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ECE 590-16 Intro to Deep Learning
HW2 Yifan Li y 1506
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Publem 1
                                                       (a) Fundamental theorem of calculus:

F(\vec{y}) = F(\vec{x}) + \int_{0}^{x} (\vec{y} - \vec{x})^{T} \nabla F(\vec{x} + t(\vec{y} - \vec{x})) dt
                                                                                    Lipschitz Contintous:
                                                                                                                                              1 PF(y) - VF(x)1/2 < L ||y-x||2
                                                                                    F(\vec{y}) = F(\vec{x}) + \int_{s}^{s} (\vec{y} - \vec{x})^{T} \nabla F(\vec{x} + t(\vec{y} - \vec{x})) dt
= F(\vec{x}) + \int_{s}^{s} \nabla F(\vec{x} + t(\vec{y} - \vec{x}))^{T} (\vec{y} - \vec{x}) dt
                                                                                   = F(\vec{x}) + \nabla F(\vec{x})^T (\vec{y} - \vec{x}) + \int_0^1 \left[ \nabla F(\vec{x} + t(\vec{y} - \vec{x})) - \nabla F(\vec{x}) \right]^T (\vec{y} - \vec{x}) dt
By the defintion of Lipschitz continuous, we have
                                                                                                                                  \nabla F(\vec{x} + t(\vec{y} - \vec{x})) - \nabla F(\vec{x}) \leq L \| t(\vec{y} - \vec{x}) \|_2
                                                                                                                   F(\vec{y}) \leq F(\vec{x}) + \nabla F(\vec{x})^T (\vec{y} - \vec{x}) + \int_0^{\infty} L \| t(\vec{y} - \vec{x}) \|_2 \| \vec{y} - \vec{x} \|_2 dt
                                                                                                                     F(\vec{y}) \leq F(\vec{x}) + \nabla F(\vec{x})^T (\vec{y} - \vec{x}) + \frac{1}{2} L ||\vec{y} - \vec{x}||_2^2
                                                                       Lemma (sequence for stochastic gradient): W_{k+1} = W_k - \alpha_k \hat{g}_k
satisfies in expectation E = \frac{1}{2} \left[ \frac{1}{2} 
                                                                                  E[F(\vec{w_{k+1}})] - F(\vec{w_k}) \leq -\alpha_k [\nabla F(\vec{w_k})]^T E[\vec{g_k}] + \frac{\alpha_k^2 L}{2} E[\|\vec{g_k}\|_2^2]
                                                                                  Want to minimize R.H.S
                                                                              Let f(a_k) = -0 \times [\nabla F(\vec{w_k})]^T E[\hat{g_k}] + \frac{0 \times^2 L}{2} E[l|\hat{g_k}||_2]
\frac{df(a_k)}{da_k} = 0 = -0 \times g_k^T E[\hat{g_k}] + 0 \times L E[l|\hat{g_k}||_2]
                                                                                 By defintion of variance, Var [1/9/2] = E[1/9/2] - E[1/9/2]
                                                                              So we have
QK = \frac{gK^T E[\widehat{gK}]}{L \left( Var \mathbb{I} \widehat{gK} \right)^2 + E[\mathbb{I} \widehat{gK} | \mathbb{I}^2]} = \frac{\|gK\|_2^2}{L(M + E[\mathbb{I} \widehat{gK} | \mathbb{I}^2]^2)} \quad var(\mathbb{I} \widehat{gK} | \mathbb{I}_2) \leq M
                                                                                        it we consider an unbiased gradient estimator, and assume that
                                                                       the variance is bounded, we have \mathbb{E}[\widehat{g_k}] = g_k, var(||g_k||_2^2) \leq M
Q_k = \frac{||g_k||_2^2}{L(M + \mathbb{E}[\widehat{H}\widehat{g_k}]_2^2}, \text{ we know that } M \text{ (the uper bound of the variance)}
                                                                   must be 0. \frac{1/9 \text{kl}_2^2}{2}, we have M = \frac{1/9 \text{kl}_2^2}{2} for 0 \text{k} to be optimal 

3) 0 \text{k} = \frac{1}{10L} = \frac{1/9 \text{kl}_2^2}{10L} we have M = \frac{9 \frac{1/9 \text{kl}_2^2}{2}}{10L} for 0 \text{k} to be optimal 

In general, if 0 \text{k} = \frac{1}{6L}, the variance is bounded to be \frac{1}{6L} = \frac{1}{6L} = \frac{1}{6L} = \frac{1}{6L}
                                                                                              for OK to be uptimal
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