mathbf{k}$.
 - Their **vector product** is defined by

$$\mathbf{u} \times \mathbf{v} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ x_1 & y_1 & z_1 \\ x_2 & y_2 & z_2 \end{vmatrix}; \quad \text{equivalently, it equals}$$

$$(y_1z_2 - y_2z_1)\mathbf{i} + (z_1x_2 - z_2x_1)\mathbf{j} + (x_1y_2 - x_2y_1)\mathbf{k}.$$
 - Geometric meaning:
 - $\mathbf{u} \times \mathbf{v}$ is perpendicular to both \mathbf{u} and \mathbf{v} , and its direction is given by the **right-hand rule**.
 - $|\mathbf{u} \times \mathbf{v}|$ represents the area of the parallelogram formed by \mathbf{u} and \mathbf{v} :
 - $|\mathbf{u} \times \mathbf{v}| = |\mathbf{u}| |\mathbf{v}| \sin \theta$, θ : angle between \mathbf{u} , \mathbf{v} .

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Vector Products

- Properties of vector products:
 - $\mathbf{u} \times \mathbf{v} = -\mathbf{v} \times \mathbf{u}$;
 - $\mathbf{i} \times \mathbf{j} = \mathbf{k}$; $\mathbf{j} \times \mathbf{k} = \mathbf{i}$, $\mathbf{k} \times \mathbf{i} = \mathbf{j}$;
 - $\mathbf{u} \times (\mathbf{v} + \mathbf{w}) = \mathbf{u} \times \mathbf{v} + \mathbf{u} \times \mathbf{w}$;
 - $\lambda(\mathbf{u} \times \mathbf{v}) = (\lambda\mathbf{u}) \times \mathbf{v} = \mathbf{u} \times (\lambda\mathbf{v})$;
 - $\mathbf{u} \times \mathbf{v} = \mathbf{0} \Leftrightarrow \mathbf{u} \parallel \mathbf{v}$;
 - $(\mathbf{u} \times \mathbf{v}) \cdot \mathbf{w} = (\mathbf{v} \times \mathbf{w}) \cdot \mathbf{u} = (\mathbf{w} \times \mathbf{u}) \cdot \mathbf{v}$.
- Applications of vector products:
 - Suppose vectors \mathbf{u} and \mathbf{v} are non-parallel vectors which are parallel to a plane Π .
 - A normal vector of Π is given by $\mathbf{u} \times \mathbf{v}$.

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Examples

- Find the equation of the line L passing through points $(-2, -1, 0)$ and $(3, 2, -3)$.
 - A direction vector of L is given by
 - $(3, 2, -3) - (-2, -1, 0) = (5, 3, -3)$.
 - Any point on L can be written as
 - $(-2, -1, 0) + \lambda(5, 3, -3)$, $\lambda \in \mathbb{R}$.
 - Therefore, the equation of L is
 - $\mathbf{r} = (-2 + 5\lambda)\mathbf{i} + (-1 + 3\lambda)\mathbf{j} - 3\lambda\mathbf{k}$.
- **Remark.** Note that the representation is not unique.
 - $(3, 2, 3) + \lambda(5, 3, -3)$, $\lambda \in \mathbb{R}$, is also a solution.

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Examples

- Find the equation of the plane Π , if
 - Π contains $(2, 2, 2)$, and
 - Π is perpendicular to $3\mathbf{i} + \mathbf{j} - 2\mathbf{k}$.
 - **Solution.**
 - A normal vector: $3\mathbf{i} + \mathbf{j} - 2\mathbf{k}$;
A point in Π : $(2, 2, 2)$.
 - Therefore, the equation of Π is:
 - $(x, y, z) \bullet (3, 1, -2) = (2, 2, 2) \bullet (3, 1, -2)$.
- That is,
- $3x + y - 2z = 4$.

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Examples

- Find the equation of the plane Π , if
 - Π contains $(2, 2, 2)$ and
the line $\mathbf{r} = \mathbf{i} - 2\mathbf{j} + 3\mathbf{k} + \lambda(3\mathbf{i} + \mathbf{j} - 2\mathbf{k})$, $\lambda \in \mathbb{R}$.
- **Solution.**
 - In order to get a normal vector to Π , we need two vectors parallel to Π :
 - One is given by $(3, 1, -2) \parallel \Pi$;
 - Let $\lambda = 0$ in the line. $(1, -2, 3) \in \Pi$.
 - $(2, 2, 2) - (1, -2, 3) = (1, 4, -1) \parallel \Pi$.
 - Normal vector: $(3, 1, -2) \times (1, 4, -1) = (7, 1, 11)$.
 - Equation of Π :
 - $(x, y, z) \bullet (7, 1, 11) = (2, 2, 2) \bullet (7, 1, 11)$;
 - That is, $7x + y + 11z = 38$.

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Examples

- Find the equation of the plane Π , if Π contains lines
 - $L_1 : \mathbf{r} = \mathbf{i} - 2\mathbf{j} + 3\mathbf{k} + \lambda_1(3\mathbf{i} + \mathbf{j} - 2\mathbf{k}), \lambda_1 \in \mathbb{R}$, and
 - $L_2 : \mathbf{r} = \mathbf{i} - 2\mathbf{j} + 3\mathbf{k} + \lambda_2(\mathbf{i} + 3\mathbf{k}), \lambda_2 \in \mathbb{R}$.
- **Solution.**
 - $(3, 1, -2)$ and $(1, 0, 3)$ are vectors parallel to Π .
 - Normal vector to Π :
 - $(3, 1, -2) \times (1, 0, 3) = (3, -11, -1)$.
 - Let $\lambda_1 = 0$ in L_1 (or $\lambda_2 = 0$ in L_2).
 - $(1, -2, 3)$ is a point in Π .
 - Equation of Π is given by
 - $(x, y, z) \bullet (3, -11, -1) = (1, -2, 3) \bullet (3, -11, -1)$
 - That is, $3x - 11y - z = 22$.

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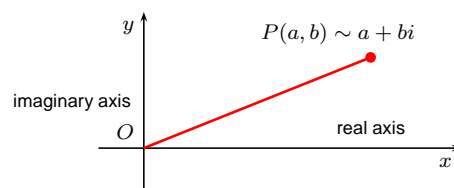
Examples

- Let $\mathbf{u} = \mathbf{i} - 2\mathbf{j} + 2\mathbf{k}$. Find the unit vector \mathbf{v} such that
 - $\mathbf{u} \bullet \mathbf{v}$ has the largest possible value;
 - $\mathbf{u} \bullet \mathbf{v}$ has the smallest possible value.
- **Solution.**
 - Recall: $\mathbf{u} \bullet \mathbf{v} = |\mathbf{u}| |\mathbf{v}| \cos \theta$, θ : angle between \mathbf{u} , \mathbf{v} .
 - $|\mathbf{u}|$ is given ($= 3$); and $|\mathbf{v}| = 1$.
 - $\mathbf{u} \bullet \mathbf{v}$ is the largest $\Leftrightarrow \cos \theta = 1 \Leftrightarrow \theta = 0$.
 - \mathbf{v} is parallel to \mathbf{u} of the same direction.
 - $\mathbf{v} = \mathbf{u}/|\mathbf{u}| = \frac{1}{3}\mathbf{i} - \frac{2}{3}\mathbf{j} + \frac{2}{3}\mathbf{k}$.
 - $\mathbf{u} \bullet \mathbf{v}$ is the smallest $\Leftrightarrow \cos \theta = -1 \Leftrightarrow \theta = \pi$.
 - \mathbf{v} is parallel to \mathbf{u} of the opposite direction.
 - $\mathbf{v} = -\mathbf{u}/|\mathbf{u}| = -\frac{1}{3}\mathbf{i} + \frac{2}{3}\mathbf{j} - \frac{2}{3}\mathbf{k}$.

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Complex Numbers

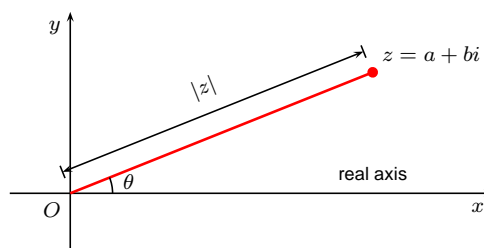
- Let $i = \sqrt{-1}$. The set of **complex numbers** is
 - $\mathbb{C} = \{a + bi \mid a, b \in \mathbb{R}\}$.
- Let $z = a + bi$ be a complex number, $a, b \in \mathbb{R}$.
 - a is the **real part** of z , denoted by $\operatorname{Re} z$;
 - b is the **imaginary part** of z , denoted by $\operatorname{Im} z$.
 - $a - bi$ is the **conjugate** of z , denoted by z^* .
 - $\sqrt{a^2 + b^2}$ is the **modulus** of z , denoted by $|z|$.
- A complex number $z = a + bi$, $a, b \in \mathbb{R}$, can be identified as a point $(a, b) \in \mathbb{R}^2$.



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Complex Numbers

- Let $z = a + bi$, $a, b \in \mathbb{R}$.
 - The angle $\theta \in (-\pi, \pi]$ between z and the real axis is called the **argument** of z , denoted by $\arg z$.



- Then $a = |z| \cos \theta$ and $b = |z| \sin \theta$.
- $z = |z|(\cos \theta + i \sin \theta)$ is the **polar form** of z .
- Euler's formula:**
 - $e^{i\theta} = \cos \theta + i \sin \theta$.

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Arithmetic Operations on \mathbb{C}

- Addition and Subtraction:
 - $(a + bi) \pm (c + di) = (a \pm c) + (b \pm d)i$.
- Multiplication:
 - $(a + bi)(c + di) = (ac - bd) + (ad + bc)i$.
 - Polar form: $z_1 = |z_1|e^{i\alpha}$ and $z_2 = |z_2|e^{i\beta}$;
 - $z_1 z_2 = |z_1| |z_2| e^{i(\alpha+\beta)}$.
 - In particular, let $z = a + bi$, $a, b \in \mathbb{R}$.
 - $zz^* = (a + bi)(a - bi) = a^2 + b^2 = |z|^2$.
 - **De Moivre's theorem:**
 - $(\cos \theta + i \sin \theta)^n = \cos n\theta + i \sin n\theta$, $n \in \mathbb{Z}$.

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Arithmetic Operations on \mathbb{C}

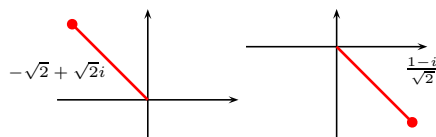
- Division:
 - $\frac{a + bi}{c + di} = \frac{a + bi}{c + di} \cdot \frac{c - di}{c - di}$
 - Multiply numerator and denominator by $(c + di)^*$.
 - $\frac{a + bi}{c + di} = \frac{(ac + bd) + (bc - ad)i}{c^2 + d^2}$.
 - Polar form: $z_1 = |z_1|e^{i\alpha}$ and $z_2 = |z_2|e^{i\beta}$;
 - $\frac{z_1}{z_2} = \frac{|z_1|}{|z_2|} e^{i(\alpha-\beta)}$.
- **Example.** Evaluate $\frac{1 + 2i}{3 + 4i}$.
 - $\frac{1 + 2i}{3 + 4i} = \frac{1 + 2i}{3 + 4i} \cdot \frac{3 - 4i}{3 - 4i} = \frac{11 + 2i}{25}$.

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Examples

- Evaluate $\left(\frac{1}{-\sqrt{2} + \sqrt{2}i}\right)^{2011}$.

- Let $z = -\sqrt{2} + \sqrt{2}i$. Then $|z| = \sqrt{2+2} = 2$.



- $\arg z = \frac{3\pi}{4}$. $z = 2e^{i\frac{3\pi}{4}}$.
- $\text{LHS} = \left(\frac{1}{z}\right)^{2011} = 2^{-2011}e^{-2011 \times \frac{3\pi}{4}i}$
 $= 2^{-2011}e^{-(1508\pi i + \frac{\pi i}{4})} = 2^{-2011}e^{-\frac{\pi i}{4}}$
 $= 2^{-2011} \cdot \frac{1-i}{\sqrt{2}}$
 $= \frac{1}{2^{2011}\sqrt{2}} - \frac{i}{2^{2011}\sqrt{2}}$.

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Examples

- Prove that for any θ with $\theta \neq \pm\pi, \pm3\pi, \pm5\pi, \dots$

- $\frac{1 + \cos \theta + i \sin \theta}{1 + \cos \theta - i \sin \theta} = \cos \theta + i \sin \theta$.

• Proof.

- $(1 + \cos \theta - i \sin \theta)(\cos \theta + i \sin \theta)$
 $= \cos \theta + \cos^2 \theta - i \sin \theta \cos \theta + i \sin \theta + i \cos \theta \sin \theta + \sin^2 \theta$
 $= 1 + \cos \theta + i \sin \theta$.

Alternative Proof.

- Let $z = \cos \theta + i \sin \theta$.
 - The identity becomes $\frac{1+z}{1+z^*} = z$, where $|z| = 1$.
 - Apply the multiplication:
 - $(1+z^*)z = z + z^*z = z + |z|^2 = z + 1$.

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